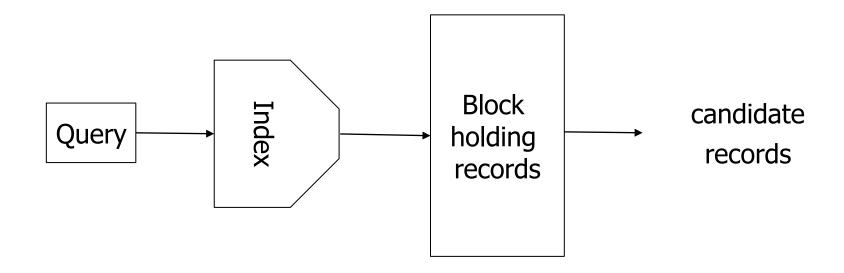
# Indexing

Hector Garcia-Molina Mahmoud Sakr

# **Indexing**



## **Topics**

- Conventional indexes
- B-trees
- Hashing schemes

### Sequential File

| 10 |  |
|----|--|
| 20 |  |

| 30 |  |
|----|--|
| 40 |  |

| 50 |  |
|----|--|
| 60 |  |

| 70 |  |
|----|--|
| 80 |  |

#### Dense Index

### Sequential File

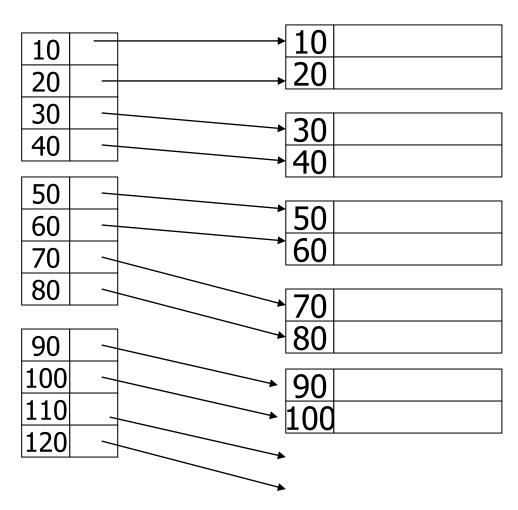
Dense Index = a pointer per key

How to search for a key= 30?

How to search for a key= 25?

Can we use a dense index on a non-sequential file?

Why querying a dense index is more efficient than querying the sequential file?



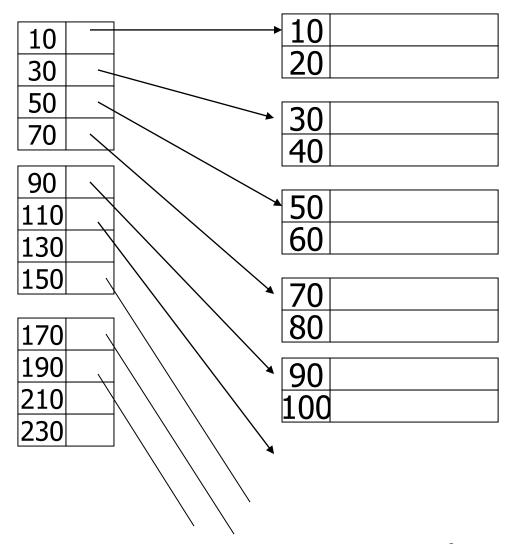
### Sparse Index

### Sequential File

Sparse index = a pointer per block

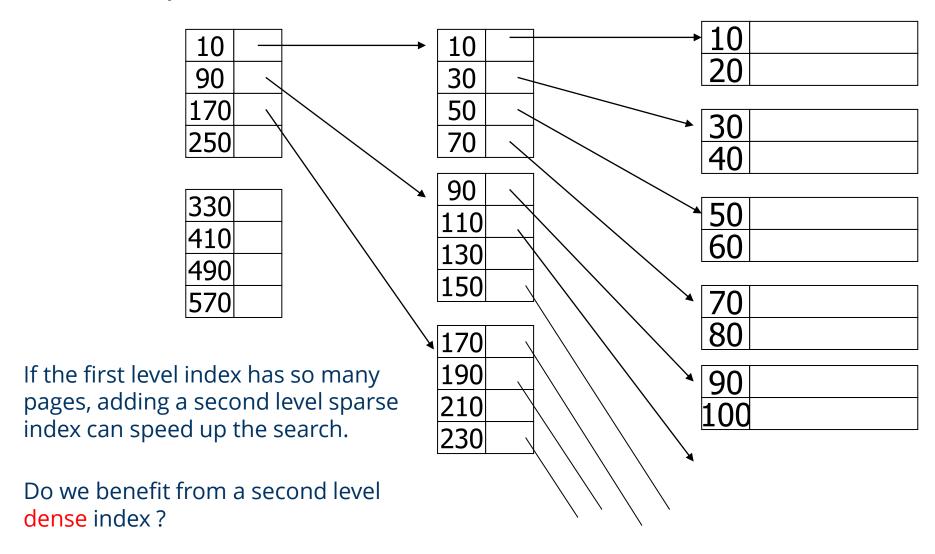
How to search for a key= 30? How to search for a key= 25?

Can we use a sparse index on a non-sequential file?



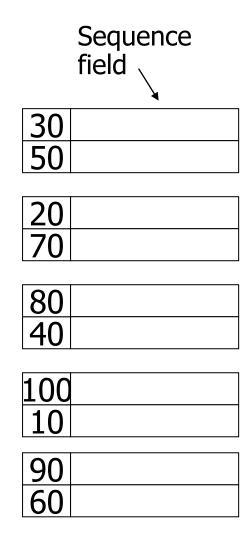
### Sparse 2nd level

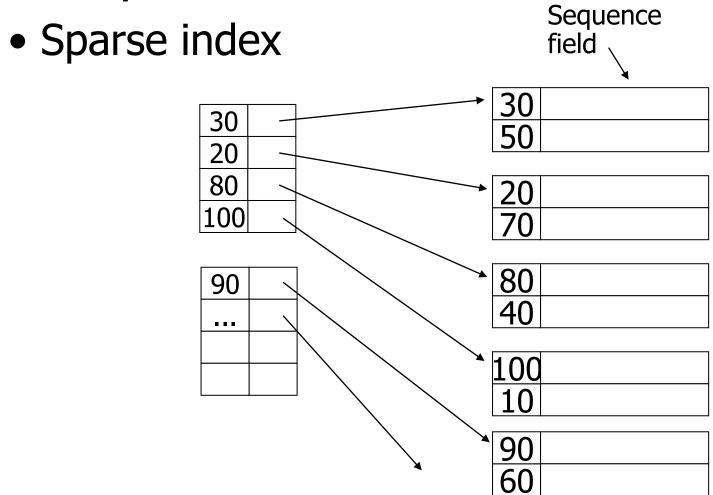
### Sequential File

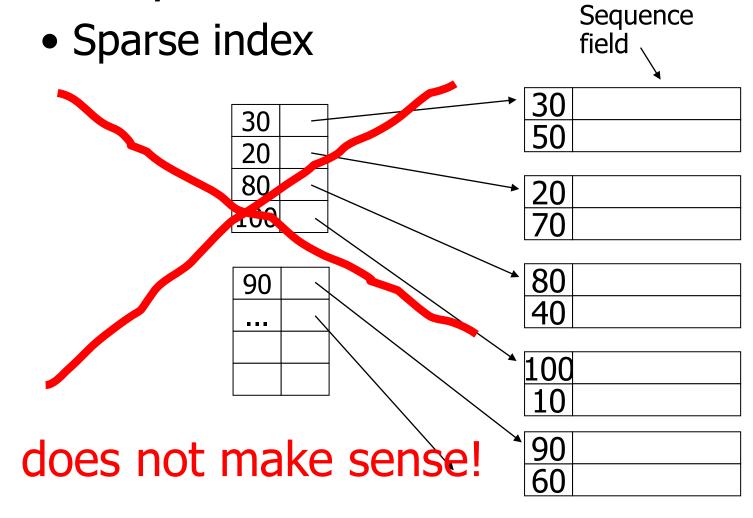


### Sparse vs. Dense Tradeoff

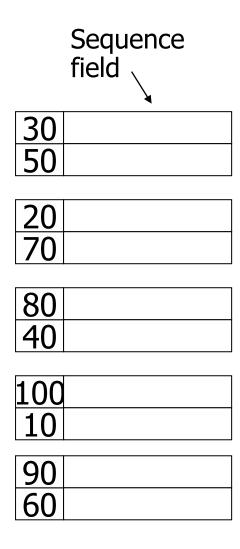
- Sparse: Less index space per record can keep more of index in memory
- Dense: Can tell if any record exists without accessing file



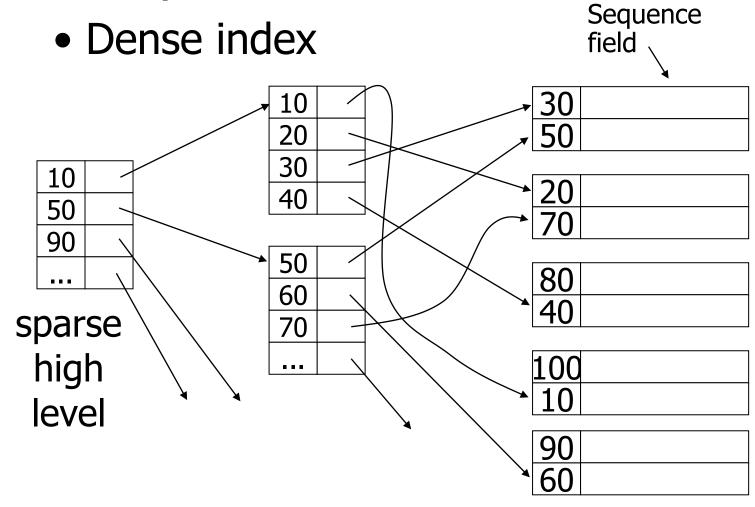




Dense index



Sequence Dense index field 



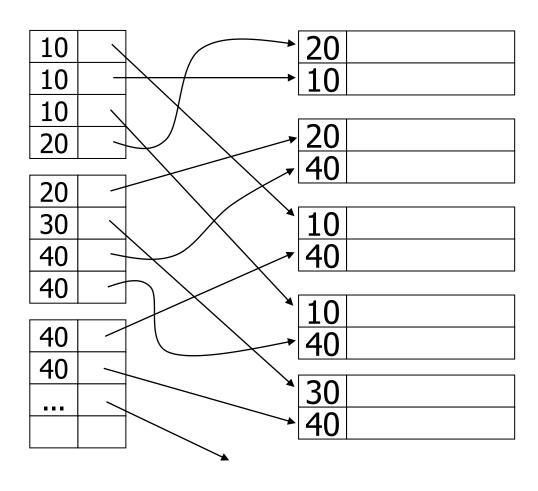
## With secondary indexes:

- Lowest level is dense
- Other levels are sparse

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| 20              |  |
|-----------------|--|
| 20<br>10        |  |
|                 |  |
| 20              |  |
| <u>20</u><br>40 |  |
|                 |  |
| 10<br>40        |  |
| 40              |  |
|                 |  |
| 10              |  |
| 10<br>40        |  |
|                 |  |
| 30<br>40        |  |
| 40              |  |

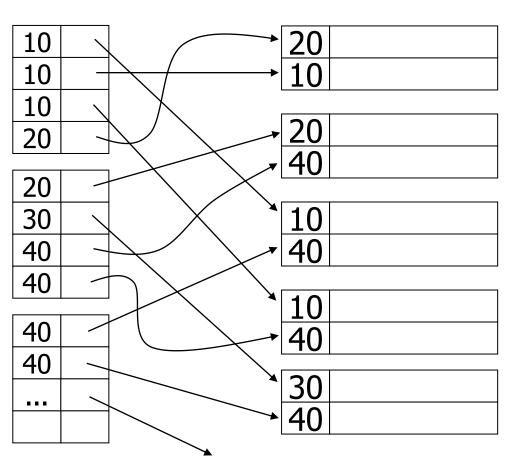
one option...



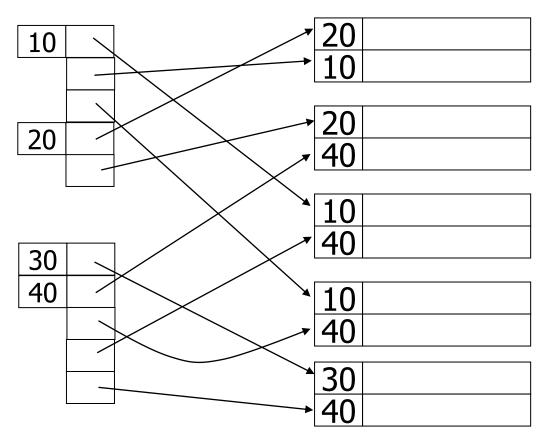
one option...

# Problem: excess overhead!

- disk space
- search time

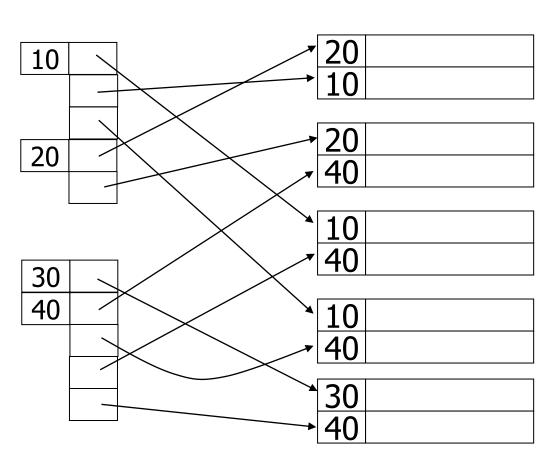


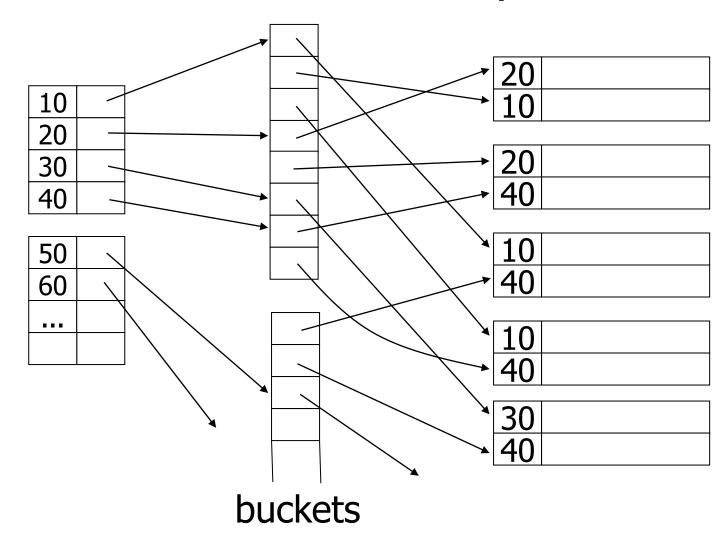
another option...



another option...

Problem:
variable size
records in
index!





# Why "bucket" idea is useful

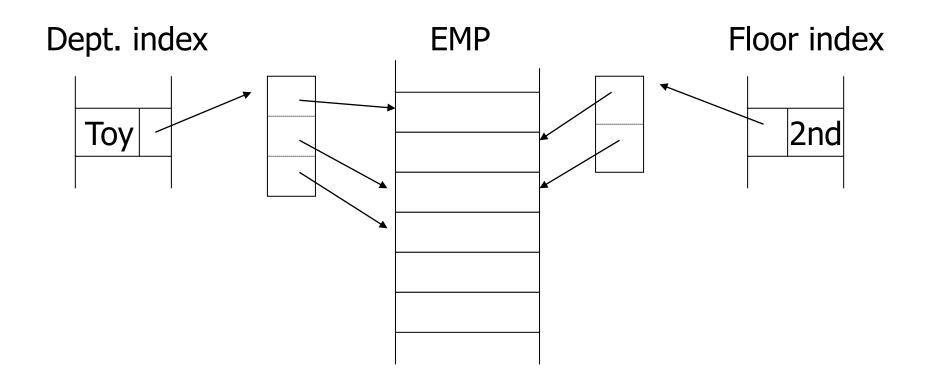
<u>Indexes</u> Records

Name: primary EMP (name,dept,floor,...)

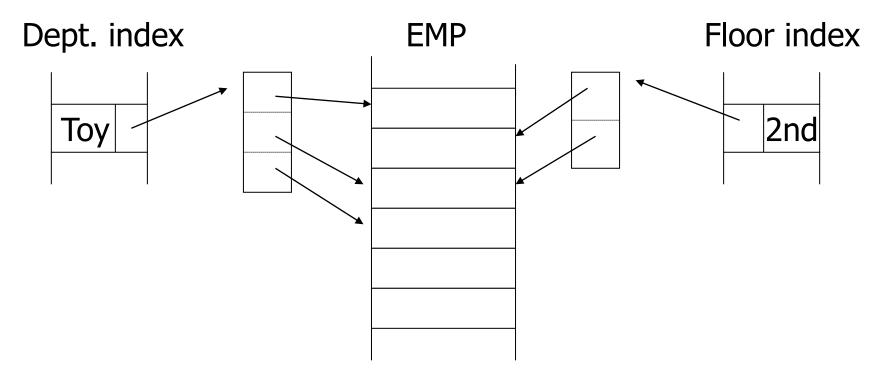
Dept: secondary

Floor: secondary

# Query: Get employees in (Toy Dept) \( \lambda \) (2nd floor)



# Query: Get employees in (Toy Dept) \( \triangle \) (2nd floor)



→ Intersect toy bucket and 2nd Floor bucket to get set of matching EMP's

### Conventional indexes

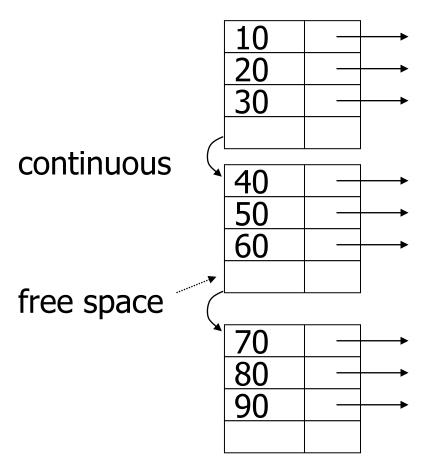
### Advantage:

- Simple
- Index is sequential file good for scans

### **Disadvantage:**

- Inserts expensive, or
- Lose sequentiality & balance

# Example Index (sequential)



#### **Example** Index (sequential) continuous free space <u>70</u> overflow area (not sequential)

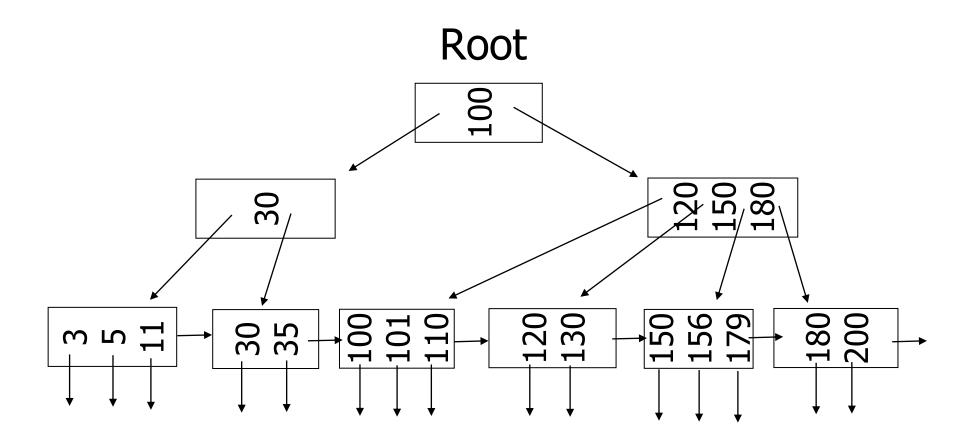
## Outline:

- Conventional indexes
- B-Trees ⇒ NEXT
- Hashing schemes

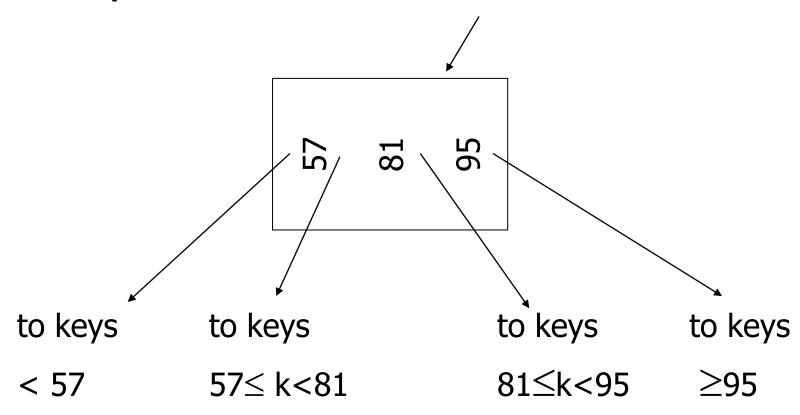
- NEXT: Another type of index
  - Give up on sequentiality of index
  - Try to get "balance"

## **B+Tree Example**

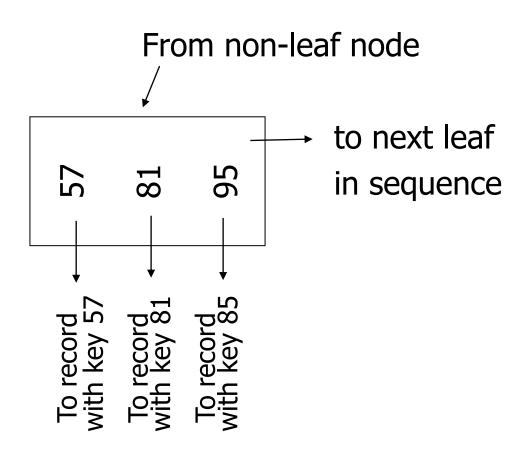
n=3



# Sample non-leaf



# Sample leaf node:



```
Size of nodes: n+1 pointers
n keys
```

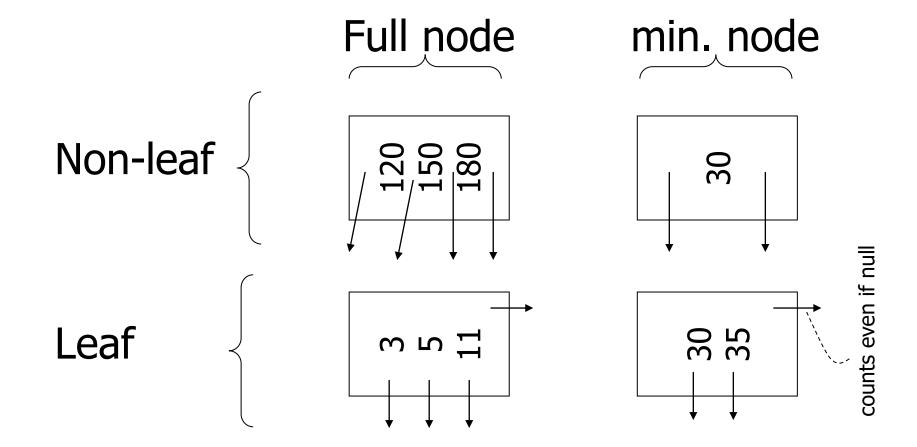
### Don't want nodes to be too empty

Use at least

Non-leaf:  $\lceil (n+1)/2 \rceil$  pointers

Leaf:  $\lfloor (n+1)/2 \rfloor$  pointers to data

### n=3



### B+tree rules tree of order n

- (1) All leaves at same lowest level (balanced tree)
- (2) Pointers in leaves point to records except for "sequence pointer"

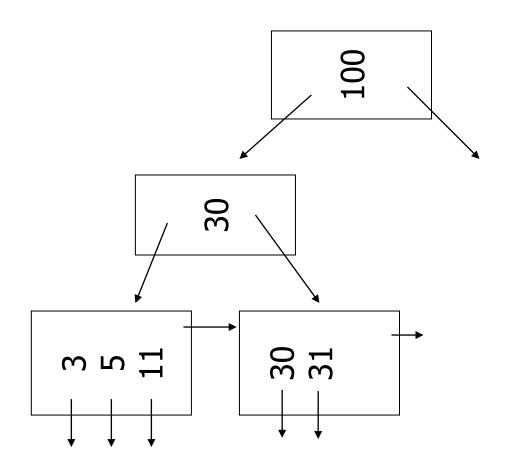
## (3) Number of pointers/keys for B+tree

|                        | Max<br>ptrs | Max<br>keys | Min<br>ptrs→data | Min<br>keys  |
|------------------------|-------------|-------------|------------------|--------------|
| Non-leaf<br>(non-root) | n+1         | n           | 「(n+1)/2         | 「(n+1)/2 - 1 |
| Leaf<br>(non-root)     | n+1         | n           | [(n+1)/2]        | [(n+1)/2]    |
| Root                   | n+1         | n           | 1                | 1            |

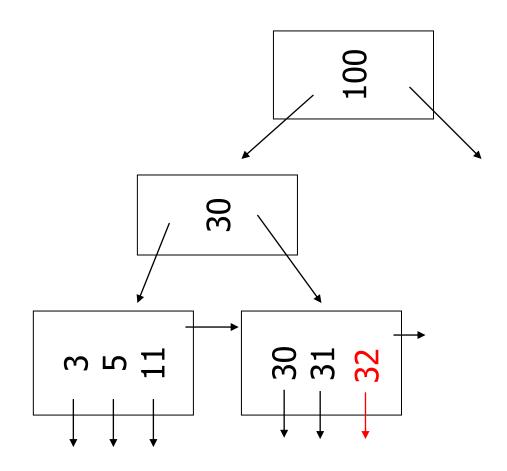
#### Insert into B+tree

- (a) simple case
  - space available in leaf
- (b) leaf overflow
- (c) non-leaf overflow
- (d) new root

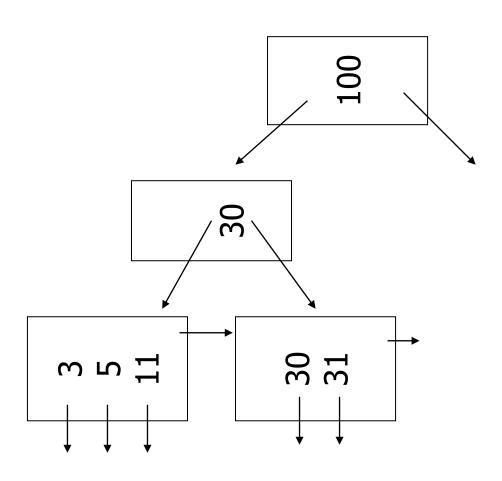


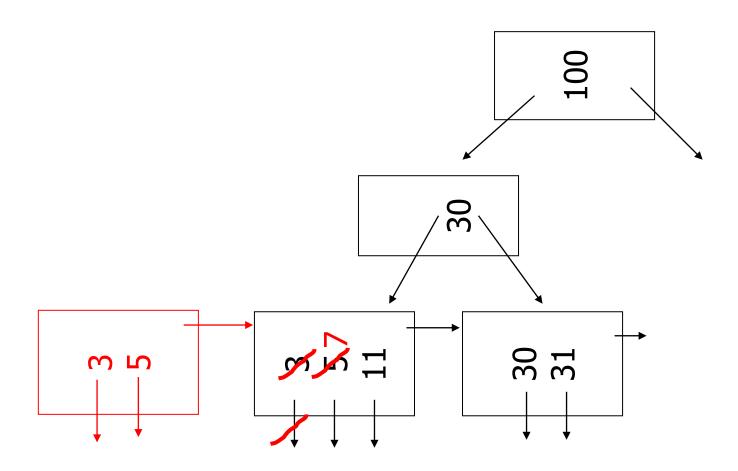




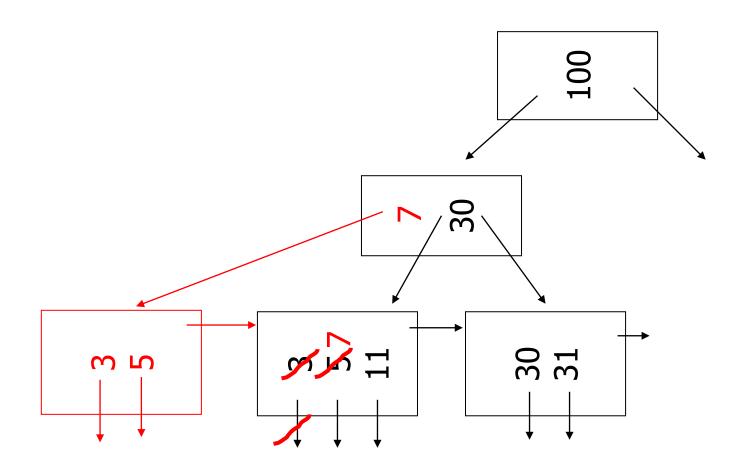


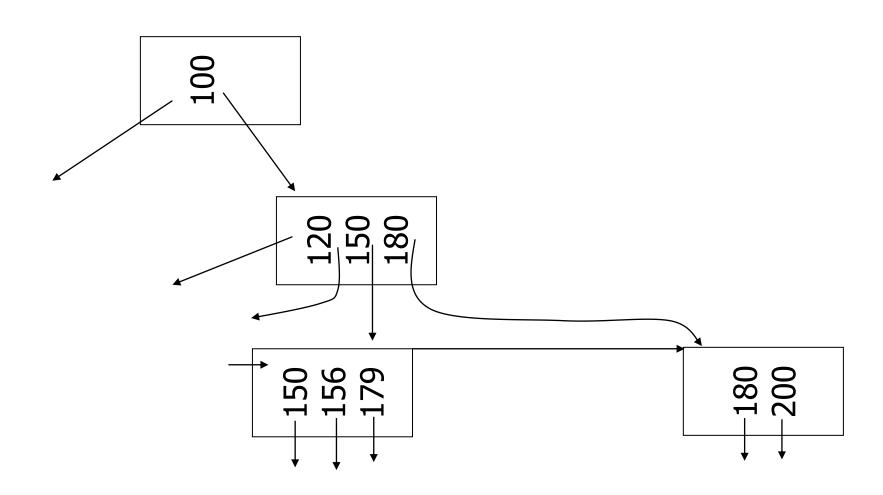


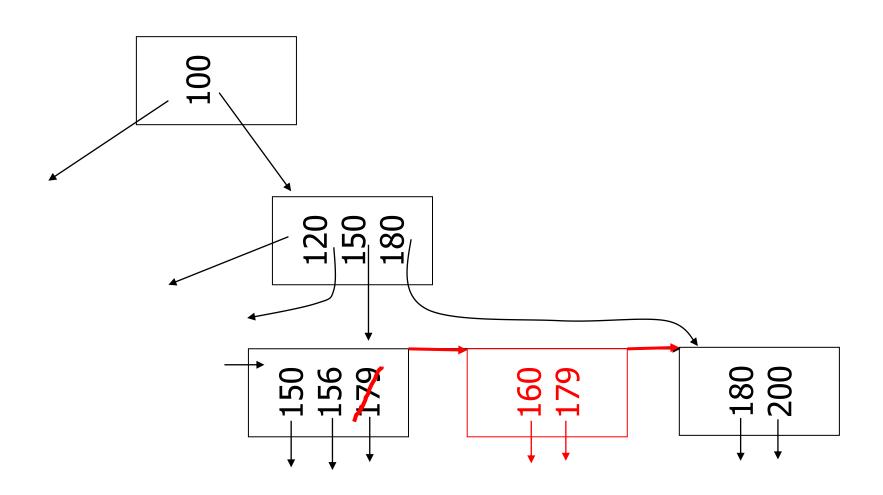




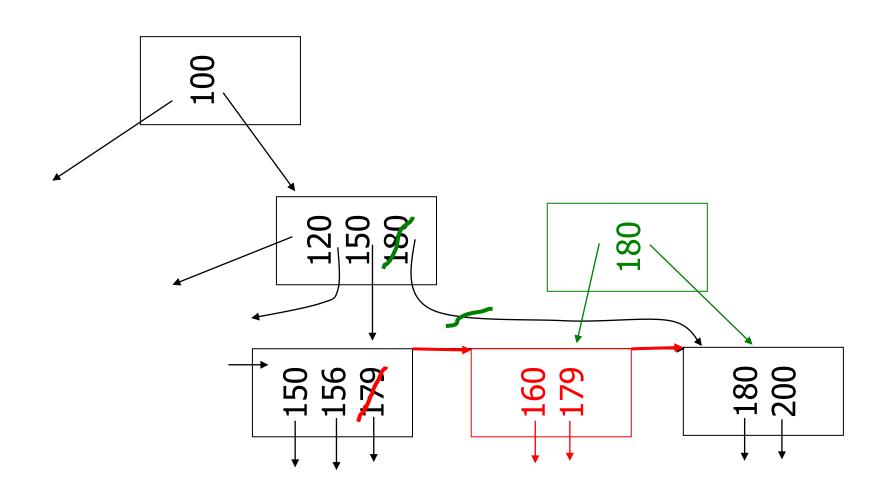




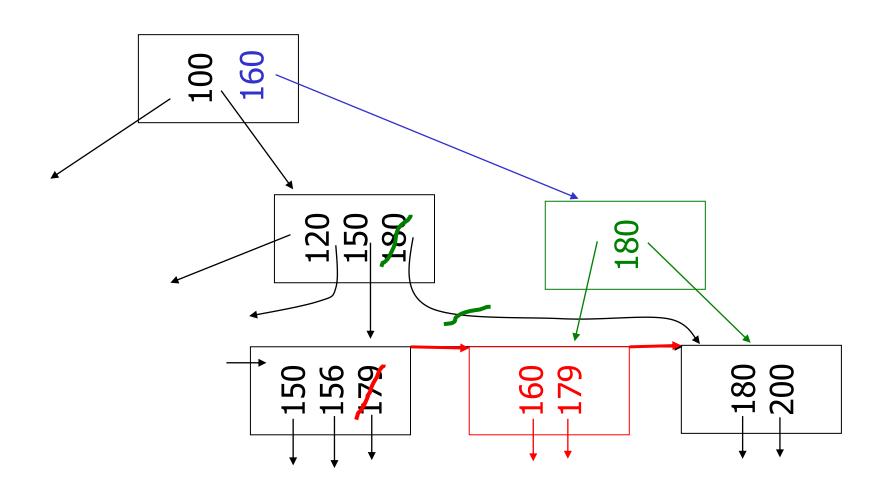


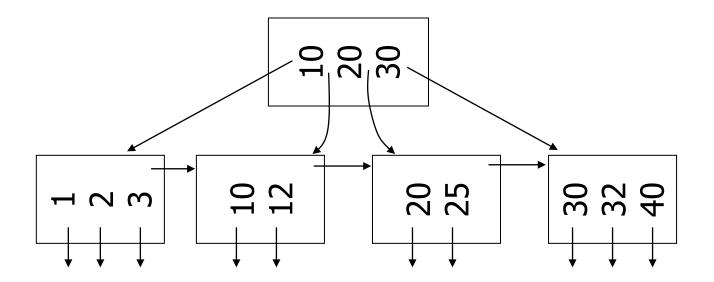


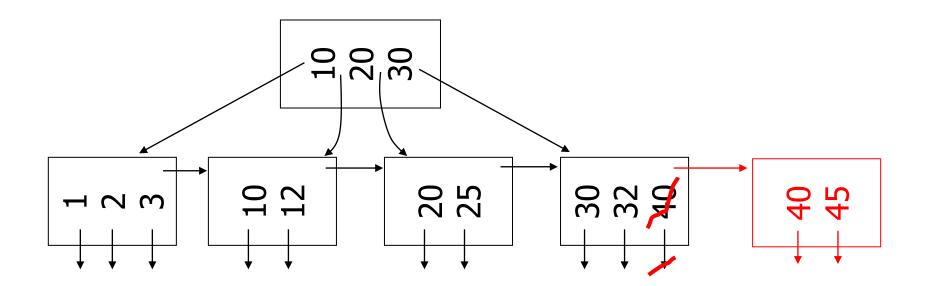


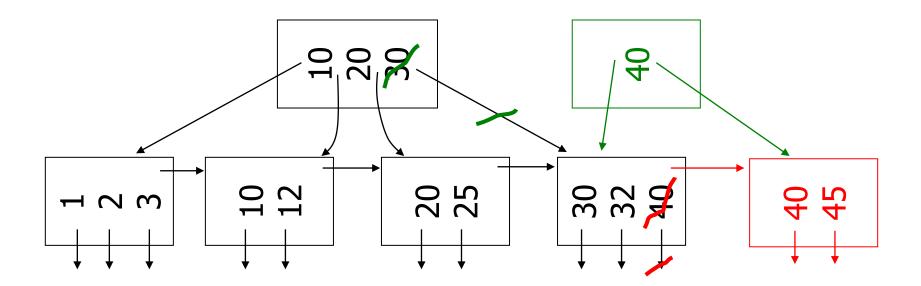


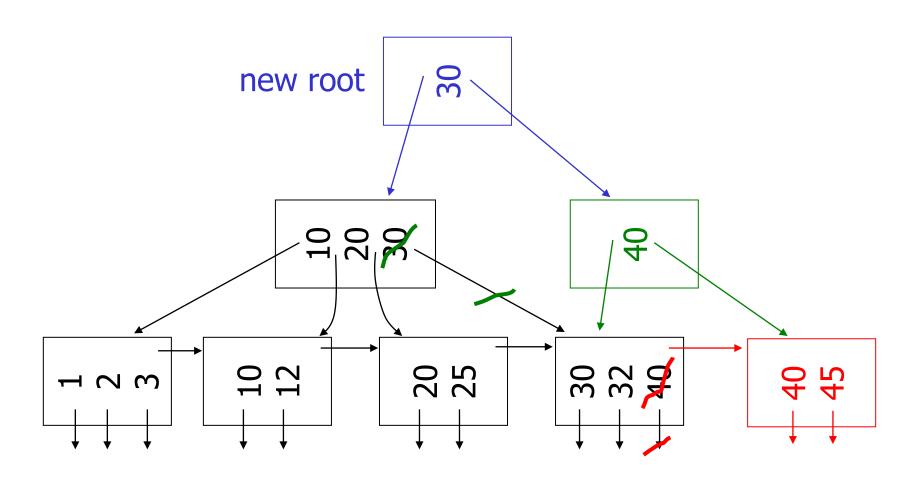










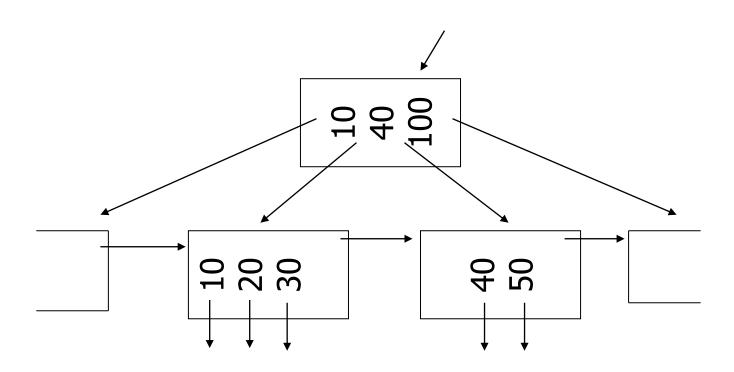


#### <u>Deletion from B+tree</u>

- (a) Simple case no example
- (b) Coalesce with neighbor (sibling)
- (c) Re-distribute keys
- (d) Cases (b) or (c) at non-leaf

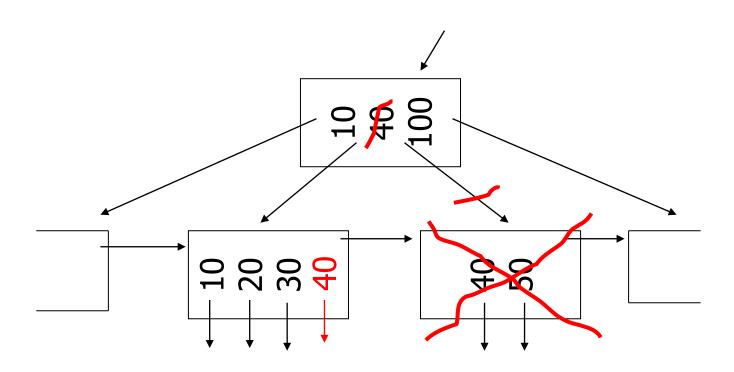
## (b) Coalesce with sibling

- Delete 50

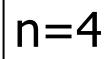


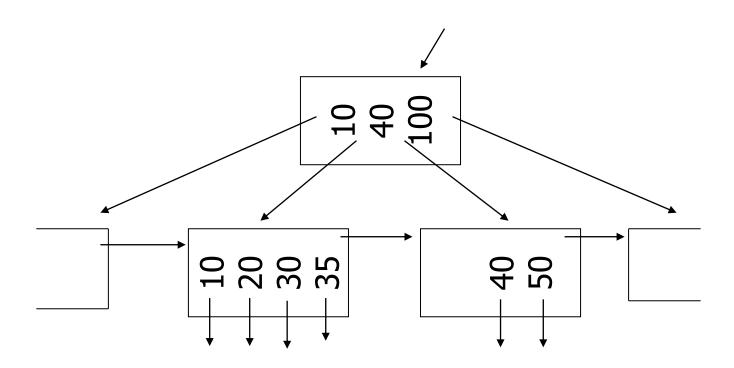
## (b) Coalesce with sibling

- Delete 50

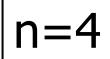


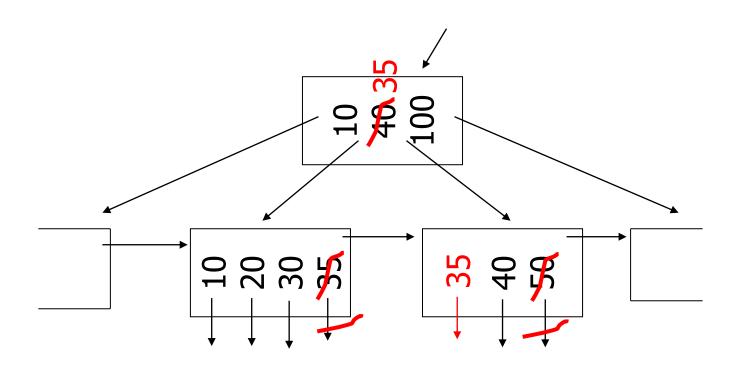
## (c) Redistribute keys

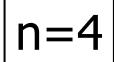


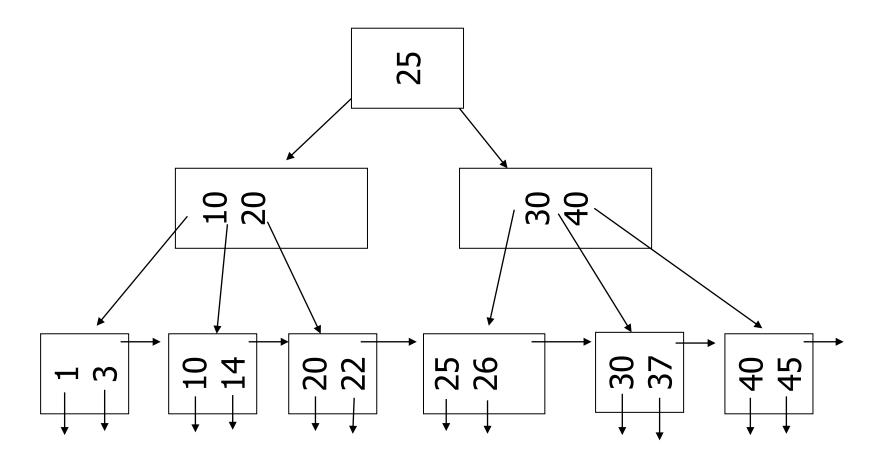


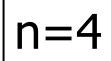
# (c) Redistribute keys

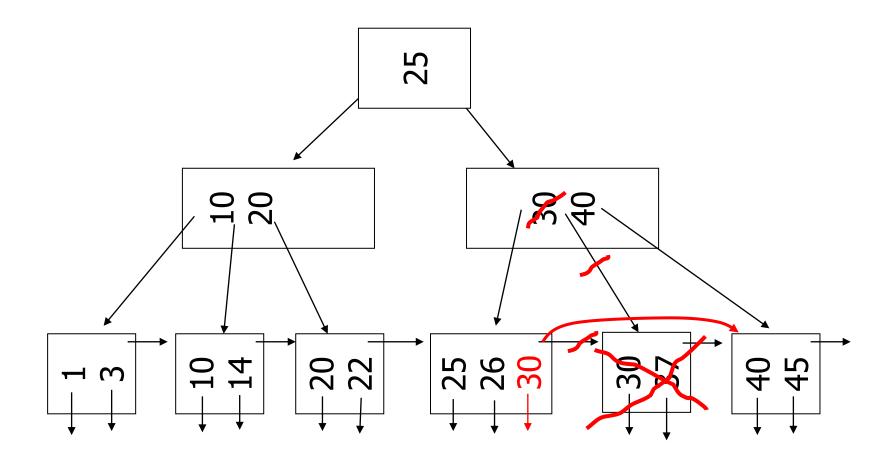




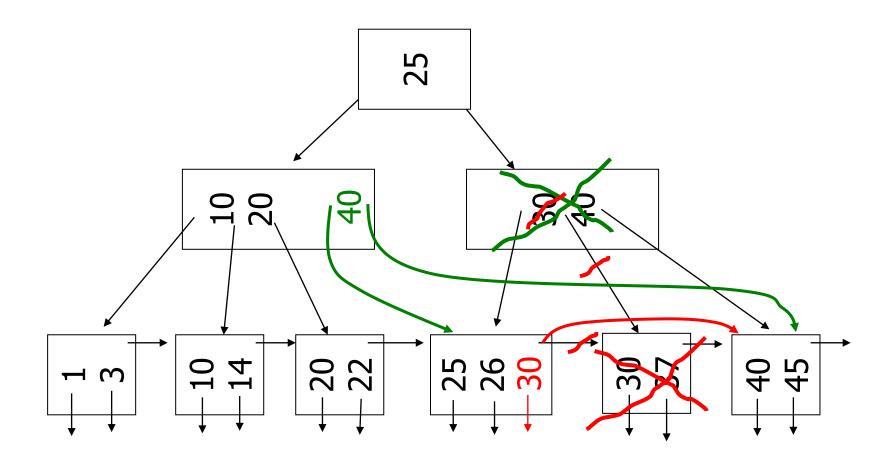




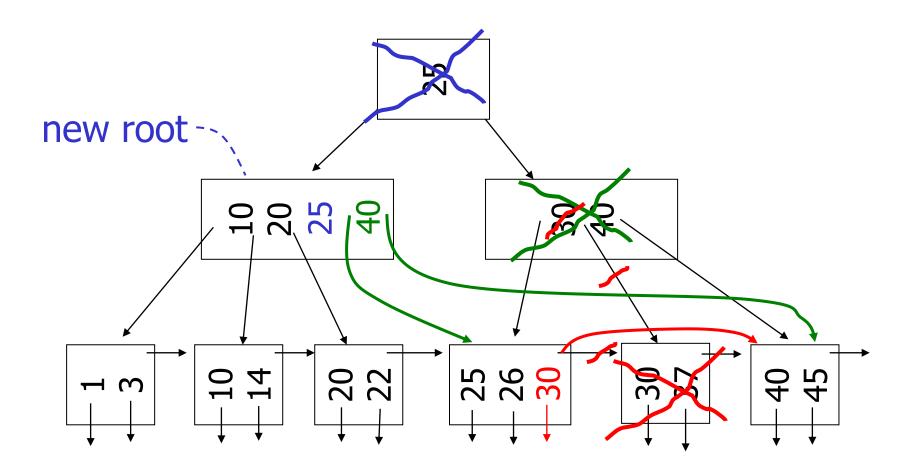




- Delete 37



- Delete 37



# B+tree deletions in practice

- Often, coalescing is <u>not</u> implemented
  - Too hard and not worth it!

# Outline/summary

- Conventional Indexes
  - Sparse vs. dense
  - Primary vs. secondary
- B trees
- Hashing schemes (recommended reading, not mandatory)

#### The slides in this lecture are taken from:

 Hector Garcia-Molina, CS 245: Database System Principles, Notes 4: Indexing.

#### Reading

 Héctor García-Molina, Jeffrey Ullman, and Jennifer Widom. Database Systems: The Complete Book