



MAX PLANCK INSTITUTE
FOR DYNAMICS OF COMPLEX
TECHNICAL SYSTEMS
MAGDEBURG

Mathematical Modeling of Infectious Disease

Compartment and Graph-based Models

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MathCoRe Seminar

Partners:





Motivation

- Goal: Avoid outbreaks in nursery homes or hospitals.
- Constraint: Tests are expensive and unpleasant.
- Research question: What is a good testing strategie?
 - What is a good model?
 - How to quantify the costs of testing or not testing?

Joint project with Prof. Achim Kaasch¹ from the OVGU Medical Faculty.

¹<http://www.immb.ovgu.de/>



1. Compartment Models and Stability Analysis
2. The SEIQR Model and MPC
3. Graph-based Modelling and Simulation



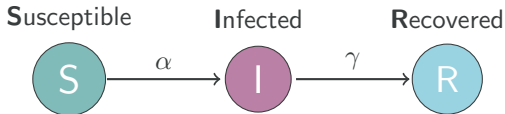
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Compartment model SIR



$$N = S + I + R$$

$$S' = -\frac{\alpha}{N}IS$$

$$I' = \frac{\alpha}{N}IS - \gamma I$$

$$R' = \gamma I$$

α : infection rate

γ : recovery rate

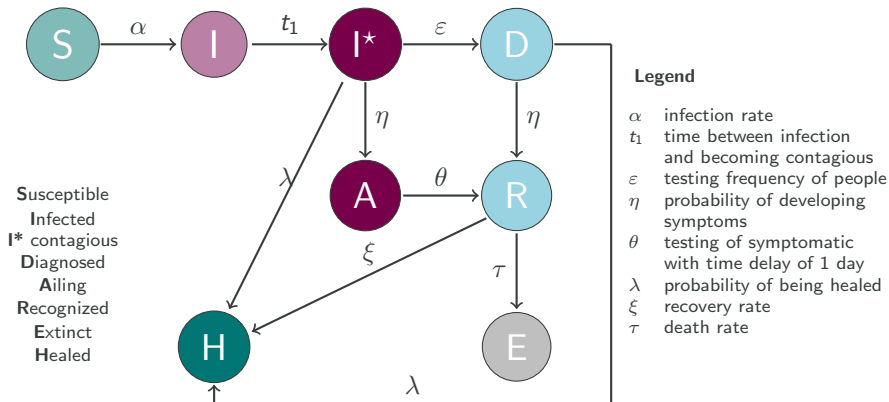
Some basic analysis:

- Conservation of mass: $S' + I' + R' = 0$.
- Positivity: $S(0), I(0), R(0) \geq 0$, then $S(t), I(t), R(t) \geq 0$.
- Set $S(0) + I(0) + R(0) = 1$, then S, I, R represent fractions of the population.



Compartment model

In the spirit of the **Susceptible-Infected-Recovered** approach^[1] and the **SIDARTHE** model^[2]



[1] W. O. Kermack, A. G. McKendrick. A contribution to the mathematical theory of epidemics. Proceedings of the royal society of london. Series A, Containing papers of a mathematical and physical character, 115(772):700-721, 1927

[2] G. Giordano, F. Blanchini, R. Bruno, P. Colaneri, A. D. Filippo, A. D. Matteo, M. Colaneri. Modelling the COVID-19 epidemic and implementation of population-wide interventions in Italy. Nature Medicine, 2020



SIDHARTE model as ODE

$$\begin{aligned}\dot{S}(t) &= -S(t)(\alpha I(t) + \beta D(t) + \gamma A(t) + \delta R(t)) \\ \dot{I}(t) &= S(t)(\alpha I(t) + \beta D(t) + \gamma A(t) + \delta R(t)) - (\varepsilon + \zeta + \lambda)I(t) \\ \dot{D}(t) &= \varepsilon I(t) - (\eta + \rho)D(t) \\ \dot{A}(t) &= \zeta I(t) - (\theta + \mu + \kappa)A(t) \\ \dot{R}(t) &= \eta D(t) + \theta A(t) - (\nu + \xi)R(t) \\ \dot{T}(t) &= \mu A(t) + \nu R(t) - (\sigma + \tau)T(t) \\ \dot{H}(t) &= \lambda I(t) + \rho D(t) + \kappa A(t) + \xi R(t) + \sigma T(t) \\ \dot{E}(t) &= \tau T(t)\end{aligned}$$

Basic analysis:

- $S' + I' + D' + A' + R' + T' + H' + E' = 0$.
- Positivity, if starting value is positive.
- Consider the states (S, x, H, E) , with x collecting all infected.
 - Can show: System has equilibria $(\bar{S}, 0, \bar{H}, \bar{E})$.
 - Can ask: Is some $(\bar{S}, 0, \bar{H}, \bar{E})$ a stable equilibrium.



$$\begin{aligned}\dot{S}(t) &= -S(t)(\alpha I(t) + \beta D(t) + \gamma A(t) + \delta R(t)) \\ \dot{I}(t) &= S(t)(\alpha I(t) + \beta D(t) + \gamma A(t) + \delta R(t)) - (\varepsilon + \zeta + \lambda)I(t) \\ \dot{D}(t) &= \varepsilon I(t) - (\eta + \rho)D(t) \\ \dot{A}(t) &= \zeta I(t) - (\theta + \mu + \kappa)A(t) \\ \dot{R}(t) &= \eta D(t) + \theta A(t) - (\nu + \xi)R(t) \\ \dot{T}(t) &= \mu A(t) + \nu R(t) - (\sigma + \tau)T(t) \\ \dot{H}(t) &= \lambda I(t) + \rho D(t) + \kappa A(t) + \xi R(t) + \sigma T(t) \\ \dot{E}(t) &= \tau T(t)\end{aligned}$$

Consider the states (S, x, H, E) , with x collecting all infected.

- **Nonlinear** only in $S(t)Cx(t)$, with $C = \begin{bmatrix} \alpha & \beta & \gamma & \delta & 0 \end{bmatrix}$.
- (H, E) do not contribute to the dynamics.



Rewrite as Feedback Loop

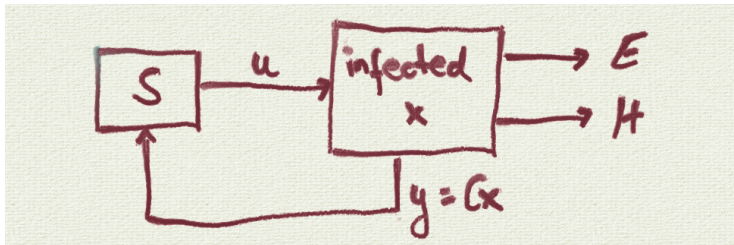
With a matrix $F \in \mathbb{R}^{5,5}$ and $B \in \mathbb{R}^{5,1}$, we rewrite the system as

$$\dot{x}(t) = Fx(t) + Bu(t)$$

$$\dot{S}(t) = -S(t)Cx(t)$$

$$0 = u(t) - S(t)Cx(t).$$

which is a linear system with a **nonlinear** feedback loop.





Linear Stability Analysis

Linearize about the steady state \bar{S} and substitute $u(t) = \bar{S}Cx(t)$:

$$\begin{bmatrix} \dot{S}(t) \\ \dot{x}(t) \end{bmatrix} = \begin{bmatrix} 0 & -\bar{S}C \\ 0 & F + B\bar{S}C \end{bmatrix} \begin{bmatrix} S(t) \\ x(t) \end{bmatrix}$$

This system is stable in S and asymptotically stable in x

- if, and only if

$$F + B\bar{S}C \text{ is Hurwitz,}$$

i.e. all eigenvalues of $F + B\bar{S}C$ have a negative real part,
which, for the SIDHARTE model is the case²

- if, and only if,

$$\bar{S} < S^*,$$

with $S^* =: \frac{1}{R_0}$ being the reciprocal of the *basic reproduction factor*.

²Giordano et al. (2020)



Interpretation of the Stability

$$\text{Stability} \quad \leftrightarrow \quad \bar{S} < \frac{1}{R_0} \quad \leftrightarrow \quad R_0 \bar{S} < 1$$

- Given a current **stable** steady state \bar{S} , a (small) number of infections $x(t)$ will simply fade out exponentially.
 - The fraction \bar{S} of unaffected people does not change significantly.
- The reproduction factor R_0 is a function of the model, not of the states.
 - If $\bar{S} = 1$, then $R_0 < 1$ is needed.
 - If $\bar{S} < 1$, then $R_0 > 1$ can be OK.
- Starting in an **unstable** state \bar{S} , a pandemics will last at least until $S(t) < \frac{1}{R_0}$.
 - With $R_0 = 3$, this means at least until $S(t) = \frac{1}{3}$ or until 67% of the population has been affected.

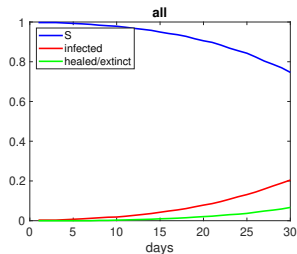
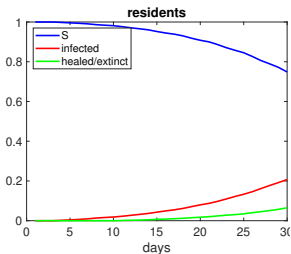
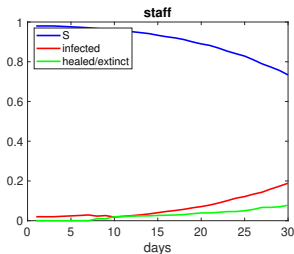


Example Computations

Also check of sensitivity

350 people = 300 residents + 50 staff, 1 staff is infected
5 contacts, $\alpha = 0.15$

Test every 7th day



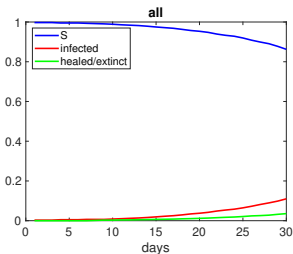
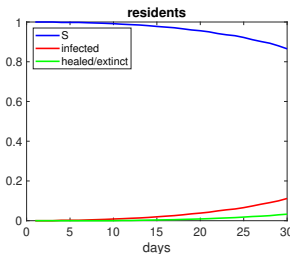
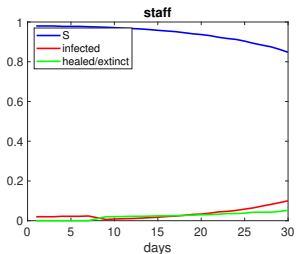


Example Computations

Also check of sensitivity

350 people = 300 residents + 50 staff, 1 staff is infected
5 contacts, $\alpha = 0.15$

Test every 3rd day



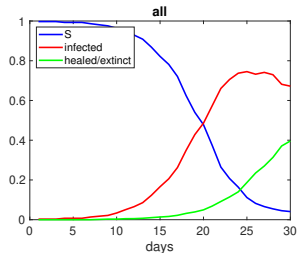
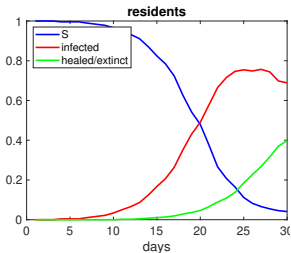
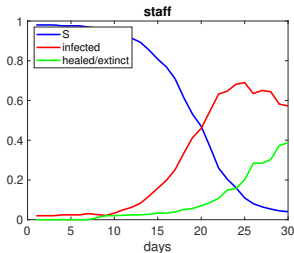


Example Computations

Also check of sensitivity

350 people = 300 residents + 50 staff, 1 staff is infected
5 contacts, $\alpha = 0.3$

Test every 3rd day





Our Current Research Direction

- Applicability to small populations like a nursery home.
 - Consider models with time-delays to account for latencies directly.
- Sensitivity analysis of fitted models
 - Improve the confidence.
 - Find parameters for optimization.



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The SEIQR_T Model

Another extension to the classic SIR model³

$$\frac{d}{dt} S(t) = -\beta(t)S(t)I(t) + \mu N - \mu S(t)$$

$$\frac{d}{dt} E(t) = \beta(t)S(t)I(t) - (\gamma + \mu)E(t)$$

$$\frac{d}{dt} I(t) = \gamma E(t) - (\eta + \mu + u(t) + \tau)I(t)$$

$$\frac{d}{dt} Q(t) = u(t)I(t) - (\tilde{\eta} + \mu + \tau)Q(t)$$

$$\frac{d}{dt} R(t) = \eta I(t) - \mu R(t)$$

$$\frac{d}{dt} R_Q(t) = \tilde{\eta} Q(t) - \mu R_Q(t)$$

$$\frac{d}{dt} T(t) = \tau I(t) + \tau Q(t) - \mu T(t)$$

³Kurt Chudej



The SEIQR Model

Another extension to the classic SIR model³

$$\frac{d}{dt} S(t) = -\beta(t)S(t)I(t) + \mu N - \mu S(t)$$

$$\frac{d}{dt} E(t) = \beta(t)S(t)I(t) - (\gamma + \mu)E(t)$$

$$\frac{d}{dt} I(t) = \gamma E(t) - (\eta + \mu + u(t) + \tau)I(t)$$

$$\frac{d}{dt} Q(t) = u(t)I(t) - (\tilde{\eta} + \mu + \tau)Q(t)$$

$$\frac{d}{dt} R(t) = \eta I(t) - \mu R(t)$$

$$\frac{d}{dt} R_Q(t) = \tilde{\eta} Q(t) - \mu R_Q(t)$$

$$\frac{d}{dt} T(t) = \tau I(t) + \tau Q(t) - \mu T(t)$$

The **research question** is how to use the controls we have to achieve what we want!

- quarantine u
- social distancing β
- division of the society by age

³Kurt Chudej



SEIQR model as a flow chart

Blue lines represent linear dynamics, and red lines represent quadratic dynamics.

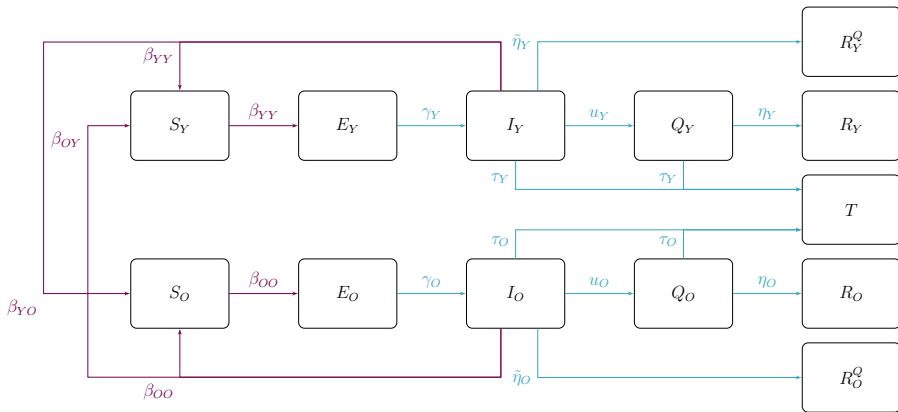


Figure: Schematic representation of the SEIQR model.



SEIQR model age compartments I

More Compartments

$$\frac{d}{dt} S_Y(t) = -\beta_{YY}(t)S_Y(t)I_Y(t) - \beta_{YO}(t)S_Y(t)I_O(t) + \mu N - \mu S_Y(t)$$

$$\frac{d}{dt} S_O(t) = -\beta_{OY}(t)S_O(t)I_Y(t) - \beta_{OO}(t)S_O(t)I_O(t) - \mu S_O(t)$$

$$\frac{d}{dt} E_Y(t) = \beta_{YY}(t)S_Y(t)I_Y(t) + \beta_{YO}(t)S_Y(t)I_O(t) - (\gamma_Y + \mu)E_Y(t)$$

$$\frac{d}{dt} E_O(t) = \beta_{OY}(t)S_O(t)I_Y(t) + \beta_{OO}(t)S_O(t)I_O(t) - (\gamma_O + \mu)E_O(t)$$

$$\frac{d}{dt} I_Y(t) = \gamma_Y E_Y(t) - (\eta_Y + \mu + u_Y(t) + \tau_Y)I_Y(t)$$

$$\frac{d}{dt} I_O(t) = \gamma_O E_O(t) - (\eta_O + \mu + u_O(t) + \tau_O)I_O(t)$$



SEIQR model age compartments II

More Compartments

$$\frac{d}{dt} Q_Y(t) = u_Y(t)I_Y(t) - (\tilde{\eta}_Y + \mu + \tau_Y)Q_Y(t)$$

$$\frac{d}{dt} Q_O(t) = u_O(t)I_O(t) - (\tilde{\eta}_O + \mu + \tau_O)Q_O(t)$$

$$\frac{d}{dt} R_Y(t) = \eta_Y I_Y(t) - \mu R_Y(t)$$

$$\frac{d}{dt} R_O(t) = \eta_O I_O(t) - \mu R_O(t)$$

$$\frac{d}{dt} R_Y^Q(t) = \tilde{\eta}_Y Q_Y(t) - \mu R_Y^Q(t)$$

$$\frac{d}{dt} R_O^Q(t) = \tilde{\eta}_O Q_O(t) - \mu R_O^Q(t)$$

$$\frac{d}{dt} T(t) = \tau_Y I_Y(t) + \tau_O I_O(t) + \tau_Y Q_Y(t) + \tau_O Q_O(t) - \mu T(t)$$



Objective Functions

Priorities: 1) minimize people in quarantine, 2) do not exceed ICU capacity for old people (\bar{I}_O), and 3) minimize social distancing ($\beta^0 \sim$ no social distancing).

We assume that $\beta_{OY} = \beta_{YO}$, i.e., old people infect young people as much as young people infect old people.

$$J_1(u, \beta) = \int_{t_k}^{t_k^f} Q_Y(t) + Q_O(t) dt$$

$$J_2(u, \beta) = \int_{t_k}^{t_k^f} \max\{0, I_O(t) - 0.9\bar{I}_O\}^2 dt$$

$$J_3(\beta) = \int_{t_k}^{t_k^f} \max\{0, \beta_{YY}(t) - \beta^0\}^2 dt$$

$$J_4(\beta) = \int_{t_k}^{t_k^f} \max\{0, \beta_{YO}(t) - \beta^0\}^2 dt$$

$$J_5(\beta) = \int_{t_k}^{t_k^f} \max\{0, \beta_{OO}(t) - \beta^0\}^2 dt$$



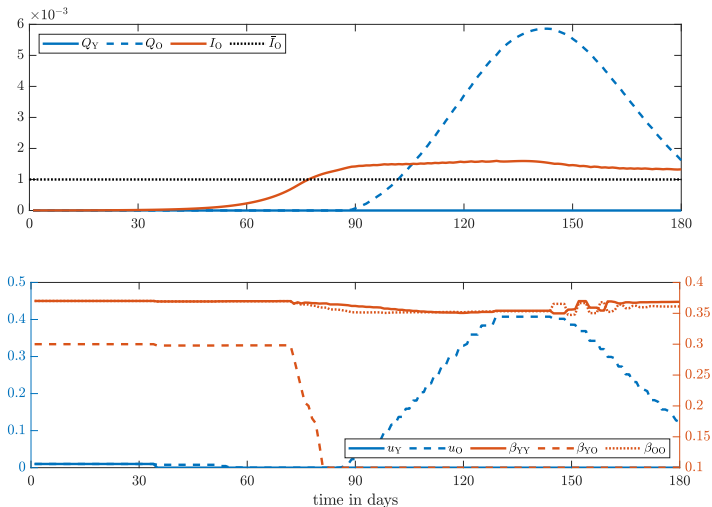
We compute the model predictive control strategy by repeatedly solving the optimal control problem

$$\begin{aligned} \min_{u, \beta} \quad & \mathcal{J}(u, \beta) = \nu_1 J_1(u, \beta) + \nu_2 J_2(u, \beta) \\ & + \nu_3 J_3(\beta) + \nu_4 J_4(\beta) + \nu_5 J_5(\beta) \\ \text{s.t.} \quad & \dot{x}(t) = f(x(t), u(t), \beta(t)), \quad x(t_k) = x_k^0, \\ & (u(t), \beta(t)) \in [0, 1] \times [\underline{\beta}, \overline{\beta}]^3 \quad \forall t \in [t_k, t_k^f], \end{aligned}$$



Model predictive control – example

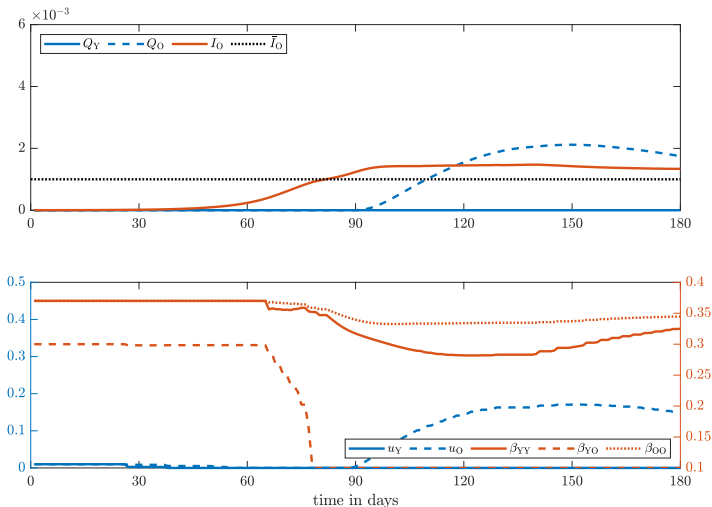
Short horizon – predict 7 days into the future.





Model predictive control – example

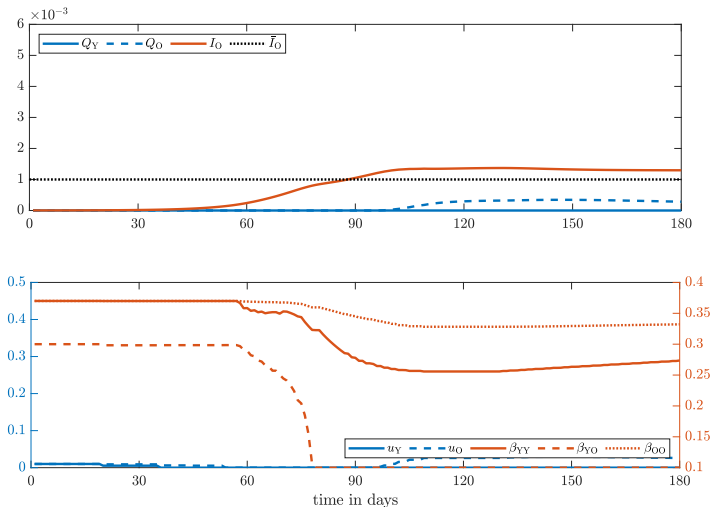
Short horizon – predict 14 days into the future.





Model predictive control – example

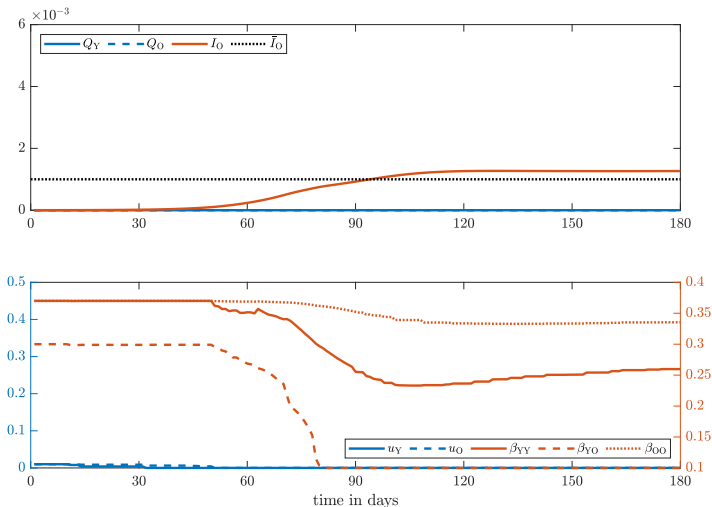
Short horizon – predict 21 days into the future.





Model predictive control – example

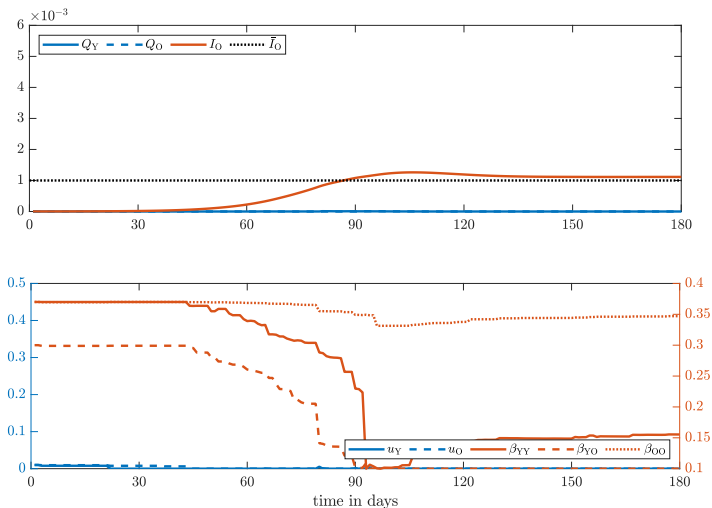
Longer horizon – predict 28 days into the future.





Model predictive control – example

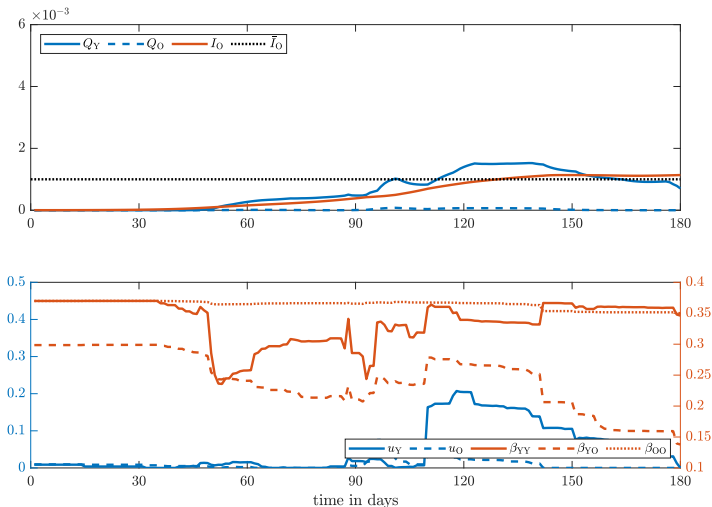
Longer horizon – predict 35 days into the future.





Model predictive control – example

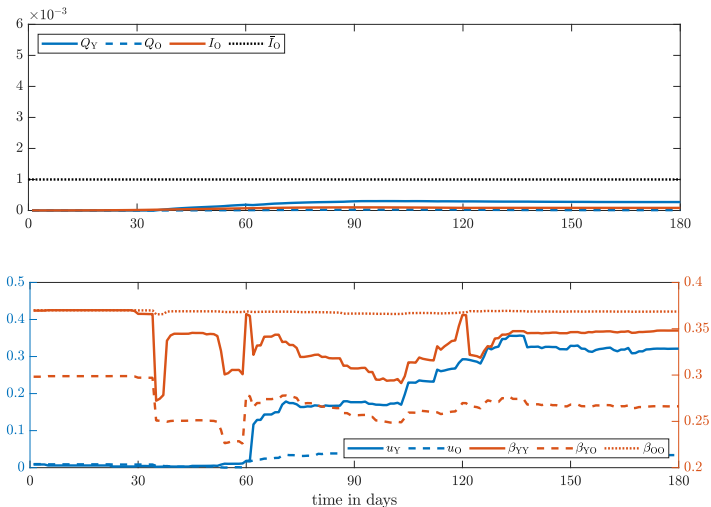
Longer horizon – predict 42 days into the future.





Model predictive control – example

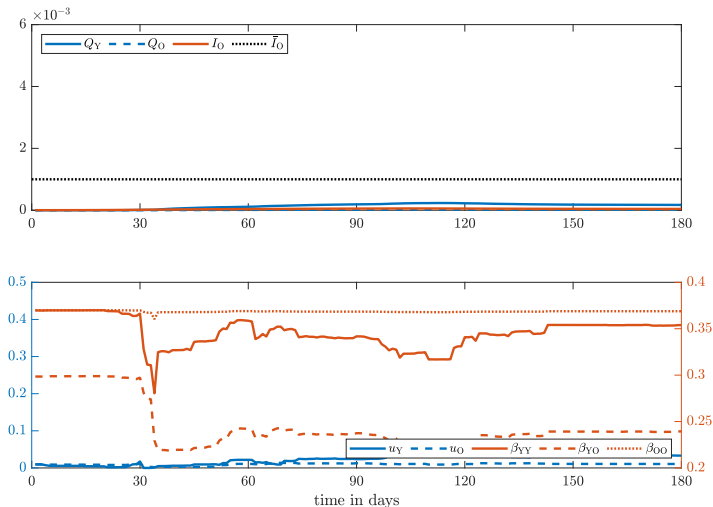
Longer horizon – predict 49 days into the future.





Model predictive control – example

Longer horizon – predict 56 days into the future.





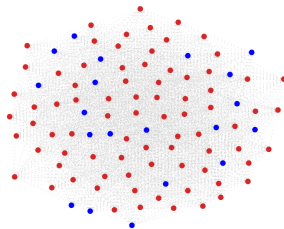
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The Graph Modell

The basis is a **weighted graph**, where each node represents a person and an edge a **probability of meeting each other**

- Forward in time simulation by spreading through the graph
- As in the model above we distinguish nodes that represent old and young people
- from E to I is a matter of time in this model
- quarantine measures can be implemented here as well easily by marking the node quarantine and removing the edges or changing the edge weights
- same is true for recovery and death rates



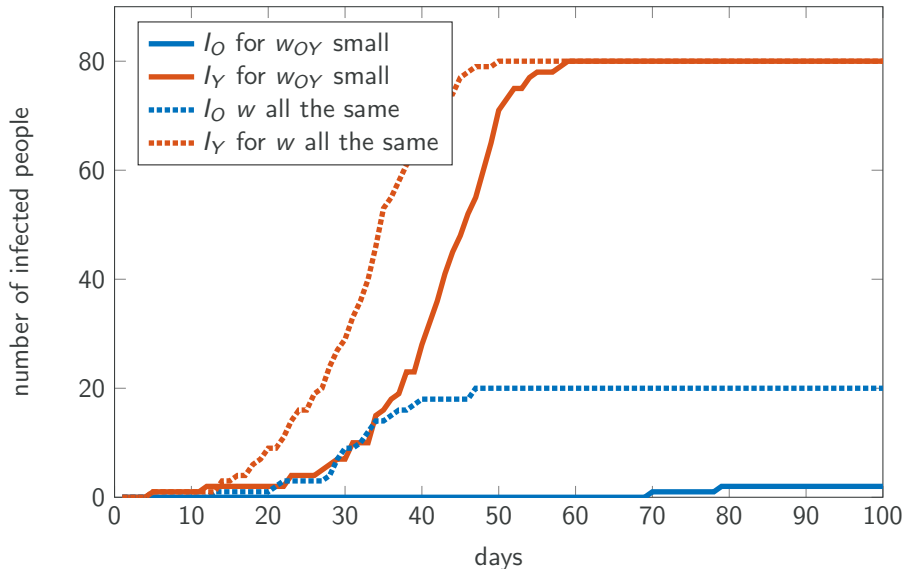


A toy example

- 100 Nodes: 20 Old and 80 Young
- Edges on the graph are random in this example
- 3 different transfer probabilities w_{OO} , w_{YY} , w_{YO}
- an infected person becomes infectious after 6 days and no longer infectious after 20
- two simulations
 - all w the same
 - w_{OY} much smaller



Toy Example Simulation Results

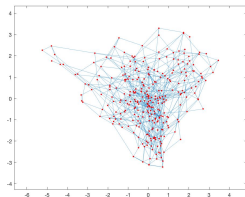




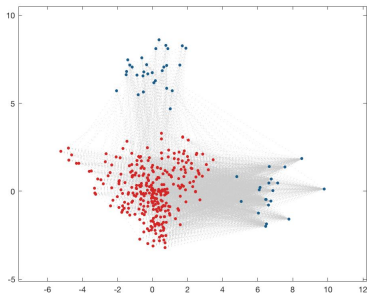
A specific Problem and a more specific graph

An elderly care facility

- 300 residents
- random edges between residents
- with random transfer probabilities between 0 and 0.25.



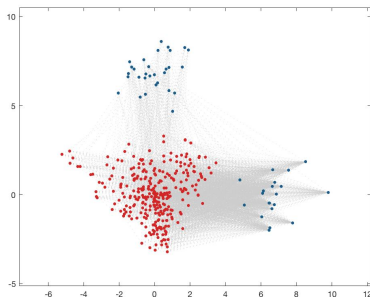
- 30 care taker and 20 other employees
- one care taker for 10 residents with a transfer probability of 0.15
- other caretaker have a transfer probability of 0.05





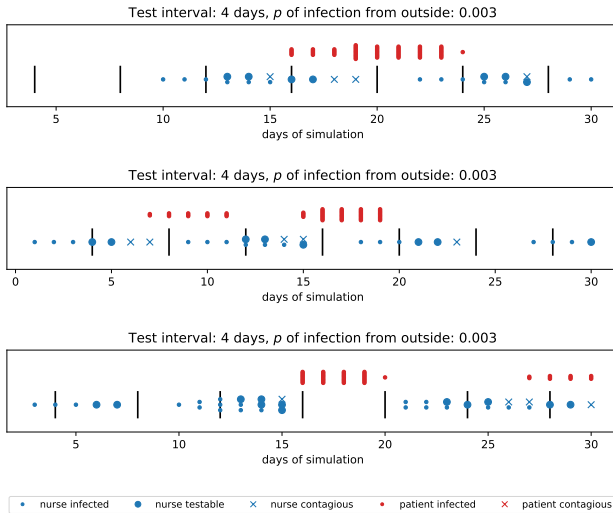
Parameters

- Infection probability per day from outside 0.003 (only from outside)
- test frequency: every 4,5,6 days
- test show positive result: after 4 days
- infectious after 6 days



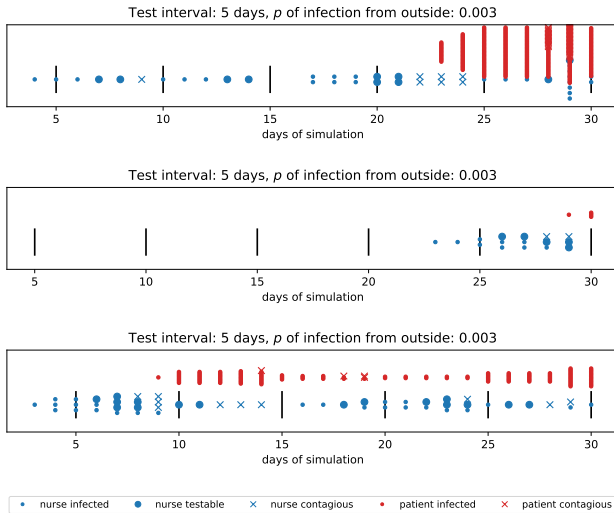


3 realizations for testing every 4 days



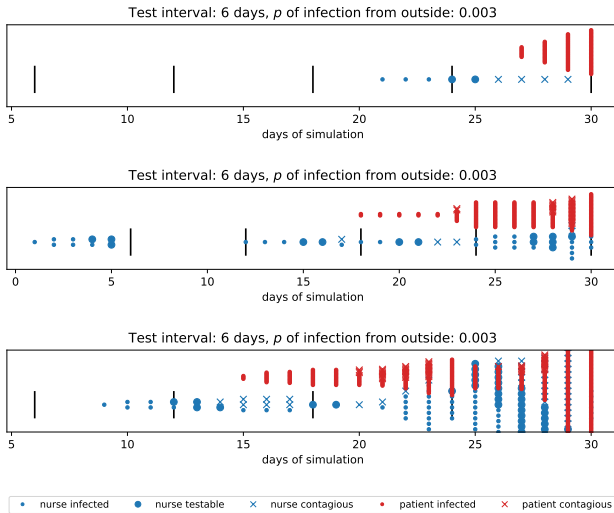


3 realizations for testing every 5 days



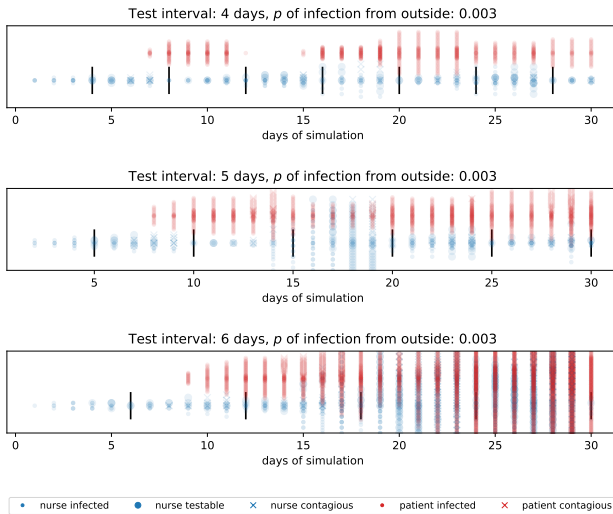


3 realizations for testing every 6 days



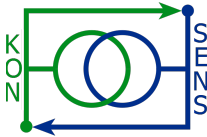


Overlay of 10 realizations





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TECHNISCHE UNIVERSITÄT
CHEMNITZ

Prof. Helmberg, Prof. Streif, Willam Esterhuizen, Bartoz Filipecki



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