Answer to 3.2 problem 19

(a) implies (b)

Recall that, by definition, N(A) is the subspace of all solutions of the homogeneous system Ax = 0. If $N(A) = \{0\}$, then the only solution to the homogeneous system Ax = 0 is the trivial solution (zero vector), thus the matrix is singular by the Theorem on Equivalent Conditions on Nonsingularity (page 8 of Lecture Notes on Elementary Matrices – Section 1.5)

(b) implies (c)

If A is nonsingular, then it is invertible and $\mathbf{A}\mathbf{x} = \mathbf{b}$ if and only if $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$. Thus $\mathbf{A}^{-1}\mathbf{b}$ is the only solution to $\mathbf{A}\mathbf{x} = \mathbf{b}$.

(c) implies (a)

If the equation Ax = b has a unique solution for each b, then in particular for b = 0 the solution x = 0 must be unique. Therefore $N(A) = \{0\}$.