

Optimization models for day-ahead scheduling

1. Introduction

This draft contains an optimization problem for day-ahead scheduling. This first problem is the optimal power flow (OPF), a common problem in power system planning and operation, which still a challenge to know the global solution for this problem, in large instances. The main characteristics for our toy problem is:

- 3 buses and 3 thermal generators; All generators are the same, with limits on active power = 400 MW and range for reactive power is $[-300, 300]$ MVar. Each bus have one generator.
- 1 load located at bus 3, with demand $P + jQ = 180 + j30$ MVA.
- All buses are connected by a single line, with $r + jx = 0,025 + j0,1$ pu of impedance.
- The unitary cost (CVU) from thermal generators are: $[10, 12, 20]$, respectively.

Considering these characteristics, we present in the rest of this draft some formulations of the OPF problem.

2. Problem Formulation – DC OPF

The DC OPF formulation to this problem is (assuming power in pu) :

$$\min 1000Pg_1 + 1200Pg_2 + 2000Pg_3$$

s.t.:

$$Pg_1 = \frac{\theta_1 - \theta_2}{0,1} + \frac{\theta_1 - \theta_3}{0,1} \quad -1 \leq \frac{\theta_1 - \theta_2}{0,1} \leq 1$$

$$Pg_2 = \frac{\theta_2 - \theta_3}{0,1} + \frac{\theta_2 - \theta_1}{0,1} \quad -1 \leq \frac{\theta_1 - \theta_3}{0,1} \leq 1$$

$$Pg_3 - 1.8 = \frac{\theta_3 - \theta_1}{0,1} + \frac{\theta_3 - \theta_2}{0,1} \quad -1 \leq \frac{\theta_2 - \theta_3}{0,1} \leq 1$$

$$0 \leq Pg_1 \leq 4; 0 \leq Pg_2 \leq 4; 0 \leq Pg_3 \leq 4$$

$$-\pi \leq \theta_1 \leq \pi; -\pi \leq \theta_2 \leq \pi; -\pi \leq \theta_3 \leq \pi$$

$$\theta_0 = 0$$

The following results are obtained by solving this problem with gurobi:

$Pg = [1.2; 0.6; 0.0]$; $\Theta = [0.0; -0.02; -0.1]$; objective cost = 1920 \$/hour.

Solved in 2 iterations (linear programming) and 0.08 seconds.

3. Problem Formulation – AC OPF with no approximations

The standart AC OPF formulation to this problem is (in polar coordinates, assuming power in pu):

$$\min 1000Pg_1 + 1200Pg_2 + 2000Pg_3$$

s.t.:

$$\begin{aligned} Pg_1 &= V_1 \left[V_1 \cdot 4.70588235 + V_2 \cdot (-2.35294118 \cos(\theta_1 - \theta_2) + 9.41176471 \sin(\theta_1 - \theta_2)) + \right. \\ &\quad \left. V_3 \cdot (-2.35294118 \cos(\theta_1 - \theta_3) + 9.41176471 \sin(\theta_1 - \theta_3)) \right] \\ Pg_2 &= V_2 \left[V_2 \cdot 4.70588235 + V_1 \cdot (-2.35294118 \cos(\theta_2 - \theta_1) + 9.41176471 \sin(\theta_2 - \theta_1)) + \right. \\ &\quad \left. V_3 \cdot (-2.35294118 \cos(\theta_2 - \theta_3) + 9.41176471 \sin(\theta_2 - \theta_3)) \right] \\ Pg_3 - 1.8 &= V_3 \left[V_3 \cdot 4.70588235 + V_1 \cdot (-2.35294118 \cos(\theta_3 - \theta_1) + 9.41176471 \sin(\theta_3 - \theta_1)) + \right. \\ &\quad \left. V_2 \cdot (-2.35294118 \cos(\theta_3 - \theta_2) + 9.41176471 \sin(\theta_3 - \theta_2)) \right] \\ Qg_1 &= V_1 \left[V_1 \cdot 18.82352941 + V_2 (-2.35294118 \sin(\theta_1 - \theta_2) - 9.41176471 \cos(\theta_1 - \theta_2)) + \right. \\ &\quad \left. V_3 (-2.35294118 \sin(\theta_1 - \theta_3) - 9.41176471 \cos(\theta_1 - \theta_3)) \right] \\ Qg_2 &= V_2 \left[V_2 \cdot 18.82352941 + V_1 (-2.35294118 \sin(\theta_2 - \theta_1) - 9.41176471 \cos(\theta_2 - \theta_1)) + \right. \\ &\quad \left. V_3 (-2.35294118 \sin(\theta_2 - \theta_3) - 9.41176471 \cos(\theta_2 - \theta_3)) \right] \\ Qg_3 - 0.3 &= V_3 \left[V_3 \cdot 18.82352941 + V_1 (-2.35294118 \sin(\theta_3 - \theta_1) - 9.41176471 \cos(\theta_3 - \theta_1)) + \right. \\ &\quad \left. V_2 (-2.35294118 \sin(\theta_3 - \theta_2) - 9.41176471 \cos(\theta_3 - \theta_2)) \right] \\ &\quad \left(2.35294118V_1^2 - 2.35294118V_1V_2 \cos(\theta_1 - \theta_2) + 9.41176471V_1V_2 \sin(\theta_1 - \theta_2) \right)^2 + \\ &\quad \left(9.41176471V_1^2 - 9.41176471V_1V_2 \cos(\theta_1 - \theta_2) - 2.35294118V_1V_2 \sin(\theta_1 - \theta_2) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_1^2 - 2.35294118V_1V_3 \cos(\theta_1 - \theta_3) + 9.41176471V_1V_3 \sin(\theta_1 - \theta_3) \right)^2 + \\ &\quad \left(9.41176471V_1^2 - 9.41176471V_1V_3 \cos(\theta_1 - \theta_3) - 2.35294118V_1V_3 \sin(\theta_1 - \theta_3) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_2^2 - 2.35294118V_2V_3 \cos(\theta_2 - \theta_3) + 9.41176471V_2V_3 \sin(\theta_2 - \theta_3) \right)^2 + \\ &\quad \left(9.41176471V_2^2 - 9.41176471V_2V_3 \cos(\theta_2 - \theta_3) - 2.35294118V_2V_3 \sin(\theta_2 - \theta_3) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_2^2 - 2.35294118V_2V_1 \cos(\theta_2 - \theta_1) + 9.41176471V_2V_1 \sin(\theta_2 - \theta_1) \right)^2 + \\ &\quad \left(9.41176471V_2^2 - 9.41176471V_1V_2 \cos(\theta_2 - \theta_1) - 2.35294118V_2V_1 \sin(\theta_2 - \theta_1) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_3^2 - 2.35294118V_3V_1 \cos(\theta_3 - \theta_1) + 9.41176471V_3V_1 \sin(\theta_3 - \theta_1) \right)^2 + \\ &\quad \left(9.41176471V_3^2 - 9.41176471V_3V_1 \cos(\theta_3 - \theta_1) - 2.35294118V_3V_1 \sin(\theta_3 - \theta_1) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_3^2 - 2.35294118V_3V_2 \cos(\theta_3 - \theta_2) + 9.41176471V_3V_2 \sin(\theta_3 - \theta_2) \right)^2 + \\ &\quad \left(9.41176471V_3^2 - 9.41176471V_3V_2 \cos(\theta_3 - \theta_2) - 2.35294118V_3V_2 \sin(\theta_3 - \theta_2) \right)^2 \leq 1^2 \\ 0 &\leq Pg_1 \leq 4; 0 \leq Pg_2 \leq 4; 0 \leq Pg_3 \leq 4; -3 \leq Qg_1 \leq 3; -3 \leq Qg_2 \leq 3; -3 \leq Qg_3 \leq 3 \\ -2\pi &\leq \theta_1 \leq 2\pi; -2\pi \leq \theta_2 \leq 2\pi; -2\pi \leq \theta_3 \leq 2\pi \\ 0.9 &\leq V_1 \leq 1.1; 0.9 \leq V_2 \leq 1.1; 0.95 \leq V_3 \leq 1.05 \\ \theta_0 &= 0 \end{aligned}$$

The following results are obtained via matpower, using an Interior Point Method:

$P_g = [1.1775; 0.6616; 0.0]$; $Q_g = [-0.1959; 0.3908; 0.2614]$;

$\Theta = [0; -0.01958; -0.08913]$; $V = [1.069; 1.084; 1.050]$

Objective cost = 1971.39 \$/hour.

Converged in 3.31 seconds.

4. Problem Formulation – AC OPF in rectangular form

The OPF formulation in rectangular form is: (not finished yet)

$$\min 1000Pg_1 + 1200Pg_2 + 2000Pg_3$$

s.t.:

$$\begin{aligned} Pg_1 &= V_{r1} (4.70588235V_{r1} + 18.82352941V_{i1} - 2.35294118V_{r2} - 9.41176471V_{i2} - 2.35294118V_{r3} - 9.41176471V_{i3}) + \\ &\quad V_{i1} (-18.82352941V_{r1} + 4.70588235V_{i1} + 9.41176471V_{r2} - 2.35294118V_{i2} + 9.41176471V_{r3} - 2.35294118V_{i3}) \\ Pg_2 &= V_{r2} (4.70588235V_{r2} + 18.82352941V_{i2} - 2.35294118V_{r1} - 9.41176471V_{i1} - 2.35294118V_{r3} - 9.41176471V_{i3}) + \\ &\quad V_{i2} (-18.82352941V_{r2} + 4.70588235V_{i2} + 9.41176471V_{r1} - 2.35294118V_{i1} + 9.41176471V_{r3} - 2.35294118V_{i3}) \\ Pg_3 - 1.8 &= V_{r3} (4.70588235V_{r3} + 18.82352941V_{i3} - 2.35294118V_{r1} - 9.41176471V_{i1} - 2.35294118V_{r2} - 9.41176471V_{i2}) + \\ &\quad V_{i3} (-18.82352941V_{r3} + 4.70588235V_{i3} + 9.41176471V_{r1} - 2.35294118V_{i1} + 9.41176471V_{r2} - 2.35294118V_{i2}) \\ Qg_1 &= V_{r1} (18.82352941V_{r1} - 4.70588235V_{i1} - 9.41176471V_{r2} + 2.35294118V_{i2} - 9.41176471V_{r3} + 2.35294118V_{i3}) + \\ &\quad V_{i1} (4.70588235V_{r1} + 18.82352941V_{i1} - 2.35294118V_{r2} - 9.41176471V_{i2} - 2.35294118V_{r3} - 9.41176471V_{i3}) \\ Qg_2 &= V_{r2} (18.82352941V_{r2} - 4.70588235V_{i2} - 9.41176471V_{r1} + 2.35294118V_{i1} - 9.41176471V_{r3} + 2.35294118V_{i3}) + \\ &\quad V_{i2} (4.70588235V_{r2} + 18.82352941V_{i2} - 2.35294118V_{r1} - 9.41176471V_{i1} - 2.35294118V_{r3} - 9.41176471V_{i3}) \\ Qg_3 - 0.3 &= V_{r3} (18.82352941V_{r3} - 4.70588235V_{i3} - 9.41176471V_{r1} + 2.35294118V_{i1} - 9.41176471V_{r2} + 2.35294118V_{i2}) + \\ &\quad V_{i3} (4.70588235V_{r3} + 18.82352941V_{i3} - 2.35294118V_{r1} - 9.41176471V_{i1} - 2.35294118V_{r2} - 9.41176471V_{i2}) \\ &\quad \left(2.35294118V_1^2 - 2.35294118V_1V_2 \cos(\theta_1 - \theta_2) + 9.41176471V_1V_2 \sin(\theta_1 - \theta_2) \right)^2 + \\ &\quad \left(9.41176471V_1^2 - 9.41176471V_1V_2 \cos(\theta_1 - \theta_2) - 2.35294118V_1V_2 \sin(\theta_1 - \theta_2) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_1^2 - 2.35294118V_1V_3 \cos(\theta_1 - \theta_3) + 9.41176471V_1V_3 \sin(\theta_1 - \theta_3) \right)^2 + \\ &\quad \left(9.41176471V_1^2 - 9.41176471V_1V_3 \cos(\theta_1 - \theta_3) - 2.35294118V_1V_3 \sin(\theta_1 - \theta_3) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_2^2 - 2.35294118V_2V_3 \cos(\theta_2 - \theta_3) + 9.41176471V_2V_3 \sin(\theta_2 - \theta_3) \right)^2 + \\ &\quad \left(9.41176471V_2^2 - 9.41176471V_2V_3 \cos(\theta_2 - \theta_3) - 2.35294118V_2V_3 \sin(\theta_2 - \theta_3) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_2^2 - 2.35294118V_2V_1 \cos(\theta_2 - \theta_1) + 9.41176471V_2V_1 \sin(\theta_2 - \theta_1) \right)^2 + \\ &\quad \left(9.41176471V_2^2 - 9.41176471V_2V_1 \cos(\theta_2 - \theta_1) - 2.35294118V_2V_1 \sin(\theta_2 - \theta_1) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_3^2 - 2.35294118V_3V_1 \cos(\theta_3 - \theta_1) + 9.41176471V_3V_1 \sin(\theta_3 - \theta_1) \right)^2 + \\ &\quad \left(9.41176471V_3^2 - 9.41176471V_3V_1 \cos(\theta_3 - \theta_1) - 2.35294118V_3V_1 \sin(\theta_3 - \theta_1) \right)^2 \leq 1^2 \\ &\quad \left(2.35294118V_3^2 - 2.35294118V_3V_2 \cos(\theta_3 - \theta_2) + 9.41176471V_3V_2 \sin(\theta_3 - \theta_2) \right)^2 + \\ &\quad \left(9.41176471V_3^2 - 9.41176471V_3V_2 \cos(\theta_3 - \theta_2) - 2.35294118V_3V_2 \sin(\theta_3 - \theta_2) \right)^2 \leq 1^2 \\ 0 &\leq Pg_1 \leq 4; 0 \leq Pg_2 \leq 4; 0 \leq Pg_3 \leq 4; -3 \leq Qg_1 \leq 3; -3 \leq Qg_2 \leq 3; -3 \leq Qg_3 \leq 3 \\ -2\pi &\leq \theta_1 \leq 2\pi; -2\pi \leq \theta_2 \leq 2\pi; -2\pi \leq \theta_3 \leq 2\pi \\ 0.9^2 &\leq V_{r1}^2 + V_{i1}^2 \leq 1.1^2; 0.9^2 \leq V_{r1}^2 + V_{i1}^2 \leq 1.1^2; 0.95^2 \leq V_{r1}^2 + V_{i1}^2 \leq 1.05^2 \\ \theta_0 &= 0 \end{aligned}$$