

# E3B Developer's Theory Manual - M3

## Double Tapered Composite Beam: Buckling Analysis

**GUI User Manual (GUI Edition)**

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### Revision History

Version	Date	Author	Summary
v1.0	2025-11-21	HYEONSOEK HAN	Manual for CLI-only
V2.0	2026-01-06	HYEONSOEK HAN	Manual for GUI-only

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## 1. Overview

E3B\_M3 is a GUI-based engineering tool for estimating **buckling critical load (Pcr)** and related mode characteristics for an **equivalent box-beam (E3B)** representation of a wing/beam-like structure. It supports:

- **Single Case Buckling** analysis (baseline run)
- **One-at-a-Time (OAT) Sensitivity** studies
- **Global Uncertainty Quantification (Sobol indices)**

The GUI is organized into three main tabs:

- **Buckling (Single Case)**
- **Sensitivity (OAT)**
- **Uncertainty (Sobol UQ)**

Insert Figure 1–3 in Section 4.

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## 2. What the Tool Solves

In early-stage design and trade studies, you often need to answer:

- “Which configuration is more buckling-resistant?”
- “Which parameter actually drives Pcr?”
- “If inputs vary  $\pm X\%$ , how uncertain is Pcr?”
- “Should I use a simplified model (M2) or a richer model (M3)?”

E3B\_M3 is built for **rapid iteration**, not for replacing full-fidelity FE buckling analyses. It provides:

- Fast estimates of **Pcr**
  - A consistent way to compare configurations
  - Sensitivity ranking and Sobol-based influence measures
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### 3. Models: M2 vs M3

The GUI lets you select the solver model:

#### 3.1 M2 (Simplified)

Use M2 when:

- You need **fast** sweeps and optimization loops.
- You want robust behavior over many iterations.
- Your goal is ranking / trend validation.

Typical characteristics:

- Lower computational cost
- Fewer coupling effects represented
- Often more numerically stable for broad sweeps

#### 3.2 M3 (Enhanced)

Use M3 when:

- You want improved physics fidelity (e.g., bending–shear coupling and richer stiffness representation).
- Your design is near a boundary of validity where simplified assumptions can bias results.
- You are performing final trade studies before FE validation.

Typical characteristics:

- Higher computational cost
- More parameters “matter” because more coupling is represented
- Can be more sensitive to numerical settings (grid density, PPW)

#### 3.3 Recommended Default

- **Start with M2** during exploration.
  - Switch to **M3** for final comparative assessment, and for cases where sensitivity/UQ suggests strong coupling effects.
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## 4. GUI Overview

### 4.1 Main Layout

Each tab follows the same structure:

- **Left panel:** inputs and settings
- **Right panel:** plots, progress messages, and results summary
- **Run buttons:** execute the selected analysis mode

### 4.2 Tabs and Purpose

#### Buckling (Single Case)

Baseline run to compute:

- $P_{cr}$
- Critical mode characteristics (e.g., wavelength / dominant mode proxy)
- Output plot(s) for quick interpretation

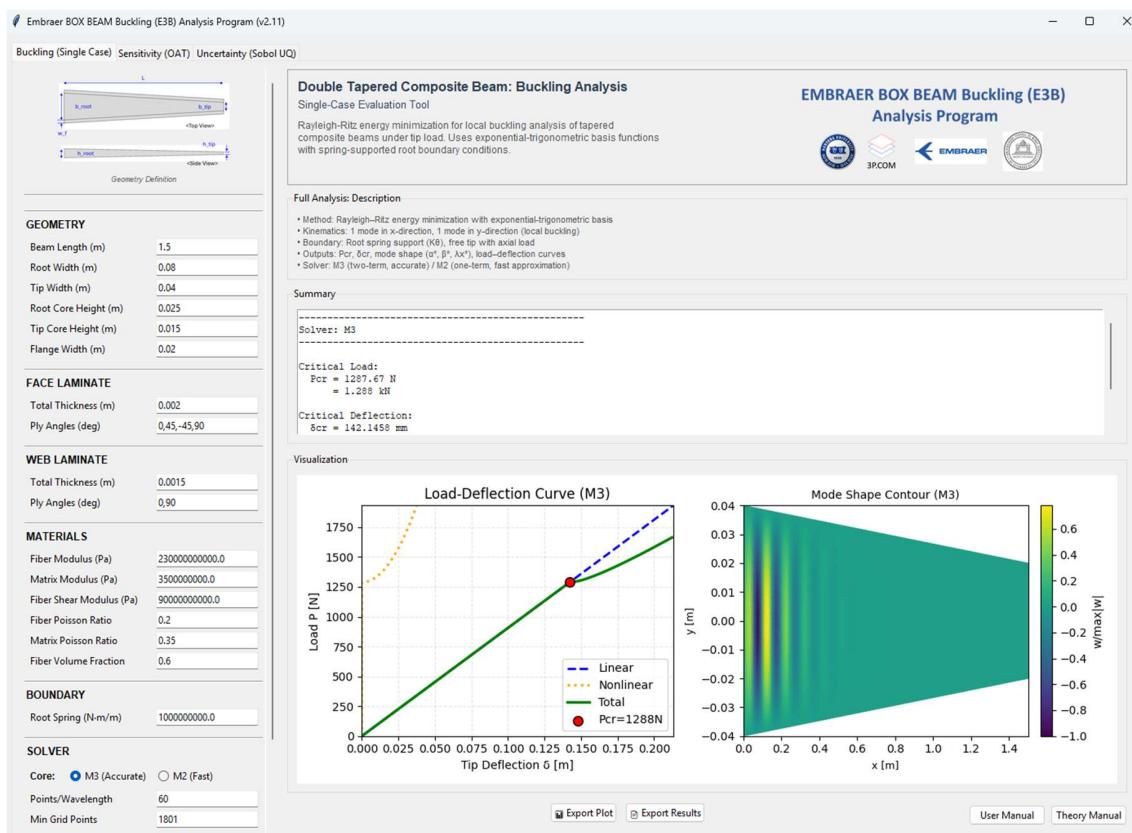


Figure 1. Buckling (Single Case) tab

## Sensitivity (OAT)

Vary one parameter at a time around the baseline and record the response of Pcr.

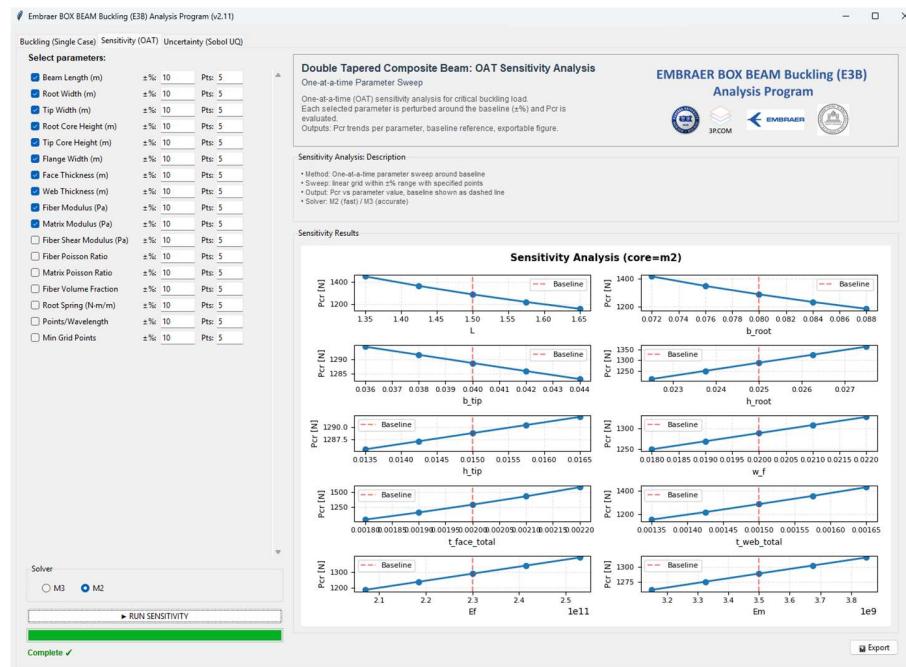


Figure 2. Sensitivity (OAT) tab

## Uncertainty (Sobol UQ)

Treat selected inputs as uncertain within specified bounds and compute Sobol indices.

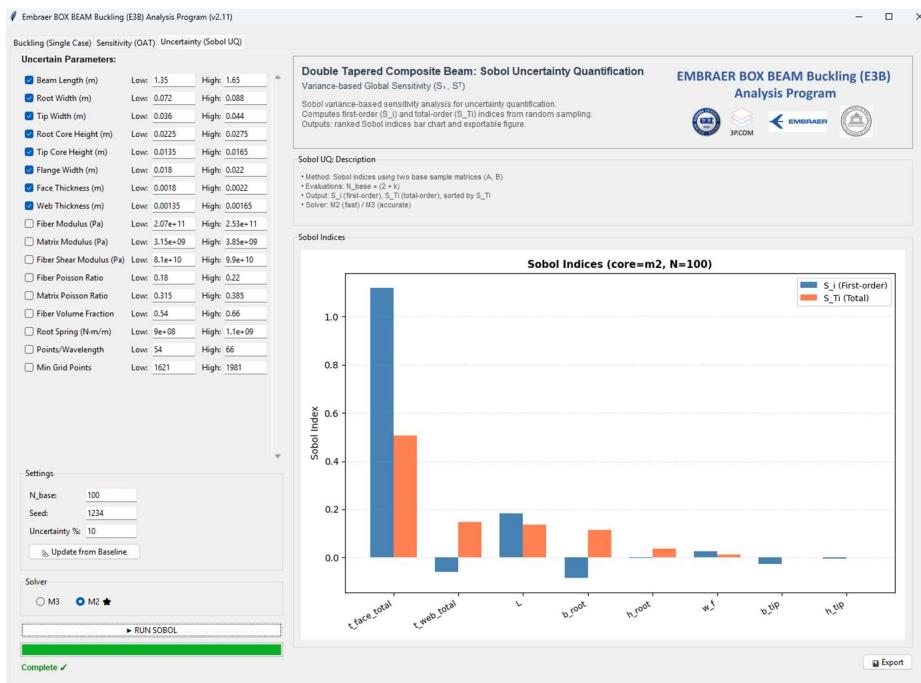


Figure 3. Uncertainty (Sobol UQ) tab

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## 5. Quick Start (3 Minutes)

### 5.1 Single Case (Baseline)

1. Open **Buckling (Single Case)** tab.
2. Enter baseline geometry:
  - o Beam Length, Root/Tip Width, Root/Tip Core Height, Flange Width
3. Enter laminate definitions:
  - o Face thickness + ply angles
  - o Web thickness + ply angles
4. Enter material parameters:
  - o Fiber/Matrix modulus, shear modulus, Poisson ratios, fiber volume fraction
5. Choose model: **M2** (recommended first).
6. Click **Run Buckling**.
7. Review:
  - o Pcr in results panel
  - o Mode/response plot on right
8. Export or record results as needed.

### 5.2 Sensitivity (OAT)

1. Go to **Sensitivity (OAT)** tab.
2. Choose one or more parameters to vary (checkbox list).
3. Set:
  - o Range (%): e.g.,  $\pm 10\%$
  - o Points: e.g., 5
4. Select solver: M2 or M3.
5. Click **Run Sensitivity**.
6. Read:

- Which parameter changes Pcr the most
- Whether response is linear or strongly nonlinear

### 5.3 Uncertainty (Sobol UQ)

1. Go to **Uncertainty (Sobol UQ)** tab.
  2. Set uncertainty approach:
    - Either per-parameter Low/High bounds
    - Or click **Update from Baseline** then apply a uniform uncertainty %
  3. Set sampling:
    - **N\_base** (base sample count)
    - Seed (for reproducibility)
  4. Select solver model.
  5. Click **Run Sobol**.
  6. Read:
    - First-order Sobol (S1): direct effect
    - Total-order Sobol (ST): direct + interactions
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## 6. Inputs (Baseline)

This section explains *what each input means* and *how it influences buckling*, in the same order shown in the GUI.

### 6.1 Geometry

#### Beam Length (L)

- Physical span or analysis length of the equivalent box beam.
- Strong influence on buckling: longer beams typically buckle at lower loads.

#### Root Width / Tip Width

- Defines chordwise dimension variation (taper).
- Influences stiffness distribution and the shape of the critical mode.

#### Root Core Height / Tip Core Height

- Represents box depth variation.

- Core height strongly drives bending stiffness; higher core height generally increases buckling resistance.

#### Flange Width

- Represents effective flange contribution (caps).
  - Affects bending stiffness and coupling depending on layup.
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## 6.2 Laminate Definitions

#### Face Laminate

- **Total thickness (Face) and Ply angles (Face)**
- Ply angles are entered as a comma-separated list of degrees. Example:  
0, 30, 60, -60, -30, 0
- The tool uses this layup to compute equivalent stiffness terms.

#### Web Laminate

- **Total thickness (Web) and Ply angles (Web)**
- Often contains  $\pm 45$ -dominant stacking for shear stability, but you should input your actual design layup.

#### Input rules (recommended):

- Angles in degrees
  - Use commas to separate values
  - Spaces are allowed (the tool should ignore whitespace)
  - Keep the list length consistent with your stacking logic (symmetric sequences help stability)
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## 6.3 Materials

These fields define constituent-level properties used to build an effective laminate behavior.

#### Fiber Modulus / Matrix Modulus

- Control axial stiffness and overall laminate stiffness.

#### Fiber Shear Modulus

- Controls shear behavior contribution.

#### Fiber Poisson Ratio / Matrix Poisson Ratio

- Influences coupling terms and lateral strain relationships.

## Fiber Volume Fraction (Vf)

- Typically one of the most sensitive inputs for stiffness-driven buckling response.
  - Increasing Vf generally increases stiffness (but the exact effect depends on the micromechanics model assumptions).
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## 7. Solver / Numerical Settings

These settings appear mainly in Sensitivity and UQ tabs but conceptually affect stability and runtime.

### 7.1 Root Spring (if used)

- A rotational spring stiffness at the root (or equivalent boundary compliance).
- If your real boundary is not perfectly clamped, tuning this can significantly change Pcr.

### 7.2 Points Per Wavelength (PPW)

- Controls how finely the solver resolves a candidate buckling wave pattern.
- Too low → inaccurate minima (missed critical mode)
- Too high → slower runtime

**Recommended default:** PPW = 24 (adjust if you see unstable mode jumps)

### 7.3 Minimum Grid Points (nx\_min)

- Sets a minimum discretization density along the beam.
- Helps prevent under-resolved geometry taper or stiffness changes.

**Recommended default:** nx\_min = 200

### 7.4 Sobol Sampling: N\_base

- Base sample count for Sobol. Total evaluations are typically a multiple of N\_base.
- Higher N\_base → more stable indices, more runtime.

**Recommended default:** N\_base = 1024 for stable reporting

**Fast check:** N\_base = 256

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## 8. Outputs and How to Read Them

### 8.1 Core Outputs

You should treat the following as the “design-facing” outputs:

- **Pcr (Critical Load):** primary buckling metric
- **Mode indicator / wavelength proxy:** helps interpret whether the solution is physically consistent
- **Plots:** shows how the solver arrived at the critical condition (and whether minima are clean)

## 8.2 What “Good” Looks Like

A reliable result typically shows:

- A **clear minimum** in the response curve (not a noisy flat region)
- Consistent behavior when you slightly change PPW or nx\_min
- No dramatic mode swapping unless geometry/layup truly triggers it

## 8.3 Exported Artifacts (General)

Depending on your build configuration, the tool typically produces:

- A **results table** (baseline + sweeps)
- **Plots** for baseline and sweep/UQ summaries
- A **run log** (warnings, parameter echo, runtime)

If your project requires strict file naming, define it in your repository “Output Convention” section and keep it version-controlled.

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## 9. Sensitivity (OAT)

### 9.1 Purpose

OAT sensitivity answers:

**“If I change one parameter  $\pm X\%$ , how much does Pcr move?”**

This is best for:

- Ranking drivers early
- Detecting nonlinearities (curvature)
- Finding parameters that cause mode switching

### 9.2 Recommended Setup

- Range:  **$\pm 10\%$**  (start here)
- Points: **5** (fast but informative)
- Model: **M2** for screening, **M3** for final sensitivity reporting

## 9.3 Interpreting Results

Common patterns:

- **Monotonic slope:** parameter has a consistent effect
  - **Nonlinear curve:** parameter interacts with model physics strongly
  - **Discontinuous jump:** likely mode switch (verify by rerunning with higher PPW / nx\_min)
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## 10. Uncertainty (Sobol UQ)

### 10.1 Purpose

Sobol UQ answers:

- “Which parameters dominate output uncertainty?”
- “Are interactions important?”

### 10.2 Bounds Setup

Two safe workflows:

1. Set Low/High manually per parameter.
2. Use **Update from Baseline**, apply a global uncertainty %, then fine-tune.

### 10.3 Reading Sobol Indices

- **S1 (First-order):** effect of parameter alone
- **ST (Total-order):** effect of parameter plus its interactions

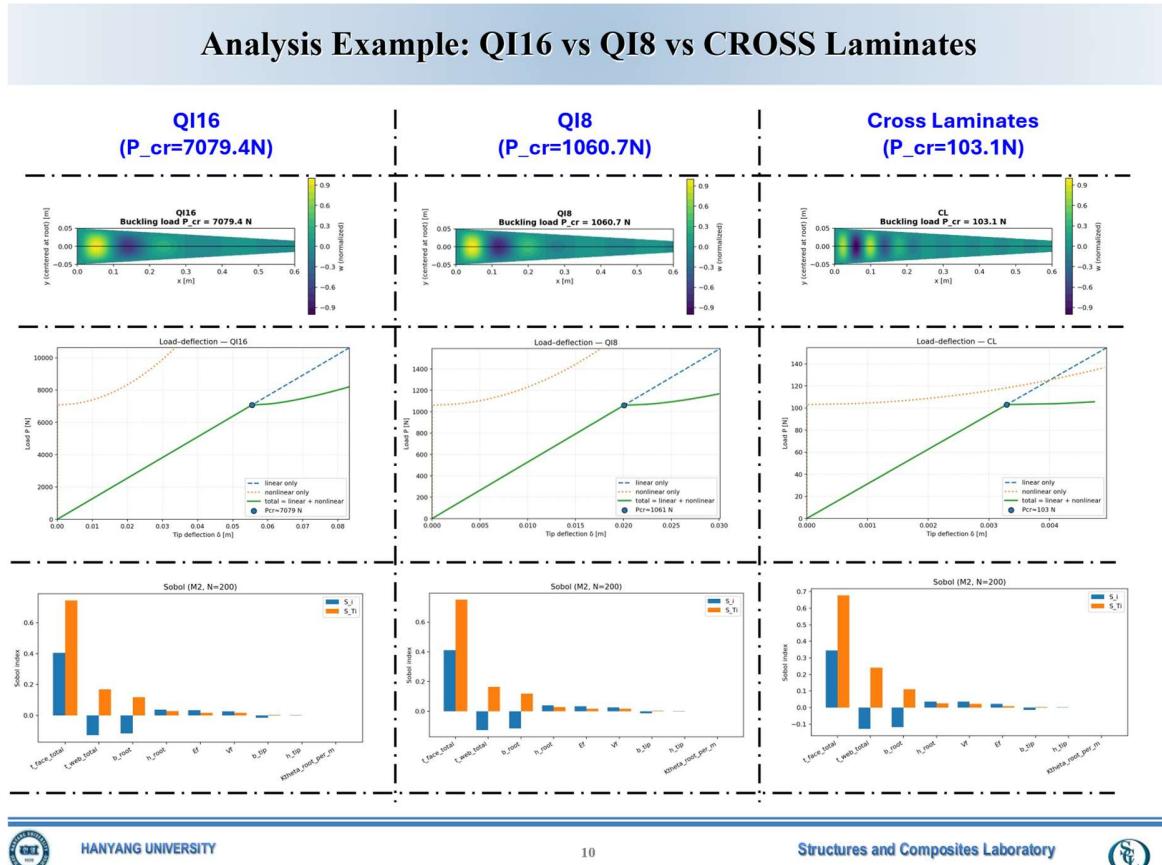
Rules of thumb:

- High S1 and ST → dominant, mostly independent driver
- Low S1 but high ST → interactions matter (coupling)

### 10.4 Reproducibility

- Fix the **Seed** if you want repeatable indices between versions.
  - If indices change significantly with same seed/bounds, it may indicate numerical instability or a model change.
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## 11. Verification & Example Cases (REF/QI16/QI8/CROSS)



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### 11.1 What These Are For

These example cases are **regression checks** to ensure that:

- $P_{cr}$  remains consistent between versions
- The solver does not drift due to numerical or code changes

### 11.2 What to Compare

- **Pcr error:** relative difference vs baseline/reference
- **Mode similarity:** qualitative consistency (shape, wavelength trend)
- **Stability:** absence of random mode swaps at same settings

### 11.3 Interpretation Notes (Practical)

- If REF matches but QI16/QI8 diverge, suspect **numerical integration/discretization sensitivity**.
- If CROSS behaves differently only in M3, suspect **coupling-term handling**.

Keep a small “golden results” CSV in your repo for automated comparison.

## 12. Limitations & Recommended Use

### 12.1 Modeling Limitations

- Equivalent-beam representation cannot capture all local 3D effects.
- Boundary conditions are simplified (even with root spring tuning).
- Laminate behavior is reduced to an effective representation; detailed stacking/local effects may be smeared.

### 12.2 Recommended Parameter Defaults

- PPW: 24
- nx\_min: 200
- N\_base: 1024 (UQ), 256 (quick)

### 12.3 When to Prefer M2 vs M3

Use **M2** when:

- High-throughput screening
- Early design ranking
- Broad sensitivity sweeps

Use **M3** when:

- Final trade study before FE validation
- Strong coupling suspected (e.g., sensitivity/UQ shows interaction-heavy behavior)
- You need improved physics representation and accept higher runtime

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### Appendix A. Input Key Reference (Table)

GUI Label	Key	Unit	Description	Where Used
Beam Length	L	mm	Equivalent beam span/length	All modes
Root Width	b_root	mm	Width at root	All modes
Tip Width	b_tip	mm	Width at tip	All modes
Root Core Height	h_root	mm	Box depth at root	All modes
Tip Core Height	h_tip	mm	Box depth at tip	All modes

Flange Width	b_flange	mm	Effective flange/cap width	All modes
Face Thickness	t_face	mm	Total face laminate thickness	All modes
Face Ply Angles	theta_face	deg	Comma-separated angles	All modes
Web Thickness	t_web	mm	Total web laminate thickness	All modes
Web Ply Angles	theta_web	deg	Comma-separated angles	All modes
Fiber Modulus	E_f	(input unit)	Constituent modulus	All modes
Matrix Modulus	E_m	(input unit)	Constituent modulus	All modes
Fiber Shear Modulus	G_f	(input unit)	Constituent shear modulus	All modes
Fiber Poisson Ratio	nu_f	–	Constituent Poisson ratio	All modes
Matrix Poisson Ratio	nu_m	–	Constituent Poisson ratio	All modes
Fiber Volume Fraction	V_f	–	Fiber volume fraction	All modes
Root Spring	k_root	N·m/m	Root compliance parameter	Sensitivity/UQ (if enabled)
Points per Wavelength	PPW	–	Discretization control	Sensitivity/UQ
Min Grid Points	nx_min	–	Minimum grid density	Sensitivity/UQ
Sobol Base Samples	N_base	–	Sobol sampling base count	UQ
Seed	seed	–	Random seed	UQ

Note: If your project uses strict units (e.g., GPa/MPa), standardize them in your team template and enforce consistency.

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#### Appendix B. Output Fields Reference (Table)

Output	Meaning	Typical Use
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Pcr	Critical buckling load	Primary comparison metric
Mode/Wavelength Proxy	Indicates the dominant buckling pattern	Detect mode switching / sanity check
Baseline Plot	Solver response curve / minima visualization	Confirm clean minimum
Sensitivity Curves	Pcr vs parameter value	Rank drivers
Tornado/Ranking (if produced)	Relative influence summary	Report-ready sensitivity
Sobol S1	First-order effect	Identify direct drivers
Sobol ST	Total effect	Identify interactions

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### Appendix C. Key Equations Summary (High-Level)

(This section is intentionally high-level to stay readable and GUI-focused.)

- **Buckling criterion:** solve for the critical condition where stability changes and the minimum critical load is obtained over admissible mode parameters.
- **Mode parameters (concept):** the solver searches a parameter space representing candidate buckling patterns (e.g., wavelength-like behavior).
- **M2 vs M3:** both compute an effective stiffness-driven stability condition, with M3 including additional coupling/terms compared to M2.
- **Sensitivity:** OAT computes  $\Delta P_{cr}$  resulting from perturbing one input while holding others constant.
- **Sobol:** decomposes output variance into contributions from inputs (direct and interaction components).

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### Troubleshooting (Quick)

- **Weird discontinuity in Pcr:** increase PPW and/or nx\_min and rerun; check for mode switching.
- **Sensitivity results look noisy:** increase points (e.g., 7–9) and raise nx\_min.
- **Sobol indices unstable:** increase N\_base, fix seed, and ensure bounds are realistic.
- **Angle list errors:** use comma-separated degrees; avoid trailing commas; keep consistent formatting.