

# Emily P Yang

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<b>Education</b>	<b>Massachusetts Institute of Technology</b>	<b>Cambridge, MA</b>
	Candidate for Bachelor of Science in Mechanical Engineering Relevant Coursework: Design and Manufacturing, Measurement and Instrumentation, Numerical Computation, Dynamics and Controls, Engineering Innovation and Design GPA: 4.9/5.0	Jun '14
<b>Experience</b>	<b>Mechatronics Research Laboratory, MIT</b>	<b>Cambridge, MA</b>
	<i>Undergraduate Researcher</i>	June '12-Sept '12
	<ul style="list-style-type: none"><li>Assessed and re-designed components of an in-pipe leak detection robot with a novel sensing mechanism using SolidWorks and 3D printing</li><li>Conducted experiments to test sensing mechanism and overall system performance</li><li>Performed product research for different electronic and mechanical components compliant with robot specifications, compiled reports, interfaced with manufacturers and vendors</li></ul>	
	<b>Fluidnet Corporation</b>	<b>Amesbury, MA</b>
	<i>Mechanical Engineering Intern</i>	Jan '12-Feb '12
<b>Leadership</b>	<ul style="list-style-type: none"><li>Assisted the Mechanical Engineering team in building and testing prototypes of Fluidnet's original pneumatic-based infusion pumping platform by conducting performance tests and part inspections, analyzing test results, and constructing device subcomponents</li><li>Designed a hand tool to facilitate installation and removal of pumping chamber port using SolidWorks</li></ul>	
	<b>Mechanical Systems Laboratory, University of Delaware</b>	<b>Newark, DE</b>
	<i>Summer Undergraduate Researcher</i>	May '11-Aug '11
	<ul style="list-style-type: none"><li>Assisted in the development of a novel, flapping-wing micro air vehicle (MAV) capable of achieving controlled symmetric and asymmetric in-phase flapping motions</li><li>Optimized the proposed two-layered MAV mechanism using MATLAB, results incorporated into a successfully operational scaled prototype of the mechanism</li><li>Second author for paper presented at the 2012 IEEE International Conference on Robotics and Automation (ICRA) in St. Paul, MN</li></ul>	
	<b>Gordon-MIT Engineering Leadership (GEL) Program</b>	Sept '12-Present
<b>Skills</b>	<ul style="list-style-type: none"><li>Participating in an interactive and experience-based program that aims to hone leadership skills in an engineering context</li></ul>	
	<b>MIT Association of Taiwanese Students (ATS)</b>	Dec '11-Present
	<i>Co-President</i>	
	<ul style="list-style-type: none"><li>Oversee 11 executive board members to coordinate 10-12 campus-wide events per semester that promote appreciation and knowledge of Taiwanese culture, maintain constructive relations with other MIT organizations</li></ul>	
	<b>MIT Undergraduate Practice Opportunities Program (UPOP)</b>	Oct '11-Present
<b>Awards</b>	<ul style="list-style-type: none"><li>Participating in a professional development and engineering practice program preparing students for success in the workplace</li></ul>	
	<b>MIT American Society of Mechanical Engineers (ASME)</b>	Feb '12-Present
	<i>Activities Manager</i>	
	<ul style="list-style-type: none"><li>Schedule and organize all department-wide events to foster a sense of community within the Mechanical Engineering Department and to provide social, educational, and career-related opportunities for students</li></ul>	
	<b>Technical:</b> Basic machine shop experience, 3D printing <b>Computer:</b> SolidWorks, MATLAB, Microsoft Office <b>Language:</b> Conversational Mandarin	
	United States Presidential Scholar (2010); National Merit Scholarship Recipient (2010)	