# Final Project Presentation MP2 Calculation

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### Intro

Step 1: Change of basis 
$$(pq|P)=\sum_{q}^{N+M}\left(C^{\dagger}\right)_{q\nu}\sum_{p}^{N+M}\left(C^{\dagger}\right)_{p\mu}\left(\mu\nu|P\right)$$

$\left(C^{\dagger}\right)$	NBASIS NBASIS
$(\mu\nu P)$	NBASIS NBASIS NAUX
$(P Q)^{-1/2}$	NAUX NAUX
MO_energy	NBASIS

Step 2: Obtain B\_matrix

 $B_{pq}^{P} = \sum_{P}^{N+M} (pq|P) (P|Q)^{-1/2}$ 

(Orthogonalization)

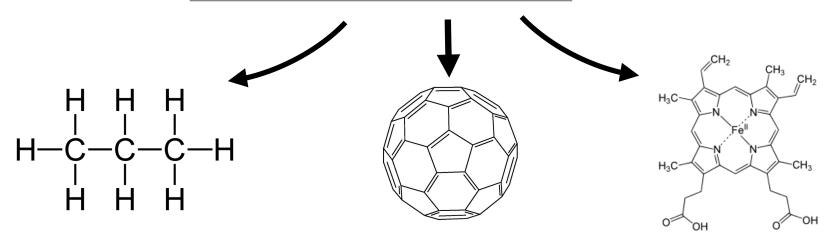
$$(ia|jb) = \sum_{P} B_{ia}^{P} B_{jb}^{P}$$

Step 3: Calculate MP2

$$E_{MP2} = \sum_{ij} \sum_{ab} \frac{(ia \mid jb)[2(ia \mid jb) - (ib \mid ja)]}{\varepsilon_i + \varepsilon_j - \varepsilon_a - \varepsilon_b}$$

# Systems of Interest

	$C_3H_8$	$C_{60}$	Heme
$\overline{N_{ m BASIS}}$	202	1800	632
$N_{ m AUX}$	483	4860	1618
$N_{ m ELEC}$	13	180	161
Memory	$157~\mathrm{MB}$	$110~\mathrm{GB}$	$5.17~\mathrm{GB}$
Total node hours	$2.96 \mathrm{\ s}$	6.61  hours	0.0903 hours



## Serial Implementation

Use BLAS Level 3 DGEMM to optimize serial code

$$(pq|P) = \sum_{q}^{N+M} (C^{\dagger})_{q\nu} \sum_{p}^{N+M} (C^{\dagger})_{p\mu} (\mu\nu|P)$$

2)

3)

# Serial Implementation

Use BLAS Level 3 DGEMM to optimize serial code

3)

```
Orthogonalization

1 cblas_dgemm(CblasColMajor, CblasNoTrans, CblasNoTrans, NBASIS*NBASIS, NAUX, NAUX, 1.0,
pqP, NBASIS*NBASIS, overlap, NAUX, 1.0, B_pqP, NBASIS*NBASIS);
```

$$B_{pq}^{P} = \sum_{P}^{N+M} (pq|P) (P|Q)^{-1/2}$$

# Serial Implementation

Use BLAS Level 3 DGEMM to optimize serial code

```
Orthogonalization

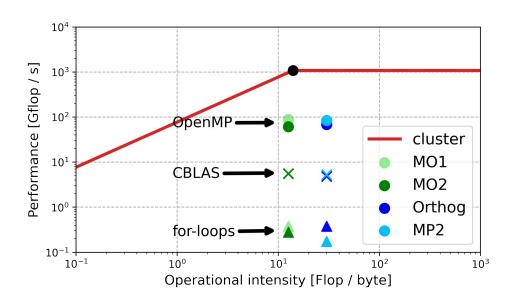
1 cblas_dgemm(CblasColMajor, CblasNoTrans, CblasNoTrans, NBASIS*NBASIS, NAUX, NAUX, 1.0, pqP, NBASIS*NBASIS, overlap, NAUX, 1.0, B_pqP, NBASIS*NBASIS);
```

$$(ia|jb) = \sum_{P} B_{ia}^{P} B_{jb}^{P}$$

$$E_{MP2} = \sum_{ij} \sum_{ab} \frac{(ia \mid jb)[2(ia \mid jb) - (ib \mid ja)]}{\varepsilon_i + \varepsilon_j - \varepsilon_a - \varepsilon_b}$$

# **Roofline Analysis**

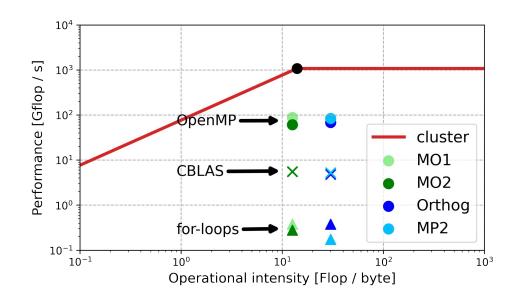
$$\pi = 1075.2 \text{ Gflop /s}$$
  
 $\beta = 76.8 \text{ GB /s}$ 



# **Roofline Analysis**

$$F_{ ext{MO1, 2}} = 2 imes N_{ ext{BASIS}}^3 imes N_{ ext{AUX}}$$
 $F_{ ext{Orthog}} = 2 imes N_{ ext{AUX}}^3 imes N_{ ext{BASIS}}$ 
 $F_{ ext{MP2}} = 2 imes (N_{ ext{BASIS}} - N_{ ext{ELECS}})^2 imes N_{ ext{AUX}} + (N_{ ext{BASIS}} - N_{ ext{ELECS}})^2 imes 11)$ 

$$I_{ ext{MO1, 2}} = rac{F_{ ext{MO1, 2}}}{8 \cdot 4 \cdot N_{ ext{BASIS}}^2 N_{ ext{AUX}}} = rac{1}{16} N_{ ext{BASIS}}$$
 $I_{ ext{Orthog}} = rac{F_{ ext{Orthog}}}{8 \cdot 4 N_{ ext{AUX}}^2 N_{ ext{BASIS}}} = rac{1}{16} N_{ ext{AUX}}$ 
 $I_{ ext{MP2}} = rac{F_{ ext{MP2}}}{3 N_{ ext{BASIS}}^2} = rac{1}{16} N_{ ext{AUX}}$ 





# Roofline Analysis: BLAS routines

$$F_{\text{MO1, 2}} = 2 \times N_{\text{BASIS}}^3 \times N_{\text{AUX}}$$

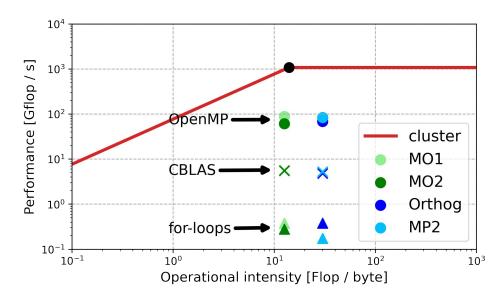
$$F_{\text{Orthog}} = 2 \times N_{\text{AUX}}^3 \times N_{\text{BASIS}}$$

$$F_{\text{MP2}} = 2 \times (N_{\text{BASIS}} - N_{\text{ELECS}})^2$$

$$\times N_{\text{AUX}} + (N_{\text{BASIS}} - N_{\text{ELECS}})^2 \times 11)$$

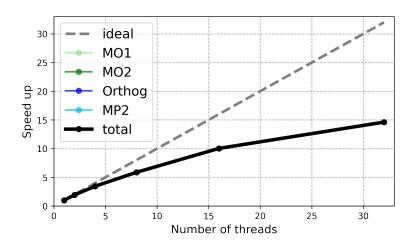
Step	for-loops	CBLAS	OpenMP
MO1	20.99	1.42	0.09
MO2	28.67	1.45	0.13
Orthogonalization	50.54	3.29	0.28
$_{ m MP2}$	34.04	1.18	0.07

#### \* cache optimization



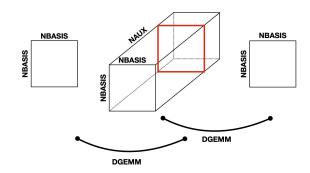
#pragma omp parallel for

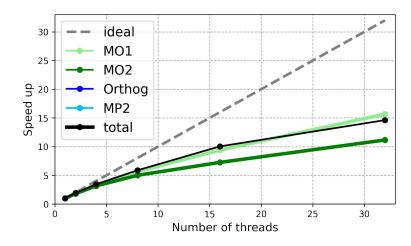
- scheduling
- first touch policy
- thread affinity



#pragma omp parallel for

- MO2 has worse cache locality



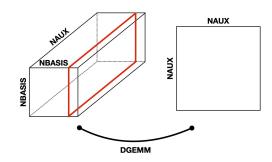


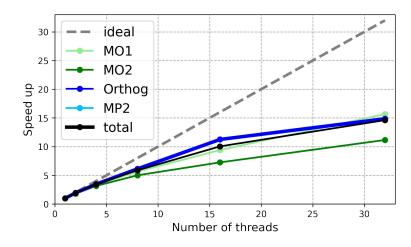
#pragma omp parallel for collapse(3)

- reshaping

#pragma omp parallel for

- DGEMM



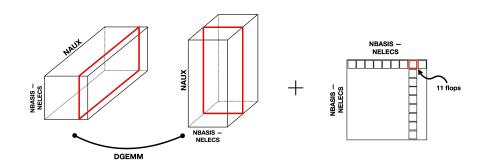


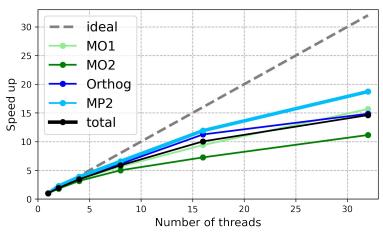
#pragma omp parallel for collapse(3)

- reshaping

#pragma omp parallel for collapse(2) reduction( $+:E_{MP2}$ )

- DGEMM + element-wise calculations





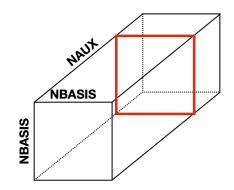
### Distributed Memory Parallelization with MPI

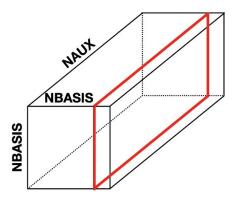
• Rank three tensor can be distributed to each rank and the change of basis can be done separately on each node.

$$(pq|P) = \sum_{q}^{N+M} (C^{\dagger})_{q\nu} \sum_{p}^{N+M} (C^{\dagger})_{p\mu} (\mu\nu|P)$$

 Orthogonalization can also be done separately on each node after some data transfer

$$B_{pq}^{P} = \sum_{P}^{NAUX} (pq|Q) (P|Q)^{-1/2}$$







### Distributed Memory Parallelization with MPI

```
Algorithm 4: Non-blocking MPI Implementation

Initialize 1D Cartesian Grid;

for k = 1; k < NumRanks do

MPI_Isend(B) to the RIGHT neighbor;

MPI_Irecv(Brecv_) from the LEFT neighbor;

MP2 Energy Calculation kernel (3) + Update index;

MPI_Waitall(2);

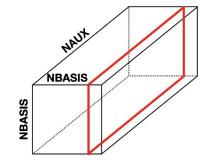
Swap B and Brecv_;

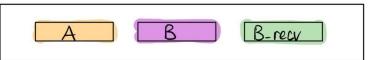
end

MP2 Energy Calculation kernel (3);

MP1_Reduce(&MP2_partial, &MP2_energy, root rank);
```

- Allocate extra memory buffer to do compute/transfer overlap
- The number of MPI Communication is minimized.
- Need an extra bookkeeping index to get the correct MO energy.





## Weak scaling analysis for MPI Implementation

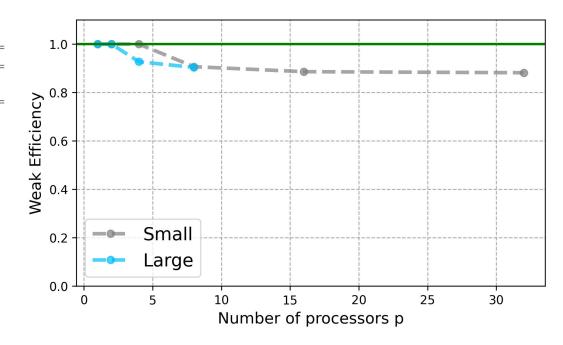
Number of processors	1	2	4	8	16	32
Time for small test	0.17	0.34	0.68	1.50	3.07	6.17
Time for large test	5.37	10.56	23.17	47.54	-	-

- Each processor is map to one core on one node
- Runtime needs to be normalized for weak scaling analysis



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# Final thoughts

- Integrate BLAS/OpenMP Implementation into MPI implementation
- Modify the MPI implementation to divide the work between different processors.
- Continue working on optimizing the vectorized kernel for MP2 energy calculation.

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- Continue working on optimizing the vectorized kernel for MP2 energy calculation.

- Ab initio calculation requires a lot computing resources
- MPI implementation is useful when we do ab initio calculation for solid state system (discretize k point in the 1st Brillouin zone)