Chapter 6: Information channel

### Presented notions

- Physical medium to send information from transmitter to receiver
- Channel has additive noise which changes the propagated signal
- Channel has different types:
  - · Discrete channel
    - · Memoryless channel
    - · Memory channel
    - · Binary channel
  - · Continuous channel
- Input source, noise source, output are considered random variables
  - Output = Input + Noise

### 6.1. Channel model

- Discrete channel: discrete input signal and discrete output signal
  - · Channel model:
    - Random variable represents discrete source
      - $X = \{x1, x2,...xn\}$
      - $P(X) = \{P(x1), P(x2),...,P(xn)\}$
    - · Alphabet of output
      - Y = {y1,y2,...,yn}
        - [y ±, y 2,..., y 11]
      - Yi = xj (alphabet of output is identical to alphabet of input)
      - Generally, number of inputs (r) is different with number of outputs (s).
      - This course only focuses: r = s = n

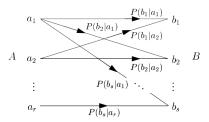
#### Discrete channel:

- This course only focus on memoryless channel
- Matrix channel for memoryless channel: consists of all transfer probabilities
  - P(Y|X) = {P(yj|xi)}

$$\begin{bmatrix} P(y_1|x_1) & P(y_2|x_1) & \dots & P(y_n|x_1) \\ P(y_1|x_2) & P(y_2|x_2) & \dots & P(y_n|x_2) \\ \dots & \dots & \dots & \dots \\ P(y_1|x_n) & P(y_2|x_n) & \dots & P(y_n|x_n) \end{bmatrix}$$

- · Elements in main diagonal is correct probability
- Elements outside off main diagonal is wrong probability
- If all correct probabilities are equal, all wrong probabilities are equal: uniform channel
- Sum of all elements in one row = 1
- · Identity matrix (unit matrix): transmission in channel not wrong
- · If all elements are equal, the channel wrong: output independents with input
- Elements of the matrix are symmetric across the main diagonal (symmetric matrix): symmetric channel

- · Transition diagram of the discrete channel:
  - r input points. Each point represents a input signal
  - s output points. Each point represents a output signal
  - Connection line between a input point and a output point represent transfer probability

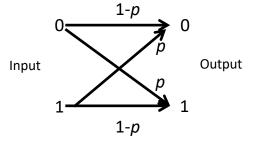


- Discrete Binary Symmetric Channel (BSC)
  - Binary channel: input signal and output signal are binary
    - For example: 0 and 1
  - Symmetric channel: The channel matrix is symmetric across the main diagonal
    - Channel matrix: contain transmission probability P(y/x)
      - P(y|x): conditional probability of receiving output signal y when input signal x is sent
- Binary symmetric channel = binary channel + symmetric channel
  - · Example: channel matrix of one BSC

$$P(Y|X) = \begin{vmatrix} 3/4 & 1/4 & x1 \\ 1/4 & 3/4 & x2 \end{vmatrix}$$

$$y1 \quad y2$$

Binary symmetric channel (BSC) model



$$P[Y = 0|X = 1] = P[Y = 1|X = 0] = p$$
  
 $P[Y = 1|X = 1] = P[Y = 0|X = 0] = 1 - p$ 

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- Continuous channel: continuous input signal and continuous output signal
  - · Channel model:
    - Random variable represents continuous source
      - $X = \{x\}$   $xmin \le x \le xmax$
      - $P_X(x)$  probability density function of source X
    - Output:
      - $Y = \{y\}$   $ymin \le y \le ymax$
      - P(y|x) conditional probability density function of output Y when input X has determined values

 According chapter 2: mutual information between two random variables X, Y:

$$I(X; Y) = \sum \sum P(x,y) \log \frac{P(x,y)}{P(x)P(y)}$$
  
= H(X) + H(Y) - H(X,Y)

• Because:  $\frac{P(x,y)}{P(y)} = P(x/y)$ 

So : 
$$I(X; Y) = \sum \sum P(x,y) \log \frac{P(x|y)}{P(x)}$$
  
=  $H(X) - H(X|Y)$ 

- Corollary:
  - Mutual information is a average information (entropy) that a symbol may transmit through channel
  - Mutual information equals average input information (H(X)) minus average loss information (H(X|Y)).
  - Average loss information is generated by noise: H(X|Y) =H(N)<sub>X</sub> with noise source N
    and source X are inputs

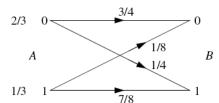
• Because: 
$$\frac{P(x,y)}{P(x)} = P(y|x)$$
So :  $I(X;Y) = \sum \sum P(x,y) \log \frac{P(y|x)}{P(y)}$ 

$$= H(Y) - H(Y|X)$$

- · Corollary:
  - Mutual information is a average information (entropy) that a symbol may transmit through channel
  - Mutual information equals average input information (H(Y)) minus average loss information (H(Y|X)).
  - Average loss information is generated by noise: H(Y|X) =H(N)<sub>Y</sub> with noise source N and source Y are inputs

- Information transmitted through channel always equals input information minus loss information
- Loss information: noise information generated by noise
- Information transmitted though channel in both ways are equals
- $0 \le I(X;Y) \le H(X)$  when no noise, X = Y

- H(A), H(A|B)?
- Mutual information?



## 6.3. Mutual information of continuous channel

- As presented in chapter 2, entropy of continuous source are calculated using integral and probability density function
  - So, mutual information is also calculated using integral

$$I(X; Y) = \iint_{x,y} P_{x,y}(x,y) \log \frac{P_{x,y}(x,y)}{P_{x}(x)P_{y}(y)} d_{x} d_{y}$$

$$= H(X) + H(Y) - H(X,Y)$$

$$= \iint_{x,y} P_{x,y}(x,y) \log \frac{P_{x|y}(x|y)}{P_{x}(x)} d_{x} d_{y}$$

$$= H(X) - H(X|Y)$$

$$= \iint_{x,y} P_{x,y}(x,y) \log \frac{P_{y|x}(y|x)}{P_{y}(y)} d_{x} d_{y}$$

$$= H(Y) - H(Y|X)$$

 Properties of mutual information in continuous channel are similar to the properties of mutual information in discrete channel

### 6.4. Channel capacity

- Maximum average amount of information that channel may transmit in a unit of time without error
- · Denoted by C
- Calculated by number of transmitted symbols  $n_o$  multiply maximum average amount of information that a symbol can transmit through channel (mutual information)
  - $C = n_o \times I(X;Y) \max$
- Remark: in information theory,  $n_o$  is physical parameter so that  $n_o$  is considered as an unit
  - $\rightarrow$  C = I(X;Y)max

### 6.4. Channel capacity (Cont.)

#### • Discrete channel:

- Number of transmitted symbols  $(n_o)$  is bandwidth of channel  $(\Delta f)$ 
  - So,  $C = \Delta f \times I(X;Y)$ max
- $C = \Delta f \times (H(X) H(X|Y)) \max = \Delta f \times (H(X) H(N)_X) \max$
- Without noise:  $H(N)_X = 0$ 
  - So:  $C = \Delta f \times H(X) \max = \Delta f \times \log |X| = \Delta f \times \log L$  (L is number of different symbols of source X)

### 6.4. Channel capacity (Cont.)

#### Continuous channel:

- ullet  $n_o$  is calculated as the number of samples of the discrete source equivalent to the continuous source
- · According to sampling theorem:
  - $n_o = 2$  Fmax (Fmax is maximum frequency of source connected to channel)
  - Fmax =  $\Delta f$  (bandwidth of channel)
- $C = 2 \Delta f \times I(X;Y) max$ 
  - =  $2 \Delta f \times (H(Y)-H(Y|X))max$

### 6.4. Channel capacity (Cont.)

#### Continuous channel:

- Normally, source has Gaussian distribution and noise has also Gaussian distribution:
  - $H(Y|X) = H(N)_V = \log \sqrt{2\Pi e P_N}$ 
    - P<sub>N</sub>: average power (variance) of the noise source
  - $H(Y) = \log \sqrt{2\Pi e P_Y}$ 
    - P<sub>Y</sub>: average power (variance) of the output
  - $P_Y = P_X + P_N$ 
    - P<sub>r</sub>: average power (variance) of input source
    - The variance of the sum of the Gaussian random variables is equal to the sum of the variances of each variable

• 
$$C = 2 \Delta f \times (\log \sqrt{2\Pi e P_Y} - \log \sqrt{2\Pi e P_N})$$
  
=  $2\Delta f \times \log \frac{P_Y}{P_N}$   
=  $\Delta f \times \log \frac{P_Y}{P_N} = \Delta f \times \log \frac{P_X + P_N}{P_N} = \Delta f \times \log(1 + \frac{P_X}{P_N})$   
 $\Rightarrow C = \Delta f \times \log(1 + \frac{S}{N})$ 

 $\frac{s}{s}$ : signal/noise rate: calculated by the ratio of the average power of the input signal with the average of the noise measured at the output of the channel