

Large scale Finite Element solvers for the large eddy simulation of incompressible turbulent flows

author:

ORIOL COLOMÉS GENÉ

supervisor:

SANTIAGO BADIA

Departament d'Enginyeria Civil i Ambiental

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Escola de Camins

Escola Tècnica Superior d'Enginyeria de Camins, Canals i Ports
UPC BARCELONATECH

1. Motivation

2. Residual-based VMS

3. Mixed FE VMS

4. Segregated Runge-Kutta

5. Segregated VMS

6. Conclusions

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Thesis motivation

Highly scalable Finite Element (FE) framework for Large Eddy Simulations (LES) of incompressible turbulent flows

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1. Variational MultiScale (VMS) methods as LES models.
2. Time integration schemes with **velocity-pressure segregation**.

Motivation

Thesis motivation

Highly scalable Finite Element (FE) framework for Large Eddy Simulations (LES) of incompressible turbulent flows

How to get there?

1. Variational MultiScale (VMS) methods as LES models.
2. Time integration schemes with velocity-pressure segregation.
3. Highly scalable algorithms based on **Domain Decomposition (DD)** and **block preconditioners**.

Motivation

Step by step...

- Residual-based VMS as LES models.

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- Mixed FE formulations LES.

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- Residual-based VMS as LES models.
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- Velocity-pressure segregation.
- Scalable solvers.

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- Application.

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- Application.

1. Motivation

Rb-VMS

2. Residual-based VMS

Formulation

Energy statements

Numerical experiments

Conclusions

3. Mixed FE VMS

4. Segregated Runge-Kutta

5. Segregated VMS

6. Conclusions

Implicit LES

ILES: only numerical dissipation (for stabilization) acts as turbulent model

- Not based on filtering of the Navier-Stokes equations
- Rely on numerical artifacts, no modification at the continuous level

Incomp. Navier Stokes equations

Find \mathbf{u} and p defined in Ω

$$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p - \nu \nabla^2 \mathbf{u} = \mathbf{f}$$

$$\nabla \cdot \mathbf{u} = 0$$

with appropriate boundary conditions on Γ .

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with appropriate boundary conditions on Γ .

The weak problem is: $\forall \mathbf{v} \in \mathcal{V}_0$ and $\forall q \in \mathcal{Q}_0$, find $\mathbf{u} \in \mathcal{V}$ and $p \in \mathcal{Q}$ such that

$$\begin{aligned} (\mathbf{v}, \partial_t \mathbf{u})_\Omega + (\nabla \mathbf{v}, \nu \nabla \mathbf{u})_\Omega + b(\mathbf{u}, \mathbf{u}, \mathbf{v}) - (\nabla \cdot \mathbf{v}, p)_\Omega &= \langle \mathbf{v}, \mathbf{f} \rangle_\Omega \\ (q, \nabla \cdot \mathbf{u})_\Omega &= 0 \end{aligned}$$

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where

$$b(\mathbf{a}, \mathbf{u}, \mathbf{v}) = \langle \mathbf{v}, \mathbf{a} \cdot \nabla \mathbf{u} \rangle_\Omega$$

Incomp. Navier Stokes equations

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where

$$b(\mathbf{a}, \mathbf{u}, \mathbf{v}) = \frac{1}{2} \langle \mathbf{v}, \mathbf{a} \cdot \nabla \mathbf{u} \rangle_\Omega - \frac{1}{2} \langle \mathbf{a} \cdot \nabla \mathbf{v}, \mathbf{u} \rangle_\Omega + \frac{1}{2} \langle \mathbf{v}, \mathbf{n} \cdot \mathbf{a} \mathbf{u} \rangle_\Gamma$$

VMS decomposition (Hughes 1995)

A decomposition of spaces \mathcal{V} and \mathcal{Q} given by

$$\mathcal{V} = \mathcal{V}_h \oplus \tilde{\mathcal{V}}, \quad \mathcal{Q} = \mathcal{Q}_h \oplus \tilde{\mathcal{Q}}$$

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is applied to the function and test spaces

$$\mathbf{u} = \mathbf{u}_h + \tilde{\mathbf{u}}, \quad p = p_h + \tilde{p}$$

$$\mathbf{v} = \mathbf{v}_h + \tilde{\mathbf{v}}, \quad q = q_h + \tilde{q}$$

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We keep all the (eight) contributions from the splitting of the convective term

$$\mathbf{u} \cdot \nabla \mathbf{u} = \mathbf{u}_h \cdot \nabla \mathbf{u}_h + \tilde{\mathbf{u}} \cdot \nabla \mathbf{u}_h + \mathbf{u}_h \cdot \nabla \tilde{\mathbf{u}} + \tilde{\mathbf{u}} \cdot \nabla \tilde{\mathbf{u}}$$

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We keep all the (eight) contributions from the splitting of the convective term

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and all the (four) contributions from the temporal term

$$\partial_t \mathbf{u} = \partial_t \mathbf{u}_h + \partial_t \tilde{\mathbf{u}}$$

Semidiscrete problem

FEM equations

$$B((\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p}) ; (\mathbf{v}_h, q_h)) = L(\mathbf{v}_h, q_h)$$

SGS equations

$$B((\tilde{\mathbf{u}}, \tilde{p}) ; (\mathbf{u}_h, p_h) ; (\tilde{\mathbf{v}}, \tilde{q})) = L(\tilde{\mathbf{v}}, \tilde{q})$$

Semidiscrete problem

FEM equations

$$\begin{aligned}
 & (\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\
 & + (\mathbf{v}_h, \partial_t \tilde{\mathbf{u}})_\Omega + (\mathcal{L}^* \mathbf{v}_h, \tilde{\mathbf{u}})_{\Omega^h} - (\nabla \cdot \mathbf{v}_h, \tilde{p})_{\Omega^h} = \langle \mathbf{v}_h, \mathbf{f} \rangle_\Omega \\
 & (q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\tau_m = \left(\frac{c_1 \nu}{h^2} + \frac{c_2 |\mathbf{a}|}{h} \right)^{-1}, \quad \tau_c = \frac{h^2}{c_1 \tau_m}$$

$$\mathbf{a} = \mathbf{u}_h + \tilde{\mathbf{u}}$$

Semidiscrete problem

FEM equations

$$\begin{aligned}
 & (\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\
 & + (\mathbf{v}_h, \partial_t \tilde{\mathbf{u}})_\Omega + (\mathcal{L}^* \mathbf{v}_h, \tilde{\mathbf{u}})_{\Omega^h} - (\nabla \cdot \mathbf{v}_h, \tilde{p})_{\Omega^h} = \langle \mathbf{v}_h, \mathbf{f} \rangle_\Omega \\
 & (q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} \mathbf{R}_c$$

$$\mathbf{R}_m := \mathbf{f} - \partial_t \mathbf{u}_h - \mathcal{L} \mathbf{u}_h - \nabla p_h, \quad \mathbf{R}_c := -\nabla \cdot \mathbf{u}_h$$

Semidiscrete problem

FEM equations

$$\begin{aligned}
 & (\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\
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 & (q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\mathcal{P} = I \quad (\text{ASGS}), \quad \mathcal{P} = P_h^\perp = I - P_h \quad (\text{OSS})$$

Semidiscrete problem

FEM equations

$$\begin{aligned}
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 & (q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\mathcal{P} = I \quad (\text{ASGS}), \quad \mathcal{P} = \mathbf{P}_h^\perp = \mathbf{I} - \mathbf{P}_h \quad (\text{OSS})$$

$$\mathbf{a} = \mathbf{u}_h + \tilde{\mathbf{u}}$$

Summary

	Sgs space	Sgs dynamics	Advection
1	ASGS	Static	Linear
2	ASGS	Dynamic	Linear
3	ASGS	Dynamic	Nonlinear
4	OSS	Static	Linear
5	OSS	Dynamic	Linear
6	OSS	Dynamic	Nonlinear

- 1 It is the most standard method (SUPG for linear elements) up to the choice of the stabilization parameters. Unknown stability properties.
- 4 Strictly pointwise positive for linear elements (no backscatter).
- 5 Convergent to weak solutions of NS equations (Badia & Gutierrez 2012).

Energy statements

FE counterpart:

$$B((\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h)) = L(\mathbf{u}_h, p_h)$$

SGS counterpart:

$$B((\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p})) = L(\tilde{\mathbf{u}}, \tilde{p})$$

TOTAL:

$$\begin{aligned} & B((\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h)) \\ & + B((\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p})) = L(\mathbf{u}_h, p_h) + L(\tilde{\mathbf{u}}, \tilde{p}) \end{aligned}$$

Energy statements

FE counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + b(\mathbf{a}, \mathbf{u}_h, \mathbf{u}_h) \\ & + (\partial_t \tilde{\mathbf{u}}, \mathbf{u}_h) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) - (\nabla \cdot \mathbf{u}_h, \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle \end{aligned}$$

SGS counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

TOTAL:

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TOTAL:

$$\frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2$$

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Energy statements

FE counterpart:

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Energy statements

FE counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + b(\mathbf{a}, \mathbf{u}_h, \mathbf{u}_h) \\ & + (\partial_t \tilde{\mathbf{u}}, \mathbf{u}_h) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) - (\nabla \cdot \mathbf{u}_h, \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle \end{aligned}$$

SGS counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

TOTAL: Static subscales

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) \\ & - (\nabla \cdot \mathbf{u}_h, \tilde{p}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle + \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

Energy statements

FE counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + b(\mathbf{a}, \mathbf{u}_h, \mathbf{u}_h) \\ & + (\partial_t \tilde{\mathbf{u}}, \mathbf{u}_h) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) - (\nabla \cdot \mathbf{u}_h, \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle \end{aligned}$$

SGS counterpart:

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TOTAL: Dynamic subscales - ASGS

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h + \tilde{\mathbf{u}}\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & - 2(\nu \Delta \mathbf{u}_h, \tilde{\mathbf{u}}) = \langle \mathbf{f}, \mathbf{u}_h \rangle + \langle \mathbf{f}, \tilde{\mathbf{u}} \rangle \end{aligned}$$

Energy statements

FE counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + b(\mathbf{a}, \mathbf{u}_h, \mathbf{u}_h) \\ & + (\partial_t \tilde{\mathbf{u}}, \mathbf{u}_h) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) - (\nabla \cdot \mathbf{u}_h, \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle \end{aligned}$$

SGS counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

TOTAL: Dynamic subscales - OSS

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & - 2(\nu \Delta \mathbf{u}_h, \tilde{\mathbf{u}}) \\ & = \langle \mathbf{f}, \mathbf{u}_h \rangle + \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

Numerical experiments

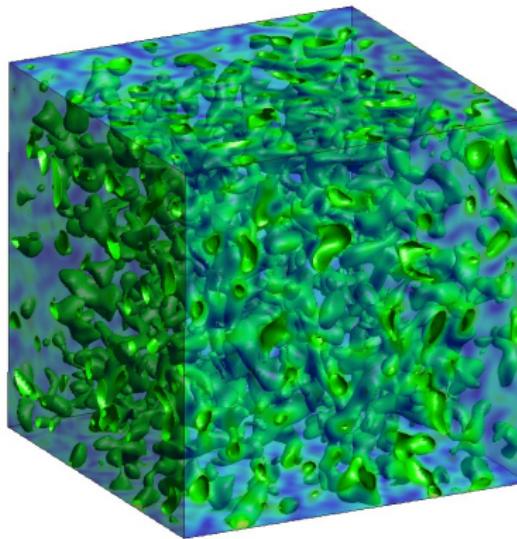
Three different turbulent benchmarks:

- Decaying of Homogeneous Isotropic Turbulence (DHIT).
- Taylor-Green Vortex (TGV) flow.
- Turbulent Channel Flow (TCF).

DHIT Decay of Homogeneous Isotropic Turbulence

Problem setting:

- Prescribed initial energy spectra corresponding to $Re_\lambda = 952$.
- Setting defined in AGARD database (Mansour & Wray 1993).
- A (very simple) time step adaptation technique is used.
- Different mesh discretizations (Q_1/Q_1 and Q_2/Q_2).



DHIT Decay of Homogeneous Isotropic Turbulence

Energy spectra (models):

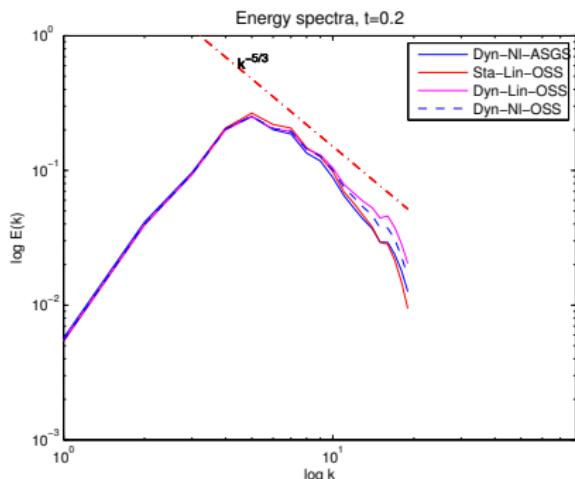


Figure : $32^3 - Q1$, $t = 0.2s$

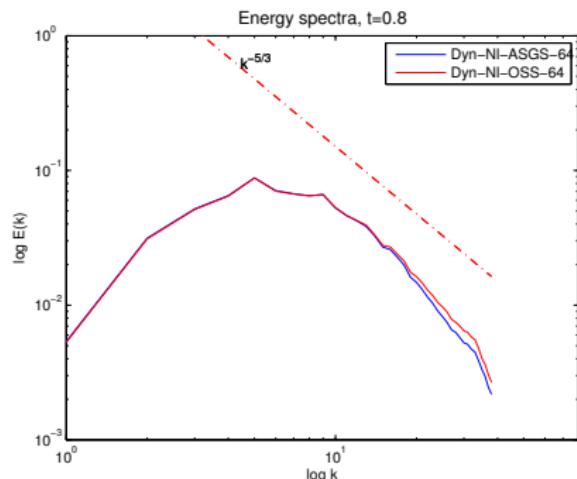


Figure : $64^3 - Q1$, $t = 0.8s$

DHIT Decay of Homogeneous Isotropic Turbulence

Energy spectra (models):

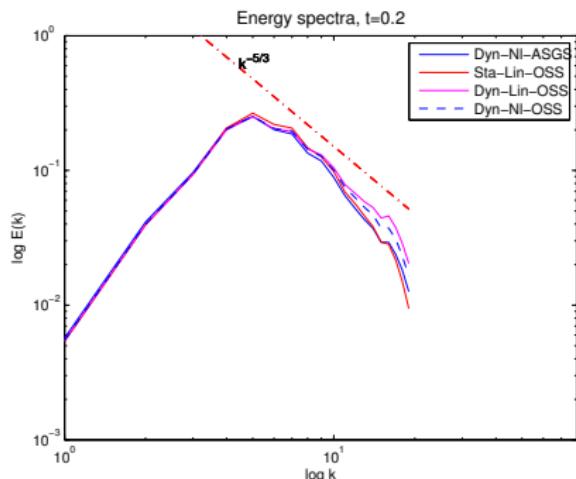


Figure : $32^3 - Q1$, $t = 0.2s$

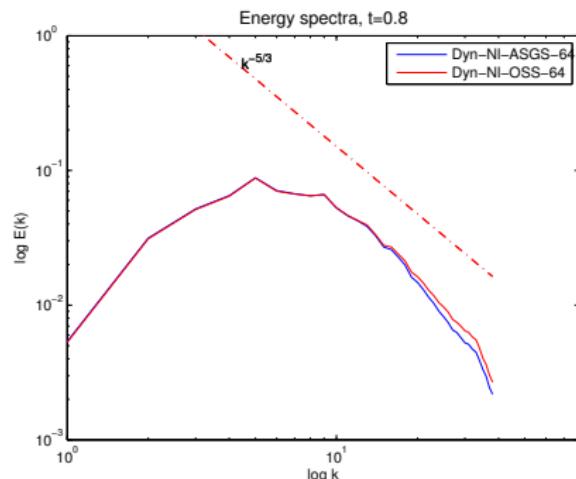


Figure : $64^3 - Q1$, $t = 0.8s$

- Small differences between methods (physical sense).

DHIT Decay of Homogeneous Isotropic Turbulence

Energy spectra (models):

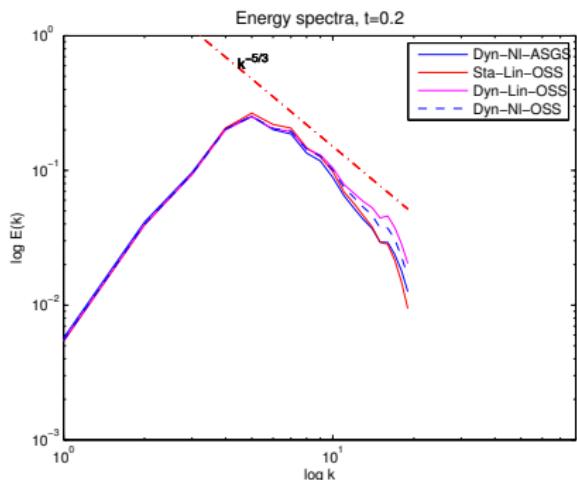


Figure : $32^3 - Q1$, $t = 0.2s$

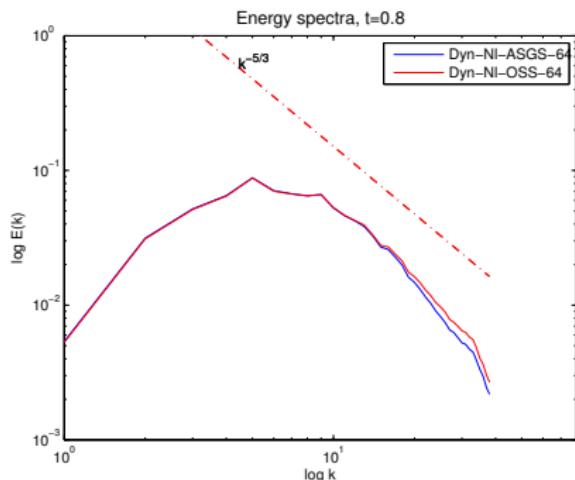


Figure : $64^3 - Q1$, $t = 0.8s$

- Small differences between methods (physical sense).
- Even more similar when we refine the mesh.

DHIT Decay of Homogeneous Isotropic Turbulence

Computational cost (models):

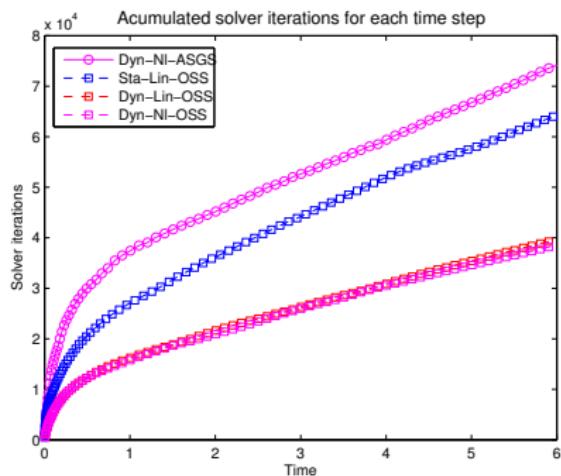


Figure : 32^3 – Q1

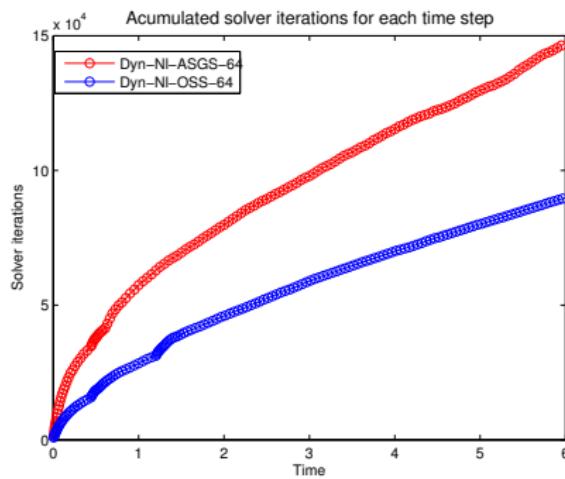


Figure : 64^3 – Q1

DHIT Decay of Homogeneous Isotropic Turbulence

Computational cost (models):

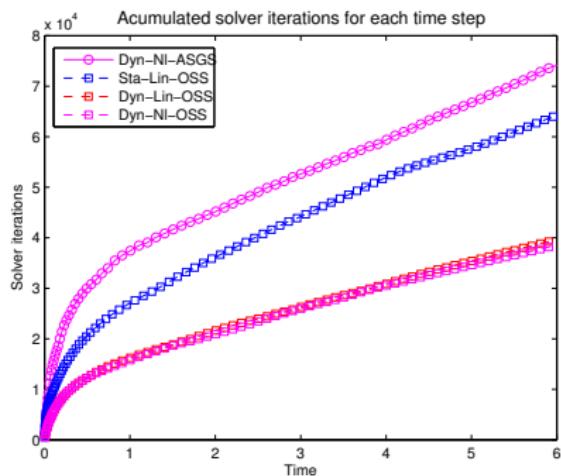


Figure : 32^3 – Q1

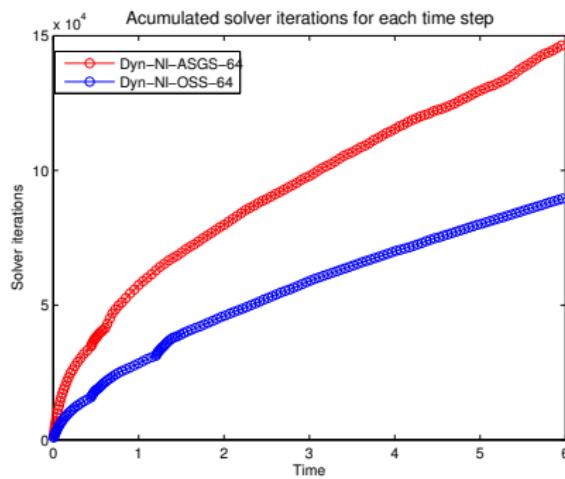


Figure : 64^3 – Q1

- Big differences between methods (computational sense).

DHIT Decay of Homogeneous Isotropic Turbulence

Computational cost (models):

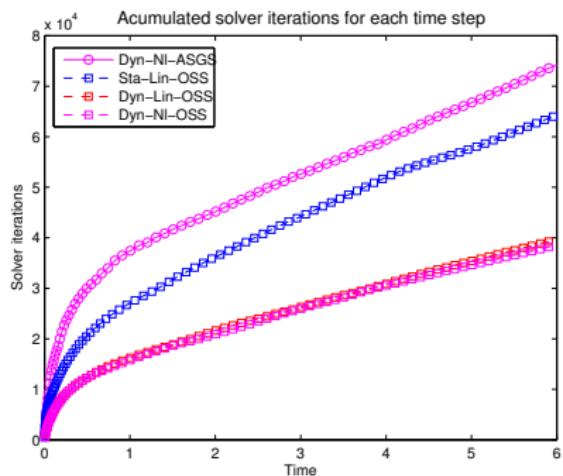


Figure : 32^3 – Q1

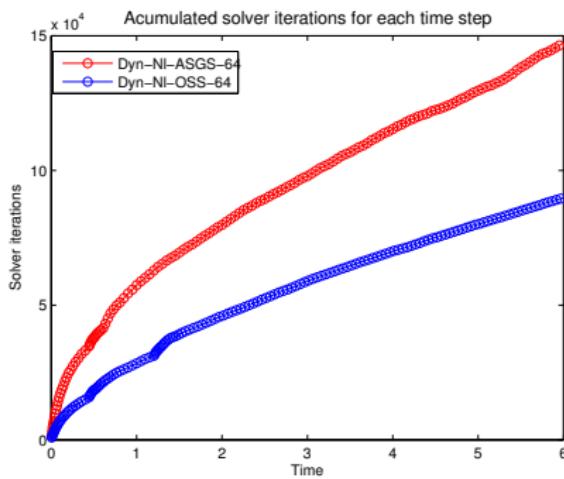
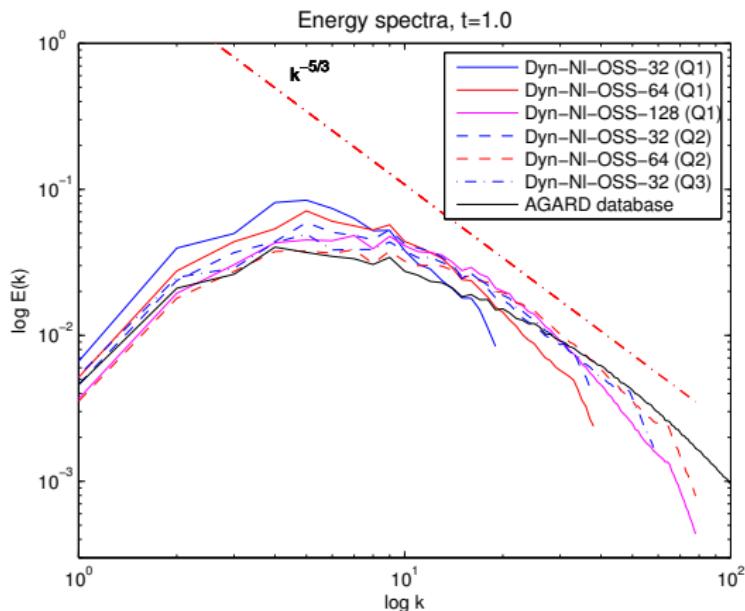


Figure : 64^3 – Q1

- Big differences between methods (computational sense).
- **Dynamic** versions of **OSS** method are **the most efficient**.

DHIT Decay of Homogeneous Isotropic Turbulence

Energy spectra (refinement):



- Results become closer to the DNS when we refine the mesh.

TGV Taylor-Green Vortex flow

Problem setting:

- Prescribed initial condition.
- $Re = 1600$.
- Different mesh discretizations (Q_1/Q_1 and Q_2/Q_2).

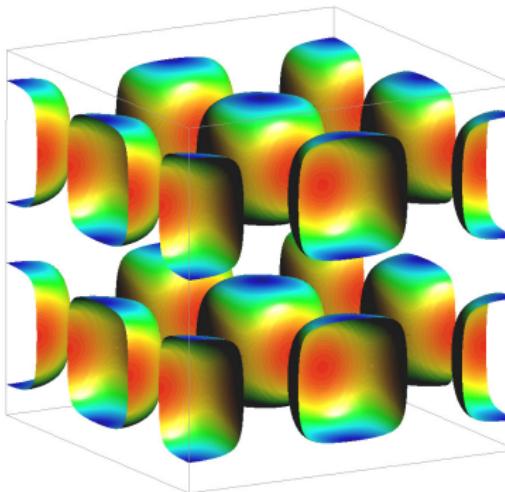


Figure : Initial vorticity isosurface $|\omega| = 1$

TGV Taylor-Green Vortex flow

Problem setting:

- Prescribed initial condition.
- $Re = 1600$.
- Different mesh discretizations (Q_1/Q_1 and Q_2/Q_2).

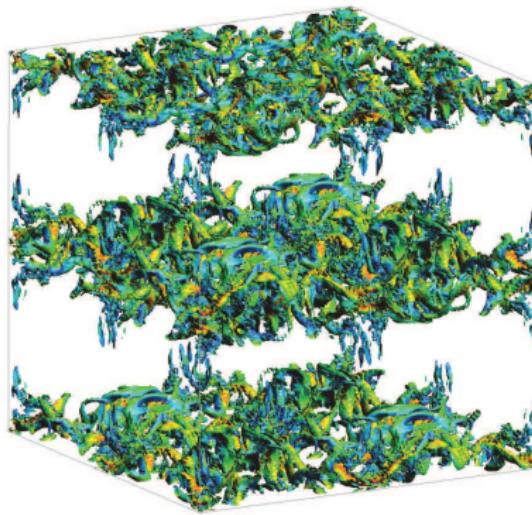


Figure : Vorticity isosurfaces $|\omega| = 9.0$

TGV Taylor-Green Vortex flow

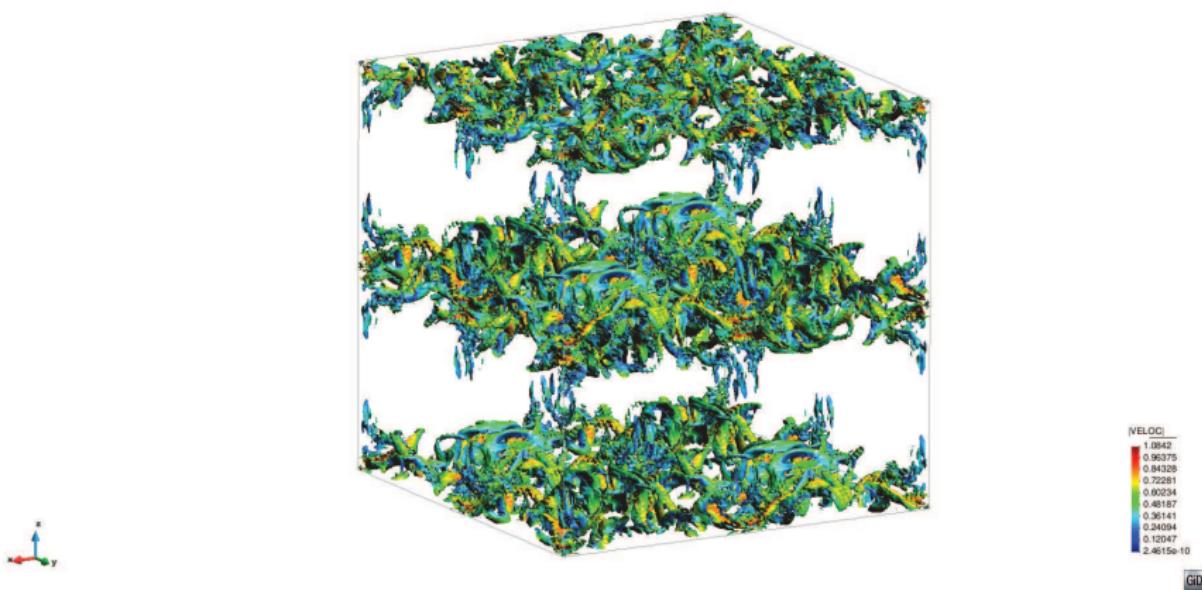


Figure : Velocity isosurface

TGV Taylor-Green Vortex flow

Energy dissipation rate (refinement):

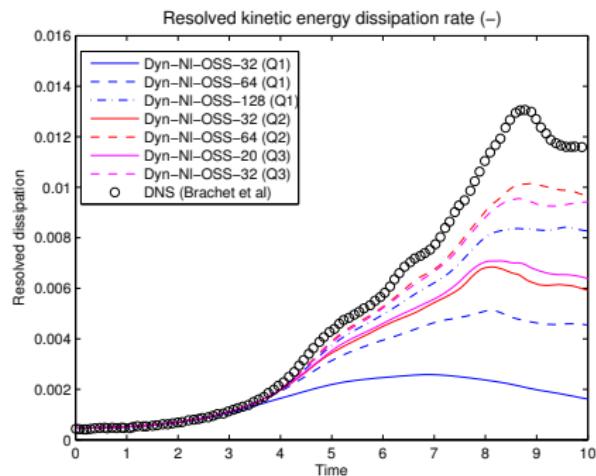


Figure : Resolved scales

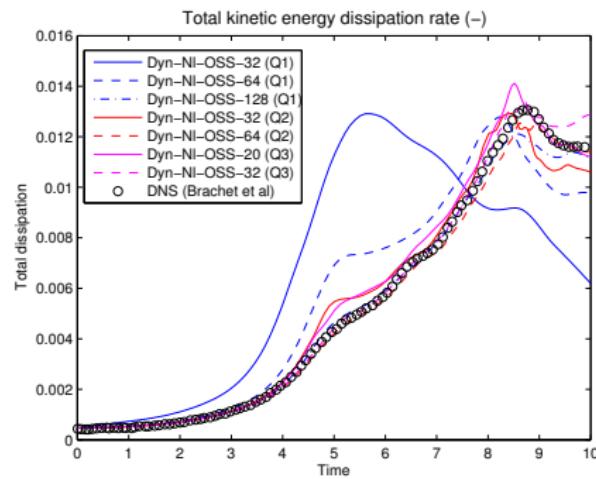


Figure : Total

TGV Taylor-Green Vortex flow

Energy dissipation rate (refinement):

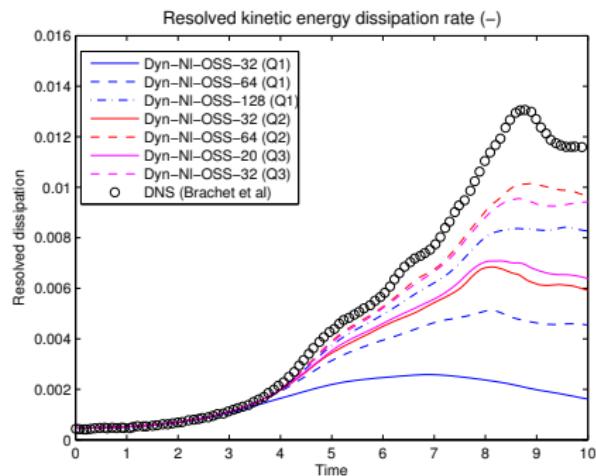


Figure : Resolved scales

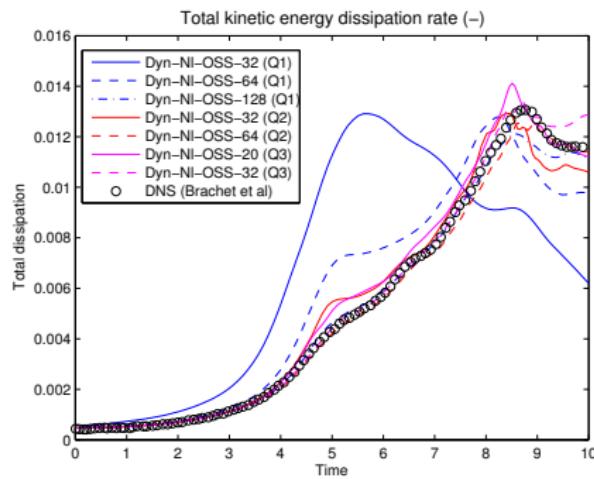


Figure : Total

- Good agreement with the DNS taking account the subscales.

TGV Taylor-Green Vortex flow

Energy dissipation rate (refinement):

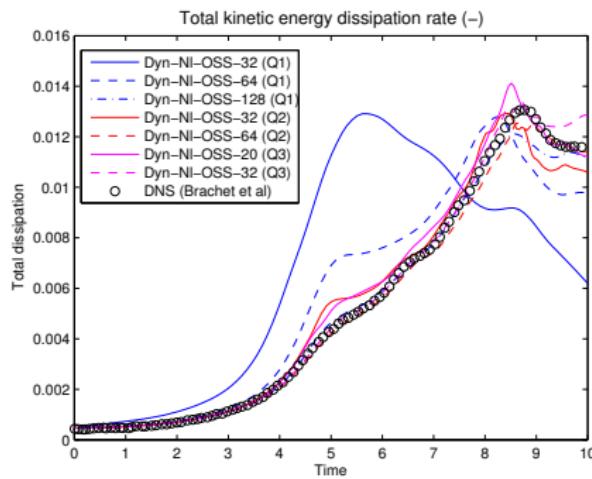
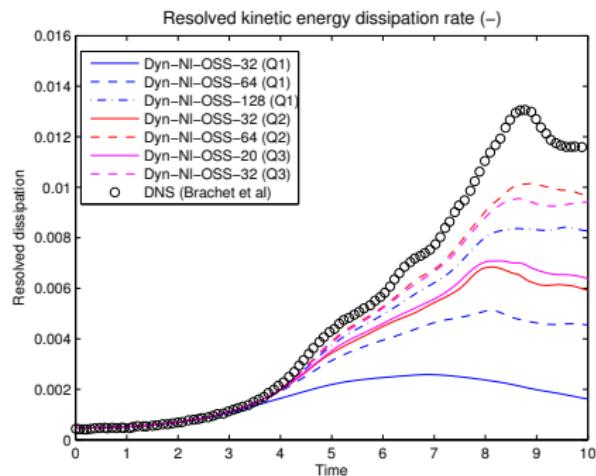


Figure : Resolved scales

Figure : Total

- Good agreement with the DNS taking account the subscales.
- More accurate results increasing the order of approximation.

TGV Taylor-Green Vortex flow

- All results until now are compared against **DNS**.
- Are our methods comparable with **LES** models?

TGV Taylor-Green Vortex flow

Energy dissipation rate (against LES model):

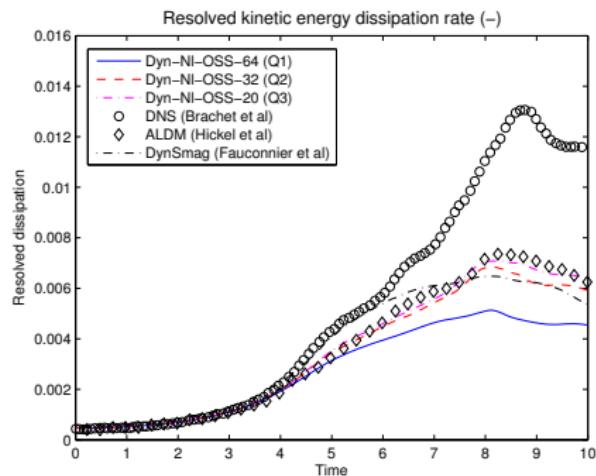


Figure : Resolved scales

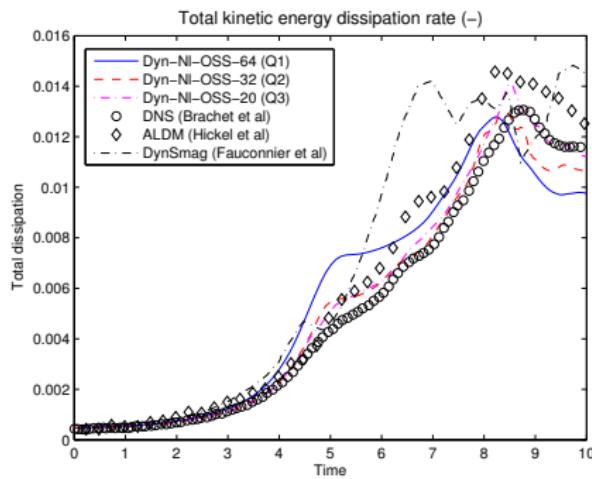


Figure : Total

TGV Taylor-Green Vortex flow

Energy dissipation rate (against LES model):

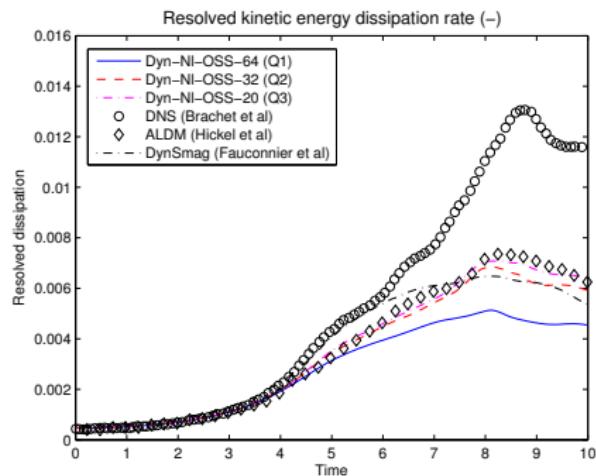


Figure : Resolved scales

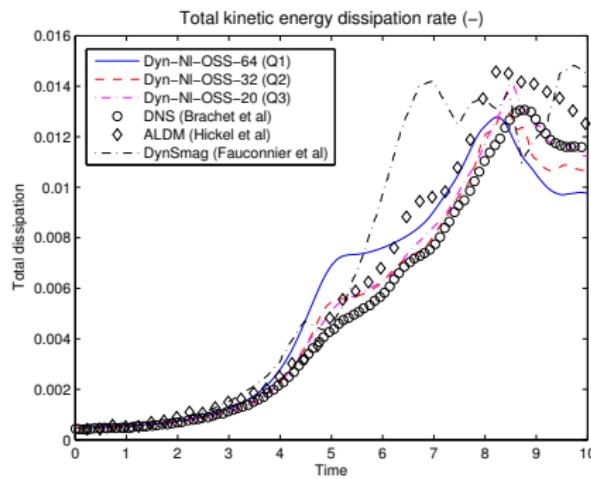


Figure : Total

- Good agreement with the LES models on resolved scales.

TGV Taylor-Green Vortex flow

Energy dissipation rate (against LES model):

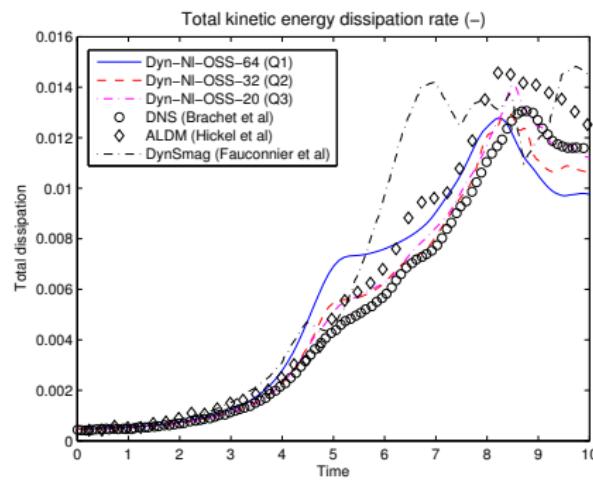
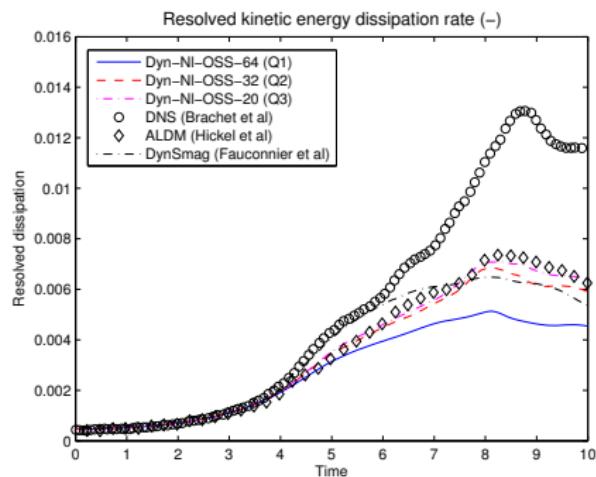


Figure : Resolved scales

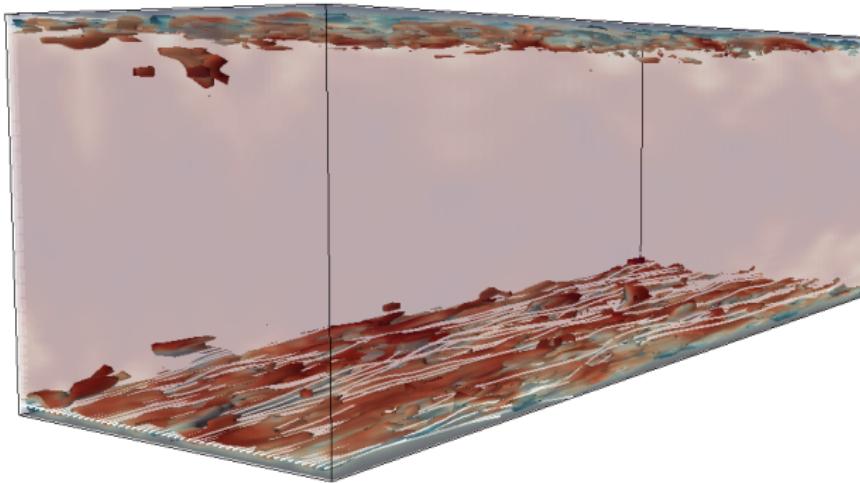
Figure : Total

- Good agreement with the LES models on resolved scales.
- Better results than LES models adding subscales counterpart.

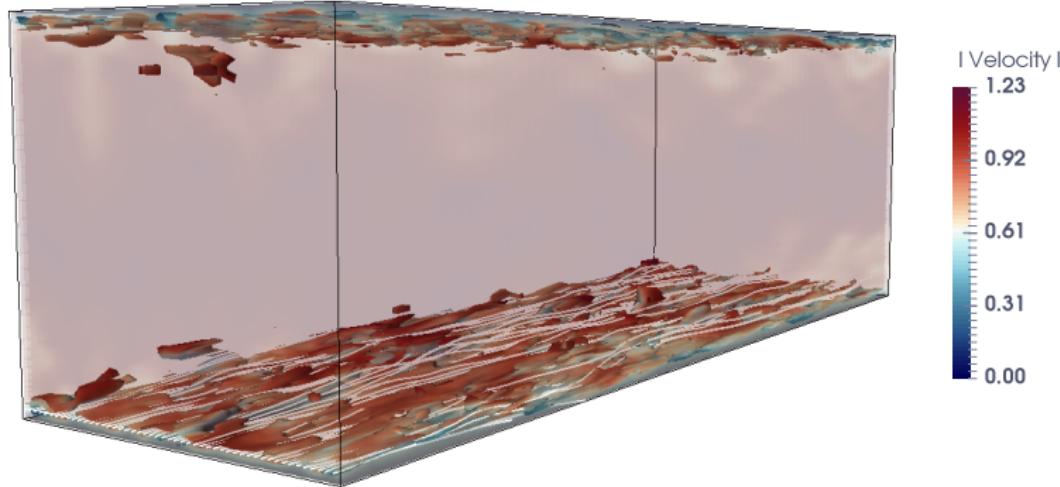
TCF Turbulent Channel Flow

Problem setting:

- Wall bounded flow.
- $Re_\tau = 180$ and $Re_\tau = 395$.
- Mesh resolution: $32^3 - Q1$.

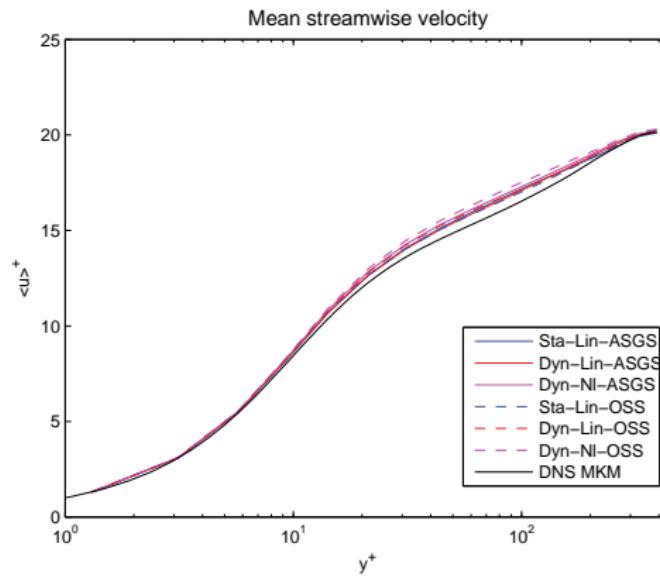


TCF Turbulent Channel Flow



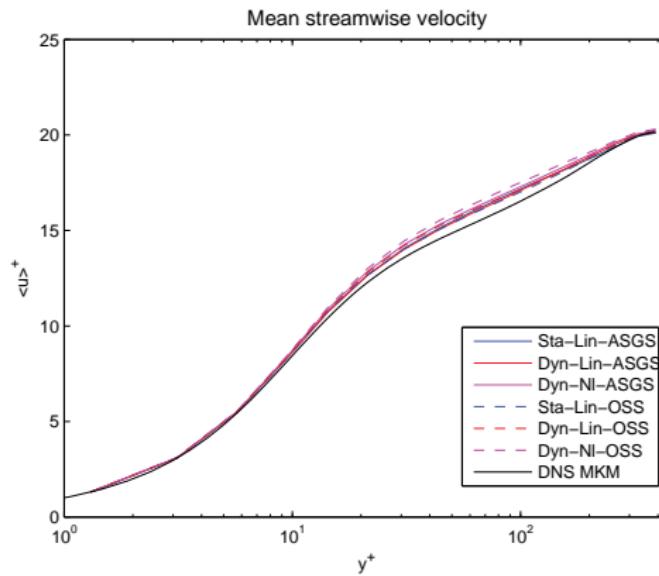
TCF Turbulent Channel Flow

Mean streamwise velocity (models):



TCF Turbulent Channel Flow

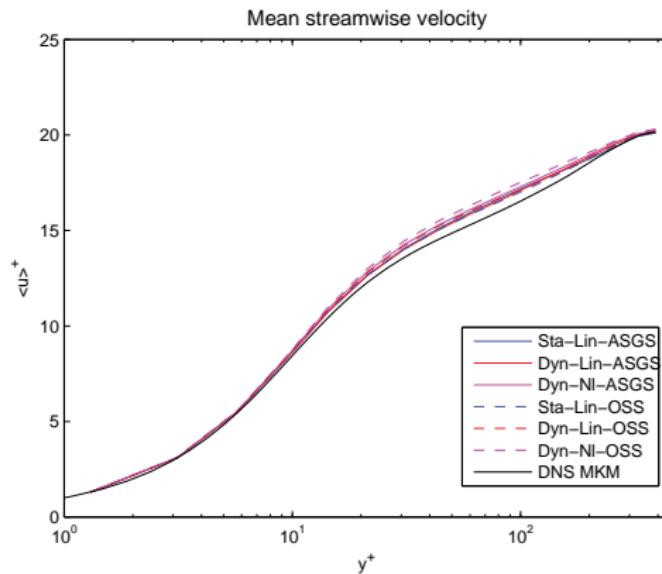
Mean streamwise velocity (models):



- Small differences between methods.

TCF Turbulent Channel Flow

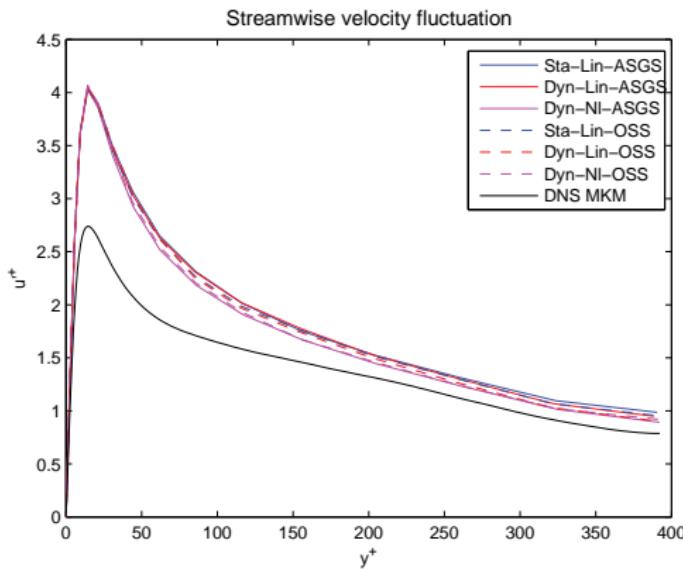
Mean streamwise velocity (models):



- Small differences between methods.
- Very accurate results compared against the DNS.

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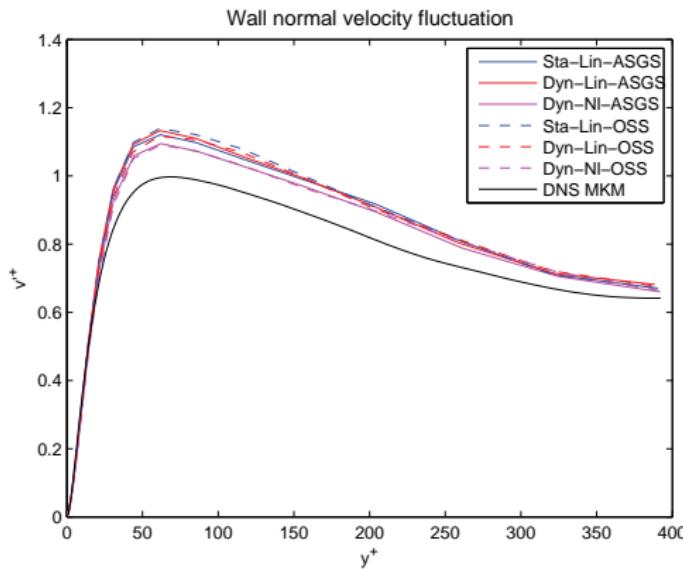
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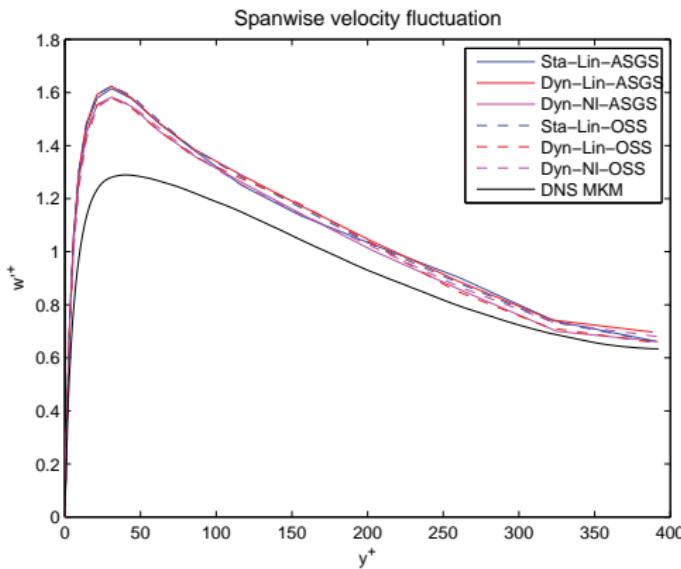
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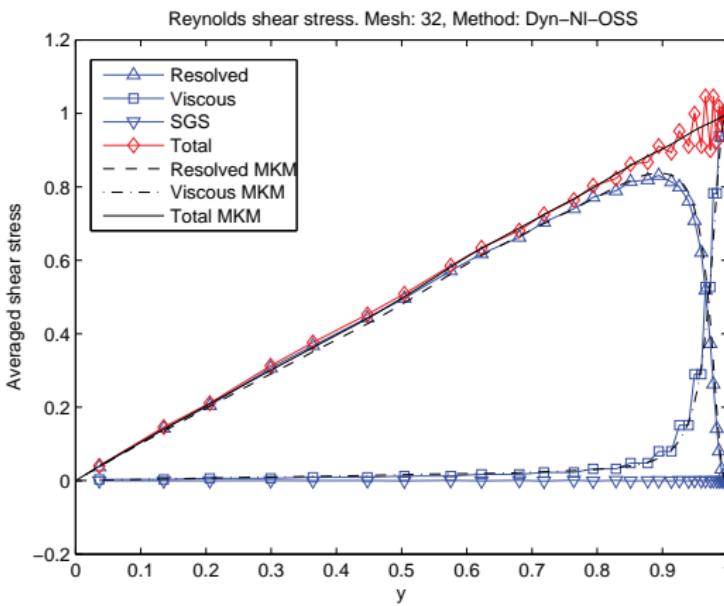
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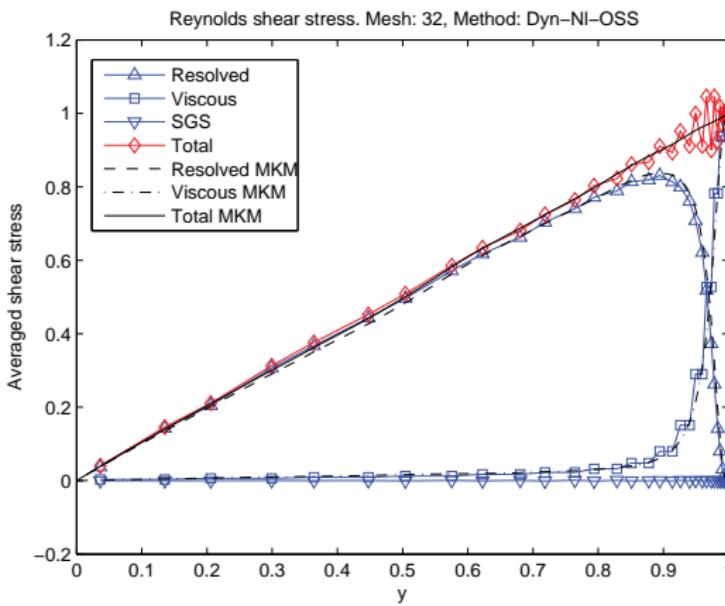
TCF Turbulent Channel Flow

Reynolds shear stress (models):



TCF Turbulent Channel Flow

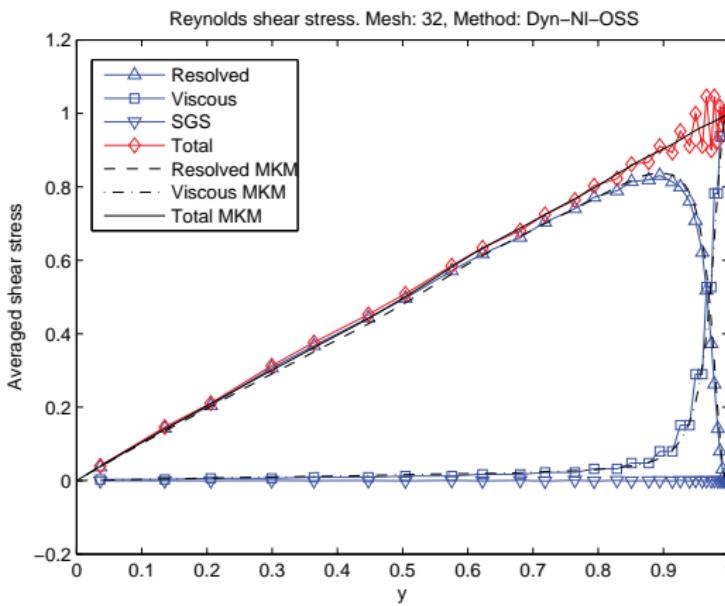
Reynolds shear stress (models):



- Almost identical to the DNS.

TCF Turbulent Channel Flow

Reynolds shear stress (models):



- Almost identical to the DNS.
- SGS counterpart does not contribute to the Reynolds shear stress.

RB-VMS Conclusions

- VMS formulations of NS equations can be used for the numerical simulation of turbulent flows.

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 - Our particular VMS modelling ingredients
 - Dynamic subscales
 - Nonlinear subscales
 - Orthgonal subscales
- seem to be important to simulate turbulent flows.

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- Among them dynamic and orthogonal subscales (linear or nonlinear) are the most effective.

RB-VMS Conclusions

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- Our particular VMS modelling ingredients
 - Dynamic subscales
 - Nonlinear subscales
 - Orthgonal subscalesseem to be important to simulate turbulent flows.
- Among them dynamic and orthogonal subscales (linear or nonlinear) are the most effective.
- The skewsymmetric formulation is important to keep stability.

RB-VMS Limitations

- ASGS:

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- **ASGS:**

- Poorly matrix conditioning \Rightarrow **High** number of **solver** iterations.

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- **Desired:**

- OSS with implicit projections.

1. Motivation

2. Residual-based VMS

3. Mixed FE VMS

Formulation

Block-preconditioning

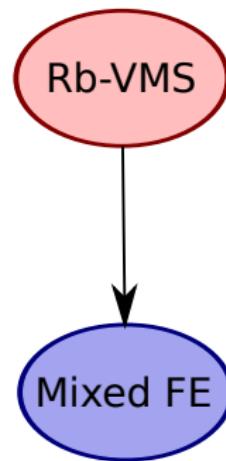
Numerical experiments

Conclusions

4. Segregated Runge-Kutta

5. Segregated VMS

6. Conclusions



Semidiscrete problem

FEM equations

$$\begin{aligned}
 & (\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\
 & + (\mathbf{v}_h, \partial_t \tilde{\mathbf{u}})_\Omega + (\mathcal{L}^* \mathbf{v}_h, \tilde{\mathbf{u}})_{\Omega^h} - (\nabla \cdot \mathbf{v}_h, \tilde{p})_{\Omega^h} = \langle \mathbf{v}_h, \mathbf{f} \rangle_\Omega \\
 & (q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\mathcal{P} = I \quad (\text{ASGS}), \quad \mathcal{P} = \mathbf{P}_h^\perp = \mathbf{I} - \mathbf{P}_h \quad (\text{OSS})$$

$$\mathbf{a} = \mathbf{u}_h + \tilde{\mathbf{u}}$$

Semidiscrete problem

FEM equations

$$\begin{aligned}
 & (\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\
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 \end{aligned}$$

SGS equations

$$\tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\mathcal{P} = \mathbf{P}_h^\perp = \mathbf{I} - \mathbf{P}_h \quad (\text{OSS})$$

$$\mathbf{a} = \mathbf{u}_h$$

Term-by-term OSS

FEM equations

$$\begin{aligned} & (\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\ & + (\mathcal{L}^* \mathbf{v}_h, \tilde{\mathbf{u}})_{\Omega^h} - (\nabla \cdot \mathbf{v}_h, \tilde{p})_{\Omega^h} = \langle \mathbf{v}_h, \mathbf{f} \rangle_\Omega \\ & (q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0 \end{aligned}$$

Term-by-term OSS

Term-by-term OSS (Codina 2008)

$$(\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega$$

$$+ \left(\tau_m \mathbf{a} \cdot \nabla \mathbf{v}_h, \mathcal{P}_h^\perp(\mathbf{a} \cdot \nabla \mathbf{u}_h) \right)_{\Omega^h}$$

$$+ \left(\tau_c \nabla \cdot \mathbf{v}_h, \mathcal{P}_h^\perp(\nabla \cdot \mathbf{u}_h) \right)_{\Omega^h} = \langle \mathbf{v}_h, \mathbf{f} \rangle_\Omega$$

$$(q_h, \nabla \cdot \mathbf{u}_h)_\Omega + \left(\tau_m \nabla q_h, \mathcal{P}_h^\perp(\nabla p_h) \right)_{\Omega^h} = 0$$

Term-by-term OSS

Term-by-term OSS (Codina 2008)

$$(\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega$$

$$+ (\tau_m \mathbf{a} \cdot \nabla \mathbf{v}_h, \mathbf{a} \cdot \nabla \mathbf{u}_h)_{\Omega^h} - (\tau_m \mathbf{a} \cdot \nabla \mathbf{v}_h, \boldsymbol{\eta}_h)_{\Omega^h}$$

$$+ (\tau_c \nabla \cdot \mathbf{v}_h, \nabla \cdot \mathbf{u}_h)_{\Omega^h} = \langle \mathbf{v}_h, \mathbf{f} \rangle_\Omega$$

$$(q_h, \nabla \cdot \mathbf{u}_h)_\Omega + (\tau_m \nabla q_h, \nabla p_h)_{\Omega^h} - (\tau_m \nabla q_h, \boldsymbol{\xi}_h)_{\Omega^h} = 0$$

$$\boldsymbol{\eta}_h := \mathcal{P}_h(\mathbf{a} \cdot \nabla \mathbf{u}_h)$$

$$\boldsymbol{\xi}_h := \mathcal{P}_h(\nabla p_h)$$

$$\mathcal{P}_h(\nabla \cdot \mathbf{u}_h) \approx 0$$

Matricial form

- ASGS:

$$\begin{bmatrix} M\dot{\mathbf{U}} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G \\ D & L_\tau \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \end{bmatrix},$$

Matricial form

- ASGS:

$$\begin{bmatrix} M\dot{\mathbf{U}} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G \\ D & L_\tau \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \end{bmatrix},$$

- Term-by-term OSS:

$$\begin{bmatrix} M\dot{\mathbf{U}} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G & B_{\eta,\tau} & 0 \\ D & L_\tau & 0 & B_{\xi,\tau} \\ -B_{\eta,\tau}^T & 0 & M_{\eta,\tau} & 0 \\ 0 & -B_{\xi,\tau}^T & 0 & M_{\xi,\tau} \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \\ \boldsymbol{\Upsilon} \\ \boldsymbol{\Xi} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix},$$

Matricial form

- ASGS:

$$\begin{bmatrix} M\dot{\mathbf{U}} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G \\ D & L_\tau \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \end{bmatrix},$$

- Term-by-term OSS:

$$\begin{bmatrix} M\dot{\mathbf{U}} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G & B_{\eta,\tau} & 0 \\ D & L_\tau & 0 & B_{\xi,\tau} \\ -B_{\eta,\tau}^T & 0 & M_{\eta,\tau} & 0 \\ 0 & -B_{\xi,\tau}^T & 0 & M_{\xi,\tau} \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \\ \boldsymbol{\Upsilon} \\ \boldsymbol{\Xi} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix},$$

- Term-by-term OSS with Inf-sup stable elements (mixed FE):

$$\begin{bmatrix} M\dot{\mathbf{U}} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G & B_\tau \\ D & 0 & 0 \\ -B_\tau^T & 0 & M_\tau \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \\ \boldsymbol{\Upsilon} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix},$$

Block-recursive preconditioning

General case:

$$\begin{bmatrix} M\dot{\mathbf{U}} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G & B_{\eta,\tau} & 0 \\ D & L_\tau & 0 & B_{\xi,\tau} \\ -B_{\eta,\tau}^T & 0 & M_{\eta,\tau} & 0 \\ 0 & -B_{\xi,\tau}^T & 0 & M_{\xi,\tau} \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \\ \boldsymbol{\Upsilon} \\ \boldsymbol{\Xi} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix},$$

Block-recursive preconditioning

General case:

$$\begin{bmatrix} M\bar{\mathbf{U}} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G & B_{\eta,\tau} & 0 \\ D & L_\tau & 0 & B_{\xi,\tau} \\ -B_{\eta,\tau}^T & 0 & M_{\eta,\tau} & 0 \\ 0 & -B_{\xi,\tau}^T & 0 & M_{\xi,\tau} \end{bmatrix} \begin{bmatrix} \bar{\mathbf{U}} \\ \bar{\mathbf{P}} \\ \bar{\boldsymbol{\Upsilon}} \\ \Xi \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix},$$

Block-recursive preconditioning

General case:

$$\begin{bmatrix} M\mathbf{U} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G & B_{\eta,\tau} & 0 \\ D & L_\tau & 0 & B_{\xi,\tau} \\ -B_{\eta,\tau}^T & 0 & M_{\eta,\tau} & 0 \\ 0 & -B_{\xi,\tau}^T & 0 & M_{\xi,\tau} \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \\ \boldsymbol{\Upsilon} \\ \boldsymbol{\Xi} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix},$$

- Outer block matrix:

$$\tilde{A} = \begin{bmatrix} M_{\eta,\tau} & 0 & -B_{\eta,\tau}^T & 0 \\ 0 & M_{\xi,\tau} & 0 & -B_{\xi,\tau}^T \\ B_{\eta,\tau} & 0 & K + C + A_\tau & G \\ 0 & B_{\xi,\tau} & D & L_\tau \end{bmatrix}$$

Block-recursive preconditioning

General case:

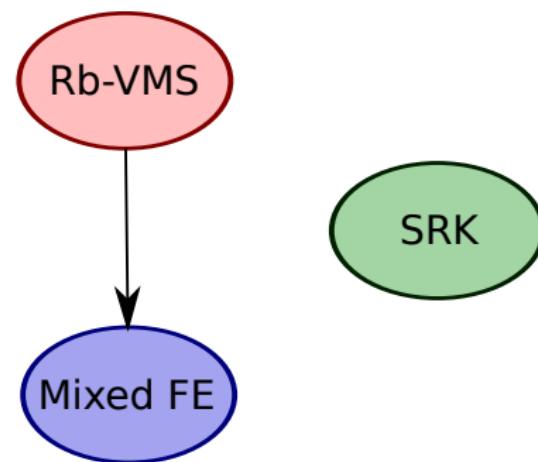
$$\begin{bmatrix} M\mathbf{U} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix} + \begin{bmatrix} K + C + A_\tau & G & B_{\eta,\tau} & 0 \\ D & L_\tau & 0 & B_{\xi,\tau} \\ -B_{\eta,\tau}^T & 0 & M_{\eta,\tau} & 0 \\ 0 & -B_{\xi,\tau}^T & 0 & M_{\xi,\tau} \end{bmatrix} \begin{bmatrix} \mathbf{U} \\ \mathbf{P} \\ \boldsymbol{\Upsilon} \\ \boldsymbol{\Xi} \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix},$$

- Outer block matrix:

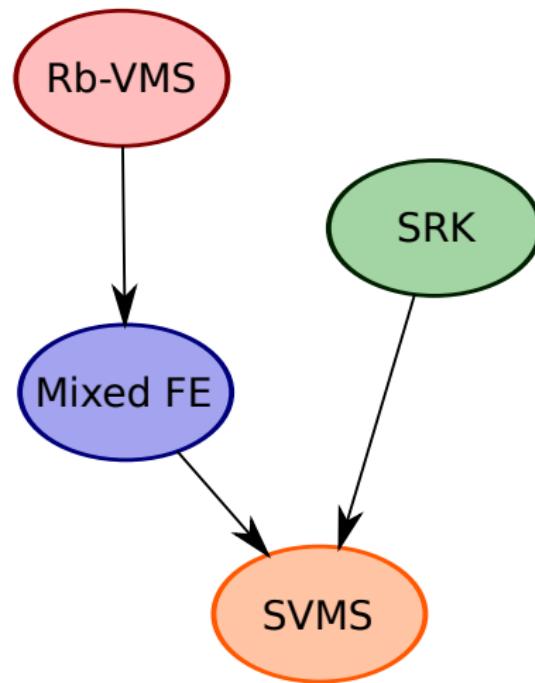
$$\tilde{A} = \begin{bmatrix} \tilde{M}_\tau & -\tilde{B}_\tau^T \\ \tilde{B}_\tau & \tilde{K} \end{bmatrix} = LU \text{ decomposition} \dots S = \dots$$

$$P(\tilde{A}) = \dots \begin{bmatrix} \tilde{M}_\tau & -\tilde{B}_\tau^T \\ \tilde{B}_\tau & \tilde{K} \end{bmatrix}, S \approx \dots$$

1. Motivation
2. Residual-based VMS
3. Mixed FE VMS
4. Segregated Runge-Kutta
Formulation
Numerical experiments
Conclusions
5. Segregated VMS
6. Conclusions



1. Motivation
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5. Segregated VMS
 - Formulation
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6. Conclusions



1. Motivation

2. Residual-based VMS

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5. Segregated VMS

6. Conclusions

Outline

- Line 1.

Outline

- Line 1.
- Line 2.

Less formal

Outline

- Line 1.
- Line 2.
Less formal
- Line 3.
Less formal, different color.

Blocks

Standard Block

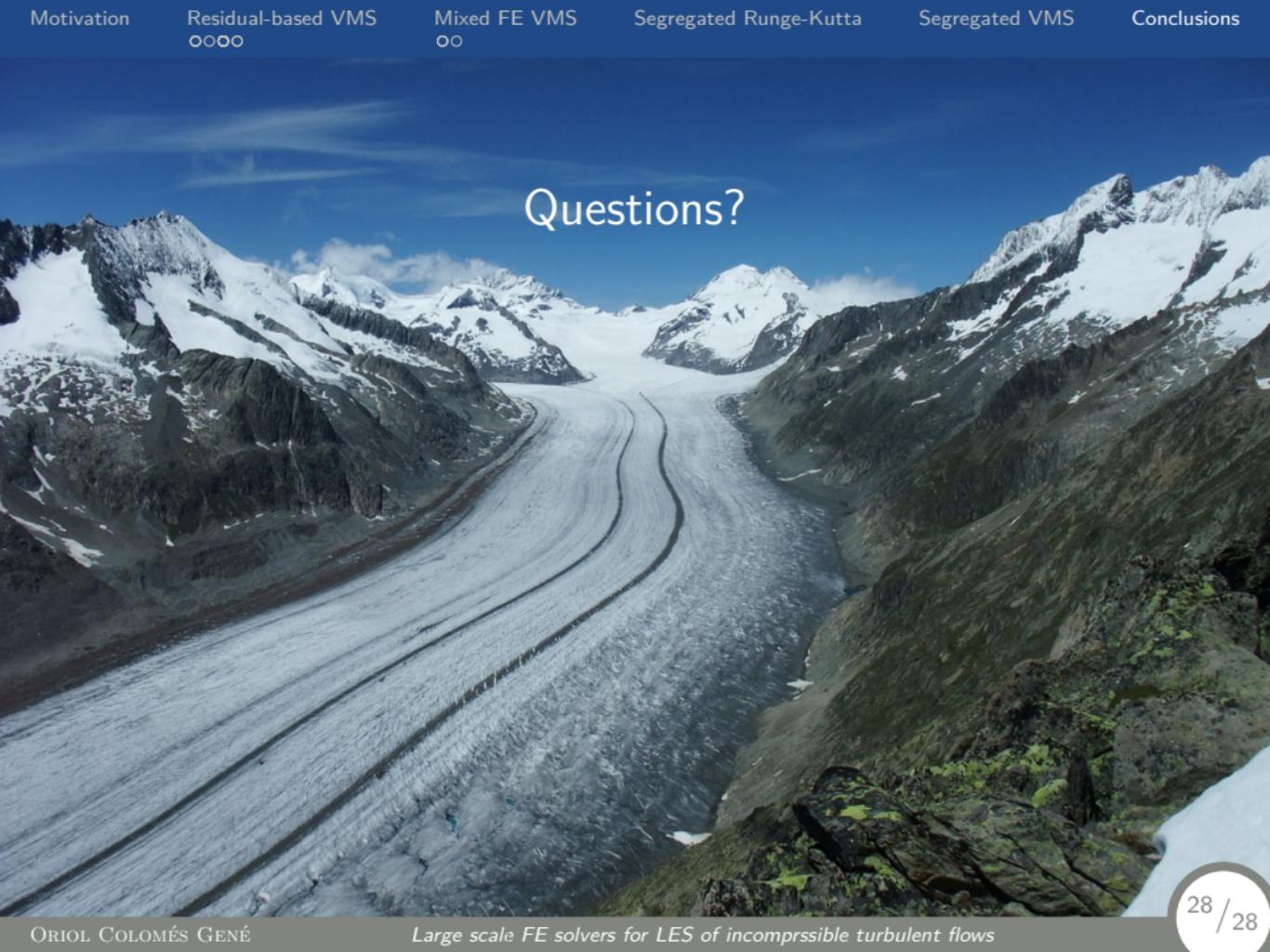
This is a standard block.

Example Block

This is an example block.

Alert Block

This is an alert block.

A wide-angle photograph of a massive glacier, likely the Aletsch Glacier in the Swiss Alps, winding its way through a deep valley between towering, snow-capped mountains. The glacier's surface is textured and shows signs of significant movement. The surrounding mountains are rugged, with patches of snow and exposed rock. The sky is a clear, vibrant blue with a few wispy clouds.

Questions?