

Hongri Hou

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EDUCATION

University of Science and Technology of China (USTC)	Hefei, China
• Hefei Institutes of Physical Science, M.S. in Optics Degree Expected	06/2026
• Current GPA: 3.74 / 4.30, Percentile Score: 88.9 / 100	
University of Science and Technology of China (USTC)	Hefei, China
• Department of Precision Machinery and Instrumentation, School of Engineering Science	06/2023
• Bachelor of Engineering in Measuring & Controlling Technology and Instrument	
• Cumulative GPA: 3.68 / 4.30, Percentile Score: 87.4 / 100, Major Ranking: 4 / 25	

Research Interests: Optics, Remote Sensing, AR/VR, Robotics, Visual Mapping, Vision Positioning System

PUBLICATION

- **H. Hou**, W. Su, C. Zhang, H. Liu, C. Liu, *First Cooperative Formaldehyde Monitoring with Chinese Morning and Afternoon Satellites: Revealing Global Multi-Temporal Concentration Dynamics*. **Revision submitted to IEEE Transaction on Geoscience and Remote Sensing**.
- **H. Hou**, W. Su, C. Zhang, C. Liu, *Transformer-based Inverse Radiance Transfer Framework for Global Trace Gas Retrieval Using Metop-B/IASI*. **Submitted to Journal of Remote Sensing**.
- X. Wang, Q. Hu, C. Zhang, W. Su, Q. Li, **H. Hou**, C. Liu, *First global twice-daily ozone profiles from Chinese UV-vis satellites via synergistic spectral calibration and retrieval*, **Remote Sensing of Environment (2025)** DOI: [10.2139/ssrn.5185353](https://doi.org/10.2139/ssrn.5185353)
- Y. Xu, W. Su, Q. Hu, C. Zhang, Z. Javed, Y. Tian, **H. Hou**, C. Liu, *Unexpected HCHO transnational transport: influence on the temporal and spatial distribution of HCHO in Tibet from 2013 to 2021 based on satellite*. **npj Clim Atmos Sci (2024)** DOI: <https://doi.org/10.1038/s41612-024-00639-9>

RESEARCH EXPERIENCE

iFLYTEK Spark Large Model Innovative Application Competition	Hefei, China
Single member as a team	08/2024-10/2024
• Built a web demo to achieve a better effect of RSS reader by automatically generating the summary of the feeds from RSS and generating PPT as well as a total summary for a specific uploaded paper using Spark LLM API	
• The front-end tech stack mainly used HTML/CSS/JavaScript, while the back-end primarily utilized the Flask framework	

China Platform of Earth Observation System: ASEAN Atmospheric Environmental Quality Application Demonstration

Beijing, China	
A Research Program Organized by Aerospace Information Research Institute, Chinese Academy of Sciences	
Module Developer, Supervised by Professor Cheng Liu	
• Constructed the Atmospheric Environmental Quality Comprehensive Demonstration Program in the ASEAN region at the China Platform of Earth Observation System; the total fund was 1.1 million yuan	05/2023-11/2024
• Developed a high-value remote sensing monitoring module and a spatiotemporal representation integrated application module for ozone control based on high-resolution satellite observation for retrieval of gas concentrations	

Verification & Application Based on Multi-time Concentration of HCHO from Domestic Satellites

Bachelor's Graduation Thesis, Supervised by Professor Cheng Liu	Hefei, China
Primary Contributor	10/2022-05/2023
• Conducted retrievals and data analysis on spectral data from domestic satellites and contributed to the writing of the research paper titled <i>Unexpected HCHO transnational transport: influence on the temporal and spatial distribution of HCHO in Tibet from 2013 to 2021 based on satellite</i>	

- Improved and optimized the inversion algorithm which inversed the radiance spectrum observed by the satellites to retrieve trace gas concentrations, and selected better inversion configurations to achieve better inversion results
- The concentration of the satellite in the morning and afternoon was applied globally after validation with MAX-DOAS site data

Robogame, the Special Program of Robotic Research and Manufacture Competition

Hefei, China

Team leader, Supervised by Professor [Huichun Ye](#)

05/2021-10/2021

- Responsible for the design, processing, and assembly of the overall structure in the robotics competition team
- Helped team members win the first prize, ranking eighth among over thirty teams

COURSE DESIGNS

Untrained Image Editing Methods based on Key Layers

Hefei, China

Digital Image Processing Course Design

Single member, Supervised by Professor [Yudong Guo](#)

10/2024-12/2024

- Tried to reproduce the data of a published paper in the absence of open-source codes
- Used GPT to generate 64 prompt words and the random function to randomly produce seeds, then carried out denoising and generation: jumped separately the 57 layers of Flux and input them into DINOv2 to compare the similarity between the reference image and the generated image after removing specific layers
- Two injection methods for key tokens were independently defined: ratio screening and threshold screening, and relatively good editing effects were obtained

The General Design and Modeling Simulation of Quadruped Robot Dogs

Hefei, China

Precision Instrument Design Course Design

Single member, Supervised by Professor [Jianping Wang](#)

08/2022-01/2023

- Investigated quadruped robotic dogs, independently established the 3D model, and produced the assembly drawing
- Built a motion model of the walking-gait of the robotic dog and used MATLAB/Simulink for simulation with mechanical feedback
- Carried out static stress analysis on the established 3D model for optimization

ACHIEVEMENTS/AWARDS

- 20th National Mathematical Modeling Competition for Graduate Students, Third Prize *October 2023*
- Outstanding Graduate of USTC (15%) *June 2023*
- Outstanding Student Scholarship, Silver Award, USTC (10%) *March 2022*
- The Special Program of Robotic Research and Manufacture Competition, First Prize (20%) *October 2021*
- Outstanding Student Scholarship, Bronze Award, USTC (20%) *March 2021*
- Outstanding Student Scholarship, Bronze Award, USTC (20%) *March 2020*

TECHNICAL PROFICIENCIES

- Programming: Proficient in Python, MATLAB, Vim and Linux/Bash, Familiar with Fortran/C++, C
- Language: English (Proficient), Japanese (Elementary)
- Personal Interest: Running, badminton, basketball