# Distributed Data Processing

Big Data Management





#### **Knowledge objectives**

- 1. Explain the CAP theorem
- 2. Identify the 3 configuration alternatives given by the CAP theorem
- 3. Explain the 4 synchronization protocols we can have
- 4. Explain what eventually consistency means
- 5. Enumerate the phases of distributed query processing
- 6. Explain the difference between data shipping and query shipping
- 7. Explain the meaning of "reconstruction" and "reduction" in syntactic optimization
- 8. Explain the purpose of the "exchange" operator in physical optimization
- 9. Enumerate the 4 different cost factors in distributed query processing
- 10. Distinguish between response time and query cost
- 11. Explain the different kinds of parallelism
- 12. Identify the impact of fragmentation in intra-operator parallelism
- 13. Explain the impact of tree topologies (i.e., linear and bushy) in inter-operator parallelism
- 14. Explain the limits of scalability





#### Understanding objectives

- Given the overall number of machines in the cluster, identify the consistency problems that arise depending on the configuration of the number of required replicas read and written to confirm the corresponding operations
- 2. Given a parallel system and a workload find the number of machines maximizing throughput (i.e., find the optimal number of machines using the Universal Scalability Law)
- 3. Estimate the cost of a distributed query





#### **Application objectives**

1. Given a query and a database design, recognize the difficulties and opportunities behind distributed query processing





# (Distributed) Transaction Management

Challenge III



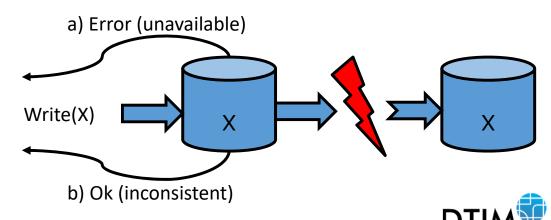


#### **CAP** theorem

"We can only achieve two of Consistency, system Availability, and tolerance to network Partition."

Eric Brewer

- Consistency (C) equivalent to a single up-to-date copy of the data
- High availability (A) of the data (for updates)
- Tolerance to network partitions (P).





#### **Configuration alternatives**

- a) Strong consistency (give availability)
  - Replicas are synchonously modified and guarantee consistent query answering
  - The whole system will be declared not to be available in case of network partition
- b) Eventually consistent (give consistency)
  - Changes are asynchronously propagated to replicas so answer to the same query depends on the replica being used
  - In case of network partition, changes will be simply delayed
- c) Non-distributed data (give network partitioning)
  - Connectivity cannot be lost
  - We can have strong consistency without affecting availability



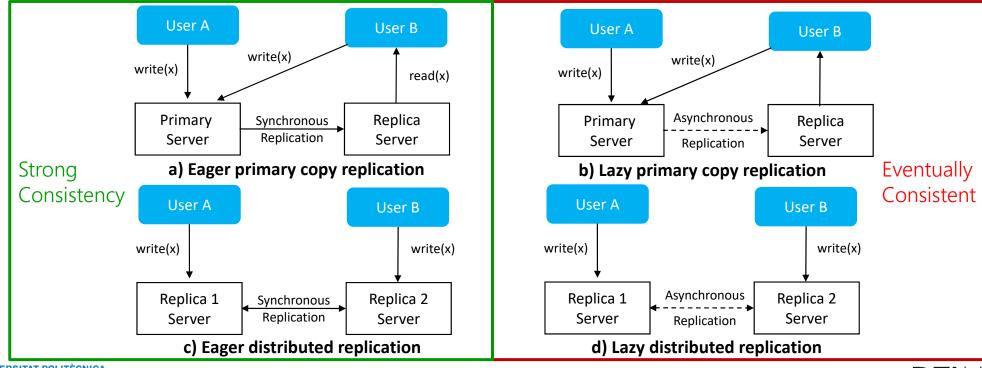
Por <u>segunda vez</u> en menos de una semana, la red social Twitter ha experimentado una caída generalizada de su servicio. En esta ocasión, los enlaces y los vídeos han dejado de funcionar durante algo más de una hora. Tampoco podían tuitearse imágenes, según quejas de distintos <u>usuarios en la red social</u>. La plataforma no funcionaba correctamente en la versión de escritorio de PC y la herramienta TweetDeck tampoco respondía bien.





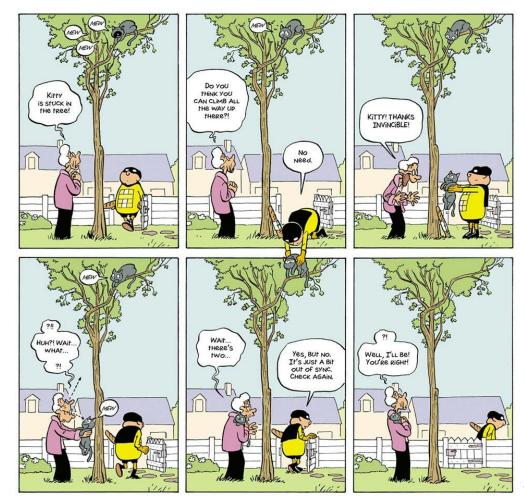
#### Managing replicas

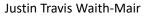
- Replicating fragments improves query latency and availability
  - Requires dealing with consistency and update (a.k.a., synchronization) performance
- Replication protocols characteristics
  - Primary Distributed versioning
  - Eager Lazy replication





#### **Eventual consistency**









#### Replication management configuration

- Definitions
  - N: #replicas
  - W: #replicas that have to be written before commit
  - R: #replicas read that need to coincide before giving response
- Named situations
  - Inconsistency window
  - Strong consistency
  - Eventually consistent
    - Sets of machines (R and W) may not overlap
    - Potential conflict
      - Sets of writing machines (W) may not overlap
- Typical configurations
  - Fault tolerant system
  - Massive replication for read scaling
  - Read One-Write All (ROWA)
    - Fast read
    - Slow write (low probability of succeeding)

- $\Rightarrow$  W<N
- $\Rightarrow$  R+W>N
- $\Rightarrow$  R+W<=N
- $\Rightarrow$  W<(N+1)/2
- $\Rightarrow$  N=3; W=2; R=2
- $\Rightarrow$  R=1
- $\Rightarrow$  R=1; W=N (1+N>N  $\Rightarrow$  Strong consistency)





# (Distributed) Query Processing

Challenge IV





#### Challenges in distributed query processing

- Communication cost (data shipping)
  - Not that critical for LAN networks
    - Assuming high enough I/O cost
- Fragmentation / Replication
  - Metadata and statistics about fragments (and replicas) in the global catalog
- Join Optimization
  - Joins order
  - Semi-join strategy
- How to decide the execution plan
  - Exploit parallelism (!)
    - Who executes what

A centralized optimizer minimizes the number of accesses to disk

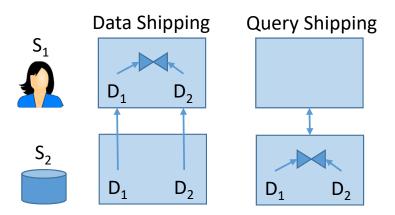
A distributed optimizer minimizes the use of network bandwidth





#### Allocation selection

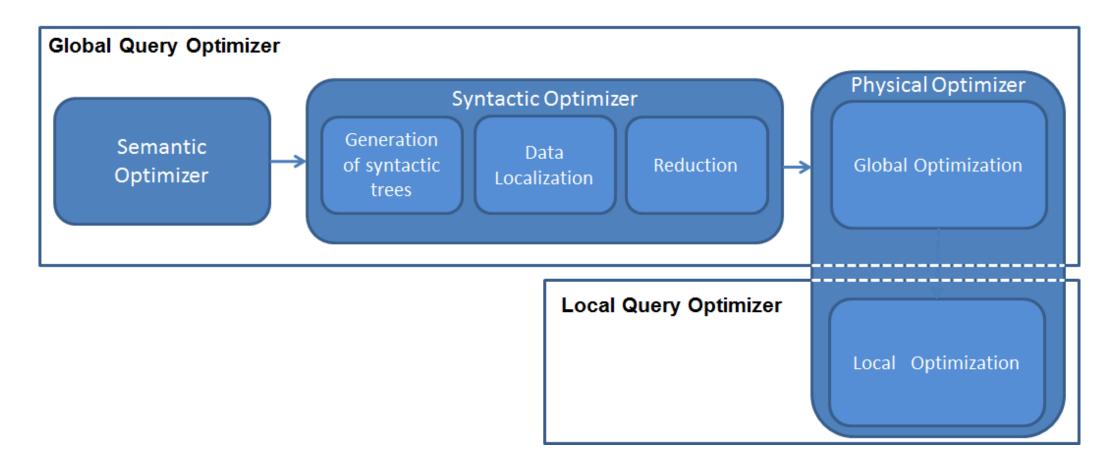
- Data shipping
  - The data is retrieved from the stored site to the site executing the query
    - Avoid bottlenecks on frequently used data
- Query shipping
  - The evaluation of the query is delegated to the site where it is stored
    - Avoid transferring large amounts of data
- Hybrid strategy
  - Dynamically decide data or query shipping







#### Phases of distributed query processing

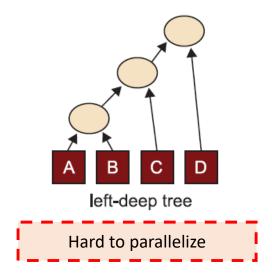


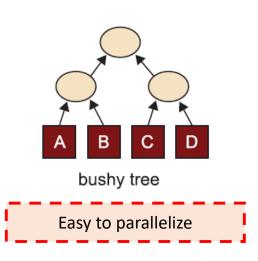




#### Syntactic optimizer

- Ordering operators
  - Left or right deep trees
  - Bushy trees





- Added difficulties
  - Consider multi-way joins
  - Consider the size of the datasets
    - Specially the size of the intermediate joins





#### Physical optimizer

- Transforms an internal query representation into an <u>efficient plan</u>
  - Replaces the logical query operators by
    - 1) Specific algorithms (plan operators)
    - 2) Access methods
  - Decides in which order to execute them
    - Parallelism (!)
  - Selects where to execute them (exploit <u>Data Location</u>)
    - More difficult for joins (multi-way joins)
- This is done by...
  - Enumerating alternative but equivalent *plans*
  - Estimating their costs
  - Searching for the best solution
    - Using available statistics regarding the physical state of the system





#### Criteria to choose the access plan

- Usually with the goal to optimize response time
  - Time needed to execute a query (i.e., latency or response time)
  - Benefits from parallelism
- Cost Model
  - Sum of local cost and communication cost
    - Local cost
      - Cost of central unit processing (#cycles),
      - Unit cost of I/O operation (#I/O ops)
    - Communication cost (commonly assumed it is linear in the number of bytes transmitted)
      - Cost of initiating a message and sending a message (#messages)
      - Cost of transmitting one byte (#bytes)
  - Knowledge required
    - Size of elementary data units processed
    - Selectivity of operations to estimate intermediate results





#### Cost model example

- Parameters:
  - Local processing:
    - Average CPU time to process an instance (T<sub>cpu</sub>)
    - Number of instances processed (#inst)
    - I/O time per operation (T<sub>I/O</sub>)
    - Number of I/O operations (#I/Os)
  - Global processing:
    - Message time (T<sub>Msq</sub>)
    - Number of messages issued (#msgs)
    - Transfer time (send a byte from one site to another)  $(T_{TR})$
    - Number of bytes transferred (#bytes)
- Calculations:

Resources Used = 
$$W_{cpu} * T_{cpu} * \# inst + W_{I/O} * T_{I/O} * \# I/Os + W_{Msg} * T_{Msg} * \# msgs + W_{TR} * T_{TR} * \# bytes$$
  
Response Time =  $T_{cpu} * seq_{\# inst} + T_{I/O} * seq_{\# I/Os} + T_{Msg} * seq_{\# msgs} + T_{TR} * seq_{\# bytes}$ 





#### The problem of parallelism

### Theory

#### Practice



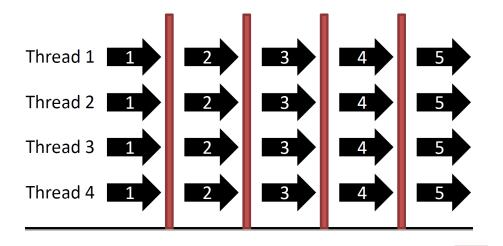


Samuel Yee



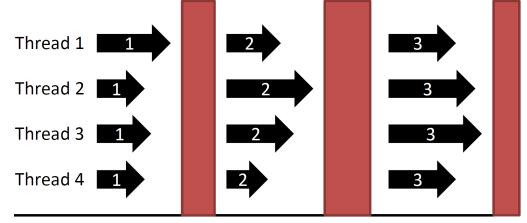


#### **Bulk Synchronous Parallel Model**



Ideal

Real



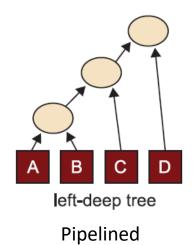
SAILING lab slides

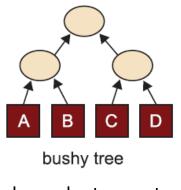




#### Kinds of parallelism

- Inter-query
- Intra-query
  - Intra-operator
    - Unary
      - Static partitioning
    - Binary
      - Static or dynamic partitioning
  - Inter-operator
    - Independent
    - Pipelined





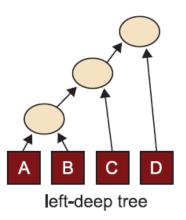






#### **Demand-Driven Pipelining**

- Each operator supports:
  - Open
  - Next
  - Close
- In principle, not parallel
  - Parent requests activate the execution
  - Nevertheless, a buffer can be used
    - This is similar to producer-driven







#### **Producer-Driven Pipelining**

- Generate output tuples eagerly
  - Until the buffers become full
- Pipeline stalls when
  - a) An operator becomes ready and no new inputs are available
    - It is propagated downstream through the pipeline like a bubble
  - b) An operator has input data available, but its output buffer is full
    - It is propagated upstream through the pipeline like a bubble

			Occupancy	Execution time
Serial			Т	Т
Inter-operator Parallelism	Independent	No stalls	T/N	h∙T/N
	Pipelining	Stalls	T/N+k	T/N+k+(h-1)(T/N)/ R

T = time units required for the whole query
N = operators in the process tree
|R| = tuples to be processed
Execution time = time to process the query
Occupancy = time until it can accept more work
h = height of the process tree
k = delay imposed by imbalance and communication overhead





### Measures of parallelism

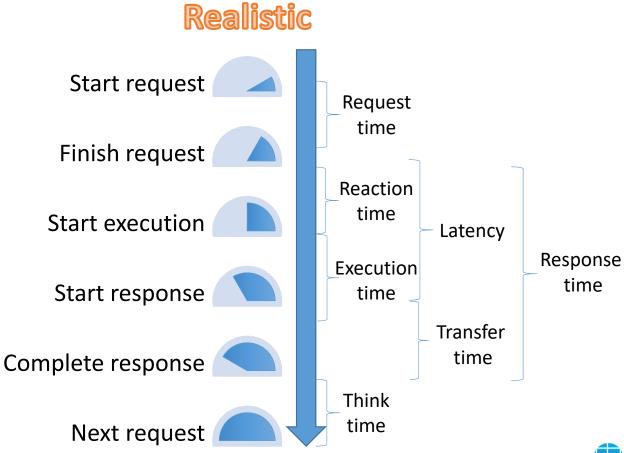
Ahmdal's law and the Universal Scalability Law





#### Response time

# User request System response time







#### Parallel processing

- Goal
  - Reduce response time
  - Increase throughput (adding resources)
    - Employ parallel hardware effectively
- Means
  - Process pieces of input in different processors
    - a) Divide the dataset into (disjoint) subsets
    - b) Adapt serial algorithms to multi-processor environments
- Consequences
  - Use more resources







#### Measuring scalability

- Scalability is normally measured in terms of
  - •Speed-up: measuring performance on adding hardware for a constant problem size
    - Linear speed-up means that N sites solve in T/N time, a problem solved in T time by a sequential version of the code
  - •Scale-up: measuring performance when the problem size is altered with resources
    - Linear scale-up means that N sites solve a problem N times bigger in T time, the same code run in 1 site solves the same problem also in T time





#### Amdahl's law

- Principle: parallel computing with many processors is useful only for highly parallelizable programs
- Amdahl's law measures the maximum improvement possible by improving a particular part of a system
  - Sequential/serial processing vs.
  - Parallel processing
- S(p,N) theoretical speed-up, where p is the fraction of parallelizable code using N processors (hardware)





#### Amdahl's law

$$S(p,N) = \frac{N}{N - p(N-1)}$$

$$N$$

$$S(p,N) = \frac{N}{N - pN + p}$$



$$S(p,N) = \frac{1}{\frac{N-pN+p}{N}}$$



$$S(p,N) = \frac{1}{1 - p + \frac{p}{N}}$$

	N/p	100%	<b>75</b> %	50%	25%
	1	1.00	1.00	1.00	1.00
	2	2.00	1.60	1.33	1.14
	3	3.00	2.00	1.50	1.20
	4	4.00	2.29	1.60	1.23
			Speed-up		
			эрсси ир		
50					
				_	
1.50					
) ——					•
)					
) ——					





#### Universal Scalability Law (I) – Generalization of Amdahl's law

- Mathematical definition of scale-up (both for SW or HW scalability)
  - Shows that linear scalability is hardly achievable
- USL is defined as follows

$$C(N) = \frac{N}{1 + \sigma(N-1) + \kappa N(N-1)}$$

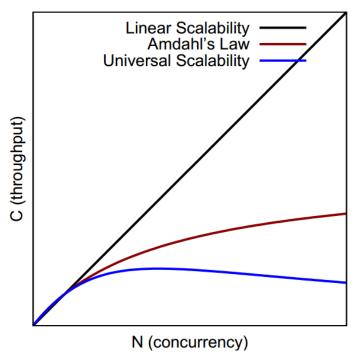
- C: System's capacity (i.e., throughput) improvement (e.g., increment of #queries per second)
- N: System's size (SW number of concurrent threads or HW number of CPUs)
- σ: System's contention (performance degradation due to serial instead of parallel processing)
  - Could be avoided (i.e.,  $\sigma = 0$ ) if our code has no serial chunks (everything parallelizable)
- κ: System's consistency delay (a.k.a. coherency delay), extra work needed to keep synchronized shared data (i.e., inter-process communication)
  - Could be avoided (i.e.,  $\kappa = 0$ ) if replicas can be synchronized without sending messages





#### **Universal Scalability Law (II)**

- If  $\kappa = 0$ , it simplifies to Amdahl's law
- If both  $\sigma = 0$  and  $\kappa = 0$ , we obtain linear scalability







#### **USL** application method

- 1. Empirical analysis: Measure  $C_i$  (throughput) for different values of N (concurrency)
- 2. Perform least-squares regression against gathered data
  - 1. x = N 1 (interpreted as concurrency)
  - 2.  $y = \frac{N}{C(N)} 1$  (interpreted as deviation from linearity), where  $C(N) = \frac{C_N}{C_1}$
  - 3. Fit a second-order polynomial
- 3. Reverse the transformation  $y = ax^2 + bx + 0$ 
  - 1.  $\sigma = b a$  (contention)
  - 2.  $\kappa = a$  (consistency delay)





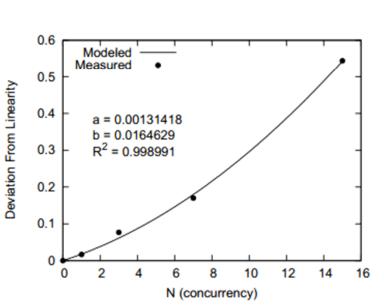
#### **USL** application method: Example

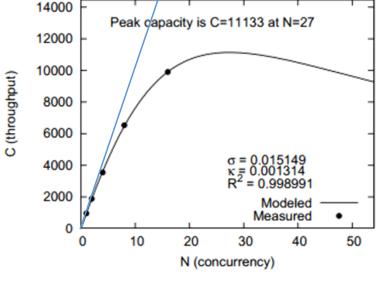
Concurrency $(N)$	Throughput $(C)$
1	955.16
2	1878.91
4	3548.68
8	6531.08
16	9897.24
10	7077.21

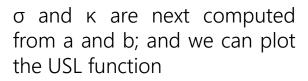
		4	
		X	У
N	C	N-1	$\frac{N}{C/C_1} - 1$
1	955.16	0	0.0000
2	1878.91	1	0.0167
4	3548.68	3	0.0766
8	6531.08	7	0.1699
16	9897.24	15	0.5441



Points are fit in a second-order polynomial: ax<sup>2</sup>+bx+0, and a and b are computed







https://www.percona.com/sites/default/files/white-paper-forecasting-mysql-scalability.pdf



### Closing





#### Summary

- Distributed Transaction Management
  - CAP theorem
  - Eventual consistency
- Distributed Query Processing
  - Kinds of Parallelism
  - Cost estimation
- Scalability measures
  - Amdahl's law
  - Universal scalability law





#### References

- G. Graefe. *Query Evaluation Techniques*. In ACM Computing Surveys, 25(2), 1993
- L. Liu, M.T. Özsu (Eds.). Encyclopedia of Database Systems. Springer, 2009
- M. T. Özsu and P. Valduriez. Principles of Distributed Database Systems, 3<sup>rd</sup> Ed. Springer, 2011
- L. G. Valiant. A bridging model for parallel computation. Commun. ACM. August 1990



