High Dimensional Probability Notes

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1 Random variables

1.1 Basic Inequalities

First, we revisit the definition of a random variable as well as some basic inequalities that we learned in introductory statistics.

Definition 1.1 (Random variable).

Let $(\Omega, \Sigma, \mathbb{P})$ be a probability space. A random variable X is defined as a mapping from the sample space Ω to \mathbb{R} :

$$X:\Omega\to\mathbb{R}$$
 (1)

 Σ is the σ -algebra containing the possible events (collection of subsets of Ω) and \mathbb{P} is a probability measure that assigns events with probabilities:

$$\mathbb{P}: \Sigma \to [0, 1] \tag{2}$$

For a given probability space $(\Omega, \Sigma, \mathbb{P})$ and a random variable $X : \Omega \to \mathbb{R}$, we will use the following basic notations throughout this note:

• $||X||_{L^p}$ - The p^{th} root of the p^{th} moment of the random variable X.

$$||X||_{L^p} = (\mathbb{E}|X|^p)^{1/p}, \ p \in (0, \infty)$$
 (3)

$$||X||_{L^{\infty}} = \operatorname{ess\,sup}|X| \tag{4}$$

• $L^p(\Omega, \Sigma, \mathbb{P})$ - The space of random variables X satisfying:

$$L^{p}(\Omega, \Sigma, \mathbb{P}) = \left\{ X : \Omega \to \mathbb{R} \middle| \|X\|_{L^{p}} < \infty \right\}$$
 (5)

Some basic inequalities and identities:

• 1. Jensen's Inequality - For a random variable X and a convex function $\varphi : \mathbb{R} \to \mathbb{R}$, we have:

$$\varphi(\mathbb{E}X) \leqslant \mathbb{E}\varphi(X) \tag{6}$$

• 2. Monotonicity of L^p norm - For a random variable X:

$$||X||_{L^p} \leqslant ||X||_{L^q}, \ 0 \leqslant p \leqslant q \leqslant \infty. \tag{7}$$

• 3. Minkowski's Inequality - For $1 \le p \le \infty$ and two random variables X, Y in $L^p(\Omega, \Sigma, \mathbb{P})$ space:

$$||X + Y||_{L^p} \le ||X||_{L^p} + ||Y||_{L^p}. \tag{8}$$

• 4. Holder's Inequality - For $p, q \in [1, \infty]$ such that 1/p + 1/q = 1. Then, for random variables $X \in L^p(\Omega, \Sigma, \mathbb{P})$ and $Y \in L^q(\Omega, \Sigma, \mathbb{P})$, we have:

$$|\mathbb{E}XY| \leqslant ||X||_{L^p} \cdot ||Y||_{L^q}. \tag{9}$$

• 5. Markov's Inequality - For a non-negative random variable X and t > 0, we have:

$$\mathbb{P}(X \geqslant t) \leqslant \frac{\mathbb{E}X}{t}.\tag{10}$$

We can also generalize Markov's Inequality for p^{th} moment:

$$\mathbb{P}(|X| \ge t) \le \frac{\mathbb{E}[|X|^p]}{t^p}, \forall t > 0, k \in [2, \infty). \tag{11}$$

• 6. Chebyshev's Inequality - For a random variable X with mean μ and variance σ^2 . Then, for any t > 0, we have:

$$\mathbb{P}(|X - \mu| \ge t) \le \frac{\sigma^2}{t^2}.\tag{12}$$

• 7. Integral Identity - Let X be a non-negative random variable, we have:

$$\mathbb{E}X = \int_0^\infty \mathbb{P}(X > t)dt. \tag{13}$$

Exercises

Exercise 1.1.1: Generalized Integral Identity

Let X be a random variable (not necessarily non-negative). Prove the following identity:

$$\mathbb{E}X = \int_0^\infty \mathbb{P}(X > t)dt - \int_{-\infty}^0 \mathbb{P}(X < t)dt. \tag{14}$$

Solution (Exercise 1.1.1).

For $x \in \mathbb{R}$, using the basic integral indentity, we have:

$$|x| = \int_0^\infty \mathbf{1}\{t < |x|\}dt$$

We consider the following cases:

• When $x < 0 \implies x = -|x|$:

$$x = -\int_0^\infty \mathbf{1}\{t < |x|\}dt = -\int_0^\infty \mathbf{1}\{t < -x\}dt = -\int_0^\infty \mathbf{1}\{-t > x\}dt = -\int_{-\infty}^0 \mathbf{1}\{t > x\}dt.$$

• When $x \ge 0 \implies x = |x|$:

$$x = \int_0^\infty \mathbf{1}\{t < |x|\}dt = \int_0^\infty \mathbf{1}\{t < x\}dt.$$

Therefore, for $x \in \mathbb{R}$, we can write:

$$x = \int_0^\infty \mathbf{1}\{t < x\}dt - \int_{-\infty}^0 \mathbf{1}\{t > x\}dt.$$

Therefore, for a random variable X not necessarily non-negative, we have:

$$\begin{split} \mathbb{E}X &= \mathbb{E}\Bigg[\int_0^\infty \mathbf{1}\{t < X\}dt - \int_{-\infty}^0 \mathbf{1}\{t > X\}dt\Bigg] \\ &= \mathbb{E}\int_0^\infty \mathbf{1}\{t < X\}dt - \mathbb{E}\int_{-\infty}^0 \mathbf{1}\{t > X\}dt \\ &= \int_0^\infty \mathbb{E}\mathbf{1}\{t < X\}dt - \int_{-\infty}^0 \mathbb{E}\mathbf{1}\{t > X\}dt \\ &= \int_0^\infty \mathbb{P}(t < X)dt - \int_{-\infty}^0 \mathbb{P}(t > X)dt. \end{split}$$

ο.

Exercise 1.1.2: p^{th} -moments via tails

Let X be a random variable and $p \in (0, \infty)$. Show that:

$$\mathbb{E}|X|^p = \int_0^\infty pt^{p-1}\mathbb{P}(|X| > t)dt. \tag{15}$$

Π.

Solution (Exercise 1.1.2).

Let X be a random variable that is not necessarily non-negative. Using the integral identity, we have:

$$\mathbb{E}|X|^p = \int_0^\infty \mathbb{P}(u < |X|^p) du.$$

Let $t^p = u \implies pt^{p-1}dt = du$. Since we integrate u from $0 \to \infty$, we also integrate t from $0 \to \infty$ when changing the variables. Hence, we have:

$$\mathbb{E}|X|^{p} = \int_{0}^{\infty} \mathbb{P}(t^{p} < |X|^{p})pt^{p-1}dt = \int_{0}^{\infty} \mathbb{P}(t < |X|)pt^{p-1}dt.$$

Hence, we obtained the desired identity.

1.2 Limit Theorems

1.2.1 Weak Law of Large Numbers

Theorem 1.1: Weak Law of Large Numbers (WLLN

Let X_1, \ldots, X_N be *i.i.d* random variables with mean μ . Consider the sum:

$$S_N = X_1 + \cdots + X_N$$

Then, the sample mean converges to μ in probability $(S_N/N \xrightarrow{p} \mu)$:

$$\lim_{N \to \infty} \mathbb{P}\Big(|S_N/N - \mu| > \epsilon\Big) = 0, \ \forall \epsilon > 0$$
 (16)

Proof (Weak Law of Large Numbers (WLLN)).

We split the proof into two sections corresponding to the assumptions of finite variance and non-finite variance.

1. Finite variance case: Suppose that $\operatorname{Var} X_i = \sigma^2 < \infty$ for all $1 \le i \le N$. Let $\bar{X} = S_N/N$. Then, \bar{X} is a random variable with the following mean and variance:

$$\mathbb{E}\bar{X} = \mu \quad and \quad \operatorname{Var}\bar{X} = \frac{\sigma^2}{N}.$$

Hence, by the Chebyshev's inequality, we have:

$$\mathbb{P}(|S_N/N - \mu| > \epsilon) = \mathbb{P}(|\bar{X} - \mu| > \epsilon) \leqslant \frac{\sigma^2}{N\epsilon^2}.$$

Therefore, we have:

$$\lim_{N \to \infty} \mathbb{P}\Big(|S_N/N - \mu| > \epsilon\Big) \leqslant \lim_{N \to \infty} \frac{\sigma^2}{N\epsilon^2} = 0.$$

Hence, we have $\lim_{N\to\infty} \mathbb{P}(|S_N/N - \mu| > \epsilon) = 0$ and we obtained (WLLN).

2. Non-finite variance case: In this case, we rely on the Levy Continuity Theorem (LCT), which relies on the convergence of the characteristic function. For $n \ge 1$, define the sequence of random variable $Y_n = S_n/n$. Hence, we have:

$$\varphi_{Y_n}(t) = \varphi_{S_n/n}(t)$$

$$= \varphi_{S_n}(t/n)$$

$$= \prod_{i=1}^n \varphi_{X_i}(t/n) = \left[\varphi_X(t/n)\right]^n,$$

Where $X = X_1 = \cdots = X_n$. By Taylor's expansion, we have:

$$\varphi_X(t/n) = 1 + \frac{it\mathbb{E}[X]}{n} + \mathcal{O}(1/n^2) = 1 + \frac{it\mu}{n} + \mathcal{O}(1/n^2).$$

Hence, we have:

$$\lim_{n\to\infty}\varphi_{Y_n}(t)=\lim_{n\to\infty}\left(1+\frac{it\mu}{n}+\mathcal{O}(1/n^2)\right)^n=e^{it\mu}.$$

Therefore, by (**LCT**), we have $Y_n \xrightarrow{p} \mu$.

Remark 1.1 (Taylor expansion of Moment Generating and Characteristic Functions). ______ Given a random variable X. For reference, the following are the Taylor expansions of the Moment Generating Function $M_X(t)$ and the Characteristic Function $\varphi_X(t)$:

$$M_X(t) = \mathbb{E}[e^{tX}] = 1 + \sum_{n=1}^{\infty} \frac{t^n}{n!} \mathbb{E}[X^n],$$

$$\varphi_X(t) = \mathbb{E}[e^{itX}] = 1 + \sum_{n=1}^{\infty} \frac{(it)^n}{n!} \mathbb{E}[X^n].$$
(17)

For the sake of my laziness, here are the Taylor expansion for the first three terms of both the MGF and the CF:

$$M_X(t) = 1 + t\mathbb{E}[X] + \frac{t^2}{2}\mathbb{E}[X^2] + \mathcal{O}(t^3),$$

$$\varphi_X(t) = 1 + it\mathbb{E}[X] - \frac{t^2}{2}\mathbb{E}[X^2] + \mathcal{O}(t^3).$$
(18)

□.

Theorem 1.2: Levy Continuity Theorem

Let X_1, X_2, \ldots be *i.i.d* random variables. Then:

$$\forall t \in \mathbb{R} : \lim_{n \to \infty} \varphi_{X_n}(t) = \varphi_X(t) \iff X_n \stackrel{d}{\to} X, \tag{19}$$

for some random variable X. In a special case where X=c for some $c\in\mathbb{R}$, we have:

$$\forall t \in \mathbb{R} : \lim_{n \to \infty} \varphi_{X_n}(t) = e^{itc} \iff X_n \xrightarrow{p} c.$$
 (20)

Proof (Levy Continuity Theorem (**LCT**)).

The proof for (LCT) can be found in Gut 2004, Section 9.1, Theorem 9.1 and Collorary 9.1 $\,$ $\,$

1.2.2 Strong Law of Large Numbers

Theorem 1.3: Strong Law of Large Numbers

Let X_1, \ldots, X_N be *i.i.d* random variables with mean $\mu < \infty$. Consider the sum:

$$S_N = X_1 + \cdots + X_N$$

Then, the sample mean converges to μ almost surely $(S_N/N \xrightarrow{a.s} \mu)$:

$$\mathbb{P}\left(\limsup_{N\to\infty}|S_N/N-\mu|>\epsilon\right)=0,\ \forall\epsilon>0$$
(21)

Proof (Strong Law of Large Numbers (SLLN)).

For the sake of simplicity, we will present the proof for (SLLN) with an additional assumption that $\mathbb{E}[|X_n|^4] < \infty$, $\forall n \geq 1$. The proof for the general case of (SLLN) (also called the Kolmogorov Strong Law) can be found in Gut 2004, Section 6, Theorem 6.1. For convenience, we assume the following:

- 1. $\mathbb{E}[|X_n|^4] = K < \infty$.
- 2. $\mathbb{E}[X_n] = 0$. For non-zero mean case, we can set $Y_n = X_n \mu$ and repeat the same arguments made below.

We aim to prove that $\mathbb{P}\Big(\limsup_{N\to\infty}|S_N/N|>\epsilon\Big)=0$ for any $\epsilon>0$. Firstly, use the Multinomial formula to expand $\mathbb{E}[S_n]$. The expansion will contain the terms in the following forms:

$$X_i^2, X_i^3 X_i, X_i^2 X_i^2, X_i^2 X_i X_i X_k, X_i X_i X_k X_\ell$$

where i, j, k, ℓ are distinct indices. By independence, we have:

$$\mathbb{E}[X_i^3 X_i] = \mathbb{E}[X_i^2 X_i X_k] = \mathbb{E}[X_i X_l X_k X_\ell] = 0.$$

As a result, we have the following remaining terms by the Multinomial formula:

$$\mathbb{E}[S_n^4] = \sum_{i=1}^n \mathbb{E}[X_i^4] + \binom{4}{2} \sum_{1 \le i < j \le n} \mathbb{E}[X_i^2 X_j^2]$$

$$= \sum_{i=1}^n \mathbb{E}[X_i^4] + 6 \sum_{1 \le i < j \le n} \mathbb{E}[X_i^2 X_j^2]$$

$$= nK + 3n(n-1)\mathbb{E}[X_i^2 X_j^2].$$

By independence, we have $\mathbb{E}[X_i^2 X_j^2] = \mathbb{E}[X_i^2] \mathbb{E}[X_j^2]$ and for any $1 \le i \le n$. Furthermore, we have $\mathbb{E}[X_i^2] = \text{Var}(X_i) + \mu^2 = \sigma^2 + \mu^2$. Therefore:

$$\mathbb{E}[S_n^4] = nK + 3n(n-1)(\sigma^2 + \mu^2) < nK + 3n^2(\sigma^2 + \mu^2).$$

Applying Markov's Inequality with the fourth moment, we have:

$$\begin{split} \mathbb{P}(|S_n/n| \geqslant \epsilon) &= \mathbb{P}(|S_n| \geqslant n\epsilon) \\ &\leqslant \frac{\mathbb{E}[S_n^4]}{n^4 \epsilon^4} \\ &< \frac{K}{n^3 \epsilon^4} + \frac{3(\sigma^2 + \mu^2)}{n^2}. \end{split}$$

Therefore, we have:

$$\sum_{n=1}^{\infty} \mathbb{P}(|S_n/n| \ge \epsilon) < \frac{K}{\epsilon^4} \sum_{n=1}^{\infty} n^{-3} + 3(\sigma^2 + \mu^2) \sum_{n=1}^{\infty} n^{-2} < \infty$$
 (22)

Finally, by the Borel-Cantelli Lemma (BCL), we have:

$$\mathbb{P}\left(\limsup_{n\to\infty}|S_n/n|\geqslant\epsilon\right)=0,\quad\forall\epsilon>0.$$

□.

Theorem 1.4: Borel-Cantelli Lemma

1. First Borel-Cantelli Lemma: Given a probability space $(X, \mathcal{S}, \mathbb{P})$ and a sequence $\{A_n\}_{n=1}^{\infty} \subset \mathcal{S}$. If $\sum_{n=1}^{\infty} \mathbb{P}(A_n) < \infty$, we have:

$$\mathbb{P}\left(\limsup_{n\to\infty} A_n\right) = 0. \tag{23}$$

2. Second Borel-Cantelli Lemma: On the other hand, if $\sum_{n=1}^{\infty} \mathbb{P}(E_n) = \infty$, we have:

$$\mathbb{P}\left(\limsup_{n\to\infty} A_n\right) = 1. \tag{24}$$

Proof (Borel-Cantelli Lemma (BCL)).

We focus on proving the first Borel-Cantelli lemma. We define another sequence of S-measurable sets $\{B_n\}_{n=1}^{\infty}$ such that:

$$B_n = \bigcup_{k=n}^{\infty} A_n.$$

Hence, we have $B_{\ell+1} \subset B_{\ell}$ for every $\ell \geqslant 1$. In other words, B_n is a decreasing sequence of S-measurable sets. By continuity of measure, we have:

$$\mathbb{P}\left(\lim_{n\to\infty} B_n\right) = \lim_{n\to\infty} \mathbb{P}(B_n)$$

$$= \lim_{n\to\infty} \sum_{k=n}^{\infty} \mathbb{P}(A_n) \quad (By \ additivity)$$

$$= \sum_{i=1}^{\infty} \mathbb{P}(A_i) - \lim_{n\to\infty} \sum_{k=1}^{n} \mathbb{P}(A_n)$$

$$= 0.$$

Furthermore, we have:

$$\mathbb{P}\Big(\lim_{n\to\infty}B_n\Big)=\mathbb{P}\bigg(\lim_{n\to\infty}\bigcup_{k=n}^{\infty}\bigg)=\mathbb{P}\bigg(\bigcap_{n=1}^{\infty}\bigcup_{k=n}^{\infty}A_n\bigg)=\mathbb{P}\bigg(\limsup_{n\to\infty}A_n\bigg).$$

Hence proved the first Borel-Cantelli Lemma. To prove the second Borel-Cantelli Lemma, we prove the following:

$$1 - \mathbb{P}\left(\limsup_{n \to \infty} A_n\right) = \mathbb{P}\left(\left\{\limsup_{n \to \infty} A_n\right\}^c\right)$$
$$= \mathbb{P}\left(\liminf_{n \to \infty} A_n^c\right) = 0.$$

1.2.3 Uniform Law of Large Numbers

The Uniform Law of Large Numbers (**ULLN**) provides a convergence result for collection of estimators where the convergence is uniform in the parameters space.

Theorem 1.5: Uniform Law of Large Numbers

Let $\mathbf{X} = (X_1, \dots, X_n)$ be a random sample from a distribution $p(.; \boldsymbol{\theta})$ over \mathcal{X} that depends on the true parameters $\boldsymbol{\theta}$. Let Θ be the parameters space and $f: \Theta \times \mathcal{X} \to \mathbb{R}$ be a function that satisfies the following conditions:

- 1. Θ is compact.
- 2. $\mathbb{E}_{\boldsymbol{\theta}}[\sup_{\theta \in \Theta} |f(\theta, x)|] < \infty$.
- 3. $f(\theta, x)$ is continuous in θ for almost all $x \in \mathcal{X}$.

Then, we have:

$$\sup_{\theta \in \Theta} \left| \frac{1}{n} \sum_{i=1}^{n} f(X_i, \theta) - \mathbb{E}_{\theta} [f(X, \theta)] \right| \xrightarrow{p} 0.$$
 (25)

Proof (Theorem 1.5).

I am too lazy to include the proof. Hence, a nice proof is provided in Ferguson 1996, Theorem 16, Page 111. The (ULLN) will be used later to prove the (strong) consistency of the Maximum Likelihood Estimator.

1.2.4 Central Limit Theorem

Theorem 1.6: Central Limit Theorem

Let $X_1, ... X_n$ be a sequence of *i.i.d* random variables with expected value μ and finite variance σ^2 . Then, we have:

$$\frac{\bar{X}_n - \mu}{\sigma/\sqrt{n}} \xrightarrow{d} \mathcal{N}(0, 1) \quad as \quad n \to \infty, \tag{26}$$

where $\bar{X}_n = S_n/n$ and $\mathcal{N}(0,1)$ is the standard normal distribution.

Proof (Central Limit Theorem (CLT)).

We prove this via the Characteristic Function. Let $\bar{Z}_n = \frac{\bar{X}_n - \mu}{\sigma/\sqrt{n}}$, notice that:

$$\bar{Z}_n = \frac{\bar{X}_n - \mu}{\sigma/\sqrt{n}} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{X_i - \mu}{\sigma},$$

Let $Z_i = X_i - \mu$ for $1 \le i \le n$ and suppose $Z = Z_1 = \cdots = Z_n$, we have:

$$\varphi_{\bar{Z}_n}(t) = \varphi_{\sum_{i=1}^n Z_i} \left(\frac{t}{\sqrt{n}} \right) = \left[\varphi_Z \left(\frac{t}{\sqrt{n}} \right) \right]^n$$

$$= \left[1 + \frac{it \mathbb{E}[Z]}{\sqrt{n}} - \frac{t^2}{2n} \mathbb{E}[Z^2] + \mathcal{O}(1/n) \right]^n \quad (Taylor's Expansion)$$

$$= \left[1 - \frac{t^2}{2n} + \mathcal{O}(1/n) \right]^n.$$

The final equality comes from the fact that $\mathbb{E}[Z] = 0$ and $\mathbb{E}[Z^2] = \mathbb{E}[Z]^2 + \text{Var}(Z) = 1$. Finally, we have:

$$\lim_{n\to\infty} \varphi_{\bar{Z}_n}(t) = \lim_{n\to\infty} \left[1 - \frac{t^2}{2n} + \mathcal{O}(1/n) \right]^n = e^{-t^2/2}.$$

Since $e^{-t^2/2}$ is the Characteristic Function of the standard normal distribution, by (LCT), we have $\bar{Z}_n \xrightarrow{d} \mathcal{N}(0,1)$.

1.3 Convergence of Random Variables

In this section, we revise the modes of convergence in random variables.

1.3.1 Convergence in Distribution

Definition 1.2 (Convergence in Distribution). Given a sequence of real-valued random variables X_1, X_2, \ldots with CDFs F_1, F_2, \ldots . We say that the sequence converges in distribution to a random variable X with CDF F, denoted $X_n \xrightarrow{d} X$ if:

$$\lim_{n \to \infty} F_n(x) = F(x),\tag{27}$$

for all $x \in \mathbb{R}$ at which F is continuous. Convergence in distribution can also be referred to as weak convergence in measure theory.

1.3.2 Convergence in Probability

Definition 1.3 (Convergence in Probability). Given a sequence of real-valued random variables X_1, X_2, \ldots We say that the sequence converges in probability to a random variable X, denoted $X_n \stackrel{p}{\to} X$ if:

$$\lim_{n \to \infty} \mathbb{P}\Big(|X_n - X| \ge \epsilon\Big) = 0, \quad \forall \epsilon > 0.$$
 (28)

We also refer to convergence in probability as convergence in measure in measure theory.

Proposition 1.1: $X_n \stackrel{p}{\rightarrow} X \implies X_n \stackrel{d}{\rightarrow} X$

Let X and the sequence X_1, X_2, \ldots be real-valued random variables. If $X_n \xrightarrow{p} X$, then $X_n \xrightarrow{d} X$.

Proof (Proposition 1.1).

We first prove the following claim: Let X, Y be random variables, $a \in \mathbb{R}$ and $\epsilon > 0$, the inequality $\mathbb{P}(Y \leq a) \leq \mathbb{P}(X \leq a + \epsilon) + \mathbb{P}(|Y - X| \geq \epsilon)$ holds. We have:

$$\begin{split} \mathbb{P}(Y \leqslant a) &= \mathbb{P}(Y \leqslant a, X \leqslant a + \epsilon) + \mathbb{P}(Y \leqslant a, X \geqslant a + \epsilon) \\ &\leqslant \mathbb{P}(X \leqslant a + \epsilon) + \mathbb{P}(Y - X \leqslant a - X, a - X \leqslant -\epsilon) \\ &\leqslant \mathbb{P}(X \leqslant a + \epsilon) + \mathbb{P}(Y - X \leqslant -\epsilon) \\ &\leqslant \mathbb{P}(X \leqslant a + \epsilon) + \mathbb{P}(Y - X \leqslant -\epsilon) + \mathbb{P}(Y - X \geqslant \epsilon) \\ &= \mathbb{P}(X \leqslant a + \epsilon) + \mathbb{P}(|Y - X| \geqslant \epsilon). \end{split}$$

Using the above inequality, we have:

$$\mathbb{P}(X \leqslant a - \epsilon) - \mathbb{P}(|X_n - X| \geqslant \epsilon) \leqslant \mathbb{P}(X_n \leqslant a) \leqslant \mathbb{P}(X \leqslant a + \epsilon) + \mathbb{P}(|X_n - X| \geqslant \epsilon).$$

Taking limits as $n \to \infty$ from both sides, we have:

$$F_X(a-\epsilon) \leqslant \lim_{n \to \infty} F_{X_n}(a) \leqslant F_X(a+\epsilon).$$

Taking $\epsilon \to 0^+$, we have $\lim_{n\to\infty} F_{X_n}(a) = F_X(a)$.

Proposition 1.2: $X_n \xrightarrow{d} c \iff X_n \xrightarrow{p} c$

Let $c \in \mathbb{R}$ be a constant and X_1, X_2, \ldots be a sequence of real-valued random variables. Then, $X_n \xrightarrow{d} c \iff X_n \xrightarrow{p} c$.

Proof (Proposition 1.2, Pishro-Nik 2014).

Since $X_n \xrightarrow{d} c$, we immediately have the following:

$$\lim_{n \to \infty} F_{X_n}(c - \epsilon) = 0,$$

$$\lim_{n \to \infty} F_{X_n}(c + \epsilon/2) = 1.$$

Then, for any $\epsilon > 0$, we have:

$$\lim_{n \to \infty} (|X_n - c| \ge \epsilon) = \lim_{n \to \infty} \mathbb{P} \Big[\mathbb{P}(X_n \le c - \epsilon) + \mathbb{P}(X_n \ge c + \epsilon) \Big]$$

$$= \lim_{n \to \infty} F_{X_n}(c - \epsilon) + \lim_{n \to \infty} \mathbb{P}(X_n \ge c + \epsilon)$$

$$\le \lim_{n \to \infty} \mathbb{P}(X_n \ge c + \epsilon/2)$$

$$= 1 - \lim_{n \to \infty} F_{X_n}(c + \epsilon/2)$$

$$= 1 - 0$$

From the above, we have $\lim_{n\to\infty} \mathbb{P}(|X_n-c| \ge \epsilon) = 0$ and $X_n \xrightarrow{p} c$.

1.3.3 Convergence in L^p norm

Definition 1.4 (Convergence in L^p norm). Given a sequence of random variables X_1, X_2, \ldots and a real number $p \in [1, \infty)$. We say that the sequence converges in L^p norm to a random variable X, denoted as $X_n \xrightarrow{L^p} X$ if:

$$\lim_{n \to \infty} \mathbb{E}|X_n - X|^p = 0. \tag{29}$$

ο.

□.

Proposition 1.3: $X_n \xrightarrow{L^p} X \implies X_n \xrightarrow{p} X$

Let $p \geqslant 1$ and X_1, X_2, \ldots be a sequence of real-valued random variables. Let X be a random variable, then, $X_n \xrightarrow{L^p} X \implies X_n \xrightarrow{p} X$.

Proof (Proposition 1.3).

Let $\epsilon > 0$, we have:

$$\mathbb{P}(|X_n - X| \ge \epsilon) = \mathbb{P}(|X_n - X|^p \ge e^p) \quad (p \ge 1)$$

$$\le \frac{\mathbb{E}|X_n - X|^p}{\epsilon^p}. \quad (Markov's Inequality)$$

Taking the limits from both sides, we have $\lim_{n\to\infty} \mathbb{P}(|X_n - X| \ge \epsilon) = 0$ and $X_n \xrightarrow{p} X$.

1.3.4 Almost-sure Convergence

Definition 1.5 (Convergence almost-surely).

Let X_1, X_2, \ldots be a sequence of real-valued random variables that map from a sample space Ω . Let X also be a real-valued random variable. We say that X_n converges almost surely to X, denoted as $X_n \xrightarrow{a.s} X$, if:

$$\mathbb{P}\Big(\limsup_{n\to\infty} E_n\Big) = 0 \quad \text{where} \quad E_n = \Big\{\omega \in \Omega : |X_n(\omega) - X(\omega)| \geqslant \epsilon\Big\}.$$

Remark 1.2 (Consequence of (BCL)).

$$\sum_{n=1}^{\infty} \mathbb{P}(E_n) < \infty \implies X_n \xrightarrow{a.s} X. \tag{30}$$

□.

Proposition 1.4: $X_n \xrightarrow{a.s} X \implies X_n \xrightarrow{p} X$

Let X_1, X_2, \ldots be a sequence of real-valued random variables and also let X be a real valued random variables. If $X_n \xrightarrow{a.s} X$ then $X_n \xrightarrow{p} X$.

Proof (Proposition 1.4).

Let $f_n: \Omega \to \mathbb{R}_+$ be a sequence of nonnegative Borel-measurable functions such that $f_n(\omega) = |X_n(\omega) - X(\omega)|$. By Fatou's Lemma (reverse), we have:

$$\underbrace{\mathbb{P}\Big(\limsup_{n\to\infty}\{\omega\in\Omega:|X_n(\omega)-X(\omega)|\geqslant\epsilon\}\Big)}_{=0} = \int f_n d\mathbb{P}$$

$$\geqslant \limsup_{n\to\infty}\mathbb{P}(|X_n-X|\geqslant\epsilon)$$

$$\geqslant \lim_{n\to\infty}\mathbb{P}(|X_n-X|\geqslant\epsilon).$$

Hence, we have $\lim_{n\to\infty} \mathbb{P}(|X_n - X| \ge \epsilon) = 0$ and $X_n \xrightarrow{p} X$.

Theorem 1.7: Continuous Mapping Theorem (CMT

Let $f : \mathbb{R} \to \mathbb{R}$ be a <u>continuous</u> function and X_1, X_2, \ldots be a sequence of real-valued random variables. Then, the following statements hold true:

1.
$$X_n \xrightarrow{d} X \implies f(X_n) \xrightarrow{d} f(X)$$
.

2.
$$X_n \xrightarrow{p} X \implies f(X_n) \xrightarrow{p} f(X)$$
.

3.
$$X_n \xrightarrow{a.s} X \implies f(X_n) \xrightarrow{a.s} f(X)$$
.

Proof (Continuous Mapping Theorem (CMT)).

Since almost-sure convergence implies the other two modes of convergence, we only have to handle the almost-sure convergence case. Since h is continuous, for any $\omega \in \Omega$ such that $X_n(\omega) \to X(\omega)$, we have $f(X_n(\omega)) \to f(X(\omega))$. Therefore, we have:

$$\Big\{\omega\in\Omega:X_n(\omega)\to X(\omega)\Big\}\subseteq \Big\{\omega\in\Omega:f(X_n(\omega))\to f(X(\omega))\Big\}.$$

Therefore, we have:

$$\mathbb{P}\Big(\limsup_{n\to\infty}\Big\{\omega\in\Omega:|f(X_n(\omega))-f(X(\omega))|\leqslant\epsilon\Big\}\Big)$$

$$\geqslant \mathbb{P}\Big(\limsup_{n\to\infty}\Big\{\omega\in\Omega:|X_n(\omega)-X(\omega)|\leqslant\epsilon\Big\}\Big)=1,$$

□.

for all $\epsilon > 0$. Therefore, we have $f(X_n) \xrightarrow{a.s} f(X)$.

2 Statistical Inference

2.1 Sufficiency & Likelihood Principles

2.1.1 Sufficiency

Definition 2.1 (Sufficient Statistics). Let $\mathbf{X} = (X_1, \dots, X_n) \sim p(.; \boldsymbol{\theta})$ be a random sample drawn i.i.d from a distribution with param-

Let $\mathbf{X} = (X_1, \dots, X_n) \sim p(.; \boldsymbol{\theta})$ be a random sample drawn i.i.d from a distribution with parameters $\boldsymbol{\theta}$. Let $\mathbf{U} = T(\mathbf{X})$ be a statistic, then it is called a <u>sufficient statistic</u> if the conditional distribution $p_{\mathbf{X}|\mathbf{U}}$ does not depend on $\boldsymbol{\theta}$.

Example 2.1 (Bernoulli random variables). _

Let $\mathbf{X} = (X_1, \dots, X_n) \sim \text{Bernoulli}(\theta)$ be a random sample from the Bernoulli distribution. Let $\mathbf{U} = \frac{1}{n} \sum_{i=1}^{n} X_i$, then \mathbf{U} is a sufficient statistic of θ . To illustrate this, suppose that $\mathbf{x} = (x_1, \dots, x_n)$ is an observation of the random sample \mathbf{X} and $\mathbf{u} = \frac{1}{n} \sum_{i=1}^{n} x_i$. We have:

$$\mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}) = \frac{\mathbb{P}(\mathbf{X} = \mathbf{x}, \mathbf{U} = \mathbf{u})}{\mathbb{P}(\mathbf{U} = \mathbf{u})} \\
= \frac{\mathbb{P}(X_1 = x_1, \dots, X_n = x_n, \sum_{i=1}^n X_i = \sum_{i=1}^n x_i)}{\mathbb{P}(\sum_{i=1}^n X_i = \sum_{i=1}^n x_i)} \\
= \frac{\mathbb{P}(X_1 = x_1, \dots, X_n = x_n)}{\mathbb{P}(\sum_{i=1}^n X_i = \sum_{i=1}^n x_i)} \\
= \frac{\theta^{\sum_{i=1}^n x_i} (1 - \theta)^{n - \sum_{i=1}^n x_i}}{\mathbb{P}(\sum_{i=1}^n X_i = \sum_{i=1}^n x_i)}.$$

Now, setting $k = \sum_{i=1}^{n} x_i$, The denominator is basically the probability that the Bernoulli variables sums up to k. Hence, we can calculate the denominator as follows:

$$\mathbb{P}\left(\sum_{i=1}^{n} X_i = k\right) = \binom{n}{k} \theta^k (1-\theta)^{n-k}.$$

Therefore, we have:

$$\mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}) = \frac{\theta^k (1 - \theta)^{n - k}}{\binom{n}{k} \theta^k (1 - \theta)^{n - k}} = \frac{1}{\binom{n}{k}}.$$

Therefore, the conditional distribution does not depend on θ and \mathbf{U} is a sufficient statistic.

Definition 2.2 (Sufficiency Principle).

If $\mathbf{U} = T(\mathbf{X})$ is a sufficient statistic for $\boldsymbol{\theta}$, then any inference about $\boldsymbol{\theta}$ should only depend on the sample \mathbf{X} through \mathbf{U} . In other words, if we estimate $\boldsymbol{\theta}$ using an estimator $\hat{\boldsymbol{\theta}}$, only \mathbf{U} shows up in the formula of $\hat{\boldsymbol{\theta}}$, not the sample \mathbf{X} itself. We will see why this is the case in the Factorisation Theorem (FacT), which states that we can factorise the density function into a function of $\mathbf{U}, \boldsymbol{\theta}$ and a function of the observations \mathbf{x} and thus, the inference about $\boldsymbol{\theta}$ is independent of the observations \mathbf{x} .

Theorem 2.1: Factorisation Theorem

Let $\mathbf{X} = (X_1, \dots, X_n)$ be a random sample with joint density function $p(\mathbf{x}; \boldsymbol{\theta})$ over \mathcal{X}^n . The statistic $\mathbf{U} = T(\mathbf{X})$ is sufficient for the parameters $\boldsymbol{\theta}$ if and only if we can find functions h, g such that:

$$p(\mathbf{x}; \boldsymbol{\theta}) = g(T(\mathbf{x}), \boldsymbol{\theta})h(\mathbf{x}),$$

for all $\mathbf{x} \in \mathbb{R}^n$ and $\boldsymbol{\theta} \in \Theta$.

Proof (Factorisation Theorem (FacT)).

We have to conduct the proof in both directions.

• $T(\mathbf{X})$ is sufficient \Longrightarrow Factorisation exists: Let $\mathbf{U} = T(\mathbf{X})$ be a sufficient statistics and $\mathbf{u} = T(\mathbf{x})$ be the statistics evaluated on the observations \mathbf{x} . Then, we have:

$$p(\mathbf{x}; \boldsymbol{\theta}) = \mathbb{P}(\mathbf{X} = \mathbf{x}; \boldsymbol{\theta})$$
$$= \mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}; \boldsymbol{\theta}) \mathbb{P}(\mathbf{U} = \mathbf{u}; \boldsymbol{\theta}).$$

Since $\mathbf{U} = T(\mathbf{X})$ is a sufficient statistics, $\mathbb{P}(=\mathbf{x}|\mathbf{U}=\mathbf{u};\boldsymbol{\theta})$ does not depend on $\boldsymbol{\theta}$. Hence, we denote $h(\mathbf{x}) = \mathbb{P}(\mathbf{X} = \mathbf{x}|\mathbf{U} = \mathbf{u};\boldsymbol{\theta})$. Furthermore, $\mathbb{P}(\mathbf{U} = \mathbf{u};\boldsymbol{\theta})$ is a function of \mathbf{u} and $\boldsymbol{\theta}$. We denote this function as $g(\mathbf{u},\boldsymbol{\theta})$ and conclude that the factorisation $p(\mathbf{x};\boldsymbol{\theta}) = h(\mathbf{x})g(T(\mathbf{x}),\boldsymbol{\theta})$ indeed exists.

• Factorisation exists \implies $T(\mathbf{X})$ is sufficient: Suppose that there exists g, h such that $p(\mathbf{x}; \boldsymbol{\theta}) = g(T(\mathbf{x}), \boldsymbol{\theta})h(\mathbf{x})$. We then have:

$$\mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}; \boldsymbol{\theta}) = \frac{p(\mathbf{x}; \boldsymbol{\theta})}{\mathbb{P}(\mathbf{U} = \mathbf{u}; \boldsymbol{\theta})} = \frac{g(\mathbf{u}, \boldsymbol{\theta}) h(\mathbf{x})}{\mathbb{P}(\mathbf{U} = \mathbf{u}; \boldsymbol{\theta})}.$$

We denote $A_{\mathbf{u}} = \left\{ \tilde{\mathbf{x}} \in \mathcal{X}^n : T(\tilde{\mathbf{x}}) = \mathbf{u} \right\}$. We have:

$$\begin{split} \mathbb{P}(\mathbf{U} = \mathbf{u}; \boldsymbol{\theta}) &= \sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} \mathbb{P}(\mathbf{X} = \tilde{\mathbf{x}}) \\ &= \sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} p(\tilde{\mathbf{x}}; \boldsymbol{\theta}) = \sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} g(T(\tilde{\mathbf{x}}), \boldsymbol{\theta}) h(\tilde{\mathbf{x}}) \\ &= g(\mathbf{u}, \boldsymbol{\theta}) \sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} h(\tilde{\mathbf{x}}). \end{split}$$

From the above, we have:

$$\mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}; \boldsymbol{\theta}) = \frac{h(\mathbf{x})}{\sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} h(\tilde{\mathbf{x}})},$$

and the above expression does not depend on θ . Hence, $T(\mathbf{X})$ is a sufficient statistics.

2.1.2 Likelihood

Definition 2.3 (Likelihood Function).

Let $\mathbf{X} = (X_1, \dots, X_n)$ be a random sample from a distribution $p(.|\theta)$ that depends on parameters $\theta \in \Theta$. Let $\mathbf{x} = (x_1, \dots, x_n)$ be an observation of the random sample \mathbf{X} . Then, the likelihood function $L(\theta; \mathbf{x})$ is defined as follows:

$$L(\theta; \mathbf{x}) = \prod_{i=1}^{n} p(x_i; \theta), \quad \theta \in \Theta.$$
 (31)

In some cases, we also use the log-likelihood function:

$$\ell(\theta; \mathbf{x}) = \log L(\theta; \mathbf{x}) = \sum_{i=1}^{n} \log p(x_i; \theta), \quad \theta \in \Theta.$$
 (32)

Essentially, $L(\theta; \mathbf{x})$ quantifies the likelihood that θ generates the observations \mathbf{x} . In a way, it is the inverse of probability density (mass) functions, we can see the contrast as follows:

- Probability Density Function: The parameters are fixed but the observations are random.
- Likelihood Function: The observations are fixed but the parameters are variable.

Definition 2.4 (Maximum Likelihood Estimator). Given $\mathbf{X} = (X_1, \dots, X_n)$ be a random sample from a distribution $p(.;\theta)$ that depends on $\theta \in \Theta$ and $\mathbf{x} = (x_1, \dots, x_n)$ be an observation of \mathbf{X} . The <u>Maximum Likelihood Estimator</u> $\theta_{MLE} \in \Theta$ is the parameter that maximizes the likelihood function:

$$\theta_{MLE} = \arg\max_{\theta \in \Theta} L(\theta; \mathbf{x}). \tag{33}$$

In the subsequent propositions, we will discuss some of the key properties of MLE.

Proposition 2.1: Consistency of MLE

Let $\mathbf{X} = (X_1, \dots, X_n)$ be a random sample from a distribution $p(.; \boldsymbol{\theta})$ over \mathcal{X} dependent on a true set of parameters $\boldsymbol{\theta}$. Let Θ be the parameters space. Then, the Maximum Likelihood Estimator $\theta_{MLE} = \arg \max_{\boldsymbol{\theta} \in \Theta} L(\boldsymbol{\theta}; \mathbf{X})$, which is a random variable, is consistent, meaning $\theta_{MLE} \stackrel{p}{\to} \boldsymbol{\theta}$, provided that the following conditions are met:

- 1. $\theta \in \Theta$ and Θ is a compact space.
- 2. If $\theta_1 \neq \theta_2$ then $p(x; \theta_1) \neq p(x; \theta_2)$, $\forall x \in \mathcal{X}$.
- 3. $\log p(x; \theta)$ is continuous in θ for almost all $x \in \mathcal{X}$.
- 4. $\mathbb{E}_{\boldsymbol{\theta}}[\sup_{\theta \in \Theta} |\log(X; \theta)|] < \infty$.

Furthermore, we can also show that θ_{MLE} is asymptotically unbiased. In other words, $\lim_{n\to\infty} \mathbb{E}[\theta_{MLE}] = \theta$.

Proof (Proposition 2.1).

A proof for consistency of MLE can be found in "Chapter 36 Large sample estimation and hypothesis testing" 1994, Theorem 2.5. In this section, we briefly go through the proof again. $\ \, \Box$.

Proposition 2.2: Asymptotic Normality of MLE

Let $\mathbf{X} = (X_1, \dots, X_n)$ be a random sample from a distribution $p(.; \boldsymbol{\theta})$ dependent on a true set of parameters $\boldsymbol{\theta}$. Let Θ be the parameters space. Then, the Maximum Likelihood Estimator $\theta_{MLE} = \arg \max_{\theta \in \Theta} L(\theta; \mathbf{X})$ is asymptotically normal:

$$\frac{\theta_{MLE} - \boldsymbol{\theta}}{\sqrt{\operatorname{Var}(\theta_{MLE})/n}} \xrightarrow{d} \mathcal{N}(0, 1). \tag{34}$$

Proof (Proposition 2.2).

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- 2.2 Point Estimation
- 2.2.1 Bias, Variance, Consistency and MSE
- 2.2.2 Sufficient Statistics & Rao-Blackwell Theorem

Theorem 2.2: Rao-Blackwell Theorem (BB

2.2.3 Estimator Variance & Cramer-Rao Lower Bound

Definition 2.5 (Fisher Information).

Let $\mathbf{X} = (X_1, \dots, X_n) \sim p(.; \boldsymbol{\theta})$ be a random sample from a distribution parameterized by $\boldsymbol{\theta}$. The (total) Fisher Information about θ in the random sample \mathbf{X} is defined as follows:

$$\mathcal{I}_{\mathbf{X}}(\boldsymbol{\theta}) = \mathbb{E}_{\mathbf{X}} \left[\left(\frac{\partial}{\partial \theta} \log L(\theta; \mathbf{X}) \right)^{2} \middle| \boldsymbol{\theta} \right]. \tag{35}$$

The Fisher Information is the total information about θ contained in the sample X.

Theorem 2.3: Cramer-Rao Lower Bound (CRLB)

2.2.4 Maximum Likelihood Estimation (MLE)

A List of Definitions

1.	1 Definition (Random variable)
1.	P Definition (Convergence in Distribution)
1.	B Definition (Convergence in Probability)
1	$(Convergence\ in\ L^p\ norm)$
1.	5 Definition (Convergence almost-surely)
2.	
2.	
2.	B Definition (Likelihood Function)
2	Definition (Maximum Likelihood Estimator)
2.	
\mathbf{B}	Important Theorems
1.	Weak Law of Large Numbers (WLLN)
1.	
1.	
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1.	
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2.	
2.	
\mathbf{C}	Important Propositions
	•
1.	
1.	$Z : X_n \xrightarrow{d} c \iff X_n \xrightarrow{p} c \dots $
1.	T D
1	
2.	
2.	

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