Tensorflow ConvNet

MNIST Classification
CAT vs DOG Classification

최준명

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Tensorflow I 지난 시간 복습

- 먼저 Graph를 Build하고 Session을 통해 실행한다.
- 변수는 tf.Variable() 보단 tf.get_variable()
- 입력은 tf.placeholder() with feed_dict 나 tf.data()를 쓰자.
- 모델 building은 Layer API 를 쓰면 간편하다. (단점: debugging이 어려움)
- 간단한 Linear Regression 모델
- 간단한 Logistic Regression 모델

Tensorflow | 오늘 목표

- Convolutional layer을 이용한 MNIST 분석
- 나만의 데이터를 이용하여 ConNet 구성

Convolutional layer in Tensorflow

MNIST Dataset

X = 28x28 array(1d size of 784)

Y = Digit value

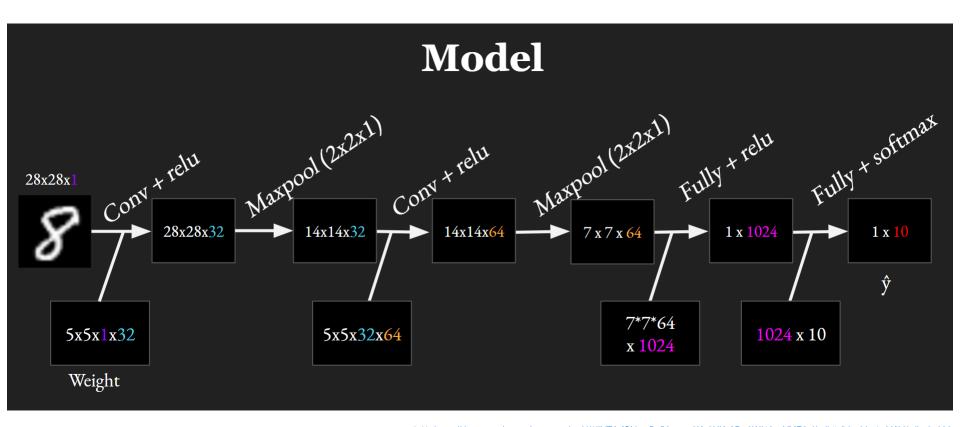
MNIST.train: 55,000 examples MNIST.validation: 5,000 examples MNIST.test: 10,000 examples

Inference: Y_predicted = softmax(X * w + b)

Cross entropy loss: -log(Y_predicted)

```
コユスココヨ ೩乙
   5575555555555
6 4 6 6 6 6 6 6 6 6 6 6 6 6 6
```

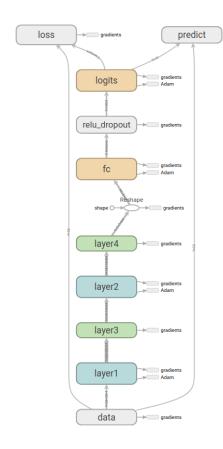
출처: https://docs.google.com/presentation/d/1lmcQVNAmJrL8x3lq0VB1mVaka1r6pOlb-TMVTX5Rufc/edit#slide=id.g1c166da651_0_5

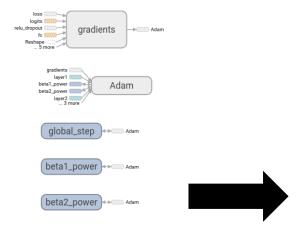


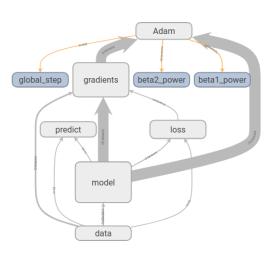
출처: https://docs.google.com/presentation/d/17VTArfQVtapBqfYecyvp3Kp9HKy8Pw2WI12acYME2nI/edit#slide=id.g1c60f09bdb_0_336

```
def conv2d(inputs, nb_filter, filter_size, strides=1, padding='same',
           activation=tf.nn.relu, bias=True, weights_init=variance_scaling_initializer,
           bias_init=zeros_initializer, trainable=True, scope='Conv2d'):
 with tf.variable_scope(scope, values=[inputs], reuse=tf.AUTO_REUSE) as scope:
   W init = weights init
   bias_init = bias_init
   x = tf.layers.conv2d(inputs_filters=nb_filter_kernel_size=filter_size_strides=[strides_strides]_padding=padding,
                         kernel_initializer=W_init,bias_initializer=bias_init,activation=activation,trainable=trainable)
 return x
def maxpool(inputs, filter_size=2, strides=1, padding='same', scope='pool'):
  with tf.variable_scope(scope, reuse=tf.AUTO_REUSE) as scope:
    x = tf.layers.max_pooling2d(inputs_pool_size=[filter_size,filter_size],strides=[strides_strides],padding=padding)
  return x
def fully_connected(inputs, nb_filter, activation=tf.nn.relu, bias=True, weights_init=variance_scaling_initializer,
           bias_init=zeros_initializer, trainable=True, scope='FC'):
  if len(inputs.get_shape().as_list())>2:
    n_inputs = int(np.prod(inputs.get_shape().as_list()[1:]))
    inputs = tf.reshape(inputs, [-1, n_inputs])
  with tf.variable_scope(scope, reuse=tf.AUTO_REUSE) as scope:
    x = tf.layers.dense(inputs_units=nb_filter_activation=activation_use_bias=bias_kernel_initializer=weights_init,
                        bias_initializer=bias_init, trainable=trainable)
  return x
```

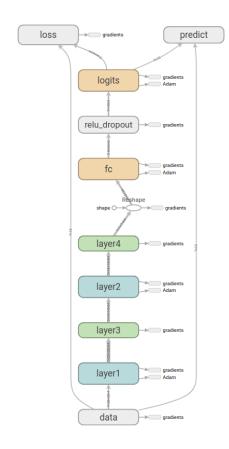
```
def inference(self):
    with tf.variable_scope('model') as scope:
        conv1 = conv2d(inputs=self.img_nb_filter=32_filter_size=5_trainable=self.training_scope='layer1')
        pool1 = maxpool(conv1, 2, 2, 'same', scope_='layer2')
        conv2 = conv2d(inputs=pool1_nb_filter=64_filter_size=5_trainable=self.training_scope='layer3')
        pool2 = maxpool(conv2, 2, 2, 'same', scope_='layer4')
        fc = fully_connected(pool2, 1024_trainable=self.training, scope='layer5')
        self.logits = fully_connected(fc, self.n_classes_trainable=self.training, scope='logits')
```

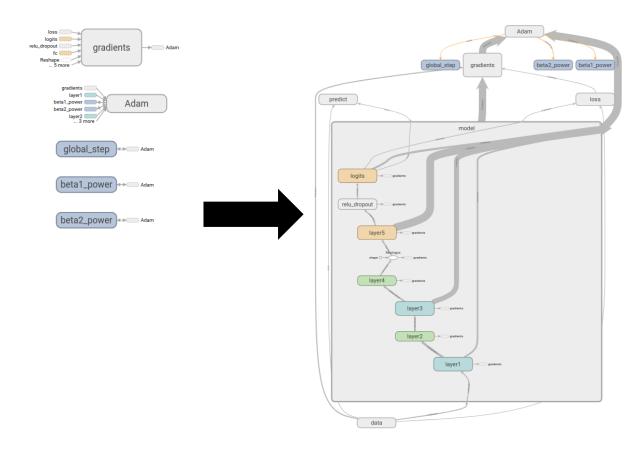






```
def inference(self):
    with tf.variable_scope('model') as scope:
        conv1 = conv2d(inputs=self.img_nb_filter=32_filter_size=5_trainable=self.training_scope='layer1')
        pool1 = maxpool(conv1, 2, 2, 'same', scope_='layer2')
        conv2 = conv2d(inputs=pool1_nb_filter=64_filter_size=5_trainable=self.training_scope='layer3')
        pool2 = maxpool(conv2, 2, 2, 'same', scope_='layer4')
        fc = fully_connected(pool2, 1024_trainable=self.training, scope='layer5')
        self.logits = fully_connected(fc, self.n_classes_trainable=self.training, scope='logits')
```





```
def loss(self):
  with tf.name_scope('loss'):
    entropy = tf.nn.softmax_cross_entropy_with_logits(labels=self.label, logits=self.logits)
    self.loss = tf.reduce_mean(entropy, name='loss')
def optimize(self):
  self.opt = tf.train.AdamOptimizer(self.lr).minimize(self.loss,
                                                       global step=self.gstep)
def summary(self):
  with tf.name_scope('summaries'):
    tf.summary.scalar('loss', self.loss)
    tf.summary.scalar('accuracy', self.accuracy_holder)
    tf.summary.histogram('histogram loss', self.loss)
    self.summary_op = tf.summary.merge_all()
def build(self):
  self.get_data()
  self.inference()
  self.loss()
  self.optimize()
  self.eval()
  self.summary()
```

```
def train_one_epoch(self, sess, saver, writer, epoch, step):
 start_time = time.time()
 self.training = True
 n_batches = int(self.mnist.train.num_examples/self.batch_size)
 total loss = 0
 for j in range(n batches):
   self.X_batch,self.Y_batch = self.mnist.train.next_batch(self.batch_size)
   _, l = sess.run([self.opt, self.loss], feed_dict={self.X: self.X_batch, self.label: self.Y_batch})
   step += 1
   total_loss += l
 saver.save(sess, 'checkpoints/convnet_mnist/mnist-convnet', step)
 print('Average loss at epoch {0}: {1} Took: {2} seconds'.format(epoch, total_loss/n_batches_time.time()-start_time))
 return step
def eval_once(self, sess, writer, epoch, step):
 start_time = time.time()
 self.training = False
 total_correct_preds = 0
 n_batches = int(self.mnist.test.num_examples/100)
 for j in range(n_batches):
   self.X_batch, self.Y_batch = self.mnist.test.next_batch(100)
   accuracy_batch = sess.run(self.accuracy, feed_dict={self.X: self.X_batch, self.label: self.Y_batch})
   total_correct_preds += accuracy_batch
 summaries = sess.run(self.summary_op, feed_dict={self.X:self.X_batch,self.label:self.Y_batch,
                                                   self.accuracy_holder:total_correct preds/n batches})
 writer.add summary(summaries, global step=step)
 print('Accuracy at epoch {0}: {1} Took: {2} seconds'.format(epoch, total_correct_preds/n_batches,
                                                              time.time()-start_time))
```

```
def train(self, n_epochs):
 utils.safe_mkdir('checkpoints')
 utils.safe_mkdir('checkpoints/convnet_mnist')
 writer = tf.summary.FileWriter('./graphs/convnet', tf.get_default_graph())
  with tf.Session() as sess:
    sess.run(tf.global_variables_initializer())
    saver = tf.train.Saver()
    ckpt = tf.train.get_checkpoint_state(os.path.dirname('checkpoints/convnet_mnist/checkpoint'))
    if ckpt and ckpt.model_checkpoint_path:
      saver.restore(sess, ckpt.model checkpoint path)
    step = self.gstep.eval()
    for epoch in range(n_epochs):
      step = self.train_one_epoch(sess, saver, writer, epoch, step)
      self.eval_once(sess, writer, epoch, step)
  writer.close()
```

Kaggle dogs vs cats (download here)

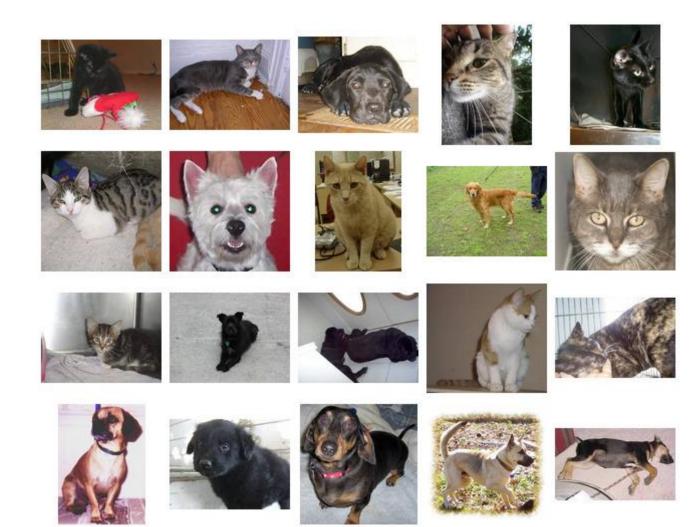
X = 크기가 다양함 Y = 0 or 1

dog.1.jpg dog.2.jpg

•••

cat.1.jpg cat.2.jpg

•••



```
def get_files(data_path,datafolder):
  cats = []
  label_cats = []
 dogs = []
 label dogs = []
  for file in datafolder:
   name = file.split('.')
    if name[0]=='cat':
      cats.append(os.path.join(data_path, file))
      label cats.append(0)
    else:
      dogs.append(os.path.join(data_path, file))
      label_dogs.append(1)
 image_list = np.hstack((cats, dogs))
  label_list = np.hstack((label_cats, label_dogs))
  shuffle = list(zip(image_list, label_list))
  random.shuffle(shuffle)
 image_list, label_list = zip(*shuffle)
  return image_list, label_list
```

```
def get_batch(image, label, image_W, image_H, batch_size, capacity):
  image = tf.cast(image, tf.string)
  label = tf.cast(label, tf.int32)
  input_queue = tf.train.slice_input_producer([image, label])
  label = input_queue[1]
  image_contents = tf.read_file(input_queue[0])
  image = tf.image.decode_jpeg(image_contents, channels=3)
  # data argumentation
  image = tf.image.resize_image_with_crop_or_pad(image, image_W, image_H)
  image = tf.image.per_image_standardization(image)
  image_batch, label_batch = tf.train.batch([image, label],
                                             batch_size=batch_size.
                                             capacity=capacity)
  label_batch = tf.one_hot(label_batch, depth=2)
  image_batch = tf.cast(image_batch, tf.float32)
  return image_batch, label_batch
```

Data augmentation (https://www.tensorflow.org/api_docs/python/tf/image)

```
adjust_brightness(...): Adjust the brightness of RGB or Grayscale images.
adjust_contrast(...): Adjust contrast of RGB or grayscale images.
                          decode_bmp(...): Decode the first frame of a BMP-encoded image to a uint8 tensor.
adjust_gamma(...): Perform
                          decode_gif(...): Decode the first frame of a GIF-en random_flip_up_down(...): Randomly flips an image vertically (ups
adjust_hue(...): Adjust hue
                          decode_image(...): Convenience function for deco random_hue(...): Adjust the hue of an RGB image by a random factor
adjust_saturation(...):A
                                                                           random_saturation(...): Adjust the saturation of an RGB image by
central_crop(...): Crop the decode_jpeg(...): Decode flip_left_right(...)
                                                                           resize_area(...): Resize images to size using area interpolation
convert image dtype(...) decode_png(...): Decode: flip up down(...):Fl
                                                                           resize_bicubic(...): Resize images to size using bicubic interp
crop_and_resize(...):Extr draw_bounding_boxes(... grayscale_to_rgb(...
                                                                           resize_bilinear(...): Resize images to size using bilinear inter
crop_to_bounding_box(...) encode_jpeg(...):JPEG-e hsv_to_rgb(...):Con
                                                                           resize_image_with_crop_or_pad(...): Crops and/or pads an image.
decode\_and\_crop\_jpeg(...) encode\_png(...) : PNG-enc is\_jpeg(...) : Convenience
                                                                           resize_images(...): Resize images to size using the specified m
                          extract_glimpse(...):Ex non_max_suppression(
                                                                           resize_nearest_neighbor(...): Resize images to size using ne
                          per_image_standardiz rgb_to_hsv(...): Converts one or more images from RGB to HSV.
                                                     random brightness(..rgb_to_yiq(...): Converts one or more images from RGB to YIQ.
                                                     random_contrast(...) rgb_to_yuv(...) : Converts one or more images from RGB to YUV.
                                                                           rot90(...): Rotate image(s) counter-clockwise by 90 degrees.
                                                                           sample_distorted_bounding_box(...): Generate a single random!
```

```
with tf.variable scope('conv1') as scope:
  weights = tf.get_variable('weights',
                            dtype=tf.float32,
                            initializer=tf.truncated_normal_initializer(stddev=0.1, dtype=tf.float32))
  biases = tf.get_variable('biases',
                           dtype=tf.float32.
                           initializer=tf.constant_initializer(0.1))
  conv = tf.nn.conv2d(images, weights, strides=[1, 1, 1, 1], padding='SAME')
  pre_activation = tf.nn.bias_add(conv, biases)
  conv1 = tf.nn.relu(pre_activation, name=scope.name)
with tf.variable_scope('pooling1_lrn') as scope:
  pool1 = tf.nn.max_pool(conv1, ksize=[1, 3, 3, 1], strides=[1, 2, 2, 1],
                         padding='SAME', name='pooling1')
with tf.variable_scope('conv2') as scope:
 weights = tf.get variable('weights',
                            dtype=tf.float32,
                            initializer=tf.truncated_normal_initializer(stddev=0.1, dtype=tf.float32))
  biases = tf.get_variable('biases',
                           dtype=tf.float32,
                           initializer=tf.constant initializer(0.1))
  conv = tf.nn.conv2d(pool1, weights, strides=[1, 1, 1, 1], padding='SAME')
  pre_activation = tf.nn.bias_add(conv, biases)
  conv2 = tf.nn.relu(pre_activation, name='conv2')
with tf.variable_scope('pooling2_lrn') as scope:
  pool2 = tf.nn.max_pool(conv2, ksize=[1, 3, 3, 1], strides=[1, 1, 1, 1],
                         padding='SAME', name='pooling2')
```

```
with tf.variable_scope('local3') as scope:
 reshape = tf.reshape(pool2, shape=[batch_size, -1])
 dim = reshape.get_shape()[1].value
 weights = tf.get_variable('weights',
                            shape=[dim, 128],
                            dtype=tf.float32,
                            initializer=tf.truncated_normal_initializer(stddev=0.005, dtype=tf.float32))
 biases = tf.get_variable('biases',
                           dtype=tf.float32,
                           initializer=tf.constant_initializer(0.1))
  local3 = tf.nn.relu(tf.matmul(reshape, weights)+biases, name=scope.name)
with tf.variable_scope('local4') as scope:
 weights = tf.get_variable('weights',
                            dtype=tf.float32.
                            initializer=tf.truncated_normal_initializer(stddev=0.005, dtype=tf.float32))
 biases = tf.get_variable('biases',
                           dtype=tf.float32,
                           initializer=tf.constant_initializer(0.1))
 local4 = tf.nn.relu(tf.matmul(local3, weights)+biases, name='local4')
with tf.variable_scope('softmax_linear') as scope:
 weights = tf.get_variable('softmax_linear',
                            dtype=tf.float32,
                            initializer=tf.truncated_normal_initializer(stddev=0.005, dtype=tf.float32))
 biases = tf.get_variable('biases',
                           dtype=tf.float32,
                           initializer=tf.constant_initializer(0.1))
  softmax_linear = tf.add(tf.matmul(local4, weights), biases, name='softmax linear')
```

```
def _run():
  train, train_label = get_files(data_path=data_path,datafolder=datafolder)
  train batch, train label batch = get batch(train,
                                              train label,
                                              img_W,
                                              img_H,
                                              batch_size,
                                              batch size*2)
  train_logits = inference(train_batch, batch_size, n_classes)
  train_loss = losses(train_logits, train_label_batch)
  train_op = trainning(train_loss, learning_rate)
  train_acc = evaluation(train_logits, train_label_batch)
  summary_op = tf.summary.merge_all()
  sess = tf.Session()
  train writer = tf.summary.FileWriter(logs_train_dir, sess.graph)
  saver = tf.train.Saver()
  sess.run(tf.global_variables_initializer())
  coord = tf.train.Coordinator()
  threads = tf.train.start_queue_runners(sess=sess, coord=coord)
  try:
    for step in np.arange(10000):
      if coord.should_stop():
        break
      _, tra_loss, tra_acc = sess.run([train_op, train_loss, train__acc])
```

Tensorflow 요약

- ConvNet 기반 MNIST 분석
- 나만의 데이터를 이용한 데이터 분석
- 다양한 방식의 코드 분석

To be continued...