Homework 1 Due:30/10/2022

Q1 A replica of the step() function of the Control system toolbox [y,t]=step_response(Gs,method) is to be coded. The function step_response accepts tf objects and the method to be used, converts the transfer function into state space representation,

$$\dot{x}(t) = Ax(t) + Bu(t) \quad y(t) = Cx(t) + Du(t)$$

since the step function is replicated, the input is going to be u=1. Implement the function using,

- [05p] the Control system toolbox's step function (method='default',color='k')
- [25p] the Mid point method (method='midpoint',color='r')
- [25p] the Heun method (method='heun',color='b')
- [25p] the 4th order Runge-kutta method (method='rkutta4',color='m')
- [10p] combine the methods on a single plot using assigned colors and showing their names in the legend, this plot is generated internally and only the method chosen is returned. You may use **stepinfo** to determine the time vector and choose h = 0.1 so that the difference of the results becomes obvious.
- [10p] Which method performs the best and why? (add your response as a comment)
- Submit a single *.m file to NINOVA. Other file types will not be accepted nor graded.
- The given main function is not going to be submitted, only the necessary implementation needs to be submitted.
- Your submission will be tested with a tester main.m file. Your code needs to run without error, or your grade will be zero.
- Each functionality will be tested and added to your grade.
- Late submissions will be deduced 10p for each day late.
- Cheating is not allowed, once cheating is detected all involved submissions will be graded zero.

```
%% UPLOAD ONLY THIS FILE
          [y,t]=step_response(Gs,method)
function
        %% default
        % default implementation goes here
        %% midpoint
        % midpoint implementation goes here
        %% heun
        % heun implementation goes here
        %% rkutta4
        % rkutta4 implementation goes here
        % plotting goes here
        % return of the result for given method method
end
%% Which method performs the best and why?
% response goes here
                           deliverables/step_response.m
%% DO NOT UPLOAD THIS FILE
clear; clc;
Gs = tf(1, [1 2*0.2*10 10^2]);
[y,t]=step_response(Gs,'midpoint');
                             deliverables/main.m
```