

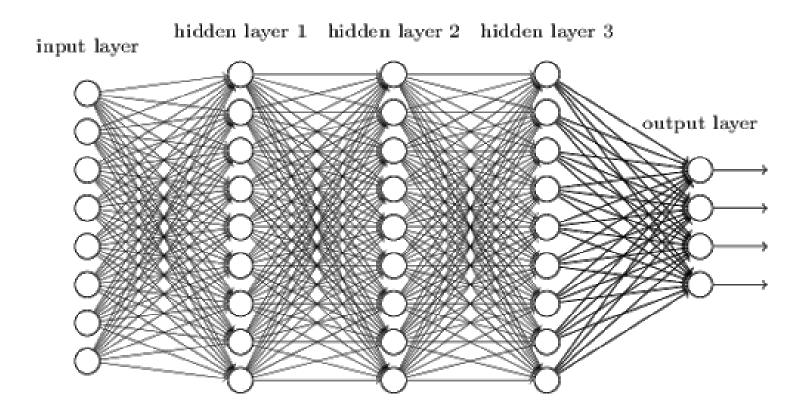
Lecture 4 – Machine Learning Models





Limitations of "regular" Neural Nets

Fully connected network

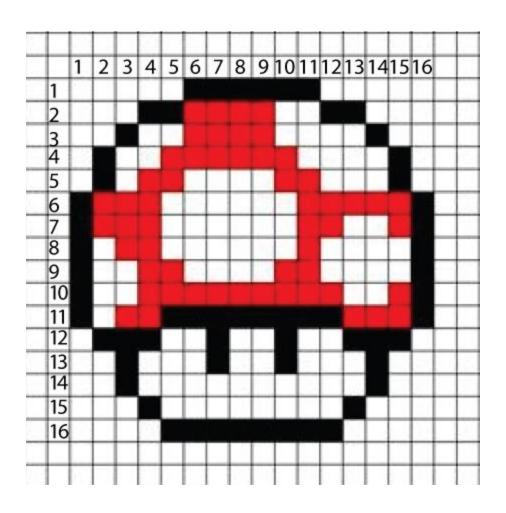


Outline – Lecture 4

Other types of neural network models

- Convolutional Neural Networks
- Recurrent Neural Networks (RNNs)
- Locally Connected Networks (LCNs)

Spatially structured data

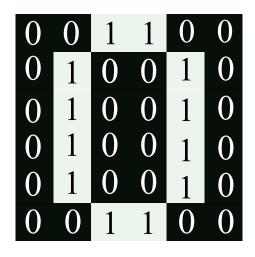


An image is more than the sum of its pixels

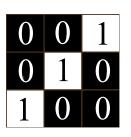
i.e. the relative position of data points contain information, not just the pixel colors

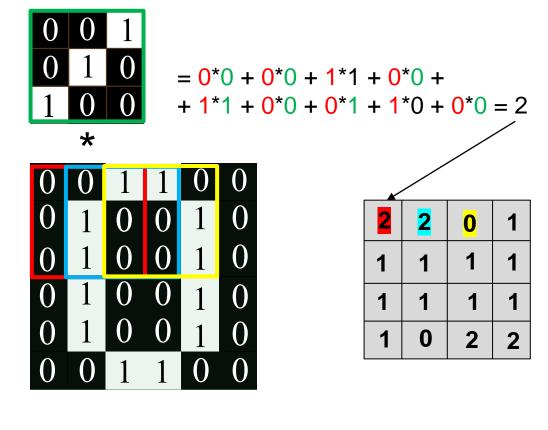
How can we build an ANN that takes advantage of this?

The convolution operation



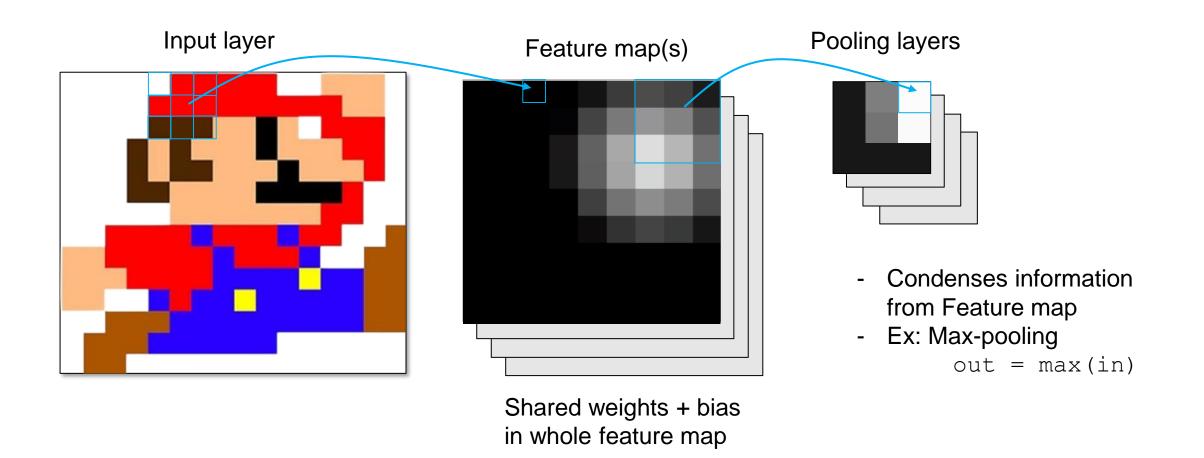
image





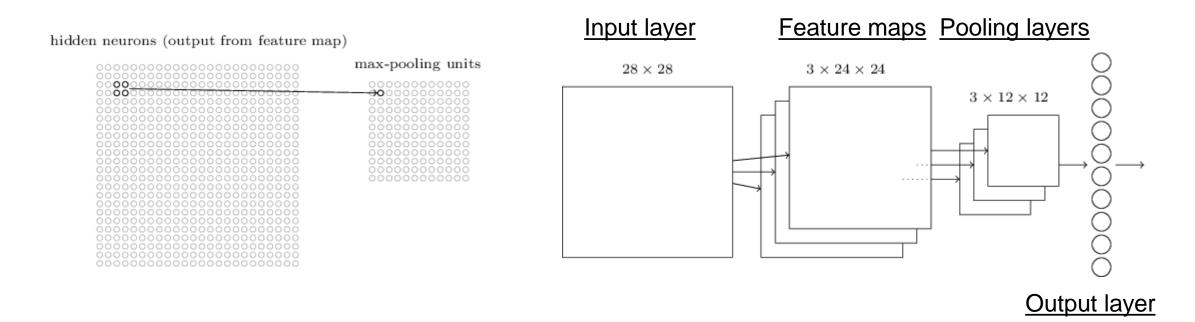
"Filter" Feature map

Convolution in an ANN



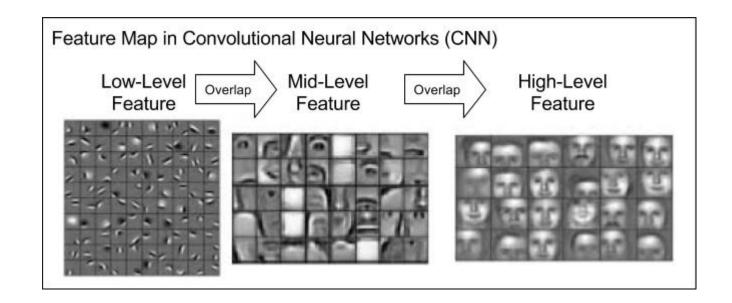
Convolutional Neural Network (CNN)

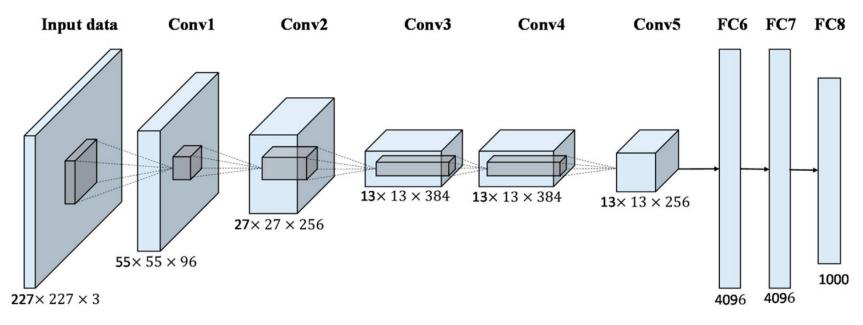
- A multitude of feature maps
- One pooling layer per feature map
 - L2 pooling: root of the sum of squares
- The Output layer is a normal completely connected layer to all neurons in the pooling layers



A full CNN

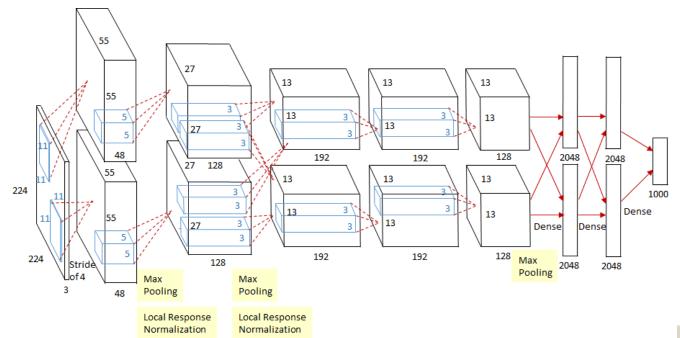
- Multiple convolutional layers for various levels of features.
- Data size reduced between layers
- For classification: Finish off with fullyconnected layers





Classification Example

- AlexNet: Pioneer in CNNs, now standard for image classification
- First to use ReLU on CNNs
- 5 conv. Layers + 2 FCLs → 62.3 million parameters (!)
- 6 days to train
- → Won the 2012 ImageNet competition by a large margin
- → Top 1 accuracy of 62.5% (Top 5: 83%)



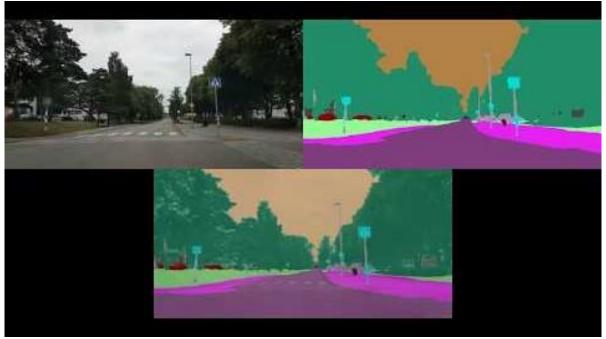
ImageNet

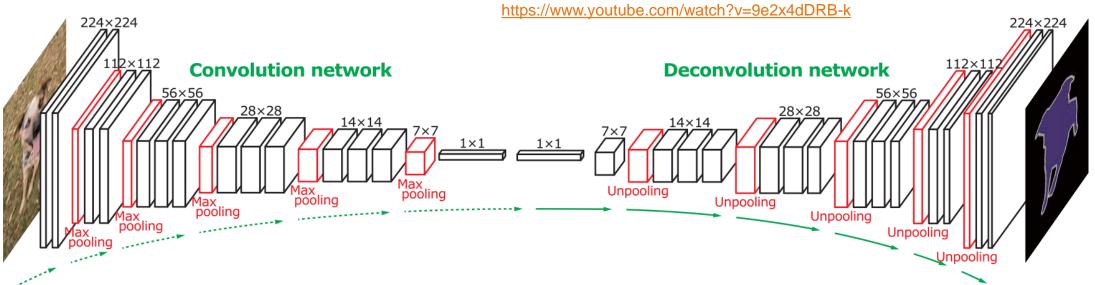
15 million high-res images in ~22000 categories



Other example

- Image segmentation
- Upscale features by "deconvolution"





Sequences

- CNNs see spatial correlations
- But what about if the order of data matters?
- Q: Examples?

How can one predict what comes next, given an existing sequence of data?

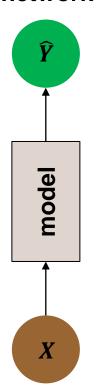
The pony ate the hat of my father

The hat of my father ate the pony

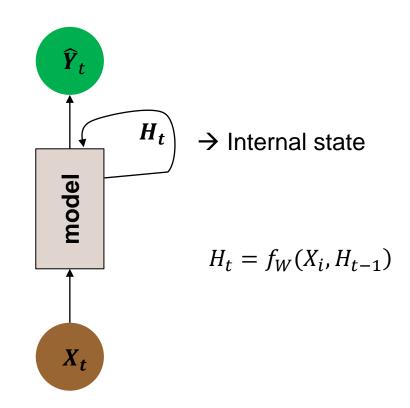
The of hat pony ate the father my

Recurrent Neural Networks

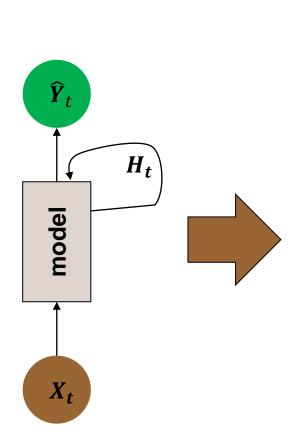
Standard "feed-forward" network

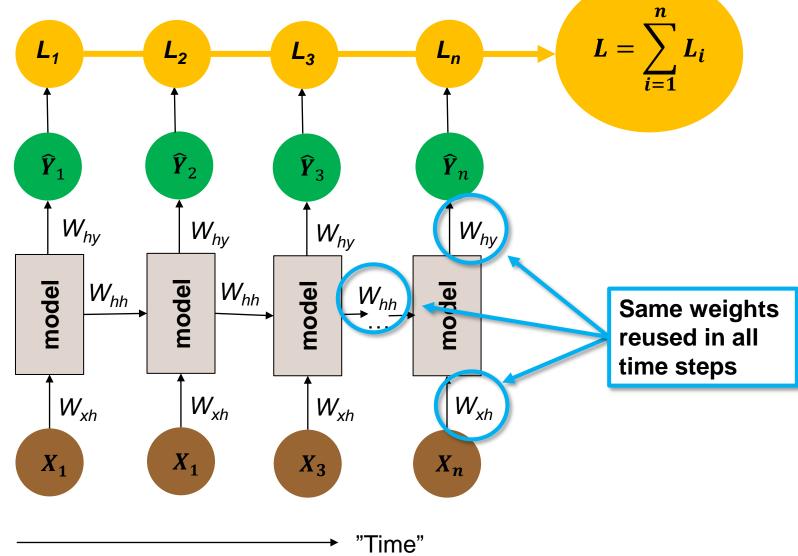


Recurrent network



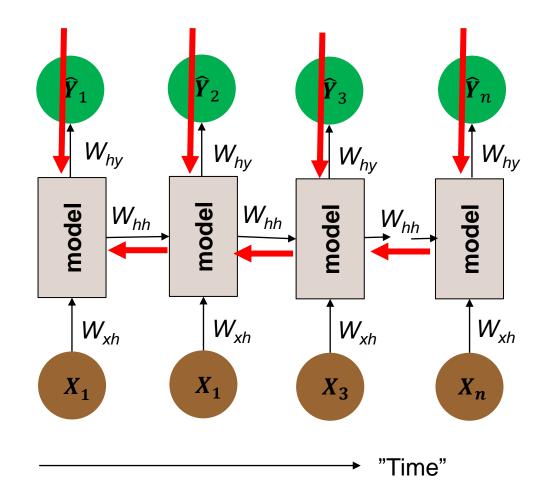
RNNs - Forward pass





RNNs - Backpropagation through time

- Training by backpropagation involves propagating gradients backwards through each time step.
- Each step consists of a matrix multiplication with W_{hh} and gradient of activation function.
- Q: Potential issues?



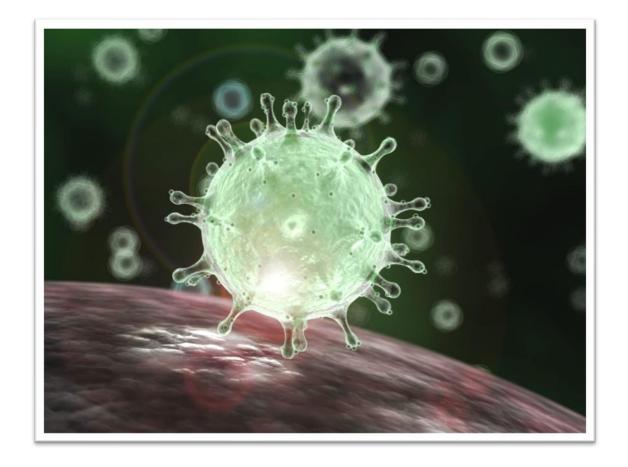
Vanishing gradient problem

Vanishing gradient → biasing to capture recent (short-term) dependencies

Short-term The virus gave me the ____.

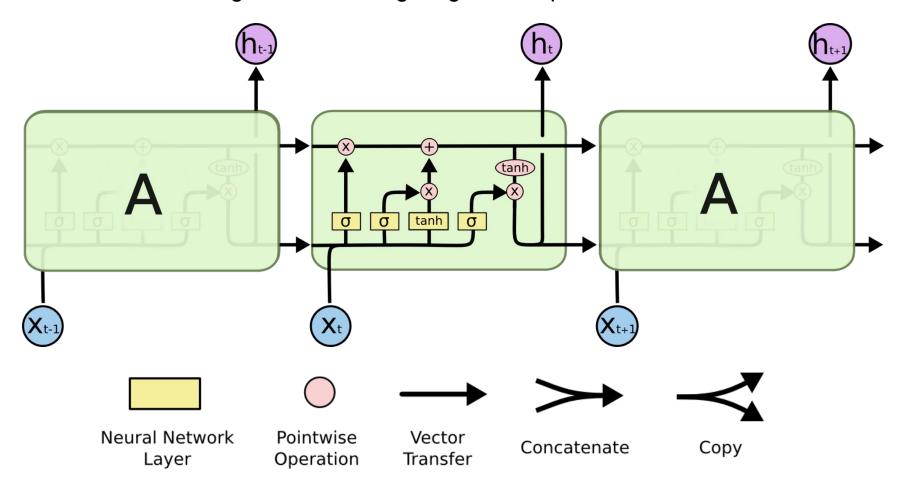
Long-term

A virus is an infective agent that typically consists of a nucleic acid molecule in a protein coat and can give a person the ____.



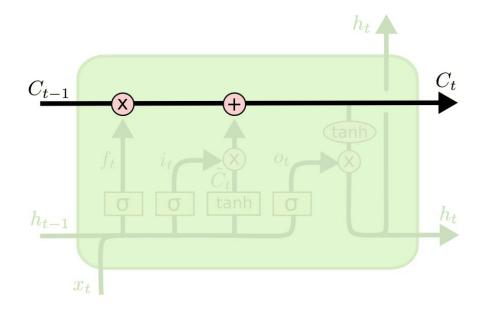
Long Short Term Memory Networks

• LSTM: Recurrent units that are good for tracking long-term dependencies



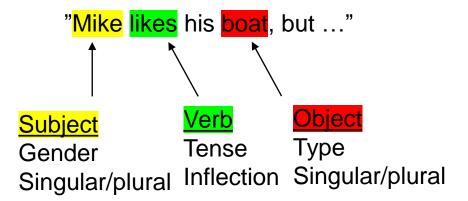
Important features of LSTMs

Cell statewith easy information transfer through time

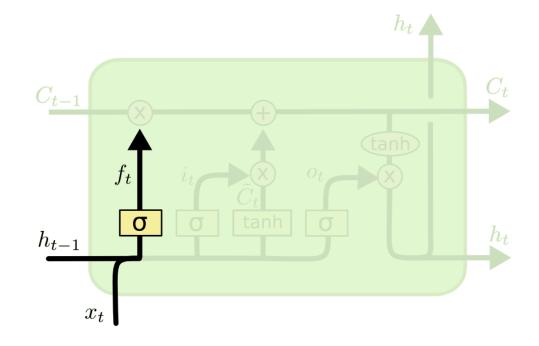


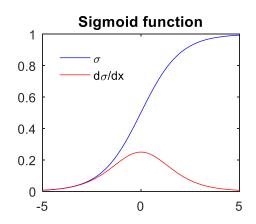
- Only elementwise multiplication and addition
- Avoids vanishing gradient problem!

Example:



1. What to forget

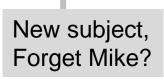




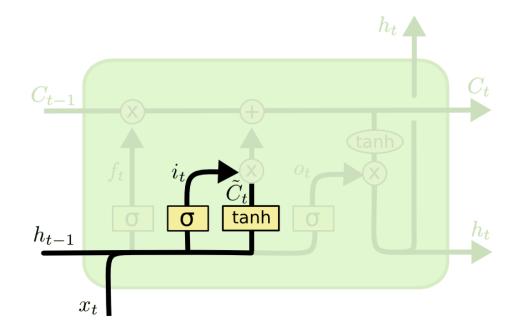
$$f_t = \sigma\left(W_f \cdot [h_{t-1}, x_t] + b_f\right)$$

"Mike likes his boat, but Maria..."

- f_t outputs 0...1 for each element in C_{t-1} , based on h_{t-1} and x_t
- $f_t = 0 \rightarrow \text{completely forget}$
- $f_t = 1 \rightarrow \text{completely remember}$



2. What to update



$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

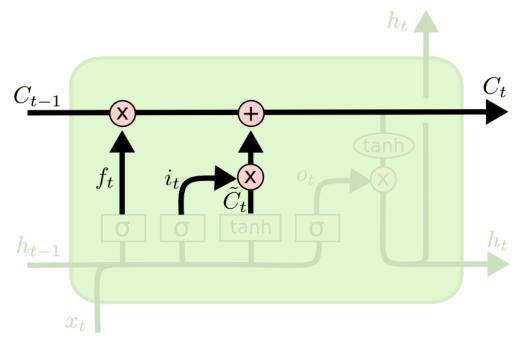
$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

"Mike likes his boat, but Maria..."

- tanh-layer creates new candidates for cell state C (like in regular RNN)
- σ -layer decides which of these to update (factor 0..1)

Candidate for new Subject

Updating cell state



 $C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$

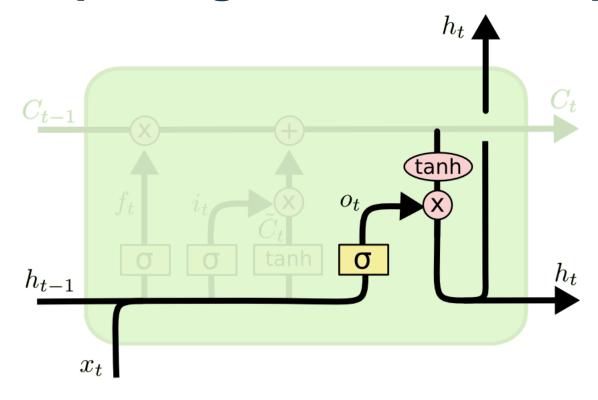
Cell state is updated elementwise! (computationally cheap)

"Mike likes his boat, but Maria..."

Update C by forgetting Mike

Update C with new Subject

Outputting to next timestep



- tanh-function bounds output between -1 and 1
- σ -layer decides what to output (factor 0..1)
 - Relevant to what should come next (verb etc)

$$o_t = \sigma (W_o [h_{t-1}, x_t] + b_o)$$
$$h_t = o_t * \tanh (C_t)$$

opposition

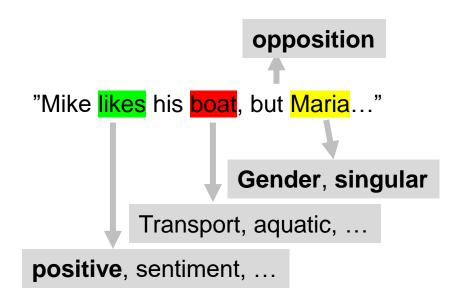
"Mike likes his boat, but Maria..."

Gender, singular

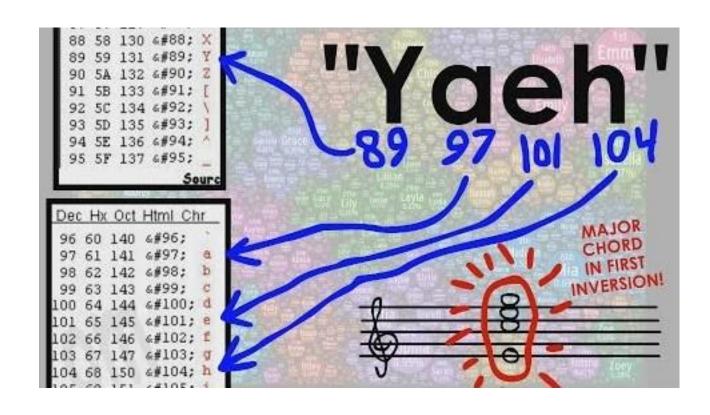
Transport, aquatic, ...

positive, sentiment, ...

2 min Exercise – What could come next?

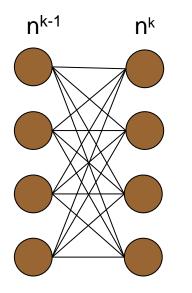


Example – Music generation

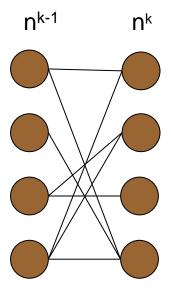


Sparse and Locally connected networks

- Typical parameter size in Neural Network: 1-10 million
 - Work-intensive
 - Risk of overfitting
 - Scalability issues!



$$n^{k-1} \times n^k$$
 synapses



 $O(n^{k-1} + n^k)$ synapses

- Can layers with $O(n^{k-1} + n^k)$ connections perform as good?
- What type of connectivity would then be ideal?

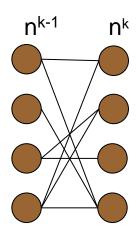
Sparse Network topologies

Erdos-Renyi network

(random graph)

$$P(W_{ij}^k) = \frac{\varepsilon(n^k + n^{k-1})}{n^k n^{k-1}}, \varepsilon \in \mathbb{R}^+$$

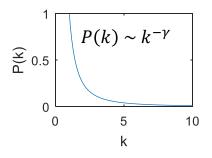
$$\rightarrow |W^k| = \varepsilon(n^k + n^{k-1}) \text{ if } \varepsilon \ll n^k, n^{k-1}$$

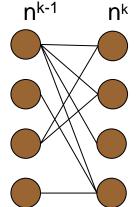


$$O(n^{k-1} + n^k)$$
 synapses

Scale-free network

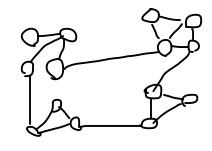
(few nodes with many connections)

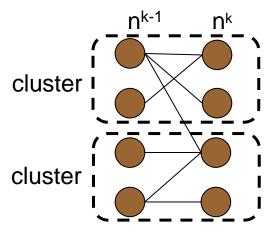




Small world network

(most nodes are not neighbors, but connected in a few steps)





Example – Adaptive sparse connectivity

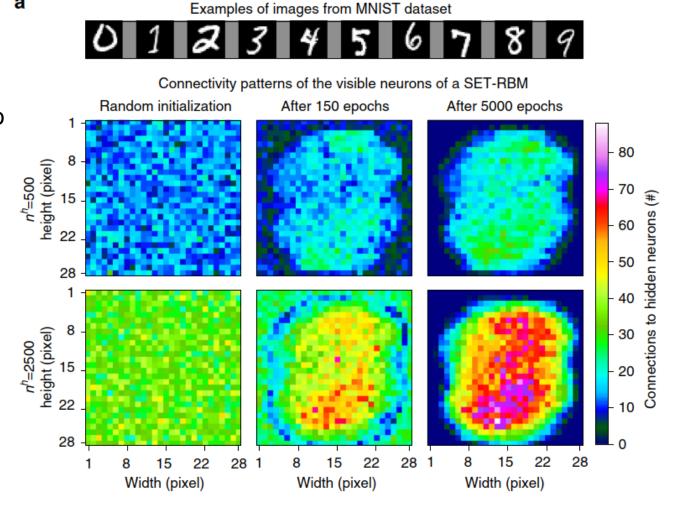
Sparse-Evolutionary-Training (SET) algorithm

```
Algorithm 1: SET pseudocode
               1 %Initialization:
               2 initialize ANN model;
               3 set \varepsilon and \zeta:
               4 for each bipartite fully-connected (FC) layer of the ANN do
                      replace FC with a Sparse Connected (SC) layer having a Erdős-Rényi topology given by \varepsilon and Eq.1:
               6 end
               7 initialize training algorithm parameters;
               8 %Training;
               9 for each training epoch e do
                      perform standard training procedure;
               10
                      perform weights update;
              11
                      for each bipartite SC layer of the ANN do
               12
                          remove a fraction \zeta of the smallest positive weights;
               13
                          remove a fraction \zeta of the largest negative weights;
               14
                          if e is not the last training epoch then
               15
                               add randomly new weights (connections) in the same amount as the ones removed previously;
               16
                          end
               17
               18
                      end
              19 end
```

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Clustering of connections

- Towards end of training:
 - Pixels in the center of the images (MNIST) have many connections
 - Pixels on the edges have few or zero connections
- → Natural data-dependent clustering (scale-free network?)

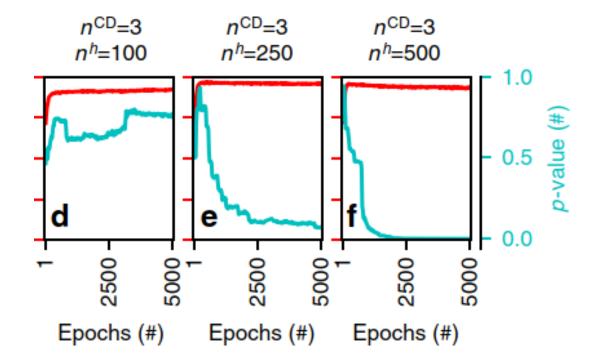


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Evolution towards scale-free network

- Indeed: Adaptive sparsity evolves towards a scale-free network
- Starts from a binomal probability distribution (Erdos-Renyi)
- With enough neurons in a layer → scale-free (p < 0.05)

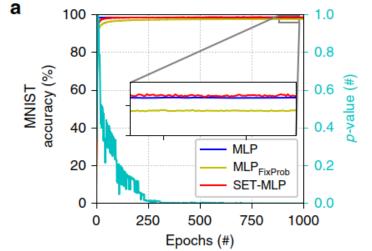


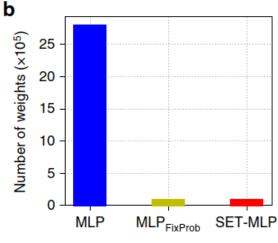
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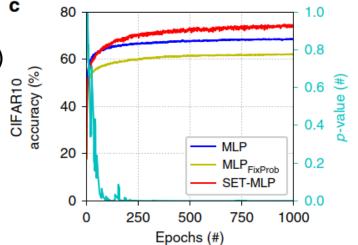
Results compared to fully connected networks

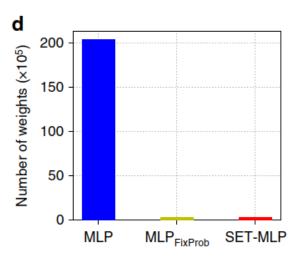
- MLP_{FixProb}: Fixed sparse network (E-R topology) ^a
- MLP: Fully connected network
- SET-MLP: Adaptively sparse network
- Fixed sparsity performs worst
 - 62% on CIFAR10
 - But with only 1.4% as many weights
- Adaptive sparsity outperforms all!
 - 75% on CIFAR10 (278K params)
 - 2nd best in literature has 74% (31M params)

	MLP	MLP _{FixProb}	SET-MLP
MNIST	98.55%	97.68%	98.74%
CIFAR10	68.70%	62.19%	74.84%









Possibilities with LCNs

- The sparsity enables:
 - MUCH larger models (1 billion neurons...) on supercomputers
 - Powerful tiny models trained directly on wearables
- Problem: GPU optimized for dense matrices, not for sparse..
 - More on GPU next lecture...

Summary

