AC6351D Datasheet

Zhuhai Jieli Technology Co.,LTD

Version: V1.3

Date: 2024.06.27

Copyright © Zhuhai Jieli Technology Co.,LTD. All rights reserved.

AC6351D Features

CPU

- 32-bit DSP supports hardware Float Point Unit(FPU)
- Up to 240MHz programmable processor
- 64Vectored interrupts
- 4 Levels interrupt priority

DSP Audio Processing

- SBC, AAC Audio decodes supported for BT audio
- mSBC voice codecs supported for BT phone
- Supports MP2, MP3, WMA, APE, FLAC, AAC, MP4, M4A, WAV, AIF, AIFC audio decoding
- Packet Loss Concealment (PLC) for voice processing
- Acoustic echo cancellation/suppression (AEC,AES)
- Single/Dual MIC Environmental Noise Cancellation (ENC)
- Multi-band DRC limiter
- 30-band EQ configuration for voice Effects

Audio Codec

- Two channels 16-bit DAC, SNR >= 92dB
- Three channels 16-bit ADC, SNR >= 90dB
- Sampling rates of 8KHz/11.025KHz/16KHz/22.05KHz/24KHz/32KHz/44.1KHz/48KHz are supported
- One analog MIC amplifier, build-in MIC bias generator
- Supports two PDM digital MIC inputs
- three channels Stereo analog MUX
- Supports cap-less, single-ended, and differential mode at the DAC path
- Supports 16ohm and 32ohm Speaker loading

Bluetooth

- Compliant with BluetoothV5.4+BR+EDR+BLE specification
- Meet class1 class2 and class3 transmitting

- power requirement
- Support GFSK and π/4 DQPSK all paket types
- Provides +6dbm transmitting power
- receiver with -90dBm sensitivity
- Fast AGC for enhanced dynamic range
- Supports a2dp\avctp\avdtp\avrcp\hfp\spp\smp\att\gap\g att\rfcomm\sdp\l2cap profile

Peripherals

- One full speed USB 2.0 OTG controller
- Two PCM/IIS for external digital Audio code, supports host and device mode
- Four multi-function 16-bit timers, support capture and PWM mode
- Three 16-bit PWM generator for motor driving
- Three full-duplex basic UART, UART0 and UART1 supports DMA mode
- Three SPI interface supports host and device mode
- Two SD Card Host controller
- One hardwareIIC interface supports host and device mode
- Four SPDIF receiving interface without analog amplify
- Supports HDMI ARC (Audio Return Channel) receiving
- Segment LCD panels
- Digital matrix LED panels
- Built-in Cap Sense Key controller
- 14 channels 10-bit ADC for analog sampling
- External wake up/interrupt on all GPIOs

PMU

- Low voltage LDO for internal digital and analog circuit supply
- 3uA current consumption in the soft-off mode
- Built-in LDO for the core, I/O, Bluetooth and flash

2

- Built-inLi-Ion battery charger with up to 200mA charger current capability
- VBAT is 2.2V to 5.5V
- VDDIO is 2.2V to 3.6V

Packages

LQFP48(7mm*7mm)

Temperature

- Operating temperature: -40°C to +85°C
- Storage temperature: -65°C to +150°C

Applications

Bluetooth Keyboard

1. Pin Definition

1.1 Pin Assignment

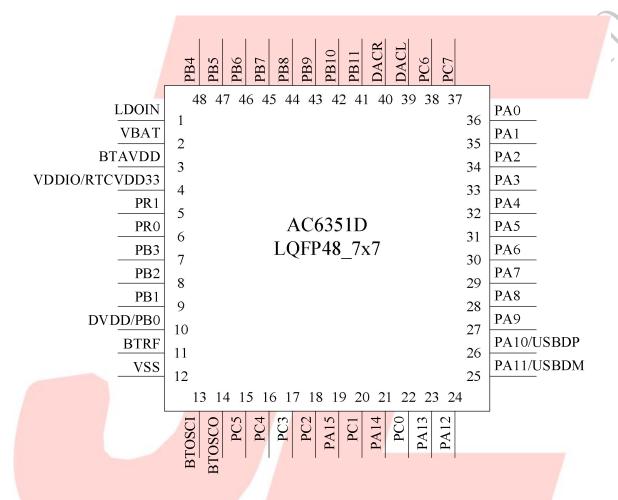


Figure 1-1 AC6351D_LQFP48 Package Diagram

1.2 Pin Description

Table 1-1 AC6351D_LQFP48 Pin Description

PIN NO.	Name	I/O Type	Drive (mA)	Function	Other Function
		Турс	(11111)		
1	LDOIN	P	/		Battery Charger Power In;
2	VBAT	P	/		Power Supply;
3	BTAVDD	P	/		BT Power;
4	VDDIO	P	/		IO Power 3.3V;
4	RTCVDD33	P	/		RTC Power;
5	PR1	I/O	8	GPIO	OSCO_32K: 32KHz OSC Out;
6	PR0	I/O	8	GPIO	OSCI_32K: 32KHz OSC In;
7	PB3	I/O	24/8	GPIO	PWM2: Timer2 PWM Output; ADC6: ADC Input Channel 6;
8	PB2	I/O	8	GPIO (High Voltage Resistance)	PWMCH1L: Motor PWM Channell (L);
9	PB1	I/O	24/8	GPIO (pull up)	Long Press Reset; ADC5: ADC Input Channel 5; UART1RXA: Uart1 Data In(A);
10	PB0	I/O	8	GPIO (High Voltage Resistance)	UARTITXA: Uart1 Data Out(A); PWMCH1H: Motor PWM Channel1 (H);
	DVDD	P	/	1	Core Power 1.2V;
11	BTRF	/	1		BT Antenna;
12	VSS	P	1		Ground;
13	BTOSCI	I	/		BT OSC In;
14	BTOSCO	0	/		BT OSC Out;
15	PC5	I/O	24/8	GPIO	SD1CLKA: SD1 Clock(A); SPI1DOB: SPI1 Data Out(B); UART2RXD: Uart2 Data In(D); IIC_SDA_B: IIC SDA(B); ADC13: ADC Input Channel 13; Touch15: Touch Input Channel 15;
					Touch15: Touch Input Channel 15; PWMCH5L: Motor PWM Channel5(L);

					SD1CMDA: SD1 Command(A);	
					SPI1CLKB: SPI1 Clock(B);	
			24/8		UART2TXD: Uart2 Data Out(D);	
16	PC4	I/O		GPIO	IIC SCL B: IIC SCL(B);	
					ADC10: ADC Input Channel 10;	
					Touch14: Touch Input Channel 14;	
					PWMCH5H: Motor PWM Channel5(H);	
					SD1DAT0A: SD1 Data0(A);	
17	PC3	I/O	24/8	GPIO	SPI1DIB: SPI1 Data In(B);	
					Touch13: Touch Input Channel 13;	
					SD1DAT1A: SD1 Data1(A);	
18	PC2	I/O	24/8	GPIO	Touch12: Touch Input Channel 12;	
			-		FPIN5: Motor Auto-Stop Protective Pin5;	
19	PA15	I/O	24/8	GPIO	CAP2: Timer2 Capture;	
					SD1DAT2A: SD1 Data2(A);	
					Touch11: Touch Input Channel 11;	
20	PC1	I/O	24/8	GPIO	UART1RXB: Uart1 Data In(B);	
					FPIN4: Motor Auto-Stop Protective Pin4;	
21	PA14	I/O	24/8	GPIO	FPIN0: Motor Auto-Stop Protective Pin0;	
					SD1DAT3A: SD1 Data3(A);	
	200	7/0	2.1/0	anta	Touch10: Touch Input Channel 10;	
22	PC0	I/O	24/8	GPIO	UARTITXB: Uart1 Data Out(B);	
			6		FPIN3: Motor Auto-Stop Protective Pin3;	
23	PA13	I/O	24/8	GPIO		
					PWM1: Timer1 PWM Output;	
24	PA12	I/O	24/8	GPIO	ADC4: ADC Input Channel 4;	
					UART0RXD: Uart0 Data In(D);	
	PA11	I/O	24/8	GPIO	UART0TXD: Uart0 Data Out(D);	
25			- 4	USB Negative	UART1RXD: Uart1 Data In(D);	
23	USBDM	I/O	4	Data	SPI2DOB: SPI2 Data Out(B);	
	to -			(pull down)	IIC_SDA_A: IIC SDA(A);	
4					SD0CLKA: SD0 Clock(A);	
					ADC3: ADC Input Channel 3;	
	BA 10	I/O	24/0	CDIO	TMR1: Timer1 Clock Input;	
	PA10		24/8	GPIO	Touch9: Touch Input Channel 9;	
200					UART2RXB: Uart2 Data In(B);	
26					PWMCH4L: Motor PWM Channel4(L);	
				HGD D:4	UART1TXD: Uart1 Data Out(D);	
	HGDDD	1/0	4	USB Positive	SPI2CLKB: SPI2 Clock(B);	
	USBDP	I/O	4	Data	IIC_SCL_A: IIC SCL(A);	
			(pull down)	ADC12: ADC Input Channel 12;		

6

	Г			T	
					SD0CMA: SD0 Command(A); Touch8: Touch Input Channel 8;
27	PA9	I/O	24/8	GPIO	UART2TXB: Uart2 Data Out(B);
					PWMCH4H: Motor PWM Channel4(H);
					SD0DAT3A: SD0 Data3(A);
28	PA8	I/O	24/8	GPIO	` /
					FPIN2: Motor Auto-Stop Protective Pin2;
20	D 4 7	I/O	24/8	GPIO	SD0DAT2A: SD0 Data2(A);
29	PA7	1/0	24/8	GPIO	TMR0: Timer0 Clock Input;
					Touch7: Touch Input Channel 7;
		8			SD0DAT1A: SD0 Data1(A);
	5.6	7/0	2.1/0	anvo.	ADC2: ADC Input Channel 2;
30	PA6	I/O	24/8	GPIO	IIC_SDA_D: IIC SDA(D);
					Touch6: Touch Input Channel 6;
				7	UART0RXA: Uart0 Data In(A);
					SD0DAT0A: SD0 Data0(A);
					ADC1: ADC Input Channel 1;
31	PA5	I/O	24/8	GPIO	IIC_SCL_D: IIC SCL(D);
	1710		2 17 0		Touch5: Touch Input Channel 5;
					PWM0: Timer0 PWM Output;
					UARTOTXA: Uart0 Data Out(A);
32	PA4	I/O	24/8	GPIO	Touch4: Touch Input Channel 4;
33	PA3	I/O	24/8	GPIO	Touch3: Touch Input Channel 3;
	1110	2.0	2 0	0.10	UART2RXA: Uart2 Data In(A);
					Touch2: Touch Input Channel 2;
34	PA2	I/O	24/8	GPIO	UART2TXA: Uart2 Data Out(A);
A				/ /	CAP3: Timer3 Capture;
					Touch1: Touch Input Channel 1;
35	PA1	I/O	24/8	GPIO	ADC0: ADC Input Channel 0;
33	TAI	1/0	24/6	GI IO	UART1RXC: Uart1 Data In(C);
					PWMCH0L: Motor PWM Channel0(L);
					Touch0: Touch Input Channel 0;
26	DAO -	I/O	24/9	CDIO	CLKOUT0: Clk Out0;
36	PA0	I/O	24/8	GPIO	UART1TXC: Uart1 Data Out(C);
					PWMCH0H: Motor PWM Channel0(H);
37	PC7	I/O	/	GPIO	MIC BIAS: Microphone Bias Output;
38	PC6	I/O	/	GPIO	MIC: MIC Input Channel;
200	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1/0	′	GFIO	ADC11: ADC Input Channel 11;
39	DACL	О	/		DAC Left Channel;
40	DACR	О	/		DAC Right Channel;
41	PB11	I/O	/	GPIO	SDPG:SDC Power Gate;

42	PB10	I/O	24/8	GPIO	SD0CMB: SD0 Command(B); SPI2DOA: SPI2 Data Out(A); SD1DAT3B: SD1 Data3(B); ADC9: ADC Input Channel 9; UART2RXC: Uart2 Data In(C); PWMCH3L: Motor PWM Channel3(L);
43	PB9	I/O	24/8	GPIO	SD0 Clock(B); SPI2CLKA: SPI2 Clk(A); SD1DAT2B: SD1 Data2(B); CAP0: Timer0 Capture; UART2TXC: Uart2 Data Out(C); PWMCH3H: Motor PWM Channel3(H);
44	PB8	I/O	24/8	GPIO	SD0DAT0B: SD0 Data0(B); SPI2_DIA: SPI2 Data In(A); SD1DAT1B: SD1 Data1(B); ADC8: ADC Input Channel 8; CLKOUT1: Clk Out1;
45	PB7	I/O	24/8	GPIO	
46	PB6	I/O	24/8	GPIO	SD1CLKB: SD1 Clock(B); SD0DAT1B: SD0 Data1(B); IIC_SDA_C: IIC SDA(C); TMR3: Timer3 Clock Input; UART0RXB: Uart0 Data In(B); PWMCH2L: Motor PWM Channel2 (L);
47	PB5	I/O	/	GPIO (High Voltage Resistance)	SD1CMDB: SD1 Command(B); SD0DAT2B: SD1 Data2(B); PWM3: Timer3 PWM Output; CAP1: Timer1 Capture; UART0TXC: Uart0 Data Out(C); UART0RXC: Uart0 Data In(C);
48	PB4	I/O	24/8	GPIO	SD1DAT0B: SD1 Data0(B); SD0DAT3B: SD0 Data3(B); IIC_SCL_C: IIC SCL(C); ADC7: ADC Input Channel 7; UART0TXB: Uart0 Data Out(B); LVD: Low Voltage Detect Input; PWMCH2H: Motor PWM Channel2 (H);

2, Electrical Characteristics

2.1 Absolute Maximum Ratings

Table 2-1

Symbol	Parameter	Min	Max	Unit
Tamb	Operating Temperature	-40	+85	°C
Tstg	Storage temperature	-65	+150	°C
VBAT	Supply Voltage	-0.3	4.5	V
LDOIN	Charger Voltage	-0.3	6	V
V _{3.3IO}	3.3V IO Input Voltage	-0.3	3.6	V

Note: The chip can be damaged by any stress in excess of the absolute maximum ratings listed below

2.2 PMU Characteristics

Table 2-2

Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions		
VBAT	Voltage Input	2.2	3.7	4.5	V	-		
LDOIN	Charger Voltage	4.5	5.0	5.5	V	-		
$V_{3.3}$	Voltage output	2.2	3.0	3.4	V	VBAT = 3.7V, 100mA loading		
V _{BT_AVDD}	Voltage output	1.2	1.25	1.35	V	VBAT = 3.7V, 100mA loading		
I _{L3.3}	Loading current	-	- /	150	mA	VBAT = 3.7V		

2.3 IO Input/Output Electrical Logical Characteristics

Table 2-3

IO input ch	aracteristics					
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
V _{IL}	Low-Level Input Voltage	-0.3	-	0.3* VDDIO	V	VDDIO = 3.3V
$V_{ m IH}$	High-Level Input Voltage	0.7* VDDIO	-	VDDIO+0.3	V	VDDIO = 3.3V
IO output c	haracteristics					
V_{OL}	Low-Level Output Voltage	-	-	0.33	V	VDDIO = 3.3V
V _{OH}	High-Level Output Voltage	2.7	-	-	V	VDDIO = 3.3V

2.4 Internal Resistor Characteristics

Table 2-4

1	Port	General Output	High Drive	Internal Pull-Up Resistor	Internal Pull-Down Resistor	Comment
PB1, PB6	0~PA15 PB3, PB4 6~PB10 0~PC6	8mA	24mA	10K	10K	1、PB1 default pull up 2、USBDM & USBDP
PB11	Output0	8mA	24mA	10K	10K	default pull down 3 PB0, PB2, PB5 can
PC7	Output1	8mA	64mA	TOIC	TOIC	pull-up resistance to 5V
PB0,	PB2, PB5	8mA	-	10K	10K	4 internal
PR	0, PR1	8mA	-	10K	10K	pull-up/pull-down resistance accuracy
U	USBDP 4mA -		1.5K	15K	±20%	
US	SBDM	4mA	<u> </u>	180K	15K	

2.5 DAC Characteristics

Table 2-5

Parameter	Min	Тур	Max	Unit	Test Conditions
Frequency Response	20	-	20K	Hz	
THD+N	-	-75	-	dB	1KHz/0dB
S/N	-	92	- /	dB	10Kohm loading
Crosstalk	- /	-80	- /	dB	With A-Weighted Filter
Output Swing	- /	1	-	Vrms	1
Dynamic Range	-	90	-	dB	1KHz/-60dB 10Kohm loading With A-Weighted Filter
DAC Output Power	11	-	-	mW	32ohm loading

2.6 ADC Characteristics

Table 2-6

Parameter	Min	Тур	Max	Unit	Test Conditions
Dynamic Range	-	80	-	dB	1KHz/-60dB
S/N	-	90	91	dB	
THD+N	-	-70	-	dB	1KHz/-60dB
Crosstalk	-	-80	-	dB	

2.7 BT Characteristics

2.7.1 Transmitter

Basic Rate

Table 2-7

<u> </u>						
Paramete	er	Min	Тур	Max	Unit	Test Conditions
RF Transmit 1	Power	1	4	6	dBm	
RF Power Contr	ol Range	-	20	-	dB	25℃,
20dB Bandv	20dB Bandwidth		950	77-	KHz	Power Supply
In-band spurious	$F=F_0\pm 1MHz$	4	-20	/-	dBm	VBAT=3.7V
Emissions	$F=F_0\pm 2MHz$	-	-45	-	dBm	2441MHz
(BQB Test Mode	$F=F_0\pm 3MHz$	-	-35	-	dBm	DH5
RF_Tx Power=4dBm)	$F=F_0\pm>3MHz$	-	-45	-	dBm	

Enhanced Data Rate

Table 2-8

Parameter		Min	Тур	Max	Unit	Test Conditions
Relative Po	wer	-	-1	-	dB	
π/4 DOPSK	DEVM RMS	-	4	-	%	25°C,
	DEVM 99%	-	10	-	%	Power Supply
Modulation Accuracy	DEVM Peak	- /	7	- /	%	11.5
In-band spurious	$F=F_0\pm 1MHz$	-/ /	-4	-/-	dBm	VBAT=3.7V
Emissions	$F=F_0\pm 2MHz$	7- /	-30	7_	dBm	2441MHz
(BQB Test Mode	$F=F_0\pm 3MHz$	7 -	-30	-	dBm	2DH5
RF_Tx Power=4dBm)	$F=F_0\pm>3MHz$	/ <u>/</u>	-37	-	dBm	

2.7.2 Receiver

Basic Rate

Table 2-9

Paramete	Min	Тур	Max	Unit	Test Conditions	
Sensitivit	-	-89	-	dBm		
Co-channel Interference Rejection		-	7	-	dB	25°C,
	+1MHz	-	-6	-	dB	Power Supply
	-1MHz	-	-6	-	dB	
Adjacent Channel selectivity C/I	+2MHz	-	-22	-	dB	VBAT=3.7V
	-2MHz	-/	-27	1-/-	dB	2441MHz
	+3MHz	_	-29	/-	dB	DH5
	-3MHz	-	-31	-	dB	

Enhanced Data Rate

Table 2-10

Paramete	er	Min	Тур	Max	Unit	Test Conditions
Sensitivit	-	-91	-	dBm		
Co-channel Interference Rejection		-	9	-	dB	25°C,
	+1MHz	-	-13	-	dB	Power Supply
Adjacent Channel selectivity C/I	-1MHz	- 19	-14	- /	dB	
	+2MHz	- /	-24	- 7	dB	VBAT=3.7V
	-2MHz	-/-	-28	- 9	dB	2441MHz
	+3MHz		-28	_	dB	2DH5
	-3MHz	/-/	-33	1-	dB	

2.7.3 BLE

1M Data Rate

Table 2-11

Parameter		Min	Тур	Max	Unit	Test Conditions
Sensitivity		-	-93	-	dBm	
RF Transmit Power		-	6.5	8	dBm	
In-band Spurious	M-N =2MHz	-	-34	-	dBm	
Emission	M-N ≥3MHz	-	-31	-	dBm	25°C
	Δf1 avg	-	250	-	KHz	Power Supply
Modulation Characteristics	Δf2 99%	-	210	-	KHz	VBAT=3.7V
	Δflavg/Δf2avg	4	0.9	-	/	2440MHz
Carrier Frequency Offset		-15	- /	+15	KHz	
Frequency Drift		-25	-/-/	+25	KHz	
Frequency Drift Rate		-5	7/	+5	KHz/50us	

2M Data Rate

Table 2-12

Paramete	Min	Тур	Max	Unit	Test Conditions		
Sensitivity		-	-90	-	dBm		
RF Transmit Power		- 0	6.5	8	dBm		
	M-N =4MHz	-	-40	-	dBm		
In-band Spurious Emission	M-N =5MHz	-	-40	-/	dBm	25°C	
Limsion	M-N ≥6MHz	-//	-40	1/2-	dBm	Power Supply	
	Δfl avg	-	500	-	KHz		
Modulation Characteristics	Δf2 99%	-	430	-	KHz	VBAT=3.7V	
	Δflavg/Δf2avg	/ ₋	0.9	-	/	2440MHz	
Carrier Frequency Offset		-20	-	+20	KHz		
Frequency Drift		-25	-	+25	KHz		
Frequency Drift Rate		-5	-	+5	KHz/50us		

Long Range

Table 2-13

Parameter	Min	Тур	Max	Unit	Test Conditions
Sensitivity LE 125K(S8)	-	-100	-	dBm	VBAT=3.7V,25°C
Sensitivity LE 500K(S2)	-	-96	-	dBm	2440MHz

3. Package Information

3.1 LQFP48(7mm*7mm)

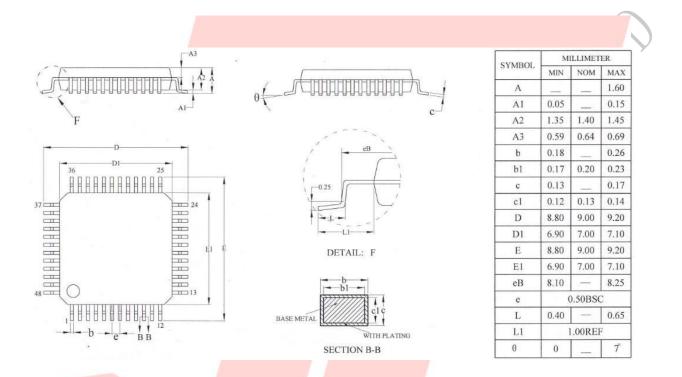


Figure 3-1. AC6351D_LQFP48 Package

4. Revision History

Date	Revisio	n	Description	
2020.08.11	V1.0		Initial Release	
2022.07.19	V1.1		Update Bluetooth Feature	
2024.03.06	V1.2		Update Bluetooth Feature, Add BLE Parameter	1
2024.06.27	V1.3	1	Update Pin Description, Add Audio Parameter	y
	111			

