## MATH 611 PROBLEM SET 1 (DUE 9/4)

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**Exercise 0.1.** (Exercise 4, Chapter 0) A deformation retraction in the weak sense of a space X to a subspace A is a homotopy  $f_t: X \to X$  such that  $f_0 = \operatorname{Id}, f_1(X) \subset A$ , and  $f_t(A) \subset A$  for all t. Show that if X deformation retracts to A in this weak sense, then the inclusion  $A \to X$  is a homotopy equivalence.

*Proof.* Let  $i: A \to X$  denote the inclusion. Let  $F: X \times I \to X$  denote the associated map  $(x,t) \to f_t(x)$ . Then F is a continuous function by the definition of a homotopy.

Let  $f: X \to A$  be defined by  $f(x) = F(x, 1) = f_1(x)$ . This definition makes sense because  $f_1(X) \subset A$ . We claim that  $f_1 \circ i \simeq \operatorname{Id}_A$  and  $i \circ f_1 \simeq \operatorname{Id}_X$ .

Consider  $G: A \times I \to A$  such that G(a,t) = F(a,t) for all  $(a,t) \in A \times I$ . This definition makes sense because  $f_t(A) \subset A$  for all t.

Then G is a homotopy in A between  $f \circ i$  and  $\mathrm{Id}_A$  because:

- G is a restriction of F, so G is continuous.
- $\forall a \in A, G(a,0) = F(a,0) = f_0(a) = \mathrm{Id}_X(a) = \mathrm{Id}_A(a).$
- $\forall a \in A, G(a, 1) = F(a, 1) = f(a) = f(i(a)) = (f \circ i)(a).$

Therefore,  $f \circ i \simeq \mathrm{Id}_A$ .

F is a homotopy between  $f_0$  and  $f_1$ .

- We are given that  $f_0 = \mathrm{Id}_X$ .
- For any  $x \in X$ ,  $(i \circ f)(x) = i(f(x)) = f(x) = f_1(x)$ , so  $i \circ f = f_1$ .

Therefore, F is a homotopy between  $\mathrm{Id}_X$  and  $i \circ F$ , so  $i \circ f \simeq \mathrm{Id}_X$ . In conclusion, i is indeed a homotopy equivalence.

**Exercise 0.2.** (Exercise 5, Chapter 0) Show that if a space X deformation retracts to a point  $x \in X$ , then for each neighborhood U of x in X there exists a neighborhood  $V \subset U$  of x such that the inclusion map  $V \to U$  is nullhomotopic.

*Proof.* Let  $p \in X$  be a point to which X deformation retracts. Since X deformation retracts to p, there exists a map  $F: X \times I \to X$  such that

- $(1) \ \forall x \in X, F(x,0) = x.$
- (2)  $\forall x \in X, F(x, 1) = p$ .

- (3)  $\forall t \in I, F(p,t) = p$ .
- (4) F is continuous.

Let U be a neighborhood of p. Then  $F^{-1}(U)$  is an open subset of the product space  $X \times I$ . By the 3rd property of F mentioned above, the slice  $\{p\} \times I$  is a subset of  $F^{-1}(U)$ . Since I is compact, there must be a open subset V of X such that  $\{p\} \times I \subset V \times I \subset F^{-1}(U)$  by the tube lemma.

We claim that this V is a desired subset.

- V is an open subset of X.
- Since  $\{p\} \times I \subset V \times I, p \in V$ .
- Since  $V \times I \subset F^{-1}(U)$ ,  $F(V \times I) \subset U$ . This implies that  $\forall v \in V$ ,  $F(v,0) = v \in U$ . Therefore,  $V \subset U$ .
- We claim that the inclusion map  $i: V \to U$  is nullhomotopic. Let  $e_p: V \to U$  denote the constant map at  $p, G: V \times I \to U$  be defined by G(x,t) = F(x,t) for all  $x \in V, t \in I$ .
  - G indeed maps  $V \times I$  into U because  $F(V \times I) \subset U$ . Therefore, G is well-defined.
  - Since G is the restriction of F to  $V \times I$  and F is continuous, G is continuous.
  - $\forall x \in V, G(x, 0) = F(x, 0) = x = i(x).$
  - $\forall x \in V, G(x, 1) = F(x, 1) = p = e_p(x).$

Thus i is indeed nullhomotopic.

**Lemma 0.3.** The neighborhood V that we find in Problem 5 is connected.

*Proof.* Suppose otherwise. Let A, B denote a separation of V. Without loss of generality, we assume  $p \in A$ . Let  $q \in B$ . (B must be nonempty since A, B are a separation.)

Let F be the homotopy we defined in the solution for Problem 5 from the inclusion map to the constant map at p. Let  $f: I \to V$  be defined such that f(t) = F(q,t). Then f is a path from f(0) = F(q,0) = q to f(1) = F(q,1) = p in V. Since f is continuous,  $f^{-1}(A)$  and  $f^{-1}(B)$  are open in I. Moreover,  $I = f^{-1}(V) = f^{-1}(A) \cup f^{-1}(B)$  and  $\emptyset = f^{-1}(\emptyset) = f^{-1}(A \cap B) = f^{-1}(A) \cap f^{-1}(B)$ . Since  $1 \in f^{-1}(p) \subset f^{-1}(A)$  and  $0 \in f^{-1}(q) \subset f^{-1}(B)$ ,  $f^{-1}(A)$  and  $f^{-1}(B)$  are nonempty. Therefore,  $f^{-1}(A)$  and  $f^{-1}(B)$  form a separation of I. However, this is impossible because I is connected.

**Exercise 0.4.** (Exercise 6(a), Chapter 0) Let X be the subspace of  $\mathbb{R}^2$  consisting of the horizontal segment  $[0,1] \times \{0\}$  together with all the vertical segments  $\{r\} \times [0,1-r]$  for r a rational number in [0,1]. Show

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that X deformation retracts to any point in the segment  $[0,1] \times \{0\}$ , but not to any other point.

*Proof.* Let  $(a,0) \in [0,1] \times \{0\}$  be given. Let  $F: X \times I \to X$  be defined such that

$$F((x,y),t) = \begin{cases} (x,(1-2t)y) & (0 \le t \le 1/2) \\ (x+(a-x)(2t-1),0) & (1/2 \le t \le 1). \end{cases}$$

F is well defined because when t = 1/2:

- (x, (1-2t)y) = (x, 0).
- (x + (a x)(2t 1), 0) = (x, 0).

Moreover, by the pasting lemma, F is continuous.

Then F is a deformation retract of X onto (a,0) because

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$$F((a,0),t) = \begin{cases} (a,0(1-2t)) = (a,0) & (t \in [0,1/2]) \\ (a+(a-a)(2t-1),0) = (a,0) & (t \in [1/2,1]). \end{cases}$$

Therefore, F((a,0),t)=(a,0) for any  $t \in I$ .

- F((x,y),0) = (x,y) for any  $(x,y) \in x$ .
- F((x,y),1) = (a,0) for any  $(x,y) \in x$ .

Therefore, F is indeed a deformation retract of X onto (a, 0).

Suppose that there exists a point  $(a,b) \in X$  to which X deformation retracts onto such that  $b \neq 0$ . Let  $G: X \times I \to X$  denote such a deformation retract. Consider the open subset  $U = B((a,b),b) \cap X$ . Note that U is disjoint from the segment  $[0,1] \times \{0\}$ . Then U is a neighborhood of (a,b), a point to which X deformation retracts onto. By Problem 5 (Chapter 0), there must exist a neighborhood  $V \subset U$  of x such that the inclusion map  $V \to U$  is nullhomotopic. By the Lemma we showed above, V must be connected. Since V is an open subset of X, there must exist an r > 0 such that  $B((a,b),r) \cap X \subset V$ . Let c be an irrational number in (a,a+r). Then  $V \cap ((-\infty,c) \times \mathbb{R})$  and  $V \cap ((c,\infty) \times \mathbb{R})$  form a separation of V. This is a contradiction, so our initial assumption that X deformation retracts onto (a,b) was wrong. Therefore, X deformation retracts to any point in the segment  $[0,1] \times \{0\}$ , but not to any other point.

**Exercise 0.5.** (Exercise 6(b), Chapter 0) Let Y be the subspace of  $\mathbb{R}^2$  that is the union of an infinite number of copies of X arranged as in the figure below. Show that Y is contractible but does not deformation retract onto any point.

Proof. Suppose Y deformation retracts onto a point  $p \in Y$ . Let  $F: Y \times I \to Y$  denote such a deformation retract. Then by limiting F to a copy of X that contains p, we get a deformation retract of X onto p. By Problem 6(a), this implies that the p must lie in the segment  $[0,1] \times \{0\}$ . The segment corresponds to the segment  $\{0\} \times [0,1]$  of an adjacent copy of X. This implies that, by restricting F to the second copy of X, we obtain a deformation retract of X onto a point that does not lie in the segment  $[0,1] \times \{0\}$ . That is a contradiction, so such a deformation retract does not exist.

**Exercise 0.6.** (Exercise 9, Chapter 0) Show that a retract of a contractible space is contractible.

*Proof.* Let X be a contractible space. Then  $\mathrm{Id}_X$  is homotopic to a constant map. This implies the existence of a fixed point  $p \in X$  and a continuous function  $F: X \times I \to X$  such that

- $\forall x \in X, F(x,0) = x$ ,
- $\forall x \in X, F(x, 1) = p$ .

Let  $A \subset X$  be a retract of X, and let  $r: X \to A$  denote a retraction. In other words, r(X) = A and  $r|_{A} = \mathrm{Id}_{A}$ .

Let  $G: A \times I \to A$  be the restriction of  $r \circ F$  to  $A \times I$ . This makes sense because F maps  $A \times I$  into X, and r maps X into A. We claim that G is a homotopy between  $\mathrm{Id}_A$  and the constant map  $e_{r(p)}$  such that  $e_{r(p)}(a) = r(p)$  for all  $a \in A$ .

- $r \circ F$  is continuous since it is a composition of continuous functions. G is a restriction of a continuous function, so G is continuous.
- $G(a,0) = r(F(a,0)) = r(a) = a = \mathrm{Id}_A(a)$ .
- $G(a,1) = r(F(a,1)) = r(p) = e_{r(p)}(a)$ .

Therefore, G is indeed a homotopy between  $\mathrm{Id}_A$  and the constant map at r(p). Since the identity map is homotopic to a constant map, A is contractible.

**Exercise 0.7.** (Exercise 13, Chapter 0) Show that any two deformation retractions  $r_t^0$  and  $r_t^1$  of a space X onto a subspace A can be joined by a continuous family of deformation retractions  $r_t^s$ ,  $0 \le s \le 1$ , of X onto A, where continuity means that the map  $X \times I \times I \to X$  sending (x, s, t) to  $r_t^s(x)$  is continuous.

*Proof.* Let  $F: X \times I \times I \to X$  be defined such that

$$F(x,t,s) = \begin{cases} r_{t(1-2s)}^{0}(x) & (s \in [0,1/2]) \\ r_{t(2s-1)}^{1}(x) & (s \in [1/2,1]). \end{cases}$$

We claim that F is well-defined and satisfies the desired properties.

- Let s = 1/2.  $r_{t(1-2s)}^0(x) = r_0^0(x) = x$  because  $r_t^0$  is a deformation retraction. Similarly,  $r_{t(2s-1)}^1(x) = r_0^1(x) = x$  because  $r_t^0$  is a deformation retraction. Therefore, F is well defined when s=1/2. Moreover, by the pasting lemma, F is continuous. This is because the intersection  $X \times I \times [0, 1/2] \cap X \times I \times [1/2, 1] =$  $X \times I \times \{1/2\}$  is closed.
- $F(x,t,0) = r_t^0(x)$  for any  $x \times t \in X \times I$ .  $F(x,t,1) = r_t^1(x)$  for any  $x \times t \in X \times I$ .

Therefore, F maps  $X \times I \times I \to X$  continuously sending (x, s, t) to  $r_t^s(x)$ .

**Exercise 0.8.** (Exercise 6, Chapter 1.1) We can regard  $\pi_1(X, x_0)$  as the set of basepoint-preserving homotopy classes of maps  $(S^1, s_0) \rightarrow$  $(X, x_0)$ . Let  $[S^1, X]$  be the set of homotopy classes of maps  $S^1 \to X$ , with no conditions on basepoints. Thus there is a natural map  $\Phi$ :  $\pi_1(X,x_0) \to [S^1,X]$  obtained by ignoring basepoints. Show that  $\Phi$ is onto if X is path-connected, and that  $\Phi([f]) = \Phi([g])$  if and only if [f] and [g] are conjugate in  $\pi_1(X,x_0)$ . Hence  $\Phi$  induces a one-toone correspondence between  $[S^1, X]$  and the set of conjugacy classes in  $\pi_1(X)$ , when X is path-connected.

*Proof.* Let  $w: I \to S^1$  be defined such that  $w(t) = (\cos(2\pi t), \sin(2\pi t))$ . Then  $\Phi$  maps  $[f] \in \pi_1(X, x_0)$  to  $[\tilde{f}]$  such that  $f \simeq \tilde{f} \circ w$ .

Suppose  $\Phi$  is surjective. Let  $x_1 \in X$  be given. Let  $e: S^1 \to X$  denote the constant map at  $x_1$ . Since  $\Phi$  is assumed to be surjective, there must exist an  $[f] \in \pi_1(X, x_0)$  such that  $\Phi([f]) = [e]$ . Then  $f \simeq e \circ w$ . Let F be a homotopy between f and  $e \circ w$  such that F(s,0) = f(s) and  $F(s,1) = e(w(s)) = x_1$ . Then  $t \mapsto F(0,t)$  is a path from  $x_0$  to  $x_1$ . Thus  $x_1$  and  $x_0$  are path connected. Since  $x_1$  was chosen arbitrarily, X is path connected. TODO: This is \*WRONG\* I proved the wrong direction.

**Exercise 0.9.** (Exercise 7, Chapter 1.1) Define  $f: S^1 \times I \to S^1 \times I$ by  $f(\theta, s) = (\theta + 2\pi s, s)$ , so f restricts to the identity on the two boundary circles of  $S^1 \times I$ . Show that f is homotopic to the identity by a homotopy  $f_t$  that is stationary on one of the boundary circles, but not by any homotopy  $f_t$  that is stationary on both boundary circles.

*Proof.* Define  $F:(S^1\times I)\times I\to S^1\times I$  such that  $F((\theta,s),t)=$  $t(\theta,s)+(1-t)f(\theta,s)$ . Then F is a homotopy between f and the identity map that is stationary on  $S^1 \times \{0\}$ . This is because  $F((\theta, 0), t) =$ 

 $t(\theta, 0) + (1 - t)f(\theta, 0) = (t\theta, 0) + ((1 - t)\theta, 0) = (\theta, 0)$  for any  $(\theta, t) \in S^1 \times I$ .

Suppose that there exists a homotopy  $G:(S^1\times I)\times I\to S^1\times I$  between f and the identity map that is stationary on both boundary circles. Let  $H:I\times I\to S^1$  be defined such that  $H(s,t)=\pi_1(F((0,t),s))$  where  $\pi_1$  denotes the projection of the first coordinate.

- $H(s,0) = \pi_1(G((0,0),s)) = \pi_1(0,0) = 0$  because G is stationary on the circle  $S^1 \times \{0\}$ .
- $H(s,1) = \pi_1(G((0,1),s)) = \pi_1(0,1) = 0$  because G is stationary on the circle  $S^1 \times \{1\}$ .
- $H(0,t) = \pi_1(G((0,t),0)) = \pi_1(f(0,t)) = \pi_1(2\pi t,t) = 2\pi t.$
- $H(1,t) = \pi_1(G((0,t),1)) = \pi_1(0,t) = 0.$

Then  $t \mapsto H(0,t)$  corresponds to the  $\omega$  in Theorem 1.7, and  $t \mapsto H(1,t)$  corresponds to a constant map. In other words, H is a homotopy between  $\omega$  and a constant map in  $S^1$ . However, this is a contradiction because Theorem 1.7 states that  $\pi_1(S^1)$  is the infinite cyclic group generated by  $\omega$ . Therefore, such a homotopy G does not exist.  $\square$ 

**Exercise 0.10.** (Exercise 16, Chapter 1.1) Show that there are no retractions  $r: X \to A$  in the following cases:

- $X = \mathbb{R}^3$  with A any subspace homeomorphic to  $S^1$ .
- $X = S^1 \times D^2$  with A its boundary torus  $S^1 \times S^1$ .
- $X = S^1 \times D^2$  with A the circle shown in the textbook.

## Proof.

- Suppose that X retracts onto A. By Proposition 1.17, the homomorphism  $i_*: \pi_1(A, x_0) \to \pi_1(X, x_0)$  induced by the inclusion  $i: A \to X$  is injective. Since A and  $S^1$  are homeomorphic,  $\pi_1(S^1)$  and  $\pi_1(A)$  are isomorphic to each other. By Theorem 1.7,  $\pi_1(S^1)$  is isomorphic to  $\mathbb{Z}$ . On the other hand,  $\pi_1(\mathbb{R}^3) = 0$  because  $\mathbb{R}^3$  is convex. This implies the existence of an injective homomorphism from  $\mathbb{Z}$  into 0, which is impossible. Therefore, X does not retract onto A.
- Suppose X retracts onto A. By Proposition 1.17, the homomorphism  $i_*: \pi_1(A, x_0) \to \pi_1(X, x_0)$  induced by the inclusion  $i: A \to X$  is injective. By Theorem 1.7,  $\pi_1(S^1)$  is isomorphic to  $\mathbb{Z}$ .  $\pi_1(D^2) = 0$  because  $D^2$  is a convex subset and thus a linear homotopy connects any paths. By Proposition 1.12,  $\pi_1(X) = \pi_1(S^1) \times \pi_1(D^2) = \mathbb{Z} \times 0 = \mathbb{Z}$  and  $\pi_1(A) = \pi_1(S^1) \times \pi_1(S^1) = \mathbb{Z} \times \mathbb{Z}$ . Let  $f: \mathbb{Z} \times \mathbb{Z} \to \mathbb{Z}$  be any homomorphism. Let a = f(1,0), b = f(0,1). If a = 0 or b = 0, f

is not injective because f(0,0) = 0. Suppose otherwise. Then f(b,0) = ab = f(0,a), so f is not injective.

Therefore, there exists no injection from  $\mathbb{Z} \times \mathbb{Z} \to \mathbb{Z}$ . Hence, X does not retract onto A.

• Since A is homeomorphic to  $S^1$ , let  $\phi: A \to S^1$  be a homeomorphism. Let  $p = \phi^{-1}(\omega)$  such that  $[\omega]$  is a generator of  $\pi_1(S^1)$ . Since p is a path in  $A \subset S^1 \times D^2$ , there exist two paths  $f: I \to S^1$  and  $g: I \to D^2$  such that p(t) = (f(t), g(t)). Then f is homotopic to the constant path  $e_1$  at f(0), and g is homotopic to the constant path  $e_2$  at g(0). Let F be a homotopy from f to  $e_1$  and G be a homotopy from g to  $e_2$ . Define  $H: I \times I \to S^1 \times D^2$  such that  $H(s,t) = F(s,t) \times G(s,t)$ . Then H is a homotopy between p and the constant map at p(0).

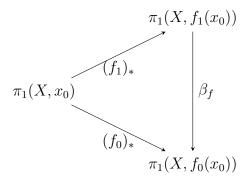
If there exists a retraction  $r: X \to A$ , then  $\phi \circ r \circ H$  is a homotopy between  $\omega$  and a constant map in  $S^1$ . However, this implies that  $\pi_1(S^1) = 0$  since  $[\omega]$  is a generator. This is a contradiction, so there exists no such retraction.

**Exercise 0.11.** (Exercise 20, Chapter 1.1) Suppose  $f_t: X \to X$  is a homotopy such that  $f_0$  and  $f_1$  are each the identity map. Use Lemma 1.19 to show that for any  $x_0 \in X$ , the loop  $f_t(x_0)$  represents an element of the center of  $\pi_1(X, x_0)$ .

*Proof.* Let  $x_0 \in X$  be given. Let  $f: I \to X$  be the loop defined such that  $f(t) = f_t(x_0)$ .

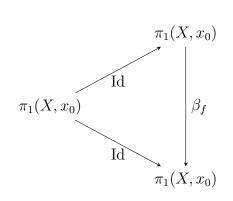
- $f_t: X \to X$  is a homotopy.
- f is a path formed by the images of the base point  $x_0$ .

By Lemma 1.19, the following diagram commutes.



 $(f_0)_* = (f_1)_* = (\mathrm{Id}_X)_* = \mathrm{Id}_{\pi_1(X,x_0)}$  by a basic property of induced homomorphisms (P.34 of Hatcher). Since  $f_0 = f_1 = \mathrm{Id}_X$ ,

 $f_0(x_0) = f_1(x_0) = x_0$ . Therefore, the diagram above can be simplified as following:



Let  $[g] \in \pi_1(X, x_0)$ . Then by the diagram above, we have  $\mathrm{Id}([g]) = \mathrm{Id}(\beta_f([g]))$ . This implies  $[g] = [f \cdot g \cdot \overline{f}]$ . Therefore,  $[g] \cdot [f] = [f] \cdot [g]$ , so [f] commutes with every element in  $\pi_1(X, x_0)$ . Hence,  $[f] \in Z(\pi_1(X, x_0))$ .