Computational Microelectronics Lecture 8 Diffusion

Sung-Min Hong (smhong@gist.ac.kr)
Semiconductor Device Simulation Laboratory
School of Electrical Engineering and Computer Science
Gwangju Institute of Science and Technology

Diffusion

A simple case

- Neglect the electric field dependence.
 - Also consider only one dopant.

$$\frac{C(x_i, t_k) - C(x_i, t_{k-1})}{\Delta t} \Delta x - D \frac{1}{\Delta x} [C(x_{i+1}, t_k) - C(x_i, t_k)] + D \frac{1}{\Delta x} [C(x_i, t_k) - C(x_{i-1}, t_k)] = 0$$

– Now, find out entries of the Jacobian matrix. Note that there are three variables, $C(x_{i+1}, t_k)$, $C(x_i, t_k)$, and $C(x_{i-1}, t_k)$.

Jacobian

• The diagonal component, $A_{i,i}$ $A_{i,i} = \frac{\Delta x}{\Lambda t} + 2\frac{D}{\Lambda x}$

- Positive
- Off-diagonal components, $A_{i,i+1}$ and $A_{i,i-1}$ $A_{i,i+1} = -\frac{D}{\Lambda x}$

$$A_{i,i-1} = -\frac{D}{\Delta x}$$

Negative

HW#8

- Due: AM08:00, September 25
- Problem#1
 - Solve again Problem#1 of HW#5. However, in this time, implement the code with the Newton-Raphson method. Of course, since the system is linear, your update vector will become very small after the first Newton iteration.

Diffusion – Electric Field

Single dopant with electric field

- Now, consider the electric field dependence.
 - -Still, consider only one dopant, which is positively charged.
 - Use the following discretized flux:

$$F_{C,i+0.5} = -\frac{D}{\Delta x} \frac{1}{\sqrt{n(x_{i+1}, t_k)n(x_i, t_k)}} \times [C(x_{i+1}, t_k)n(x_{i+1}, t_k) - C(x_i, t_k)n(x_i, t_k)]$$

- Confirm the correctness of the above expression.

Jacobian

ullet The diagonal component, $A_{i,i}$

$$A_{i,i} = \frac{\Delta x}{\Delta t} + \frac{D}{\Delta x} \sqrt{\frac{n(x_i, t_k)}{n(x_{i+1}, t_k)}} + \frac{D}{\Delta x} \sqrt{\frac{n(x_i, t_k)}{n(x_{i-1}, t_k)}} + terms related to \frac{dn}{dC} \Big|_{C(x_i, t_k)}$$

- We must prepare $\frac{dn}{\partial c}\Big|_{C(x_i,t_k)}$.
- (Similar terms for off-diagonal components)

Note

Linear case

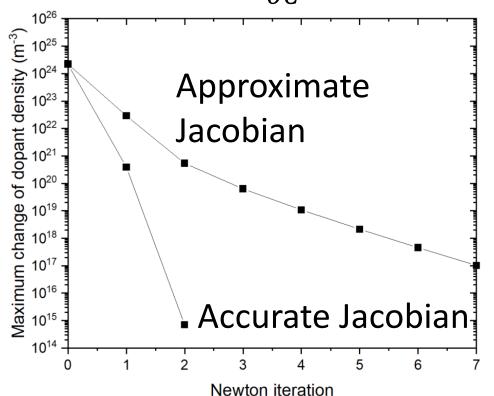
- Every time instance, t_k , takes only one Ax = b.
- -A is time-independent.
- C's are calculated directly.

Nonlinear case

- -Several iterations at every time instance
- The Jacobian matrix depends on the solution. (We must re-calculate it at every iteration.)
- $-\delta C$'s are calculated and C's are updated.

Number of iterations

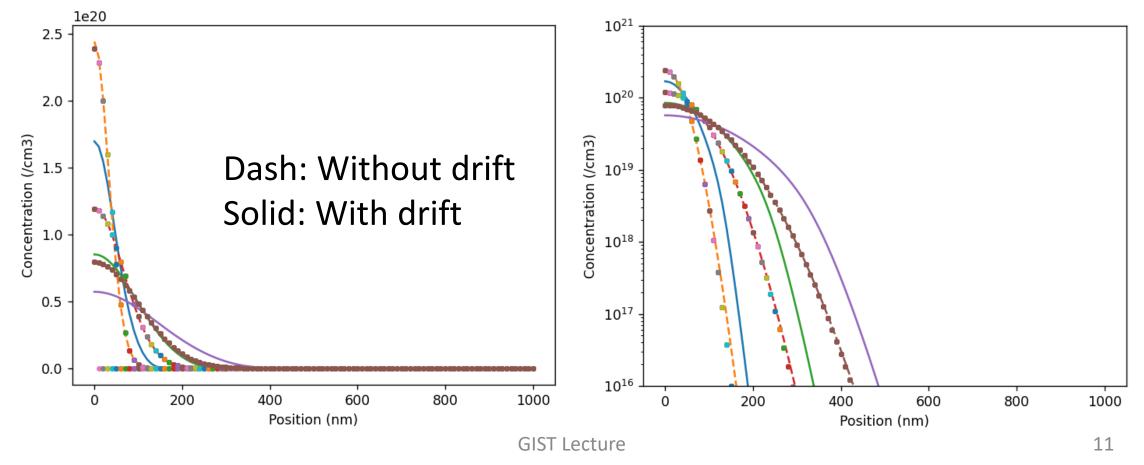
- For a given transient simulation, it takes
 - An accurate Jacobian matrix: 137 iterations
- 0 2.169197554059118e+24 1 3.900680956190052e+20 2 692935559081258.4
- A Jacobian matrix without $\frac{dn}{\partial c}$ terms: 526 iterations



0 2.1978298208828112e+24 1 2.9053050667858773e+22 2 5.346531455478733e+20 3 6.31481868904466e+19 4 1.0742905060590954e+19 5 2.1224080530933048e+18 6 4.538011714971787e+17 7 1.0180945920086405e+17

Simulation results @ 1000 °C

- Observe the impact of drift term. (Delta-like dose, 2X10¹⁵ cm⁻²)
 - -Three time instances, 400 sec, 1600 sec, and 3600 sec



Thank you!