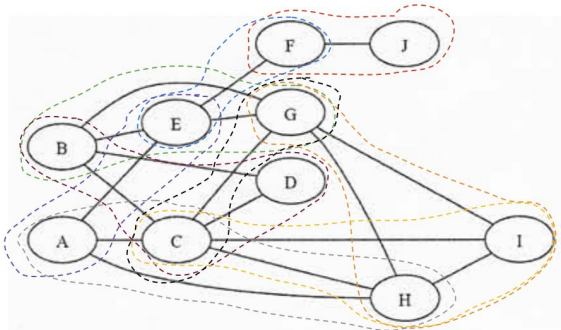


Directed and Undirected Graphs

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Machine Intelligence I

January 26, 2016



$C_1 : F, J$

$C_2 : F, E$

$C_3 : B, E, G$

$C_4 : G, H, I$

$C_5 : C, H, I$

$C_6 : A, C, H$

$C_7 : B, C, D$

$C_8 : A, E$

$C_9 : C, G$

a) construction of the moral graph

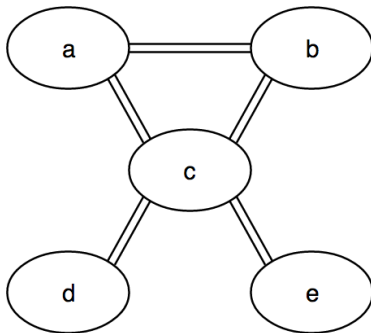


Figure: moral graph of given DAG

b) pdf from cliques and separators

- we show that the DAG representation equals the given formula for the joint distribution:

$$P(a, b, c, d, e) = P(a)P(b)P(c|a, b)P(d|c)P(e|c) \quad (1)$$

$$= \frac{P(a, b)P(a, b, c)P(d, c)P(e, c)}{P(c)^2 P(a, b)} \quad (2)$$

$$= \frac{P(a, b, c)P(d, c)P(e, c)}{P(c)P(c)} \quad (3)$$

$$= \frac{P(C_1)P(C_2)P(C_3)}{P(S_1)P(S_2)} = \frac{\prod_i P(C_i)}{\prod_j P(S_j)} \quad (4)$$

$$(5)$$

a) potential functions and the clique-marginal representation

- ▶ potential functions are used to represent joint probabilities of cliques, can be easily updated by new data
- ▶ potential functions are strictly positive, real-valued and only depend on random variables in their assigned clique
- ▶ don't need to be normalised so that $\psi_n(C_n) = \alpha P(C_n)$, $\alpha > 0$
- ▶ link between joint probability distribution and clique-marginal representation:

$$P(V \in \mathcal{V}) = \prod_{V \in \mathcal{V}} P(V | V_{pa(V)}) = \frac{\prod_i P(C_i)}{\prod_j P(S_j)} = \alpha \frac{\prod_i \psi_i(C_i)}{\prod_j \psi_j(S_j)} \quad (6)$$

- ▶ at the beginning, all potentials are chosen to be 1

b) exploitation of potential functions to make inferences

1. update clique potential

- ▶ inference by observed evidence at one node: $V_I = v_I$
- ▶ introduce indicator function $E(V_I) = \begin{cases} 1 & \text{se } V_I = v_I \\ 0 & \text{se else} \end{cases}$
- ▶ update clique potential of observed node: $\psi_{i,new}(C_i) = \psi_i(C_i)E(V_I)$

2. message passing

- ▶ new separator potential: $\psi_c^*(S_c) = \sum_{V \in C_i, V \notin \psi_c} \psi_i(V \in C_i)$
- ▶ the update of one clique demands updates of the neighbor cliques which happens by passing the update ratio $\frac{\psi_c^*(S_c)}{\psi_c(S_c)}$ (S_c : common separator)
- ▶ updated neighbor potential obtained by multiplication of current potential with the update rate

c) benefit in comparison to DAG factorisation

- ▶ simpler and clearer models due to substitution of subgraphs by cliques
- ▶ highly improved interference

Literature



'Machine Intelligence I', Lecture Notes by Prof. Dr. Klaus Obermayer, 2015



'Probabilistic Networks and Expert Systems', Chapter 3, Cowell et al., 1999