

Info-H-415 - Advanced Databases

Mobility (Moving Objects) Databases

Lesson 2: The abstract Model

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Abstract vs. Discrete models

Two options:

- **Abstract Model:** Definitions in terms of infinite sets allowed. We don't care about finite representation.
- **Discrete Model:** Only definitions in terms of finite representations are allowed.

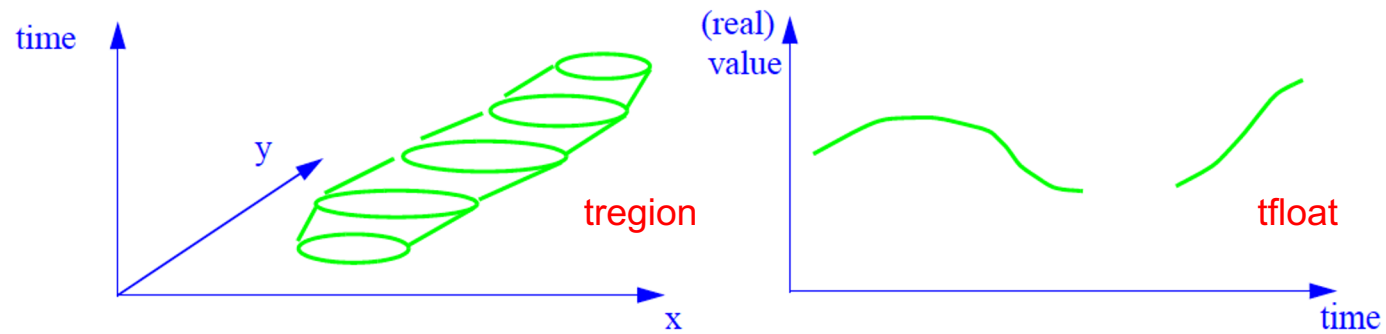
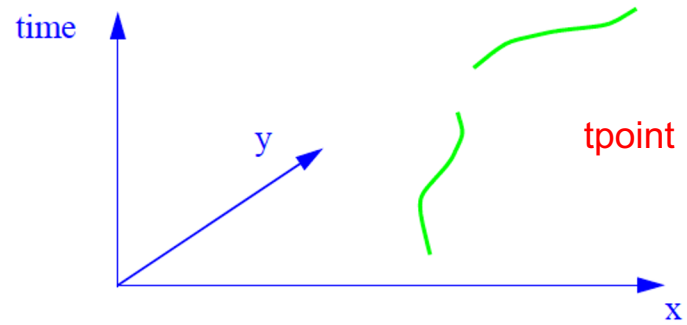
Abstract vs. Discrete models

- Two options:
- **Abstract Model:** Definitions in terms of infinite sets. Don't care about finite representation.
- **Discrete Model:** Only definitions in terms of finite representations are allowed.
- In both cases:
 1. Define a signature (data types + operations)
 2. Define a semantics for the above

Abstract vs. Discrete models

Abstract – Continuous - Infinite	Discrete – Concrete – Finite
A region is a closed subset of \mathbb{R}^2 with non-empty interior	A region is a set of polygons which may have polygonal holes
A line is a curve in \mathbb{R}^2	A line is a polyline (a list of line segments)
A temporal (point) is a function from time into Point values	A temporal(point) is a polyline in a 3D space
A temporal (float) is a function from time into Real values	A temporal(float) is a piecewise quadratic function
A temporal(region) is a function from time into Region values	A temporal(region) is a polyhedron in 3D

Temporal points, lines, regions, reals (float)



Abstract Data Types for Moving Objects

- Basic abstractions in spatial databases: point, line, region.
 - Point: An entity for which only the position in space is relevant.
 - Line: Usually ways for moving, connections in space.
 - Region: An entity for which also the extent is relevant.
- We focus on *moving points* and *moving regions*. “Temporal” and “moving” used indistinctly
- Temporal (moving) points: people, animals, stars, cars, planes, ships, ...
- Temporal (moving) regions: forests, forest fires, oil spills, countries, hurricanes, bird flock, fish colony, ...
- Support all kinds of queries about such moving objects.

Abstract vs. discrete models

- Abstract models are
 - + simple
 - + generic (admit several discrete implementations)
 - – not (directly) implementable
- Discrete models
 - are more complex
 - represent specific choices not suitable for all applications
 - offer a direct implementation
- Conclusion: Proceed in two steps
 1. Design abstract model as a target.
 2. Design and implement a discrete models as an instantiations of the abstract model

Abstract model: Base (non-temporal) data types

- Non-spatial types : as usual, int, float, bool, etc.
- Spatial types

point



points



line



region



Making base types temporal

- base type + time

tpoint = time x point

tregion = time x region

tfloat = time x float

tint = time x int

tbool = time x bool

ttext = time x text

Continuous changes

Discrete changes

Temporal data types: constructors

Two data types to represent time: **instants** and **periods**

- Type *instant*: isomorphic to *real*
- Type *periods*: set of disjoint time intervals)

Two type constructors for temporal data types: **temporal** and **intime**

- Type constructor *temporal* yields for each base and spatial type, a **temporal type**
- Type constructor *intime* yields for each base or spatial type, a type whose values are pairs e.g., *intime(int)* yields a pair (*instant*, *int*)

Temporal data types: constructors

When α is an ordered domain (*int, real, bool, string, instant*)

- *range(α)* Yields a finite set of disjoint, non-adjacent intervals (closed, open, half-open) over α (e.g., *periods = range(instant)*).

When α is a standard or spatial type (*int, real, bool, string, point, points, line, region*)

- *temporal(α)* Values are feined by a partial function $f: A_{instant} \rightarrow A_{\alpha}$ where A_{α} is the carrier set of α .
- *intime(α)* Produces a value that is a pair in $A_{instant} \times A_{\alpha}$.
(In MobilityDB implemented by *instants()*)

Operations

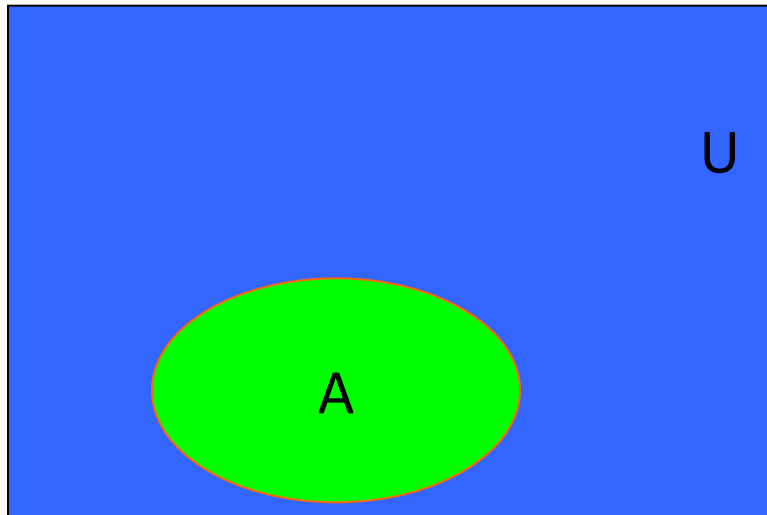
- Four steps:
 1. Define operations on non-temporal types
 2. Define (unary) operations for temporal types
 3. “**Lift**” operations on non-temporal types to temporal types: extend these operations to the temporal version of non-temporal types (e.g., distance computation)
 4. Include operations from various domains (e.g., topological operations)

Topological relationships and predicates (reminder)

- Topological Relationships
 - Invariant under elastic deformation (without tear, merge)
 - Two countries which touch each other in a planar paper map will continue to do so in spherical globe maps
- Example queries with topological operations
 - What is the topological relationship between two objects A and B ?
 - Find all objects which have a given topological relationship to object A ?
- Expressed by spatial predicates
- A spatial (non-temporal) predicate is a function with signature
$$T1 \times \dots \times Tn. \rightarrow bool$$
where Ti is of base type int, text, point, etc. For example
*E.g.: Grand Place **within** Bruxelles*

Topological relationships

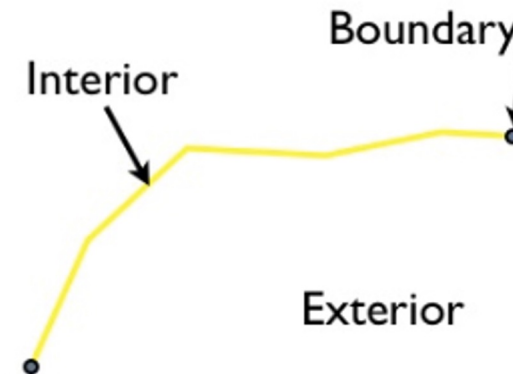
- Interior, boundary, exterior
 - Let A be an object in a “Universe” U



Green is A interior (A°)

Red is boundary of A (∂A)

Blue – (Green + Red) is A exterior (A^-)



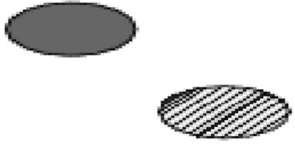





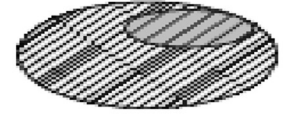

The 9-intersection model (Egenhofer, 1993)

- Topological relationships between A and B can be specified using the 9-intersection model
- Nine-intersection matrix
 - Intersections between interior, boundary, exterior of A, B
 - Can be arranged as a 3 x 3 Boolean matrix
 - Every different set of 9-intersections describes a different topological relation. Relations with the same specification are topologically equivalent
- For this matrix $2^9 = 512$ different configurations are possible, **but only a subset makes sense**
- For **two simple regions, eight meaningful configurations** have been identified which leads to eight predicates: *equal, disjoint, coveredBy, covers, overlap, meet, inside, and contains*

$$\begin{bmatrix} \partial A \cap \partial B \neq \emptyset & \partial A \cap B^\circ \neq \emptyset & \partial A \cap B^- \neq \emptyset \\ A^\circ \cap \partial B \neq \emptyset & A^\circ \cap B^\circ \neq \emptyset & A^\circ \cap B^- \neq \emptyset \\ A^- \cap \partial B \neq \emptyset & A^- \cap B^\circ \neq \emptyset & A^- \cap B^- \neq \emptyset \end{bmatrix}$$

Topological configurations of the 9-intersection matrix

The eight meaningful configurations for two simple regions

			
$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix}$ <p>disjoint</p>	$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ <p>contains</p>	$\begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix}$ <p>inside</p>	$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ <p>equal</p>
			
$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$ <p>meet</p>	$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ <p>covers</p>	$\begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}$ <p>coveredBy</p>	$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$ <p>overlap</p>

Operations on non-temporal types

- π : variables ranging over types whose values are single elements
- σ : variables ranging over types whose values are subsets of the space (e.g., ranges, points)
- For example, the *within* operation

within: $\pi \times \sigma \rightarrow bool$

- This is an abbreviation for:

within: $int \times range(int) \rightarrow bool$
 $bool \times range(bool) \rightarrow bool$
 $text \times range(string) \rightarrow bool$
 $float \times range(float) \rightarrow bool$
 $instant \times periods \rightarrow bool$
 $point \times points \rightarrow bool$
 $point \times line \rightarrow bool$
 $point \times region \rightarrow bool$

Operations on non-temporal types

Class	Operations
Predicates	isempty =, /=, intersects, within <, <=, >=, >, before touches, attached, overlaps, on_border, in_interior
Set Operations	intersection, union, minus crossings, touch_points, common_border
Aggregation	min, max, avg, center, single
Numeric	no_components, size, perimeter, duration, length, area
Distance and Direction	distance, direction
Base Type Specific	and, or, not

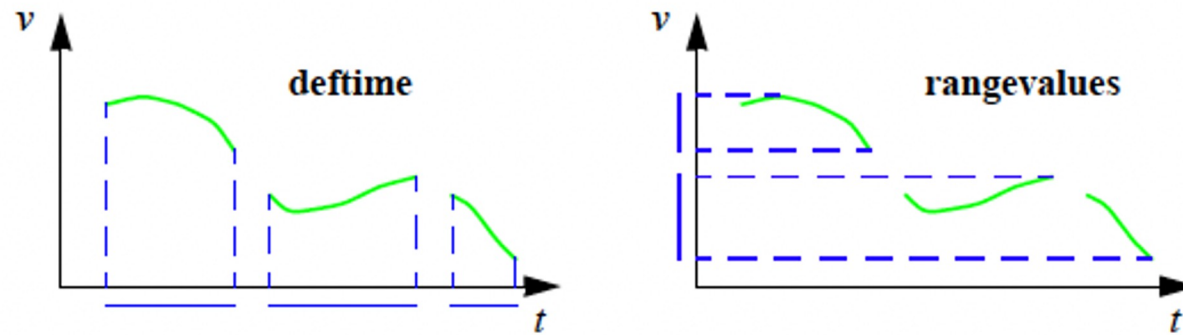
Unary operations on temporal types

Projection to domain or range

deftime (**getTime**): returns the set of time intervals when a temporal function is defined (projection into domain)

rangevalues: performs the projection into the range for the one-dimensional types

For a *temporal(real)*:



locations: projection of a *temporal(point)* into the plane as points

trajectory (**trajectory**): projection of a *temporal(point)* into the plane as lines

inst and **val**: access the components of **intime** types

Unary operations on temporal types

Projection to domain or range

Operation	Signature	
Deftime (getTime)	$temporal(\alpha)$	$\rightarrow periods$
rangevalues	$temporal(\alpha)$	$\rightarrow range(\alpha)$
locations	$temporal(point)$ $temporal(points)$	$\rightarrow points$ $\rightarrow points$
trajectory	$Temporal(point)$ $temporal(points)$	$\rightarrow line$ $\rightarrow line$
traversed	$temporal(line)$ $temporal(region)$	$\rightarrow region$ $\rightarrow region$
Inst (getTimestamp)	$intime(\alpha)$	$\rightarrow instant$
Val (getValue)	$intime(\alpha)$	$\rightarrow \alpha$

Unary operations on temporal types

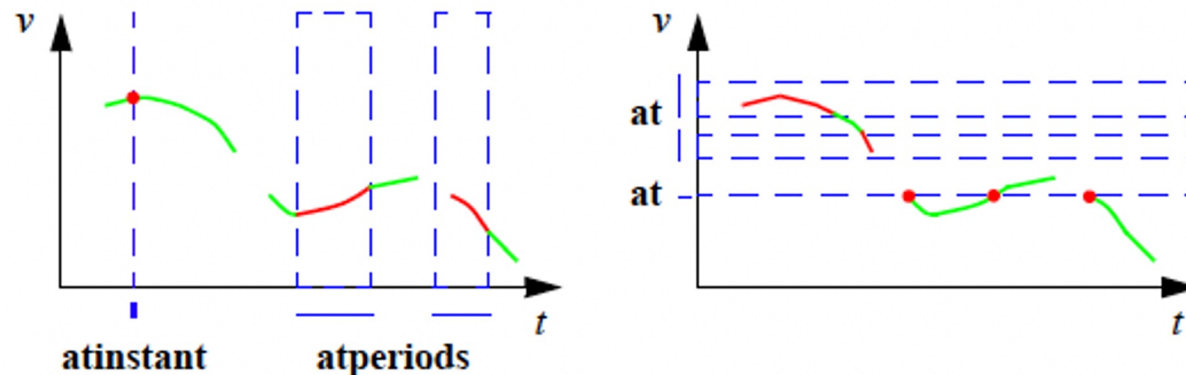
Interaction with points and point sets in domain or range

atinstant and **atperiods** (**atTime**): restrict the function to a given instant of time or set of time intervals, respectively

at (or **atValues**): restricts to a point or point set in the range of the function.

- If a *temporal(point)* is restricted by a region, the result is a *temporal(point)*.
- If a *temporal(region)* is restricted by a point value, the result is a *temporal(point)*

For a *temporal(real)*:



Unary operations on temporal types

Interaction with points and point sets in domain or range

atmin and **atmax** restrict the function to the minimum and maximum values of the base types

initial and **final** (**startinstant**, **endinstant**) return the (**instant**, **value**) pairs for the first and last instant of the definition time

startInstant returns a (value, inst) pair, i.e., an **intime** value.

present: checks whether the temporal function is/has been ever defined at a time instant or in a given set of time intervals

Unary operations on temporal types

Interaction with points and point sets in domain or range

Operation	Signature	
atInstant (atTime)	$temporal(\alpha) \times instant$	$\rightarrow intime(\alpha)$
atPeriods (atTime)	$temporal(\alpha) \times periods$	$\rightarrow temporal(\alpha)$
initial, final (startInstant, endInstant)	$temporal(\alpha)$	$\rightarrow intime(\alpha)$
present	$temporal(\alpha) \times instant$ $temporal(\alpha) \times periods$	$\rightarrow bool$ $\rightarrow bool$
at (atValues)	$temporal(\alpha) \times \beta$ $temporal(\alpha) \times \beta$	$\rightarrow temporal(\alpha)$ $\rightarrow temporal(min((\alpha, \beta)))$
atmin, atmax	$temporal(\alpha)$	$\rightarrow temporal(\alpha)$
passes	$temporal(\alpha)$	$\rightarrow bool$

Operations over time and interval types

Time constants constructors

<i>Operation</i>	<i>Signature</i>	
year	<u><i>int</i></u>	→ <u><i>periods</i></u>
month	<u><i>int</i></u> × <u><i>int</i></u>	→ <u><i>periods</i></u>
day	<u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u>	→ <u><i>periods</i></u>
hour	<u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u>	→ <u><i>periods</i></u>
minute	<u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u>	→ <u><i>periods</i></u>
second	<u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u> × <u><i>int</i></u>	→ <u><i>periods</i></u>
period	<u><i>periods</i></u> × <u><i>periods</i></u>	→ <u><i>periods</i></u>

Ex.: year denotes the interval comprising the time between the first and last instant of a year

The basic constructors are already given in any programming language

For example in Postgres we have `SELECT extract(hour from timestamp '2002-09-17 19:27:45');`

period(date1, date2) constructs the time interval ranging from the first instant of date1 to the last instant of date2

Operations over time and interval types

Interval constructors

Operation	Signature	
range	$\alpha \times \alpha$	$\rightarrow \text{range}(\alpha)$
open, closed, leftclosed, rightclosed	$\text{range}(\alpha)$	$\rightarrow \text{range}(\alpha)$
minint, maxint		$\rightarrow \text{int}$
minfloat, maxfloat		$\rightarrow \text{float}$
mininstant, maxinstant		$\rightarrow \text{instant}$

range: builds the closed interval of the given argument values.

open, closed, leftclosed, and rightclosed: construct open or half-open intervals given a range provided

Lifted binary operations

- Consider an operation **op** with signature

$$\alpha_1 \times \alpha_2 \times \dots \times \alpha_n \rightarrow \beta$$

- Lifting allows any of the argument types to be replaced by the respective temporal type and *return a corresponding temporal type*. **The lifted version of op** has signatures:

$$\alpha_1' \times \alpha_2' \times \dots \times \alpha_n' \rightarrow \beta. \text{ Where } \alpha_i' \in \{\alpha_i, \text{moving}(\alpha_i)\}.$$

- Eg.: The **equality** operation on real numbers with signature:

$$= \text{float} \times \text{float} \rightarrow \text{bool}$$

has lifted versions

$$= \text{temporal}(\text{float}) \times \text{float} \rightarrow \text{temporal}(\text{bool})$$

$$= \text{float} \times \text{temporal}(\text{float}) \rightarrow \text{temporal}(\text{bool})$$

$$= \text{temporal}(\text{float}) \times \text{temporal}(\text{float}) \rightarrow \text{temporal}(\text{bool})$$

Lifted binary operations

- The **intersection** operation with signature

***intersection** $point \times region \rightarrow point$*

has **lifted** versions

tintersection *$temporal(point) \times region \rightarrow temporal(point)$*

tintersection *$point \times temporal(region) \rightarrow temporal(point)$*

tintersection *$temporal(point) \times temporal(region) \rightarrow temporal(point)$*

- The **distance** operation with signature

***distance** $point \times point \rightarrow float$*

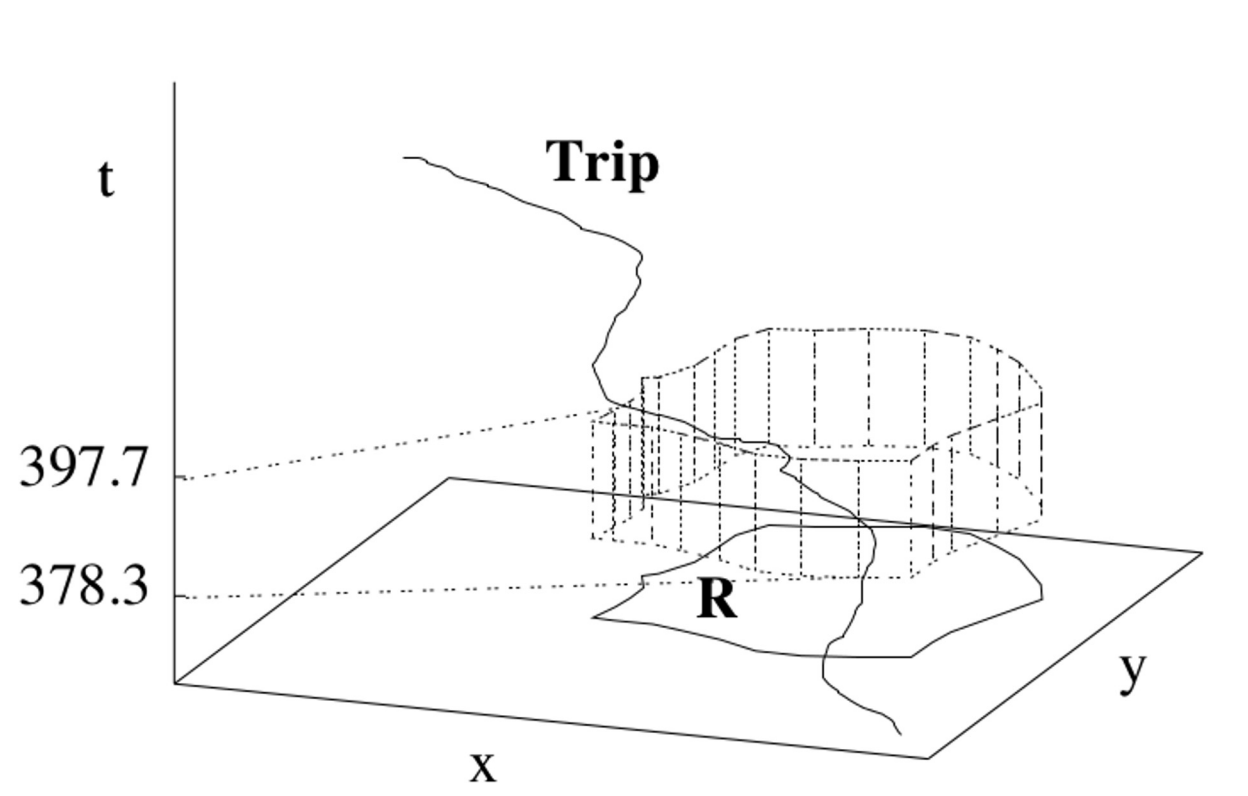
has **lifted** versions

tdistance (**<-->**) *$temporal(point) \times point \rightarrow temporal(float)$*

tdistance (**<-->**) *$point \times temporal(point) \rightarrow temporal(float)$*

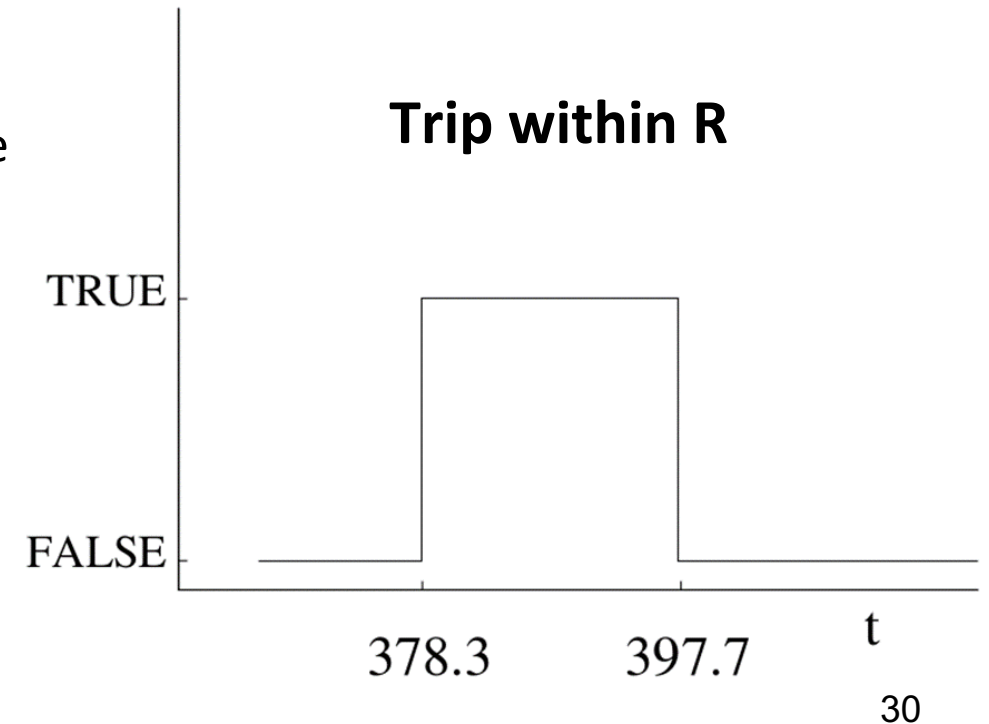
tdistance (**<-->**) *$temporal(point) \times temporal(point) \rightarrow temporal(float)$*

Spatiotemporal predicates

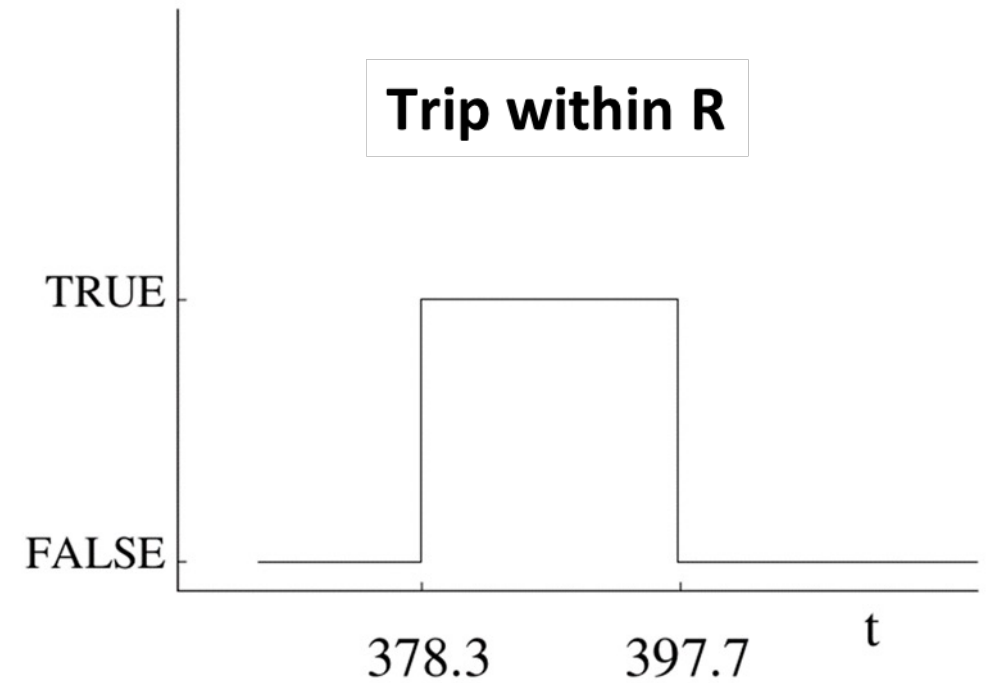
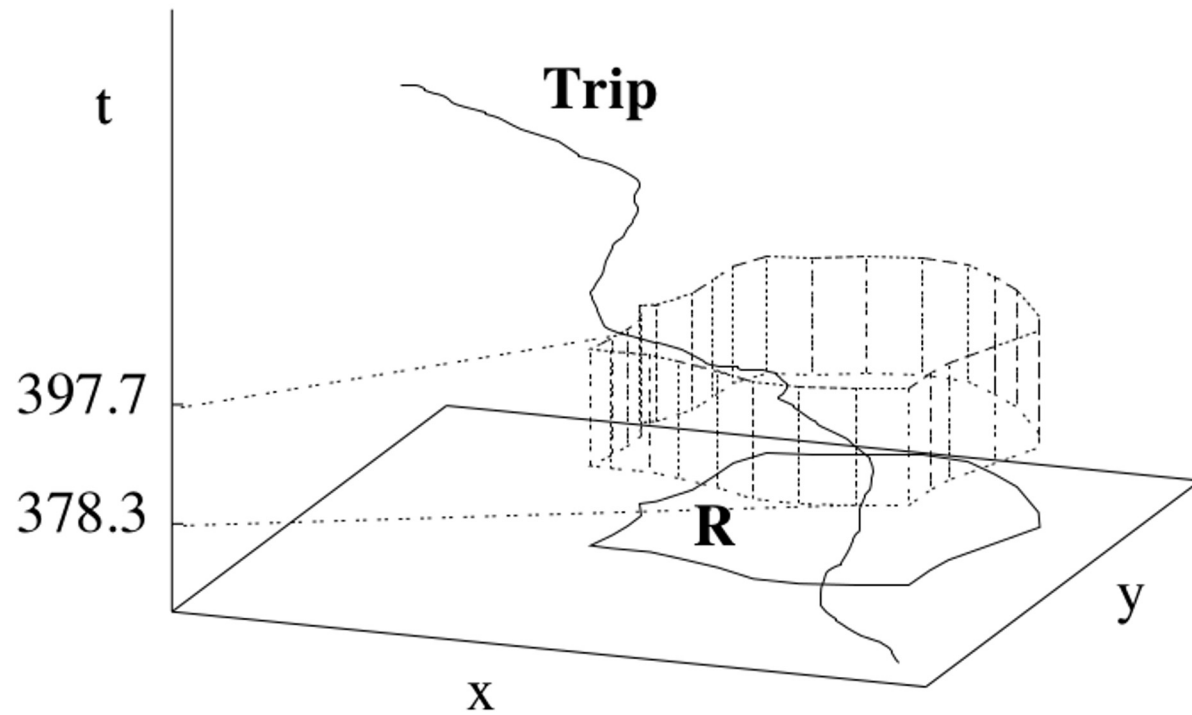


Lifted topological predicates

- A **temporally lifted** topological predicate is a function from two spatio-temporal data types to *temporal(bool)*
- Example **within:** *point x region → bool*
 within: *temporal(point) x temporal(region) → temporal(bool)*
- **within** yields *true* for each time point at which the moving point is inside the evolving region, undefined (\perp) when the point or region is undefined, *false* in all other cases.



Spatiotemporal predicates



Lifting operations

We now have available in our query language all the operations of the algebra in their lifted versions:

- predicates
- set operations
- aggregation operations
- numeric operations
- distance and direction operations
- Boolean operations

We now give examples of queries that can be expressed over this abstract model

Queries over the abstract model (in red temporal types)

- Example Schema:

Trips (TripId: int, TripDate: date, VehId: int, Trip: **tgeompoint**)

- Query 1: Trips longer than 50 kms

```
SELECT TripId
FROM Trips
WHERE length(trajectory(Trip)) > 50
```

- Query 2: Which are the trips that took less than two hours?

```
SELECT TripId
FROM Trips
WHERE duration(Trip) <= 2
```

Queries (extended schema)

- Extended Schema:

```
Trips    (TripId: int, TripDate: date, VehId: int, Trip: tgeompoint)
Vehicles (VehId int, Licence text, Type text, Model text);
Points   (PointId int, PosX float, PosY float, Type text, Geom Geometry(Point))
Communes (CommuneId int, Name text, Area float, Geom Geometry(Polygon),...)
Weather  (Kind: string, Area: tregion)
```

- Query 3: Find all pairs of vehicles that during their trip came closer to each other than 500 meters

```
SELECT A.TripId, B.TripId
FROM   Trips A, Trips B
WHERE  A.TripId < B.TripId and minValue(tdistance(A.Trip, B.Trip)) < 0.5
```

- Query 4: Which trips passed through the commune of Ixelles?

```
SELECT id
FROM Trips, Communes
WHERE Name = 'Ixelles' and duration(tintersection(Trip, Area)) > 0
```

Queries (cont.)

```
WITH Brussels AS (Select ST_UNION (Area) as Area FROM Communes)
WITH Storm AS    (SELECT Area FROM weather WHERE Kind = 'Snow Storm'),
WITH TripLic AS  (SELECT Trip FROM Trips T JOIN Vehicles V on T.VehId = V. VehId
                  WHERE Licenseid = 'ABC393')
```

- **Query 5:** *Duration of snowstorms over Brussels*

```
SELECT duration(getTime(atGeometry(Storm.Area, (SELECT Brussels.Area FROM Brussels))))
FROM Storm
```

- **Query 6:** *Where was vehicle with license ABC393 during snowstorms in Brussels?*

```
SELECT trajectory(atTime(Trip, getTime(atGeometry(Storm.Area, (SELECT Brussels.Area
FROM Brussels))))
FROM TripsLic, Storm
```

Queries (cont.)

- **Query 7:** *At what times did the area of a storm shrink?*

```
SELECT getTime(atValues(derivative(Storm.Area), open(range(minreal, 0))))  
FROM Storm
```

open(**range**(minreal, 0)) means that the derivative is negative.

- **Query 8:** *Show the parts of the route of the trips of vehicle with licence 'ABC393' when the vehicle's speed was at least 30 km/h.*

```
SELECT trajectory(atTime(Trip, getTime(atValues(speed(Trip), range(30, maxreal))))  
FROM TripLic
```

Lifting operations

- **Query 9:** *At what times did storms split into two separate parts?*

```
SELECT  inst(initial(atValues(no_components(Storm.Area), range(2,2))))  
FROM Storm
```

Here `no_components` returns a *temporal(int)* which by the `atValues` operation is reduced to the times when it has value "2"; `initial` is a (value,time) pair and `inst` takes the time instant of the pair.

- **Query 10:** *Compute for each airport the minimal distance ever from the center of a storm*

```
WITH Airport AS (SELECT Geom FROM Points WHERE Type = 'Airport')
```

```
SELECT id, val(initial(atmin(tdistance(center(Storm.Area), pos(PosX, PosY)))))  
FROM Airport, Storm
```

`atmin` returns the *moving real (tdistance)* when Lizzy was closest to the airport across time, `initial(startInstant in MobilityDB)` returns the initial *intime* of this moving real, and `val(getValue in MobilityDB)` obtains the value of the (value, instant) pair. The instant would be obtained with `getTimestamp`.

The **When** operation

- An operation that restricts a temporal value (or moving object) to the times when a condition is fulfilled.

Example:

- **Query 11:** *List the trips when their speed was over 80 km/h*

```
SELECT Trip from Trips when Speed(Trip) > 80;
```

The semantics is:

```
SELECT atperiods(Trip, getperiods(atValues(speed(Trip) #>80), true)
FROM Trips
WHERE Speed(Trip) > 80
```

- The semantics of this operator can be implemented using lifted functions

```
SELECT atperiods(Trip, getTime(atValues(speed(Trip) > 80, true)))
FROM Trips
```

Lifted predicates semantics

- For each lifted predicate there is a preferred temporal semantics
- Example:
 - “A plane route did not encounter a storm” -> disjointedness **during the whole common lifetime** (\forall_{\cap} disjoint)
 - “species living in a climatic region” -> “insideness” **using the species lifetime** (\forall_{π_1} within)
- For some spatio-temporal predicates the default expected behavior is existential
- For **two moving regions** there are 8 possible predicates
- For a **temporal point and a temporal region** there are three basic predicates **Disjoint**, **Meet**, and **Contains/Inside**
- For **two moving points** (only possibility in MobilityDB) we have two predicates: **Disjoint** and **Meet**

Basic spatiotemporal predicates

For two **moving regions** we have the following predicates (lowercase for non-temporal, uppercase temporal):

Disjoint	$:=$	$\forall_{\cap} \text{disjoint}$
Meet	$:=$	$\forall_{\cup} \text{meet}$
Overlap	$:=$	$\forall_{\cup} \text{overlap}$
Equal	$:=$	$\forall_{\cup} \text{equal}$
Covers	$:=$	$\forall_{\pi} \text{covers}$
Contains	$:=$	$\forall_{\pi^2} \text{contains}$
CoveredBy	$:=$	$\forall_{\pi^2} \text{coveredBy}$
Inside	$:=$	$\forall_{\pi^1} \text{inside}$

For example, **Disjoint** means disjointness throughout the whole intersection of the lifespans.

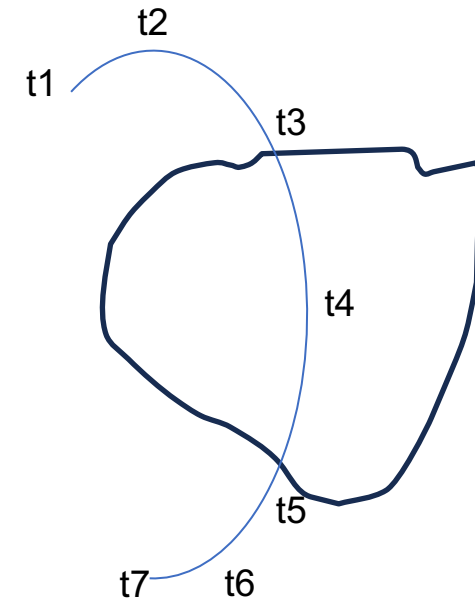
For a **temporal point** and a **temporal region** we have the three basic predicates **Disjoint**, **Meet**, and **Contains/Inside**.

For **two moving points** (only possibility in MobilityDB) we have the predicates **Disjoint** and **Meet**

Composition of spatiotemporal predicates

- We can combine basic spatiotemporal predicates to capture change of spatial situation over time
- Relationships between two spatio-temporal objects modeled by sequences of spatial and (basic) spatiotemporal predicates
- Example: a moving point enters a (temporal) region, then exits it, and finally reenters the region (that is, *P crosses R*). At **t2** *P* is outside *R*. At **t4** *P* is inside *R* (*P enters R*). At **t6** it is outside *R* again.

Predicate	Holds	Observation
Disjoint(<i>P</i> , <i>R</i>)	During $I_1 = [t_1, t_3)$	t2 $\in I_1$
meet(<i>P</i> , <i>R</i>)	at t_3	
Inside(<i>P</i> , <i>R</i>)	During $I_2 = (t_3, t_5)$	t4 $\in I_2$
meet(<i>P</i> , <i>R</i>)	at t_5	
Disjoint(<i>P</i> , <i>R</i>)	During $I_3 = (t_5, t_7]$	t6 $\in I_3$



Composition of spatiotemporal predicates

- Compositions are denoted by a sequence of predicates
- Example:
 - **Disjoint** \triangleright **meet** \triangleright **Inside** \triangleright **meet** \triangleright **Disjoint**
 - This is an abbreviation for: **Disjoint** until **meet** then (**Inside** until **meet** then **Disjoint**)
- Notation: **meet** is a spatial predicate, **Inside**, **Disjoint**, **Meet** (capitalized) are spatiotemporal predicates
- We can define other predicates in a natural way.
- For a *tpoint* and a *tregion*:

Enter := **Disjoint** \triangleright **meet** \triangleright **Inside**

Cross := **Disjoint** \triangleright **meet** \triangleright **Inside** \triangleright **meet** \triangleright **Disjoint**

- For two *tregions*:

Cross := **Disjoint** \triangleright **meet** \triangleright **Overlap** \triangleright **coveredBy** \triangleright **Inside** \triangleright
coveredBy \triangleright **Overlap** \triangleright **meet** \triangleright **Disjoint**

Composition of spatiotemporal predicates

- Consider again the tables Trips, and Weather

Trips (TripId: int, TripDate: date, VehId: int, Trip: tgeompoint)

Weather(Kind: string, Extent: tregion)

Query 12: “Determine the trips entering a snowstorm in the road”.

- *Problem: For each car/snowstorm combination check whether the car and the storm were disjoint for a while, then they met at one point in time, and the car was inside the storm for a while*
- *The development of entering a storm is only true **if each of the three subqueries are true** and if they **have occurred one after the other***
- *This can be written as the next slide shows*

Composition of spatiotemporal predicates

Query 12: “Determine the trips entering a snowstorm in the road and ending during the storm.”

Answer **without using the spatiotemporal predicates**

```
SELECT id
FROM Trips, Weather
WHERE kind = "snowstorm" AND
      not (getValue (atTime (Trip, startTimestamp (getTime (Trip)))) within
            getValue (atTime (Extent, startTimestamp (getTime (Trip)))) AND
            getValue (atTime (Trip, endTimestamp (getTime (Trip)))) within
            getValue (atTime (Extent, endTimestamp (getTime (Trip))))
```

- First compute the starting time of the trip (**startTimestamp(getTime(Trip))**), then the (time, point)-pair is computed at this instant by the operation **atTime**. The **extent** of the storm at that instant is determined as a region.
- If **within** is false, the car was outside of the storm when starting the trip
- Similarly, we compute the end of the trip (**endTimestamp(getTime(Trip))**). If **within** is true, then the car must have entered the storm and ended within the latter.

Credits - Readings

These slides were based on material from:

Modeling and Querying History of Movement. Ch.4, Moving Objects Databases, Ralf Hartmut Güting, Markus Schneider, 2005

Güting, Ralf & Böhlen, Michael & Erwig, Martin & Jensen, Christian & Lorentzos, Nikos & Schneider, Markus & Vazirgiannis, Michalis. A Foundation for Representing and Querying Moving Objects. ACM Transactions on Database Systems (TODS). 25. 1-42, 2000

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