

# Synthetic Controls with Staggered Adoption

Eli Ben-Michael, Avi Feller, and Jesse Rothstein

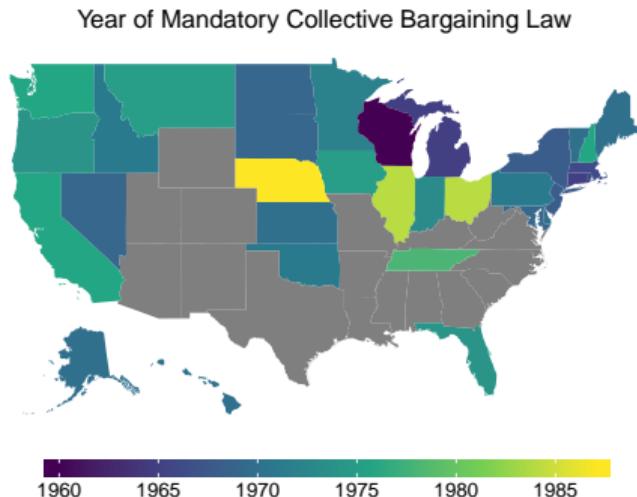
UC Berkeley

Online Causal Inference Seminar

September 2020

# What is the impact of teacher unionization on education spending?

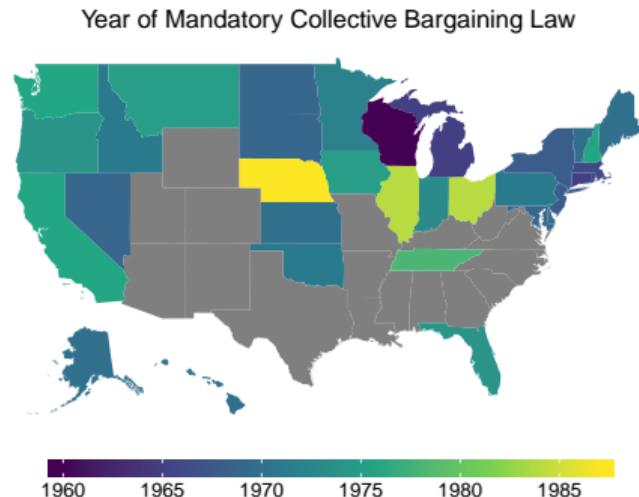
- 1960 – 1987: 34 states pass mandatory collective bargaining laws



# What is the impact of teacher unionization on education spending?

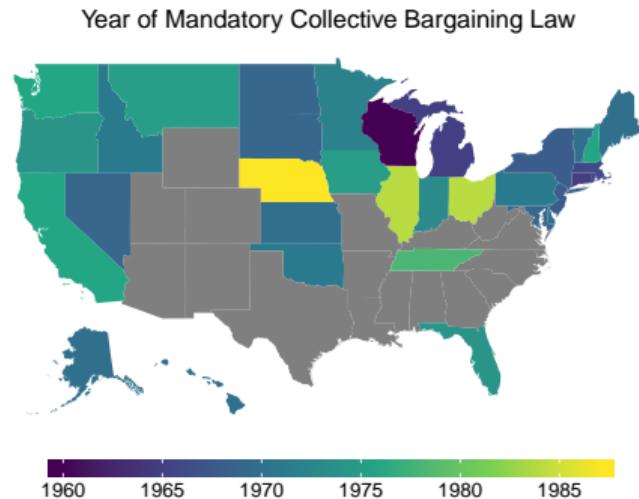
- 1960 – 1987: 34 states pass mandatory collective bargaining laws

- Impact of teachers unions unclear
  - ↑ Increase expenditures by **12%** [Hoxby, 1996]
  - ↔ Or really no effect at all? [Paglayan, 2019]



# What is the impact of teacher unionization on education spending?

- 1960 – 1987: 34 states pass mandatory collective bargaining laws
- Impact of teachers unions unclear
  - ↑ Increase expenditures by **12%** [Hoxby, 1996]
  - ↔ Or really no effect at all? [Paglayan, 2019]
- What should we believe?



## Estimating effects under staggered adoption

*Staggered adoption:* Multiple units adopt treatment over time

## Estimating effects under staggered adoption

*Staggered adoption:* Multiple units adopt treatment over time

*Common approaches can fail:* Little guidance when this happens

- Difference in Differences (DiD) requires parallel trends assumption
- Synthetic Control Method (SCM) designed for single treated unit, poor fit for average

# Estimating effects under staggered adoption

*Staggered adoption:* Multiple units adopt treatment over time

*Common approaches can fail:* Little guidance when this happens

- Difference in Differences (DiD) requires parallel trends assumption
- Synthetic Control Method (SCM) designed for single treated unit, poor fit for average

*Partially pooled SCM*

- Modify optimization problem to target overall and state-specific fit
- Account for level differences with Intercept-Shifted SCM

# What do we want to estimate?

Units:  $i = 1, \dots, N$ ,  $J$  total treated units

Time:  $t = 1, \dots, T$ , treatment times  $T_1, \dots, T_J, \infty$

Outcome: at event time  $k$ ,  $Y_{i,T_j+k}$

- Some assumptions to write down potential outcomes  
[Athey and Imbens, 2018; Imai and Kim, 2019]

$$\text{treat} = \begin{pmatrix} \checkmark & \checkmark & \checkmark \\ & \checkmark & \checkmark \\ & & \checkmark \end{pmatrix}$$

# What do we want to estimate?

Units:  $i = 1, \dots, N$ ,  $J$  total treated units

Time:  $t = 1, \dots, T$ , treatment times  $T_1, \dots, T_J, \infty$

Outcome: at event time  $k$ ,  $Y_{i,T_j+k}$

- Some assumptions to write down potential outcomes  
[Athey and Imbens, 2018; Imai and Kim, 2019]

Basic building block:

$$\tau_{jk} = Y_{j,T_j+k}(T_j) - \underbrace{Y_{j,T_j+k}(\infty)}_{\sum \hat{\gamma}_{ij} Y_{i,T_j+k}}$$

$$\text{treat} = \begin{pmatrix} \checkmark & \checkmark & \checkmark \\ & \checkmark & \checkmark \\ & & \checkmark \end{pmatrix}$$

# What do we want to estimate?

Units:  $i = 1, \dots, N$ ,  $J$  total treated units

Time:  $t = 1, \dots, T$ , treatment times  $T_1, \dots, T_J, \infty$

Outcome: at event time  $k$ ,  $Y_{i,T_j+k}$

- Some assumptions to write down potential outcomes  
[Athey and Imbens, 2018; Imai and Kim, 2019]

Basic building block:

$$\tau_{jk} = Y_{j,T_j+k}(T_j) - \underbrace{Y_{j,T_j+k}(\infty)}_{\sum \hat{\gamma}_{ij} Y_{i,T_j+k}}$$

$$\text{treat} = \begin{pmatrix} \checkmark & \checkmark & \checkmark \\ & \checkmark & \checkmark \\ & & \checkmark \end{pmatrix}$$

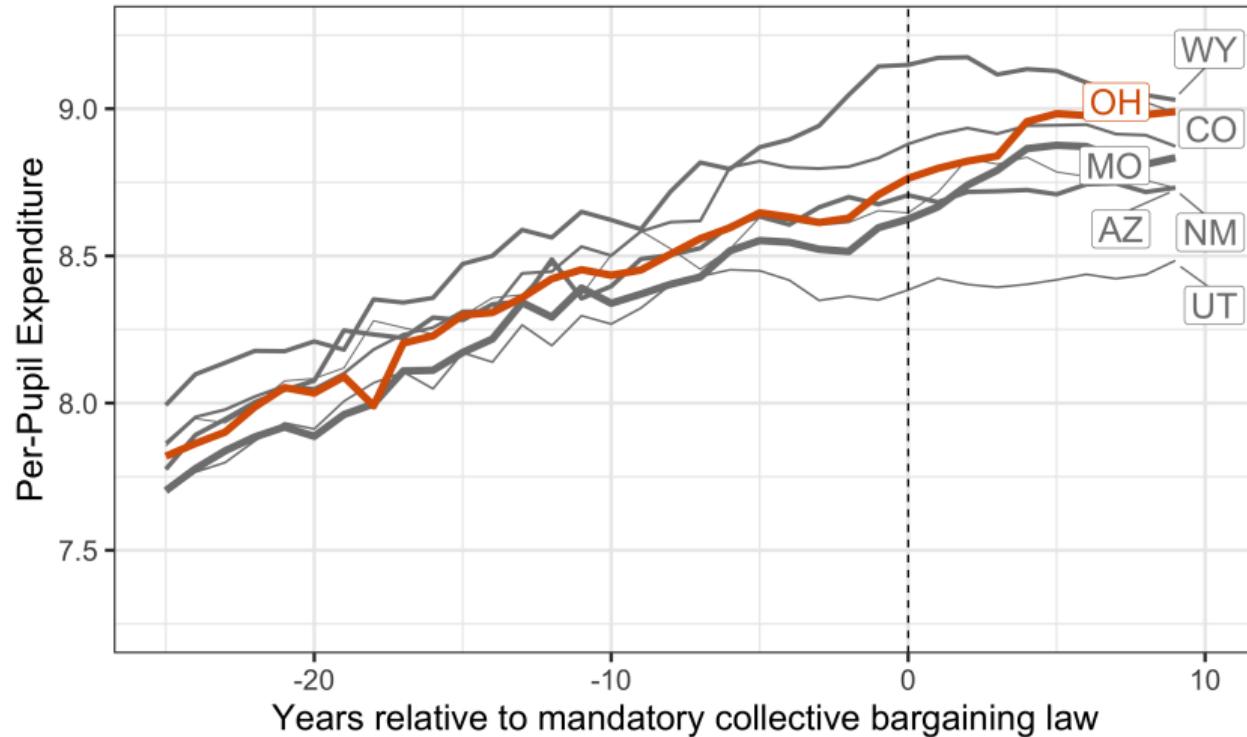
Average at event time  $k$ :

$$\text{ATT}_k = \frac{1}{J} \sum_{j=1}^J \tau_{jk}$$

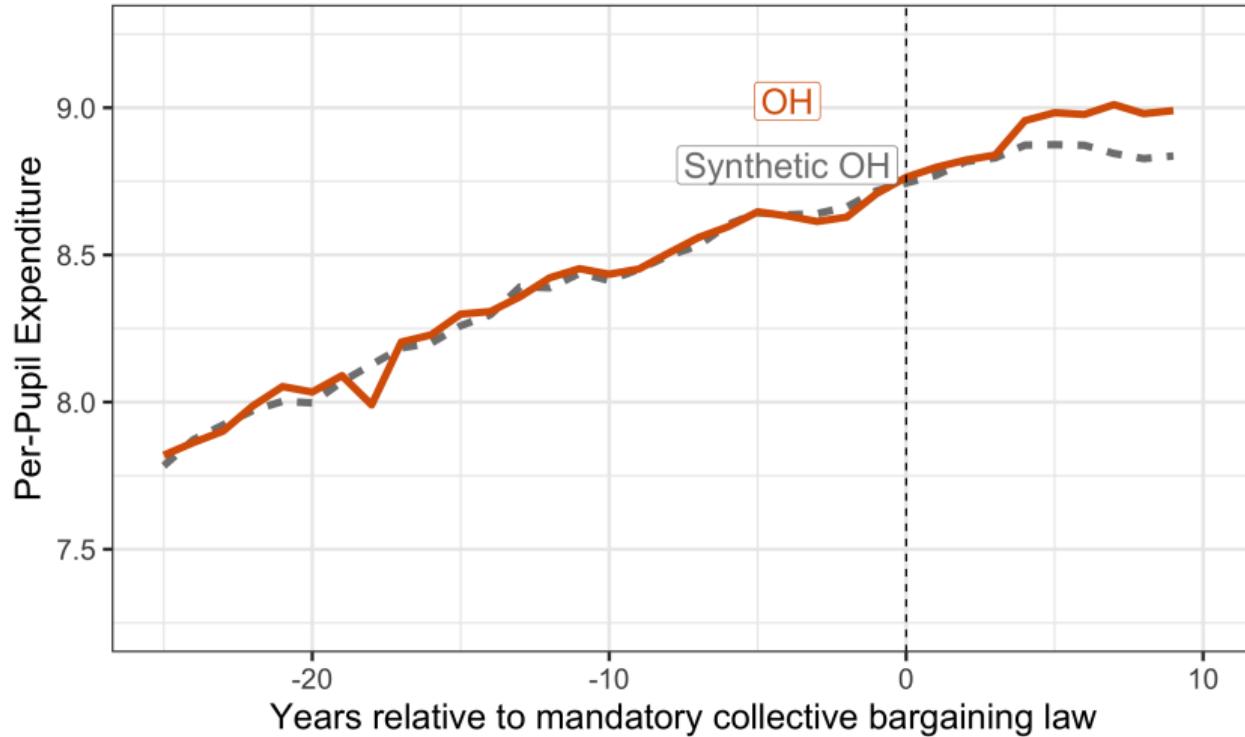
Separate  
SCM



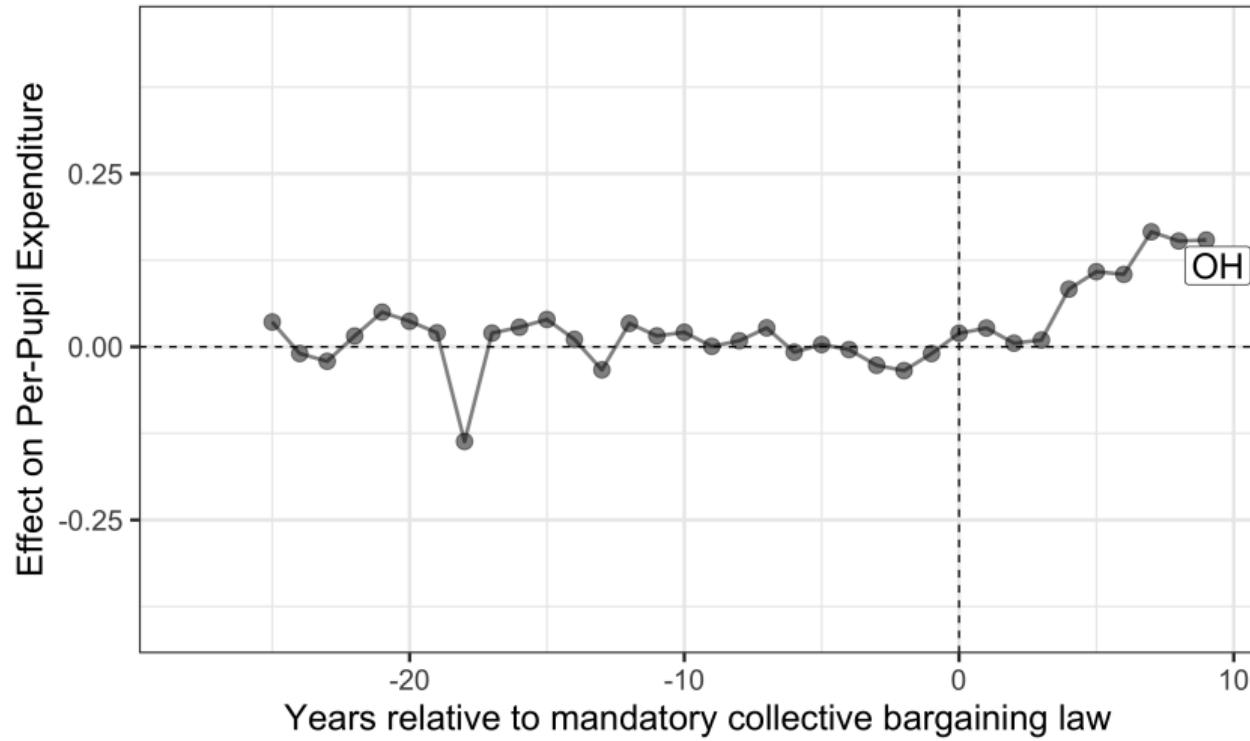




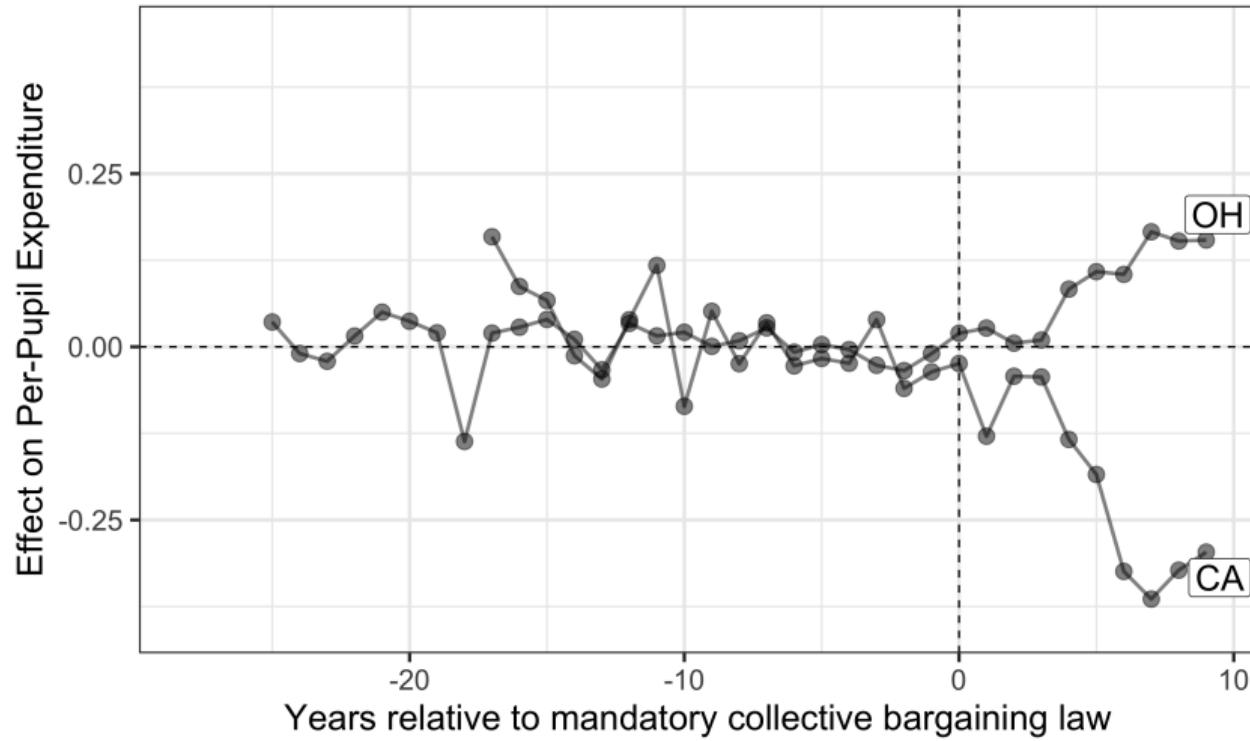
$$\min_{\gamma_j \in \Delta_j^{\text{scm}}} \|\text{State Balance}_j\|_2^2$$



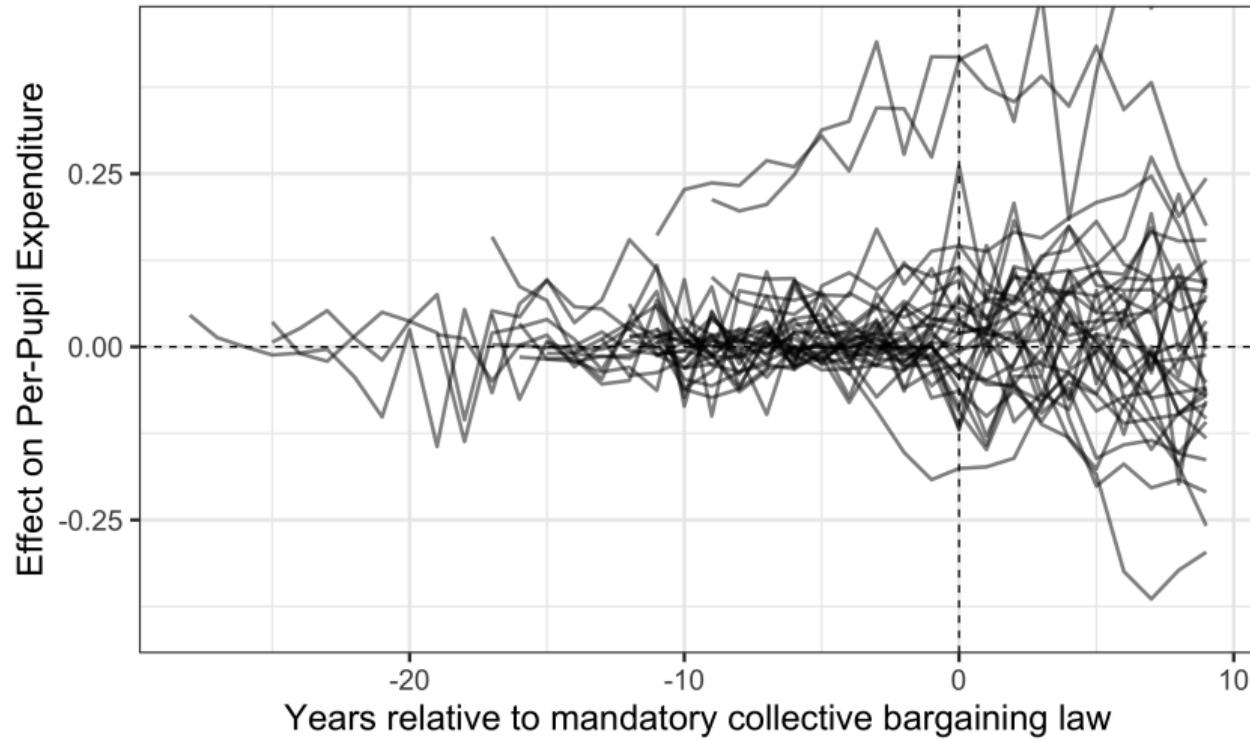
$$\min_{\gamma_j \in \Delta_j^{\text{scm}}} \|\text{State Balance}_j\|_2^2$$



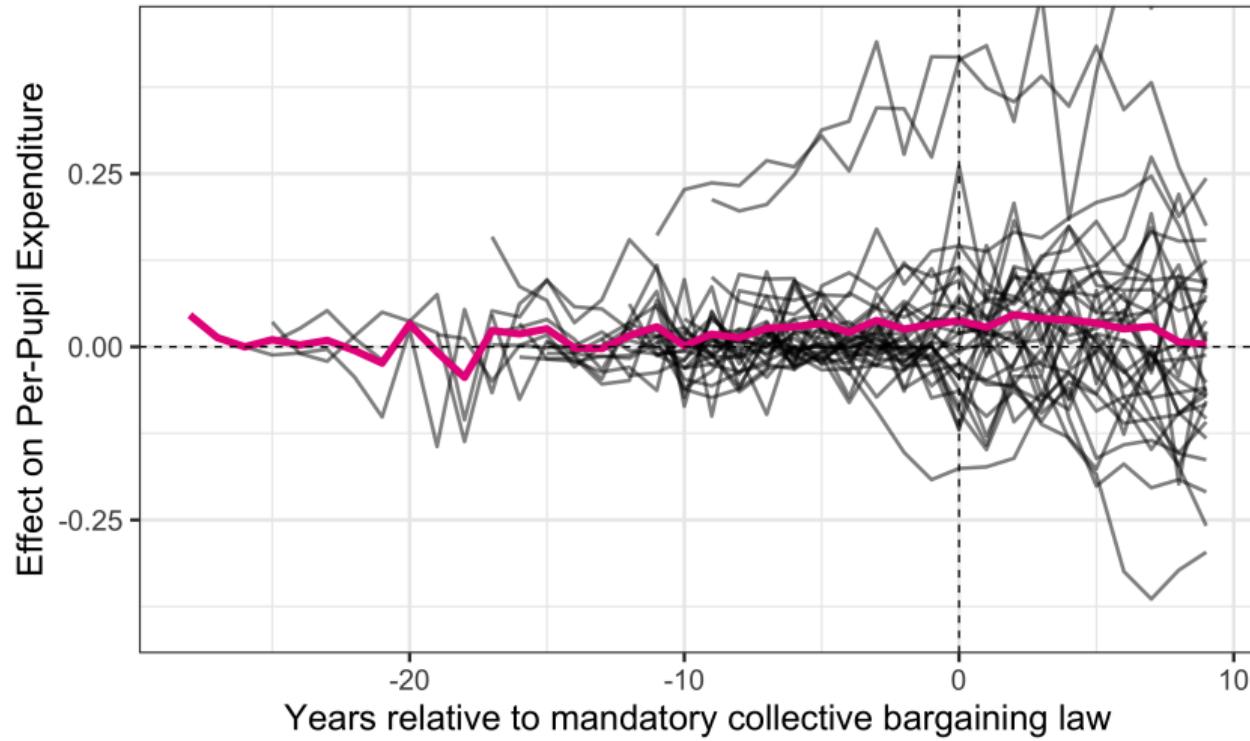
$$\min_{\gamma_j \in \Delta_j^{\text{scm}}} \|\text{State Balance}_j\|_2^2$$



$$\min_{\gamma_1, \dots, \gamma_J \in \Delta^{\text{scm}}} \frac{1}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$

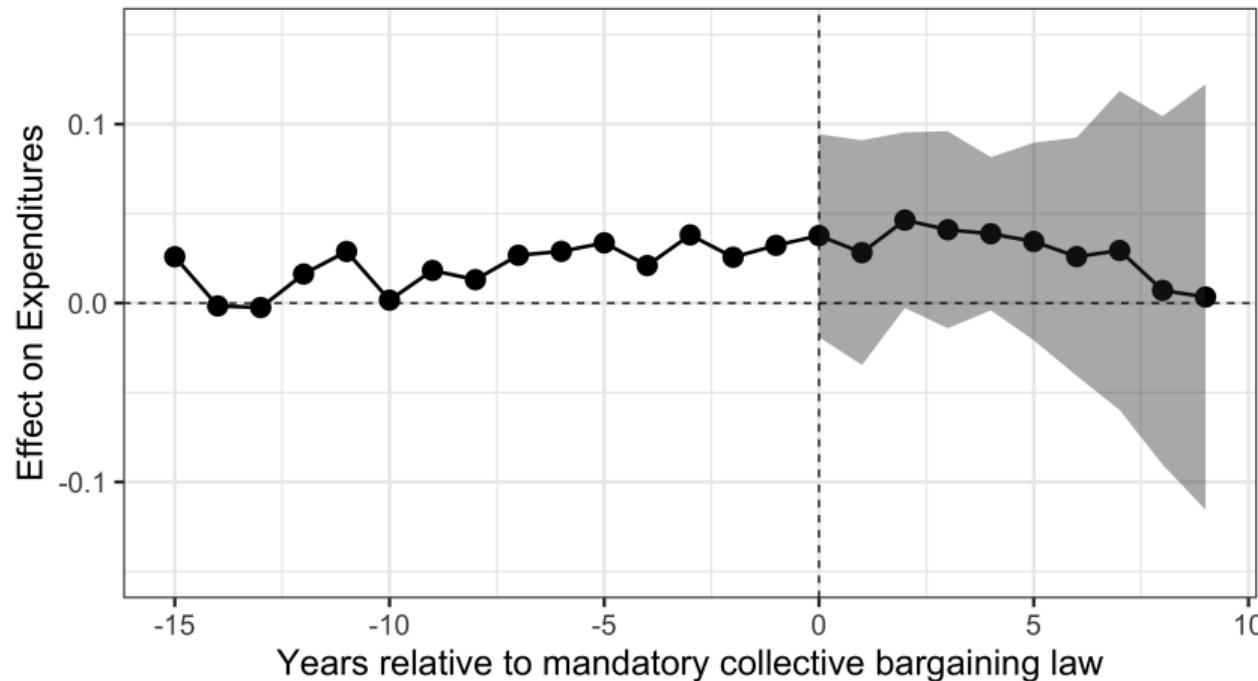


$$\min_{\gamma_1, \dots, \gamma_J \in \Delta^{\text{scm}}} \frac{1}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$



$$\min_{\gamma_1, \dots, \gamma_J \in \Delta^{\text{scm}}} \frac{1}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$

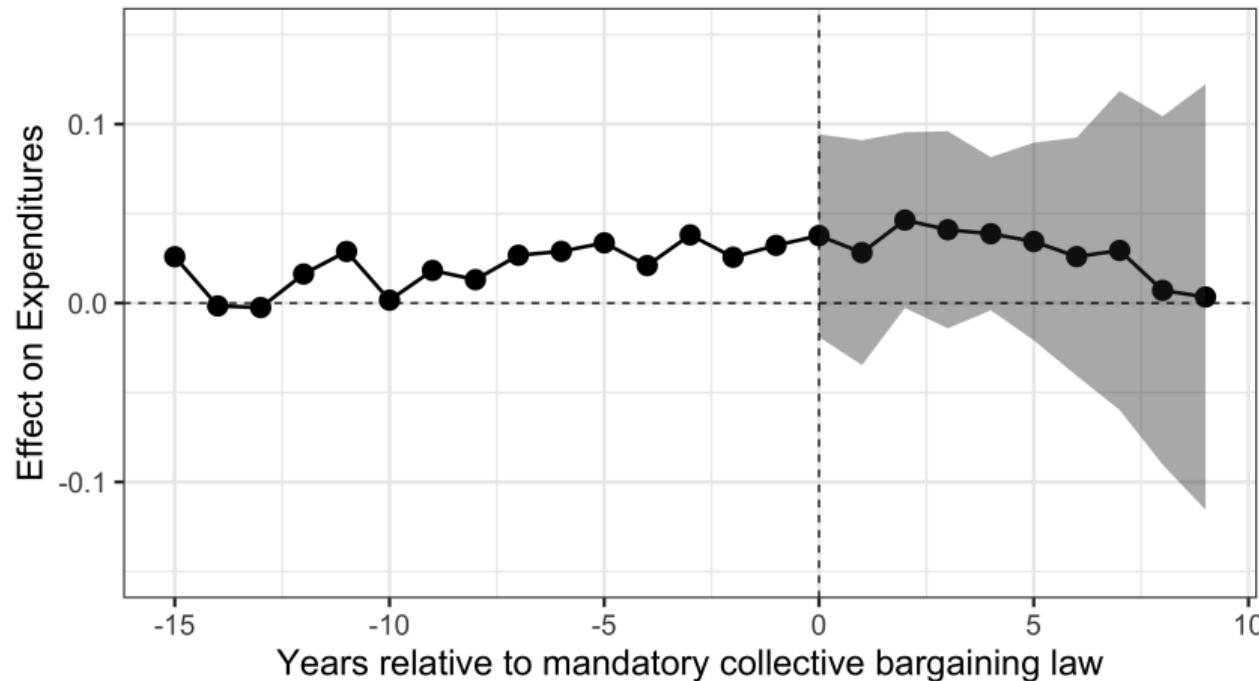
## Separate SCM



$$\min_{\gamma_1, \dots, \gamma_J \in \Delta^{\text{scm}}} \frac{1}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$

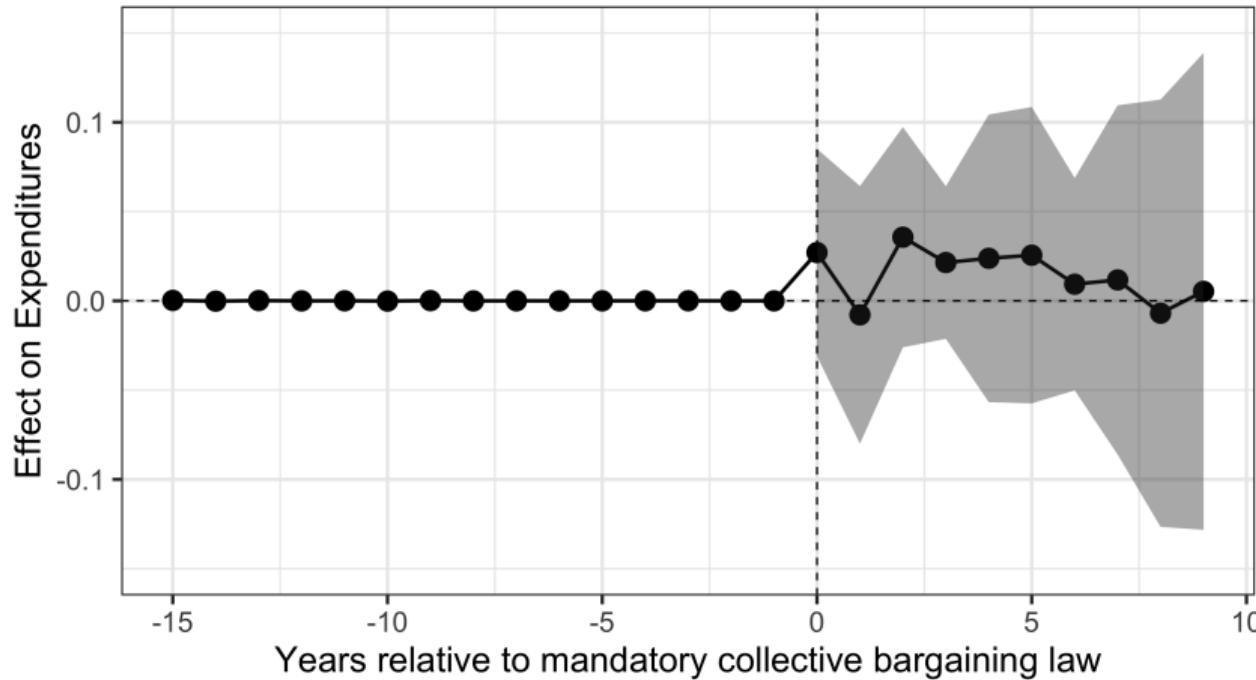
# Moving Beyond Separate SCM

## Separate SCM



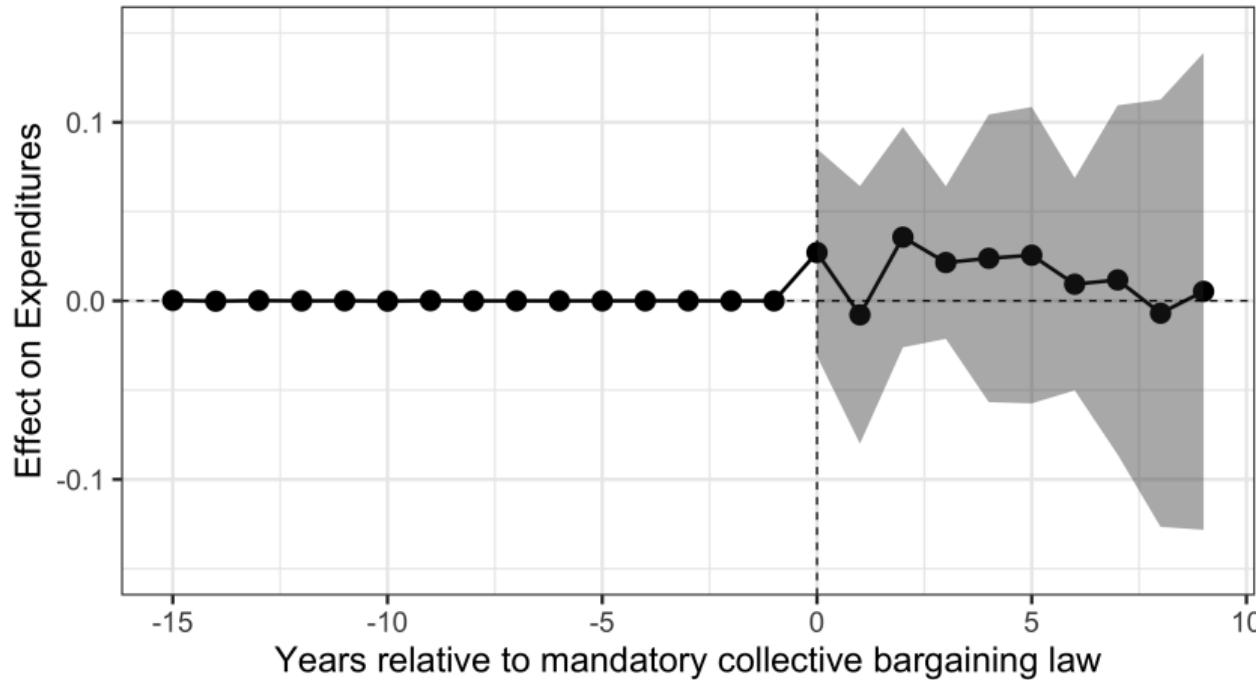
$$\min_{\Gamma} \frac{1}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$

## Pooled SCM



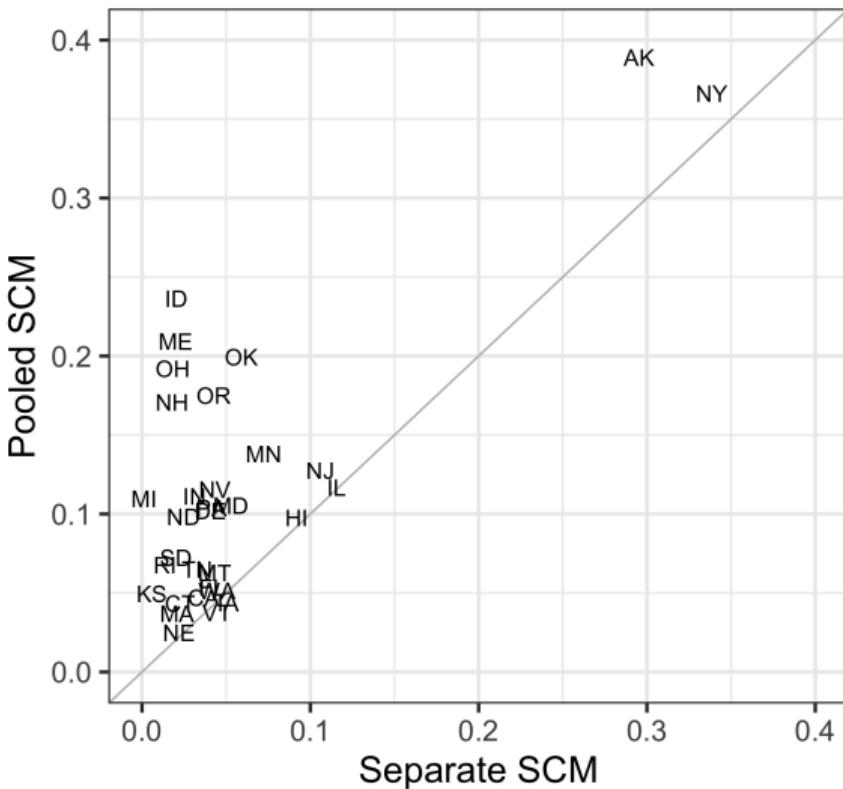
$$\min_{\Gamma} \left\| \frac{1}{J} \sum_{j=1}^J \text{State Balance}_j \right\|_2^2$$

## Pooled SCM



$$\min_{\Gamma} \|\text{Avg Balance}\|_2^2$$

## SCM pre-treatment imbalance by state



- Avg Balance is better
- but State Balance is worse.

Which matters more?

Generalization of parallel trends: Linear Factor Model

$$Y_{it}(\infty) = \phi_i' \mu_t + \varepsilon_{it}$$

# Which matters more?

## Generalization of parallel trends: Linear Factor Model

$$Y_{it}(\infty) = \phi_i' \mu_t + \varepsilon_{it}$$

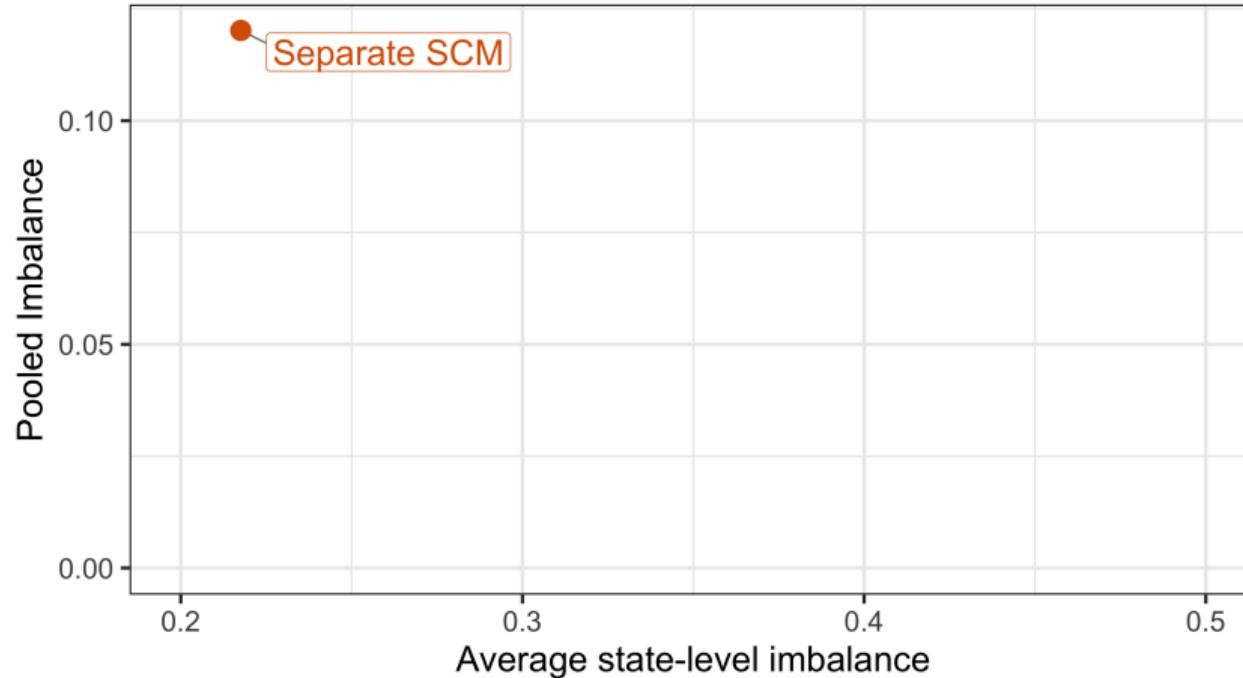
### Error for ATT

$$\left| \widehat{\text{ATT}}_0 - \text{ATT}_0 \right| \lesssim \|\bar{\mu}\|_2 \|\text{Avg Balance}\|_2 + S \sqrt{\sum_{j=1}^J \|\text{State Balance}_j\|_2^2} + \sqrt{\frac{\log NJ}{T}}$$

Level of **heterogeneity over time** is important

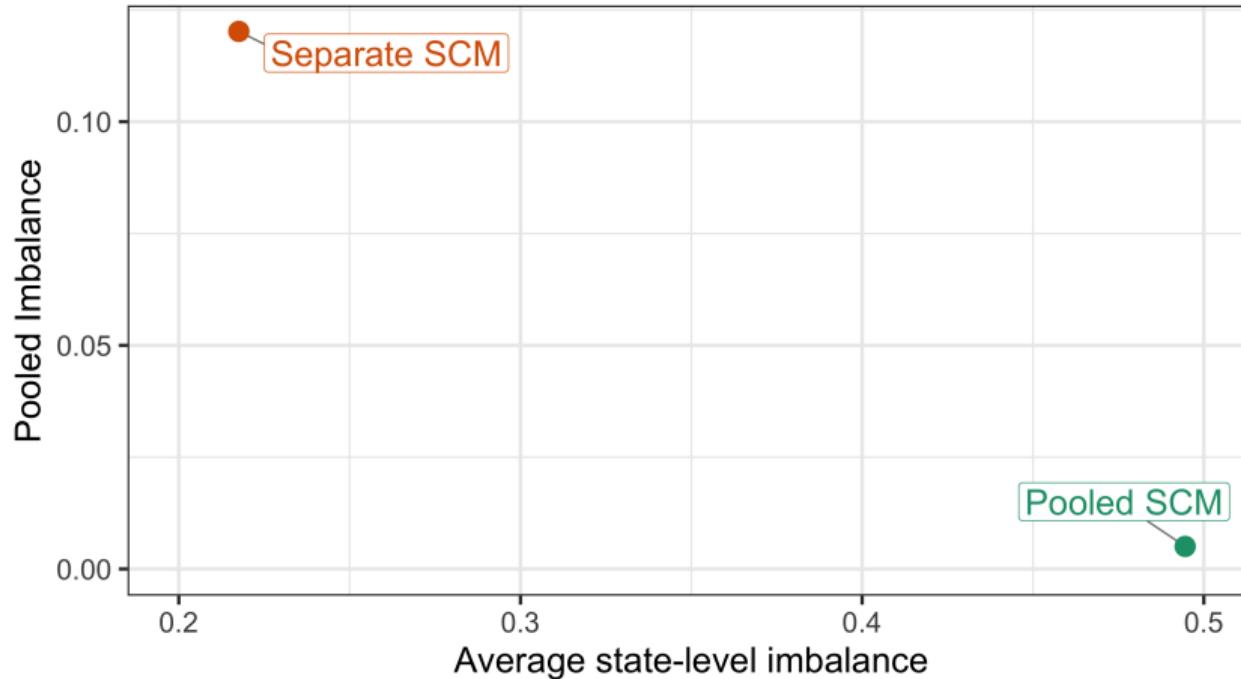
- $\bar{\mu}$  is the **average factor value** → importance of **Avg Balance**
- $S$  is the **factor standard deviation** → importance of **State Balance**
- Special case: unit fixed effects, only **Avg Balance** matters

## Balance possibility frontier



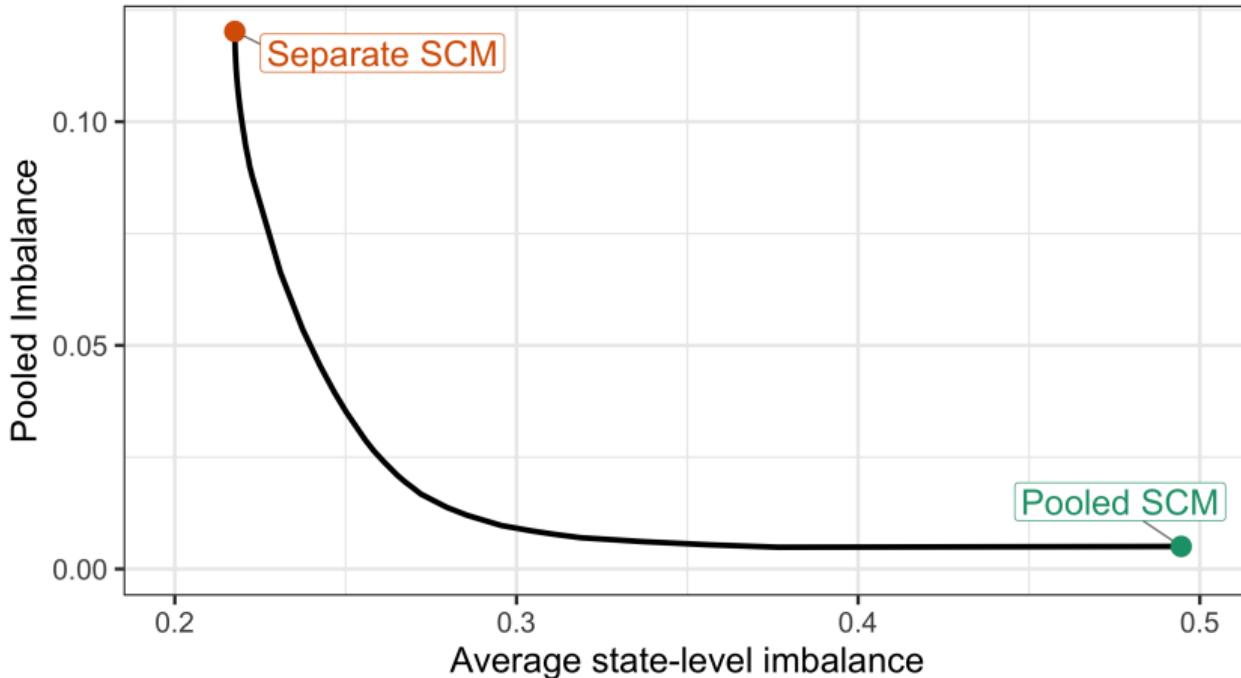
$$\min_{\Gamma} \frac{1}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$

## Balance possibility frontier



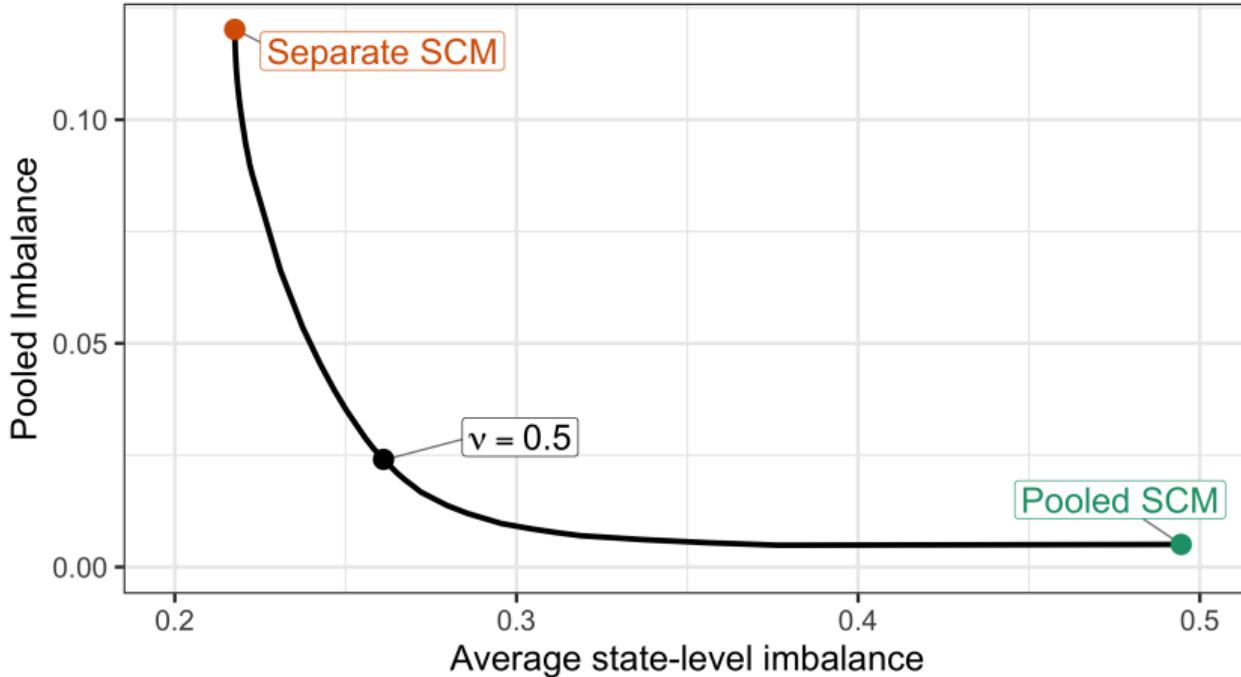
$$\min_{\Gamma} \|\text{Avg Balance}\|_2^2$$

## Balance possibility frontier



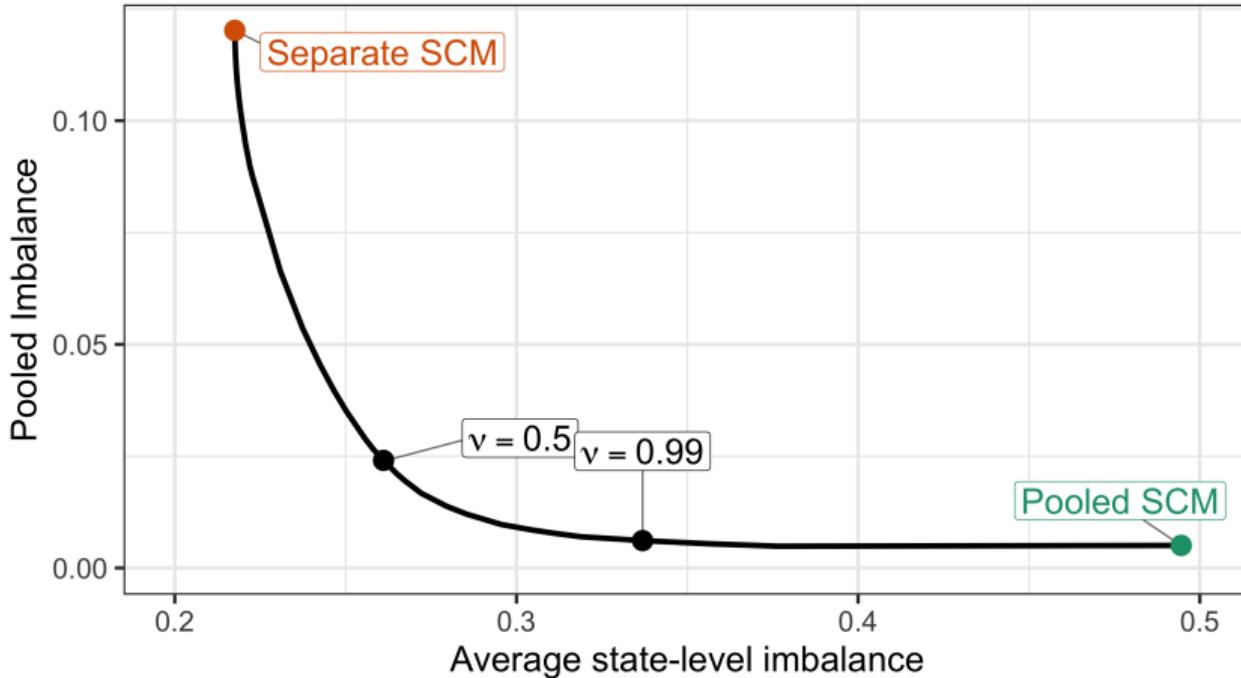
$$\min_{\Gamma} \quad \nu \|\text{Avg Balance}\|_2^2 + \frac{1-\nu}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$

## Balance possibility frontier



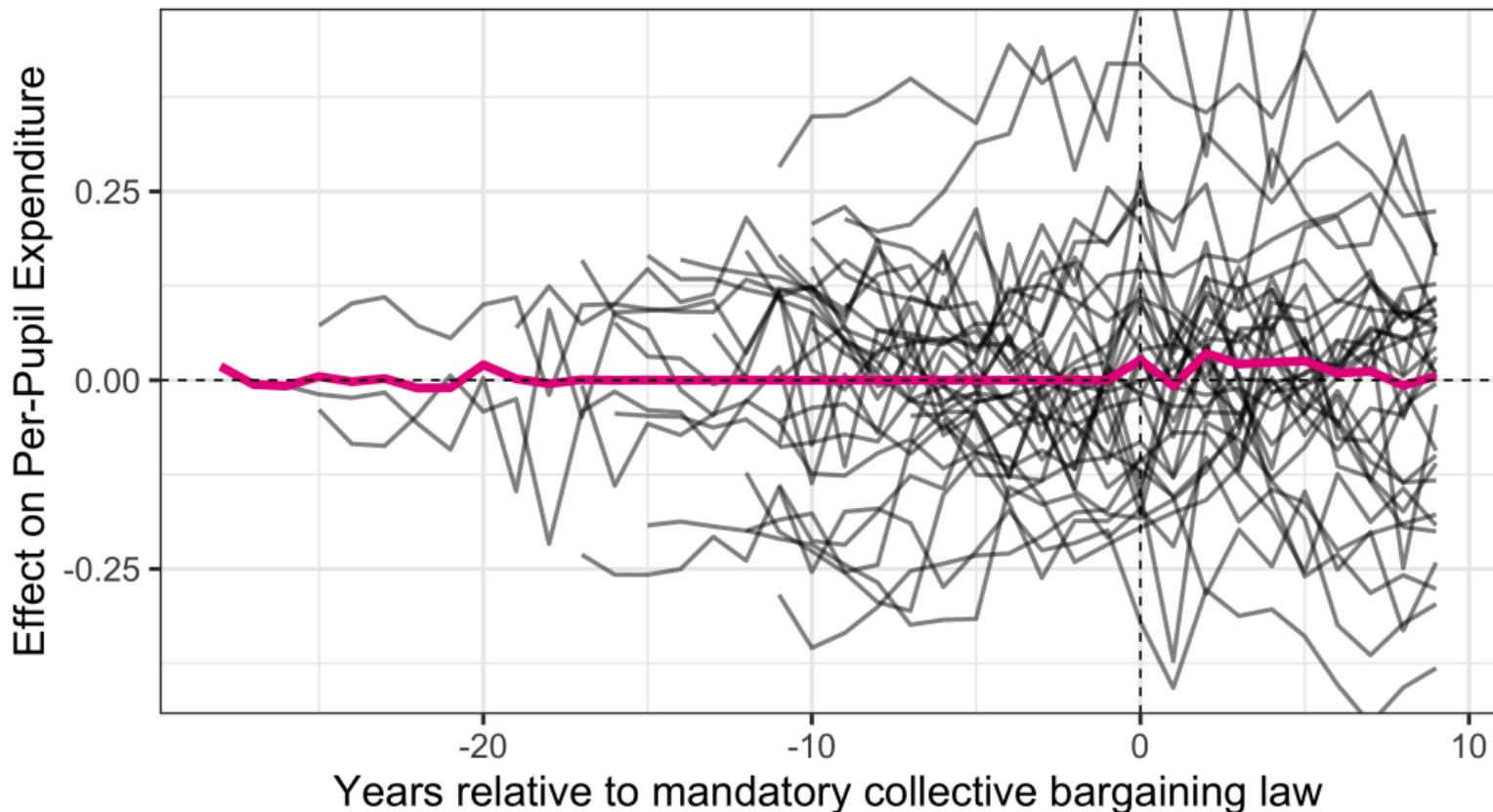
$$\min_{\Gamma} \nu \|\text{Avg Balance}\|_2^2 + \frac{1-\nu}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$

## Balance possibility frontier

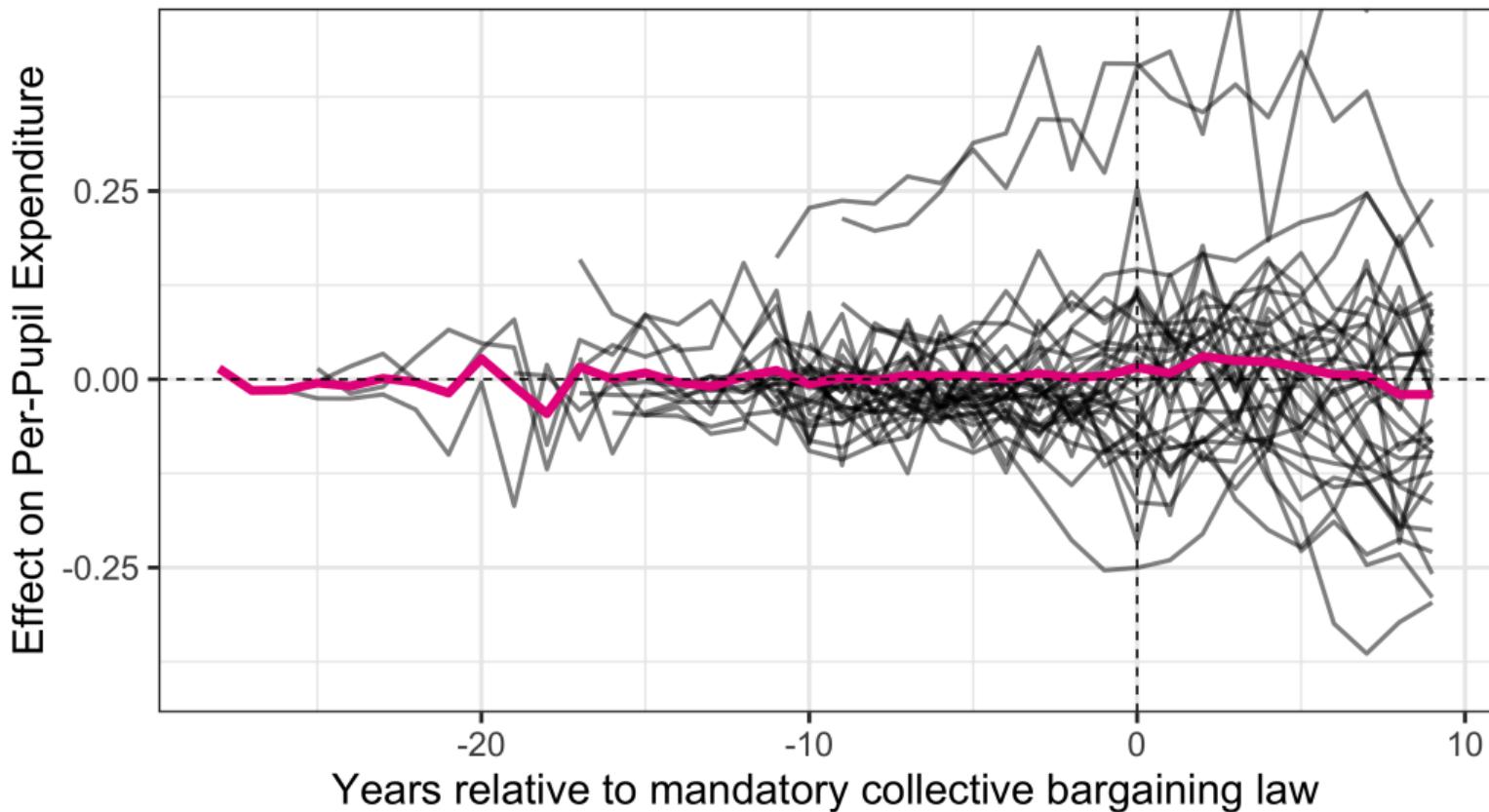


$$\min_{\Gamma} \quad \nu \|\text{Avg Balance}\|_2^2 + \frac{1-\nu}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2$$

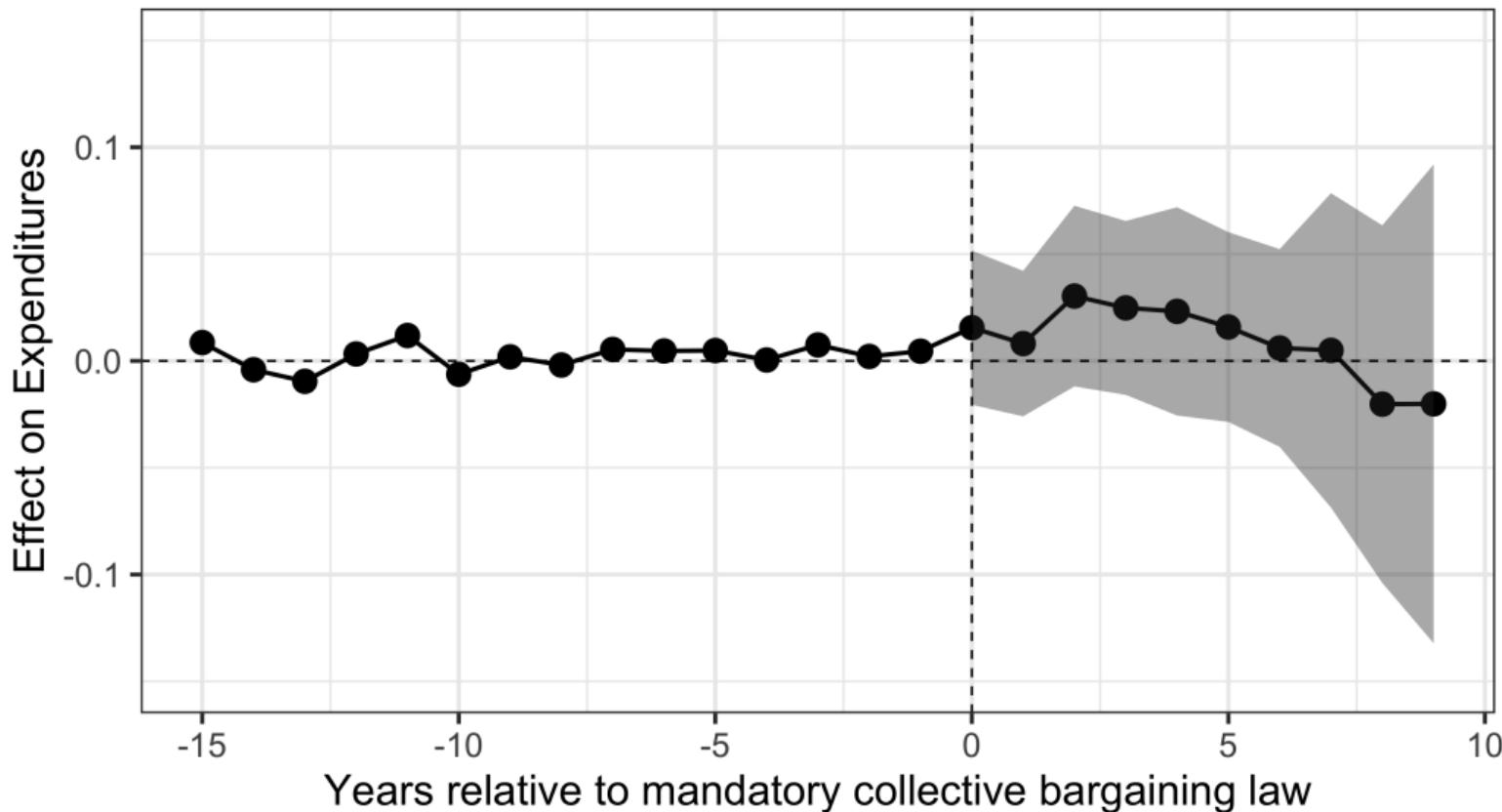
## Pooled SCM



## Partially Pooled SCM



## Partially Pooled SCM



# Intercept Shifts

## Intercept-Shifted SCM

Adjust for level differences by adding an intercept to the optimization problem

[Doudchenko and Imbens, 2017; Ferman and Pinto, 2018]

$$\hat{Y}_{j,T_j+k}^*(\infty) = \hat{\alpha}_j + \sum_i \hat{\gamma}_{ij}^* Y_{i,T_j+k}$$

## Intercept-Shifted SCM

Adjust for level differences by adding an intercept to the optimization problem

[Doudchenko and Imbens, 2017; Ferman and Pinto, 2018]

$$\hat{Y}_{j,T_j+k}^*(\infty) = \hat{\alpha}_j + \sum_i \hat{\gamma}_{ij}^* Y_{i,T_j+k}$$

Solution: De-meaning by pre-treatment average  $\bar{Y}_{i,T_j}^{\text{pre}}$

## Intercept-Shifted SCM

Adjust for level differences by adding an intercept to the optimization problem

[Doudchenko and Imbens, 2017; Ferman and Pinto, 2018]

$$\hat{Y}_{j,T_j+k}^*(\infty) = \hat{\alpha}_j + \sum_i \hat{\gamma}_{ij}^* Y_{i,T_j+k}$$

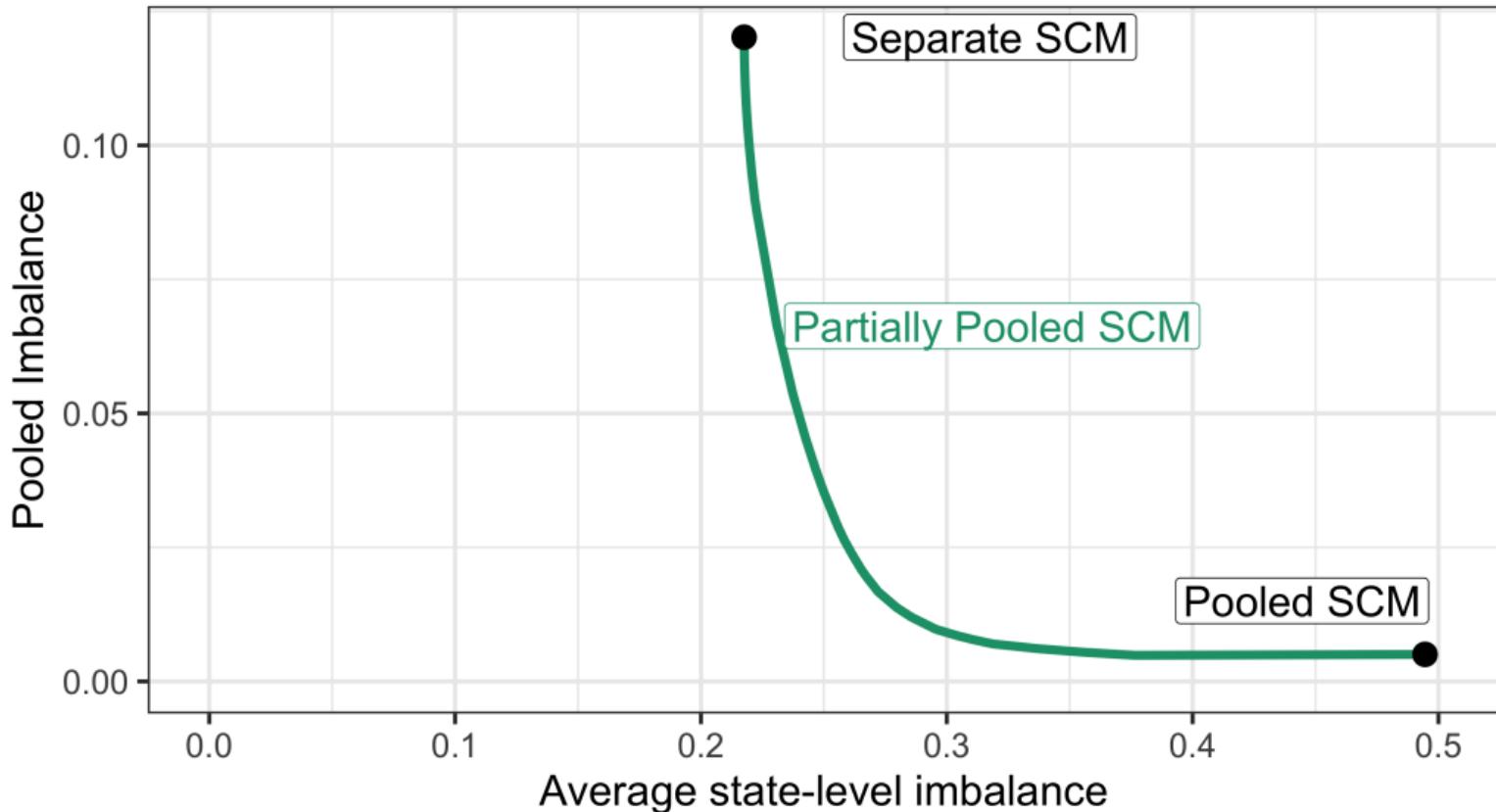
Solution: De-meaning by pre-treatment average  $\bar{Y}_{i,T_j}^{\text{pre}}$

Treatment effect estimate is **weighted difference-in-differences**

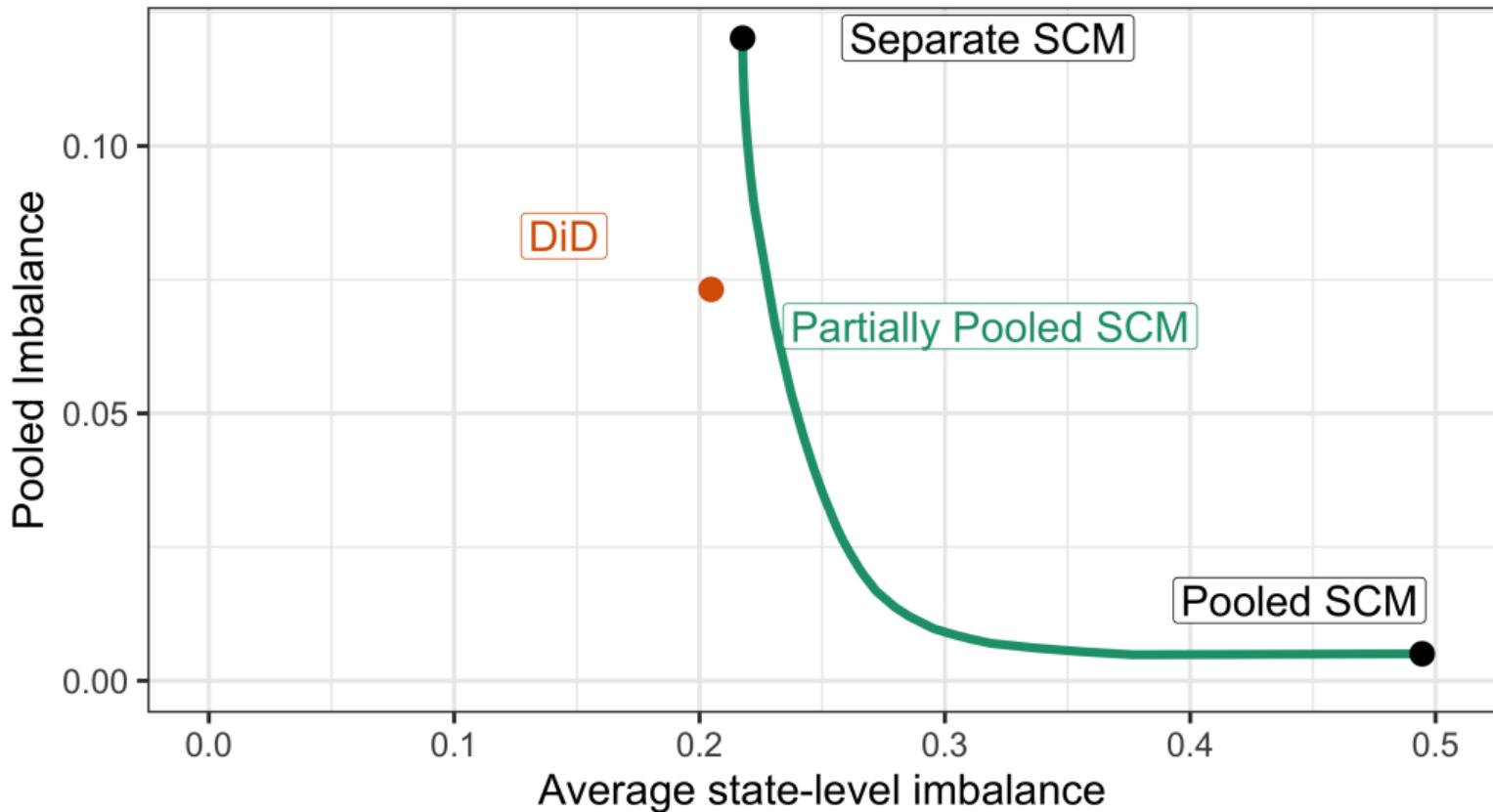
$$\hat{\tau}_{jk}^{\text{aug}} = \left( Y_{j,T_j+k} - \bar{Y}_{j,T_j}^{\text{pre}} \right) - \sum_{i=1}^N \hat{\gamma}_{ij}^* \left( Y_{i,T_j+k} - \bar{Y}_{i,T_j}^{\text{pre}} \right)$$

- Uniform weights recover “stacked” DiD [Abraham and Sun, 2018]
- Similar in form to P-score weighted DiD [Abadie, 2005; Callaway and Sant'Anna, 2018]

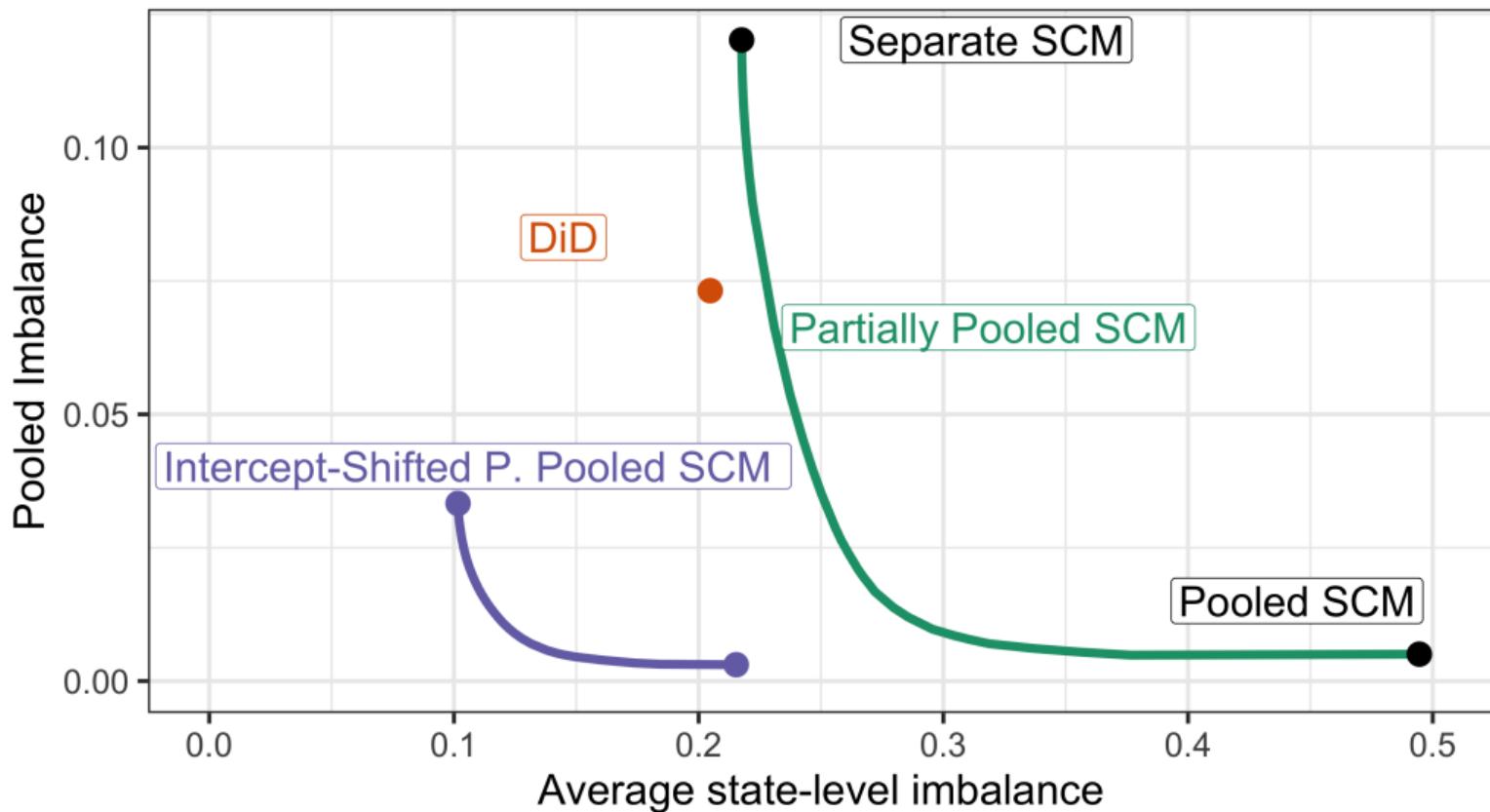
## Balance possibility frontier



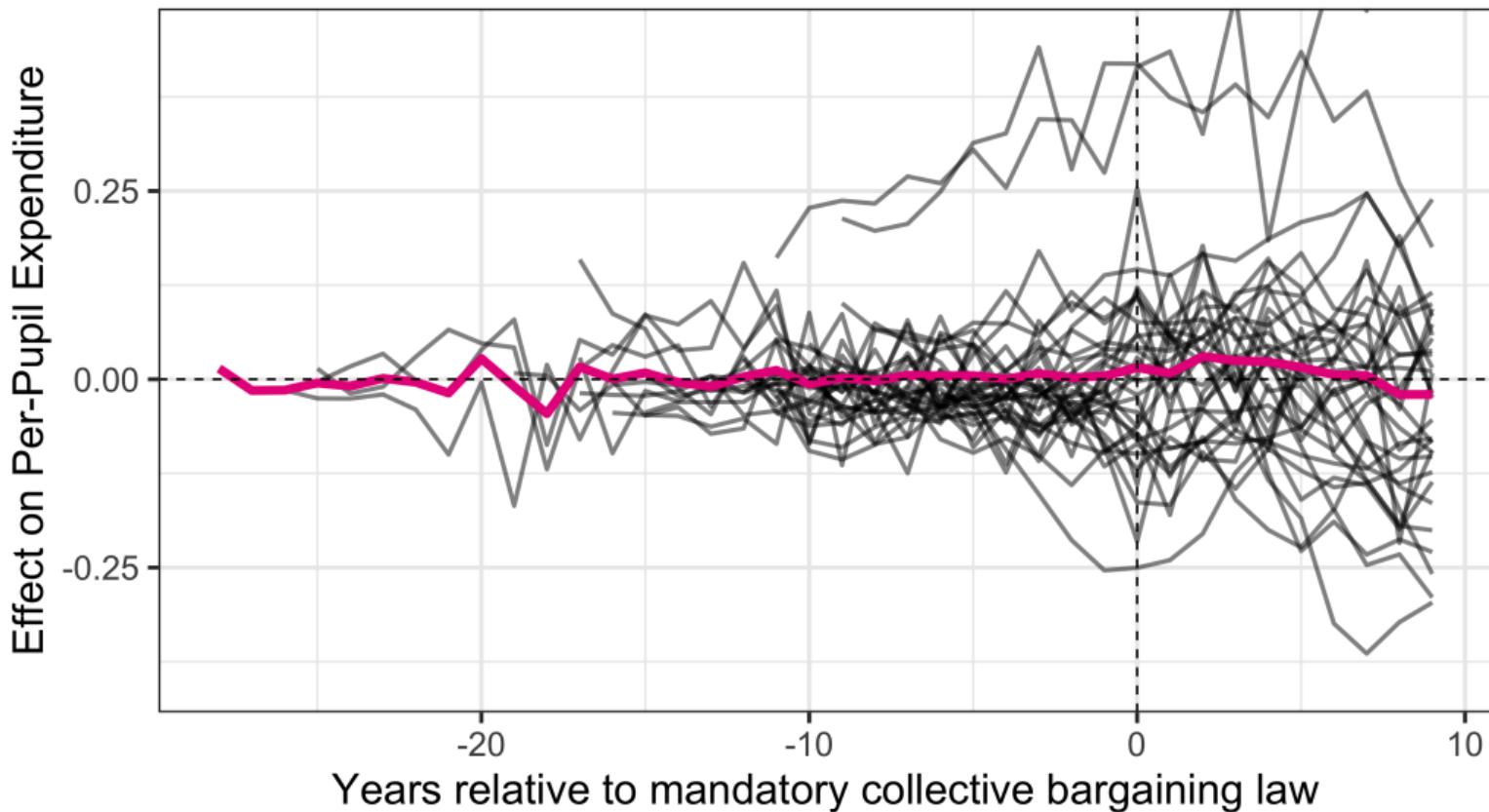
## Balance possibility frontier



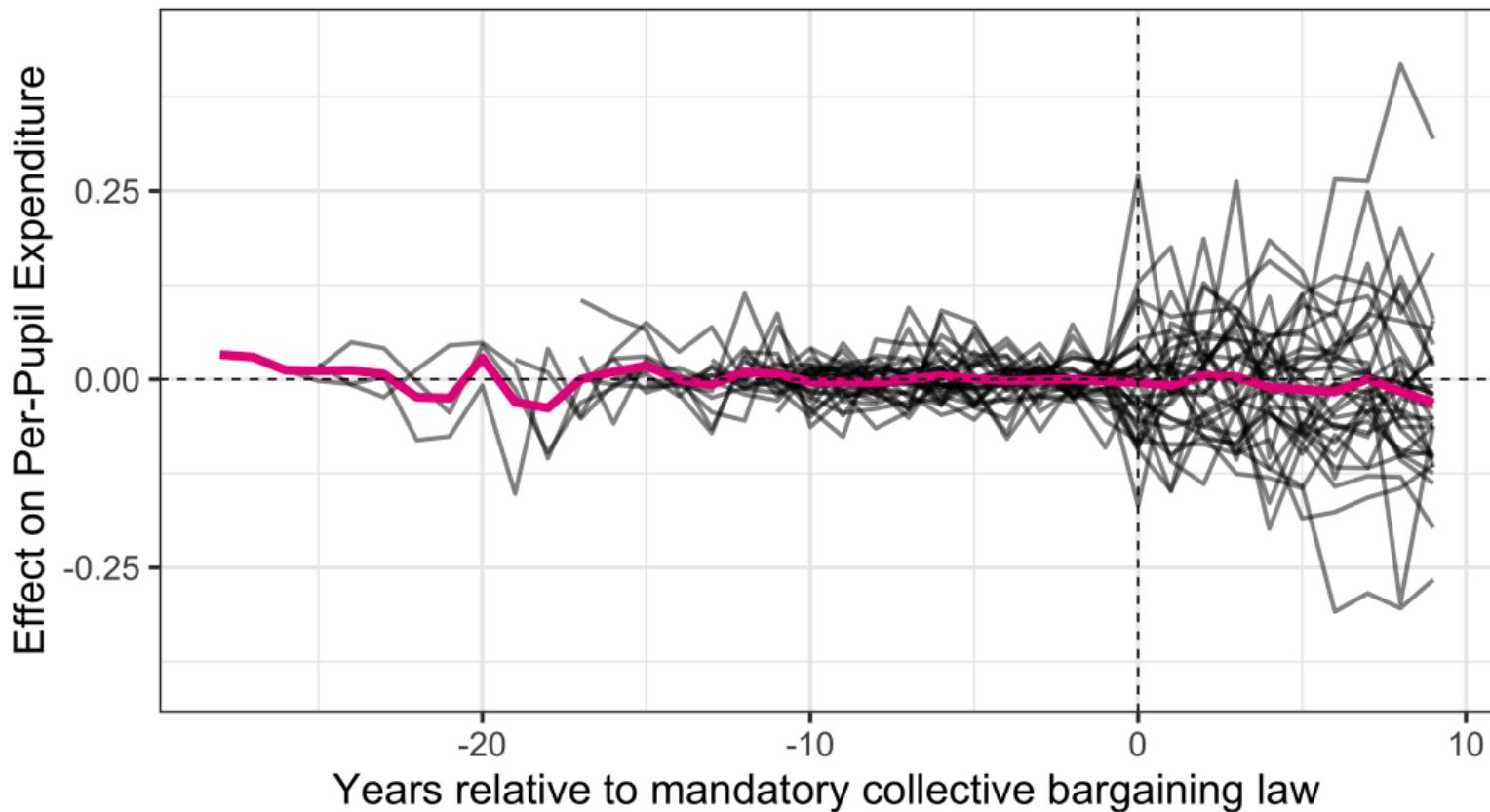
## Balance possibility frontier

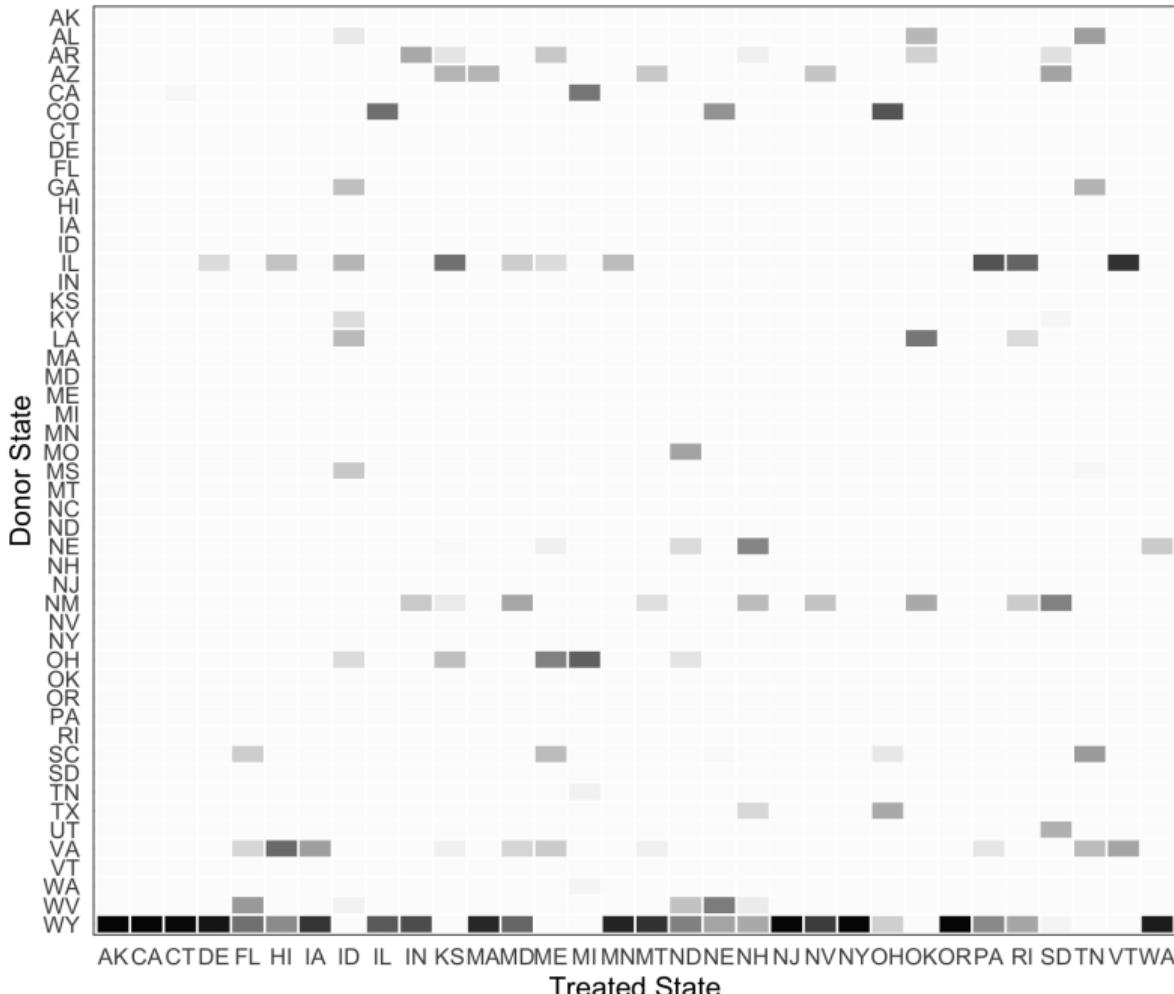


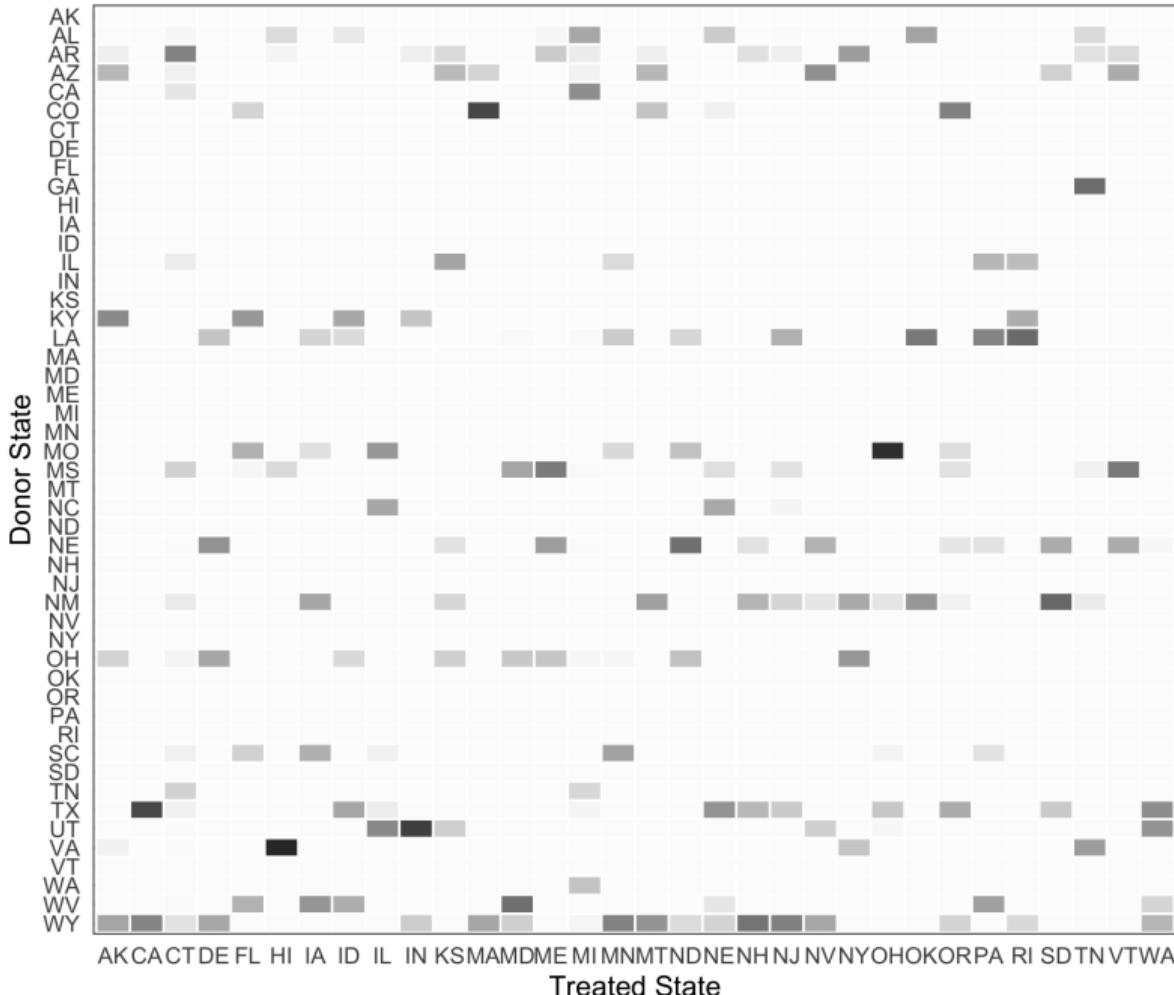
## Partially Pooled SCM



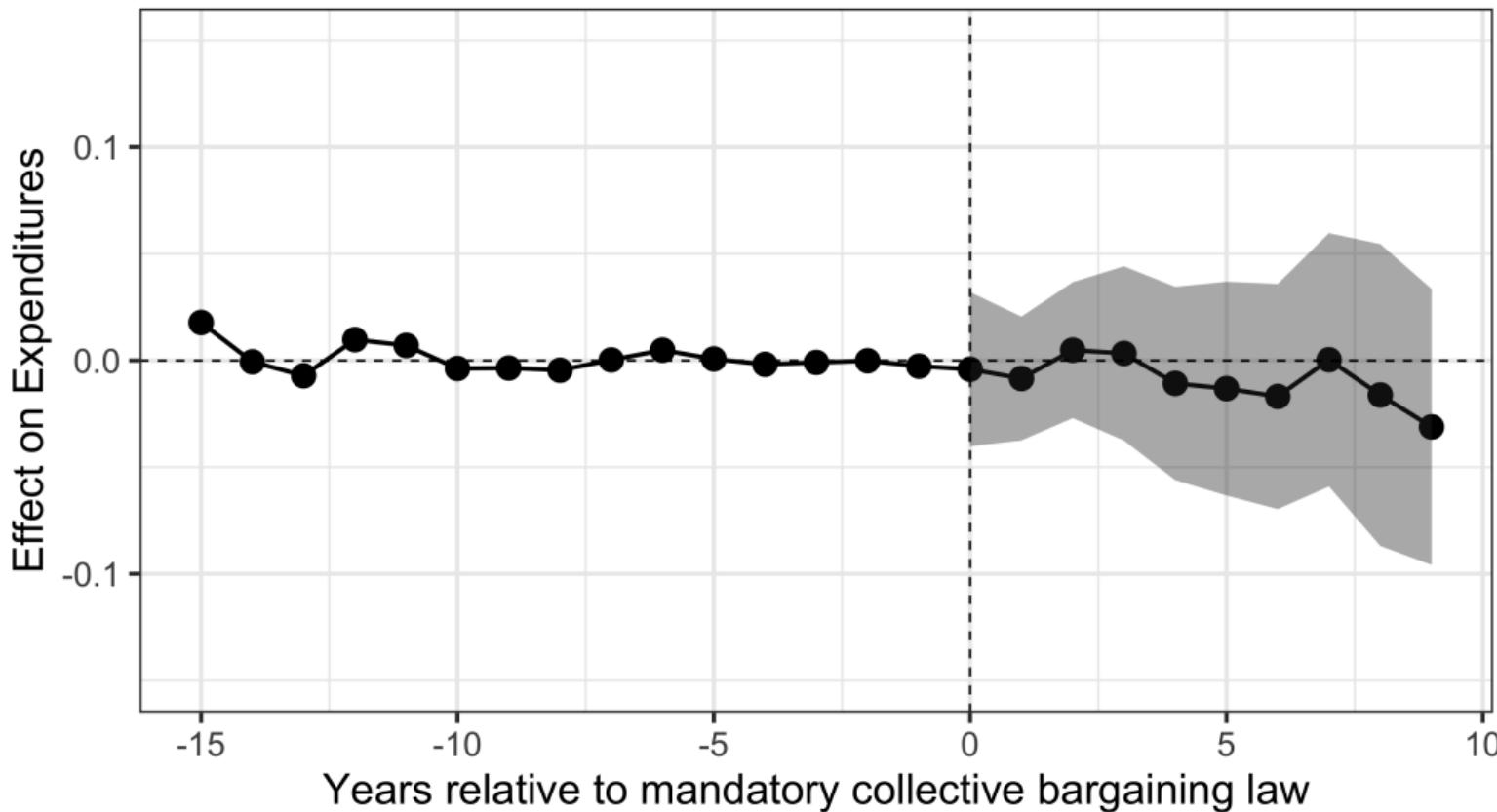
## Intercept-Shifted P. Pooled SCM







## Intercept-Shifted P. Pooled SCM



## Recap

*This paper:* Extend SCM to staggered adoption

- Find weights that control State Balance and Avg Balance
- Include an intercept to adjust for level differences
- *Under the hood:* Dual shrinkage; connection to (generalized) IPW

# Recap

*This paper:* Extend SCM to staggered adoption

- Find weights that control State Balance and Avg Balance
- Include an intercept to adjust for level differences
- Under the hood: Dual shrinkage; connection to (generalized) IPW

*Extras:*

- Incorporating auxiliary covariates
- Weighted bootstrap confidence intervals

*In progress:*

- Extend to unbalanced panels
- Sensitivity analysis

# Recap

*This paper:* Extend SCM to staggered adoption

- Find weights that control State Balance and Avg Balance
- Include an intercept to adjust for level differences
- Under the hood: Dual shrinkage; connection to (generalized) IPW

*Extras:*

- Incorporating auxiliary covariates
- Weighted bootstrap confidence intervals

*In progress:*

- Extend to unbalanced panels
- Sensitivity analysis

Thank you!

<https://arxiv.org/abs/1912.03290>

<https://github.com/ebenmichael/augsynth>

# Appendix

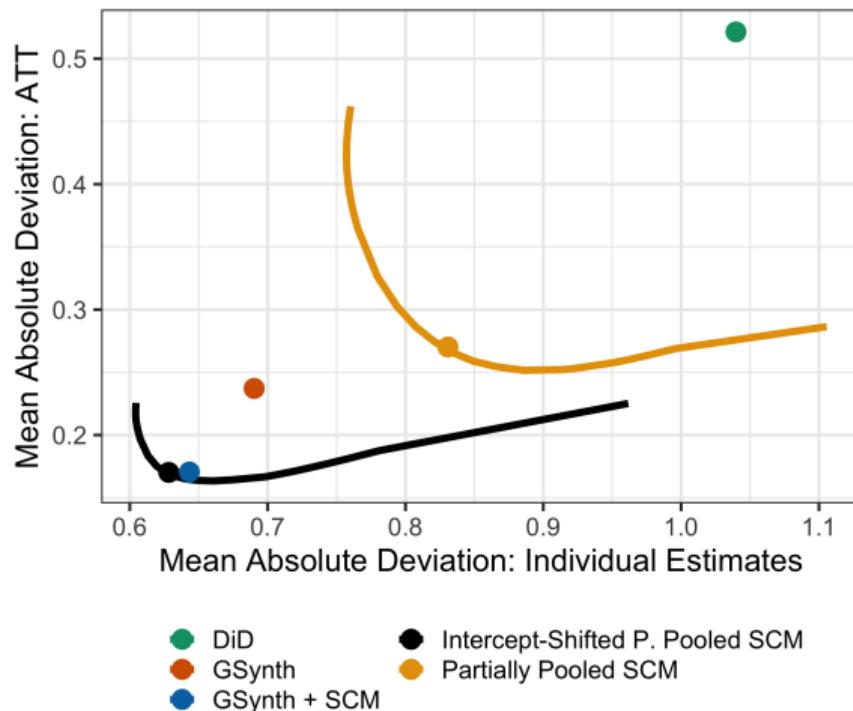
# Random effects AR simulation: level of pooling really matters

## Calibrated sim study: Random Effects AR

- Fit random effects model  
[Gelman and Hill, 2007]

$$Y_{it} = \sum_{k=1}^3 \rho_{tk} Y_{i(t-k)} + \varepsilon_{it}$$
$$\rho_t \sim N(\bar{\rho}, \Sigma)$$

- $\pi_i = \text{logit} \left( \theta_0 + \theta_1 \sum_{k=-3}^1 Y_{i(t-k)} \right)$



# DGP is FE Model: Intercept-Shifting + Partial Pooling performs well

## Calibrated sim study: FE

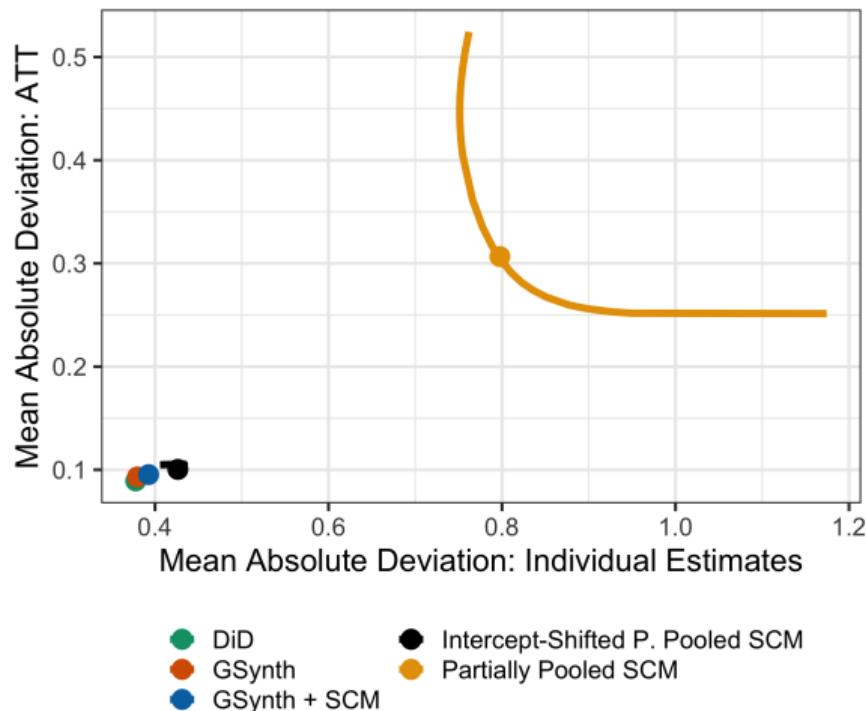
- Fit FE model

$$Y_{it} = \text{unit}_i + \text{time}_t + \varepsilon_{it}$$

- $\text{unit}_i \sim \widehat{\text{Normal}}$

- $\pi_i = \text{logit}(\theta_0 + \theta_1 \cdot \text{unit}_i)$

Event study is correct model



# DGP is Factor Model: Intercept-Shifting + Partial Pooling does best

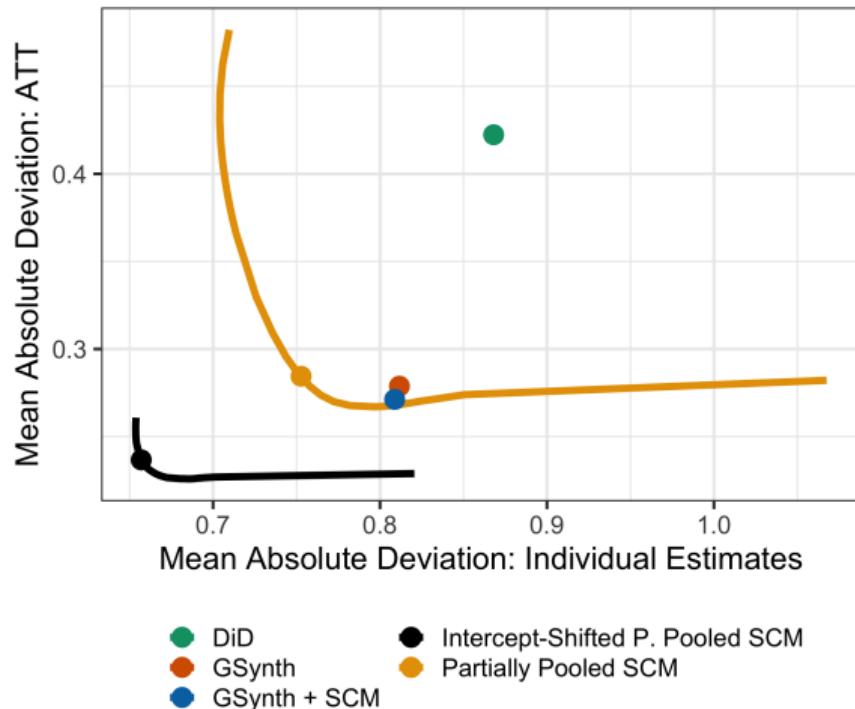
## Calibrated sim study: Factor

- Fit gsynth [Xu, 2017]

$$Y_{it} = \text{unit}_i + \text{time}_t + \phi'_i \mu_t + \varepsilon_{it}$$

- $\{\text{unit}_i, \phi_i\} \sim \widehat{\text{MVN}}$

- $\pi_i = \text{logit}(\theta_0 + \theta_1(\text{unit}_i + \phi_{i1} + \phi_{i2}))$



Heuristic for  $\nu$ : fit with  $\nu = 0$  then choose

$$\hat{\nu} = \frac{\frac{1}{\sqrt{L}} \|\text{Avg Balance}\|_2}{\sqrt{\frac{1}{J} \sum_{j=1}^J \|\text{State Balance}_j\|_2^2}}$$

## References |

- Abadie, A. (2005). Semiparametric difference-in-differences estimators. *The Review of Economic Studies*, 72(1):1–19.
- Abraham, S. and Sun, L. (2018). Estimating dynamic treatment effects in event studies with heterogeneous treatment effects.
- Athey, S. and Imbens, G. W. (2018). Design-based analysis in difference-in-differences settings with staggered adoption. Technical report, National Bureau of Economic Research.
- Callaway, B. and Sant'Anna, P. H. C. (2018). Difference-in-Differences With Multiple Time Periods and an Application on the Minimum Wage and Employment.
- Doudchenko, N. and Imbens, G. W. (2017). Difference-In-Differences and Synthetic Control Methods: A Synthesis. *arxiv* 1610.07748.
- Ferman, B. and Pinto, C. (2018). Synthetic controls with imperfect pre-treatment fit.
- Gelman, A. and Hill, J. (2007). *Data Analysis Using Regression and Multilevel/Hierarchical Models*.

## References II

- Hoxby, C. M. (1996). How teachers' unions affect education production. *The Quarterly Journal of Economics*, 111(3):671–718.
- Imai, K. and Kim, I. S. (2019). On the use of two-way fixed effects regression models for causal inference with panel data.
- Paglayan, A. S. (2019). Public-sector unions and the size of government. *American Journal of Political Science*, 63(1):21–36.
- Xu, Y. (2017). Generalized Synthetic Control Method: Causal Inference with Interactive Fixed Effects Models. *Political Analysis*, 25:57–76.