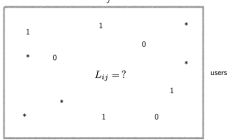
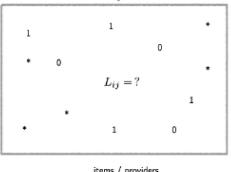
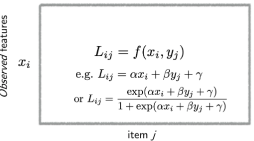
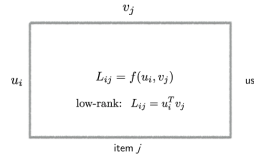
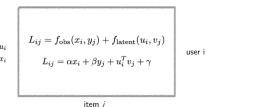
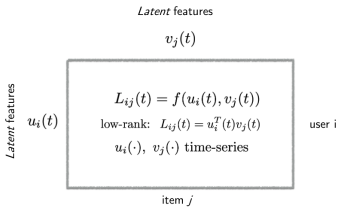

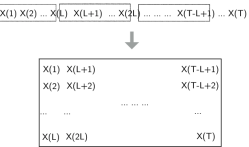
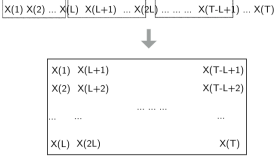
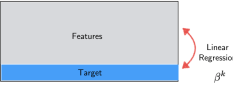
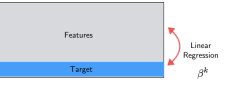


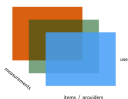


Matrix Estimation Meets Content Based Filtering

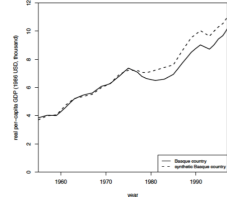
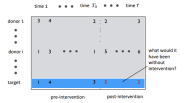
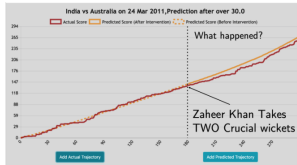
Description	What	Limitations/Assumptions	Example/Form ula	Reference/Co mments
Outline	Matrix Estimation meets Content-based Matrix Estimation across time Matrix Estimation everything together			
Combined Approach	1. Content based supervised learning 2. Matrix Estimation 3. Combine estimates			

Matrix Estimation Meets Content Based Filtering				
Description	What	Limitations/Assumptions	Example/Formula	Reference/Comments
Problem statement Prediction problem: complete the matrix				
Problem statement Prediction problem: complete the matrix	<p>If (i, j) is observed</p> $E[Y_{ij}] = L_{ij}$ <p>If (i, j) is <i>not</i> observed</p> $Y_{ij} = * \text{ or } ?$ <p>Goal: produce estimation \hat{L}_{ij} for all i, j</p> <p>Observed features</p> 	Observations : Y_{ij} over i in users, j in items Goal: produce estimation \hat{L}_{ij} for all i, j		
Problem statement Prediction problem: complete the matrix Content-based: Model	<p>Observed features</p>  <p>Problem reduces to learning model f That is, traditional supervised learning (regression or classification)</p>			
Problem statement Prediction problem: complete the matrix Matrix Estimation: Model	<p>Latent features</p> 		Problem reduces to learning "factorization" of the matrix either through similarities or algebraic approaches	
Matrix Estimation meets Content-based: Model Prediction problem: complete the matrix	<p>item features</p> <p>latent: v_j, obs/val: y_j</p> 		Problem reduces to learning model f That is, traditional supervised learning (regression or classification)	
Matrix Estimation meets Content-based: Algorithm	<p>Step 1. Content-based supervised learning</p> <p>Learn the regressor (or classifier) f_{obs}</p> $L_{ij}^{obs} = f_{obs}(x_i, y_j)$ <p>Step 2. Matrix estimation</p> <p>Compute "difference" matrix</p> $L_{ij}^{diff} = L_{ij} - L_{ij}^{obs}$ <p>Use matrix estimation on L_{ij}^{diff} to produce \hat{L}_{ij}^{diff}</p> <p>Step 3. Combine estimates:</p> $\hat{L}_{ij} = L_{ij}^{obs} + \hat{L}_{ij}^{diff}$		1. Content based supervised learning 2. Matrix estimation 3. Combine estimates	
Matrix Estimation Across Time				
Description	What	Limitations/Assumptions	Example/Formula	Reference/Comments

<p>Matrix Estimation over time: Model</p> <p>Prediction problem: complete the matrix over time, indexed by t</p> <p>Matrix Estimation over Time: Model</p> <p>Prediction problem: complete the matrix over time, indexed by t</p>		<p>Problem reduces estimating time varying matrix where</p> <p>Latent factors are time varying, observations are partial and noisy</p>		
<p>Matrix Estimation over Time: Model</p> <p>Prediction problem: complete the matrix over time, indexed by t</p>	<p>Multiple time series</p> <p>They obey latent structure</p> <p>where each component of u_i, v_j is a structured time-series</p>	<p>$L_{ij}(t), i \in [N], j \in [M]$</p>		
<p>Matrix Estimation over Time: Model</p> <p>Prediction problem: complete the matrix over time, indexed by t</p>		<p>$L_{ij}(t) = u_i(t)^T v_j(t), u_i(t), v_j(t) \in \mathbb{R}^d$</p>		
<p>Matrix Estimation over Time: Model</p> <p>Prediction problem: complete the matrix over time, indexed by t</p>	<p>Observations</p>	<p>Partial, noisy observations of the $L_{ij}(t), i \in [N], j \in [M]$</p> <p>NOT $u_i(t), v_j(t) \in \mathbb{R}^d$</p>		
<p>A digression: time series imputation, forecasting</p>	<p>Ground truth of interest:</p> <p>..., X(-1), X(0), X(1),...,X(T-1),X(T),X(T+1),....</p>	<p>Observations:</p> 		
<p>Page Matrix</p>	<p>Page Matrix</p>  <p>$P = [P_{ij} = X(i + (j-1)L)] \in \mathbb{R}^{L \times \frac{T}{L}}$</p>			
<p>Imputation of time series data</p>	<p>Transform to Matrix, Do Matrix Estimation, Undo Transformation</p>			
<p>Forecasting of time series data</p>	<p>Transform to Matrix, Do Matrix Estimation, Regression , Prediction</p>	<p>Matrix Est</p> <p>$\mathcal{X} \Rightarrow M$</p> 		
<p>Forecasting of time series data</p>	<p>Transform to Matrix, Do Matrix Estimation, Regression , Prediction</p>	<p>Matrix Est</p> <p>$\mathcal{X} \Rightarrow M$</p> 		

Forecasting of time series data	Transform to Matrix, Do Matrix Estimation, Regression , Prediction	<div>$[X(T-L+2) \dots X(T)] \xrightarrow{\text{Project on Col Space of } M^k} V(T+1)$$\downarrow \text{Inner product with } \beta^k$$\hat{X}(T+1)$<p>where $k = (T+1) \bmod L + 1$</p></div>	Easy to use implementation: tspdb.mit.edu																																																																									
Does it really work	<table><thead><tr><th></th><th colspan="4">Mean Imputation (NIMSI)</th><th colspan="4">Mean Forecasting (NIMSF)</th></tr><tr><th></th><th>Electricity</th><th>Traffic</th><th>Synthetic</th><th>Financial</th><th>Electricity</th><th>Traffic</th><th>Synthetic</th><th>Financial</th></tr></thead><tbody><tr><td>noSA</td><td>0.391</td><td>0.494</td><td>0.253</td><td>0.283</td><td>0.483</td><td>0.525</td><td>0.196</td><td>0.358</td></tr><tr><td>SEA</td><td>0.519</td><td>0.608</td><td>0.626</td><td>0.466</td><td>0.552</td><td>0.704</td><td>0.522</td><td>0.592</td></tr><tr><td>LSTM</td><td>NA</td><td>NA</td><td>NA</td><td>NA</td><td>0.551</td><td>0.473</td><td>0.444</td><td>1.203</td></tr><tr><td>DeepAR</td><td>NA</td><td>NA</td><td>NA</td><td>NA</td><td>0.484</td><td>0.474</td><td>0.331</td><td>0.395</td></tr><tr><td>TRMF</td><td>0.694</td><td>0.512</td><td>0.325</td><td>0.513</td><td>0.534</td><td>0.570</td><td>0.267</td><td>0.464</td></tr><tr><td>Prophet</td><td>NA</td><td>NA</td><td>NA</td><td>NA</td><td>0.582</td><td>0.617</td><td>1.005</td><td>1.296</td></tr></tbody></table>		Mean Imputation (NIMSI)				Mean Forecasting (NIMSF)					Electricity	Traffic	Synthetic	Financial	Electricity	Traffic	Synthetic	Financial	noSA	0.391	0.494	0.253	0.283	0.483	0.525	0.196	0.358	SEA	0.519	0.608	0.626	0.466	0.552	0.704	0.522	0.592	LSTM	NA	NA	NA	NA	0.551	0.473	0.444	1.203	DeepAR	NA	NA	NA	NA	0.484	0.474	0.331	0.395	TRMF	0.694	0.512	0.325	0.513	0.534	0.570	0.267	0.464	Prophet	NA	NA	NA	NA	0.582	0.617	1.005	1.296	Out-performs: DeepAR from Amazon Prophet from Facebook LSTM, the shiny neural network approach	NeurIPS 2020 demo: https://www.powtoon.com/s/fkVh3axA4Jy/1/m	
	Mean Imputation (NIMSI)				Mean Forecasting (NIMSF)																																																																							
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Matrices Changing with Time	1. Convert time series for each component into a (Page) matrix	<div>$[I_{ij}(1), \dots, I_{ij}(P), I_{ij}(P+1), \dots, I_{ij}(P^*)] \dots$$\downarrow$<div>$I_{ij}(1) \quad I_{ij}(P+1)$$\vdots \quad \vdots$$I_{ij}(P) \quad I_{ij}(P^*)$</div></div>																																																																										
Matrices Changing with Time	2. Concatenate matrices of all components along columns observation over of a T time units	<div><div>$I_{ij}(1) \quad I_{ij}(P+1)$$\vdots \quad \vdots$$I_{ij}(P) \quad I_{ij}(P^*)$</div>$\circ \circ \circ$<div>$I_{ij}(1) \quad I_{ij}(P+1)$$\vdots \quad \vdots$$I_{ij}(P) \quad I_{ij}(P^*)$</div></div>																																																																										
Matrices Changing with Time	This combine matrix, say Z, has P rows T/P x N x M columns	<div><div>$I_{ij}(1) \quad I_{ij}(P+1)$$\vdots \quad \vdots$$I_{ij}(P) \quad I_{ij}(P^*)$</div>$\circ \circ \circ$<div>$I_{ij}(1) \quad I_{ij}(P+1)$$\vdots \quad \vdots$$I_{ij}(P) \quad I_{ij}(P^*)$</div></div> <p>Let estimated matrix from Z is \hat{Z}</p> <p>By reversing the map we can obtain</p> $\hat{I}_{ij}(t), t \in [T], i \in [N], j \in [M]$																																																																										
Matrices Changing with Time	3. Perform matrix estimation over Z																																																																											
Everything together																																																																												
Description	What	Limitations/Assumptions	Example/Formula	Reference/Comments																																																																								
Recommendation: Problem statement Prediction problem: complete the matrix	<div>$I_{ij} = ?$</div>																																																																											
Content based - Model 1	<div><p>Observed features</p>y_j<div>$I_{ij} = f(x_i, y_j)$<p>or $I_{ij} = \alpha x_i + \beta y_j + \gamma$ or $I_{ij} = 1 + \sin(\alpha x_i + \beta y_j + \gamma)$</p></div><p>Item j</p></div>	Problem reduces to learning model f That is, traditional supervised learning (regression or classification)																																																																										
Matrix Estimation - Model 2	<div><p>Latent features</p>u_i<div>$I_{ij} = f(u_i, v_j)$<p>low rank: $I_{ij} = u_i^T v_j$</p></div><p>Item j</p></div>	Problem reduces to learning "factorization" of the matrix either through similarities or algebraic approaches																																																																										
Matrix Estimation over time - Model 3	<div><p>Latent features</p>$u_i(t)$<div>$I_{ij}(t) = f(u_i(t), v_j(t))$<p>low rank: $I_{ij}(t) = u_i^T(t) v_j(t)$ $u_i(t), v_j(t)$ time-varying</p></div><p>Item j</p></div>	Problem reduces estimating time varying matrix where Latent factors are time varying , observations are partial and noisy																																																																										

Multiple measurements	 <p>Multiple measurements</p> <p>items / providers</p>			
Recommendation: Model Everything	<p>Put everything together</p> <p>Users: N, Items: M</p> <p>Time Horizon: T</p> <p>Measurements: K</p> <p>Quantity of interest: user i, item j, measurement k at time t</p> <p>Problem statement:</p> <p>Estimate the above using noisy, sparse observations</p>	$L_{ijk}(t)$		
Recommendation: Model Everything	<p>The model</p> $L_{ijk}(t) = f_{\text{obs}}^k(x_i, y_j) + f_{\text{latent}}^k(u_i(t), v_j(t))$ <p>$u_i(\cdot), v_j(\cdot)$ time-series</p> <p>A useful special instance</p> $f_{\text{obs}}^k(x_i, y_j) = \alpha^k x_i + \beta^k y_j + \gamma^k$ $f_{\text{latent}}^k(u_i(t), v_j(t)) = \sum_{\ell=1}^d u_{i\ell}(t) v_{j\ell}(t) w_{k\ell}$			
Recommendation: Algorithm	<p>1. Content based learning</p> <p>For each measurement K, learn via supervised learning</p> <p>2. Obtain difference (not learnt through content)</p>	<p>Step 1. Content based learning</p> <p>For each measurement k, learn via supervised learning</p> $f_{\text{obs}}^k \text{ that is } (\alpha^k, \beta^k, \gamma^k)$ <p>Step 2. Obtain difference (not learnt through content)</p> $L_{ijk}^{\text{diff}}(t) = L_{ijk}(t) - L_{ijk}^{\text{obs}}$ <p>where $L_{ijk}^{\text{obs}} = f_{\text{obs}}^k(x_i, y_j)$</p>		
Recommendation: Algorithm	<p>3. Build stack Pace matrix across entries, slices of tensor</p> <p>That is, for measurement k, create Page matrix with P rows, T/P x N x M columns</p>	$\begin{matrix} L_{ijk}(1) & L_{ijk}(P+1) \\ \vdots & \vdots \\ L_{ijk}(P) & L_{ijk}(2P) \end{matrix}$		
Recommendation: Algorithm	<p>3. Build stack Pace matrix across entries, slices of tensor</p> <p>That is, for measurement k, create Page matrix with P rows, T/P x N x M columns</p>	<p>Call it Z^k</p> 		
Recommendation: Algorithm	<p>3. Build stack Pace matrix across entries, slices of tensor</p> <p>That is, for measurement k, create Page matrix with P rows, T/P x N x M columns</p> <p>4. Perform matrix estimation on it</p>	<p>Call it Z^k</p>  <p>Step 4. Perform matrix estimation on it to obtain</p> $\hat{L}_{ijk}^{\text{diff}}(t)$		
Recommendation: Algorithm	<p>5. Final Estimate</p> <p>Some remarks:</p> <p>We flattened tensor in matrix to estimate to $L^{\text{diff}}_{ijk}(t)$</p> <p>But, it comes at the cost of increased computation</p>	$\hat{L}_{ijk}(t) = \hat{L}_{ijk}^{\text{diff}}(t) + L_{ijk}^{\text{obs}}$ <p>Some remarks:</p> <p>We flattened tensor in matrix to estimate to $\hat{L}_{ijk}^{\text{diff}}(t)$</p>		

Post session summary Recommendation systems				
Description	What	Limitations/Assumptions	Example/Formula	Reference/Comments
3 dimensions of recommendation systems	1. Multiple measurements - Data for observed preferences 2. Content or Exogenous features : Features of users/items 3. Dynamics - Time varying aspect			
synthetic prediction	This is a counterfactual prediction where actual prediction and synthetic prediction which will be predicted if the event did not occur to provide analysis of what is the impact of the event		Basque cuntry is in norther spain. It was affected by terrorism from mid to late 70's and it also experienced a decline in the per-capita GDP income around the same time. The question is whether this decline was due to that terrorism or due to some other factors To answer this question, we need to come up with a counterfactual prediction or synthetic prediction of the per-capita GDP of the Basque country if there was no terrorism	
How do we find these predictions	We will use Matrix estimation to determine the synthetic predictions Idea is similar to what we have learned in collaborative filtering We identify the intervention			
Synthetic control	We will observe pre-intervention data, find the similarity of each donor with the target, and use it to create synthetic post-intervention data. This method is called synthetic control			
Applications for matrix technique estimation	Predict scores in an ongoing game Can be used to find highlights or breakthroughs in a game or history when comparing the predictions change and some gap between the actual and predicted score can be observed		Forecasting cricket trajectory in an India vs Australia game from 2011	