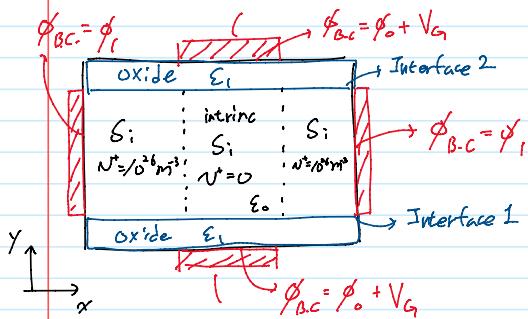


# HW 10.

Thursday, October 8, 2020 4:44 PM

20184060 Jichael Kim



Edge & Bulk & Interface 由 분으로

$$\text{내부} \int dz \nabla \cdot (\epsilon \nabla \phi_{\text{bulk}}) = \int_V dz - P(\phi_{\text{bulk}}) \quad (1)$$

Discretization 과정.

$$\phi_i \in N^+ - N(\phi) + P(\phi) = 0 \quad \text{solution을 찾았다.}$$

가장 가까운  $L_x$ , 가장 가까운  $L_y$ .

i) Bulk



$$\int_V dz \epsilon \nabla^2 \phi_{\text{bulk}} = \epsilon \int_S d\vec{a} \cdot \nabla \phi_{\text{bulk}} = \int_V dz - P(\phi_{\text{bulk}})$$

$$= \int_V dz [g N_{\text{acc}} + g (N(\phi) - P(\phi))]$$

Discretization  $\rightarrow$  grid spacing :  $\Delta$

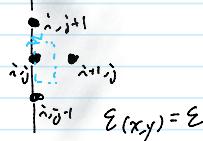
$$\text{Transform into } A \vec{\phi} = \vec{b}$$

$$\epsilon (-4\phi_{i,j} + \phi_{i+1,j} + \phi_{i-1,j} + \phi_{i,j+1} + \phi_{i,j-1}) = \Delta^2 g (N_{\text{acc}} + (N(\phi) - P(\phi)))$$

$$(j \text{th row})_{\text{th row}} \leftarrow \begin{pmatrix} \ddots & & & \\ \epsilon & \epsilon - 4\epsilon & \epsilon & \epsilon \\ & \ddots & \ddots & \ddots \\ & & \ddots & \ddots \end{pmatrix} \begin{pmatrix} \phi_{i,j-1} \\ \phi_{i-1,j} \\ \phi_{i,j+1} \\ \phi_{i+1,j} \\ \phi_{i,j+1} \end{pmatrix} = \begin{pmatrix} \ddots \\ \Delta^2 g (N_{\text{acc}} + 2N_i \sinh(\frac{\phi_{i,j}}{kT})) \\ \ddots \\ \ddots \end{pmatrix}$$

ii) Edge

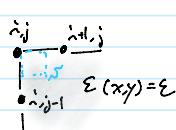
For homogeneous Neumann B.C.,



By discretization,

$$\epsilon (-2\phi_{i,j} + \phi_{i+1,j} + \frac{1}{2}\phi_{i,j+1} + \frac{1}{2}\phi_{i,j-1}) = 0$$

$$(j \text{th row})_{\text{th row}} \leftarrow \begin{pmatrix} \ddots & & & \\ \frac{1}{2}\epsilon & -2\epsilon & \epsilon & \frac{1}{2}\epsilon \\ & \ddots & \ddots & \ddots \\ & & \ddots & \ddots \end{pmatrix} \begin{pmatrix} \phi_{i,j+1} \\ \phi_{i,j} \\ \phi_{i+1,j} \\ \phi_{i,j-1} \end{pmatrix} = \begin{pmatrix} \ddots \\ 0 \\ \ddots \\ \ddots \end{pmatrix}$$



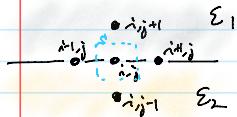
$$\epsilon (-\phi_{i,j} + \frac{1}{2}\phi_{i+1,j} + \frac{1}{2}\phi_{i,j-1}) = 0$$

$$(j \text{th row})_{\text{th row}} \leftarrow \begin{pmatrix} \ddots & & & \\ \frac{1}{2}\epsilon & -\epsilon & \frac{1}{2}\epsilon & 0 \\ & \ddots & \ddots & \ddots \\ & & \ddots & \ddots \end{pmatrix} \begin{pmatrix} \phi_{i,j+1} \\ \phi_{i,j} \\ \phi_{i+1,j} \\ \phi_{i,j-1} \end{pmatrix} = \begin{pmatrix} \ddots \\ 0 \\ \ddots \\ \ddots \end{pmatrix}$$

For Dirichlet B.C.,

$$\phi_{i,j} = \phi_{\text{ac.}} \rightarrow \begin{pmatrix} \ddots & & \\ & 1 & \\ & & \ddots \end{pmatrix} \begin{pmatrix} \vdots \\ \phi_{i,j} \\ \vdots \end{pmatrix} = \begin{pmatrix} \vdots \\ \phi_{\text{ac.}} \\ \vdots \end{pmatrix}$$

iii) Interface

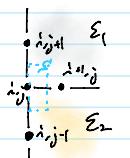


By discretization,

$$-2(\epsilon_1 + \epsilon_2)\phi'_{i,j} + \frac{\epsilon_1 + \epsilon_2}{2}\phi'_{i+1,j} + \frac{\epsilon_1 + \epsilon_2}{2}\phi'_{i-1,j} + \epsilon_1\phi'_{i,j+1} + \epsilon_2\phi'_{i,j-1}$$

$$= \Delta^2 \phi (N_{\text{acc}} + (n_i \phi'_{i,j}) P(\phi'_{i,j}))$$

$$\left( \begin{array}{cccccc} \ddots & & & & & \\ & \epsilon_2 & \frac{\epsilon_1 + \epsilon_2}{2} & -2(\epsilon_1 + \epsilon_2) & \frac{\epsilon_1 + \epsilon_2}{2} & \epsilon_1 \\ & & & & & \ddots \\ & & & & & \epsilon_1 \end{array} \right) \begin{pmatrix} \phi'_{i,j+1} \\ \phi'_{i,j} \\ \phi'_{i,j-1} \\ \phi'_{i+1,j} \\ \phi'_{i-1,j} \\ \vdots \end{pmatrix} = \begin{pmatrix} \Delta^2 \phi (N_{\text{acc}} + 2n_i \sinh(\frac{\partial \phi_{i,j}}{\epsilon_0 T})) \\ \vdots \\ \vdots \end{pmatrix}$$

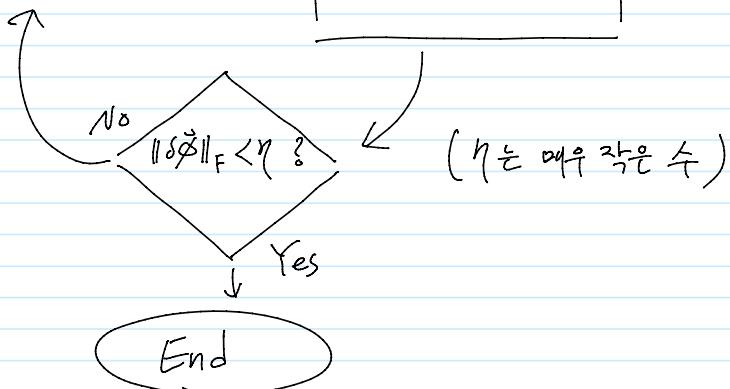


$$-(\epsilon_1 + \epsilon_2)\phi'_{i,j} + \frac{\epsilon_1 + \epsilon_2}{2}\phi'_{i+1,j} + \frac{\epsilon_1}{2}\phi'_{i,j+1} + \frac{\epsilon_2}{2}\phi'_{i,j-1} = 0 \quad (\because \text{Neumann B.C.})$$

$$\left( \begin{array}{ccc} \ddots & & \\ & \frac{\epsilon_2}{2} & -(\epsilon_1 + \epsilon_2) & \frac{\epsilon_1 + \epsilon_2}{2} & \frac{\epsilon_1}{2} \\ & & & & \ddots \\ & & & & \epsilon_1 \end{array} \right) \begin{pmatrix} \phi'_{i,j+1} \\ \phi'_{i,j} \\ \phi'_{i,j-1} \\ \phi'_{i+1,j} \\ \vdots \end{pmatrix} = \begin{pmatrix} \vdots \\ 0 \\ \vdots \end{pmatrix}$$

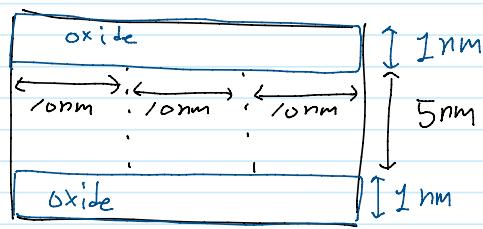
\* Algorithm

$$\boxed{\begin{array}{l} \text{Initialize} \\ \vec{\phi} = \vec{\phi}_0 \end{array}} \rightarrow \boxed{\begin{array}{l} \text{Make } \mathbf{r}(\vec{\phi}), \mathbf{J}(\vec{\phi}) \\ \mathbf{r}(\vec{\phi}) = \mathbf{A}\vec{\phi} - \vec{b} \\ \mathbf{J}(\vec{\phi}) = \mathbf{A} - \mathbf{d}\vec{\phi} \end{array}} \rightarrow \boxed{\begin{array}{l} \text{Solve } \mathbf{J} \delta\vec{\phi} = -\mathbf{r}(\vec{\phi}) \\ \text{Update } \vec{\phi} \rightarrow \vec{\phi} + \delta\vec{\phi} \end{array}}$$

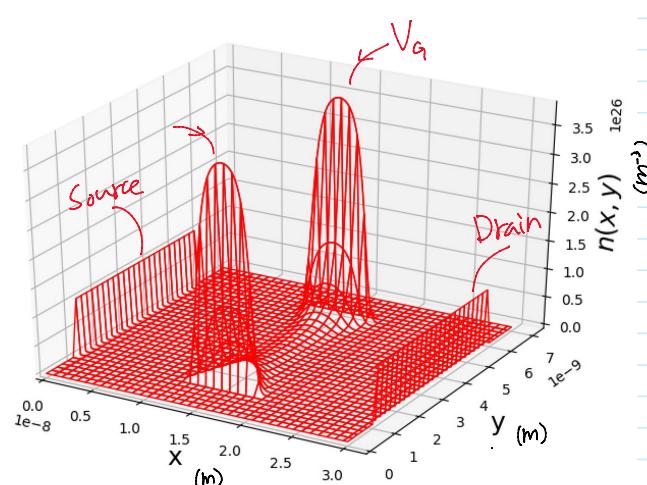
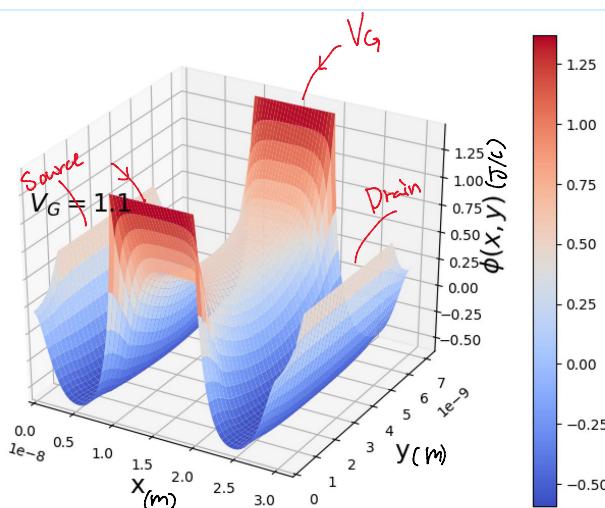
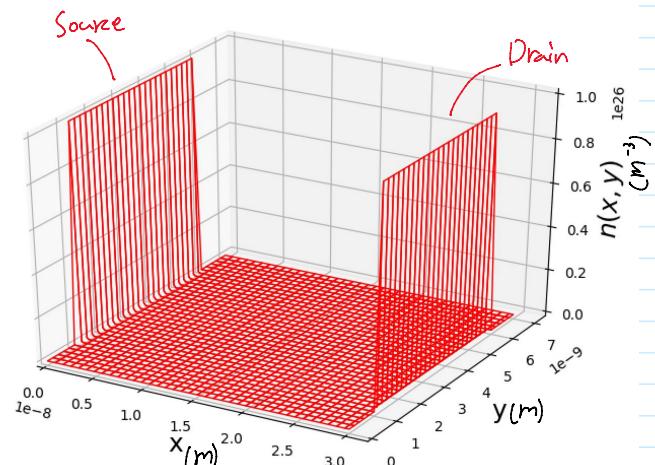
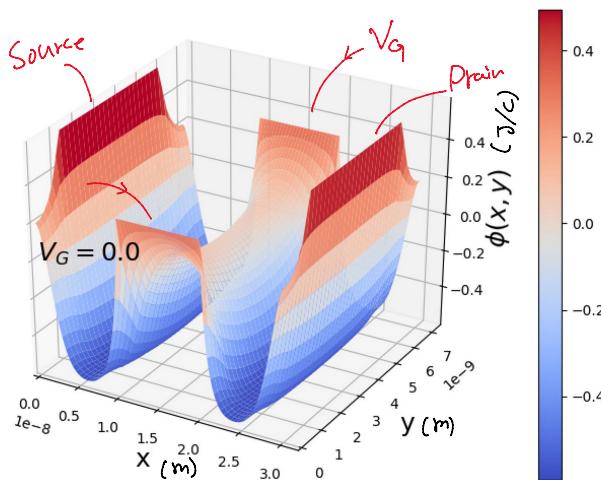


## Results

$$\Delta = 0.2 \text{ nm}, L_x = 30 \text{ nm}, L_y = 7 \text{ nm}$$



1)  $\phi(x,y)$  &  $n(x,y)$  for  $V_G$



Homogeneous Neumann B.C. 부분에서  $\nabla \phi \cdot \vec{n} = 0$ 인 것이 잘 나타난다.

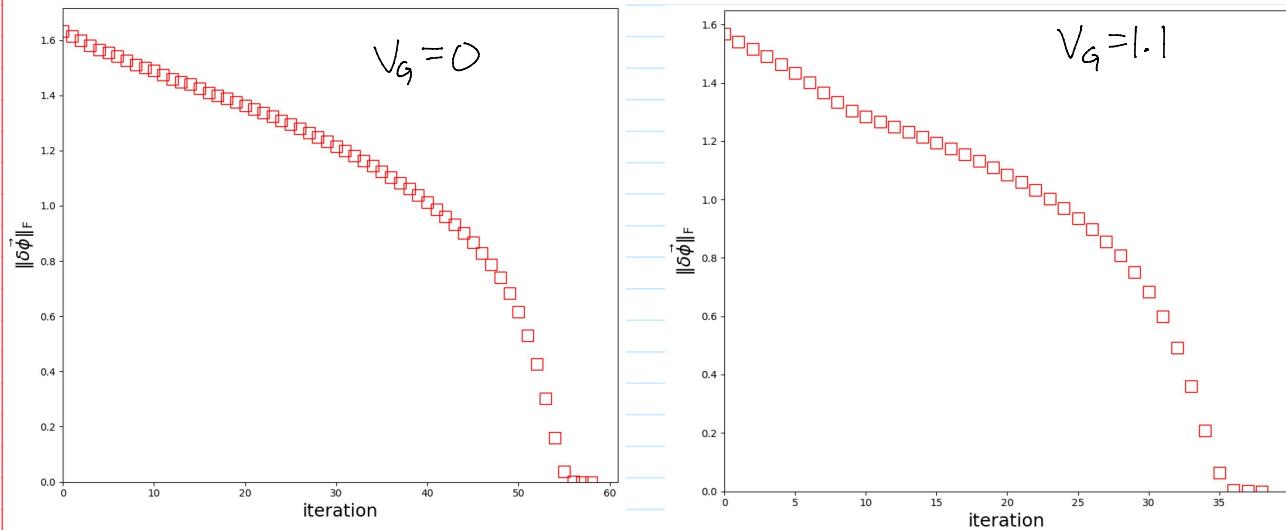
Gate voltage  $V_G$ 가 커지면서 gate 쪽 electron density가 증가한다.

2) Converge trend for initial  $\phi$ .

initial  $\phi$ 이  $\phi_0$ かつ Newton-Raphson method의 Converge가 어떻게 달라지는지  
관찰해보았다.  $\eta = 10^{-7} \sim 10^{-8}$ 였다.

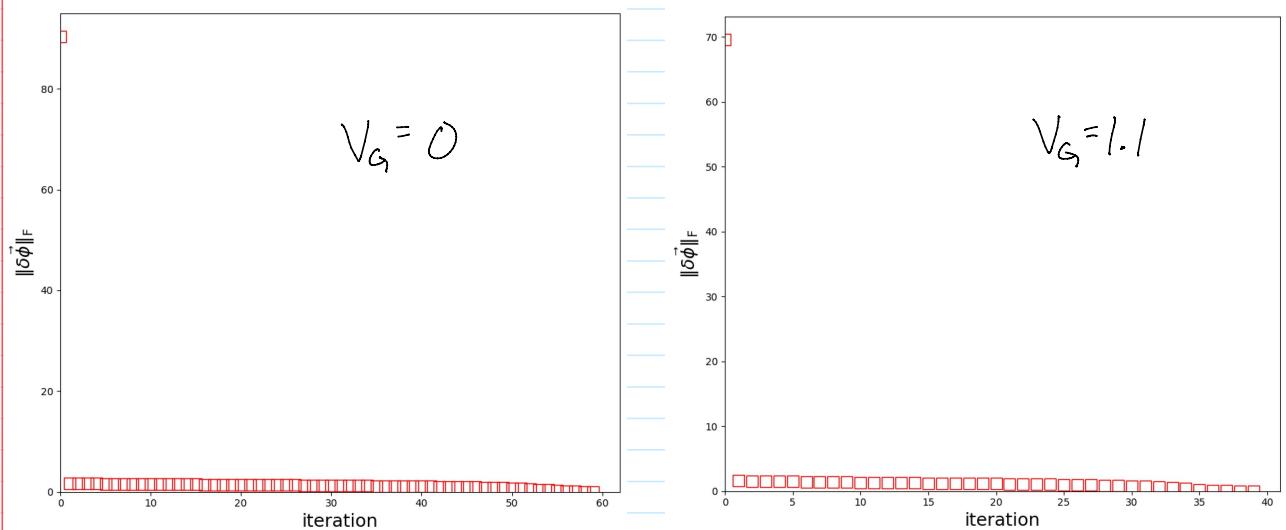
$$i) \vec{\phi}_{\text{init.}} = \begin{bmatrix} \vec{\phi} \\ \omega_0 n(\phi), p(\phi) \end{bmatrix}$$

Initial  $\vec{\phi}$ 를 선택할 때,  $\nabla \cdot (\epsilon \nabla \phi) = -\rho$  or  $\rho = gN^+$  et 생각하고  $A\vec{\phi} = \vec{b}$  를 풀어 구한  $\vec{\phi}$ 를 이용했다.



대략 40 ~ 60 iteration에서 Converge 함을 알 수 있다.

$$ii) \vec{\phi}_{\text{init.}} = \vec{0}$$



대략 40~60 iteration에서 Converge 함을 알 수 있다.

그러나,  $\|\delta\phi\|_F$ 의 trend가 다음과 알 수 있다.

i) 와 ii) 를 보면 initial  $\phi$ 의 따라 수렴 조건이  
다른 차이점을 알 수 있다.