

Large scale Finite Element solvers for the large eddy simulation of incompressible turbulent flows

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February 25, 2016



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1. Motivation
2. Residual-based VMS
3. Mixed FE VMS
4. Segregated Runge-Kutta
5. Segregated VMS
6. Conclusions

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Thesis motivation

Highly scalable Finite Element (FE) framework for Large Eddy Simulations (LES) of incompressible turbulent flows

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1. **Variational MultiScale** (VMS) methods as LES models.

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How to get there?

1. Variational MultiScale (VMS) methods as LES models.
2. Time integration schemes with **velocity-pressure segregation**.

Motivation

Thesis motivation

Highly scalable Finite Element (FE) framework for Large Eddy Simulations (LES) of incompressible turbulent flows

How to get there?

1. Variational MultiScale (VMS) methods as LES models.
2. Time integration schemes with velocity-pressure segregation.
3. Highly scalable algorithms based on **Domain Decomposition (DD)** and **block preconditioners**.

Motivation

Step by step...

- Residual-based VMS as LES models.

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- Mixed FE formulations LES.

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- Residual-based VMS as LES models.
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- High-order FE methods.

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- Velocity-pressure segregation.
- Scalable solvers.

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- Application.

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- Application.

1. Motivation


2. Residual-based VMS

Formulation

Energy statements

Numerical experiments

Conclusions



Rb-VMS

3. Mixed FE VMS

4. Segregated Runge-Kutta

5. Segregated VMS

6. Conclusions

Implicit LES

ILES: only numerical dissipation (for stabilization) acts as turbulent model

- Not based on filtering of the Navier-Stokes equations
- Rely on numerical artifacts, no modification at the continuous level

Incomp. Navier Stokes equations

Find \mathbf{u} and p defined in Ω

$$\begin{aligned}\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p - \nu \nabla^2 \mathbf{u} &= \mathbf{f} \\ \nabla \cdot \mathbf{u} &= 0\end{aligned}$$

with appropriate boundary conditions on Γ .

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The weak problem is: $\forall \mathbf{v} \in \mathcal{V}_0$ and $\forall q \in \mathcal{Q}_0$, find $\mathbf{u} \in \mathcal{V}$ and $p \in \mathcal{Q}$ such that

$$\begin{aligned}(\mathbf{v}, \partial_t \mathbf{u})_{\Omega} + (\nabla \mathbf{v}, \nu \nabla \mathbf{u})_{\Omega} + b(\mathbf{u}, \mathbf{u}, \mathbf{v}) - (\nabla \cdot \mathbf{v}, p)_{\Omega} &= \langle \mathbf{v}, \mathbf{f} \rangle_{\Omega} \\ (q, \nabla \cdot \mathbf{u})_{\Omega} &= 0\end{aligned}$$

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where

$$b(\mathbf{a}, \mathbf{u}, \mathbf{v}) = \langle \mathbf{v}, \mathbf{a} \cdot \nabla \mathbf{u} \rangle_\Omega$$

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where

$$b(\mathbf{a}, \mathbf{u}, \mathbf{v}) = \frac{1}{2} \langle \mathbf{v}, \mathbf{a} \cdot \nabla \mathbf{u} \rangle_{\Omega} - \frac{1}{2} \langle \mathbf{a} \cdot \nabla \mathbf{v}, \mathbf{u} \rangle_{\Omega} + \frac{1}{2} \langle \mathbf{v}, \mathbf{n} \cdot \mathbf{a} \mathbf{u} \rangle_{\Gamma}$$

VMS decomposition (Hughes 1995)

A decomposition of spaces \mathcal{V} and \mathcal{Q} given by

$$\mathcal{V} = \mathcal{V}_h \oplus \tilde{\mathcal{V}}, \quad \mathcal{Q} = \mathcal{Q}_h \oplus \tilde{\mathcal{Q}}$$

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$$\mathcal{V} = \mathcal{V}_h \oplus \tilde{\mathcal{V}}, \quad \mathcal{Q} = \mathcal{Q}_h \oplus \tilde{\mathcal{Q}}$$

is applied to the function and test spaces

$$\mathbf{u} = \mathbf{u}_h + \tilde{\mathbf{u}}, \quad p = p_h + \tilde{p}$$

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We keep all the (eight) contributions from the splitting of the convective term

$$\mathbf{u} \cdot \nabla \mathbf{u} = \mathbf{u}_h \cdot \nabla \mathbf{u}_h + \tilde{\mathbf{u}} \cdot \nabla \mathbf{u}_h + \mathbf{u}_h \cdot \nabla \tilde{\mathbf{u}} + \tilde{\mathbf{u}} \cdot \nabla \tilde{\mathbf{u}}$$

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and all the (four) contributions from the temporal term

$$\partial_t \mathbf{u} = \partial_t \mathbf{u}_h + \partial_t \tilde{\mathbf{u}}$$

Semidiscrete problem

FEM equations

$$B((\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{v}_h, q_h)) = L(\mathbf{v}_h, q_h)$$

SGS equations

$$B((\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h); (\tilde{\mathbf{v}}, \tilde{q})) = L(\tilde{\mathbf{v}}, \tilde{q})$$

Semidiscrete problem

FEM equations

$$\begin{aligned}
 &(\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\
 &+ (\mathbf{v}_h, \partial_t \tilde{\mathbf{u}})_\Omega + (\mathcal{L}^* \mathbf{v}_h, \tilde{\mathbf{u}})_{\Omega^h} - (\nabla \cdot \mathbf{v}_h, \tilde{p})_{\Omega^h} = \langle \mathbf{v}_h, \mathbf{f} \rangle_\Omega \\
 &(q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\tau_m = \left(\frac{c_1 \nu}{h^2} + \frac{c_2 |\mathbf{a}|}{h} \right)^{-1}, \quad \tau_c = \frac{h^2}{c_1 \tau_m}$$

$$\mathbf{a} = \mathbf{u}_h + \tilde{\mathbf{u}}$$

Semidiscrete problem

FEM equations

$$\begin{aligned}
 &(\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\
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 &(q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\mathbf{R}_m := \mathbf{f} - \partial_t \mathbf{u}_h - \mathcal{L} \mathbf{u}_h - \nabla p_h, \quad R_c := -\nabla \cdot \mathbf{u}_h$$

Semidiscrete problem

FEM equations

$$\begin{aligned}
 &(\mathbf{v}_h, \partial_t \mathbf{u}_h)_\Omega + b(\mathbf{a}, \mathbf{u}_h, \mathbf{v}_h) + (\nabla \mathbf{v}_h, \nu \nabla \mathbf{u}_h)_\Omega - (\nabla \cdot \mathbf{v}_h, p_h)_\Omega \\
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 &(q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\mathcal{P} = I \quad (\text{ASGS}), \quad \mathcal{P} = P_h^\perp = I - P_h \quad (\text{OSS})$$

Semidiscrete problem

FEM equations

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 &(q_h, \nabla \cdot \mathbf{u}_h)_\Omega - (\nabla q_h, \tilde{\mathbf{u}})_{\Omega^h} = 0
 \end{aligned}$$

SGS equations

$$\partial_t \tilde{\mathbf{u}} + \tau_m^{-1} \tilde{\mathbf{u}} = \mathcal{P} \mathbf{R}_m$$

$$\tau_c^{-1} \tilde{p} = \mathcal{P} R_c$$

$$\mathcal{P} = I \quad (\text{ASGS}), \quad \mathcal{P} = P_h^\perp = I - P_h \quad (\text{OSS})$$

$$\mathbf{a} = \mathbf{u}_h + \tilde{\mathbf{u}}$$

Summary

	Sgs space	Sgs dynamics	Advection
1	ASGS	Static	Linear
2	ASGS	Dynamic	Linear
3	ASGS	Dynamic	Nonlinear
4	OSS	Static	Linear
5	OSS	Dynamic	Linear
6	OSS	Dynamic	Nonlinear

- 1 It is the most standard method (SUPG for linear elements) up to the choice of the stabilization parameters. Unknown stability properties.
- 4 Strictly pointwise positive for linear elements (no backscatter).
- 5 Convergent to weak solutions of NS equations (Badia & Gutierrez 2012).

Energy statements

FE counterpart:

$$B((\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h)) = L(\mathbf{u}_h, p_h)$$

SGS counterpart:

$$B((\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p})) = L(\tilde{\mathbf{u}}, \tilde{p})$$

TOTAL:

$$\begin{aligned} & B((\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h)) \\ & + B((\tilde{\mathbf{u}}, \tilde{p}); (\mathbf{u}_h, p_h); (\tilde{\mathbf{u}}, \tilde{p})) = L(\mathbf{u}_h, p_h) + L(\tilde{\mathbf{u}}, \tilde{p}) \end{aligned}$$

Energy statements

FE counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + b(\mathbf{a}, \mathbf{u}_h, \mathbf{u}_h) \\ & + (\partial_t \tilde{\mathbf{u}}, \mathbf{u}_h) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) - (\nabla \cdot \mathbf{u}_h, \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle \end{aligned}$$

SGS counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

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TOTAL:

$$\frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2$$

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FE counterpart:

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Energy statements

FE counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + b(\mathbf{a}, \mathbf{u}_h, \mathbf{u}_h) \\ & + (\partial_t \tilde{\mathbf{u}}, \mathbf{u}_h) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) - (\nabla \cdot \mathbf{u}_h, \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle \end{aligned}$$

SGS counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

TOTAL: Static subscales

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) \\ & - (\nabla \cdot \mathbf{u}_h, \tilde{p}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle + \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

Energy statements

FE counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + b(\mathbf{a}, \mathbf{u}_h, \mathbf{u}_h) \\ & + (\partial_t \tilde{\mathbf{u}}, \mathbf{u}_h) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) - (\nabla \cdot \mathbf{u}_h, \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle \end{aligned}$$

SGS counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

TOTAL: **Dynamic subscales - ASGS**

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h + \tilde{\mathbf{u}}\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & - 2(\nu \Delta \mathbf{u}_h, \tilde{\mathbf{u}}) \\ & = \langle \mathbf{f}, \mathbf{u}_h \rangle + \langle \mathbf{f}, \tilde{\mathbf{u}} \rangle \end{aligned}$$

Energy statements

FE counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + b(\mathbf{a}, \mathbf{u}_h, \mathbf{u}_h) \\ & + (\partial_t \tilde{\mathbf{u}}, \mathbf{u}_h) + (\mathcal{L}_a^*(\mathbf{u}_h, p_h), \tilde{\mathbf{u}}) - (\nabla \cdot \mathbf{u}_h, \tilde{p}) = \langle \mathbf{f}, \mathbf{u}_h \rangle \end{aligned}$$

SGS counterpart:

$$\begin{aligned} & \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & + (\mathcal{P}(\partial_t \mathbf{u}_h), \tilde{\mathbf{u}}) + (\mathcal{P}(\mathcal{L}_a^*(\mathbf{u}_h, p_h)), \tilde{\mathbf{u}}) - (\mathcal{P}(\nabla \cdot \mathbf{u}_h), \tilde{p}) = \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

TOTAL: **Dynamic subscales - OSS**

$$\begin{aligned} & \frac{1}{2} d_t \|\mathbf{u}_h\|^2 + \frac{1}{2} d_t \|\tilde{\mathbf{u}}\|^2 + \nu \|\nabla \mathbf{u}_h\|^2 + \tau_m^{-1} \|\tilde{\mathbf{u}}\|^2 + \tau_c^{-1} \|\tilde{p}\|^2 \\ & - 2(\nu \Delta \mathbf{u}_h, \tilde{\mathbf{u}}) \\ & = \langle \mathbf{f}, \mathbf{u}_h \rangle + \langle \mathcal{P}(\mathbf{f}), \tilde{\mathbf{u}} \rangle \end{aligned}$$

Numerical experiments

Three different turbulent benchmarks:

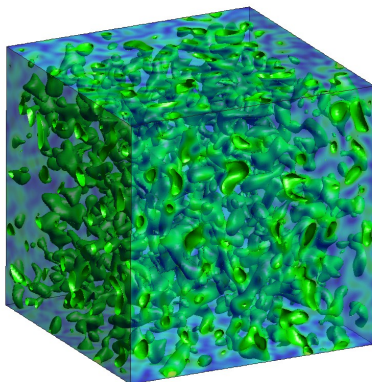
- Decaying of Homogeneous Isotropic Turbulence (DHIT).
- Taylor-Green Vortex (TGV) flow.
- Turbulent Channel Flow (TCF).

DHIT

Decay of Homogeneous Isotropic Turbulence

Problem setting:

- Prescribed initial energy spectra corresponding to $Re_\lambda = 952$.
- Setting defined in AGARD database (Mansour & Wray 1993).
- A (very simple) time step adaptation technique is used.
- Different mesh discretizations (Q_1/Q_1 and Q_2/Q_2).



DHIT Decay of Homogeneous Isotropic Turbulence

Energy spectra (models):

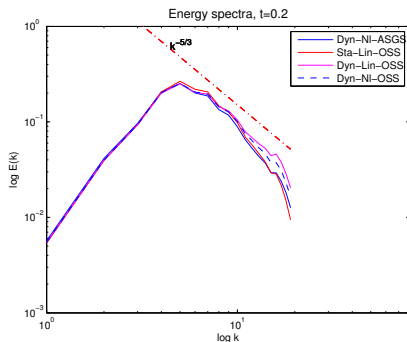


Figure : $32^3 - Q1$, $t = 0.2s$

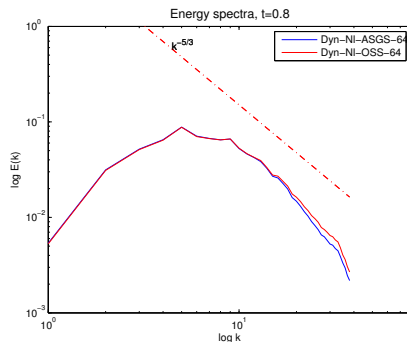


Figure : $64^3 - Q1$, $t = 0.8s$

DHIT Decay of Homogeneous Isotropic Turbulence

Energy spectra (models):

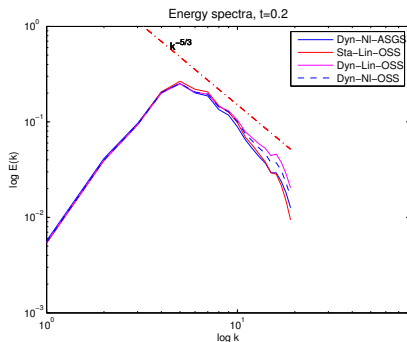


Figure : $32^3 - Q1$, $t = 0.2s$

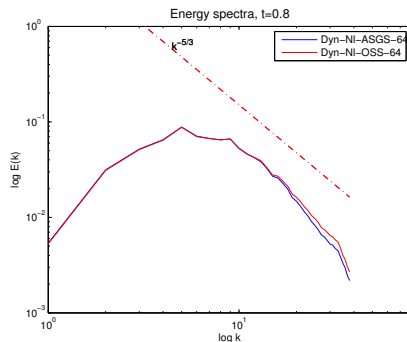


Figure : $64^3 - Q1$, $t = 0.8s$

- Small differences between methods (physical sense).

DHIT Decay of Homogeneous Isotropic Turbulence

Energy spectra (models):

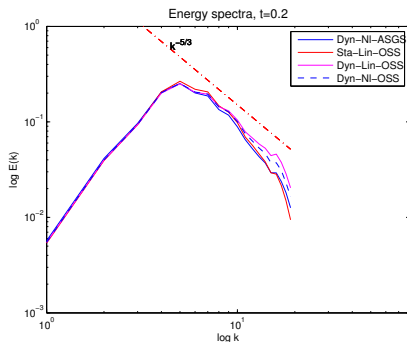


Figure : $32^3 - Q1$, $t = 0.2s$

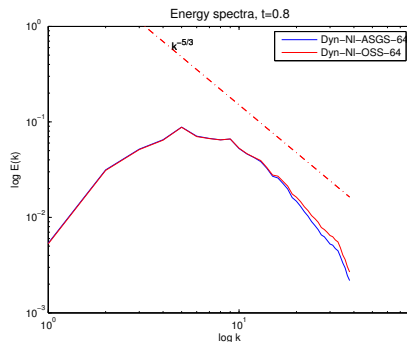


Figure : $64^3 - Q1$, $t = 0.8s$

- Small differences between methods (physical sense).
- Even **more similar when we refine** the mesh.

DHIT Decay of Homogeneous Isotropic Turbulence

Computational cost (models):

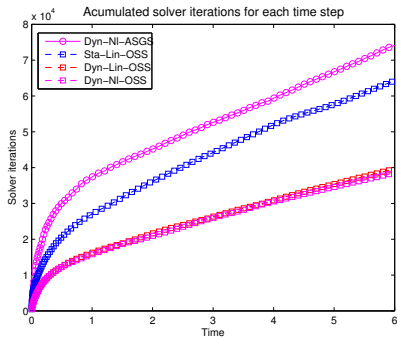


Figure : 32³ - Q1

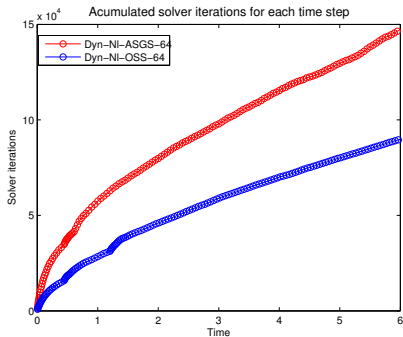


Figure : 64³ - Q1

DHIT Decay of Homogeneous Isotropic Turbulence

Computational cost (models):

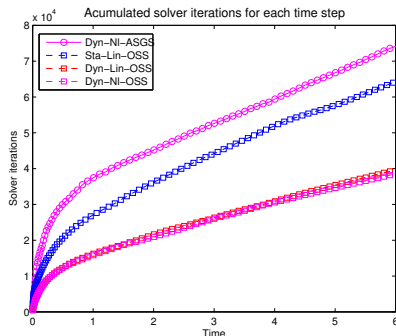


Figure : 32³ - Q1

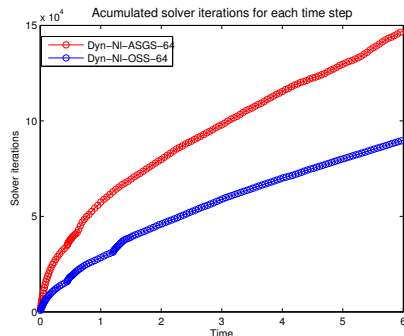


Figure : 64³ - Q1

- Big differences between methods (computational sense).

DHIT Decay of Homogeneous Isotropic Turbulence

Computational cost (models):

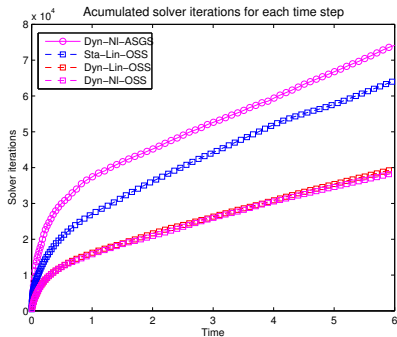


Figure : 32³ - Q1

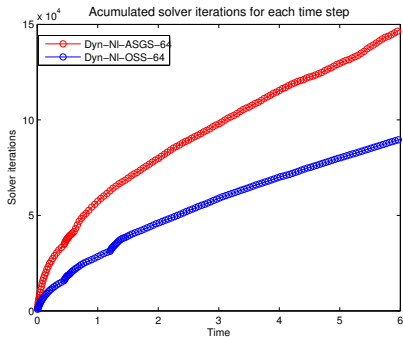
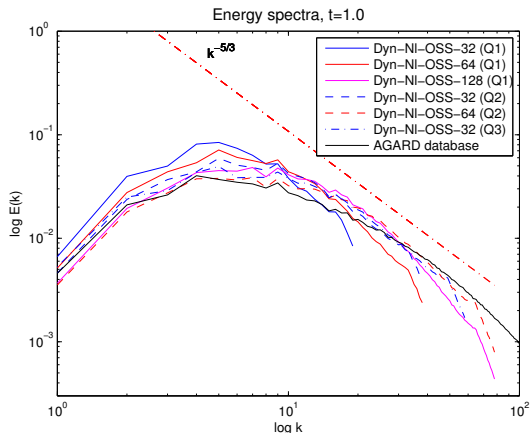


Figure : 64³ - Q1

- Big differences between methods (computational sense).
- **Dynamic** versions of **OSS** method are **the most efficient**.

DHIT Decay of Homogeneous Isotropic Turbulence

Energy spectra (refinement):



- Results become closer to the DNS when we refine the mesh.

TGV Taylor-Green Vortex flow

Problem setting:

- Prescribed initial condition.
- $Re = 1600$.
- Different mesh discretizations (Q_1/Q_1 and Q_2/Q_2).

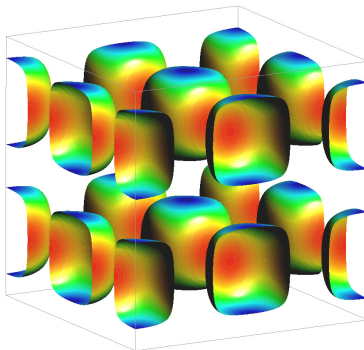


Figure : Initial vorticity isosurface $|\omega| = 1$

TGV Taylor-Green Vortex flow

Problem setting:

- Prescribed initial condition.
- $Re = 1600$.
- Different mesh discretizations (Q_1/Q_1 and Q_2/Q_2).

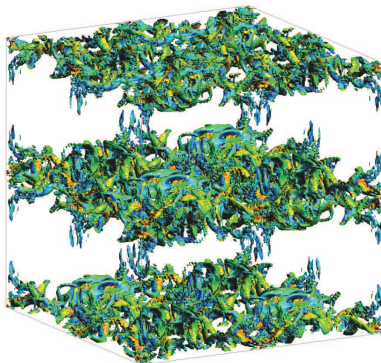


Figure : Vorticity isosurfaces $|\omega| = 9.0$

TGV Taylor-Green Vortex flow

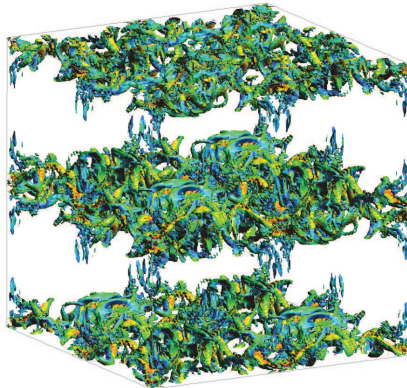


Figure : Velocity isosurface

1. Motivation

2. Residual-based VMS

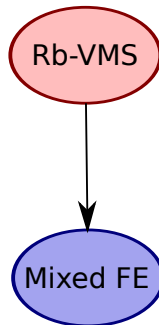
3. Mixed FE VMS

Formulation

Block-preconditioning

Numerical experiments

Conclusions



4. Segregated Runge-Kutta

5. Segregated VMS

6. Conclusions

1. Motivation

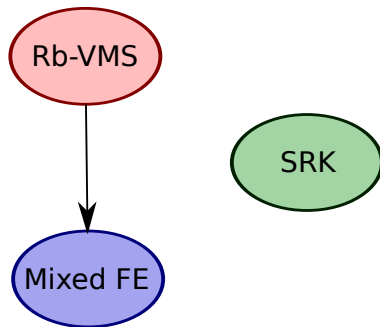
2. Residual-based VMS

3. Mixed FE VMS

4. Segregated Runge-Kutta
Formulation
Numerical experiments
Conclusions

5. Segregated VMS

6. Conclusions



1. Motivation

2. Residual-based VMS

3. Mixed FE VMS

4. Segregated Runge-Kutta

5. Segregated VMS

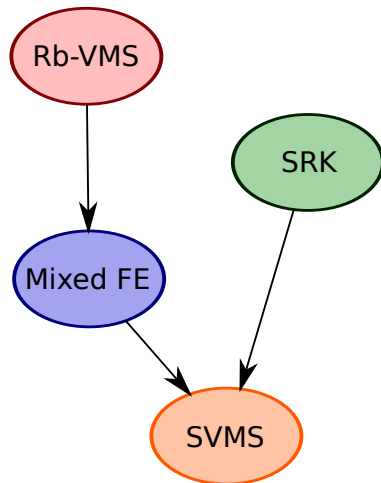
Formulation

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Numerical experiments

Conclusions

6. Conclusions



1. Motivation
2. Residual-based VMS
3. Mixed FE VMS
4. Segregated Runge-Kutta
5. Segregated VMS
6. Conclusions

Outline

- Line 1.

Outline

- Line 1.
- Line 2.

Less formal

Outline

- Line 1.
- Line 2.
Less formal
- Line 3.
Less formal, different color.

Blocks

Standard Block

This is a standard block.

Example Block

This is an example block.

Alert Block

This is an alert block.

Questions?