

ALGEBRAIC TOPOLOGY II LECTURE NOTES

HIDENORI SHINOHARA

CONTENTS

1. Geometric Description of Cocycles	1
2. Poincare Duality	4
2.1. Orientations	4
2.2. Poincare Duality (Version 1)	5
2.3. Cap Products	5
2.4. Poincare Duality (Version 2)	6
2.5. Differential Forms on \mathbb{R}^n	7

1. GEOMETRIC DESCRIPTION OF COCYCLES

Example 1.1. Let X be a Δ -complex and $\phi \in C^k(X; \mathbb{Z})$. What does it mean that $\delta\phi = 0$? As a toy model, we will consider a surface. One way to construct such a $\phi \in C^1(X; \mathbb{Z})$ is to take an oriented closed curve γ transverse to 1-simplices. Then we define $\phi(\sigma)$ to be the number of intersections between σ and γ with signs. See the following example:

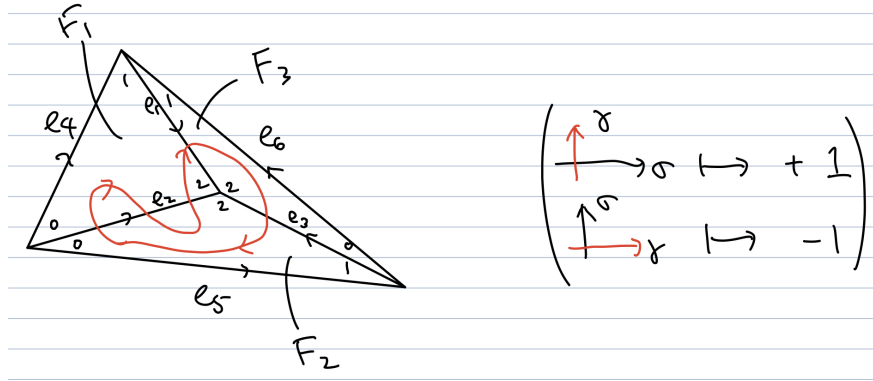


FIGURE 1. Oriented closed curve in a surface

γ gives us the following 1-cocycle ϕ which maps each e_i to an integer as following:

$$\begin{aligned}
 e_1 &\mapsto 1 \\
 e_2 &\mapsto 1 - 1 + 1 = 1 \\
 e_3 &\mapsto 1 \\
 e_4 &\mapsto 0 \\
 e_5 &\mapsto 0 \\
 e_6 &\mapsto 0.
 \end{aligned}$$

Then $\delta\phi = 0$ because

$$\begin{aligned}(\delta\phi)(F_1) &= \phi(\partial F_1) = \phi(e_1) - \phi(e_2) + \phi(e_4) = 0 \\(\delta\phi)(F_2) &= \phi(\partial F_2) = \phi(e_3) - \phi(e_2) + \phi(e_5) = 0 \\(\delta\phi)(F_3) &= \phi(\partial F_3) = \phi(e_1) - \phi(e_3) + \phi(e_6) = 0.\end{aligned}$$

This is not a coincidence because $\phi(\partial\sigma)$ represents

$$(\text{the number of times } \gamma \text{ enters } \sigma) - (\text{the number of times } \gamma \text{ exits } \sigma)$$

which is always 0 for any 2-simplex σ and any traverse closed oriented curve γ . In this case, we call ϕ the **Poincare dual** to γ , or simply $\phi = \text{PD}(\gamma)$, and this concept can be generalized further.

Definition 1.2. Let X be a topological manifold of dimension n . Let γ be an $(n-k)$ -cycle in X transverse to the k -skeleton of X . Define $\phi \in C^k(X; \mathbb{Z})$ such that

$$\phi(\sigma) = \text{The number of intersections between } \sigma \text{ and } \gamma \text{ with signs.}$$

Then we call ϕ the **Poincare dual** of γ and denote it by $\phi = \text{PD}(\gamma)$.

Example 1.3. We will look at a torus which is a slightly more complicated example. We obtain the following

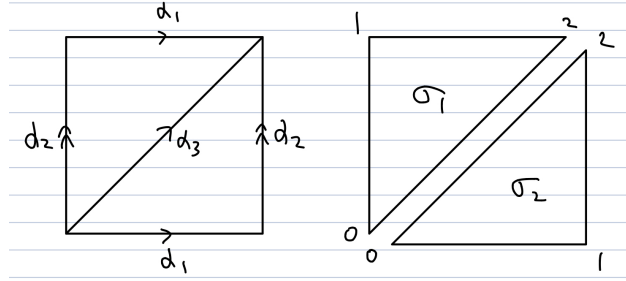


FIGURE 2. Torus

cellular chain complex from Figure 2:

$$C_2 = \langle \sigma_1, \sigma_2 \rangle \longrightarrow C_1 = \langle \alpha_1, \alpha_2, \alpha_3 \rangle \longrightarrow C_0 = \langle v \rangle$$

$$\sigma_i \longmapsto \alpha_1 + \alpha_2 - \alpha_3$$

$$\alpha_i \longmapsto 0$$

Thus

$$H_i(T^2) = \begin{cases} \mathbb{Z} & (i = 0, 2) \\ \mathbb{Z}^2 & (i = 1). \end{cases}$$

Now, we will examine the cellular cochain complex.

$$\begin{aligned}\delta(v^*)(\alpha_i) &= v^*(\partial\alpha_i) \\ &= v^*(0) \\ &= 0\end{aligned}$$

for any $\alpha_i \in C_1$. Therefore, $\delta(v^*) = 0$.

$$\begin{aligned}\delta(\alpha_1^*)(\sigma_i) &= \alpha_1^*(\partial(\sigma_i)) \\ &= \alpha_1^*(\alpha_1 + \alpha_2 - \alpha_3) \\ &= 1\end{aligned}$$

for any $\sigma_i \in C_2$. By performing similar calculation on α_2^* and α_3^* , we obtain

$$C^2 = \langle \sigma_1^*, \sigma_2^* \rangle \longleftarrow C^1 = \langle \alpha_1^*, \alpha_2^*, \alpha_3^* \rangle \longleftarrow C^0 = \langle v^* \rangle$$

$$\sigma_1^* + \sigma_2^* \longleftarrow \alpha_1^*, \alpha_2^*$$

$$-(\sigma_1^* + \sigma_2^*) \longleftarrow \alpha_3^*$$

$$0 \longleftarrow v^*$$

Thus

$$H^i(T^2) = \begin{cases} \mathbb{Z} & (i = 0, 2) \\ \mathbb{Z}^2 & (i = 1). \end{cases}$$

- $H^0(T^2) = \langle v^* \rangle / 0$, so $H^0(T^2)$ is generated by $[v^*]$.
- $H^2(T^2)$ is generated by $[\sigma_2^*]$ because $H^2(T^2) = \langle \sigma_1^*, \sigma_2^* \rangle / \langle \sigma_1^* + \sigma_2^* \rangle$.

We can picture $H^1(T^2)$ by using Poincare duals. Let $\phi_1 = \text{PD}(\gamma_1), \phi_2 = \text{PD}(\gamma_2)$. Then $\phi_1(\alpha_1) = 0, \phi_1(\alpha_2) =$

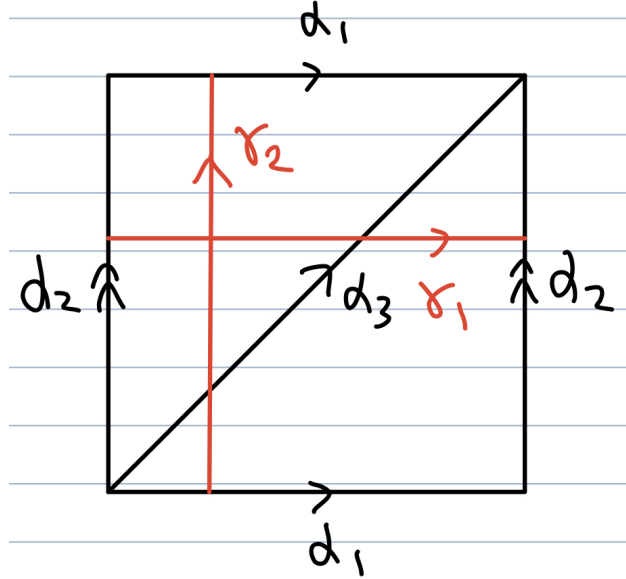


FIGURE 3. Torus Poincare Duals

1, $\phi_1(\alpha_3) = 1$, and $\phi_2(\alpha_1) = -1, \phi_2(\alpha_2) = 0, \phi_2(\alpha_3) = -1$. Moreover,

$$(\delta\phi_1)(\sigma_i) = \phi_1(\partial\sigma_i) = \phi_1(\alpha_1 + \alpha_2 - \alpha_3) = \phi_1(\alpha_1) + \phi_1(\alpha_2) - \phi_1(\alpha_3) = 0.$$

$$(\delta\phi_2)(\sigma_i) = \phi_2(\partial\sigma_i) = \phi_2(\alpha_1 + \alpha_2 - \alpha_3) = \phi_2(\alpha_1) + \phi_2(\alpha_2) - \phi_2(\alpha_3) = 0.$$

Therefore, the classes represented by ϕ_1, ϕ_2 are in $H^1(T^2; \mathbb{Z})$. Moreover, they clearly generate $H^1(T^2; \mathbb{Z})$, so every element in $H^1(T^2; \mathbb{Z})$ can be considered as a function with a fixed closed curve that counts the number of times the curve intersects a given 1-simplex.

Now, we will examine the cup product structure. By definition, we know that $[\phi_1] \smile [\phi_2] \in H^2(T^2; \mathbb{Z})$. Therefore, we will check what σ_1, σ_2 get sent to.

$$\begin{aligned} (\phi_1 \smile \phi_2)(\sigma_1) &= \phi_1(\sigma_1|_{[0,1]})\phi_2(\sigma_1|_{[1,2]}) \\ &= \phi_1(\alpha_2)\phi_2(\alpha_1) \\ &= -1 \cdot 1 = -1. \\ (\phi_1 \smile \phi_2)(\sigma_2) &= \phi_1(\sigma_2|_{[0,1]})\phi_2(\sigma_2|_{[1,2]}) \\ &= \phi_1(\alpha_1)\phi_2(\alpha_2) \\ &= 0. \end{aligned}$$

Recall that $[\sigma_1^* + \sigma_2^*] = 0$ because $\sigma_1^* + \sigma_2^*$ is in the kernel. Therefore, $[\phi_1 \smile \phi_2] = [-\sigma_1^*] = [\sigma_2^*]$. Similarly, we obtain $(\phi_2 \smile \phi_1)(\sigma_1) = 0$ and $(\phi_2 \smile \phi_1)(\sigma_2) = -1$. Thus $[\phi_2 \smile \phi_1] = -[\sigma_2^*]$.

I don't understand the alternative approach using the universal coefficient theorem.

Finally, we obtain the following multiplication table for $H^*(T^2; \mathbb{Z}) \cong \mathbb{Z}\langle 1, [\phi_1], [\phi_2], [\sigma_2^*] \rangle$:

\smile	1	$[\phi_1]$	$[\phi_2]$	$[\sigma_2^*]$
1	1	$[\phi_1]$	$[\phi_2]$	$[\sigma_2^*]$
$[\phi_1]$	$[\phi_1]$	0	$[\sigma_2^*]$	0
$[\phi_2]$	$[\phi_2]$	$-[\sigma_2^*]$	0	0
$[\sigma_2^*]$	$[\sigma_2^*]$	0	0	0

2. POINCARÉ DUALITY

Since $H^*(T^n) \cong \wedge_{\mathbb{Z}} M$ where $M = \langle v_1, \dots, v_n \rangle$, we have

k	0	1	2	\dots	$n-1$	n
$\text{rank } H^k(T^n; \mathbb{Z})$	$\binom{n}{0}$	$\binom{n}{1}$	$\binom{n}{2}$	\dots	$\binom{n}{n-1}$	$\binom{n}{n}$

This symmetry phenomenon is true in general and very useful. Another example: The cellular complex for \mathbb{CP}^n is $\mathbb{Z} \rightarrow 0 \rightarrow \mathbb{Z} \rightarrow 0 \rightarrow \dots \rightarrow 0 \rightarrow \mathbb{Z} \rightarrow 0$. Thus

k	0	1	2	\dots	$2n-1$	$2n$
$\text{rank } H^k(\mathbb{CP}^n; \mathbb{Z})$	1	0	1	\dots	0	1

2.1. Orientations.

Definition 2.1. Let M be a triangulable closed n -manifold. Let $\sigma_1, \dots, \sigma_k$ be n -simplices such that $M = \sigma_1 \cup \dots \cup \sigma_k$. Then $\sigma_i \in C_n(M)$ for each i . Suppose that the ordering of the vertices in σ_i and the signs \pm can be chosen such that

$$\sum \pm \partial \sigma_i = 0 \in C_{n-1}(M).$$

Then M is said to be *orientable*.

Example 2.2. A tetrahedron and torus are examples of orientable manifolds.

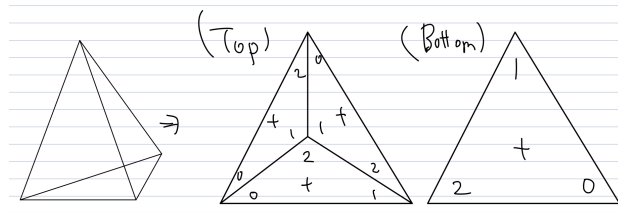


FIGURE 4. Orientation of a tetrahedron

Definition 2.3. Let M be an n -dimensional orientable manifold. Choose $\sigma_i \in C_n(M)$ and signs $\text{sgn}_i \in \{-1, 1\}$ such that $M = \sigma_1 \cup \dots \cup \sigma_k$ and $\sum \text{sgn}_i \partial \sigma_i = 0$. The class represented by $\sum \text{sgn}_i \sigma_i \in \ker(\partial)$ in $H_n(M)$ is called a fundamental class $[M]$.

Theorem 2.4. If M connected, then $[M]$ is a generator of $H_n(M)$.

Proof. By Poincare Duality (which will be discussed later (2.7)), $H_n(M) \cong H^0(M) = \mathbb{Z}$. Let $\sum c_i \sigma_i$ represent a generator of $H_n(M)$ where $c_i \in \mathbb{Z}$. Then $\sum \text{sgn}_i \sigma_i = \lambda \sum c_i \sigma_i = \sum (\lambda c_i) \sigma_i$ for some $\lambda \in \mathbb{Z}$. Since each $\lambda c_i = \text{sgn}_i \in \{-1, 1\}$, λ must be 1 or -1. Therefore, the class represented by $\sum \text{sgn}_i \sigma_i$ is a generator of $H_n(M)$. \square

Corollary 2.5. There are two fundamental classes for any connected orientable manifold.

Proof. By (2.4), a fundamental class $[M]$ is a generator of $H_n(M) = \mathbb{Z}$. Since \mathbb{Z} has exactly two generators 1, -1, M has exactly two fundamental classes. \square

Definition 2.6. Let M be a connected, orientable manifold. Then a choice of a fundamental class is called an orientation of M .

2.2. Poincare Duality (Version 1).

Theorem 2.7. If M is an orientable closed n -manifold, then

$$H^k(M; G) \cong H_{n-k}(M; G)$$

for any integer $0 \leq k \leq n$ and an abelian group G .

Remark. If M is not orientable, Poincare Duality holds when $G = \mathbb{Z}/2$. In other words,

$$H^k(M; \mathbb{Z}/2) \cong H_{n-k}(M; \mathbb{Z}/2).$$

For instance,

$H_*(\mathbb{RP}^2; \mathbb{Z})$	0	$\mathbb{Z}/2$	\mathbb{Z}
$H^*(\mathbb{RP}^2; \mathbb{Z})$	$\mathbb{Z}/2$	0	\mathbb{Z}

so Poincare Duality does not hold in this case. However, with $\mathbb{Z}/2$,

$H_*(\mathbb{RP}^2; \mathbb{Z}/2)$	$\mathbb{Z}/2$	$\mathbb{Z}/2$	$\mathbb{Z}/2$
$H^*(\mathbb{RP}^2; \mathbb{Z}/2)$	$\mathbb{Z}/2$	$\mathbb{Z}/2$	$\mathbb{Z}/2$

so Poincare Duality holds in this case.

Definition 2.8. The k th Betti number of a manifold M is defined to be $b_k = \text{rank}(H^k(M; \mathbb{Z}))$.

Theorem 2.9. $b_k = b_{n-k}$ for all k if M is a closed orientable n -manifold.

Proof. By the Universal Coefficient Theorem, $\text{rank}(H^k(M)) = \text{rank}(H_k(M))$. By Poincare Duality, $\text{rank}(H^k(M)) = \text{rank}(H_{n-k}(M))$. Therefore, $b_k = \text{rank}(H^k(M)) = \text{rank}(H_{n-k}(M)) = \text{rank}(H^{n-k}(M)) = b_{n-k}$. \square

2.3. Cap Products. There is a nice way to explicitly write down the isomorphism when G is a commutative ring.

Definition 2.10. Let a space X and a commutative ring R be given. For any $k \geq l$, define the cap product

$$\frown: C_k(X; R) \otimes C^l(X; R) \longrightarrow C_{k-l}(X; R)$$

$$\sigma \otimes \phi \longmapsto \phi(\sigma|_{[v_0, \dots, v_l]}) \sigma|_{[v_l, \dots, v_k]}$$

Theorem 2.11. $\partial(\sigma \frown \phi) = (-1)^l((\partial\sigma) \frown \phi - \sigma \frown (\partial\phi))$.

Proof. Let $k \geq l, \sigma \in C_{k+1}(X; R), \phi \in C^l(X; R)$ be given.

$$\begin{aligned}
(\partial\sigma) \frown \phi &= \left(\sum_j (-1)^j \sigma|_{[v_0, \dots, \hat{v}_j, \dots, v_k]} \right) \frown \phi \\
&= \sum_j (-1)^j (\sigma|_{[v_0, \dots, \hat{v}_j, \dots, v_k]} \frown \phi) \\
&= \sum_{j=1}^l (-1)^j \phi(\sigma|_{[v_0, \dots, \hat{v}_j, \dots, v_{l+1}]}) \sigma|_{[v_{l+1}, \dots, v_k]} + \sum_{j=l+1}^k (-1)^j \phi(\sigma|_{[v_0, \dots, v_l]}) \sigma|_{[v_l, \dots, \hat{v}_j, \dots, v_k]} \\
&= \sum_{j=1}^l (-1)^j \phi(\sigma|_{[v_0, \dots, \hat{v}_j, \dots, v_{l+1}]}) \sigma|_{[v_{l+1}, \dots, v_k]} + (-1)^{l+1} \phi(\sigma|_{[v_0, \dots, v_l, \hat{v}_{l+1}]}) \sigma|_{[v_{l+1}, \dots, v_k]} \\
&\quad + (-1)^l \phi(\sigma|_{[v_0, \dots, v_l]}) \sigma|_{[\hat{v}_l, v_{l+1}, \dots, v_k]} + \sum_{j=l+1}^k (-1)^j \phi(\sigma|_{[v_0, \dots, v_l]}) \sigma|_{[v_l, \dots, \hat{v}_j, \dots, v_k]} \\
&= \sum_{j=1}^{l+1} (-1)^j \phi(\sigma|_{[v_0, \dots, \hat{v}_j, \dots, v_{l+1}]}) \sigma|_{[v_{l+1}, \dots, v_k]} + \sum_{j=l}^k (-1)^j \phi(\sigma|_{[v_0, \dots, v_l]}) \sigma|_{[v_l, \dots, \hat{v}_j, \dots, v_k]}.
\end{aligned}$$

We will compute each summand.

$$\begin{aligned}
\sum_{j=1}^{l+1} (-1)^j \phi(\sigma|_{[v_0, \dots, \hat{v}_j, \dots, v_{l+1}]}) \sigma|_{[v_{l+1}, \dots, v_k]} &= \phi \left(\sum_{j=1}^{l+1} (-1)^j \sigma|_{[v_0, \dots, \hat{v}_j, \dots, v_{l+1}]} \right) \sigma|_{[v_{l+1}, \dots, v_k]} \\
&= \phi(\partial\sigma|_{[v_0, \dots, v_{l+1}]}) \sigma|_{[v_{l+1}, \dots, v_k]} \\
&= \sigma \frown \delta\phi.
\end{aligned}$$

On the other hand,

$$\begin{aligned}
\sum_{j=l}^k (-1)^j \phi(\sigma|_{[v_0, \dots, v_l]}) \sigma|_{[v_l, \dots, \hat{v}_j, \dots, v_k]} &= (-1)^l \sum_{j=0}^{k-l} (-1)^j \phi(\sigma|_{[v_0, \dots, v_{l+j}]}) \sigma|_{[v_l, \dots, \hat{v}_{l+j}, \dots, v_k]} \\
&= (-1)^l \partial(\phi(\sigma|_{[v_0, \dots, v_{l+j}]})) \sigma|_{[v_l, \dots, v_k]} \\
&= (-1)^l \partial(\sigma \frown \phi).
\end{aligned}$$

Therefore, we obtain the desired result $\partial(\sigma \frown \phi) = (-1)^l((\partial\sigma) \frown \phi - \sigma \frown (\delta\phi))$. \square

Theorem 2.12. $\frown: C_k(X; R) \otimes C^l(X; R) \rightarrow C_{k-l}(X; R)$ induces a map $H_k(X; R) \otimes H^l(X; R) \rightarrow H_{k-l}(X; R)$.

Proof. Let $[\sigma] \in H_k(X; R)$ and $[\phi] \in H^l(X; R)$ be given where $\sigma \in C_k(X; R)$ and $\phi \in C^l(X; R)$. Then $\partial(\sigma) = \delta(\phi) = 0$. By (2.11), $\partial(\sigma \frown \phi) = (-1)^l(0 - 0) = 0$. Therefore, $\sigma \frown \phi$ represents a class in $H_{k-l}(X; R)$. \square

2.4. Poincare Duality (Version 2).

Theorem 2.13. If M is an orientable closed n -manifold, let $[M] \in H_n(M)$ be a fundamental class for M , and let R be a commutative ring. View $[M] \in H_n(M; R)$. Then the map

$$H^l(M; R) \longrightarrow H_{n-l}(M; R)$$

$$\phi \longmapsto [M] \frown \phi$$

is an R -module isomorphism.

If M is not orientable, then $[M] \in H_n(M; \mathbb{Z}/2)$ still exists, and we have

$$H^l(M; \mathbb{Z}/2) \longrightarrow H_{n-l}(M; \mathbb{Z}/2)$$

$$\phi \longmapsto [M] \frown \phi$$

2.5. Differential Forms on \mathbb{R}^n .

Definition 2.14. Let dx_1, \dots, dx_n be formal indeterminates. Let V be the vector space over \mathbb{R} generated by dx_1, \dots, dx_n . Let Ω^* be the \mathbb{R} -algebra generated by dx_1, \dots, dx_n module relations $dx_i \wedge dx_i = 0$ and $dx_i \wedge dx_j = -dx_j \wedge dx_i$.

Lemma 2.15. *The dimension of Ω^* over \mathbb{R} is 2^n .*

Proof. Ω^* is generated by the set of elements of the form $dx_{i_1} \wedge \dots \wedge dx_{i_k}$ where $0 \leq k \leq n$ and $i_1 < \dots < i_k$. This is because of the two relations of Ω^* . We denote it by dx_I where $I = \{i_1, \dots, i_k\}$. Then there are exactly 2^n I 's, so the dimension is 2^n . \square

Definition 2.16. Let $U \subset \mathbb{R}^n$ be open. Then $\Omega^*(U) = C^\infty(U) \otimes \Omega^*$.

Lemma 2.17. $\Omega^*(U)$ is a graded, sign-commutative \mathbb{R} -algebra.

Proof. $\Omega^*(U)$ is a vector space over \mathbb{R} because addition can be defined in a trivial way and for any $c \in \mathbb{R}$ and $f \otimes dx_I \in \Omega^*(U)$, $c(f \otimes dx_I) = (cf) \otimes dx_I$. Moreover, $(f_I dx_I) \wedge (f_J dx_J) = (f_I f_J)(dx_I \wedge dx_J)$ is a well-defined multiplication. It is easy to see that the multiplication, addition and scalar multiplication commute. Thus $\Omega^*(U)$ is a \mathbb{R} -algebra. Moreover, $\Omega^*(U) = \bigoplus_{k=0}^n \Omega^k(U)$ where $\Omega^k(U) = \{\sum_{|I|=k} f_I dx_I\}$. Finally, for any $\omega_1 \in \Omega^{k_1}(U)$, $\omega_2 \in \Omega^{k_2}(U)$, $\omega_1 \wedge \omega_2 = (-1)^{k_1 k_2} \omega_2 \wedge \omega_1$. \square

Definition 2.18. The exterior derivative $d : \Omega^k(U) \rightarrow \Omega^{k+1}(U)$ is defined as following:

- For any $f \in \Omega^0(U)$, $df = \sum_{i=1}^n \frac{\partial f}{\partial x_i} dx_i$.
- For any $\omega \in \sum f_I dx_I$, $d\omega = \sum df_I \wedge dx_I$.