

Chapter 2

Determinants and Matrices

solutions by Hikari

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2.1 Determinants

- 2.1.1** (a) $1 \times (-1 \times 1) = -1$
 (b) $1 \times (1 \times 1 - 2 \times 3) - 2 \times (3 \times 1 - 2 \times 0) = -11$
 (c) $\frac{1}{\sqrt{2}}(-\sqrt{3}) \times \sqrt{3} \times (-\sqrt{3} \times \sqrt{3}) = \frac{9}{\sqrt{2}}$

2.1.2 $\begin{vmatrix} 1 & 3 & 3 \\ 1 & -1 & 1 \\ 2 & 1 & 3 \end{vmatrix} = 2$, So the homogeneous linear independent equations have no nontrivial solutions.

- 2.1.3** (a) $\begin{vmatrix} 1 & 2 \\ 2 & 4 \end{vmatrix} = 0$
 (b) $\begin{vmatrix} 3 & 2 \\ 6 & 4 \end{vmatrix} = 0$
 (c) $(1, 1), (2, 2)$

2.1.4 (a) $|A| = \sum_{ij\dots} \varepsilon_{ij\dots} a_{1i} a_{2j} \dots$, which is the sum of all products formed by choosing one entry in each row that they are all in different columns (call it a valid combination), multiplying them together, and multiplying $+1$ or -1 depending on the parity of permutation $c_1 c_2 \dots$, where c_i is the column of the entry chosen in row i . $a_{ji} C_{ji} = a_{ji} M_{ji} (-1)^{j+i}$, is the sum of all products of valid combinations in M_{ji} , multiplying a_{j+i} , multiplying $(-1)^{j+i}$. If it takes n steps for a permutation in M_{ji} to return to reference order, then it will take $n + |j - i|$ steps for the permutation appended a_{ji} to return to reference order, so $a_{ij} M_{ij} (-1)^{|j-i|} = a_{ij} M_{ij} (-1)^{j+i}$ will contribute to the sum of products of valid combinations in A that contains a_{ji} , so $\sum_i a_{ji} C_{ji}$ contains all products of valid combinations, and is therefore equal to $|A|$.

Example:

$$\begin{array}{ccc} \begin{vmatrix} & o & \\ o & & \\ & o & \end{vmatrix} & \xrightarrow{2 \text{ steps}} & \begin{vmatrix} o & & \\ & o & \\ & & o \end{vmatrix} \\ \\ \begin{vmatrix} & o & & \\ o & & a_{24} & \\ & & & o \end{vmatrix} & \xrightarrow{2 \text{ steps}} & \begin{vmatrix} o & & & \\ & o & a_{24} & \\ & & o & \\ & & & o \end{vmatrix} & \xrightarrow{|4-2| \text{ steps}} & \begin{vmatrix} o & & & \\ & a_{24} & & \\ & & o & \\ & & & o \end{vmatrix} \end{array}$$

(b) If A' is the matrix whose k^{th} column is the j^{th} column of A and all the other columns is the same with A , then $\sum_i a_{ij} C_{ik} = \sum_i a'_{ik} C'_{ik}$ is the determinant of A' , but A' has two equal rows (j^{th} and k^{th} rows), so it equals to zero.

2.1.5 (a) $\det(H_1) = 1$, $\det(H_2) = 8.3333 \times 10^{-2}$, $\det(H_3) = 4.62963 \times 10^{-4}$

(b) for $\det(H_4)$:

Subtract the last row from each row above it:

$$\begin{vmatrix} \frac{1}{1} & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ \frac{1}{4} & \frac{1}{5} & \frac{1}{6} & \frac{1}{7} \end{vmatrix} = \begin{vmatrix} \frac{3}{(1)(4)} & \frac{3}{(2)(5)} & \frac{3}{(3)(6)} & \frac{3}{(4)(7)} \\ \frac{2}{(2)(4)} & \frac{2}{(3)(5)} & \frac{2}{(4)(6)} & \frac{2}{(5)(7)} \\ \frac{1}{(3)(4)} & \frac{1}{(4)(5)} & \frac{1}{(5)(6)} & \frac{1}{(6)(7)} \\ \frac{1}{4} & \frac{1}{5} & \frac{1}{6} & \frac{1}{7} \end{vmatrix} = \frac{(1)(2)(3)}{(4)(5)(6)(7)} \begin{vmatrix} \frac{1}{1} & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ 1 & 1 & 1 & 1 \end{vmatrix} = \frac{(3!)^2}{7!} \begin{vmatrix} \frac{1}{1} & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ 1 & 1 & 1 & 1 \end{vmatrix}$$

Subtract the last column from each column precedes it:

$$\frac{(3!)^2}{7!} \begin{vmatrix} \frac{1}{1} & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ 1 & 1 & 1 & 1 \end{vmatrix} = \frac{(3!)^2}{7!} \begin{vmatrix} \frac{3}{(1)(4)} & \frac{2}{(2)(4)} & \frac{1}{(3)(4)} & \frac{1}{4} \\ \frac{3}{(2)(5)} & \frac{2}{(3)(5)} & \frac{1}{(4)(5)} & \frac{1}{5} \\ \frac{3}{(3)(6)} & \frac{2}{(4)(6)} & \frac{1}{(5)(6)} & \frac{1}{6} \\ 0 & 0 & 0 & 1 \end{vmatrix} = \frac{(3!)^2}{7!} \frac{(3!)^2}{6!} \begin{vmatrix} \frac{1}{1} & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ 0 & 0 & 0 & 1 \end{vmatrix} = \frac{(3!)^4}{(7!)(6!)} \det(H_3)$$

By this procedure, we found that

$$\det(H_n) = \frac{(n-1)!^4}{(2n-1)!(2n-1)!} \det(H_{n-1})$$

So $\det(H_4) = \frac{3!^4}{7!6!} \det(H_3) = 1.65344 \times 10^{-7}$, $\det(H_5) = \frac{4!^4}{9!8!} \det(H_4) = 3.74930 \times 10^{-12}$, $\det(H_6) = \frac{5!^4}{11!10!} = 5.36730 \times 10^{-18}$

2.1.6 Linear dependence implies one row (or column) can be expressed by linear combination of other rows (columns), so $A_{ni} = a_1 A_{1i} + a_2 A_{2i} + \dots$. Add $-a_j$ times the j^{th} row to the n^{th} row, then the determinant remains the same, but all entries in the n^{th} row becomes 0, so the determinant equals to zero.

2.1.7 By Gauss's elimination, $x_1 = 1.88282$, $x_2 = -0.36179$, -0.96889 , 0.44221 , 0.41022 , 0.39219

2.1.8 (a) $\sum_i \delta_{ii} = \delta_{11} + \delta_{22} + \delta_{33} = 3$

(b) $\sum_{ij} \delta_{ij} \varepsilon_{ijk} = \sum_i \delta_{ii} \varepsilon_{iik} = 0$

(c) If $i \neq j$, then at least two of $1, j, p, q$ is the same, and $\varepsilon_{ipq} \varepsilon_{j pq} = 0$. If $i = j = 1$, then $\sum_{pq} \varepsilon_{ipq} \varepsilon_{j pq} = \varepsilon_{123} \varepsilon_{123} + \varepsilon_{132} \varepsilon_{132} = 2$, and the case is similar when $i = j = 2$ and $i = j = 3$. Therefore, $\sum_{pq} \varepsilon_{ipq} \varepsilon_{j pq} = 2\delta_{ij}$

(d) $\sum_{ijk} \varepsilon_{ijk} \varepsilon_{ijk} = (-1)^2 \times 6 = 6$

2.1.9 The only case that $\varepsilon_{ijk} \varepsilon_{pqk} \neq 0$ is : k is one of $(1, 2, 3)$ and $(i, j), (p, q)$ are the other two of $(1, 2, 3)$, respectively. So $i = p, j = q$ or $i = q, j = p$. For the former case, $\varepsilon_{ijk} \varepsilon_{pqk} = (\pm 1)^2 = 1 = \delta_{ip} \delta_{jq}$, and for the latter case, $\varepsilon_{ijk} \varepsilon_{pqk} = (1)(-1) = -1 = -\delta_{iq} \delta_{jp}$. Therefore, $\sum_k \varepsilon_{ijk} \varepsilon_{pqk} = \delta_{ip} \delta_{jq} - \delta_{iq} \delta_{jp}$

2.2 Matrices

2.2.1

$$((AB)C)_{il} = \sum_m (AB)_{im} C_{ml} = \sum_m \sum_k A_{ik} B_{km} C_{ml} = \sum_k \sum_m A_{ik} B_{km} C_{ml} = \sum_k A_{ik} (BC)_{kl} = (A(BC))_{il}$$

2.2.2 If $(A+B)(A-B) = A^2 - B^2$, then $A^2 + BA - AB - B^2 = A^2 - B^2$, so $AB - BA = [A, B] = 0$. If $[A, B] = 0$, then $(A+B)(A-B) = A^2 - B^2 - (AB - BA) = A^2 - B^2$

2.2.3 (a)

$$(a + ib) + (c + id) \longleftrightarrow \begin{pmatrix} a & b \\ -b & a \end{pmatrix} + \begin{pmatrix} c & d \\ -d & c \end{pmatrix} = \begin{pmatrix} a + c & b + d \\ -(b + d) & a + c \end{pmatrix} \longleftrightarrow (a + c) + i(b + d)$$

$$(a + ib)(c + id) \longleftrightarrow \begin{pmatrix} a & b \\ -b & a \end{pmatrix} \begin{pmatrix} c & d \\ -d & c \end{pmatrix} = \begin{pmatrix} ac - bd & ad + bc \\ -(ad + bc) & ac - bd \end{pmatrix} \longleftrightarrow (ac - bd) + i(ad + bc)$$

(b)

$$(a + ib)^{-1} = \frac{1}{a^2 + b^2}(a - ib) \longleftrightarrow \frac{1}{a^2 + b^2} \begin{pmatrix} a & -b \\ b & a \end{pmatrix}$$

2.2.4 Multiply each row of A by -1 will turn A into $-A$, so $\det(-A) = (-1)^n \det(A)$.

2.2.5 (a) If $A^2 = 0$ and $A = \begin{pmatrix} x & y \\ z & t \end{pmatrix}$

$$A^2 = \begin{pmatrix} x & y \\ z & t \end{pmatrix} \begin{pmatrix} x & y \\ z & t \end{pmatrix} = 0$$

Then $x^2 + yz = 0$, $t^2 + yz = 0$, $y(x + t) = 0$, $z(x + t) = 0$. Let $y = b^2$, $z = -a^2$, then $x = \pm ab$, $t = \pm ab$. Without loss of generality let $x = ab$ because the sign of a and b is arbitrary. If $y \neq 0$, then $t = -x = -ab$; if $y = 0$, then $t = x = ab = 0$ so $t = -ab$. Therefore, in all cases we can find a, b such that $\begin{pmatrix} x & y \\ z & t \end{pmatrix} = \begin{pmatrix} ab & b^2 \\ -a^2 & -ab \end{pmatrix}$

(b) Let $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, $B = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$, then $\det C = \det \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = 0$ but $\det A + \det B = 1 + 1 = 2$

2.2.6 $K = \begin{pmatrix} 0 & 0 & i \\ -i & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix}$, $K^2 = \begin{pmatrix} 0 & -i & 0 \\ 0 & 0 & 1 \\ i & 0 & 0 \end{pmatrix}$, $K^3 = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} = -I$, $K^4 = -K$, $K^5 = -K^2$, $K^6 = I$. So if $n = 6k$, k is positive integer, then $K^n = I$

2.2.7

$$[A, [B, C]] = [A, BC - CB] = (ABC - ACB) - (BCA - CBA) = ABC - ACB - BCA + CBA$$

$$[B, [A, C]] - [C, [B, A]] = [B, AC - CA] - [C, AB - BA]$$

$$= (BAC - BCA) - (ACB - CAB) - [(CAB - CBA) - (ABC - BAC)] = ABC - ACB - BCA + CBA$$

$$\text{So } [A, [B, C]] = [B, [A, C]] - [C, [B, A]]$$

2.2.8 Use the definition of commutator and carry out the corresponding matrix multiplication, then all the three relations are trivially satisfied.

2.2.9 Carry out the corresponding matrix multiplication, then all the relations are trivially satisfied.

2.2.10 If A and B are upper right triangular matrices, then $A_{ij} = 0$ when $j < i$, $B_{ij} = 0$ when $j < i$. $(AB)_{ij} = \sum_k A_{ik}B_{kj}$, when $j < i$: if $k > j$, then $B_{kj} = 0$, if $k \leq j$, then $k < i$ and $A_{ik} = 0$. So in all case $(AB)_{ij} = \sum_k A_{ik}B_{kj} = 0$ when $j < i$, so AB is also an upper right triangular matrix.

2.2.11 (a)(b) By matrix multiplication the relations hold trivially.

(c) When $i = j$, $\sigma_i \sigma_j + \sigma_j \sigma_i = 2(\sigma_i)^2 = 2I_2 = 2\delta_{ij}I_2$. When $i \neq j$: by (a) we know the inverse matrix of σ_i is itself, and by (b) we have $\sigma_i \sigma_j = i\sigma_k$, so $(\sigma_i \sigma_j)^{-1} = \sigma_j^{-1} \sigma_i^{-1} = \sigma_j \sigma_i = (i\sigma_k)^{-1} = -i\sigma_k$, so $\sigma_i \sigma_j + \sigma_j \sigma_i = i\sigma_k - i\sigma_k = 0 = 2\delta_{ij}I_2$. So $\sigma_i \sigma_j + \sigma_j \sigma_i = 2\delta_{ij}I_2$ holds for all cases.

2.2.12 (a)(b) By definition of commutator and matrix multiplication, the relations can be easily verified.

$$(c) [M^2, M_i] = 2IM_i - M_i 2I = 0; [M_z, L^+] = [M_z, M_x] + i[M_z, M_y] = iM_y + i(-i)M_x = M_x + iM_y; [L^+, L^-] = [M_x + iM_y, M_x - iM_y] = i[M_y, M_x] - i[M_x, M_y] = 2M_z$$

2.2.13 It is similar with Exercise 2.2.12.

2.2.14 If the i^{th} diagonal entries of A is a_i , then $(AB)_{ij} = a_i B_{ij}$, and $(BA)_{ij} = B_{ij} a_j$. So if $i \neq j$, then by $a_i B_{ij} = a_j B_{ij}$ and $a_i \neq a_j$, we have $B_{ij} = 0$, which means B is a diagonal matrix.

2.2.15 $(AB)_{ij} = \sum_k A_{ik} B_{kj} = \sum_k a_i \delta_{ik} b_j \delta_{kj} = a_i b_j \delta_{ij} = a_i b_i \delta_{ij}$. $(BA)_{ij} = \sum_k B_{ik} A_{kj} = \sum_k b_i \delta_{ik} a_j \delta_{kj} = a_j b_i \delta_{ij} = a_i b_i \delta_{ij}$. So $(AB)_{ij} = (BA)_{ij}$, and A and B commute.

2.2.16 For any two matrices X, Y we have $\text{trace}(XY) = \text{trace}(YX)$. If A, B commute, $\text{trace}(ABC) = \text{trace}(BAC) = \text{trace}(CBA)$; if B, C commute, $\text{trace}(ABC) = \text{trace}(ACB) = \text{trace}(CBA)$; if A, C commute, $\text{trace}(ABC) = \text{trace}(CAB) = \text{trace}(ACB) = \text{trace}(CBA)$.

2.2.17 $\text{trace}([M_j, M_k]) = \text{trace}(M_j M_k - M_k M_j) = \text{trace}(M_j M_k) - \text{trace}(M_k M_j) = 0 = \text{trace}(i M_l) = i \text{trace}(M_l)$, so $\text{trace}(M_l) = 0$, and so as M_j and M_k because the commutation relation is cyclic.

2.2.18 $\text{trace}(A) = \text{trace}(ABB) = \text{trace}(BAB) = \text{trace}(-ABB) = \text{trace}(-A) = -\text{trace}(A)$, so $\text{trace}(A) = 0$. The same is for $\text{trace}(B)$.

2.2.19 (a) If $AB = -BA$ and both are non-singular (so the matrix inverses exist): $\text{trace}(A) = \text{trace}(ABB^{-1}) = \text{trace}(B^{-1}AB) = \text{trace}(-B^{-1}BA) = \text{trace}(-A) = -\text{trace}(A)$, so $\text{trace}(A) = 0$. The same is for $\text{trace}(B)$.

(b) A, B being non-singular means $\det(A), \det(B) \neq 0$. Suppose they are anti-commuting and n is odd, then $\det(A) \det(B) = \det(AB) = \det(-BA) = \det(-B) \det(A) = (-1)^n \det(B) \det(A) = -\det(A) \det(B)$, so $\det(A) \det(B) = 0$. So either $\det(A)$ or $\det(B)$ equals to zero, contradicting to $\det(A), \det(B) \neq 0$.

2.2.20 $(A^{-1}A)_{ik} = \sum_j (A^{-1})_{ij} A_{jk} = \sum_j \frac{(-1)^{i+j} M_{ji}}{\det(A)} A_{jk} = \frac{1}{\det(A)} \sum_j (-1)^{i+j} M_{ji} A_{jk}$. If $i = k$, notice that $\det(A) = \det(A^T) = \sum_j (-1)^{i+j} M_{ji} A_{ji}$, so $(A^{-1}A)_{ik} = \frac{\det(A)}{\det(A)} = 1$; if $i \neq k$, then $(A^{-1}A)_{ik} = \frac{1}{\det(A)} \sum_j (-1)^{i+j} M_{ji} A_{jk} = \frac{1}{\det(A)} A_{jk} C_{ji} = 0$ by Exercise 2.1.4(b) (it is obvious by noticing that $\sum_j (-1)^{i+j} M_{ji} A_{jk}$ is the determinant of A whose k^{th} column is replaced by j^{th} column, and the determinant of matrix with two same column is zero). Therefore, $(A^{-1}A)_{ik} = \delta_{ik}$, so $A^{-1}A = I$.

2.2.21 (a) The unit matrix with M_{ii} replaced by k .

(b) The unit matrix with M_{im} replaced by $-K$.

(c) The unit matrix with M_{ii}, M_{mm} replaced by 0 and M_{im}, M_{mi} replaced by 1.

2.2.22 (a) The unit matrix with M_{ii} replaced by k .

(b) The unit matrix with M_{mi} replaced by $-k$.

(c) The unit matrix with M_{ii}, M_{mm} replaced by 0 and M_{im}, M_{mi} replaced by 1.

2.2.23 By Gauss-Jordan matrix inversion, $A^{-1} = \begin{pmatrix} 1 & -1 & 0 \\ -1 & \frac{11}{7} & -\frac{1}{7} \\ 0 & -\frac{1}{7} & \frac{2}{7} \end{pmatrix}$

2.2.24 (a) $\sum_{i=1}^n T_{ij}$ is the sum of fraction of population of j th area having moved to other(including j) areas, so the sum add up to 1.

(b) $\sum_{i=1}^n Q_i = \sum_{i=1}^n (TP)_i = \sum_{i=1}^n \sum_{j=1}^n T_{ij} P_j = \sum_{j=1}^n (\sum_{i=1}^n T_{ij}) P_j = \sum_{j=1}^n P_j = 1$

2.2.25

$$\begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{4} & \frac{1}{8} & \frac{1}{16} & \frac{1}{32} \\ \frac{1}{2} & 1 & \frac{1}{2} & \frac{1}{4} & \frac{1}{8} & \frac{1}{16} \\ \frac{1}{4} & \frac{1}{2} & 1 & \frac{1}{2} & \frac{1}{4} & \frac{1}{8} \\ \frac{1}{8} & \frac{1}{4} & \frac{1}{2} & 1 & \frac{1}{2} & \frac{1}{4} \\ \frac{1}{16} & \frac{1}{8} & \frac{1}{4} & \frac{1}{2} & 1 & \frac{1}{2} \\ \frac{1}{32} & \frac{1}{16} & \frac{1}{8} & \frac{1}{4} & \frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_i - \frac{1}{2}R_{i-1} \rightarrow R_i \ i=6 \sim 2}$$

$$\begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{4} & \frac{1}{8} & \frac{1}{16} & \frac{1}{32} \\ 0 & \frac{3}{4} & \frac{3}{8} & \frac{3}{16} & \frac{3}{32} & \frac{3}{64} \\ 0 & 0 & \frac{3}{4} & \frac{3}{8} & \frac{3}{16} & \frac{3}{32} \\ 0 & 0 & 0 & \frac{3}{4} & \frac{3}{8} & \frac{3}{16} \\ 0 & 0 & 0 & 0 & \frac{3}{4} & \frac{3}{8} \\ 0 & 0 & 0 & 0 & 0 & \frac{3}{4} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ -\frac{1}{2} & 1 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & 1 & 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{2} & 1 & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{2} & 1 & 0 \\ 0 & 0 & 0 & 0 & -\frac{1}{2} & 1 \end{pmatrix} \xrightarrow{\begin{matrix} \frac{3}{4}R_1 \rightarrow R_1 \\ R_i - \frac{1}{2}R_{i+1} \rightarrow R_i \ i=1 \sim 5 \end{matrix}}$$

$$\begin{pmatrix} \frac{3}{4} & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{3}{4} & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{3}{4} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{3}{4} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{3}{4} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{3}{4} \end{pmatrix} \begin{pmatrix} 1 & -\frac{1}{2} & 0 & 0 & 0 & 0 \\ -\frac{1}{2} & \frac{5}{4} & -\frac{1}{2} & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{5}{4} & -\frac{1}{2} & 0 & 0 \\ 0 & 0 & -\frac{1}{2} & \frac{5}{4} & -\frac{1}{2} & 0 \\ 0 & 0 & 0 & -\frac{1}{2} & \frac{5}{4} & -\frac{1}{2} \\ 0 & 0 & 0 & 0 & -\frac{1}{2} & 1 \end{pmatrix} \xrightarrow{\frac{4}{3}R_i \rightarrow R_i \ i=1 \sim 6}$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{4}{3} & -\frac{2}{3} & 0 & 0 & 0 & 0 \\ -\frac{2}{3} & \frac{5}{3} & -\frac{2}{3} & 0 & 0 & 0 \\ 0 & -\frac{2}{3} & \frac{5}{3} & -\frac{2}{3} & 0 & 0 \\ 0 & 0 & -\frac{2}{3} & \frac{5}{3} & -\frac{2}{3} & 0 \\ 0 & 0 & 0 & -\frac{2}{3} & \frac{5}{3} & -\frac{2}{3} \\ 0 & 0 & 0 & 0 & -\frac{2}{3} & \frac{4}{3} \end{pmatrix}$$

2.2.26 If A, B are orthogonal, $AA^T = I$ and $BB^T = I$, then $(AB)(AB)^T = ABB^TA^T = AA^T = I$, so AB is also orthogonal.

2.2.27 $\det(AA^T) = \det(A)\det(A^T) = (\det(A))^2 = \det(I) = 1$, so $\det(A) = \pm 1$

2.2.28 If $A = A^T$ and $B = -B^T$, then $\text{trace}(AB) = \text{trace}(BA) = \text{trace}(-B^TA^T) = \text{trace}(-(AB)^T) = -\text{trace}(AB)$, so $\text{trace}(AB) = 0$.

2.2.29 $AA^T = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} a & c \\ b & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, so $a^2 + b^2 = 1$, $c^2 + d^2 = 1$, $ac + bd = 0$. Let $\theta = \tan^{-1} \frac{b}{a}$, then $a = \cos \theta$, $b = \sin \theta$, $\frac{c}{d} = -\tan \theta$, $c = -\sin \theta$, $d = \cos \theta$. So the most general form is $\begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$.

2.2.30 $\det(A^*) = \sum_{ij\dots} \varepsilon_{ij\dots} a_{1i}^* a_{2j}^* \dots = (\sum_{ij\dots} \varepsilon_{ij\dots} a_{1i} a_{2j} \dots)^* = (\det A)^*$
 $\det(A^*) = \det((A^*)^T) = A^\dagger$

2.2.31 If two of the matrices are real, then their commutator is real, so i multiply the third matrix must be real, so the third matrix must be pure imaginary.

$$\mathbf{2.2.32} \quad (AB)^\dagger = ((AB)^T)^* = (B^T A^T)^* = ((B)^T)^*((A)^T)^* = B^\dagger A^\dagger$$

2.2.33 $S_{ij}^\dagger = S_{ji}^*$, so $\text{trace}(S^\dagger S) = \sum_i (S^\dagger S)_{ii} = \sum_i \sum_j S_{ij}^\dagger S_{ji} = \sum_i \sum_j |S_{ji}|^2 > 0$ when S is not null matrix.

2.2.34 $A^\dagger = A$, $B^\dagger = B$. $(AB + BA)^\dagger = B^\dagger A^\dagger + A^\dagger B^\dagger = BA + AB = AB + BA$; $[i(AB - BA)]^\dagger = -i(B^\dagger A^\dagger - A^\dagger B^\dagger) = -i(BA - AB) = i(AB - BA)$. So both $(AB - BA)$ and $i(AB - BA)$ are Hermitian.

2.2.35 $(C + C^\dagger)^\dagger = C^\dagger + C = C + C^\dagger$; $[i(C - C^\dagger)]^\dagger = -i(C^\dagger - C) = i(C - C^\dagger)$. So both matrices are Hermitian,

2.2.36 $C = -i(AB - BA)$, $C^\dagger = i(B^\dagger A^\dagger - A^\dagger B^\dagger) = i(BA - AB) = -i(AB - BA) = C$ so C is Hermitian.

2.2.37 If $AB = BA$, then $(AB)^\dagger = B^\dagger A^\dagger = BA = AB$ so AB is Hermitian; if AB is Hermitian, then $AB = (AB)^\dagger = B^\dagger A^\dagger = BA$. Therefore, $AB = BA$ is a necessary and sufficient condition for AB to be Hermitian.

2.2.38 $UU^\dagger = I$, $U^\dagger = U^{-1}$, $U = (U^{-1})^\dagger$, $U^{-1}U = I = U^{-1}(U^{-1})^\dagger$, so U^{-1} is unitary.

2.2.39 It is obvious that $(A \otimes B)^T = A^T \otimes B^T$, so $(A \otimes B)^\dagger = A^\dagger \otimes B^\dagger$. If A and B are unitary, then $(A \otimes B)(A \otimes B)^\dagger = (A \otimes B)(A^\dagger \otimes B^\dagger) = (AA^\dagger \otimes BB^\dagger) = I_1 \otimes I_2 = I$

$$\mathbf{2.2.40} \quad \boldsymbol{\sigma} \cdot \mathbf{p} = \sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3 = \begin{pmatrix} 0 & p_1 \\ p_1 & 0 \end{pmatrix} + \begin{pmatrix} 0 & -ip_2 \\ ip_2 & 0 \end{pmatrix} + \begin{pmatrix} p_3 & 0 \\ 0 & -p_3 \end{pmatrix} = \begin{pmatrix} p_3 & p_1 - ip_2 \\ p_1 + ip_2 & -p_3 \end{pmatrix},$$

so $(\boldsymbol{\sigma} \cdot \mathbf{p})^2 = \begin{pmatrix} p_3 & p_1 - ip_2 \\ p_1 + ip_2 & -p_3 \end{pmatrix} \begin{pmatrix} p_3 & p_1 - ip_2 \\ p_1 + ip_2 & -p_3 \end{pmatrix} = \begin{pmatrix} \mathbf{p}^2 & 0 \\ 0 & \mathbf{p}^2 \end{pmatrix} = \mathbf{p}^2 \mathbf{1}_2$

2.2.41 $(\gamma^0)^2 = (\sigma_3)^2 \otimes (\mathbf{1}_2)^2 = \mathbf{1}_2 \otimes \mathbf{1}_2 = \mathbf{1}_4$. $(\gamma^i)^2 = \gamma^2 \otimes (\sigma_i)^2 = (-\mathbf{1}_2) \otimes \mathbf{1}_2 = -\mathbf{1}_4$. When $\mu \neq 0$, $\gamma^\mu \gamma^i + \gamma^i \gamma^\mu = \gamma^2 \otimes (\sigma_\mu \sigma_i) + \gamma^2 \otimes (\sigma_i \sigma_\mu) = \gamma^2 \otimes (\sigma_\mu \sigma_i + \sigma_i \sigma_\mu) = \gamma^2 \otimes 0 = 0$; when $\mu = 0$, $\gamma^0 \gamma^i + \gamma^i \gamma^0 = (\sigma_3 \gamma) \otimes (\sigma_i) + (\gamma \sigma_3) \otimes (\sigma_i) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \otimes (\sigma_i) + \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \otimes (\sigma_i) = 0$

2.2.42 $\gamma^5 \gamma^\mu = i\gamma^0 \gamma^1 \gamma^2 \gamma^3 \gamma^\mu$. Switch γ^μ with γ^i left to it: if $i = \mu$, it won't change; if $i \neq \mu$, it will be multiplied (-1) by the anti-commuting properties. So after switching four times to move γ^μ to the left-most side, three (-1) have been multiplied, so $\gamma^5 \gamma^\mu = -i\gamma^\mu \gamma^0 \gamma^1 \gamma^2 \gamma^3 = -\gamma^\mu \gamma^5$, so γ^5 anti-commutes with all four γ^μ .

2.2.43 $(\gamma_\mu = \sum g_{\nu\mu} \gamma^\nu = \text{should be } \gamma_\nu = \sum g_{\nu\mu} \gamma^\mu)$ $\gamma_0 = \gamma^0$ and $\gamma_i = -\gamma^i$, $i = 1, 2, 3$. Along with $(\gamma^0)^2 = 1$ and $(\gamma^i)^2 = -1$, we have $\gamma_\mu \gamma^\mu = 1$, $\mu = 0, 1, 2, 3$.

(a) If $\mu = \alpha$, $\gamma_\mu \gamma^\alpha \gamma^\mu = \gamma_\mu \gamma^\mu \gamma^\alpha = \gamma^\alpha$; if $\mu \neq \alpha$, $\gamma_\mu \gamma^\alpha \gamma^\mu = -\gamma_\mu \gamma^\mu \gamma^\alpha = -\gamma^\alpha$. So $\sum \gamma_\mu \gamma^\alpha \gamma^\mu = (1 - 3)\gamma^\alpha = -2\gamma^\alpha$

(b) If $\alpha = \beta$, $\gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\mu = \gamma^\alpha \gamma^\beta = (\gamma^\alpha)^2 = g^{\alpha\alpha} = g^{\alpha\beta}$ for all $\mu = 0, 1, 2, 3$, so $\sum \gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\mu = 4g^{\alpha\beta}$. If $\alpha \neq \beta$, for $\mu = \alpha$ or $\mu = \beta$, $\gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\mu = -\gamma^\alpha \gamma^\beta$, and for $\mu \neq \alpha$ and $\mu \neq \beta$, $\gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\mu = \gamma^\alpha \gamma^\beta$, so $\sum \gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\mu = (-2 + 2)\gamma^\alpha \gamma^\beta = 0 = g^{\alpha\beta}$. So $\sum \gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\mu = 4g^{\alpha\beta}$.

(c) If α, β, ν are different with each other, then $\sum \gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\nu \gamma^\mu = (3 - 1)\gamma^\alpha \gamma^\beta \gamma^\nu = 2(-1)^3 \gamma^\nu \gamma^\beta \gamma^\alpha = -2\gamma^\nu \gamma^\beta \gamma^\alpha$. If only two of α, β, ν are the same, then $\sum \gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\nu \gamma^\mu = (-3 + 1)\gamma^\alpha \gamma^\beta \gamma^\nu = -2(1)(-1)^2 \gamma^\nu \gamma^\beta \gamma^\alpha = -2\gamma^\nu \gamma^\beta \gamma^\alpha$. If α, β, ν are all the same, then $\sum \gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\nu \gamma^\mu = (-3 + 1)\gamma^\alpha \gamma^\beta \gamma^\nu = -2\gamma^\nu \gamma^\beta \gamma^\alpha$. Therefore, in all cases, $\sum \gamma_\mu \gamma^\alpha \gamma^\beta \gamma^\nu \gamma^\mu = -2\gamma^\nu \gamma^\beta \gamma^\alpha$.

2.2.44 $(\gamma^5)^2 = -\gamma^0 \gamma^1 \gamma^2 \gamma^3 \gamma^0 \gamma^1 \gamma^2 \gamma^3 = -(-1)^{3+2+1} (\gamma^0)^2 (\gamma^1)^2 (\gamma^2)^2 (\gamma^3)^2 = 1$, so $M^2 = \frac{1}{4}(1 + 2\gamma^5 + (\gamma^5)^2) = \frac{1}{4}(2 + 2\gamma^5) = \frac{1}{2}(1 + \gamma^5) = M$.

2.2.45 By evaluation, we can find that the 16 Dirac matrices is equal to $(i)^n \sigma_i \otimes \sigma_j$, $i, j = 0, 1, 2, 3$ with each Dirac matrix having different (i, j) , if we let $\sigma_0 = 1_2$, n depend on i, j . Then the problem is equivalent to prove that the 16 $\sigma_i \otimes \sigma_j$ form a linearly independent set. If $a, b \neq 0$ and $(i, j) \neq (k, l)$, then $a\sigma_i \otimes \sigma_j + b\sigma_k \otimes \sigma_l \neq 0$ because the four σ_μ form a linearly independent set. So the 16 $\sigma_i \otimes \sigma_j$ form a linearly independent set, and the 16 Dirac matrices form a linearly independent set

2.2.46 (The 16 Dirac matrices is defined as $E_{ij} = \sigma_i \otimes \sigma_j$, $i, j = 0, 1, 2, 3$, where $\sigma_0 = I_2$)
For $(i, j) \neq (0, 0)$, $\text{trace}(E_{ij}) = \text{trace}(\sigma_i)(\sigma_j) = 0$ because $\text{trace}(\sigma_k) = 0$ when $k = 1, 2, 3$. So $\text{trace}(E_{ij}E_{mn}) \neq 0$ only when $(\sigma_i \otimes \sigma_j)(\sigma_m \otimes \sigma_n) = \sigma_0 \otimes \sigma_0$, that is, $i = m$ and $j = n$. Let $c_i = c_{mn}$, $\Gamma_i = E_{mn}$, $\sum_{i=1}^{16} c_i \Gamma_i = \sum_{i,j=0}^3 c_{ij} E_{ij}$, then $\text{trace}(A\Gamma_i) = \text{trace}(\sum_{i,j=0}^3 c_{ij} E_{ij} E_{mn}) = c_{mn} \text{trace}(E_{mn} E_{mn}) = c_{mn} \text{trace}(I_4) = 4c_{mn} = 4c_i$, so $c_i = \frac{1}{4} \text{trace}(A\Gamma_i)$.

2.2.47 Note that $(\gamma^0)^T = \gamma^0$, $(\gamma^1)^T = -\gamma^1$, $(\gamma^2)^T = \gamma^2$, $(\gamma^3)^T = -\gamma^3$. $C^{-1} = -i(\gamma^0)^{-1}(\gamma^2)^{-1} = i\gamma^0\gamma^2$, so $C\gamma^\mu C^{-1} = -\gamma^2\gamma^0\gamma^\mu\gamma^0\gamma^2$. If $\mu = 0$ or 2 , $-\gamma^2\gamma^0\gamma^\mu\gamma^0\gamma^2 = -(-1)(1)(-1)\gamma^\mu = -\gamma^\mu = -(\gamma^\mu)^T$; If $\mu = 1$ or 3 , $-\gamma^2\gamma^0\gamma^\mu\gamma^0\gamma^2 = -(-1)^2(1)(-1)\gamma^\mu = \gamma^\mu = -(\gamma^\mu)^T$. So in all cases $C\gamma^\mu C^{-1} = -(\gamma^\mu)^T$.

2.2.48 (a)

$$\begin{aligned} \gamma^0 mc^2 &= mc^2 \sigma_3 \otimes I_2 = \begin{pmatrix} mc^2 & 0 \\ 0 & -mc^2 \end{pmatrix} \\ c(\alpha_1 p_1 + \alpha_2 p_2 + \alpha_3 p_3) &= c\gamma^0(\gamma^1 p_1 + \gamma^2 p_2 + \gamma^3 p_3) = c(\sigma_3 \otimes I_2)(\gamma \otimes \sigma_1 p_1 + \gamma \otimes \sigma_2 p_2 + \gamma \otimes \sigma_3 p_3) \\ &= c\sigma_1 \otimes (\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) = \begin{pmatrix} 0 & c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) \\ \sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3 & 0 \end{pmatrix} \\ -EI_4 &= -EI_2 \otimes I_2 = \begin{pmatrix} -E & 0 \\ 0 & -E \end{pmatrix} \\ \psi &= \begin{pmatrix} \psi_L \\ \psi_S \end{pmatrix} \end{aligned}$$

So $[\gamma^0 mc^2 + c(\alpha_1 p_1 + \alpha_2 p_2 + \alpha_3 p_3) - E] \psi = 0$ becomes

$$\begin{pmatrix} mc^2 - E & c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) \\ c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) & -mc^2 - E \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_S \end{pmatrix} = 0$$

(b) By the indicated approximation, the equation becomes

$$\begin{pmatrix} -\varepsilon & c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) \\ c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) & -2mc^2 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_S \end{pmatrix} = 0$$

It can be separated to $\varepsilon\psi_L = c(\alpha_1 p_1 + \alpha_2 p_2 + \alpha_3 p_3)\psi_S$ and $c(\alpha_1 p_1 + \alpha_2 p_2 + \alpha_3 p_3)\psi_L = 2mc^2\psi_S$. Eliminating ψ_S and we obtain $\frac{1}{2m}(p_1^2 + p_2^2 + p_3^2)\psi_L = \varepsilon\psi_L$

(c) From the two separated equations, we can get $(\frac{\psi_S}{\psi_L})^2 = \frac{\varepsilon}{2mc^2} \ll 1$ in the non-relativistic approximation.

2.2.49

$$\begin{aligned} (\gamma^0)^2 &= \begin{pmatrix} I_2 & 0 \\ 0 & I_2 \end{pmatrix} = I_4 \\ (\gamma^i)^2 &= \begin{pmatrix} -\sigma_i^2 & 0 \\ 0 & -\sigma_i^2 \end{pmatrix} = \begin{pmatrix} -I_2 & 0 \\ 0 & -I_2 \end{pmatrix} = -I_4, \quad i = 1, 2, 3 \\ \gamma^\mu \gamma^i + \gamma^i \gamma^\mu &= \begin{pmatrix} -\sigma_\mu \sigma_i & 0 \\ 0 & -\sigma_\mu \sigma_i \end{pmatrix} + \begin{pmatrix} -\sigma_i \sigma_\mu & 0 \\ 0 & -\sigma_i \sigma_\mu \end{pmatrix} = 0, \quad \mu \neq i \end{aligned}$$

2.2.50 As in Exercise 2.2.48 but with γ^0 and γ^i defined in Exercise 2.2.49, the Dirac equation becomes

$$\begin{pmatrix} -c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) - E & mc^2 \\ mc^2 & c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) - E \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_S \end{pmatrix} = 0$$

In the limit that m approaches zero, the equation becomes

$$\begin{pmatrix} -c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) - E & 0 \\ 0 & c(\sigma_1 p_1 + \sigma_2 p_2 + \sigma_3 p_3) - E \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_S \end{pmatrix} = 0$$

which separates into independent 2×2 blocks.

- 2.2.51** (a) $|r'|^2 = r'^{\dagger}r' = r^{\dagger}U^{\dagger}Ur = r^{\dagger}r = |r|^2$
 (b) $r^{\dagger}r = r'^{\dagger}r' = r^{\dagger}U^{\dagger}Ur$ for any r , so $U^{\dagger}U = I$.