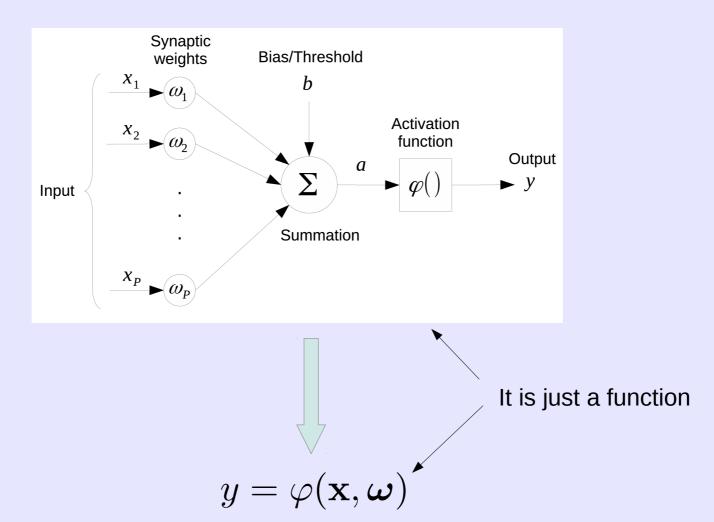
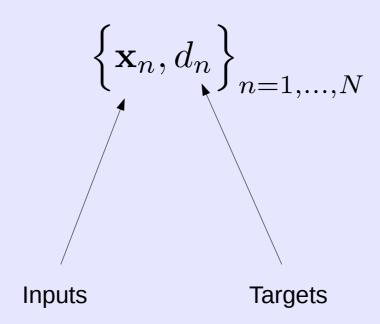
The perceptron - details



Summary of the "perceptron"

We have data, typically called a training dataset!



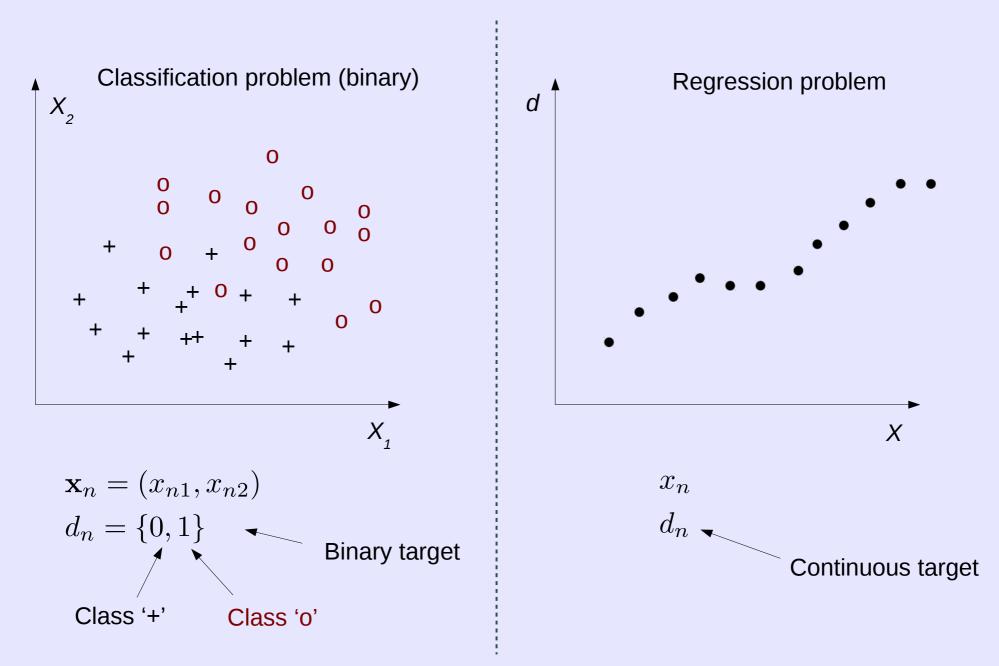
An example (MNIST database)!



Inputs = 28 x 28 grayscale images

Targets = $\{ (0', 1', 2', 3', 4', 5', 6', 7', 8', 9' \}$

We are going to use simpler datasets, that are easier to illustrate



So, we have

$$y(\mathbf{x}_n) = \varphi(\mathbf{x}_n, oldsymbol{\omega})$$
 $\left\{\mathbf{x}_n, d_n\right\}$ Perceptron Training data

Task!

$$y_n = d_n$$
, $\forall n$

How?

Summary of the "perceptron"

Common approach, construct an error function, e.g.

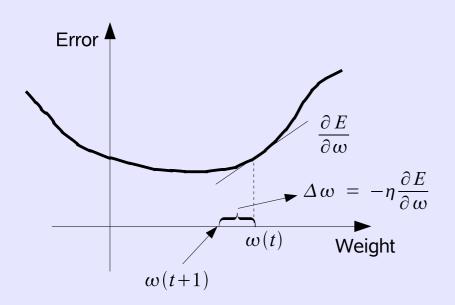
$$E(\boldsymbol{\omega}) = \frac{1}{N} \sum_{n=1}^{N} (y(\mathbf{x}_n) - d_n)^2$$

A function of the weights!

Minimizing E(w) means "solving" the task (or at least an attempt to solve it)

How?

Minimize using gradient descent



$$\Delta\omega_i = -\eta \frac{\partial E(\boldsymbol{\omega})}{\partial \omega_i}$$

$$\Delta\omega_i = -\eta \frac{1}{N} \sum_n \frac{\partial E_n(\boldsymbol{\omega})}{\partial \omega_i}$$

Stochastic gradient descent (SGD)

$$\Delta\omega_i = -\eta \frac{1}{P} \sum_{p=1}^{P} \frac{\partial E_p(\boldsymbol{\omega})}{\partial \omega_i}$$

Where *P* is typically between 10-15 (randomly selected from the training data)

Finally!

$$y(\mathbf{x}_n) = \varphi(\mathbf{x}_n, oldsymbol{\omega}) \qquad \left\{ \mathbf{x}_n, d_n
ight\}$$
Perceptron Training data

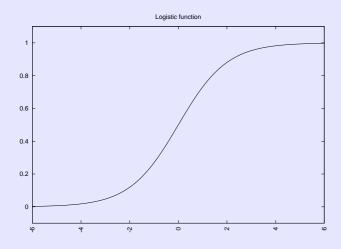
Train the perceptron using SGD

$$\omega_i \to \omega_i - \eta \frac{1}{P} \sum_{p=1}^P \frac{\partial E_p(\boldsymbol{\omega})}{\partial \omega_i}$$

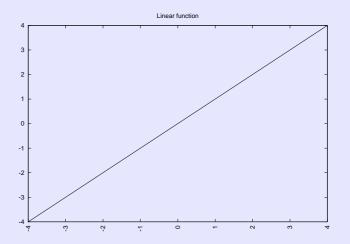
Repeat until convergence!

What about activation functions for the perceptron?

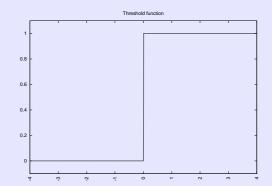
Classification problems



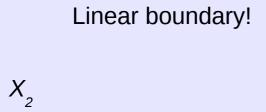
Regression problems

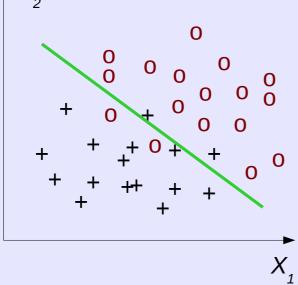


Not so common!

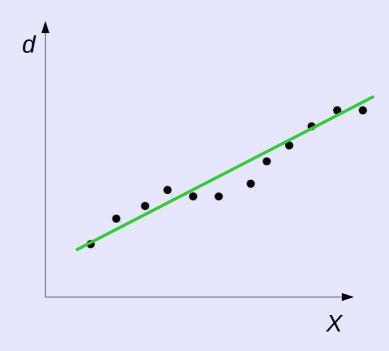


Fundamental limitation of the perceptron!





Linear regression!



To "get around" this limitation, we introduce a hidden layer → Multi-Layer Perceptron (MLP)

