Homework 6

Name: Zheyuan Hu

NetID: zh2095

Decision Tree Implementation

Load Data

```
In [1]:
          import matplotlib.pyplot as plt
          from itertools import product
          import numpy as np
          from collections import Counter
          from sklearn.base import BaseEstimator, RegressorMixin, ClassifierMixin
          from sklearn.tree import DecisionTreeClassifier, DecisionTreeRegressor, export_graph
          from sklearn.ensemble import GradientBoostingClassifier, GradientBoostingRegressor,
          import graphviz
          from IPython.display import Image
          %matplotlib inline
          data_train = np. loadtxt('svm-train.txt')
          data_test = np. loadtxt('svm-test.txt')
          x_train, y_train = data_train[:, 0: 2], data_train[:, 2].reshape(-1, 1)
          x_{test}, y_{test} = data_{test}[:, 0: 2], data_{test}[:, 2]. reshape(-1, 1)
In [3]:
          # Change target to 0-1 label
          y_{train} label = np. array(list(map(lambda x: 1 if x > 0 else 0, y_{train}))). reshape(
```

Q1

```
In [4]:
          def compute entropy (label array):
              Calulate the entropy of given label list
              :param label_array: a numpy array of binary labels shape = (n, 1)
              :return entropy: entropy value
,,,
              # Your code goes here
              K = np. unique(label_array)
              N = label_array. shape[0]
              entropy = 0
              for k in K:
                  p = np. count nonzero (label array == k)/N
                  entropy -= p*np. log(p)
              return entropy
          def compute_gini(label_array):
              Calulate the gini index of label list
              :param label array: a numpy array of labels shape = (n, 1)
```

```
:return gini: gini index value
;;;

# Your code goes here
K = np. unique(label_array)
N = label_array. shape[0]
gini = 0
for k in K:
    p = np. count_nonzero(label_array == k)/N
    gini += p*(1-p)
return gini
```

```
class Decision Tree (BaseEstimator):
    def __init__(self, split_loss_function, leaf_value_estimator,
                 depth=0, min_sample=5, max_depth=10):
        Initialize the decision tree classifier
        :param split_loss_function: method with args (X, y) returning loss
        :param leaf_value_estimator: method for estimating leaf value from array of ys
        :param depth: depth indicator, default value is 0, representing root node
        :param min sample: an internal node can be splitted only if it contains points
        :param max_depth: restriction of tree depth.
        self.split_loss_function = split_loss_function
        self.leaf_value_estimator = leaf_value_estimator
        self.depth = depth
        self. min sample = min sample
        self. max depth = max depth
        self. is leaf = False
    def fit(self, x, y):
        This should fit the tree classifier by setting the values self.is_leaf,
        self.split_id (the index of the feature we want ot split on, if we're splitting
        self.split_value (the corresponding value of that feature where the split is),
        and self.value, which is the prediction value if the tree is a leaf node. If
        splitting the node, we should also init self.left and self.right to be Decision
        objects corresponding to the left and right subtrees. These subtrees should be
        the data that fall to the left and right, respectively, of self. split value.
        This is a recurisive tree building procedure.
        :param X: a numpy array of training data, shape = (n, m)
        :param y: a numpy array of labels, shape = (n, 1)
        :return self
        # Your code goes here
        # if reach min sample or max depth, then end up spliting
        if self. depth == self. max depth or len(y) <= self. min sample:
            self. is leaf = True
            self. value = self. leaf_value_estimator(y)
            return self
        split_id, split_value = self.find_best_feature_split(x, y)
        if split_id != None and split_value != None:
            # update depth after each spliting
            self. depth += 1
            # initialize the two trees to fit the left and right data
            self. left = Decision Tree(self. split loss function, self. leaf value estim
```

```
self.right = Decision_Tree(self.split_loss_function, self.leaf_value_esti
        # split with the optimal feature and the corresponding value
        idx_left = np. where(x[:, split_id] <= split_value)
        idx_right = np. where(x[:, split_id] > split_value)
        x left = x[idx left]
        x_right = x[idx_right]
        y_left = y[idx_left]
        y_right = y[idx_right]
        # fit the tree on the left and right nodes
        self. left. fit(x_left, y_left)
        self. right. fit(x_right, y_right)
        self. split_id = split_id
        self. split_value = split_value
    else:
        self. is_leaf = True
        self. value = self. leaf_value_estimator(y)
    return self
def find_best_split(self, x_node, y_node, feature_id):
    For feature number feature_id, returns the optimal splitting point
    for data X_node, y_node, and corresponding loss
    :param X: a numpy array of training data, shape = (n_node)
    :param y: a numpy array of labels, shape = (n_node, 1)
    # Your code
    n_node = x_node. shape[0]
    x = x_node[:, feature_id]
    best_loss = self.split_loss_function(y_node)
    split value = None
    for i in range(n_node):
        idx_left = np. where(x <= x[i])
        idx_right = np. where(x > x[i])
        x_1eft = x_node[idx_1eft]
        x_right = x_node[idx_right]
        y_left = y_node[idx_left]
        y_right = y_node[idx_right]
        left_loss = self. split_loss_function(y_left)
        right_loss = self.split_loss_function(y_right)
        # loss is the weighted average of left and right loss
        loss = (len(y_left)*left_loss + len(y_right)*right_loss)/len(y_node)
        if loss < best_loss:</pre>
            best loss = loss
            split value = x[i]
    return split_value, best_loss
def find_best_feature_split(self, x_node, y_node):
    Returns the optimal feature to split and best splitting point
    for data X_node, y_node.
    :param X: a numpy array of training data, shape = (n_node, 1)
    :param y: a numpy array of labels, shape = (n node, 1)
    # Your code
    m = x \text{ node. shape}[1]
    best loss = self. split loss function(y node)
    split_id = None
    split value = None
    for feature id in range (m):
        value, loss = self.find_best_split(x_node, y_node, feature_id)
```

```
if loss < best_loss:
    split_id = feature_id
    split_value = value
    best_loss = loss
return split_id, split_value

def predict_instance(self, instance):
    ,,,,

Predict label by decision tree

:param instance: a numpy array with new data, shape (1, m)

:return whatever is returned by leaf_value_estimator for leaf containing instance;
if self.is_leaf:
    return self.value
if instance[self.split_id] <= self.split_value:
    return self.left.predict_instance(instance)
else:
    return self.right.predict_instance(instance)</pre>
```

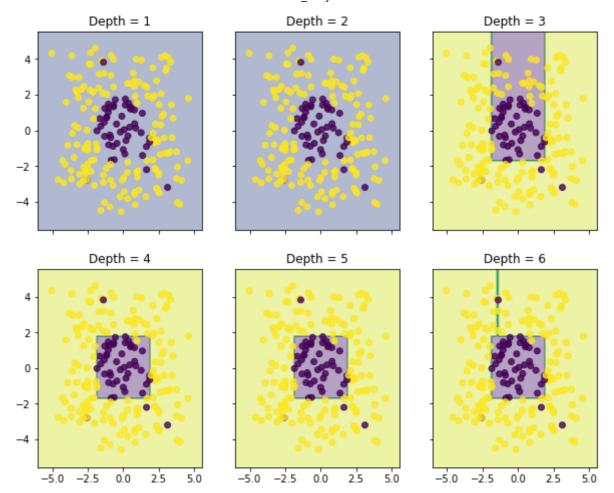
Decision Tree Classifier

```
In [6]:
          def most common label(y):
              Find most common label
              label_cnt = Counter(y. reshape(len(y)))
              label = label\_cnt.most\_common(1)[0][0]
              return label
In [7]:
          class Classification_Tree (BaseEstimator, ClassifierMixin):
              loss_function_dict = {
                  'entropy': compute entropy,
                  'gini': compute gini
              def __init__(self, loss_function='entropy', min_sample=5, max_depth=10):
                  :param loss_function(str): loss function for splitting internal node
                  self. tree = Decision_Tree(self. loss_function_dict[loss_function],
                                           most_common_label,
                                           0, min sample, max depth)
              def fit(self, X, y=None):
                  self. tree. fit (X, y)
                  return self
              def predict_instance(self, instance):
                  value = self. tree. predict_instance(instance)
                  return value
```

```
In [8]: # Training classifiers with different depth
```

```
clf1 = Classification_Tree(max_depth=1)
clf1. fit(x_train, y_train_label)
c1f2 = Classification_Tree(max_depth=2)
clf2.fit(x_train, y_train_label)
c1f3 = Classification Tree(max depth=3)
c1f3.fit(x_train, y_train_label)
clf4 = Classification Tree (max depth=4)
clf4. fit(x_train, y_train_label)
clf5 = Classification_Tree(max_depth=5)
clf5.fit(x_train, y_train_label)
clf6 = Classification_Tree(max_depth=20)
clf6. fit (x train, y train label)
# Plotting decision regions
x_{min}, x_{max} = x_{train}[:, 0]. min() - 1, <math>x_{train}[:, 0]. max() + 1
y_{min}, y_{max} = x_{train}[:, 1]. min() - 1, x_{train}[:, 1]. max() + 1
xx, yy = np. meshgrid(np. arange(x_min, x_max, 0.1),
                     np. arange (y_min, y_max, 0.1))
f, axarr = plt.subplots(2, 3, sharex='col', sharey='row', figsize=(10, 8))
for idx, clf, tt in zip(product([0, 1], [0, 1, 2]),
                         [clf1, clf2, clf3, clf4, clf5, clf6],
                         ['Depth = \{\}'. format(n) for n in range(1, 7)]):
    Z = np. array([clf. predict_instance(x) for x in np. c_[xx. ravel(), yy. ravel()]])
    Z = Z. reshape (xx. shape)
    axarr[idx[0], idx[1]].contourf(xx, yy, Z, alpha=0.4)
    axarr[idx[0], idx[1]].scatter(x_train[:, 0], x_train[:, 1], c=y_train_label, alpha
    axarr[idx[0], idx[1]].set_title(tt)
plt. show()
```

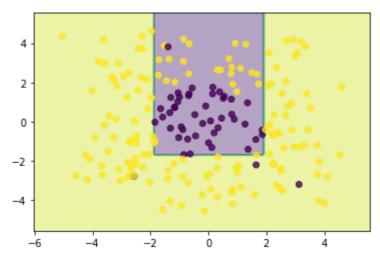
2021/4/24 HW6 ZheyuanHu



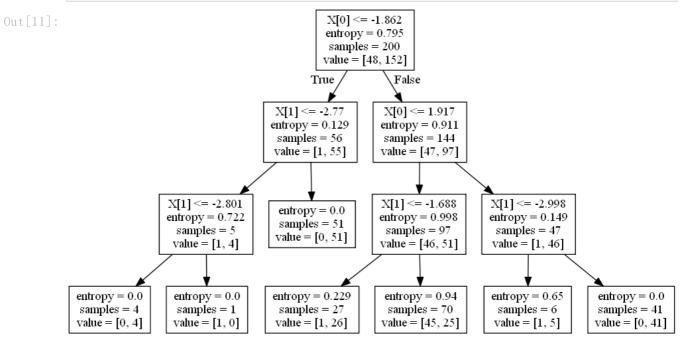
Compare decision tree with tree model in sklearn

```
In [9]:
            clf = DecisionTreeClassifier(criterion='entropy', max_depth=3, min_samples_split=2)
            clf. fit(x_train, y_train_label)
            export_graphviz(clf, out_file='tree_classifier.dot')
In [10]:
            # Plotting decision regions
            x \min, x \max = x \operatorname{train}[:, 0]. \min() - 1, x \operatorname{train}[:, 0]. \max() + 1
            y_{min}, y_{max} = x_{train}[:, 1]. min() - 1, <math>x_{train}[:, 1]. max() + 1
            xx, yy = np. meshgrid(np. arange(x_min, x_max, 0.1),
                                   np. arange (y_min, y_max, 0.1))
            Z = np. array([clf. predict(x[np. newaxis, :]) for x in np. c_[xx. ravel(), yy. ravel()]])
            Z = Z. reshape(xx. shape)
            plt. figure()
            plt. contourf(xx, yy, Z, alpha=0.4)
            plt. scatter(x_train[:, 0], x_train[:, 1],
            c=y_train_label[:,0], alpha=0.8)
```

 $\verb|Out[10]|: $$\langle \mathtt{matplotlib.collections.PathCollection}$ at $0x1aa2b48d520 \rangle$$



```
# Visualize decision tree
! dot -Tpng tree_classifier.dot -o tree_classifier.png
Image(filename='tree_classifier.png')
```



Decision Tree Regressor

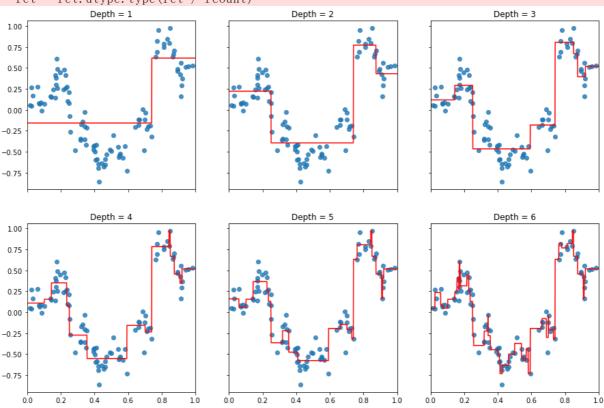
```
In [13]: class Regression_Tree():
```

```
:attribute loss_function_dict: dictionary containing the loss functions used for s
:attribute estimator_dict: dictionary containing the estimation functions used in
loss function dict = {
    'mse': np. var,
    'mae': mean_absolute_deviation_around_median
estimator_dict = {
    'mean': np. mean,
    'median': np. median
def __init__(self, loss_function='mse', estimator='mean', min_sample=5, max_depth
    Initialize Regression Tree
    :param loss_function(str): loss function used for splitting internal nodes
    :param estimator(str): value estimator of internal node
    self. tree = Decision_Tree(self. loss_function_dict[loss_function],
                              self. estimator_dict[estimator],
                              0, min_sample, max_depth)
def fit(self, X, y=None):
    self. tree. fit (X, y)
    return self
def predict_instance(self, instance):
    value = self. tree. predict_instance(instance)
    return value
```

Fit regression tree to one-dimensional regression data

```
In [14]:
           data_krr_train = np. loadtxt('krr-train.txt')
           data_krr_test = np. loadtxt('krr-test.txt')
           x_krr_train, y_krr_train = data_krr_train[:,0].reshape(-1,1),data_krr_train[:,1].resh
           x_{krr_{test}}, y_{krr_{test}} = data_{krr_{test}}; 0]. reshape(-1, 1), data_{krr_{test}}; 1]. reshape(-1, 1)
           # Training regression trees with different depth
           clf1 = Regression_Tree(max_depth=1, min_sample=3, loss_function='mae', estimator='me
           clfl. fit(x_krr_train, y_krr_train)
           c1f2 = Regression Tree (max depth=2,
                                                  min sample=3, loss function='mae', estimator='me
           clf2. fit(x_krr_train, y_krr_train)
           c1f3 = Regression Tree (max depth=3,
                                                  min sample=3, loss function='mae', estimator='me
           clf3. fit(x_krr_train, y_krr_train)
           c1f4 = Regression_Tree(max_depth=4,
                                                  min_sample=3, loss_function='mae', estimator='me
           clf4. fit (x_krr_train, y_krr_train)
           clf5 = Regression Tree (max depth=5,
                                                  min sample=3, loss function='mae', estimator='me
           clf5. fit(x_krr_train, y_krr_train)
           clf6 = Regression_Tree(max_depth=10, min_sample=3, loss_function='mae', estimator='m
           clf6. fit (x_krr_train, y_krr_train)
           plot size = 0.001
           x_range = np. arange(0., 1., plot_size). reshape(-1, 1)
```

```
C:\Users\52673\anaconda3\lib\site-packages\numpy\core\fromnumeric.py:3372: RuntimeWarn
ing: Mean of empty slice.
   return _methods._mean(a, axis=axis, dtype=dtype,
C:\Users\52673\anaconda3\lib\site-packages\numpy\core\_methods.py:170: RuntimeWarning:
invalid value encountered in double_scalars
   ret = ret.dtype.type(ret / rcount)
```



Ensembling

Q5

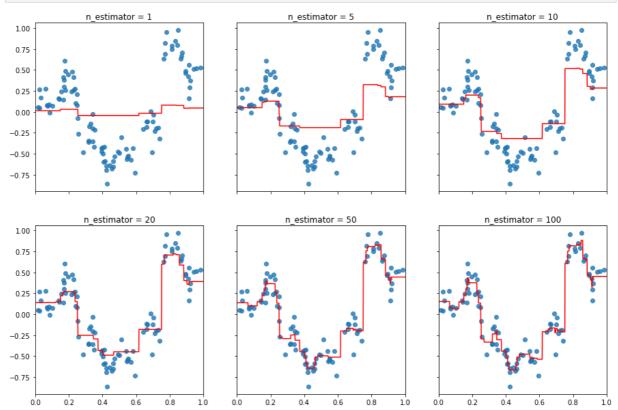
```
Gradient Boosting regressor class
:method fit: fitting model
def __init__(self, n_estimator, pseudo_residual_func, learning_rate=0.1, min_samp
    Initialize gradient boosting class
    :param n_estimator: number of estimators (i.e. number of rounds of gradient be
    :pseudo_residual_func: function used for computing pseudo-residual
    :param learning_rate: step size of gradient descent
    self. n_estimator = n_estimator
    self.pseudo_residual_func = pseudo_residual_func
    self.learning_rate = learning_rate
    self.min_sample = min_sample
    self. max depth = max depth
    self.estimators = []
def fit(self, train_data, train_target):
    Fit gradient boosting model
    # Your code goes here
    train\_predict = 0
    residuals = self.pseudo_residual_func(train_target.reshape(-1), train_predict
    for i in range (self. n estimator):
        hm = DecisionTreeRegressor(max_depth=self.max_depth, min_samples_leaf=sel
        self. estimators. append (hm)
        self. estimators[i]. fit(train_data, residuals)
        train_predict += self. learning_rate * self. estimators[i]. predict(train_da
        residuals = self.pseudo_residual_func(train_target.reshape(-1), train_pre
    return self
def predict(self, test_data):
    Predict value
    # Your code goes here
    test_predict = 0
    for i in range (len (self. estimators)):
        test_predict += self.learning_rate * self.estimators[i].predict(test_data
    return test_predict
```

1-D GBM visualization - KRR data

2021/4/24 HW6 ZheyuanHu

```
y_range_predict = gbm_1d. predict(x_range)

axarr2[idx[0], idx[1]]. plot(x_range, y_range_predict, color='r')
axarr2[idx[0], idx[1]]. scatter(x_krr_train, y_krr_train, alpha=0.8)
axarr2[idx[0], idx[1]]. set_title(tt)
axarr2[idx[0], idx[1]]. set_xlim(0, 1)
```



Classification of images with Gradient Boosting

Q7

The logistic loss:

$$\ell\left(y_i,f_{m-1}(x_i)
ight) = \ln\Bigl(1 + e^{-y_i f_{m-1}(x_i)}\Bigr)$$

The pseudo residual:

$$-\mathbf{g}_{m} = -\left(\frac{\partial}{\partial f_{m-1}(x_{j})} \sum_{i=1}^{n} \ell\left(y_{i}, f_{m-1}(x_{i})\right)\right)_{j=1}^{n}$$

$$= -\left(\frac{\partial}{\partial f_{m-1}(x_{j})} \sum_{i=1}^{n} \ln\left(1 + e^{-y_{i}f_{m-1}(x_{i})}\right)\right)_{j=1}^{n}$$

$$= -\left(\frac{\partial}{\partial f_{m-1}(x_{j})} \ln\left(1 + e^{-y_{j}f_{m-1}(x_{j})}\right)\right)_{j=1}^{n}$$

$$= \left(\frac{y_{j}}{1 + e^{y_{j}f_{m-1}(x_{j})}}\right)_{j=1}^{n}$$

The dimension of \mathbf{g}_m :

$$\dim(\mathbf{g}_m) = n$$

SO

$$egin{aligned} h_m &= rgmin_{h \in \mathcal{F}} \sum_{i=1}^n \left((-\mathbf{g}_m)_i - h(x_i)
ight)^2 \ &= rgmin_{h \in \mathcal{F}} \sum_{i=1}^n \left(rac{y_i}{1 + e^{y_i f_{m-1}(x_i)}} - h(x_i)
ight)^2 \end{aligned}$$

Q9

from sklearn.datasets import fetch_openml

In [18]:

```
from sklearn.linear_model import LogisticRegression
from sklearn. model selection import train test split
from sklearn.preprocessing import StandardScaler
from sklearn.utils import check_random_state
from sklearn.ensemble import GradientBoostingClassifier
def pre_process_mnist_01():
    Load the mnist datasets, selects the classes 0 and 1
    and normalize the data.
    Args: none
    Outputs:
        X_train: np.array of size (n_training_samples, n_features)
        X_test: np. array of size (n_test_samples, n_features)
        y_train: np.array of size (n_training_samples)
    y_test: np.array of size (n_test_samples)
    X_mnist, y_mnist = fetch_openml('mnist_784', version=1,
                                     return_X_y=True, as_frame=False)
    indicator 01 = (y_mnist == '0') + (y_mnist == '1')
    X_mnist_01 = X_mnist[indicator_01]
    y_mnist_01 = y_mnist[indicator_01]
    X_train, X_test, y_train, y_test = train_test_split(X_mnist_01, y_mnist_01,
                                                          test size=0.33,
                                                         shuffle=False)
    scaler = StandardScaler()
    X_train = scaler.fit_transform(X_train)
    X_{\text{test}} = \text{scaler.transform}(X_{\text{test}})
    y_{test} = 2 * np. array([int(y) for y in y_test]) - 1
    y train = 2 * np. array([int(y) for y in y train]) - 1
    return X train, X test, y train, y test
```

Train the model

```
estimators = [2, 5, 10, 100, 200]
train_acc_set = []
test_acc_set = []

for n_estimators in estimators:
    clf = GradientBoostingClassifier(loss='deviance', n_estimators=n_estimators, max_
```

X_train, X_test, y_train, y_test = pre_process_mnist_01()

```
clf.fit(X_train, y_train)
train_acc = clf.score(X_train, y_train)
test_acc = clf.score(X_test, y_test)
train_acc_set.append(train_acc)
test_acc_set.append(test_acc)
```

Plot the accuracy

```
fig, ax = plt.subplots(figsize=[10,6])
ax.set_title('Accuracy vs Num of Estimators')
ax.set_xlabel('Estimators')
ax.set_ylabel('Accuracy')
ax.plot(estimators, train_acc_set, '--x', label='train accuracy')
ax.plot(estimators, test_acc_set, '--x', label='test accuracy')
ax.legend()
plt.show()
```

