

1.9. Fixed point Method:

$$\begin{cases} \partial_t u = -\mathcal{J}u + f(u) & \mathcal{J} = -\sum_{i,j} (a_{ij} \partial x_i) \partial x_j \\ u|_{t=0} = g \end{cases}$$

Banach fixed point th:

X is Banach (complete + normed linear space), $A: X \rightarrow X$ nonlinear,

if $\exists \gamma < 1$ s.t. $\|A[u] - A[v]\| \leq \gamma \|u - v\|, \forall u, v \in X$

$\Rightarrow A$ has fixed point $\exists u$ s.t. $Au = u$

proof: let $v = Au \in X$

$$\|A[u] - A^2[u]\| \leq \gamma \|u - A[u]\|$$

$$\|A^n[u] - A^{n+1}[u]\| \leq \|A^n[u] - A^{n+1}[u]\| + \|A^{n+1}[u] - A^{n+2}[u]\| + \dots + \|A^{n+m}[u] - A^{n+m+1}[u]\|$$

$$\leq \gamma^n \|u - A[u]\| + \gamma^{n+1} \|u - A[u]\| + \dots + \gamma^{n+m} \|u - A[u]\|$$

$$\leq \frac{1}{1-\gamma} \gamma^n \|u - A[u]\|$$

$\therefore \{A^n[u]\}_{n=0}^{\infty}$ is Cauchy sequence, $\forall u \in X$.

$\therefore \exists w \in X$ s.t. $A^n[u] \rightarrow w, A^{n+1}[u] \rightarrow A[w] = w$; 这个Cauchy列的极限就是fixed point

Example: DDE: $\begin{cases} \dot{x}(t) = f(t, x) \\ x(0) = a \end{cases}$, f bounded, Lipschitz cts in Banach space X

let $X = C([0, T]) \cap \{x(0) = a\}$, X is Banach space, x is the function of X

let $A[x](t) = \int_0^t f(s, x(s)) ds$; $A[x](t)' = f(t, x(t))$

$$\begin{aligned} \text{then: } |A[x](t) - A[\tilde{x}](t)| &\leq \int_0^t |f(s, x(s)) - f(s, \tilde{x}(s))| ds \\ &\leq L \cdot T \cdot \sup_{s \in [0, T]} |x(s) - \tilde{x}(s)| \end{aligned}$$

$$\therefore \|A[x](t) - A[\tilde{x}](t)\| \leq L \cdot T \cdot \|x - \tilde{x}\|, \text{ let } T < \frac{1}{L}$$

在 X 中, $A^n[x](t) \rightarrow y, A^{n+1}[x](t) \rightarrow A[y](t) = y$

Q: 在 X 中, $A[x](t)$ 就是ODE解, 为什么要去求 $A^{n+1}[x](t) \rightarrow y$

{ let $T < \frac{1}{L}$, restrict X , 求出的是局部解吧, y 在 $\mathbb{R}^n \ni X$, 并不一定还是解 }

$$\text{Th: } \begin{cases} u_t = -\mathcal{J}u + f(u) & f: \mathbb{R} \rightarrow \mathbb{R} \text{ Lipschitz cts, } |f(z)| \leq C(1+|z|) \\ u(t=0) = g \\ u|_{\partial\Omega} = 0 \end{cases} \text{ then:}$$

$$(1) \bar{u} \in L^2_0 H^1_0, \bar{u}' \in L^2 H^1, \Rightarrow \bar{u} \in C_t L^2; (2) \frac{d}{dt} \|\bar{u}\|_{L^2}^2 = 2\langle \bar{u}, \bar{u}' \rangle, \max_{0 \leq t \leq T} \|\bar{u}\|_{L^2} \leq C(\|\bar{u}\|_{L^2 H^1_0} + \|\bar{u}'\|_{L^2 H^1})$$

\downarrow
EpoXu

recall: $C_c^k(U) = \{v \in C^k(U) : \lim_{x \rightarrow \partial U} |v(x)| = 0\}$

$C_c^k(U) = \{v \in C^k(U) : \exists \text{ cpt } K \subseteq U, \text{ s.t. } v=0 \text{ in } K^c\}$ Bp support is cpt

$H^k(U) = \{u \in L^2_{loc}(U) : D^\alpha u \in L^2(U) \text{ for } |\alpha| \leq k\}$

$H^k(U) = C_c^\infty$ closure under $\|\cdot\|_{H^k(U)}$

$$\|u\|_{H^k(U)} = \sum_{|\alpha| \leq k} \|D^\alpha u\|_{L^2(U)}$$

$$\|f\|_{H^1(U)} = \int_U (|f(x)| + |\nabla f(x)|) dx, \quad L_{loc}: \text{在 } \partial U \text{ 附近 } \int_K |f| du < \infty \quad \forall \text{ cpt } K \subseteq X$$

Proof: Let $X = C([0, T], L^2(U))$

1: $\tilde{w} = A[u]$ is weak solution of: $\begin{cases} \partial_t w = -\mathcal{L}w + f(u) \\ w|_{t=0} = g \end{cases}$ Bp: $\int_U \phi \mathcal{L}u dx = \int_U \phi f dx \quad \forall \text{ test } \phi$
given $\mathcal{L}u = f$

$$\int_0^T \int_U f^2(u(t, x)) \leq \int_0^T \int_U C(1+u^2) \leq C(1 + \|u\|_{L^2_t L^\infty_x}^2) \leq C(1 + \|u\|_{L^2_t H^1_x}^2) < \infty$$

$\therefore f(u(t, x)) \in L^2_t L^2_x$ w.e. exist

2. T small enough, $u \rightarrow w = A[u]$ is contradiction

设: $w_1 = A[u], w_2 = A[\tilde{u}]$ 均为解

$$\partial_t u + \mathcal{L}u = f(u)$$

$$\Rightarrow \int \partial_t u \cdot v + \int \mathcal{L}u \cdot v = \int f(u) \cdot v$$

A和B是什么?

consider weak solution: w_1, w_2 为拟线性函数. $\forall u \in H^1_0, 0 \leq t \leq T$

$$\begin{cases} (w_1, v) + B[w_1, v] = (f(u), v) \\ (w_2, v) + B[w_2, v] = (f(\tilde{u}), v) \end{cases} \quad ; \quad \int \mathcal{L}w_1 v = \int \mathcal{L}w_2 v + (\sum b_i \partial_i x_i u) v, \quad (1) \quad \int \mathcal{L}u v = 0$$

$$(w_1 - w_2, v) + B[w_1 - w_2, v] = (f(u) - f(\tilde{u}), v)$$

$$\begin{aligned} ? \therefore \frac{d}{dt} \|w_1 - w_2\|_{L^2}^2 + \theta \|\tilde{w}_1 - \tilde{w}_2\|_{H^1_0}^2 &\leq L \|u - \tilde{u}\|_{L^2} \|\tilde{w}_1 - \tilde{w}_2\|_{L^2} \leq \frac{L}{2\epsilon} \|u - \tilde{u}\|_{L^2}^2 + \frac{L\epsilon}{2} \|w_1 - w_2\|_{L^2}^2 \\ &\leq \frac{L}{2\epsilon} \|u - \tilde{u}\|_{L^2}^2 + \frac{L\epsilon C}{2} \|w_1 - w_2\|_{H^1_0}^2 \end{aligned}$$

L : Lipschitz constant. C : Poincaré const

choose $\epsilon: \frac{\epsilon L C}{2} \leq \theta$

$$\text{then: } \frac{d}{dt} \|w_1 - w_2\|_{L^2}^2 \leq \frac{L}{2\epsilon} \|u - \tilde{u}\|_{L^2}^2$$

$$\therefore \|w_1 - w_2\|_{L^2}^2 \leq \int_0^T \frac{L}{2\epsilon} \|u - \tilde{u}\|_{L^2}^2 dt \leq \frac{LT}{2\epsilon} \|u - \tilde{u}\|_{L^\infty}^2; \text{ 在 } \mathbb{R}^d \text{ 中 } T < \frac{4\epsilon}{L} \text{ 时 } \frac{L}{2\epsilon} < \frac{1}{2} \text{ 不是 fixed point}$$

$$\text{Bp } \|A[u] - A[\tilde{u}]\|_{L^2}^2 \leq \gamma \|u - \tilde{u}\|_{L^\infty}^2$$

$$\|A[u] - A[\tilde{u}]\|_{L^2} \leq \gamma \|u - \tilde{u}\|_{L^\infty}, \quad \gamma < 1$$

$\therefore \exists$ fixed point, u_0 . Bp 为不动点解

3. Uniqueness: (Gronwall)

$$\|u - \tilde{u}\|_{L^2}^2 \leq \int_0^T \frac{L}{2\epsilon} \|u - \tilde{u}\|_{L^2}^2 dt, \text{ 设 } \exists u'_0 \text{ 也为解 } u'_0 - u \text{ 代入 } \rightarrow 0$$

Hamilton-Jacobi equation: $\partial_t U(t, x) + H(\partial_x U, t, x) = 0 \quad (*)$

H : hamilton function 系统总能量, U : 作用量, x, t 坐标, 时间

换元 (method of char) : $\begin{cases} x = \eta(s), t = s \\ z(s) = U(t, x) = U(s, \eta(s)) \\ p(s) = \partial_x U(t, x) = \partial_x U(s, \eta(s)) \end{cases} \Rightarrow \partial_t z(s) + H(p(s), s, \eta(s)) = 0$ 只剩 s 变量

$\dot{p}(s) = \partial_x \partial_t U(s, \eta(s)) + \partial_x \partial_x U(s, \eta(s)) \cdot \dot{\eta}(s)$ 此处 ∂_t, ∂_x 表示对第 i 个 slot 求导

or $\partial_t \partial_x U(t, x) = \partial_x (-H(\partial_x U, t, x)) = -\partial_x H(p(s), s, \eta(s))$

$\dot{\eta}(s) = \partial_p H(p(s), s, \eta(s))$

since: 由 $\dot{p}(s)$ 的不同表示为 $\partial_x \partial_t U + \partial_x^2 U \cdot \dot{\eta}(s) + \partial_x H = 0$

对 $(*)$ 整体求 x 的偏导: $\partial_x \partial_t U + \partial_p H \cdot \partial_x U + \partial_x H = 0$

$\Rightarrow \dot{\eta}(s) = \partial_p H$

$\dot{z}(s) = \partial_t U + \partial_x U(s, \eta(s)) \cdot \dot{\eta}(s)$

$= p(s) \cdot \dot{\eta}(s) - H(p(s), s, \eta(s)) = p(s) \cdot \partial_p H(p(s), s, \eta(s)) - H(p(s), s, \eta(s))$

\Rightarrow Hamilton ODE: $\begin{cases} \partial_t z(s) + H(p(s), s, \eta(s)) = 0 \\ \dot{\eta}(s) = \partial_p H(p(s), s, \eta(s)) \\ \dot{p}(s) = -\partial_x H(p(s), s, \eta(s)) \end{cases}$

若 $\partial_t U = 0$, energy not depends on time: conservative (物理意义)

$\dot{H}(s) = \partial_p H \cdot \dot{p}(s) + \partial_x H \cdot \dot{\eta}(s)$

$= \partial_p H \cdot (-\partial_x H) + \partial_x H \cdot \partial_p H = 0$

注意: 为啥 $\dot{p}(s) = \partial_t \partial_x U(s, \eta(s)) + \partial_x^2 U(s, \eta(s)) \cdot \dot{\eta}(s)$

$= \partial_t \partial_x U(t, x) = \partial_x (-H(\partial_x U, t, x)) = -\partial_x H(p(s), s, \eta(s))$ 为例:

" $p(s) = \partial_x U(t, x), s = t, \therefore \dot{p}(s) = \partial_t (\partial_x U(t, x))$

另外: 在 $U(t, x)$ 这个表达式中, t 和 x 是没有关系的, 换元的时候 let $x = \eta(s), t = s$, 和原来的式子没关系

$x = \eta(t)$ 不行

Q: 为什么不能 $x = \eta(s), t = s \Rightarrow \dot{\eta}(s) = \partial_t x$

$p(s) = \partial_x U(t, x), s = t, \Rightarrow \dot{p}(s) = \partial_t \partial_x U(t, x)$, 用过 η , 两者有什么区别?

both right, but meaningless if "dx/dt"

Calculus of variation: 接下来 L 均表示 Lagrangian,

let $L(q, \dot{q}, t)$ 表示 Lagrangian function; q, \dot{q}, t 是开式变量, $q = w(s), \dot{q} = \dot{w}(s), t = s$ 代入本问题

$$I[w] = \int_0^t L(\dot{w}(s), w(s), s) ds; \quad q = \dot{w}(s), \dot{q} = \dot{w}(s), t = s \dots \textcircled{1}$$

$$A = \{w \in C^2[0, t]: w(0) = y, w(t) = x\}$$

若要变分问题: $\inf_w I[w]$

let $\tilde{w}(s) = I[w + \varepsilon v], v \in C_0^\infty[0, t], w \in A$

$$\tilde{w}'(s) = \frac{d}{d\varepsilon} \int_0^t L(\dot{w} + \varepsilon \dot{v}, w + \varepsilon v, s) ds = \int_0^t (\partial_{\dot{q}} L) \dot{v} + (\partial_x L) v ds = 0$$

$$= \int_0^t (\partial_{\dot{q}} L) d\varepsilon + \int_0^t (\partial_x L) v ds = (\partial_{\dot{q}} L) v \Big|_0^t + \int_0^t -\partial_s (\partial_{\dot{q}} L) v + (\partial_x L) v ds$$

$$\therefore \underline{-\partial_s (\partial_{\dot{q}} L) + \partial_x L = 0} \text{ since } v|_{\partial C_0^\infty[0, t]} = 0, \quad \leftarrow \text{对 } v \in C_0^\infty \text{ 要满足 } v|_{\partial C_0^\infty} = 0, \text{ 对 } v \in C_0^\infty \text{ 当然也零}$$

[Euler-Lagrange equation] under $\textcircled{1}$.

\Rightarrow Legendre transform 的原因

例: $L(q, \dot{q}, t) = L(q, \dot{q}) = \frac{1}{2} m \dot{q}^2 - \phi(x)$; 求 $I[w] = \int L$ 的不定值, 对应的 $q, x \Rightarrow q, x$ 不是定值, 是一个轨迹, q 与 x 相关

$$\partial_x L = -\phi'(x), \quad \partial_{\dot{q}} L = m \dot{q}$$

代入: $q = \dot{w}(s), \dot{q} = \dot{w}(s)$, then $\partial_x L = -\phi'(w(s)), \partial_{\dot{q}} L = m \cdot \dot{w}(s)$

代入 Euler-Lagrange: $-\partial_s (m \cdot \dot{w}(s)) + [-\phi'(w(s))] = 0$

$$\therefore m \cdot \ddot{w}(s) = -\phi'(w(s))$$

关于 s 的 ODE, 在 ϕ 已知时, $w(s)$ 可求, 代入 $q = \dots, x = \dots$ 可知 q, x 的趋向轨迹

q 和 s 没有关系, consider $L(q, x), q = \dot{w}(s), x = w(s)$ Some $w, s \Rightarrow$ characteristic line