

Input frames $\mathbf{I}_0^{1/4}, \mathbf{I}_2^{1/4}$



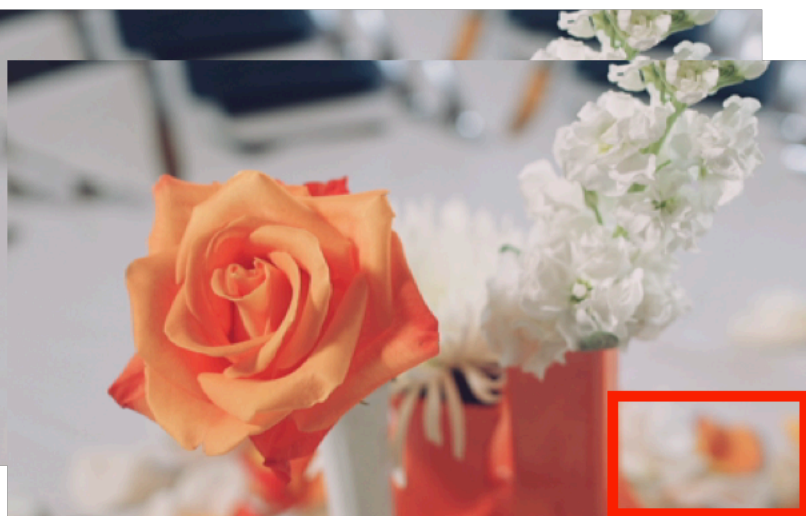
Denoised prediction $\hat{\mathbf{I}}_1^{1/4}$

Input frames $\mathbf{I}_0^{1/2}, \mathbf{I}_2^{1/2}$



Denoised prediction $\hat{\mathbf{I}}_1^{1/2}$

Input frames $\mathbf{I}_0, \mathbf{I}_2$



Denoised prediction $\hat{\mathbf{I}}_1$

Upsample

Upsample

 indicates the region seen by the model in one diffusion process