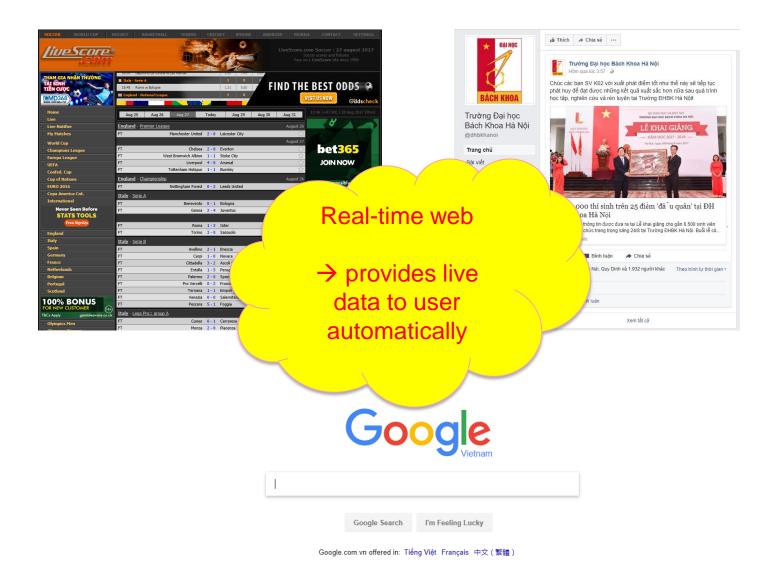
Real-time Systems

Ngo Lam Trung

Dept. of Computer Engineering

What is real-time?



What is real-time?



Example 1

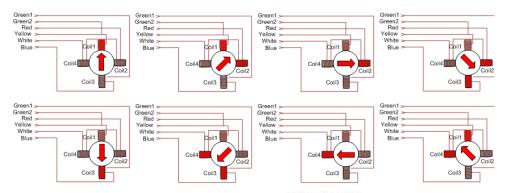
- Write a program in Windows to blink a LED with frequency of 1 Hz
- □ A piece of cake/code, right?

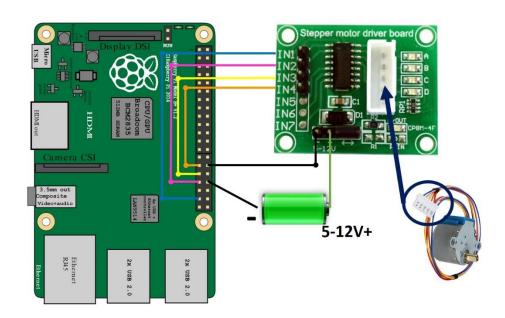
```
DispatcherTimer timer = new DispatcherTimer();
timer.Interval = TimeSpan.FromMilliseconds(500);
timer.Tick += Timer_Tick;
timer.Start();

private void Timer_Tick(object sender, object e)
{
    now = DateTime.Now;
    TimeSpan span = now - prev;
    prev = now;
    txtTime.Text = span.TotalMilliseconds.ToString();
}
```

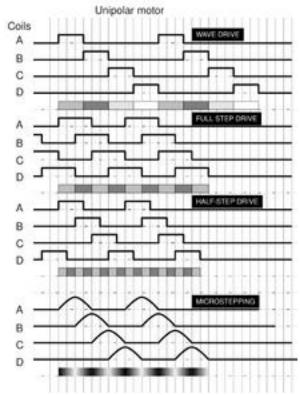
Not really!!!

Example 2: Linux is better than Windows?





Smooth controlling of motor requires accurate timing



Example 2

□ With RT_PREMPT Linux seems better, but not sufficient



□ In contrast, controlling a stepper motor with a low-cost Arduino is not that hard!!!

Course content

- Basic concepts of real-time systems.
- Hard real-time systems and soft real-time systems.
- □ Tasks scheduling algorithms in real time system.
- Schedulability analysis

References

- Qing Li and Carolyn Yao, Real-Time Concepts for Embedded Systems, 2003.
- Giorgio C. Buttazzo, Hard Real-time Computing Systems Predictable Scheduling Algorithms and Applications, 1997.

Class administration

- Instructor: Ngo Lam Trung
- Class time: Wednesday AM
- Mid-term & Final exam: TBA

Chapter 1: Introduction

- Introduction of embedded system
- Characteristics of embedded system
- Real time system and real time embedded systems
- Hard real time vs soft real time.

1. Embedded system

Definition from Textbook 1:

 Computing systems with tightly coupled hardware and software integration, that are designed to perform a dedicated function

Systems within systems

MOST Digital radio Speaker Vehicle computer Lock Window lift Universal light Additional systems Œ ⊗ ⊗ light Drive train Trunk 88 Steering wheel Universal motor Universal panel

Standalone system



CAN Controller area network
GPS Global Positioning System

GSM Global System for Mobile Communications

LIN Local interconnect network
MOST Media-oriented systems transport

[Leen02]

Other definitions of Embedded Systems

"Dortmund" Definition: [Peter Marwedel]

Embedded systems are information processing systems embedded into a larger product

Berkeley: [Edward A. Lee]:

Embedded software is software integrated with physical processes. The technical problem is managing time and concurrency in computational systems.

Wikipedia:

An embedded system is a computer system with a dedicated function within a larger mechanical or electrical system, often with real-time computing constraints. It is embedded as part of a complete device often including hardware and mechanical parts.



Sonicare Elite toothbrush

Microprocessor: 8-bit

Has a programmable speed control, timer, and charge gauge



Product: Microsoft's Smart Personal Object Technology (SPOT) watch (discontinued in 2008).

Microprocessor: 32-bit ARM with FM Radio Chip

Downloads data using extra bandwidth on FM radio stations in major cities

Big idea but also a failure!

Domestic robots











S class Mercedes

Control system contains around 100 embedded processors

2. Characteristics of embedded systems

Dependability

- Dependability is the most important characteristic
 - Reliability R(t) = probability of system working correctly provided that is was working at t=0
 - Maintainability M(d) = probability of system working correctly d time units after error occurred.
 - Availability A(t): probability of system working at time t
 - Safety: no harm to be caused
 - Security: confidential and authentic communication
- System dependability depends on the estimation of working/runtime condition in design time.
- Incorrect/insufficient estimation → good system will fail.
- Dependability must be considered very early in design time

Efficiency

- Embedded system must be efficient
 - Code-size efficient: (especially for systems on a chip)
 - Run-time efficient
 - Weight efficient
 - Cost efficient
 - Energy efficient

Efficiency and application awareness

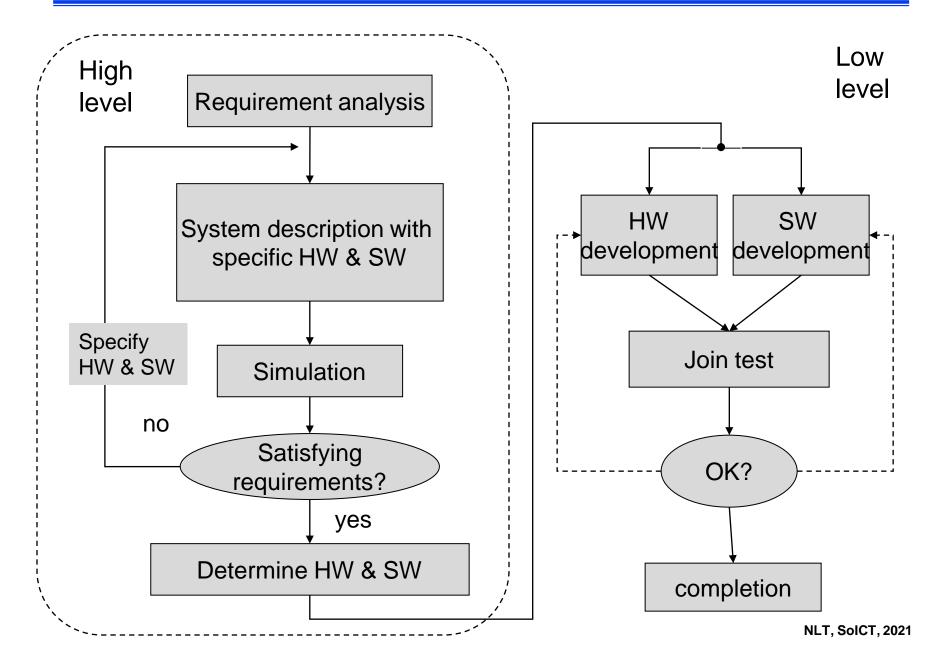
- Which CPU is faster, why?
 - CPU in spacecraft
 - CPU in Boeing 777
 - CPU in your laptop
- Which is better for a mobile phone: a quad-core 2.2GHz or single-core 1GHz CPU?

Hardware and software co-design model

- How to design embedded system?
 - Hardware of software first?
 - How to optimize system design and performance?
- □ Hardware and software co-design
 - Parallel development of HW & SW of an embedded system
 - Beneficial in an embedded system with custom hardware and software

- Software component can use special hardware features.
- Hardware component can simplify module design if functionality can be achieved in software.

Hardware and software co-design model



Cross-platform development

- □ Target system: limited hardware resource → cannot be used as development environment
- How to develop software to run on target system?
 - → Use a different platform as development environment
- Platform: hardware, OS, and development tools



Cross-platform development

- Cross-platform development
 - □ Platform: HW + OS + SW development tools
 - Software development where developing platform and running platform are separating

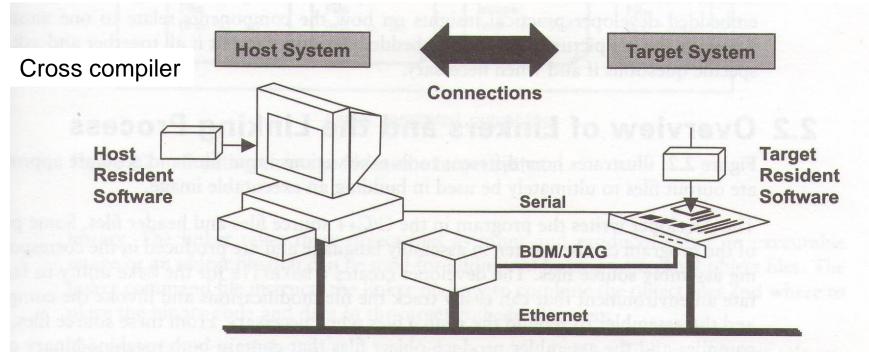
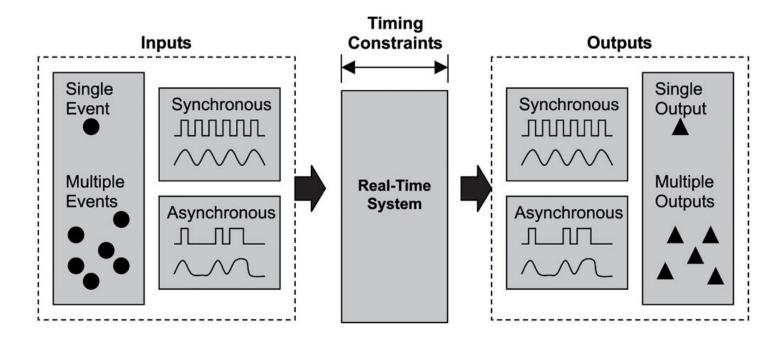


Figure 2.1 Typical cross-platform development environment.

3. Real time systems

Real-time systems



■ Real-time systems:

- Those systems that respond to external events with guaranteed timing constraints
- Timing constraints: start time, finished time
- External events: periodic/aperiodic
- Both of the timing correctness and logical correctness are important.

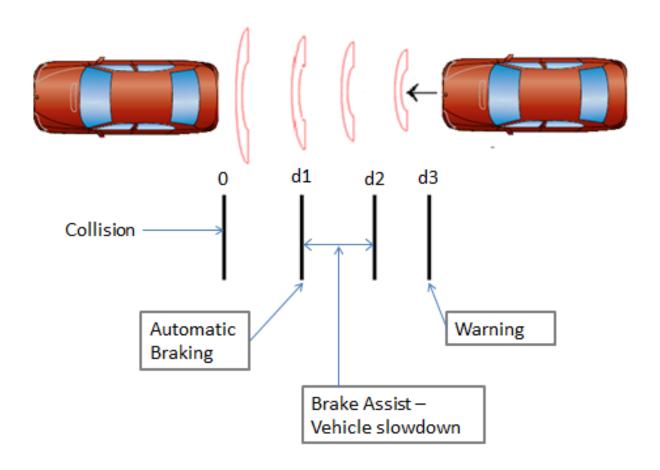
Real-time embedded systems

Example: DVD player

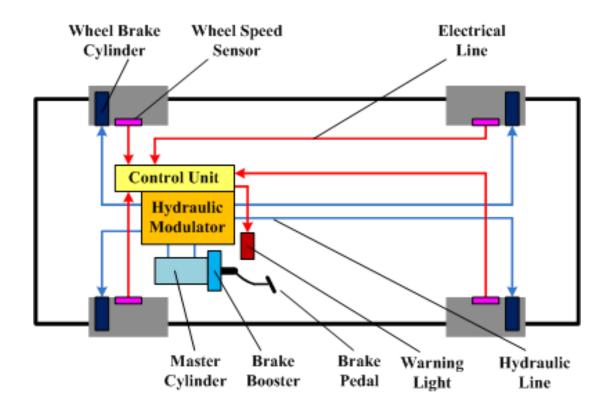


What are real-time requirements?

Autonomous Emergency Breaking System



Anti-lock Breaking System



Hard and soft real-time systems

□ Hard real-time systems

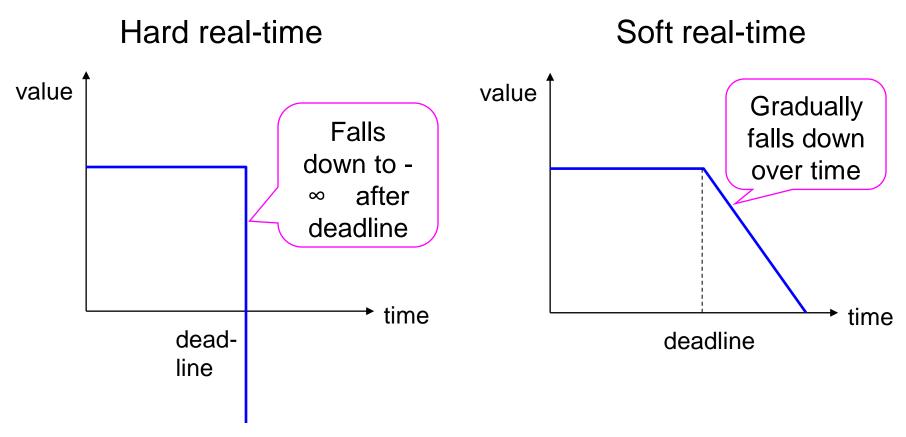
- Must meet deadlines with a non-zero degree of flexibility
- Missing deadlines derives catastrophes
- Ex: car ABS, aviation systems, missile guidance

□ Soft real-time systems

- Must meet deadlines but with a degree of flexibility
- Missing deadlines decreases the value of the computed results. Decrement of the value is proportion to the delay.
- Ex: DVD player

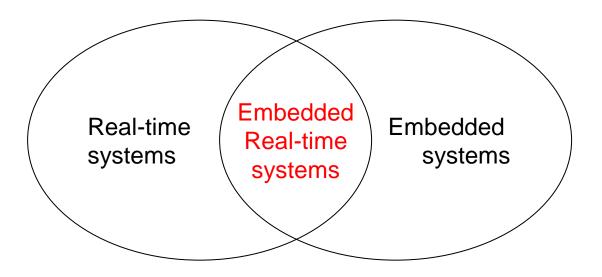
Penalties in real-time systems

Variations of values of execution results with respect to the finished time



Real-time embedded systems

Large overlap of real-time systems and embedded systems

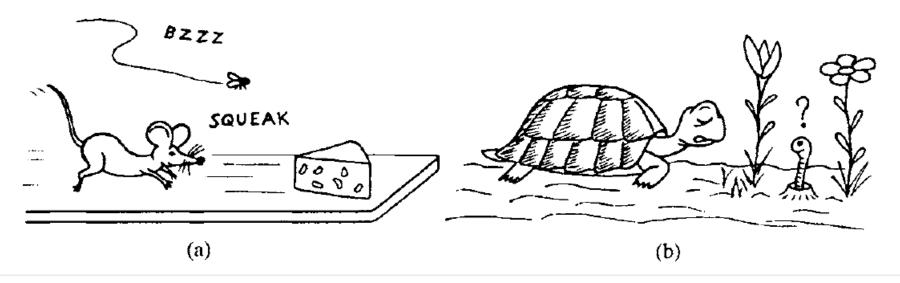


Points to remember

- □ Embedded systems:
 - Computing systems with tightly coupled hardware and software integration, that are designed to perform a dedicated function
- Real-time embedded systems
 - Real-time: required timing & function correctness
 - Commutative between embedded systems and realtime systems
- □ Hard/soft real-time systems
 - Determined by penalty in deadline misses

Comparison

□ Real-time vs real-fast?



La Fontaine's The Hare and the Tortoise "it's no use running, it's better to leave early..."

Comparison

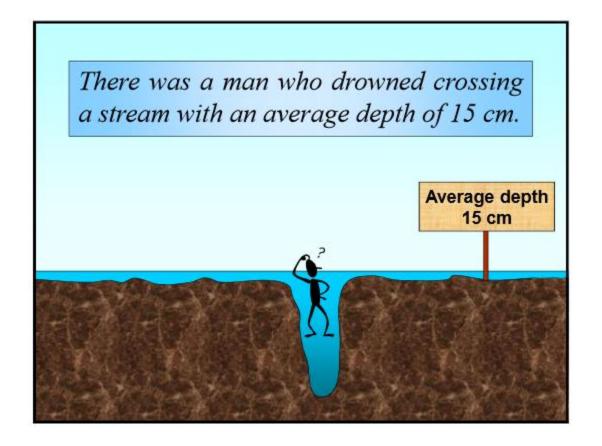
- □ The objective of a real-time system is to guarantee the timing behavior of each individual task.
- □ The objective of a fast system is to minimize the average response time of a task set.

- Which is more difficult?
- A high performance server is running with 1% CPU usage. Is it a real-time system?

Don't trust average

```
🜃 centos@ec2-54-211-215-59.compute-1.amazonaws.com:22 - Bitvise xterm
                                                                                           Х
                                       57.6%
                                                Tasks: 71, 42 thr; 6 running
                                       58.3%]
                                                Load average: 0.95 1.83 2.09
                                 799M/3.52G
                                                Uptime: 43 days, 16:43:21
                                       0K/0K
 Swp
                                    SHR S CPU% MEM%
 PID USER
               PRI
                    NI VIRT
                              RES
                                                      TIME+ Command
16105 centos
                20
                     0 119M
                             2172
                                  1452 R 1.3 0.1 0:00.13 http
7758 nginx
                                                    1h19:31 nginx: worker process
                     0 48372
                             2608
                                   1048 S 0.7 0.1
                20
                                                    9h59:46 /usr/libexec/mysqld --basedir=/usr --
                                   6944 5 0.7 6.6
4507 mysql
                20
                     0 1595M
                             238M
7711 nginx
                     0 558M 24440 14232 S 0.7 0.7 3:06.89 php-fpm: pool www
                20
4517 mysql
                                   6944 S 0.7 6.6 2:06.02 /usr/libexec/mysqld --basedir=/usr --
                20
                     0 1595M 238M
5367 nginx
                     0 561M 25552 14284 S 0.7 0.7 3:08.37 php-fpm: pool www
                20
15800 mysql
                     0 1595M 238M 6944 S 0.0 6.6 0:00.44 /usr/libexec/mysqld --basedir=/usr -
                20
23868 nginx
                     0 557M 24860 15088 S 0.0 0.7 3:09.76 php-fpm: pool www
                20
7763 nginx
                     0 561M 26868 15860 S 0.0 0.7 3:06.59 php-fpm: pool www
                20
23864 nginx
                20
                     0 559M 25280 15668 S 0.0 0.7 3:04.89 php-fpm: pool www
4514 mysql
                20
                     0 1595M 238M
                                   6944 S 0.0 6.6 2:09.42 /usr/libexec/mysqld --basedir=/usr --
23827 nginx
                     0 560M 26180 14408 S 0.0 0.7 3:08.23 php-fpm: pool www
                20
7764 nginx
                     0 559M 24508 14848 S 0.0 0.7 3:01.33 php-fpm: pool www
                20
5427 nginx
                20
                     0 561M 25988 15160 S 0.0 0.7 3:10.29 php-fpm: pool www
                     0 557M 22944 13552 S 0.0 0.6 3:03.22 php-fpm: pool www
5435 nginx
                20
7765 nginx
                20
                     0 558M 23568 13472 S 0.0 0.6 3:01.91 php-fpm: pool www
5330 nginx
                20
                    0 558M 24780 14272 S 0.0 0.7 3:07.31 php-fpm: pool www
7760 nginx
                     0 48440 2700 1044 S 0.0 0.1 1h20:55 nginx: worker process
                20
11067 nginx
                     0 557M 20480 10868 S 0.0 0.6 0:53.14 php-fpm: pool www
                20
23869 nginx
                     0 560M 25208 15128 S 0.0 0.7 3:04.55 php-fpm: pool www
                20
                     0 558M 24528 13752 S 0.0 0.7 3:07.82 php-fpm: pool www
5473 nginx
                20
7759 nginx
                     0 48328 2584
                                   1040 S 0.0 0.1 1h19:51 nginx: worker process
                20
4524 mysql
                                   6944 S 0.0 6.6 34:40.11 /usr/libexec/mysqld --basedir=/usr --
                20
                     0 1595M
                             238M
5443 nginx
                     0 560M 25100 15072 S 0.0 0.7 3:04.27 php-fpm: pool www
                20
4511 mysql
                                   6944 $ 0.0 6.6 2:08.50 /usr/libexec/mysqld --basedir=/usr --
                20
                     0 1595M 238M
4520 mysql
                                   6944 S 0.0 6.6 3:42.73 /usr/libexec/mysqld --basedir=/usr --
                20
                     0 1595M 238M
7574 nginx
                    0 560M 25332 15104 S 0.0 0.7 3:06.14 php-fpm: pool www
F1Help F2Setup F3SearchF4FilterF5Tree F6SortByF7Nice -F8Nice +F9Kill F10Ouit
```

Don't trust average



Discussion

- What is the most important part of a real-time system?
 - Hardware?
 - Software?
- Homework: do some research on computing system on spacecraft

http://www.cpushack.com/space-craft-cpu.html