

# High Dimensional Probability Notes

Nong Minh Hieu<sup>1</sup>

<sup>1</sup> School of Physical and Mathematical Sciences, Nanyang Technological University (NTU - Singapore)

## Contents

|             |   |           |
|-------------|---|-----------|
| <b>1</b>    | <b>Basic Distribution Theory</b>              | <b>2</b>  |
| 1.1         | Basic Inequalities . . . . .                  | 2         |
| 1.2         | Limit Theorems . . . . .                      | 4         |
| 1.2.1       | Weak Law of Large Numbers . . . . .           | 4         |
| 1.2.2       | Strong Law of Large Numbers . . . . .         | 6         |
| 1.2.3       | Uniform Law of Large Numbers . . . . .        | 8         |
| 1.2.4       | Central Limit Theorem . . . . .               | 10        |
| 1.3         | Convergence of Random Variables . . . . .     | 11        |
| 1.3.1       | Convergence in Distribution . . . . .         | 11        |
| 1.3.2       | Convergence in Probability . . . . .          | 14        |
| 1.3.3       | Convergence in $L^p$ norm . . . . .           | 15        |
| 1.3.4       | Almost-sure Convergence . . . . .             | 16        |
| <b>2</b>    | <b>Point Estimation</b>                       | <b>18</b> |
| 2.1         | Properties of Point Estimators . . . . .      | 18        |
| 2.1.1       | Sufficiency . . . . .                         | 18        |
| 2.1.2       | Bias and Efficiency . . . . .                 | 21        |
| 2.1.3       | Consistent Estimator . . . . .                | 21        |
| 2.2         | Important Results . . . . .                   | 21        |
| 2.2.1       | Maximum Likelihood Estimation (MLE) . . . . . | 21        |
| 2.2.2       | Rao-Blackwell Theorem . . . . .               | 24        |
| 2.2.3       | Cramer-Rao Lower Bound . . . . .              | 24        |
| <b>3</b>    | <b>Concentration Inequalities</b>             | <b>28</b> |
| 3.1         | Sub-Gaussian Distributions . . . . .          | 28        |
| <b>I</b>    | <b>. Appendix</b>                             | <b>33</b> |
| I.1         | Leibniz Differentiation Rule . . . . .        | 33        |
| <b>II</b>   | <b>. List of Definitions</b>                  | <b>35</b> |
| <b>III.</b> | <b>Important Theorems</b>                     | <b>35</b> |
| <b>IV .</b> | <b>Important Propositions</b>                 | <b>35</b> |
| <b>V</b>    | <b>. To-do List</b>                           | <b>36</b> |
| <b>VI .</b> | <b>References</b>                             | <b>37</b> |

# 1 Basic Distribution Theory

## 1.1 Basic Inequalities

First, we revisit the definition of a random variable as well as some basic inequalities that we learned in introductory statistics.

**Definition 1.1** (Random variable).

Let  $(\Omega, \Sigma, \mathbb{P})$  be a probability space. A random variable  $X$  is defined as a mapping from the sample space  $\Omega$  to  $\mathbb{R}$ :

$$X : \Omega \rightarrow \mathbb{R} \quad (1)$$

$\Sigma$  is the  $\sigma$ -algebra containing the possible events (collection of subsets of  $\Omega$ ) and  $\mathbb{P}$  is a probability measure that assigns events with probabilities:

$$\mathbb{P} : \Sigma \rightarrow [0, 1] \quad (2)$$

For a given probability space  $(\Omega, \Sigma, \mathbb{P})$  and a random variable  $X : \Omega \rightarrow \mathbb{R}$ , we will use the following basic notations throughout this note:

- $\|X\|_{L^p}$  - The  $p^{th}$  root of the  $p^{th}$  moment of the random variable  $X$ .

$$\|X\|_{L^p} = (\mathbb{E}|X|^p)^{1/p}, \quad p \in (0, \infty) \quad (3)$$

$$\|X\|_{L^\infty} = \text{ess sup } |X| \quad (4)$$

- $L^p(\Omega, \Sigma, \mathbb{P})$  - The space of random variables  $X$  satisfying:

$$L^p(\Omega, \Sigma, \mathbb{P}) = \left\{ X : \Omega \rightarrow \mathbb{R} \mid \|X\|_{L^p} < \infty \right\} \quad (5)$$

Some basic inequalities and identities:

- **1. Jensen's Inequality** - For a random variable  $X$  and a convex function  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ , we have:

$$\varphi(\mathbb{E}X) \leq \mathbb{E}\varphi(X) \quad (6)$$

- **2. Monotonicity of  $L^p$  norm** - For a random variable  $X$ :

$$\|X\|_{L^p} \leq \|X\|_{L^q}, \quad 0 \leq p \leq q \leq \infty. \quad (7)$$

- **3. Minkowski's Inequality** - For  $1 \leq p \leq \infty$  and two random variables  $X, Y$  in  $L^p(\Omega, \Sigma, \mathbb{P})$  space:

$$\|X + Y\|_{L^p} \leq \|X\|_{L^p} + \|Y\|_{L^p}. \quad (8)$$

- **4. Holder's Inequality** - For  $p, q \in [1, \infty]$  such that  $1/p + 1/q = 1$ . Then, for random variables  $X \in L^p(\Omega, \Sigma, \mathbb{P})$  and  $Y \in L^q(\Omega, \Sigma, \mathbb{P})$ , we have:

$$|\mathbb{E}XY| \leq \|X\|_{L^p} \cdot \|Y\|_{L^q}. \quad (9)$$

- **5. Markov's Inequality** - For a non-negative random variable  $X$  and  $t > 0$ , we have:

$$\mathbb{P}(X \geq t) \leq \frac{\mathbb{E}X}{t}. \quad (10)$$

We can also generalize Markov's Inequality for  $p^{th}$  moment:

$$\mathbb{P}(|X| \geq t) \leq \frac{\mathbb{E}[|X|^p]}{t^p}, \quad \forall t > 0, p \in [2, \infty). \quad (11)$$

- **6. Chebyshev's Inequality** - For a random variable  $X$  with mean  $\mu$  and variance  $\sigma^2$ . Then, for any  $t > 0$ , we have:

$$\mathbb{P}(|X - \mu| \geq t) \leq \frac{\sigma^2}{t^2}. \quad (12)$$

- **7. Integral Identity** - Let  $X$  be a non-negative random variable, we have:

$$\mathbb{E}X = \int_0^\infty \mathbb{P}(X > t)dt. \quad (13)$$

## Exercises

### Exercise 1.1.1: Generalized Integral Identity

Let  $X$  be a random variable (not necessarily non-negative). Prove the following identity:

$$\mathbb{E}X = \int_0^\infty \mathbb{P}(X > t)dt - \int_{-\infty}^0 \mathbb{P}(X < t)dt. \quad (14)$$

**Solution** (Exercise 1.1.1).

For  $x \in \mathbb{R}$ , using the basic integral identity, we have:

$$|x| = \int_0^\infty \mathbf{1}\{t < |x|\}dt$$

We consider the following cases:

- When  $x < 0 \implies x = -|x|$ :

$$x = - \int_0^\infty \mathbf{1}\{t < |x|\}dt = - \int_0^\infty \mathbf{1}\{t < -x\}dt = - \int_0^\infty \mathbf{1}\{-t > x\}dt = - \int_{-\infty}^0 \mathbf{1}\{t > x\}dt.$$

- When  $x \geq 0 \implies x = |x|$ :

$$x = \int_0^\infty \mathbf{1}\{t < |x|\}dt = \int_0^\infty \mathbf{1}\{t < x\}dt.$$

Therefore, for  $x \in \mathbb{R}$ , we can write:

$$x = \int_0^\infty \mathbf{1}\{t < x\}dt - \int_{-\infty}^0 \mathbf{1}\{t > x\}dt.$$

Therefore, for a random variable  $X$  not necessarily non-negative, we have:

$$\begin{aligned} \mathbb{E}X &= \mathbb{E} \left[ \int_0^\infty \mathbf{1}\{t < X\}dt - \int_{-\infty}^0 \mathbf{1}\{t > X\}dt \right] \\ &= \mathbb{E} \int_0^\infty \mathbf{1}\{t < X\}dt - \mathbb{E} \int_{-\infty}^0 \mathbf{1}\{t > X\}dt \\ &= \int_0^\infty \mathbb{E} \mathbf{1}\{t < X\}dt - \int_{-\infty}^0 \mathbb{E} \mathbf{1}\{t > X\}dt \\ &= \int_0^\infty \mathbb{P}(t < X)dt - \int_{-\infty}^0 \mathbb{P}(t > X)dt. \end{aligned}$$

□.

**Exercise 1.1.2:  $p^{th}$ -moments via tails**

Let  $X$  be a random variable and  $p \in (0, \infty)$ . Show that:

$$\mathbb{E}|X|^p = \int_0^\infty pt^{p-1}\mathbb{P}(|X| > t)dt. \quad (15)$$

**Solution** (Exercise 1.1.2). \_\_\_\_\_

Let  $X$  be a random variable that is not necessarily non-negative. Using the integral identity, we have:

$$\mathbb{E}|X|^p = \int_0^\infty \mathbb{P}(u < |X|^p)du.$$

Let  $t^p = u \implies pt^{p-1}dt = du$ . Since we integrate  $u$  from  $0 \rightarrow \infty$ , we also integrate  $t$  from  $0 \rightarrow \infty$  when changing the variables. Hence, we have:

$$\mathbb{E}|X|^p = \int_0^\infty \mathbb{P}(t^p < |X|^p)pt^{p-1}dt = \int_0^\infty \mathbb{P}(t < |X|)pt^{p-1}dt.$$

Hence, we obtained the desired identity.  $\square$ .

**1.2 Limit Theorems****1.2.1 Weak Law of Large Numbers****Theorem 1.1: Weak Law of Large Numbers (WLLN)**

Let  $X_1, \dots, X_N$  be *i.i.d* random variables with mean  $\mu$ . Consider the sum:

$$S_N = X_1 + \dots + X_N$$

Then, the sample mean **converges to  $\mu$  in probability** ( $S_N/N \xrightarrow{p} \mu$ ):

$$\lim_{N \rightarrow \infty} \mathbb{P}\left(|S_N/N - \mu| > \epsilon\right) = 0, \quad \forall \epsilon > 0 \quad (16)$$

**Proof** (Weak Law of Large Numbers (WLLN)). \_\_\_\_\_

We split the proof into two sections corresponding to the assumptions of finite variance and non-finite variance.

1. **Finite variance case:** Suppose that  $\text{Var}X_i = \sigma^2 < \infty$  for all  $1 \leq i \leq N$ . Let  $\bar{X} = S_N/N$ . Then,  $\bar{X}$  is a random variable with the following mean and variance:

$$\mathbb{E}\bar{X} = \mu \quad \text{and} \quad \text{Var}\bar{X} = \frac{\sigma^2}{N}.$$

Hence, by the Chebyshev's inequality, we have:

$$\mathbb{P}\left(|S_N/N - \mu| > \epsilon\right) = \mathbb{P}\left(|\bar{X} - \mu| > \epsilon\right) \leq \frac{\sigma^2}{N\epsilon^2}.$$

Therefore, we have:

$$\lim_{N \rightarrow \infty} \mathbb{P}\left(|S_N/N - \mu| > \epsilon\right) \leq \lim_{N \rightarrow \infty} \frac{\sigma^2}{N\epsilon^2} = 0.$$

Hence, we have  $\lim_{N \rightarrow \infty} \mathbb{P}\left(|S_N/N - \mu| > \epsilon\right) = 0$  and we obtained **(WLLN)**.

2. **Non-finite variance case:** In this case, we rely on the Levy Continuity Theorem (**LCT**), which relies on the convergence of the characteristic function. For  $n \geq 1$ , define the sequence of random variable  $Y_n = S_n/n$ . Hence, we have:

$$\begin{aligned}\varphi_{Y_n}(t) &= \varphi_{S_n/n}(t) \\ &= \varphi_{S_n}(t/n) \\ &= \prod_{i=1}^n \varphi_{X_i}(t/n) = \left[ \varphi_X(t/n) \right]^n,\end{aligned}$$

Where  $X = X_1 = \dots = X_n$ . By Taylor's expansion, we have:

$$\varphi_X(t/n) = 1 + \frac{it\mathbb{E}[X]}{n} + \mathcal{O}(1/n^2) = 1 + \frac{it\mu}{n} + \mathcal{O}(1/n^2).$$

Hence, we have:

$$\lim_{n \rightarrow \infty} \varphi_{Y_n}(t) = \lim_{n \rightarrow \infty} \left( 1 + \frac{it\mu}{n} + \mathcal{O}(1/n^2) \right)^n = e^{it\mu}.$$

Therefore, by (**LCT**), we have  $Y_n \xrightarrow{p} \mu$ .

**Remark 1.1** (Taylor expansion of Moment Generating and Characteristic Functions). \_\_\_\_\_  
Given a random variable  $X$ . For reference, the following are the Taylor expansions of the Moment Generating Function  $M_X(t)$  and the Characteristic Function  $\varphi_X(t)$ :

$$\begin{aligned}M_X(t) &= \mathbb{E}[e^{tX}] = 1 + \sum_{n=1}^{\infty} \frac{t^n}{n!} \mathbb{E}[X^n], \\ \varphi_X(t) &= \mathbb{E}[e^{itX}] = 1 + \sum_{n=1}^{\infty} \frac{(it)^n}{n!} \mathbb{E}[X^n].\end{aligned}\tag{17}$$

For the sake of my laziness, here are the Taylor expansion for the first three terms of both the MGF and the CF:

$$\begin{aligned}M_X(t) &= 1 + t\mathbb{E}[X] + \frac{t^2}{2}\mathbb{E}[X^2] + \mathcal{O}(t^3), \\ \varphi_X(t) &= 1 + it\mathbb{E}[X] - \frac{t^2}{2}\mathbb{E}[X^2] + \mathcal{O}(t^3).\end{aligned}\tag{18}$$

□.

### Theorem 1.2: Levy Continuity Theorem (**LCT**)

Let  $X_1, X_2, \dots$  be *i.i.d* random variables. Then:

$$\forall t \in \mathbb{R} : \lim_{n \rightarrow \infty} \varphi_{X_n}(t) = \varphi_X(t) \iff X_n \xrightarrow{d} X,\tag{19}$$

for some random variable  $X$ . In a special case where  $X = c$  for some  $c \in \mathbb{R}$ , we have:

$$\forall t \in \mathbb{R} : \lim_{n \rightarrow \infty} \varphi_{X_n}(t) = e^{itc} \iff X_n \xrightarrow{p} c.\tag{20}$$

**Proof** (Levy Continuity Theorem (**LCT**)). \_\_\_\_\_  
The proof for (**LCT**) can be found in Gut 2004, Section 9.1, Theorem 9.1 and Corollary 9.1 □.

### 1.2.2 Strong Law of Large Numbers

#### Theorem 1.3: Strong Law of Large Numbers (**SLLN**)

Let  $X_1, \dots, X_N$  be *i.i.d* random variables with mean  $\mu < \infty$ . Consider the sum:

$$S_N = X_1 + \dots + X_N$$

Then, the sample mean **converges to  $\mu$  almost surely** ( $S_N/N \xrightarrow{a.s} \mu$ ):

$$\mathbb{P}\left(\limsup_{N \rightarrow \infty} |S_N/N - \mu| > \epsilon\right) = 0, \quad \forall \epsilon > 0 \quad (21)$$

**Proof** (Strong Law of Large Numbers (**SLLN**)).

For the sake of simplicity, we will present the proof for (**SLLN**) with an additional assumption that  $\mathbb{E}[|X_n|^4] < \infty, \forall n \geq 1$ . The proof for the general case of (**SLLN**) (also called the Kolmogorov Strong Law) can be found in Gut 2004, Section 6, Theorem 6.1. For convenience, we assume the following:

1.  $\mathbb{E}[|X_n|^4] = K < \infty$ .
2.  $\mathbb{E}[X_n] = 0$ . For non-zero mean case, we can set  $Y_n = X_n - \mu$  and repeat the same arguments made below.

We aim to prove that  $\mathbb{P}\left(\limsup_{N \rightarrow \infty} |S_N/N| > \epsilon\right) = 0$  for any  $\epsilon > 0$ . Firstly, use the Multinomial formula to expand  $\mathbb{E}[S_n]$ . The expansion will contain the terms in the following forms:

$$X_i^2, X_i^3 X_j, X_i^2 X_j^2, X_i^2 X_j X_k, X_i X_j X_k X_\ell,$$

where  $i, j, k, \ell$  are distinct indices. By independence, we have:

$$\mathbb{E}[X_i^3 X_j] = \mathbb{E}[X_i^2 X_j X_k] = \mathbb{E}[X_i X_j X_k X_\ell] = 0.$$

As a result, we have the following remaining terms by the Multinomial formula:

$$\begin{aligned} \mathbb{E}[S_n^4] &= \sum_{i=1}^n \mathbb{E}[X_i^4] + \binom{4}{2} \sum_{1 \leq i < j \leq n} \mathbb{E}[X_i^2 X_j^2] \\ &= \sum_{i=1}^n \mathbb{E}[X_i^4] + 6 \underbrace{\sum_{1 \leq i < j \leq n} \mathbb{E}[X_i^2 X_j^2]}_{n(n-1)/2 \text{ terms}} \\ &= nK + 3n(n-1)\mathbb{E}[X_i^2 X_j^2]. \end{aligned}$$

By independence, we have  $\mathbb{E}[X_i^2 X_j^2] = \mathbb{E}[X_i^2] \mathbb{E}[X_j^2]$  and for any  $1 \leq i \leq n$ . Furthermore, we have  $\mathbb{E}[X_i^2] = \text{Var}(X_i) + \mu^2 = \sigma^2 + \mu^2$ . Therefore:

$$\mathbb{E}[S_n^4] = nK + 3n(n-1)(\sigma^2 + \mu^2) < nK + 3n^2(\sigma^2 + \mu^2).$$

Applying Markov's Inequality with the fourth moment, we have:

$$\begin{aligned} \mathbb{P}(|S_n/n| \geq \epsilon) &= \mathbb{P}(|S_n| \geq n\epsilon) \\ &\leq \frac{\mathbb{E}[S_n^4]}{n^4 \epsilon^4} \\ &< \frac{K}{n^3 \epsilon^4} + \frac{3(\sigma^2 + \mu^2)}{n^2}. \end{aligned}$$

Therefore, we have:

$$\sum_{n=1}^{\infty} \mathbb{P}(|S_n/n| \geq \epsilon) < \frac{K}{\epsilon^4} \sum_{n=1}^{\infty} n^{-3} + 3(\sigma^2 + \mu^2) \sum_{n=1}^{\infty} n^{-2} < \infty \quad (22)$$

Finally, by the Borel-Cantelli Lemma (**BCL**), we have:

$$\mathbb{P}\left(\limsup_{n \rightarrow \infty} |S_n/n| \geq \epsilon\right) = 0, \quad \forall \epsilon > 0.$$

□.

#### Theorem 1.4: Borel-Cantelli Lemma (**BCL**)

**1. First Borel-Cantelli Lemma:** Given a probability space  $(X, \mathcal{S}, \mathbb{P})$  and a sequence  $\{A_n\}_{n=1}^{\infty} \subset \mathcal{S}$ . If  $\sum_{n=1}^{\infty} \mathbb{P}(A_n) < \infty$ , we have:

$$\mathbb{P}\left(\limsup_{n \rightarrow \infty} A_n\right) = 0. \quad (23)$$

**2. Second Borel-Cantelli Lemma:** On the other hand, if  $\sum_{n=1}^{\infty} \mathbb{P}(E_n) = \infty$ , we have:

$$\mathbb{P}\left(\limsup_{n \rightarrow \infty} A_n\right) = 1. \quad (24)$$

**Proof** (Borel-Cantelli Lemma (**BCL**)).

We focus on proving the first Borel-Cantelli lemma. We define another sequence of  $\mathcal{S}$ -measurable sets  $\{B_n\}_{n=1}^{\infty}$  such that:

$$B_n = \bigcup_{k=n}^{\infty} A_k.$$

Hence, we have  $B_{\ell+1} \subset B_{\ell}$  for every  $\ell \geq 1$ . In other words,  $B_n$  is a decreasing sequence of  $\mathcal{S}$ -measurable sets. By continuity of measure, we have:

$$\begin{aligned} \mathbb{P}\left(\lim_{n \rightarrow \infty} B_n\right) &= \lim_{n \rightarrow \infty} \mathbb{P}(B_n) \\ &= \lim_{n \rightarrow \infty} \sum_{k=n}^{\infty} \mathbb{P}(A_k) \quad (\text{By additivity}) \\ &= \sum_{i=1}^{\infty} \mathbb{P}(A_i) - \lim_{n \rightarrow \infty} \sum_{k=1}^n \mathbb{P}(A_k) \\ &= 0. \end{aligned}$$

Furthermore, we have:

$$\mathbb{P}\left(\lim_{n \rightarrow \infty} B_n\right) = \mathbb{P}\left(\lim_{n \rightarrow \infty} \bigcup_{k=n}^{\infty} A_k\right) = \mathbb{P}\left(\bigcap_{n=1}^{\infty} \bigcup_{k=n}^{\infty} A_k\right) = \mathbb{P}\left(\limsup_{n \rightarrow \infty} A_n\right).$$

Hence proved the first Borel-Cantelli Lemma. To prove the second Borel-Cantelli Lemma, we prove the following:

$$\begin{aligned} 1 - \mathbb{P}\left(\limsup_{n \rightarrow \infty} A_n\right) &= \mathbb{P}\left(\left\{\limsup_{n \rightarrow \infty} A_n\right\}^c\right) \\ &= \mathbb{P}\left(\liminf_{n \rightarrow \infty} A_n^c\right) = 0. \end{aligned}$$

□.

### 1.2.3 Uniform Law of Large Numbers

The Uniform Law of Large Numbers (**ULLN**) provides a convergence result for collection of estimators where the convergence is uniform in the parameters space.

#### Theorem 1.5: Uniform Law of Large Numbers (**ULLN**)

Let  $\mathbf{X} = (X_1, \dots, X_n)$  be a random sample from a distribution  $p_{\theta_*}$  over  $\mathcal{X}$  that depends on the true parameters  $\theta_*$ . Let  $\Theta \subset \mathbb{R}^m$  be the parameters space and  $f_\theta : \mathcal{X} \rightarrow \mathbb{R}$  be a function indexed by  $\theta \in \Theta$  that satisfies the following conditions:

1.  $\theta_* \in \Theta$  and  $\Theta$  is compact.
2.  $\mathbb{E}_{\theta_*}[\sup_{\theta \in \Theta} |f_\theta(X)|] < \infty^a$ .
3.  $f_\theta(x)$  is continuous in  $\theta$  for all  $x \in \mathcal{X}$ .

Then, we have:

$$\sup_{\theta \in \Theta} \left| \frac{1}{n} \sum_{i=1}^n f_\theta(X_i) - \mathbb{E}_{\theta_*}[f_\theta(X)] \right| \xrightarrow{p} 0. \quad (25)$$

<sup>a</sup> $\mathbb{E}_{\theta_*}$  denotes the expectation taken over the distribution described by  $p_{\theta_*}$ .

**Proof** (Theorem 1.5).

A nice proof is provided in Ferguson 1996, Theorem 16, Page 111. However, we will conduct our own version of the proof relying on results in learning theory. For  $\theta \in \Theta$ , define the following function:

$$\phi_\theta(\mathbf{X}) = \left| \frac{1}{n} \sum_{i=1}^n \left( f_\theta(X_i) - \mathbb{E}_{\theta_*}[f_\theta(X)] \right) \right| \quad (26)$$

We have to prove that  $\mathbb{P}(\sup_{\theta \in \Theta} |\phi_\theta(\mathbf{X})| \geq \epsilon) \rightarrow 0$  for all  $\epsilon > 0$ . For  $\epsilon > 0$ , we have:

$$\begin{aligned} \mathbb{P}\left(\sup_{\theta \in \Theta} |\phi_\theta(\mathbf{X})| \geq \epsilon\right) &= \mathbb{P}\left(\left\{\sup_{\theta \in \Theta} \phi_\theta(\mathbf{X}) \geq \epsilon\right\} \cup \left\{\sup_{\theta \in \Theta} (-\phi_\theta(\mathbf{X})) \geq \epsilon\right\}\right) \\ &\leq \mathbb{P}\left(\sup_{\theta \in \Theta} \phi_\theta(\mathbf{X}) \geq \epsilon\right) + \mathbb{P}\left(\sup_{\theta \in \Theta} (-\phi_\theta(\mathbf{X})) \geq \epsilon\right) \\ &\leq \frac{1}{\epsilon} \left( \mathbb{E}\left[\sup_{\theta \in \Theta} \phi_\theta(\mathbf{X})\right] + \mathbb{E}\left[\sup_{\theta \in \Theta} (-\phi_\theta(\mathbf{X}))\right] \right) \quad (\text{Markov's Inequality}) \end{aligned}$$

Now, we need to bound the expectations on the right-hand-side. To do so, we use the symmetrization trick. Specifically, given a sequence of i.i.d random variables  $S = \{Z_1, \dots, Z_n\} \sim \rho^n$  sampled from a distribution  $\rho$  and a class of functions  $\mathcal{F}$ . Let  $S' = \{Z'_1, \dots, Z'_n\} \sim \rho^n$  be a another sample



from the same distribution  $\rho$  (which we called the phantom sample), we have:

$$\begin{aligned}
& \mathbb{E}_S \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n (f(Z_i) - \mathbb{E}_S[f(Z_i)]) \right] \\
&= \mathbb{E}_S \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n (f(Z_i) - \mathbb{E}_{S'}[f(Z'_i)]) \right] \\
&= \mathbb{E}_S \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n f(Z_i) - \frac{1}{n} \sum_{i=1}^n \mathbb{E}_{S'}[f(Z'_i)] \right] \\
&= \mathbb{E}_S \left[ \sup_{f \in \mathcal{F}} \mathbb{E}_{S'} \left[ \frac{1}{n} \sum_{i=1}^n (f(Z_i) - f(Z'_i)) \right] \right] \\
&\leq \mathbb{E}_{S, S'} \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n (f(Z_i) - f(Z'_i)) \right] \quad (\text{Jensen's Inequality}) \\
&= \mathbb{E}_{S, S', \sigma} \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \sigma_i (f(Z_i) - f(Z'_i)) \right] \quad (\sigma \sim \text{Rad}^n, f(Z_i) - f(Z'_i) \text{ is symmetric}) \\
&\leq \mathbb{E}_{S, \sigma} \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \sigma_i f(Z_i) \right] + \mathbb{E}_{S', \sigma} \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n (-\sigma_i) f(Z'_i) \right] \\
&= \mathbb{E}_{S, \sigma} \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \sigma_i f(Z_i) \right] + \mathbb{E}_{S', \sigma} \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \sigma_i f(Z'_i) \right] \quad (\text{Rademacher variables are symmetric}) \\
&= 2\mathbb{E}_{S, \sigma} \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \sigma_i f(Z_i) \right] \quad (S \text{ and } S' \text{ are identically distributed}) \\
&= 2\mathfrak{R}_n(\mathcal{F}).
\end{aligned} \tag{27}$$

Using the same argument, we can also have:

$$\mathbb{E}_S \left[ \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n (\mathbb{E}_S[f(Z_i)] - f(Z_i)) \right] \leq 2\mathfrak{R}_n(\mathcal{F}). \tag{28}$$

Using equations 27 and 28 to bound  $\mathbb{P}(\sup_{\theta \in \Theta} |\phi_\theta(S)| \geq \epsilon)$ , we have:

$$\mathbb{P} \left( \sup_{\theta \in \Theta} |\phi_\theta(S)| \geq \epsilon \right) \leq \frac{4\mathfrak{R}_n(\mathcal{F}_\Theta)}{\epsilon}, \text{ where } \mathcal{F}_\Theta = \{f_\theta : \theta \in \Theta\}.$$

To complete the proof, we have to show that the Rademacher complexity  $\mathfrak{R}_n(\mathcal{F}_\Theta) \rightarrow 0$  as  $n \rightarrow \infty$ . By the definition of Rademacher Complexity, we have:

$$\mathfrak{R}_n(\mathcal{F}_\Theta) = \mathbb{E}_{\mathbf{X} \sim p_{\theta_*}^n} \mathbb{E}_\sigma [\hat{\mathfrak{R}}_{\mathbf{X}}(\mathcal{F}_\Theta)],$$

It is sufficient to prove that the Empirical Rademacher Complexity  $\hat{\mathfrak{R}}_{\mathbf{X}}(\mathcal{F}_\Theta) \rightarrow 0$  as  $n \rightarrow \infty$ . Using Dudley's Entropy Integral Bartlett et al. 2017, Lemma A.5, we have:

$$\hat{\mathfrak{R}}_{\mathbf{X}}(\mathcal{F}_\Theta) \leq \frac{12}{\sqrt{n}} \int_\alpha^M \sqrt{\log \mathcal{N}(\mathcal{F}_\Theta, \epsilon, L_2(\mathbf{X}))} d\epsilon, \quad \alpha > 0, \tag{29}$$

where  $M < \infty$  is a constant such that  $|f_\theta(x)| \leq M$   $p_{\theta_*}$ -(almost everywhere) on  $\mathcal{X}$  for all  $\theta \in \Theta^1$ . Now, we need to construct a cover in  $L_2$  norm for the class  $\mathcal{F}_\Theta$ . Since  $f_\theta(x)$  is continuous in  $\theta$  for all  $x \in \mathcal{X}$ , for all  $\epsilon > 0$ , there exists  $\delta_x > 0$  such that  $\|\theta - \theta'\|_2 < \delta_x \implies |f_\theta(x) - f_{\theta'}(x)| < \epsilon$ . Define  $\delta > 0$  as follows:

$$\delta = \min_{1 \leq i \leq n} \delta_{X_i}, \quad X_i \in \mathbf{X}. \tag{30}$$

---

<sup>1</sup>M exists because we have  $\mathbb{E}_{\theta_*}[\sup_{\theta \in \Theta} |f_\theta(X)|] < \infty$ .

Due to continuity, constructing an  $\epsilon$ -cover in  $\mathcal{F}_\Theta$  is equivalent to constructing a  $\delta$ -cover for  $\Theta$  with respect to the Euclidean norm. Since  $\Theta$  is compact, there exists  $N \in \mathbb{N}$  and a sequence of open balls  $\{\mathcal{B}(y_j, r_j)\}_{j=1}^N$  where  $y_j \in \Theta$  for all  $1 \leq j \leq N$  such that:

$$\Theta \subseteq \bigcup_{j=1}^N \mathcal{B}(y_j, r_j). \quad (31)$$

By Long et al. 2020, Lemma A.8, we have:

$$\log \mathcal{N}(\mathcal{B}(y_j, r_j), \delta, \|\cdot\|_2) \leq m \log \left( \frac{3r_j}{\delta} \right). \quad (32)$$

Therefore, we have:

$$\log \mathcal{N}(\Theta, \delta, \|\cdot\|_2) \leq \sum_{j=1}^N \log \mathcal{N}(\mathcal{B}(y_j, r_j), \delta, \|\cdot\|_2) \leq mN \log \left( \frac{\prod_{j=1}^N r_j}{\delta^N} \right). \quad (33)$$

From the above covering number bound, we can see that  $\log \mathcal{N}(\Theta, \delta, \|\cdot\|_2)$  does not grow with  $n$  and therefore,  $\log \mathcal{N}(\mathcal{F}_\Theta, \epsilon, L_2(\mathbf{X}))$  does not grow with  $n$ . Therefore, we have  $\hat{\mathfrak{R}}_{\mathbf{X}}(\mathcal{F}_\Theta) \in \mathcal{O}(1/\sqrt{n})$  and  $\hat{\mathfrak{R}}_{\mathbf{X}}(\mathcal{F}_\Theta) \rightarrow 0$  as  $n \rightarrow \infty$ .  $\square$ .

#### 1.2.4 Central Limit Theorem

##### Theorem 1.6: Central Limit Theorem (CLT)

Let  $X_1, \dots, X_n$  be a sequence of *i.i.d* random variables with expected value  $\mu$  and finite variance  $\sigma^2$ . Then, we have:

$$\frac{\bar{X}_n - \mu}{\sigma/\sqrt{n}} \xrightarrow{d} \mathcal{N}(0, 1) \quad \text{as } n \rightarrow \infty, \quad (34)$$

where  $\bar{X}_n = S_n/n$  and  $\mathcal{N}(0, 1)$  is the standard normal distribution.

**Proof** (Central Limit Theorem (CLT)).

We prove this via the Characteristic Function. Let  $\bar{Z}_n = \frac{\bar{X}_n - \mu}{\sigma/\sqrt{n}}$ , notice that:

$$\bar{Z}_n = \frac{\bar{X}_n - \mu}{\sigma/\sqrt{n}} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \frac{X_i - \mu}{\sigma},$$

Let  $Z_i = X_i - \mu$  for  $1 \leq i \leq n$  and suppose  $Z = Z_1 = \dots = Z_n$ , we have:

$$\begin{aligned} \varphi_{\bar{Z}_n}(t) &= \varphi_{\sum_{i=1}^n Z_i} \left( \frac{t}{\sqrt{n}} \right) = \left[ \varphi_Z \left( \frac{t}{\sqrt{n}} \right) \right]^n \\ &= \left[ 1 + \frac{it\mathbb{E}[Z]}{\sqrt{n}} - \frac{t^2}{2n} \mathbb{E}[Z^2] + \mathcal{O}(1/n) \right]^n \quad (\text{Taylor's Expansion}) \\ &= \left[ 1 - \frac{t^2}{2n} + \mathcal{O}(1/n) \right]^n. \end{aligned}$$

The final equality comes from the fact that  $\mathbb{E}[Z] = 0$  and  $\mathbb{E}[Z^2] = \mathbb{E}[Z]^2 + \text{Var}(Z) = 1$ . Finally, we have:

$$\lim_{n \rightarrow \infty} \varphi_{\bar{Z}_n}(t) = \lim_{n \rightarrow \infty} \left[ 1 - \frac{t^2}{2n} + \mathcal{O}(1/n) \right]^n = e^{-t^2/2}.$$

Since  $e^{-t^2/2}$  is the Characteristic Function of the standard normal distribution, by **(LCT)**, we have  $\bar{Z}_n \xrightarrow{d} \mathcal{N}(0, 1)$ .  $\square$ .

## 1.3 Convergence of Random Variables

### 1.3.1 Convergence in Distribution

**Definition 1.2** (Convergence in Distribution). 

---

Given a sequence of real-valued random variables  $X_1, X_2, \dots$  with CDFs  $F_1, F_2, \dots$ . We say that the sequence converges in distribution to a random variable  $X$  with CDF  $F$ , denoted  $X_n \xrightarrow{d} X$  if:

$$\lim_{n \rightarrow \infty} F_n(x) = F(x), \quad (35)$$

for all  $x \in \mathbb{R}$  at which  $F$  is continuous. Convergence in distribution can also be referred to as weak convergence in measure theory.

#### Theorem 1.7: Slutsky's Theorem (**SLUTSKY**)

Let  $X_n$  and  $Y_n$  be two sequences of random variables such that  $X_n \xrightarrow{d} X$  and  $Y_n \xrightarrow{d} c^a$  where  $c < \infty$  is a constant. Then, we have:

1.  $X_n + Y_n \xrightarrow{d} X + c$ .
2.  $X_n Y_n \xrightarrow{d} cX$ .
3.  $X_n/Y_n \xrightarrow{d} X/c$  if  $c \neq 0$ .

---

<sup>a</sup>In the next section, we will see that  $Y_n \xrightarrow{d} c$  implies  $Y_n \xrightarrow{p} c$  for a constant  $c$ .

**Proof** (Theorem 1.7). 

---

1.  $X_n + Y_n \xrightarrow{d} X + c$ . Let  $\epsilon > 0$  be any positive constant, we have:

$$\begin{aligned} F_{X_n+Y_n}(t) &= \mathbb{P}(X_n + Y_n \leq t) \\ &= \mathbb{P}(X_n + Y_n \leq t, |Y_n - c| \leq \epsilon) + \mathbb{P}(X_n + Y_n \leq t, |Y_n - c| > \epsilon) \\ &\leq \mathbb{P}(X_n + Y_n \leq t, |Y_n - c| \leq \epsilon) + \underbrace{\mathbb{P}(|Y_n - c| > \epsilon)}_{\text{approaches 0 as } n \rightarrow \infty}. \end{aligned}$$

In the event that  $|Y_n - c| \leq \epsilon$ , we have  $Y_n \geq c - |Y_n - c| \geq c - \epsilon$ . Therefore, we have:

$$F_{X_n+Y_n}(t) \leq \mathbb{P}(X_n \leq t - c + \epsilon) + \mathbb{P}(|Y_n - c| > \epsilon).$$

Similarly, we have:

$$F_{X_n+Y_n}(t) \geq \mathbb{P}(X_n \leq t - c - \epsilon) - \mathbb{P}(|Y_n - c| > \epsilon).$$

Taking limits of both inequalities, we have:

$$F_X(t - c - \epsilon) \leq \lim_{n \rightarrow \infty} F_{X_n+Y_n}(t) \leq F_X(t - c + \epsilon).$$

Let  $\epsilon \rightarrow 0$ , we have  $\lim_{n \rightarrow \infty} F_{X_n+Y_n}(t) \rightarrow F_X(t - c) = F_{X+c}(t)$  as  $n \rightarrow \infty$ .

2.  $X_n Y_n \xrightarrow{d} cX$ . (Apply the same proof method as (1)).
3.  $X_n/Y_n \xrightarrow{d} X/c$  if  $c \neq 0$ . (Apply the same proof method as (1)).

$\square$ .

## Connection to Weak Convergence of Measures

### Definition 1.3 (Continuity Sets).

Let  $X$  be a metric space and  $\mathcal{B}$  be the Borel- $\sigma$ -algebra generated from open subsets of  $X$ . Let  $A \in \mathcal{B}$  be a Borel set. Then, we say that  $A$  is a continuity set with respect to a measure  $\mu$ , or  $A$  is a  $\mu$ -continuity set, if:

$$\mu(\partial A) = 0, \text{ or } \mu(\text{cl}_X(A)) = \mu(A), \quad (36)$$

where  $\partial A$  is the topological boundary of  $A$ , defined as:

$$\partial A = \text{cl}_X(A) \setminus \text{in}_X(A), \quad (37)$$

where  $\text{cl}_X(A)$  is the closure, which contains all limit points of  $A$  and  $\text{in}_X(A)$  is the set of all interior points of  $A$ . Intuitively, a set is continuous with respect to a measure if its closure does not change its measure.

### Remark 1.2 (Non-examples of Continuity Sets).

Some examples of the non-continuity sets are as follows:

1. The set of rational numbers  $\mathbb{Q}$  is not a continuity set with respect to the Lebesgue measure  $\lambda$  because its closure is the set of real numbers. Hence, we have:

$$\lambda(\partial \mathbb{Q}) = \lambda(\mathbb{R} \setminus \mathbb{Q}) = \infty.$$

2. Given an experiment of rolling an unfair 6-sided die with probabilities  $p_1, \dots, p_6$ . Let the sample space  $\Omega = [1, 6]$  and  $\mathcal{B}(\Omega)$  be the Borel- $\sigma$ -algebra generated from open subsets of the sample space. Then, we have the corresponding probability space  $(\Omega, \mathcal{B}(\Omega), \mu)$  where  $\mu$  is defined as:

$$\mu((a, b)) = \sum_{i=\lfloor a \rfloor}^{\lfloor b \rfloor} p_i, \quad \forall (a, b) \in \mathcal{B}(\Omega),$$

which denotes the probability that the rolled die lands on a face in the range between  $a$  and  $b$ . Then, any set  $(a, b)$  in  $\mathcal{B}(\Omega)$  where  $a$  or  $b$  is integer is not  $\mu$ -continuous. For example:

$$\begin{aligned} \mu((2, 4.5)) &= p_3 + p_4, \\ \mu(\text{cl}((2, 4.5))) &= \mu([2, 4.5]) = p_2 + p_3 + p_4 > \mu((2, 4.5)). \end{aligned}$$

### Definition 1.4 (Weak Convergence of Measures).

Let  $\{\mu_n\}_{n=1}^{\infty}$  be a sequence of measures and  $\mu$  be a measure on a measurable space  $(X, \mathcal{F})$ . We say that  $\mu_n$  converges weakly to a measure  $\mu$  if:

$$\lim_{n \rightarrow \infty} \mu_n(A) = \mu(A), \quad (38)$$

for all  $\mu$ -continuity sets  $A \in \mathcal{F}$ .

### Theorem 1.8: Portmanteau's Theorem (PORTMANTEAU)

Let  $\{\mathbb{P}_n\}_{n=1}^\infty, \mathbb{P}$  be probability measures on a measurable space  $(X, \mathcal{F})$ . Then, the following statements are equivalent:

1.  $\mathbb{P}_n$  converges weakly to  $\mathbb{P}$ .
2.  $\int f d\mathbb{P}_n \rightarrow \int f d\mathbb{P}$  for all  $f \in C_b(X)^a$ .
3.  $\limsup_{n \rightarrow \infty} \mathbb{P}_n(F) \leq \mathbb{P}(F)$  for all closed  $F \in \mathcal{F}$ .
4.  $\liminf_{n \rightarrow \infty} \mathbb{P}_n(G) \geq \mathbb{P}(G)$  for all open  $G \in \mathcal{F}$ .

<sup>a</sup> $C_b(X)$  denotes the space of bounded continuous  $f : X \rightarrow \mathbb{C}$  functions.

**Proof** (Theorem 1.8).

Assume that for all Borel sets  $A \in \mathcal{F}$  that is  $\mathbb{P}$ -continuity, we have  $\lim_{n \rightarrow \infty} \mathbb{P}_n(A) = \mathbb{P}(A)$ . We prove the following:

1.  $\int f d\mathbb{P}_n \rightarrow \int f d\mathbb{P}$  for all  $f \in C_b(X)$  : Let  $b > 0$ , without loss of generality, suppose that  $0 \leq f \leq b$  for all  $f \in C_b(X)$ . By the integral identity, we have:

$$f(x) = \int_0^b \mathbf{1}\{t < f(x)\} dt, \quad \forall x \in X.$$

Hence, for  $n \geq 1$ , we have:

$$\begin{aligned} \int f d\mathbb{P}_n &= \int \int_0^b \mathbf{1}\{t < f\} dt d\mathbb{P}_n \\ &= \int_0^b \int \mathbf{1}\{t < f\} d\mathbb{P}_n dt \quad (\text{Fubini's Theorem}) \\ &= \int_0^b \mathbb{P}_n(f^{-1}(t, b)) dt. \end{aligned}$$

We have  $\partial f^{-1}(t, b) \subseteq f^{-1}(\{t, b\})$ . Hence, we have  $\mathbb{P}(\partial f^{-1}(t, b)) \leq \mathbb{P}(f^{-1}(\{t, b\})) = 0$ , which means that  $f^{-1}(t, b)$  is a  $\mathbb{P}$ -continuity set. Therefore, by the initial assumption, we have:

$$\lim_{n \rightarrow \infty} \mathbb{P}_n(f^{-1}(t, b)) = \mathbb{P}(f^{-1}(t, b)).$$

By Dominated Convergence Theorem, we have  $\int_0^b \mathbb{P}_n(f^{-1}(t, b)) dt \rightarrow \int_0^b \mathbb{P}(f^{-1}(t, b)) dt$ . Hence, we obtain the desired result.

2.  $\liminf_{n \rightarrow \infty} \mathbb{P}_n(G) \geq \mathbb{P}(G)$  for all open  $G \in \mathcal{F}$ : Let  $G \in \mathcal{F}$  be an open set and let  $U = G^c$ . Consider the following sequence of continuous, bounded functions:

$$f_m(s) = \min(1, m \cdot d_X(s, U)),$$

where we denote:

$$d_X(s, U) = \inf_{x \in U} d_X(s, x),$$

which is the projection of a point  $s$  onto the set  $U$ . We can re-write  $f_m$  as follows:

$$f_m(s) = \begin{cases} 1, & \text{if } d(s, U) \geq \frac{1}{m} \\ m \cdot d(s, U), & \text{if } d(s, U) < \frac{1}{m} \end{cases}.$$

In other words,  $f_m(s) = 1$  when the point  $s$  is sufficiently far away from the complement  $U$  and as  $m$  increases, the distance threshold required for  $f_m(s) = 1$  becomes smaller, making  $f_m$  approaches the indicator function  $\mathbf{1}_G$ . Hence, we have:

$$\mathbb{P}_n(G) = \int \mathbf{1}_G d\mathbb{P}_n \geq \int f_m d\mathbb{P}_n \rightarrow \int f_m d\mathbb{P}, \quad (\text{By (1)}).$$

Hence, we have  $\liminf_{n \rightarrow \infty} \mathbb{P}_n(G) \geq \int f_m d\mathbb{P}^2$ . Taking  $m \rightarrow \infty$  and using Monotone Convergence Theorem, we have:

$$\liminf_{n \rightarrow \infty} \mathbb{P}_n(G) \geq \lim_{m \rightarrow \infty} \int f_m d\mathbb{P} = \int \lim_{m \rightarrow \infty} f_m d\mathbb{P} = \int \mathbf{1}_G d\mathbb{P} = \mathbb{P}(G).$$

3.  $\limsup_{n \rightarrow \infty} \mathbb{P}_n(F) \leq \mathbb{P}(F)$  for all closed  $F \in \mathcal{F}$ : Taking the complement of  $F$  and apply (2), we obtain the desired result.

□.

### 1.3.2 Convergence in Probability

**Definition 1.5** (Convergence in Probability). \_\_\_\_\_

Given a sequence of real-valued random variables  $X_1, X_2, \dots$ . We say that the sequence converges in probability to a random variable  $X$ , denoted  $X_n \xrightarrow{p} X$  if:

$$\lim_{n \rightarrow \infty} \mathbb{P}(|X_n - X| \geq \epsilon) = 0, \quad \forall \epsilon > 0. \quad (39)$$

We also refer to convergence in probability as convergence in measure in measure theory.

**Proposition 1.1:**  $X_n \xrightarrow{p} X \implies X_n \xrightarrow{d} X$

Let  $X$  and the sequence  $X_1, X_2, \dots$  be real-valued random variables. If  $X_n \xrightarrow{p} X$ , then  $X_n \xrightarrow{d} X$ .

**Proof** (Proposition 1.1). \_\_\_\_\_

We first prove the following claim: Let  $X, Y$  be random variables,  $a \in \mathbb{R}$  and  $\epsilon > 0$ , the inequality  $\mathbb{P}(Y \leq a) \leq \mathbb{P}(X \leq a + \epsilon) + \mathbb{P}(|Y - X| \geq \epsilon)$  holds. We have:

$$\begin{aligned} \mathbb{P}(Y \leq a) &= \mathbb{P}(Y \leq a, X \leq a + \epsilon) + \mathbb{P}(Y \leq a, X \geq a + \epsilon) \\ &\leq \mathbb{P}(X \leq a + \epsilon) + \mathbb{P}(Y - X \leq a - X, a - X \leq -\epsilon) \\ &\leq \mathbb{P}(X \leq a + \epsilon) + \mathbb{P}(Y - X \leq -\epsilon) \\ &\leq \mathbb{P}(X \leq a + \epsilon) + \mathbb{P}(Y - X \leq -\epsilon) + \mathbb{P}(Y - X \geq \epsilon) \\ &= \mathbb{P}(X \leq a + \epsilon) + \mathbb{P}(|Y - X| \geq \epsilon). \end{aligned}$$

Using the above inequality, we have:

$$\mathbb{P}(X \leq a - \epsilon) - \mathbb{P}(|X_n - X| \geq \epsilon) \leq \mathbb{P}(X_n \leq a) \leq \mathbb{P}(X \leq a + \epsilon) + \mathbb{P}(|X_n - X| \geq \epsilon).$$

Taking limits as  $n \rightarrow \infty$  from both sides, we have:

$$F_X(a - \epsilon) \leq \lim_{n \rightarrow \infty} F_{X_n}(a) \leq F_X(a + \epsilon).$$

Taking  $\epsilon \rightarrow 0^+$ , we have  $\lim_{n \rightarrow \infty} F_{X_n}(a) = F_X(a)$ . □.

<sup>2</sup>From  $\mathbb{P}_n(G) \geq \int f_m d\mathbb{P}_n$ , we have  $\liminf_{n \rightarrow \infty} \mathbb{P}_n(G) \geq \liminf_{n \rightarrow \infty} \int f_m d\mathbb{P}_n = \lim_{n \rightarrow \infty} \int f_m d\mathbb{P}_n = \int f_m d\mathbb{P}$ .

**Proposition 1.2:**  $X_n \xrightarrow{d} c \iff X_n \xrightarrow{p} c$

Let  $c \in \mathbb{R}$  be a constant and  $X_1, X_2, \dots$  be a sequence of real-valued random variables. Then,  $X_n \xrightarrow{d} c \iff X_n \xrightarrow{p} c$ .

**Proof** (Proposition 1.2, Pishro-Nik 2014). \_\_\_\_\_

Since  $X_n \xrightarrow{d} c$ , we immediately have the following:

$$\begin{aligned}\lim_{n \rightarrow \infty} F_{X_n}(c - \epsilon) &= 0, \\ \lim_{n \rightarrow \infty} F_{X_n}(c + \epsilon/2) &= 1.\end{aligned}$$

Then, for any  $\epsilon > 0$ , we have:

$$\begin{aligned}\lim_{n \rightarrow \infty} \mathbb{P}(|X_n - c| \geq \epsilon) &= \lim_{n \rightarrow \infty} \mathbb{P}[\mathbb{P}(X_n \leq c - \epsilon) + \mathbb{P}(X_n \geq c + \epsilon)] \\ &= \underbrace{\lim_{n \rightarrow \infty} F_{X_n}(c - \epsilon)}_{=0} + \lim_{n \rightarrow \infty} \mathbb{P}(X_n \geq c + \epsilon) \\ &\leq \lim_{n \rightarrow \infty} \mathbb{P}(X_n \geq c + \epsilon/2) \\ &= 1 - \underbrace{\lim_{n \rightarrow \infty} F_{X_n}(c + \epsilon/2)}_{=1} \\ &= 0.\end{aligned}$$

From the above, we have  $\lim_{n \rightarrow \infty} \mathbb{P}(|X_n - c| \geq \epsilon) = 0$  and  $X_n \xrightarrow{p} c$ . □.

### 1.3.3 Convergence in $L^p$ norm

**Definition 1.6** (Convergence in  $L^p$  norm). \_\_\_\_\_

Given a sequence of random variables  $X_1, X_2, \dots$  and a real number  $p \in [1, \infty)$ . We say that the sequence converges in  $L^p$  norm to a random variable  $X$ , denoted as  $X_n \xrightarrow{L^p} X$  if:

$$\lim_{n \rightarrow \infty} \mathbb{E}|X_n - X|^p = 0. \quad (40)$$

**Proposition 1.3:**  $X_n \xrightarrow{L^p} X \implies X_n \xrightarrow{p} X$

Let  $p \geq 1$  and  $X_1, X_2, \dots$  be a sequence of real-valued random variables. Let  $X$  be a random variable, then,  $X_n \xrightarrow{L^p} X \implies X_n \xrightarrow{p} X$ .

**Proof** (Proposition 1.3). \_\_\_\_\_

Let  $\epsilon > 0$ , we have:

$$\begin{aligned}\mathbb{P}(|X_n - X| \geq \epsilon) &= \mathbb{P}(|X_n - X|^p \geq \epsilon^p) \quad (p \geq 1) \\ &\leq \frac{\mathbb{E}|X_n - X|^p}{\epsilon^p}. \quad (\text{Markov's Inequality})\end{aligned}$$

Taking the limits from both sides, we have  $\lim_{n \rightarrow \infty} \mathbb{P}(|X_n - X| \geq \epsilon) = 0$  and  $X_n \xrightarrow{p} X$ . □.

### 1.3.4 Almost-sure Convergence

**Definition 1.7** (Convergence almost-surely). \_\_\_\_\_

Let  $X_1, X_2, \dots$  be a sequence of real-valued random variables that map from a sample space  $\Omega$ . Let  $X$  also be a real-valued random variable. We say that  $X_n$  converges almost surely to  $X$ , denoted as  $X_n \xrightarrow{a.s.} X$ , if  $X_n(\omega) \rightarrow X(\omega)$  as  $n \rightarrow \infty$  for almost all  $\omega \in \Omega$ :

$$\mathbb{P}\left(\left\{\omega \in \Omega : \lim_{n \rightarrow \infty} X_n(\omega) = X(\omega)\right\}\right) = 1. \quad (41)$$

In other words, we can write:

$$\mathbb{P}\left(\limsup_{n \rightarrow \infty} E_n\right) = 0 \quad \text{where} \quad E_n = \left\{\omega \in \Omega : |X_n(\omega) - X(\omega)| \geq \epsilon\right\}. \quad (42)$$

**Remark 1.3** (Consequence of **(BCL)**). \_\_\_\_\_

Let  $X, X_1, X_2, \dots$  be random variables defined over the same probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . For  $\epsilon > 0$  be chosen arbitrarily, let  $E_n = \{\omega \in \Omega : |X_n(\omega) - X(\omega)| \geq \epsilon\}$ . Then, we have:

$$\sum_{n=1}^{\infty} \mathbb{P}(E_n) < \infty \implies X_n \xrightarrow{a.s.} X. \quad (43)$$

In other words, if the sequence  $\{\mathbb{P}(E_n)\}_{n=1}^{\infty}$  converges, then  $X_n$  converges almost surely to  $X$ .

**Proposition 1.4:**  $X_n \xrightarrow{a.s.} X \implies X_n \xrightarrow{p} X$

Let  $X_1, X_2, \dots$  be a sequence of real-valued random variables and also let  $X$  be a real valued random variables. If  $X_n \xrightarrow{a.s.} X$  then  $X_n \xrightarrow{p} X$ .

**Proof** (Proposition 1.4). \_\_\_\_\_

Let  $f_n : \Omega \rightarrow \mathbb{R}_+$  be a sequence of nonnegative Borel-measurable functions such that  $f_n(\omega) = |X_n(\omega) - X(\omega)|$ . By Fatou's Lemma (reverse), we have:

$$\begin{aligned} \underbrace{\mathbb{P}\left(\limsup_{n \rightarrow \infty} \{\omega \in \Omega : |X_n(\omega) - X(\omega)| \geq \epsilon\}\right)}_{=0} &= \int f_n d\mathbb{P} \\ &\geq \limsup_{n \rightarrow \infty} \mathbb{P}(|X_n - X| \geq \epsilon) \\ &\geq \lim_{n \rightarrow \infty} \mathbb{P}(|X_n - X| \geq \epsilon). \end{aligned}$$

Hence, we have  $\lim_{n \rightarrow \infty} \mathbb{P}(|X_n - X| \geq \epsilon) = 0$  and  $X_n \xrightarrow{p} X$ . □.

**Theorem 1.9: Continuous Mapping Theorem (CMT)**

Let  $f : \mathbb{R} \rightarrow \mathbb{R}$  be a continuous almost everywhere function and  $X_1, X_2, \dots$  be a sequence of real-valued random variables. Then, the following statements hold:

1.  $X_n \xrightarrow{d} X \implies f(X_n) \xrightarrow{d} f(X)$ .
2.  $X_n \xrightarrow{p} X \implies f(X_n) \xrightarrow{p} f(X)$ .
3.  $X_n \xrightarrow{a.s.} X \implies f(X_n) \xrightarrow{a.s.} f(X)$ .



**Proof** (Continuous Mapping Theorem (**CMT**)).

We handle each statement separately:

1. Let  $\mathbb{P}_n, \mathbb{P}$  be the probability measures induced by  $X_n$  and  $X$ , respectively. By (**PORTMANTEAU**),  $\mathbb{P}_n$  converges weakly to  $\mathbb{P}$  is equivalent to  $\int g d\mathbb{P}_n \rightarrow \int g d\mathbb{P}$  for all continuous, bounded  $g : \mathbb{R} \rightarrow \mathbb{R}$ . For all  $g$  continuous and bounded,  $g \circ f$  is also continuous and bounded. Hence:

$$\int g \circ f d\mathbb{P}_n \rightarrow \int g \circ f d\mathbb{P} \text{ as } n \rightarrow \infty.$$

Hence, let  $\mathbb{P}_n f$  and  $\mathbb{P} f$  be the probability measures induced by  $f(X_n)$  and  $f(X)$ , respectively. We have  $\mathbb{P}_n f$  converges  $\mathbb{P} f$  weakly. Therefore,  $f(X_n) \xrightarrow{d} f(X)$ .

2. Let  $C_f$  denotes the set of points on  $\mathbb{R}$  where  $f$  is continuous. By assumption, we have  $\mathbb{P}(x)$ . Let  $\epsilon > 0$  be arbitrary. For all  $\delta > 0$ , we denote the following set:

$$B_\delta = \left\{ x \in C_f : \exists y \in \mathbb{R} \text{ s.t. } |x - y| < \delta \text{ but } |f(x) - f(y)| \geq \epsilon \right\}$$

In other words,  $B_\delta$  denotes the set of all continuous points  $x$  of  $f$  such that we can find a point close to  $x$  but its output is not close to  $f(x)$ . We have:

$$\begin{aligned} \mathbb{P}(|f(X_n) - f(X)| \geq \epsilon) &= \mathbb{P}\left(\left\{X \notin C_f\right\} \cup \left\{|X_n - X| \geq \delta\right\} \cup \left\{X \in B_\delta\right\}\right) \\ &\leq \underbrace{\mathbb{P}(X \notin C_f)}_{=0} + \mathbb{P}(|X_n - X| \geq \delta) + \mathbb{P}(X \in B_\delta) \\ &= \mathbb{P}(|X_n - X| \geq \delta) + \mathbb{P}(X \in B_\delta). \end{aligned}$$

Since  $\lim_{n \rightarrow \infty} \mathbb{P}(|X_n - X| \geq \delta) = 0$  for all  $\delta > 0$  by assumption and  $\mathbb{P}(X \in B_\delta) = 0$  when  $\delta \rightarrow 0$ , we have:

$$\lim_{n \rightarrow \infty} \mathbb{P}(|f(X_n) - f(X)| \geq \epsilon) = 0 \text{ or } f(X_n) \xrightarrow{p} f(X).$$

3. Since  $f$  is continuous, for any  $\omega \in \Omega$  such that  $X_n(\omega) \rightarrow X(\omega)$ , we have  $f(X_n(\omega)) \rightarrow f(X(\omega))$ . Therefore, we have:

$$\left\{ \omega \in \Omega : X_n(\omega) \rightarrow X(\omega) \right\} \subseteq \left\{ \omega \in \Omega : f(X_n(\omega)) \rightarrow f(X(\omega)) \right\}.$$

Therefore, for all  $\epsilon > 0$ , we have:

$$\begin{aligned} &\mathbb{P}\left(\left\{ \omega \in \Omega : \lim_{n \rightarrow \infty} f(X_n(\omega)) = f(X(\omega)) \right\}\right) \\ &\geq \mathbb{P}\left(\left\{ \omega \in \Omega : \lim_{n \rightarrow \infty} X_n(\omega) = X(\omega) \right\}\right) = 1, \end{aligned}$$

Hence, we have  $f(X_n) \xrightarrow{a.s.} f(X)$ .

□.

## 2 Point Estimation

### 2.1 Properties of Point Estimators

In this section, we will discuss “point estimators”, the desirable properties of classes of point estimators and important results. Firstly, let us define what a point estimator is:

**Definition 2.1** (Point Estimator). 

---

Let  $\mathbf{X} = (X_1, \dots, X_n)$  be a random i.i.d sample from a distribution  $p_{\theta_*}$  over  $\mathcal{X}$  that relies on parameter(s)  $\theta_*$ . Let  $\theta \in \Theta$  be a population parameter (population mean, variance, etc). A point estimator for  $\theta$  is a mapping:

$$\hat{\Theta} : \mathcal{X}^n \rightarrow \Theta, \quad (44)$$

where  $\hat{\Theta}(\mathbf{X})$  serves as a “best guess” of the quantity  $\theta$  based on the available data. Due to the randomness of the sample, the estimator  $\hat{\Theta}(\mathbf{X})$  is a **random variable**.

In this note, we discuss some desirable properties of point estimators. To summarize these properties before getting into the technicality, we will illustrate the concepts with an example. Suppose that you are given a truck of apples and you want to guess the average weight  $\theta$  of these apples. Suppose you have a method  $\hat{\Theta}$  to estimate  $\theta$ , the properties of unbiasedness, consistency, efficiency and sufficiency can be demonstrated as follows:

1. **Unbiasedness:** Suppose that your method is to guess  $\theta$  as the mean of the first 10 apples you see. You repeat this guessing process over and over again and realize that the average of all your guesses matches the true value of  $\theta$ . So, on average, you guess  $\theta$  correctly.
2. **Consistency:** You take the first 5 apples, your method  $\hat{\Theta}$  gives you an estimate a bit far off from  $\theta$ . You take 45 more apples, your guess gets closer to the true value of  $\theta$ . Now, you take 450 more apples, your guess gets even closer. So, your guess gets closer and closer to the true value as you increase sample size.
3. **Efficiency:** Suppose your friend has an estimation method  $\tilde{\Theta}$ . It took you 50 apples to get an estimate that is close to  $\theta$  while it took your friend’s method 500 apples to get similarly close. So, your method is more efficient.
4. **Sufficiency:** Suppose someone gives you a summary table stating that you have 5000 apples in the truck and the total weight is 100kg. Then, you do not even have to measure any apple. The summary table already gives you sufficient information.

#### 2.1.1 Sufficiency

**Definition 2.2** (Sufficient Statistics). 

---

Let  $\mathbf{X} = (X_1, \dots, X_n) \sim p_{\theta_*}$  be a random sample drawn i.i.d from a distribution with parameters  $\theta_*$ . Let  $\mathbf{U} = T(\mathbf{X})$  be a statistic, then it is called a sufficient statistic if the conditional distribution  $p_{\mathbf{X}|\mathbf{U}}$  does not depend on  $\theta_*$ .

**Remark 2.1** (Intuition for “Sufficiency”). 

---

To give a bit of intuition into what we consider a “sufficient” statistics. Given a random sample  $\mathbf{X}$  from a distribution whose parameters are denoted as  $\theta_*$ . A statistics  $\mathbf{U} = T(\mathbf{X})$  is **sufficient** for the inference of  $\theta_*$  iff **once we know  $\mathbf{U}$ , there is no further information about  $\theta_*$  that we can derive from the data  $\mathbf{X}$** . For example, given  $\mathbf{X} = (X_1, \dots, X_n) \sim_{\text{i.i.d}} \mathcal{N}(\mu, \sigma^2)$  and our task is to estimate the expectation  $\mu$ . Consider the following intuitive example:

- (i)  $\mathbf{U}_1 = \frac{1}{n} \sum_{i=1}^n X_i$ :  $\mathbf{U}_1$  is a sufficient statistics because we have used up all the information from the sample  $\mathbf{X}$ . More specifically, we have taken the sample mean of all available instances available.
- (ii)  $\mathbf{U}_2 = X_1$ : While it is unbiased like  $\mathbf{U}_1$ , this is not a sufficient statistics because there are further information (the remaining instances  $X_2, \dots, X_n$ ) that is yet to be utilized in the random sample  $\mathbf{X}$ .

**Example 2.1** (Intuition for “Sufficiency” - A Gaussian Illustration).

Suppose that we are conducting a survey about children’s height. Suppose that the distribution of heights follows a Gaussian distribution  $\mathcal{N}(\mu, \sigma^2)$  and we are given a random sample of size 2:  $X_1, X_2 \sim \mathcal{N}(\mu, \sigma^2)$ . Then, we use the following statistics to make inference about  $\mu$ :

- (i)  $\mathbf{U}_1 = X_1$ , and
- (ii)  $\mathbf{U}_2 = \frac{X_1 + X_2}{2}$ .

Now, we analyse the sufficiency of both  $\mathbf{U}_1, \mathbf{U}_2$  by calculating the conditional density functions  $p_{\mathbf{X}|\mathbf{U}_1}$  and  $p_{\mathbf{X}|\mathbf{U}_2}$  as follows: Let  $\mathbf{x} = \{x_1, x_2\}$  be a particular observation of the random sample  $\mathbf{X}$  and  $\mathbf{u}_1, \mathbf{u}_2$  be values of  $\mathbf{U}_1, \mathbf{U}_2$ . We have

- (i) **Calculation of  $p_{\mathbf{X}|\mathbf{U}_1}(\mathbf{x}|\mathbf{u}_1)$** : Obviously, when  $x_1 \neq \mathbf{u}_1$ , we have  $p_{\mathbf{X}|\mathbf{U}_1}(\mathbf{x}|\mathbf{u}_1) = 0$ . On the other hand, if  $x_1 = \mathbf{u}_1$ , we have

$$\begin{aligned} p_{\mathbf{X}|\mathbf{U}_1}(\mathbf{x}|\mathbf{u}_1) &= \mathbb{P}(X_1 = x_1, X_2 = x_2 | \mathbf{U}_1 = \mathbf{u}_1) \\ &= \mathbb{P}(X_1 = \mathbf{u}_1, X_2 = x_2) \\ &= \frac{1}{2\pi\sigma^2} \exp \left[ -\frac{(\mathbf{u}_1 - \mu)^2 + (x_2 - \mu)^2}{2\sigma^2} \right], \end{aligned}$$

which still depends on  $\mu$ . Therefore,  $\mathbf{U}_1$  is not a sufficient statistics.

- (ii) **Calculation of  $p_{\mathbf{X}|\mathbf{U}_2}(\mathbf{x}|\mathbf{u}_2)$** : Again, when  $x_1 + x_2 \neq \mathbf{u}_2$ ,  $p_{\mathbf{X}|\mathbf{U}_2}(\mathbf{x}|\mathbf{u}_2) = 0$ . Suppose that  $x_1 + x_2 = \mathbf{u}_2$ , using Bayes rule, we have

$$\begin{aligned} p_{\mathbf{X}|\mathbf{U}_2}(\mathbf{x}|\mathbf{u}_2) &= \mathbb{P} \left( X_1 = x_1, X_2 = x_2 \middle| \frac{X_1 + X_2}{2} = \mathbf{u}_2 \right) \\ &= \frac{\mathbb{P}(\mathbf{U}_2 = \mathbf{u}_2 | X_1 = x_1, X_2 = x_2) \mathbb{P}(X_1 = x_1, X_2 = x_2)}{\mathbb{P}(\mathbf{U}_2 = \mathbf{u}_2)} \\ &= \frac{\mathbb{P}(X_1 = x_1, X_2 = x_2)}{\mathbb{P}(\mathbf{U}_2 = \mathbf{u}_2)}. \end{aligned}$$

Note that  $\mathbf{U}_2 \sim \mathcal{N}(\mu, \frac{\sigma^2}{2})$ . Hence, we have:

$$\begin{aligned} p_{\mathbf{X}|\mathbf{U}_2}(\mathbf{x}|\mathbf{u}_2) &= \frac{\frac{1}{2\pi\sigma^2} \exp \left[ -\frac{(x_1 - \mu)^2 + (x_2 - \mu)^2}{2\sigma^2} \right]}{\frac{1}{\sqrt{\pi\sigma^2}} \exp \left[ -\frac{(\mathbf{u}_2 - \mu)^2}{\sigma^2} \right]} \\ &= \frac{1}{2\sigma\sqrt{\pi}} \exp \left[ -\frac{-(x_1 - \mu)^2 + (x_2 - \mu)^2 - 2(\mathbf{u}_2 - \mu)^2}{2\sigma^2} \right] \\ &= \frac{1}{2\sigma\sqrt{\pi}} \exp \left[ -\frac{x_1^2 + x_2^2 - 2\mathbf{u}_2^2}{2\sigma^2} \right]. \end{aligned}$$

Since the above conditional density is independent of  $\mu$ , it is a sufficient statistics for  $\mu$ .

**Example 2.2** (Bernoulli random variables).

Let  $\mathbf{X} = (X_1, \dots, X_n) \sim \text{Bernoulli}(\theta)$  be a random sample from the Bernoulli distribution. Let  $\mathbf{U} = \frac{1}{n} \sum_{i=1}^n X_i$ , then  $\mathbf{U}$  is a sufficient statistic of  $\theta$ . To illustrate this, suppose that  $\mathbf{x} = (x_1, \dots, x_n)$  is an observation of the random sample  $\mathbf{X}$  and  $\mathbf{u} = \frac{1}{n} \sum_{i=1}^n x_i$ . We have:

$$\begin{aligned} \mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}) &= \frac{\mathbb{P}(\mathbf{X} = \mathbf{x}, \mathbf{U} = \mathbf{u})}{\mathbb{P}(\mathbf{U} = \mathbf{u})} \\ &= \frac{\mathbb{P}(X_1 = x_1, \dots, X_n = x_n, \sum_{i=1}^n X_i = \sum_{i=1}^n x_i)}{\mathbb{P}(\sum_{i=1}^n X_i = \sum_{i=1}^n x_i)} \\ &= \frac{\mathbb{P}(X_1 = x_1, \dots, X_n = x_n)}{\mathbb{P}(\sum_{i=1}^n X_i = \sum_{i=1}^n x_i)} \\ &= \frac{\theta^{\sum_{i=1}^n x_i} (1 - \theta)^{n - \sum_{i=1}^n x_i}}{\mathbb{P}(\sum_{i=1}^n X_i = \sum_{i=1}^n x_i)}. \end{aligned}$$

Now, setting  $k = \sum_{i=1}^n x_i$ , The denominator is basically the probability that the Bernoulli variables sums up to  $k$ . Hence, we can calculate the denominator as follows:

$$\mathbb{P}\left(\sum_{i=1}^n X_i = k\right) = \binom{n}{k} \theta^k (1 - \theta)^{n-k}.$$

Therefore, we have:

$$\mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}) = \frac{\theta^k (1 - \theta)^{n-k}}{\binom{n}{k} \theta^k (1 - \theta)^{n-k}} = \frac{1}{\binom{n}{k}}.$$

Therefore, the conditional distribution does not depend on  $\theta$  and  $\mathbf{U}$  is a sufficient statistic.

**Definition 2.3** (Sufficiency Principle).

If  $\mathbf{U} = T(\mathbf{X})$  is a sufficient statistic for  $\theta_*$ , then any inference about  $\theta_*$  should only depend on the sample  $\mathbf{X}$  through  $\mathbf{U}$ . In other words, if we estimate  $\theta_*$  using an estimator  $\hat{\theta}_*$ , only  $\mathbf{U}$  shows up in the formula of  $\hat{\theta}_*$ , not the sample  $\mathbf{X}$  itself. We will see why this is the case in the Factorisation Theorem (**FacT**), which states that we can factorise the density function into a function of  $\mathbf{U}, \theta_*$  and a function of the observations  $\mathbf{x}$  and thus, the inference about  $\theta_*$  is independent of the observations  $\mathbf{x}$ .

#### Theorem 2.1: (Fisher-Neyman) Factorisation Theorem (**FacT**)

Let  $\mathbf{X} = (X_1, \dots, X_n)$  be a random sample with joint density function  $p_{\theta_*}$  over  $\mathcal{X}^n$ . The statistic  $\mathbf{U} = T(\mathbf{X})$  is sufficient for the parameters  $\theta_*$  if and only if we can find functions  $h, g$  such that:

$$p_{\theta_*}(\mathbf{x}) = g(T(\mathbf{x}), \theta_*) h(\mathbf{x}),$$

for all  $\mathbf{x} \in \mathbb{R}^n$  and  $\theta_* \in \Theta$ .

**Proof** (Factorisation Theorem (**FacT**)).

We have to conduct the proof in both directions.

- $T(\mathbf{X})$  is sufficient  $\implies$  Factorisation exists: Let  $\mathbf{U} = T(\mathbf{X})$  be a sufficient statistics and  $\mathbf{u} = T(\mathbf{x})$  be the statistics evaluated on the observations  $\mathbf{x}$ . Then, we have:

$$\begin{aligned} p_{\theta_*}(\mathbf{x}) &= \mathbb{P}(\mathbf{X} = \mathbf{x}; \theta_*) \\ &= \mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}; \theta_*) \mathbb{P}(\mathbf{U} = \mathbf{u}; \theta_*). \end{aligned}$$

Since  $\mathbf{U} = T(\mathbf{X})$  is a sufficient statistics,  $\mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}; \theta_*)$  does not depend on  $\theta_*$ . Hence, we denote  $h(\mathbf{x}) = \mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}; \theta_*)$ . Furthermore,  $\mathbb{P}(\mathbf{U} = \mathbf{u}; \theta_*)$  is a function of  $\mathbf{u}$  and  $\theta_*$ . We denote this function as  $g(\mathbf{u}, \theta_*)$  and conclude that the factorisation  $p_{\theta_*}(\mathbf{x}) = h(\mathbf{x})g(T(\mathbf{x}), \theta_*)$  indeed exists.

- Factorisation exists  $\implies T(\mathbf{X})$  is sufficient: Suppose that there exists  $g, h$  such that we have the factorisation  $p_{\theta_*}(\mathbf{x}) = g(T(\mathbf{x}), \theta_*)h(\mathbf{x})$ . We then have:

$$\mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}; \theta_*) = \frac{p_{\theta_*}(\mathbf{x})}{\mathbb{P}(\mathbf{U} = \mathbf{u}; \theta_*)} = \frac{g(\mathbf{u}, \theta_*)h(\mathbf{x})}{\mathbb{P}(\mathbf{U} = \mathbf{u}; \theta_*)}.$$

We denote  $A_{\mathbf{u}} = \{\tilde{\mathbf{x}} \in \mathcal{X}^n : T(\tilde{\mathbf{x}}) = \mathbf{u}\}$ . We have:

$$\begin{aligned} \mathbb{P}(\mathbf{U} = \mathbf{u}; \theta_*) &= \sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} \mathbb{P}(\mathbf{X} = \tilde{\mathbf{x}}) \\ &= \sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} p(\tilde{\mathbf{x}}; \theta_*) = \sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} g(T(\tilde{\mathbf{x}}), \theta_*)h(\tilde{\mathbf{x}}) \\ &= g(\mathbf{u}, \theta_*) \sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} h(\tilde{\mathbf{x}}). \end{aligned}$$

From the above, we have:

$$\mathbb{P}(\mathbf{X} = \mathbf{x} | \mathbf{U} = \mathbf{u}; \theta_*) = \frac{h(\mathbf{x})}{\sum_{\tilde{\mathbf{x}} \in A_{\mathbf{u}}} h(\tilde{\mathbf{x}})},$$

and the above expression does not depend on  $\theta_*$ . Hence,  $T(\mathbf{X})$  is a sufficient statistics.

□.

### 2.1.2 Bias and Efficiency

### 2.1.3 Consistent Estimator

## 2.2 Important Results

### 2.2.1 Maximum Likelihood Estimation (MLE)

**Definition 2.4** (Likelihood Function).

Let  $\mathbf{X} = (X_1, \dots, X_n)$  be a random sample whose distribution belongs to a family of distributions  $\mathcal{P} = \{p_{\theta} : \theta \in \Theta\}$ . Let  $\mathbf{x} = (x_1, \dots, x_n)$  be an observation of the random sample  $\mathbf{X}$ . Then, the likelihood function  $L(\theta; \mathbf{x})$  is defined as follows:

$$L(\theta; \mathbf{x}) = \prod_{i=1}^n p_{\theta}(x_i), \quad \theta \in \Theta. \quad (45)$$

In some cases, we also use the log-likelihood function:

$$\ell(\theta; \mathbf{x}) = \log L(\theta; \mathbf{x}) = \sum_{i=1}^n \log p_{\theta}(x_i), \quad \theta \in \Theta. \quad (46)$$

Essentially,  $L(\theta; \mathbf{x})$  quantifies the likelihood that  $\theta$  generates the observations  $\mathbf{x}$ . In a way, it is the inverse of probability density (mass) functions, we can see the contrast as follows:

- **Probability Density Function:** The parameters are fixed but the observations are random.
- **Likelihood Function:** The observations are fixed but the parameters are variable.

**Definition 2.5** (Maximum Likelihood Estimator). \_\_\_\_\_

Given  $\mathbf{X} = (X_1, \dots, X_n)$  be a random sample whose distribution belongs to a family of distributions  $\mathcal{P} = \{p_{\theta} : \theta \in \Theta\}$  and let  $\mathbf{x} = (x_1, \dots, x_n)$  be an observation of the random sample  $\mathbf{X}$ . The Maximum Likelihood Estimator  $\theta_{MLE} \in \Theta$  is the parameter that maximizes the likelihood function:

$$\theta_{MLE} = \arg \max_{\theta \in \Theta} L(\theta; \mathbf{x}). \quad (47)$$

In the subsequent propositions, we will discuss some of the key properties of MLE.

#### Proposition 2.1: Consistency of MLE

Let  $\mathbf{X} = (X_1, \dots, X_n)$  be a random sample from a distribution  $p_{\theta_*}$  over  $\mathcal{X}$  dependent on a true set of parameters  $\theta_*$ . Let  $\Theta$  be the parameters space. Then, the Maximum Likelihood Estimator  $\Theta_{MLE} = \arg \max_{\theta \in \Theta} L(\theta; \mathbf{X})$ , which is a random variable, is consistent, meaning  $\Theta_{MLE} \xrightarrow{p} \theta_*$ , provided that the following conditions are met:

1.  $\theta_* \in \Theta$  and  $\Theta$  is a compact space.
2.  $\log p_{\theta}(x)$  is continuous in  $\theta$  for almost all  $x \in \mathcal{X}$ .
3.  $\mathbb{E}_{\theta_*}[\sup_{\theta \in \Theta} |\log p_{\theta}(X)|] < \infty$ .
4. The mapping  $\xi \mapsto p_{\xi}$ ,  $\xi \in \Theta$  is one-to-one (Identifiability).<sup>a</sup>

Furthermore, we can also show that  $\Theta_{MLE}$  is asymptotically unbiased. In other words,  $\lim_{n \rightarrow \infty} \mathbb{E}[\Theta_{MLE}] = \theta_*$ .

<sup>a</sup>In general, it is required that the model is strongly identifiable. However, since the parameters space  $\Theta$  is compact, this requirement is satisfied.

**Proof** (Proposition 2.1). \_\_\_\_\_

A proof for consistency of MLE can be found in “Chapter 36 Large sample estimation and hypothesis testing” 1994, Theorem 2.5 but we attempt our own proof anyway. The general proof strategy is listed below:

1. First, prove that  $\theta_* = \arg \max_{\xi \in \Theta} \mathbb{E}_{\theta_*}[\log p_{\xi}(X)]$ .
2. Then, by (ULLN):  $\frac{1}{n} \sum_{i=1}^n \log p_{\theta}(X_i) \xrightarrow{p} \mathbb{E}_{\theta_*}[\log p_{\theta}(X)]$ ,  $\forall \theta \in \Theta$ .
3. Prove that if a stochastic process converges in probability to a deterministic process, then the maximizers of the stochastic process converges in probability to the maximizer of the deterministic process.

To complete the proof, it is sufficient to prove the first point. For any  $\theta \in \Theta$ , we have:

$$\mathbb{E}_{\theta_*} \left[ \log \frac{p_\theta(X)}{p_{\theta_*}(X)} \right] \leq \log \mathbb{E}_{\theta_*} \left[ \frac{p_\theta(X)}{p_{\theta_*}(X)} \right] = \log \int_{\mathcal{X}} \frac{p_\theta(x)}{p_{\theta_*}(x)} p_{\theta_*}(x) dx = \log 1 = 0.$$

Therefore, for all  $\theta \in \Theta$ :  $\mathbb{E}_{\theta_*}[\log p_\theta(X)] \leq \mathbb{E}_{\theta_*}[\log p_{\theta_*}(X)]$ . Hence,  $\theta_* = \arg \max_{\xi \in \Theta} \mathbb{E}_{\theta_*}[\log p_\xi(X)]$  as desired. Define the following continuous mappings:

$$M_n = \xi \mapsto \frac{1}{n} \sum_{i=1}^n \log p_\xi(X_i),$$

and  $M = \xi \mapsto \mathbb{E}_{\theta_*}[\log p_\xi(X)]$ .

Then, by **(ULLN)**, we have  $\|M_n - M\|_\infty \xrightarrow{p} 0$ . This means that for any fixed  $\epsilon > 0$  and  $\delta \in (0, 1)$ , there exists  $N \in \mathbb{N}$  such that for all  $n \geq N$ , with probability of at least  $1 - \delta$ , we have:

$$|M_n(\hat{\theta}_n) - M(\hat{\theta}_n)| < \frac{\epsilon}{2}, \quad \text{and} \quad |M_n(\theta_*) - M(\theta_*)| < \frac{\epsilon}{2},$$

simultaneously, where  $\hat{\theta}_n = \arg \max_{\theta \in \Theta} M_n(\theta)$ . From the above, with probability of at least  $1 - \delta$ , we have:

$$M(\hat{\theta}_n) \geq M_n(\hat{\theta}_n) - \frac{\epsilon}{2} \geq M_n(\theta_*) - \frac{\epsilon}{2} \geq M(\theta_*) - \epsilon.$$

Hence, we have  $M(\theta_*) - M(\hat{\theta}_n) < \epsilon$  with high probability. Since  $M$  is continuous on a compact space, for all  $\epsilon > 0$ , there exists a constant  $\xi > 0$  such that  $|\theta - \theta_*| < \xi \implies |M(\theta_*) - M(\theta)| < \epsilon$ . Hence, we have:

$$\mathbb{P}(|\theta_* - \hat{\theta}_n| < \xi) = \mathbb{P}(|M(\theta_*) - M(\hat{\theta}_n)| < \epsilon) \geq 1 - \delta.$$

Hence, we have  $|\theta_* - \hat{\theta}_n| < \xi$  with high probability. Since  $\delta$  is chosen arbitrarily, we can take  $\delta \rightarrow 0$  and for all  $\xi > 0$ , we have:

$$\lim_{n \rightarrow \infty} \mathbb{P}(|\theta_* - \hat{\theta}_n| < \xi) = 1 \implies \hat{\theta}_n \xrightarrow{p} \theta_*.$$

□.

### Proposition 2.2: Asymptotic Normality of MLE

Let  $\mathbf{X} = (X_1, \dots, X_n)$  be a random sample from a distribution  $p_{\theta_*}$  dependent on a true set of parameters  $\theta_*$ . Suppose that the MLE is consistent. Then, the Maximum Likelihood Estimator  $\Theta_{\text{MLE}} = \arg \max_{\theta \in \Theta} L(\theta; \mathbf{X})$  is asymptotically normal:

$$\sqrt{n}(\Theta_{\text{MLE}} - \theta_*) \xrightarrow{d} \mathcal{N}(0, \mathcal{I}_{\mathbf{X}}(\theta_*)^{-1}). \quad (48)$$

**Proof** (Proposition 2.2).

By the Mean Value Theorem, for a continuous function  $f : [a, b] \rightarrow \mathbb{R}$ , we have:

$$\frac{f(b) - f(a)}{b - a} = f'(c), \quad \text{for some } c \in [a, b].$$

Apply MVT for the log-likelihood function, for some  $\varphi_n$  within the interval formed by  $\hat{\Theta}_{\text{MLE}}$  and  $\theta_*$  (hence,  $\varphi_n$  is a random variable since  $\hat{\Theta}_{\text{MLE}}$  is random), we have:

$$\ell''(\varphi_n; \mathbf{X}) = \frac{\ell'(\hat{\Theta}_{\text{MLE}}; \mathbf{X}) - \ell'(\theta_*; \mathbf{X})}{\hat{\Theta}_{\text{MLE}} - \theta_*} = -\frac{\ell'(\theta_*; \mathbf{X})}{\hat{\Theta}_{\text{MLE}} - \theta_*} \quad \left( \ell'(\hat{\Theta}_{\text{MLE}}; \mathbf{X}) = 0 \right).$$

Therefore, we have:

$$\hat{\Theta}_{\text{MLE}} - \theta_* = -\frac{\ell'(\theta_*; \mathbf{X})}{\ell''(\varphi_n; \mathbf{X})} \implies \sqrt{n}(\hat{\Theta}_{\text{MLE}} - \theta_*) = -\frac{\frac{1}{\sqrt{n}}\ell'(\theta_*; \mathbf{X})}{\frac{1}{n}\ell''(\varphi_n; \mathbf{X})}. \quad (\text{A})$$

We have:

$$\begin{aligned} \frac{1}{\sqrt{n}}\ell'(\theta_*; \mathbf{X}) &= \sqrt{n} \left[ \frac{1}{n} \sum_{i=1}^n \frac{d}{d\xi} \ln p_\xi(X_i) \right]_{\xi=\theta_*} \\ &= \sqrt{n} \left[ \frac{1}{n} \sum_{i=1}^n s(\theta_*; X_i) \right] \\ &= \sqrt{n} \left[ \frac{1}{n} \sum_{i=1}^n s(\theta_*; X_i) - \underbrace{\mathbb{E}_{\theta_*}[s(\theta_*; X)]}_0 \right] \\ &\xrightarrow{d} \mathcal{N}(0, \text{Var}_{\theta_*}[s(\theta_*; X)]) \quad (\text{CLT}) \\ &= \mathcal{N}(0, \mathcal{I}_{\mathbf{X}}(\theta_*)). \end{aligned} \quad (\text{B})$$

We also have:

$$\frac{1}{n}\ell''(\varphi_n; \mathbf{X}) = \frac{1}{n} \sum_{i=1}^n \frac{d^2}{d\xi^2} \ln p_\xi(X_i) \Big|_{\xi=\varphi_n} \xrightarrow{p} \mathbb{E}_{\theta_*} \left[ \frac{d^2}{d\xi^2} \ln p_\xi(X) \Big|_{\xi=\varphi_n} \right]. \quad (\text{WLLN})$$

By the initial assumption,  $\hat{\Theta}_{\text{MLE}} \xrightarrow{p} \theta_*$  and  $\varphi_n$  lies between  $\hat{\Theta}_{\text{MLE}}$  and  $\theta_*$ . Therefore,  $\varphi_n \xrightarrow{p} \theta_*$ . As a result, by **(CMT)**<sup>3</sup>, we have  $\mathbb{E}_{\theta_*} \left[ \frac{d^2}{d\xi^2} \ln p_\xi(X) \Big|_{\xi=\varphi_n} \right] \xrightarrow{p} \mathbb{E}_{\theta_*} \left[ \frac{d^2}{d\xi^2} \ln p_\xi(X) \Big|_{\xi=\theta_*} \right] = -\mathcal{I}_{\mathbf{X}}(\theta_*)$ .

Therefore, we have:

$$\frac{1}{n}\ell''(\varphi_n; \mathbf{X}) \xrightarrow{p} \mathbb{E}_{\theta_*} \left[ \frac{d^2}{d\xi^2} \ln p_\xi(X) \Big|_{\xi=\varphi_n} \right] \xrightarrow{p} -\mathcal{I}_{\mathbf{X}}(\theta_*). \quad (\text{C})$$

From Eqns. A, B, C and **(SLUTSKY)** lemma, we have  $\sqrt{n}(\hat{\Theta}_{\text{MLE}} - \theta_*) \xrightarrow{d} \mathcal{N}(0, \mathcal{I}_{\mathbf{X}}(\theta_*)^{-1})$ , as desired.  $\square$ .

## 2.2.2 Rao-Blackwell Theorem

### Theorem 2.2: Rao-Blackwell Theorem **(RB)**

## 2.2.3 Cramer-Rao Lower Bound

**Definition 2.6** (Fisher Information).

Let  $\mathbf{X} = (X_1, \dots, X_n) \sim p_{\theta_*}$  be a random sample from a distribution  $p_{\theta_*}$  with the true unknown parameter  $\theta_*$ . The Fisher Information about  $\theta_*$  in the random sample  $\mathbf{X}$  is defined as follows:

$$\mathcal{I}_{\mathbf{X}}(\theta_*) = \mathbb{E}_{\theta_*} \left[ \left( \frac{\partial}{\partial \xi} \log L(\xi; \mathbf{X}) \Big|_{\xi=\theta_*} \right)^2 \right], \quad (49)$$

where  $\mathbb{E}_{\theta_*}$  denotes the expectation conditioned on  $\theta_*$ . The Fisher Information is the total information about  $\theta_*$  contained in the sample  $\mathbf{X}$ .

<sup>3</sup>The mapping  $p \mapsto \mathbb{E}_{\theta_*} \left[ \frac{d^2}{d\xi^2} \ln p_\xi(X) \Big|_{\xi=p} \right]$  is a continuous mapping by the initial assumption that  $p_\theta$  is continuous in  $\theta$  for  $\theta \in \Theta$ .



**Remark 2.2.**


---

*Some Notes on Fisher Information:*

1. The expectation  $\mathbb{E}_\theta$  conditioned on  $\theta$  means that the expectation is taken over the sample  $\mathbf{X}$  under the hypothesis that  $\theta$  is the true parameter of all the  $X_i$ 's.
2. Inside the expectation is the score function evaluated at  $\theta_*$ .
3. From two points above, the Fisher Information is essentially calculated as **the variance conditioned on  $\theta_*$  of the score evaluated at  $\theta_*$** .

**Proposition 2.3: Alternative Representation of Fisher Information**

Let  $\mathbf{X} = (X_1, \dots, X_n) \sim p_{\theta_*}$  be a random sample from a distribution parameterized by a true unknown parameter  $\theta_*$ . Let  $\ell(\theta; \mathbf{X}) = \log L(\theta; \mathbf{X})$  be the log-likelihood function. Then, we have:

$$\mathcal{I}_{\mathbf{X}}(\theta_*) = \text{Var}(s(\theta_*; \mathbf{X})), \quad (50)$$

where  $s(\theta_*; \mathbf{X}) = \frac{\partial \ell(\theta_*; \mathbf{X})}{\partial \theta_*}$  is the score evaluated at the true parameter  $\theta_*$ . Furthermore, we have:

$$\mathcal{I}_{\mathbf{X}}(\theta_*) = -\mathbb{E}_{\theta_*} \left[ \frac{\partial^2}{\partial \xi^2} \ell(\xi; \mathbf{X}) \Big|_{\xi=\theta_*} \right]. \quad (51)$$

**Proof** (Proposition 2.3).

---

Denote  $s(\theta_*; \mathbf{X})$  as the score evaluated at the true parameter  $\theta_*$ , we have:

$$\begin{aligned} \text{Var}(s(\theta_*; \mathbf{X})) &= \mathbb{E}_{\theta_*} \left[ \left( \frac{\partial}{\partial \xi} \ell(\xi; \mathbf{X}) \Big|_{\xi=\theta_*} \right)^2 \right] - \mathbb{E}_{\theta_*} \left[ \frac{\partial}{\partial \xi} \ell(\xi; \mathbf{X}) \Big|_{\xi=\theta_*} \right]^2 \\ &= \mathcal{I}_{\mathbf{X}}(\theta_*) - \mathbb{E}_{\theta_*} \left[ \frac{1}{n} \sum_{i=1}^n \frac{\partial \log p_{\xi}(X_i)}{\partial \xi} \Big|_{\xi=\theta_*} \right] \\ &= \mathcal{I}_{\mathbf{X}}(\theta_*) - \mathbb{E}_{\theta_*} [s(\theta_*; X)]^2, \end{aligned}$$

where  $X$  is identically distributed as  $X_1, \dots, X_n$ . We claim that  $\mathbb{E}_{\theta_*} [s(\theta_*; X)] = 0$ . Let  $\chi$  be the sample space, we have:

$$\begin{aligned} \mathbb{E}_{\theta_*} [s(\theta_*; X)] &= \int_{\chi} p_{\theta_*}(x) \frac{\partial \log p_{\xi}(x)}{\partial \xi} \Big|_{\xi=\theta_*} dx \\ &= \int_{\chi} p_{\theta_*}(x) \cdot \frac{1}{p_{\theta_*}(x)} \frac{\partial p_{\theta_*}(x)}{\partial \theta_*} dx \\ &= \int_{\chi} \frac{\partial p_{\theta_*}(x)}{\partial \theta_*} dx \\ &= \frac{\partial}{\partial \theta_*} \int_{\chi} p_{\theta_*}(x) dx = \frac{\partial}{\partial \theta_*} 1 = 0. \quad (\text{Leibniz's Differentiation Rule}) \end{aligned}$$

Therefore, we have  $\boxed{\mathcal{I}_{\mathbf{X}}(\theta_*) = \text{Var}(s(\theta_*; \mathbf{X}))}$ . Now, we prove the second point:  $\mathcal{I}_{\mathbf{X}}(\theta_*) = -\mathbb{E}_{\theta_*} \left[ \frac{\partial^2}{\partial \xi^2} \ell(\xi; \mathbf{X}) \Big|_{\xi=\theta_*} \right]$ .

Expanding  $\frac{\partial^2}{\partial \xi^2} \ell(\xi; \mathbf{X}) \Big|_{\xi=\theta_*}$ , we have:

$$\begin{aligned}
\frac{\partial^2}{\partial \xi^2} \ell(\xi; \mathbf{X}) \Big|_{\xi=\theta_*} &= \frac{\partial}{\partial \theta_*} \left[ \frac{\partial}{\partial \theta_*} \ell(\theta_*; \mathbf{X}) \right] \\
&= \frac{\partial}{\partial \theta_*} \left[ \frac{1}{L(\theta_*; \mathbf{X})} \frac{\partial}{\partial \theta_*} L(\theta_*; \mathbf{X}) \right] \\
&= -\frac{1}{L(\theta_*; \mathbf{X})^2} \left[ \frac{\partial}{\partial \theta_*} L(\theta_*; \mathbf{X}) \right]^2 + \frac{1}{L(\theta_*; \mathbf{X})} \frac{\partial^2 L(\theta_*; \mathbf{X})}{\partial \theta_*^2} \\
&= -\left[ \frac{\partial}{\partial \theta_*} \ell(\theta_*; \mathbf{X}) \right]^2 + \frac{1}{L(\theta_*; \mathbf{X})} \frac{\partial^2 L(\theta_*; \mathbf{X})}{\partial \theta_*^2}.
\end{aligned}$$

Now, let  $P_{\theta_*}$  be the probability density function for the random sample  $\mathbf{X}$ . Then, essentially,  $P_{\theta_*}(\mathbf{X}) = L(\theta_*; \mathbf{X})$ . Therefore, we have:

$$\begin{aligned}
\mathbb{E}_{\mathbf{X} \sim P_{\theta_*}} \left[ \frac{1}{L(\theta_*; \mathbf{X})} \frac{\partial^2 L(\theta_*; \mathbf{X})}{\partial \theta_*^2} \right] &= \int_{\mathcal{X}^n} \frac{1}{L(\theta_*; \mathbf{x})} \frac{\partial^2 L(\theta_*; \mathbf{x})}{\partial \theta_*^2} P_{\theta_*}(\mathbf{x}) d\mathbf{x} \\
&= \int_{\mathcal{X}^n} \frac{\partial^2 L(\theta_*; \mathbf{x})}{\partial \theta_*^2} d\mathbf{x} \\
&= \frac{\partial^2}{\partial \theta_*^2} \int_{\mathcal{X}^n} L(\theta_*; \mathbf{x}) d\mathbf{x} \quad (\text{Leibniz's Differentiation Rule}) \\
&= \frac{\partial^2}{\partial \theta_*^2} 1 = 0.
\end{aligned}$$

Therefore, we have:

$$-\mathbb{E}_{\theta_*} \left[ \frac{\partial^2}{\partial \xi^2} \ell(\xi; \mathbf{X}) \Big|_{\xi=\theta_*} \right] = \mathbb{E}_{\theta_*} \left[ \left( \frac{\partial}{\partial \theta_*} \ell(\theta_*; \mathbf{X}) \right)^2 \right] = \mathcal{I}_{\mathbf{X}}(\theta_*),$$

as desired.  $\square$ .

**Remark 2.3** (Exchanging Derivative and Integral).

Note that in the proof of proposition 2.3, we exchanged the integration and the partial derivative to prove that  $\mathbb{E}_{\theta_*}[s(\theta_*; \mathbf{X})] = 0$ . This exchange of differentiation and integral can be done under certain conditions, which are listed in the appendix, section I.1.

### Theorem 2.3: Cramer-Rao Lower Bound (CRLB)

Let  $\mathbf{X} = \{X_1, \dots, X_n\}$  be a random sample where  $X_i \sim p_{\theta_*}$ . If  $\hat{\Theta}(\mathbf{X})$  is an estimator (biased or unbiased) for  $\theta_*$  based on the random sample  $\mathbf{X}$ , then, we have:

$$\text{Var}(\hat{\Theta}(\mathbf{X})) \geq \mathcal{I}_{\mathbf{X}}(\theta_*)^{-1} \left[ \frac{d}{d\theta_*} \mathbb{E}[\hat{\Theta}(\mathbf{X})] \right]^2. \quad (52)$$

When  $\hat{\Theta}$  is unbiased, we have  $\mathbb{E}[\hat{\Theta}(\mathbf{X})] = \theta_*$ . Hence, we have  $\boxed{\text{Var}(\hat{\Theta}(\mathbf{X})) \geq \mathcal{I}_{\mathbf{X}}(\theta_*)^{-1}}$ .

**Proof** (Cramer-Rao Lower Bound (**CRLB**)).

We make use of the following covariance inequality: For two random variables  $X, Y$ , the following inequality holds

$$\text{Cov}(X, Y)^2 \leq \text{Var}(X) \cdot \text{Var}(Y). \quad (53)$$

We denote  $X, Y$  as follows:

$$X = \hat{\Theta}(\mathbf{X}); \quad Y = s(\boldsymbol{\theta}_*; \mathbf{X}).$$

Applying the above inequality, we have:

$$\text{Var}(\hat{\Theta}(\mathbf{X})) \geq \frac{\text{Cov}(\hat{\Theta}(\mathbf{X}), s(\boldsymbol{\theta}_*; \mathbf{X}))}{\text{Var}(s(\boldsymbol{\theta}_*; \mathbf{X}))} = \mathcal{I}_{\mathbf{X}}(\boldsymbol{\theta}_*)^{-1} \text{Cov}(\hat{\Theta}(\mathbf{X}), s(\boldsymbol{\theta}_*; \mathbf{X})).$$

Now, we derive the lower bound for  $\text{Cov}(\hat{\Theta}(\mathbf{X}), s(\boldsymbol{\theta}_*; \mathbf{X}))$ . Suppose that the random variables  $X_i$  maps from a sample space to  $\chi$  and  $P_{\boldsymbol{\theta}_*} : \chi^n \rightarrow [0, 1]$  is the probability density for the random sample  $\mathbf{X}$ , we have:

$$\begin{aligned} \text{Cov}(\hat{\Theta}(\mathbf{X}), s(\boldsymbol{\theta}_*; \mathbf{X})) &= \mathbb{E}[\hat{\Theta}(\mathbf{X})s(\boldsymbol{\theta}_*; \mathbf{X})] - \underbrace{\mathbb{E}[\hat{\Theta}(\mathbf{X})]\mathbb{E}[s(\boldsymbol{\theta}_*; \mathbf{X})]}_{\text{Equals 0}} \\ &= \int_{\chi^n} \hat{\Theta}(\mathbf{x})s(\boldsymbol{\theta}_*; \mathbf{x})P_{\boldsymbol{\theta}_*}(\mathbf{x})d\mathbf{x} \\ &= \int_{\chi^n} \hat{\Theta}(\mathbf{x})\frac{d}{d\boldsymbol{\theta}_*} \ln L(\boldsymbol{\theta}_*; \mathbf{x})P_{\boldsymbol{\theta}_*}(\mathbf{x})d\mathbf{x} \\ &= \int_{\chi^n} \hat{\Theta}(\mathbf{x})\frac{\frac{d}{d\boldsymbol{\theta}_*} L(\boldsymbol{\theta}_*; \mathbf{x})}{L(\boldsymbol{\theta}_*; \mathbf{x})}P_{\boldsymbol{\theta}_*}(\mathbf{x})d\mathbf{x} \\ &= \int_{\chi^n} \hat{\Theta}(\mathbf{x})\frac{d}{d\boldsymbol{\theta}_*} L(\boldsymbol{\theta}_*; \mathbf{x})d\mathbf{x} \quad (L(\boldsymbol{\theta}_*; \mathbf{x}) = P_{\boldsymbol{\theta}_*}(\mathbf{x})) \\ &= \frac{d}{d\boldsymbol{\theta}_*} \int_{\chi^n} \hat{\Theta}(\mathbf{x})L(\boldsymbol{\theta}_*; \mathbf{x})d\mathbf{x} \quad (\text{Leibniz Differentiation Rule}) \\ &= \frac{d}{d\boldsymbol{\theta}_*} \mathbb{E}[\hat{\Theta}(\mathbf{X})]. \end{aligned}$$

Hence, we obtain the desired lower bound. □.

## 3 Concentration Inequalities

### 3.1 Sub-Gaussian Distributions

A random variable  $X$  is called “sub-Gaussian” if its distribution has a strong tail decay similar to that of a Gaussian distribution. More precisely, the tail of  $X$ ’s probability density/mass function is dominated by the tail of a Gaussian distribution, hence the name “sub-Gaussian”.

Sub-Gaussian is a particularly interesting family of random variables because by modelling random events using sub-Gaussian distributions, we can bound the probability of very rare events happening at the tail. Furthermore, sub-Gaussianity implies the following properties:

- (i) Bounded **tail probability**.
- (ii) Bounded **moment**.
- (iii) Bounded **moment generating function** (for  $X$  and  $X^2$ ).
- (iv) Bounded **sub-Gaussian norm\***.

**Definition 3.1** (Sub-Gaussian Random Variable). 

---

A random variable  $X$  is called sub-Gaussian if there exists a constant  $C > 0$  such that:

$$\mathbb{P}(|X| \geq t) \leq 2 \exp(-t^2/C^2). \quad (54)$$

**Definition 3.2** (Sub-Gaussian Norm). 

---

Let  $X$  be a random variable. Then, we denote the sub-Gaussian norm of  $X$  as:

$$\|X\|_{\psi_2} = \inf \left\{ t > 0 : \mathbb{E} \left[ \exp \left( X^2/t^2 \right) \right] \leq 2 \right\}. \quad (55)$$

From the above definition and the definition of sub-Gaussian variables, we can deduce that  $X$  is sub-Gaussian if and only if  $\|X\|_{\psi_2} < \infty$ . Furthermore, the intuition behind  $\|\cdot\|_{\psi_2}$  norm is that it measures the light-tailed-ness of a random variable. In other words, **the smaller the sub-Gaussian norm, the faster the tail decays**.

**Definition 3.3** (Sub-Gaussian Variance Proxy). 

---

Let  $X$  be a sub-Gaussian random variable. Then, we say that  $X$  is sub-Gaussian with variance proxy  $\sigma^2$  if:

$$M_X(\lambda) \leq \exp(\lambda^2 \sigma^2 / 2), \quad \forall \lambda \in \mathbb{R}. \quad (56)$$

We denote that  $X \in \mathcal{G}(\sigma^2)$ .

### Proposition 3.1: Properties of Sub-Gaussian Variables

Let  $X$  be a random variable with mean  $\mu$ . Then, the following properties are equivalent:

- (i) **Sub-Gaussianity (bounded tail probability)**: There exists  $K_1 > 0$  such that

$$\mathbb{P}(|X| \geq t) \leq 2 \exp\left(-\frac{t^2}{K_1^2}\right). \quad (57)$$

- (ii) **Bounded  $p$ -moment**: There exists  $K_2 > 0$  such that

$$\|X\|_{L^p} = (\mathbb{E}|X|^p)^{1/p} \leq K_2 \sqrt{p}, \quad \forall p \geq 1. \quad (58)$$

- (iii) **Bounded MGF (of  $X^2$ )**: There exists  $K_3 > 0$  such that

$$M_{X^2}(\lambda^2) \leq \exp(K_3^2 \lambda^2), \quad \forall \lambda \in \mathbb{R} \text{ and } |\lambda| < \frac{1}{K_3}. \quad (59)$$

- (iv) **Bounded MGF (of  $X$ )**: There exists  $K_4 > 0$  such that

$$M_{X-\mu}(\lambda) \leq \exp(K_4^2 \lambda^2), \quad \forall \lambda \in \mathbb{R}. \quad (60)$$

In other words,  $X - \mu$  has a variance proxy of  $\sigma^2 \leq 2K_4^2$ .

- (v) **Bounded sub-Gaussian norm**: There exists  $K_5 > 0$  such that

$$\mathbb{E}\left[\exp\left(X^2/K_5^2\right)\right] \leq 2. \quad (61)$$

In other words,  $\|X\|_{\psi_2} \leq K_5$ .

The parameters  $K_1, \dots, K_5$  differ from each other by at most an absolute constant. Meaning, there exists a constant  $C$  independent of  $K_1, \dots, K_5$  such that  $K_i \leq CK_j$  for any two  $i, j \in \{1, \dots, 5\}$ .

#### Proof (Proposition 3.1).

We prove that (i)  $\implies$  (ii)  $\implies$  (iii)  $\implies$  (v) then prove that (v)  $\implies$  (i). This means that the statements (i), (ii), (iii), (v) are equivalent. Then, we prove that (ii)  $\iff$  (iv). Without loss of generality, assume that  $K_1 = 1$  because we can rescale  $X$  to  $X/K_1$ .

1. (i)  $\implies$  (ii): By the integral identity for  $p^{\text{th}}$  moments, we have

$$\begin{aligned} \mathbb{E}|X|^p &= \int_0^\infty pt^{p-1} \mathbb{P}(|X| > t) dt \\ &\leq 2p \int_0^\infty t^{p-1} e^{-t^2} dt. \end{aligned}$$

Recall that  $\Gamma(z) = \int_0^\infty u^{z-1} e^{-u} du$ . By the change of variable, let  $u = t^2$  (then, we have  $du = 2t dt$ ). We have:

$$\begin{aligned} \mathbb{E}|X|^p &\leq p \int_0^\infty (\sqrt{u})^{p-2} e^{-u} du \\ &= p \int_0^\infty u^{p/2-1} e^{-u} du = p\Gamma(p/2). \end{aligned}$$

Since  $\Gamma(z) < 3z^z$  for all  $z \geq 1/2$ , we have  $\mathbb{E}|X|^p \leq 3p(p/2)^{p/2}$ . Taking  $p^{\text{th}}$  root from both sides, we can have  $K_2 = 3$  since  $[3p(p/2)^{p/2}]^{1/p} \leq 3\sqrt{p}$ .

2. (ii)  $\implies$  (iii): Using the identity  $e^x = 1 + \sum_{k=1}^{\infty} \frac{x^k}{k!}$ , we have:

$$\begin{aligned} M_{X^2}(\lambda^2) &= \mathbb{E} \exp(X^2 \lambda^2) \\ &= \mathbb{E} \left[ 1 + \sum_{k=1}^{\infty} \frac{(\lambda^2 X^2)^k}{k!} \right] \\ &= 1 + \sum_{k=1}^{\infty} \frac{\lambda^{2k} \mathbb{E}[X^{2k}]}{k!}. \end{aligned}$$

By property (ii), we have  $\mathbb{E}[X^{2k}] \leq K_2^{2k} (2k)^k$ . By Stirling's approximation, we have  $k! \geq (k/e)^k$ . Combining the bounds, we have:

$$M_{X^2}(\lambda^2) \leq 1 + \sum_{k=1}^{\infty} \frac{\lambda^{2k} K_2^{2k} (2k)^k}{(k/e)^k} = 1 + \sum_{k=1}^{\infty} \frac{(2k \lambda^2 K_2^2)^k}{(k/e)^k} = 1 + \sum_{k=1}^{\infty} (2e \lambda^2 K_2^2)^k.$$

When  $2e \lambda^2 K_2^2 < 1$ , we have the sum of geometric series that converges to  $\frac{1}{1-2e \lambda^2 K_2^2}$ . Hence, we need  $|\lambda| < \frac{1}{K_2 \sqrt{2e}}$ . Therefore, property (iii) holds with  $K_3 = K_2 \sqrt{2e}$ .

3. (iii)  $\implies$  (v): Let  $K_5 = \frac{K_3}{\sqrt{\ln 2}}$  and set  $\lambda = \frac{1}{K_5}$ . Since  $K_5^{-1} < \frac{1}{K_3}$ , statement (iii) holds with  $\lambda = K_5^{-1}$ . Therefore:

$$\mathbb{E} \exp \left[ X^2 / K_5^2 \right] \leq \exp(K_3^2 / K_5^2) = \exp(\ln 2) = 2.$$

4. (v)  $\implies$  (i): Let  $K_5 > 0$  be the constant that makes (v) hold. We have

$$\begin{aligned} \mathbb{P}(|X| \geq t) &= \mathbb{P}(X^2 \geq t^2) \\ &= \mathbb{P}\left(e^{X^2/K_5^2} \geq e^{t^2/K_5^2}\right) \\ &\leq \exp\left(-\frac{t^2}{K_5^2}\right) \mathbb{E}\left[e^{X^2/K_5^2}\right] \quad (\text{Markov's Inequality}) \\ &\leq 2 \exp\left(-\frac{t^2}{K_5^2}\right). \end{aligned}$$

Hence, (i) holds with  $K_1 \geq K_5$ . From here on, we have proved that the statements (i), (ii), (iii) and (v) are equivalent.

5. (i)  $\iff$  (iv): This relationship is proven below in theorem 3.1.

□.

### Theorem 3.1: Bounded Tail Probability $\iff \mathcal{SG}$ (BTP – SG)

Let  $X$  be a random variable with mean  $\mathbb{E}[X] = \mu$  and  $Z$  be the centered random variable  $Z = X - \mu$ . Then, for all  $t \in \mathbb{R}$ ,

- (i)  $Z \in \mathcal{SG}(\sigma^2) \implies \mathbb{P}(|X - \mu| \geq t) \leq 2 \exp\left(-\frac{t^2}{2\sigma^2}\right)$  for some  $\sigma > 0$ .
- (ii)  $\mathbb{P}(|X - \mu| \geq t) \leq 2 \exp\left(-\frac{t^2}{2\xi^2}\right) \implies Z \in \mathcal{SG}(16\xi^2)$  for some  $\xi > 0$ .

**Proof** (Theorem **(BTP – SG)**).

We prove each bullet point one by one.

- (i) From the definition, for all  $\lambda \in \mathbb{R}$ , we have  $M_Z(\lambda) = \mathbb{E} \exp[\lambda Z] \leq \exp\left(\frac{\lambda^2 \sigma^2}{2}\right)$ . For  $\lambda > 0$  and for all  $t > 0$ , we have:

$$\begin{aligned} \mathbb{P}(|X - \mu| \geq t) &= \mathbb{P}\left(\left\{X - \mu \geq t\right\} \vee \left\{X - \mu \leq -t\right\}\right) \\ &\leq \mathbb{P}(Z \geq t) + \mathbb{P}(Z \leq -t) \\ &= \mathbb{P}(e^{\lambda Z} \geq e^{\lambda t}) + \mathbb{P}(Z \leq -t) \end{aligned}$$

Then, we have the following inequalities:

$$\begin{cases} \mathbb{P}(e^{\lambda Z} \geq e^{\lambda t}) &\leq e^{-\lambda t} M_Z(\lambda) & (\text{Markov's Inequality}) \\ \mathbb{P}(Z \leq -t) &\leq e^{-\lambda t} M_Z(-\lambda) & (\text{Chernoff's Bound}) \end{cases},$$

where the second inequality comes from the left-tail Chernoff's Bound<sup>4</sup>. As a result, we have:

$$\begin{aligned} \mathbb{P}(|X - \mu| \geq t) &\leq e^{-\lambda t} [M_Z(\lambda) + M_Z(-\lambda)] \\ &\leq 2e^{-\lambda t} \exp\left(\frac{\lambda^2 \sigma^2}{2}\right) \\ &= 2 \exp\left(-\lambda t + \frac{\lambda^2 \sigma^2}{2}\right). \end{aligned}$$

Using Lagrange multiplier to solve for  $\lambda$ , we have  $\lambda = \frac{t}{\sigma^2}$ . Hence, we have:

$$\mathbb{P}(|X - \mu| \geq t) \leq 2 \exp\left(-\frac{t^2}{2\sigma^2}\right).$$

- (ii) Firstly, we prove that bounded tail probability implies that  $\mathbb{E}|Z|^{2q} \leq q!(4\xi^2)^q$  for all integers  $q \geq 1$ . Using the identity  $\mathbb{E}|Z|^q = \int_0^\infty q t^{q-1} \mathbb{P}(|Z| \geq t) dt$ , we have:

$$\begin{aligned} \mathbb{E}|Z|^{2q} &= 2q \int_0^\infty t^{2q-1} \mathbb{P}(|Z| \geq t) dt \\ &\leq 4q \int_0^\infty t^{2q-1} \exp\left(-\frac{t^2}{2\xi^2}\right) dt. \end{aligned}$$

Letting  $u = \frac{t^2}{2\xi^2}$ , hence  $t^2 = 2u\xi^2$  and  $dt = \frac{\xi^2 du}{t}$ , the above integral becomes:

$$\begin{aligned} \mathbb{E}|Z|^{2q} &\leq 4q\xi^2 \int_0^\infty t^{2q-2} e^{-u} du \\ &= 4q\xi^2 \int_0^\infty (2u\xi^2)^{q-1} e^{-u} du \\ &= 2q \cdot (2\xi^2)^q \underbrace{\int_0^\infty u^{q-1} e^{-u} du}_{\Gamma(q)} \\ &= 2q!(2\xi^2)^q \leq q!(4\xi^2)^q. \end{aligned}$$

---

<sup>4</sup> $\mathbb{P}(X \leq a) \leq e^{-sa} M_X(s)$  for all  $s < 0$ . Hence,  $\mathbb{P}(Z \leq -t) \leq e^{st} M_Z(s)$  for all  $s < 0$ . Setting  $s = -\lambda$ , we have  $\mathbb{P}(Z \leq -t) \leq e^{-\lambda t} M_Z(-\lambda)$ .

Let  $\tilde{Z}$  be the i.i.d copy of  $Z$ . Hence,  $Z - \tilde{Z}$  is symmetric about 0, which means that  $\mathbb{E}[(Z - \tilde{Z})^p] = 0$  for odd-order  $p$ -moments. Therefore, For all  $\lambda > 0$ , we have:

$$\begin{aligned} M_Z(\lambda)M_{-\tilde{Z}}(\lambda) &= M_{Z-\tilde{Z}}(\lambda) \quad (\text{Due to independence}) \\ &= \mathbb{E} \exp \left( \lambda(Z - \tilde{Z}) \right) \\ &= 1 + \sum_{q=1}^{\infty} \frac{\lambda^{2q} \mathbb{E}[(Z - \tilde{Z})^{2q}]}{(2q)!}. \end{aligned}$$

By the convexity of  $f(z) = z^{2q}$ , for all  $t \in (0, 1)$ , we have:

$$\left[ tZ + (1-t)(-\tilde{Z}) \right]^{2q} \leq tZ^{2q} + (1-t)\tilde{Z}^{2q}.$$

Setting  $t = \frac{1}{2}$ , we have:

$$\left[ \frac{Z - \tilde{Z}}{2} \right]^{2q} \leq \frac{Z^{2q} + \tilde{Z}^{2q}}{2} \implies (Z - \tilde{Z})^{2q} \leq 2^{2q-1}(Z^{2q} + \tilde{Z}^{2q}).$$

As a result, we have  $\mathbb{E}[(Z - \tilde{Z})^{2q}] \leq 2^{2q-1}(\mathbb{E}[Z^{2q}] + \mathbb{E}[\tilde{Z}^{2q}]) = 2^{2q}\mathbb{E}[Z^{2q}]$ . Plugging this back to the formula of  $M_{Z-\tilde{Z}}(\lambda)$ , we have:

$$\begin{aligned} \mathbb{E}[e^{\lambda Z}]\mathbb{E}[e^{-\lambda \tilde{Z}}] &\leq 1 + \sum_{q=1}^{\infty} \frac{\lambda^{2q} 2^{2q} \mathbb{E}[Z^{2q}]}{(2q)!} \\ &\leq 1 + \sum_{q=1}^{\infty} \frac{\lambda^{2q} 2^{2q} (4\xi^2)^q q!}{(2q)!}. \end{aligned}$$

Since  $\mathbb{E}[e^{-\lambda \tilde{Z}}] \geq 1$  for all  $\lambda > 0$  and

$$\frac{(2q)!}{q!} = \prod_{j=1}^q (q+j) \geq \prod_{j=1}^q (2j) = 2^q q!,$$

We have:

$$\mathbb{E}[e^{\lambda Z}] \leq 1 + \sum_{q=1}^{\infty} \frac{(2\lambda^2 \cdot 4\xi^2)^q}{q!} = e^{8\lambda^2 \xi^2}.$$

Hence,  $Z \in \mathcal{SG}(16\xi^2)$ .

□.



# I . Appendix

## I.1 Leibniz Differentiation Rule

**Leibniz Differentiation/Integral Rule** refers to the conditions by which differentiation and integration can be exchanged. Essentially, let  $\Omega$  be a measure space and  $A \subset \mathbb{R}^n$  be an open subset. Then, if a function  $f : A \times \Omega \rightarrow \mathbb{R}$  satisfies:

1. For all  $x \in A$ ,  $\omega \mapsto f(x, \omega)$  is a measurable function in  $\omega$  ( $f$  is a Caratheodory Function).
2. For almost all  $\omega \in \Omega$ ,  $\frac{\partial f(x, \omega)}{\partial x}$  exists for all  $x \in A$ .
3. For almost all  $\omega \in \Omega$ , there is an integrable function  $h : \Omega \rightarrow \mathbb{R}$  such that  $|f(x, \omega)| \leq h(\omega)$  for all  $x \in A$ .

Then, we have:

1.  $g(x) = \int_{\Omega} f(x, \omega) d\mu(\omega)$  is continuous.
2.  $D_i g(x) = \int_{\Omega} D_i f(x, \omega) d\mu(\omega)$ .

**Definition I.1** (Caratheodory Function). \_\_\_\_\_

Let  $(\Omega, \mathcal{F}, \mu)$  be a measure space and  $A \subset \mathbb{R}^n$ . We say  $f : A \times \Omega \rightarrow \mathbb{R}$  is a *Caratheodory Function* if it satisfies:

1. For all  $x \in A$ :  $\omega \mapsto f(x, \omega)$  is  $\mathcal{F}$ -measurable.
2. For all  $\omega \in \Omega$ :  $x \mapsto f(x, \omega)$  is continuous.

We also say that  $f$  is a *Caratheodory function* if it is measurable in  $\omega$  and continuous in  $x$ .

### Proposition I.1: Leibniz Differentiation Rule

Let  $(\Omega, \mathcal{F}, \mu)$  be a measure space and  $A \subset \mathbb{R}^n$  be open. Let the function  $f : A \times \Omega \rightarrow \mathbb{R}$  satisfy the following:

1.  $f$  is a Caratheodory function.
2. There exists  $h : \Omega \rightarrow \mathbb{R}$  such that  $|f(x, \omega)| \leq h(\omega)$  for almost all  $\omega \in \Omega$  for all  $x \in A$ .

Then, if we define  $g(x) = \int_{\Omega} f(x, \omega) d\mu(\omega)$ , we have:

- (i)  $g$  is continuous.
- (ii)  $D_i g(x) = \int_{\Omega} D_i f(x, \omega) d\mu(\omega)$ .

**Proof** (Proposition I.1). \_\_\_\_\_

We prove the above points one by one:

- (i) Suppose that  $\{x_n\}_{n=1}^{\infty} \subset A$  is a sequence such that  $x_n \rightarrow x \in A$ . We have to prove that  $g(x_n) \rightarrow g(x)$ . Since  $f$  is a Caratheodory function, we have  $x \mapsto f(x, \omega)$  is continuous for almost all  $\omega \in \Omega$ . Therefore,  $f(x_n, \omega) \rightarrow f(x, \omega)$  for almost all  $\omega \in \Omega$ . Then, by the Dominated Convergence Theorem<sup>5</sup>:

$$\int_{\Omega} f(x_n, \omega) d\mu(\omega) \rightarrow \int_{\Omega} f(x, \omega) d\mu(\omega).$$

Hence, we have  $g(x_n) \rightarrow g(x)$  as desired.

---

<sup>5</sup>DCT is applied for the sequence of functions  $\{k_n\}_{n=1}^{\infty}$  where  $k_n : \Omega \rightarrow \mathbb{R}$  and  $k_n(\omega) = f(x_n, \omega)$ .

(ii) Let  $e_i$  denotes the  $i^{\text{th}}$  standard basis in  $\mathbb{R}^n$ . We have:

$$D_i f(x, \omega) = \lim_{\xi \rightarrow 0} \frac{f(x + \xi e_i, \omega) - f(x, \omega)}{\xi}.$$

Furthermore, we have:

$$\begin{aligned} D_i g(x) &= \lim_{\xi \rightarrow 0} \frac{g(x + \xi e_i) - g(x)}{\xi} \\ &= \lim_{\xi \rightarrow 0} \xi^{-1} \left[ \int_{\Omega} f(x + \xi e_i, \omega) d\mu(\omega) - \int_{\Omega} f(x, \omega) d\mu(\omega) \right] \\ &= \lim_{\xi \rightarrow 0} \int_{\Omega} \frac{f(x + \xi e_i, \omega) - f(x, \omega)}{\xi} d\mu(\omega) \end{aligned}$$

By the Mean Value Theorem, there exists a point  $y(\xi, \omega)$  between  $x$  and  $x + \xi e_i$  such that:

$$f(x + \xi e_i, \omega) - f(x, \omega) = \xi D_i f(y(\xi, \omega), \omega).$$

Therefore, we have:

$$\begin{aligned} D_i g(x) &= \lim_{\xi \rightarrow 0} \int_{\Omega} D_i f(y(\xi, \omega), \omega) d\mu(\omega) \\ &= \lim_{n \rightarrow \infty} \int_{\Omega} D_i f(y(n^{-1}, \omega)) d\mu(\omega) \\ &= \int_{\Omega} \lim_{n \rightarrow \infty} D_i f(y(n^{-1}, \omega)) d\mu(\omega) \quad (\text{Dominated Convergence Theorem}). \end{aligned}$$

As  $n \rightarrow \infty$ , we have  $y(n^{-1}, \omega) \rightarrow x$  since it lies between  $x$  and  $x + \frac{e_i}{n}$ . Hence, we have  $D_i f(y(n^{-1}, \omega), \omega) \rightarrow D_i f(x, \omega)$ . Therefore,  $D_i g(x) = \int_{\Omega} D_i f(x, \omega) d\mu(\omega)$  as desired.

□.

## II . List of Definitions

|     |   |    |
|-----|---|----|
| 1.1 | Definition (Random variable)              | 2  |
| 1.2 | Definition (Convergence in Distribution)  | 11 |
| 1.3 | Definition (Continuity Sets)              | 12 |
| 1.4 | Definition (Weak Convergence of Measures) | 12 |
| 1.5 | Definition (Convergence in Probability)   | 14 |
| 1.6 | Definition (Convergence in $L^p$ norm)    | 15 |
| 1.7 | Definition (Convergence almost-surely)    | 16 |
| 2.1 | Definition (Point Estimator)              | 18 |
| 2.2 | Definition (Sufficient Statistics)        | 18 |
| 2.3 | Definition (Sufficiency Principle)        | 20 |
| 2.4 | Definition (Likelihood Function)          | 21 |
| 2.5 | Definition (Maximum Likelihood Estimator) | 22 |
| 2.6 | Definition (Fisher Information)           | 24 |
| 3.1 | Definition (Sub-Gaussian Random Variable) | 28 |
| 3.2 | Definition (Sub-Gaussian Norm)            | 28 |
| 3.3 | Definition (Sub-Gaussian Variance Proxy)  | 28 |
| I.1 | Definition (Caratheodory Function)        | 33 |

## III . Important Theorems

|     |  |    |
|-----|--|----|
| 1.1 | Weak Law of Large Numbers ( <b>WLLN</b> )                        | 4  |
| 1.2 | Levy Continuity Theorem ( <b>LCT</b> )                           | 5  |
| 1.3 | Strong Law of Large Numbers ( <b>SLLN</b> )                      | 6  |
| 1.4 | Borel-Cantelli Lemma ( <b>BCL</b> )                              | 7  |
| 1.5 | Uniform Law of Large Numbers ( <b>ULLN</b> )                     | 8  |
| 1.6 | Central Limit Theorem ( <b>CLT</b> )                             | 10 |
| 1.7 | Slutsky's Theorem ( <b>SLUTSKY</b> )                             | 11 |
| 1.8 | Portmanteau's Theorem ( <b>PORTMANTEAU</b> )                     | 13 |
| 1.9 | Continuous Mapping Theorem ( <b>CMT</b> )                        | 16 |
| 2.1 | (Fisher-Neyman) Factorisation Theorem ( <b>FacT</b> )            | 20 |
| 2.2 | Rao-Blackwell Theorem ( <b>RB</b> )                              | 24 |
| 2.3 | Cramer-Rao Lower Bound ( <b>CRLB</b> )                           | 26 |
| 3.1 | Bounded Tail Probability $\iff \mathcal{SG}$ ( <b>BTP – SG</b> ) | 30 |

## IV . Important Propositions

|     |  |    |
|-----|--|----|
| 1.1 | $X_n \xrightarrow{p} X \implies X_n \xrightarrow{d} X$   | 14 |
| 1.2 | $X_n \xrightarrow{d} c \iff X_n \xrightarrow{p} c$       | 15 |
| 1.3 | $X_n \xrightarrow{L^p} X \implies X_n \xrightarrow{p} X$ | 15 |
| 1.4 | $X_n \xrightarrow{a.s} X \implies X_n \xrightarrow{p} X$ | 16 |
| 2.1 | Consistency of MLE                                       | 22 |
| 2.2 | Asymptotic Normality of MLE                              | 23 |
| 2.3 | Alternative Representation of Fisher Information         | 25 |
| 3.1 | Properties of Sub-Gaussian Variables                     | 29 |
| I.1 | Leibniz Differentiation Rule                             | 33 |

## V . To-do List

1. (**DONE**) State and prove the Leibniz Differentiation Rule.
2. (**DONE**) State and prove the Cramer-Rao Lower Bound (CRLB).
3. (**IN-PROGRESS**) State and prove the Rao-Blackwell Theorem + Work on sufficiency principle.
4. (**DONE**) Prove the Asymptotic Normality of the MLE.
5. (**DONE**) Prove the properties of sub-Gaussian variables.
6. (**DONE**) Prove the relationship between bounded tail probability and sub-Gaussianity (Thm. 2.1 from Boucheron et. al).
7. (**IN-PROGRESS**) Create a brief chapter on Bayesian inference.
8. (**IN-PROGRESS**) Connect Bayesian inference to frequentist inference using the BvM theorem.
9. (**IN-PROGRESS**) Continue the “Concentration Inequality” chapter.
10. (**IN-PROGRESS**) Revisit the (**ULLN**) under learning theory’s perspective.

## VI . References

### References

- Bartlett, Peter L., Dylan J. Foster, and Matus Telgarsky (2017). “Spectrally-normalized margin bounds for neural networks”. In: *Conference on Neural Information Processing Systems*.
- “Chapter 36 Large sample estimation and hypothesis testing” (1994). In: vol. 4. Handbook of Econometrics. Elsevier, pp. 2111–2245. DOI: [https://doi.org/10.1016/S1573-4412\(05\)80005-4](https://doi.org/10.1016/S1573-4412(05)80005-4). URL: <https://www.sciencedirect.com/science/article/pii/S1573441205800054>.
- Durrett, Rick (2010). *Probability: Theory and Examples*. 4th. USA: Cambridge University Press. ISBN: 0521765390.
- Ferguson, Thomas S. (1996). *A Course in Large Sample Theory*. Chapman & Hall.
- Gut, Allan (2004). *A Graduate Course in Probability*. Graduate Text in Mathematics.
- Long, Philip M. and Hanie Sedghi (2020). “Generalization Bounds for Deep Convolutional Neural Networks”. In: *International Conference on Learning Representation*.
- Pishro-Nik, Hossein (2014). *Introduction to Probability, Statistics and Random Processes*. Kappa Research, LLC.
- undefinedinar, Erhan (2011). *Probability and Stochastics*. Springer New York. ISBN: 9780387878591. URL: <http://dx.doi.org/10.1007/978-0-387-87859-1>.
- Wikipedia (2023). *Vitali set* — *Wikipedia, The Free Encyclopedia*. <http://en.wikipedia.org/w/index.php?title=Vitali%20set&oldid=1187241923>. [Online; accessed 24-December-2023].