Language Modeling

Advanced: Good Turing Smoothing

Reminder: Add-1 (Laplace) Smoothing

$$P_{Add\text{-}1}(w_i \mid w_{i-1}) = \frac{c(w_{i-1}, w_i) + 1}{c(w_{i-1}) + V}$$

More general formulations: Add-k

$$P_{Add\text{-}k}(w_i \mid w_{i-1}) = \frac{c(w_{i-1}, w_i) + k}{c(w_{i-1}) + kV}$$

$$P_{Add\text{-}k}(w_i \mid w_{i-1}) = \frac{c(w_{i-1}, w_i) + m(\frac{1}{V})}{c(w_{i-1}) + m}$$

Unigram prior smoothing

$$P_{Add\text{-}k}(w_i \mid w_{i-1}) = \frac{c(w_{i-1}, w_i) + m(\frac{1}{V})}{c(w_{i-1}) + m}$$

$$P_{\text{UnigramPrior}}(w_i \mid w_{i-1}) = \frac{c(w_{i-1}, w_i) + mP(w_i)}{c(w_{i-1}) + m}$$

Advanced smoothing algorithms

- Intuition used by many smoothing algorithms
  - Good-Turing
  - Kneser-Ney
  - Witten-Bell
- Use the count of things we've **seen once**
  - to help estimate the count of things we've **never seen**

Notation: N_c = Frequency of frequency c

- N_c = the count of things we've seen c times
- Sam I am I am Sam I do not eat

I 3

sam 2

am 2

do 1

not 1

eat 1

$N_1 = 3$

$N_2 = 2$

$N_3 = 1$

Good-Turing smoothing intuition

- You are fishing (a scenario from Josh Goodman), and caught:
  - 10 carp, 3 perch, 2 whitefish, 1 trout, 1 salmon, 1 eel = 18 fish
- How likely is it that next species is trout?
  - 1/18
- How likely is it that next species is new (i.e. catfish or bass)
  - Let’s use our estimate of things-we-saw-once to estimate the new things.
  - 3/18 (because N_1=3)
- Assuming so, how likely is it that next species is trout?
  - Must be less than 1/18
  - How to estimate?

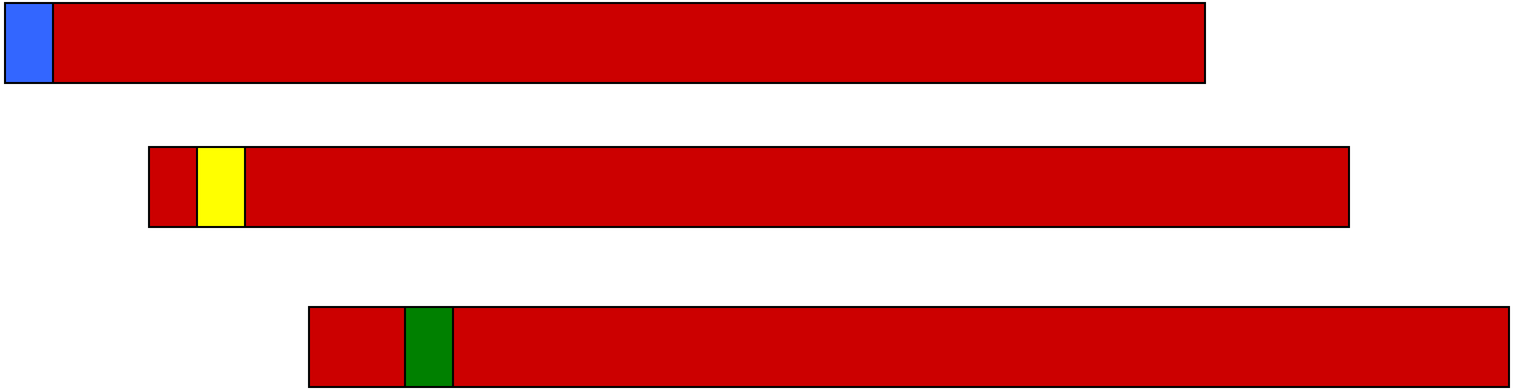
Good Turing calculations

$$P^*_{GT}(\text{things with zero frequency}) = \frac{N_1}{N} \qquad c^* = \frac{(c+1)N_{c+1}}{N_c}$$

- Unseen (bass or catfish)
  - c = 0:
  - MLE p = 0/18 = 0
  - P^*_{GT} (unseen) = N_1/N = 3/18
- Seen once (trout)
  - c = 1
  - MLE p = 1/18
  - C*(trout) = 2 * N2/N1
    = 2 * 1/3
    = 2/3
  - P^*_{GT}(trout) = 2/3 / 18 = 1/27

Ney et al.’s Good Turing Intuition

H. Ney, U. Essen, and R. Kneser, 1995. On the estimation of 'small' probabilities by leaving-one-out. IEEE Trans. PAMI. 17:12,1202-1212

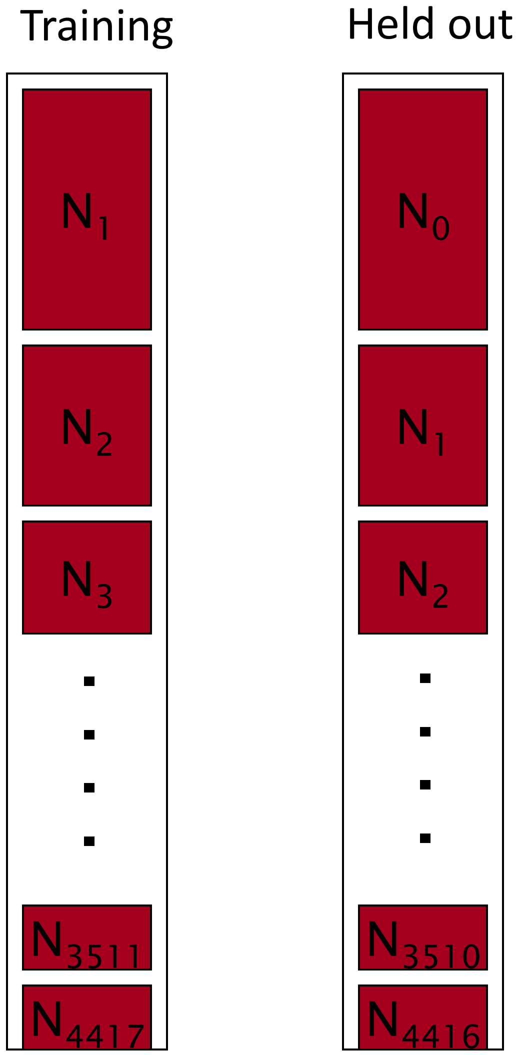


Held-out words:

Ney *et al.* Good Turing Intuition (slide from Dan Klein)

- Intuition from leave-one-out validation
  - Take each of the *c* training words out in turn
  - *c* training sets of size *c*–1, held-out of size 1
  - What fraction of held-out words are unseen in training?
    - N_1/c
  - What fraction of held-out words are seen *k* times in training?
    - $(k+1)N_{k+1}/c$
  - So in the future we expect $(k+1)N_{k+1}/c$ of the words to be those with training count *k*
  - There are N_k words with training count *k*
  - Each should occur with probability:
    - $(k+1)N_{k+1}/c/N_k$
  - …or expected count:

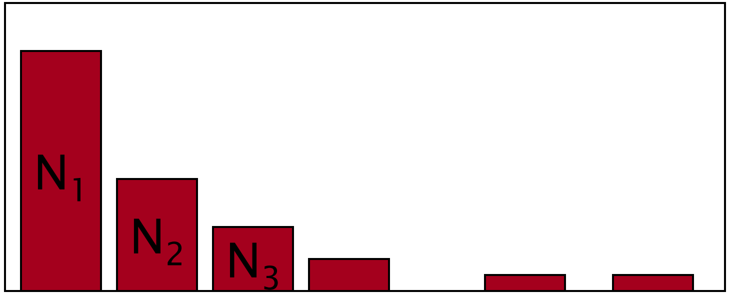
$$k^* = \frac{(k+1)N_{k+1}}{N_k}$$



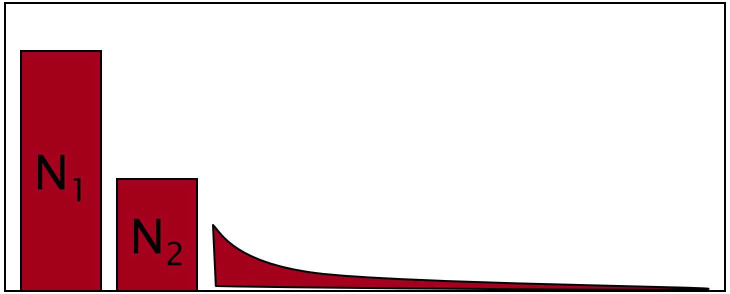
Good-Turing complications

(slide from Dan Klein)

- Problem: what about "the"? (say c=4417)
  - For small k, $N_k > N_{k+1}$
  - For large k, too jumpy, zeros wreck estimates



  - Simple Good-Turing [Gale and Sampson]: replace empirical N_k with a best-fit power law once counts get unreliable



Resulting Good-Turing numbers

- Numbers from Church and Gale (1991)
- 22 million words of AP Newswire

$$c^* = \frac{(c+1)N_{c+1}}{N_c}$$

Count c	Good Turing c*
0	.0000270
1	0.446
2	1.26
3	2.24
4	3.24
5	4.22
6	5.19
7	6.21
8	7.24
9	8.25

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