# **BLUETOOTH FW FOR SMART SPEAKER DEVICE**

### I. Requirements

The device SDK runs on Raspberry Pi, Beaglebone. It requires C++11 or later.

# II. Dependencies

This is list of requirement and dependencies for the Device SDK for C++.

Building with Bluetooth is optional and is currently limited to Raspberry Pi and Beaglebone. `A2DP-SINK`,`A2DP-SOURCE`, `AVRCPTarget` and `AVRCPController` profiles are supported.

If you choose to build with Bluetooth, these libraries and modules, and their dependencies, must be installed:

Library	Minimum version
SBC Library	1.3
Bluez5	5.37 or earlier
Libpulse-dev. Only require if enabling Cmake variable :	8.0
BLUETOOTH_BLUEZ_PULSEAUDIOINITIALIZER	
Module	Minimum version
Pulseaudio	12.2 or earlier
Pulseaudio Bluetooth	
Cmake	3.7

# III. Setup Environment on Debian Image

Download the latest firmware for your Beaglebone as website: <a href="https://beagleboard.org/latest-images">https://beagleboard.org/latest-images</a>
In case of document, the version is <a href="Debian 9.5 2018-10-07">Debian 9.5 2018-10-07 4GB SD IoT</a>

## 1. Pulseaudio

- Installing:
  - sudo apt-get update
  - sudo apt-get install pulseaudio pulseaudio-module-bluetooth
- Automatically change sound Input Output device:
   Add the following line into our "/etc/pulse/default.pa"
   load-module module-switch-on-connect

# 2. Blue**Z 5**

Install Dependencies:
 sudo apt-get update

sudo apt-get install -y libusb-dev libdbus-1-dev libglib2.0-dev libudev-dev libical-dev libreadline-dev

• Download, Compile and Install:

wget http://www.kernel.org/pub/linux/bluetooth/bluez-5.48.tar.xz

tar xvf bluez-5.48.tar.xz

cd bluez-5.48

./configure --prefix=/usr --mandir=/usr/share/man --sysconfdir=/etc --localstatedir=/var -enable-experimental

make

sudo make install

### 3. Cmake

sudo apt-get install cmake

4. **SBC** 

sudo apt-get install libsbc-dev

# IV. Build and run the example

- Install libsoc just for testing:
  - Git clone libsoc from git repository:
     git clone <a href="https://github.com/jackmitch/libsoc.git">https://github.com/jackmitch/libsoc.git</a>
  - Enter the libsoc.git directory:

cd libsoc

- Run autoreconf to generate the libsoc configure scripts

autoreconf -i

- Configure the libsoc library with the required features

./configure --enable-debug --enable-board=beaglebone\_black --with-board-configs

Compile and Install

make && sudo make install

• Git clone source code from git repository:

git clone https://github.com/olli-ai/omni-device-sdk.git

Go to direction of example

cd omni-device-sdk/BluetoothDevice/BlueZ/test/Discoverable

Create folder for building

mkdir build && cd build

- Use Cmake to generate Makefiles cmake ..
- Compile the code using make make
- Run the example as 2 cases

Start the pulseaudio with command:

pulseaudio --start

In discoverable Mode:

```
oot@beaglebone:~/omni-device-sdk/BluetoothDevice/BlueZ/test/Discoverable/build# ./BluetoothStreamFromDevice
libsoc-debug: debug enabled (libsoc_set_debug)
libsoc-gpio-debug: requested gpio (7, libsoc_gpio_request)
libsoc-gpio-debug: GPIO already exported (7, libsoc_gpio_request)
libsoc-gpio-debug: setting direction to in (7, libsoc_gpio_set_direction)
libsoc-gpio-debug: setting edge to rising (7, libsoc_gpio_set_edge)
libsoc-gpio-debug: creating new callback (7, libsoc_gpio_callback_interrupt)
[2019-07-26 05:37:48][INFO]
[2019-07-26 05:37:48][INFO]
                                    Discoverable On
                                    Starting main dispatching loop
[2019-07-26 05:38:12][DEBUG]
                                    BlueZBluetoothDevice
                                                               connectedChanged: 1
 [2019-07-26 05:38:16][DEBUG]
                                    BlueZDeviceManager
                                                               on {\tt MediaPlayerPropertyChanged, currentStatus: paused}
 [2019-07-26 05:39:00][DEBUG]
                                    BlueZDeviceManager
                                                               onMediaPlayerPropertyChanged, currentStatus: playing
[2019-07-26 05:39:04][DEBUG]
                                    BlueZDeviceManager
                                                               onMediaPlayerPropertyChanged, currentStatus: paused
[2019-07-26 05:39:04][DEBUG]
                                    BlueZDeviceManager
                                                               onMediaPlayerPropertyChanged, currentStatus: playing
libsoc-gpio-debug: caught interrupt (7, __libsoc_new_interrupt_callback_thread)
[2019-07-26 05:39:20][INFO] Pause Command
[2019-07-26 05:39:20][INFO]
[2019-07-26 05:39:20][DEBUG]
                                    BlueZDeviceManager
                                                               onMediaPlayerPropertyChanged, currentStatus: paused
libsoc-gpio-debug: caught interrupt (7, __libsoc_new_interrupt_callback_thread)
                                    Play Command
[2019-07-26 05:39:26][INFO]
                                    BlueZDeviceManager
[2019-07-26 05:39:26][DEBUG]
                                                               onMediaPlayerPropertyChanged, currentStatus: playing
libsoc-gpio-debug: caught interrupt (7, __libsoc_new_interrupt_callback_thread)
[2019-07-26 05:39:29][INFO]
                                    Next Command
libsoc-gpio-debug: caught interrupt (7, __libsoc_new_interrupt_callback_thread)
[2019-07-26 05:39:35][INFO] Previous Command
[2019-07-26 05:39:35][INFO]
                                    BlueZDeviceManager
                                                               onMediaPlayerPropertyChanged, currentStatus: paused
 [2019-07-26 05:39:35][DEBUG]
[2019-07-26 05:39:35][DEBUG]
                                    BlueZDeviceManager
                                                               onMediaPlayerPropertyChanged, currentStatus: playing
libsoc-gpio-debug: caught interrupt (7, __libsoc_new_interrupt_callback_thread)
[2019-07-26 05:39:39][INFO]
                                    Disconnect Command
[2019-07-26 05:39:41][DEBUG]
                                    BlueZBluetoothDevice
                                                               connectedChanged: 0
 C[2019-07-26 05:45:54][INFO]
                                    Exiting the main loop
[2019-07-26 05:45:54][INFO]
                                    BlueZDeviceManager
                                                               Clean all before exit
```

#### And Pairing Mode:

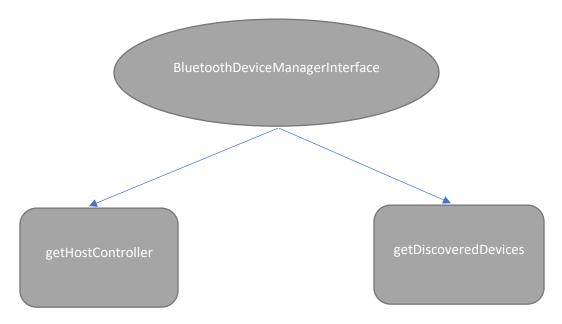
```
oot@beaglebone:~/omni-device-sdk/BluetoothDevice/BlueZ/test/Pairing/build# ./BluetoothStreamToDevice
                                      Please Enter the mac address of device which you want to connect
[2019-07-26 05:50:21][INFO]
oot@beaglebone:~/omni-device-sdk/BluetoothDevice/BlueZ/test/Pairing/build# ./BluetoothStreamToDevice 30:22:11:51:68:59
 2019-07-26 05:51:28][DEBUG]
                                     MaccAddress: 30:22:11:51:6B:59
libsoc-debug: debug enabled (libsoc_set_debug)
libsoc-gpio-debug: requested gpio (7, libsoc_gpio_request)
libsoc-gpio-debug: GPIO already exported (7, libsoc_gpio_request)
libsoc-gpio-debug: setting direction to in (7, libsoc_gpio_set_direction)
libsoc-gpio-debug: setting edge to rising (7, libsoc_gpio_set_edge)
libsoc-gpio-debug: creating new callback (7, libsoc_gpio_callback_interrupt)
[2019-07-26 05:51:29][INFO]
                                      Scanning
                                      Name: Hiep Nokia 7 Plus, MacAddress as A0:28:ED:AB:59:E1
[2019-07-26 05:51:29][INFO]
 2019-07-26 05:51:29][INFO]
                                      Starting main dispatching loop
libsoc-gpio-debug: caught interrupt (7, __libsoc_new_interrupt_callback_thread)
                                      Pairing device with MacAddres 30:22:11:51:6B:59
[2019-07-26 05:51:44][INFO]
 2019-07-26 05:51:45][DEBUG]
                                      BlueZBluetoothDevice
                                                                  connectedChanged: 1
                                                                   pairedChanged: 1
[2019-07-26 05:51:49][DEBUG]
                                      BlueZBluetoothDevice
```

#### V. Issue

If Pulseaudio can not auto switch on new Audio Output Device. Please follow instructions below:

- Now let's check that A2DP streaming is working. We start by checking that PulseAudio is listing the Bluetooth sound card:
   pacmd list-cards
- The Bluetooth card will be index #1, you can also see the supported profiles (a2dp, hsp, off...). Set A2DP as active profile:
   pacmd set-card-profile bluez\_card.xx\_xx\_xx\_xx\_xx\_xx\_a2dp\_sink
- Set the Bluetooth device as output audio:
   pacmd set-default-sink bluez\_sink.xx\_xx\_xx\_xx\_xx\_xx\_a2dp\_sink

# VI. API



## 1. HostController:

An interface to represent the HostControllerInterface on the local system.

This is responsible for Scanning and Discovery.

- **getMac**(): @return the MAC address of the adapter.
- **getFriendlyname()**: @return the friendly name of the adapter.
- **isDiscoverable**(): @return the device is current discoverable by other devices. If right, return True. Otherwise, False.
- enterDiscoverableMode(): Set the adapter to become discoverable.
   @return True if the operation was successful. Otherwise, False.

- exitDiscoverableMode(): Set the adapter become non-discoverable.
  - @return True if the operation was successful. Otherwise, False.
- **isScanning**(): Getter for the scanning state of the device. This must wait until any priority startScan and StopScan methods have finished.
  - @return the device is currently scanning for other device. If right, return True. Otherwise, False.
- **startScan**(): Set the adapter to start scanning
  - @return True if the operation was successful. Otherwise, False.
- **stopScan**(): Set the adapter to stop scanning.
  - @return True if the operation was successful. Otherwise, False.

#### 2. BluetoothDeviceInterface:

- getMac(): return the MAC address of the Bluetooth Device.
- **getFriendlyName**(): return the friendly name of the Bluetooth Device.
- getDeviceState(): return the DeviceState of the current device. Like: FOUND, UNPAIRED, PAIRED, IDLE, DISCOVERED, CONNECTED.
- **isPaired**(): Getter for the paired state of the device. This should return the state after any pending state changes have been resolved.
  - @return if the device is paired, return True. Otherwise, False.
- pair(): Initiate a pair with this device.
  - @return if the pairing was successful, return True. Otherwise, False.
- unpair(): Initiate an unpair with this device.
  - @return if the unpairing was successful, return True. Otherwise, False.
- **isConnected**(): Getter for the paired state of the device. This should return the state after any pending state changes have been resolved.
  - @return if the device is paired, return True. Otherwise, False.
- connect(): Initiate a connect with this device.
  - @return if the connecting was successful, return True. Otherwise, False.
- disconnect(): Initiate an disconect with this device.
  - @return if the disconnecting was successful, return True. Otherwise, False
- getAVRCPTarget(): Audio/Video Remote Control Profile
  - o **play**(): sends a play command to device supporting the AVRCPTarget.
    - @return a Boolean indicating the success of the function.

- pause(): sends a pause command to device supporting the AVRCPTarget.
   @return a Boolean indicating the success of the function.
- next(): sends a next command to device supporting the AVRCPTarget.
   @return a Boolean indicating the success of the function.
- previous(): sends a previous command to device supporting the AVRCPTarget.
   @return a Boolean indicating the success of the function.