

# EE102

## Lecture 5

# EE102 Announcements

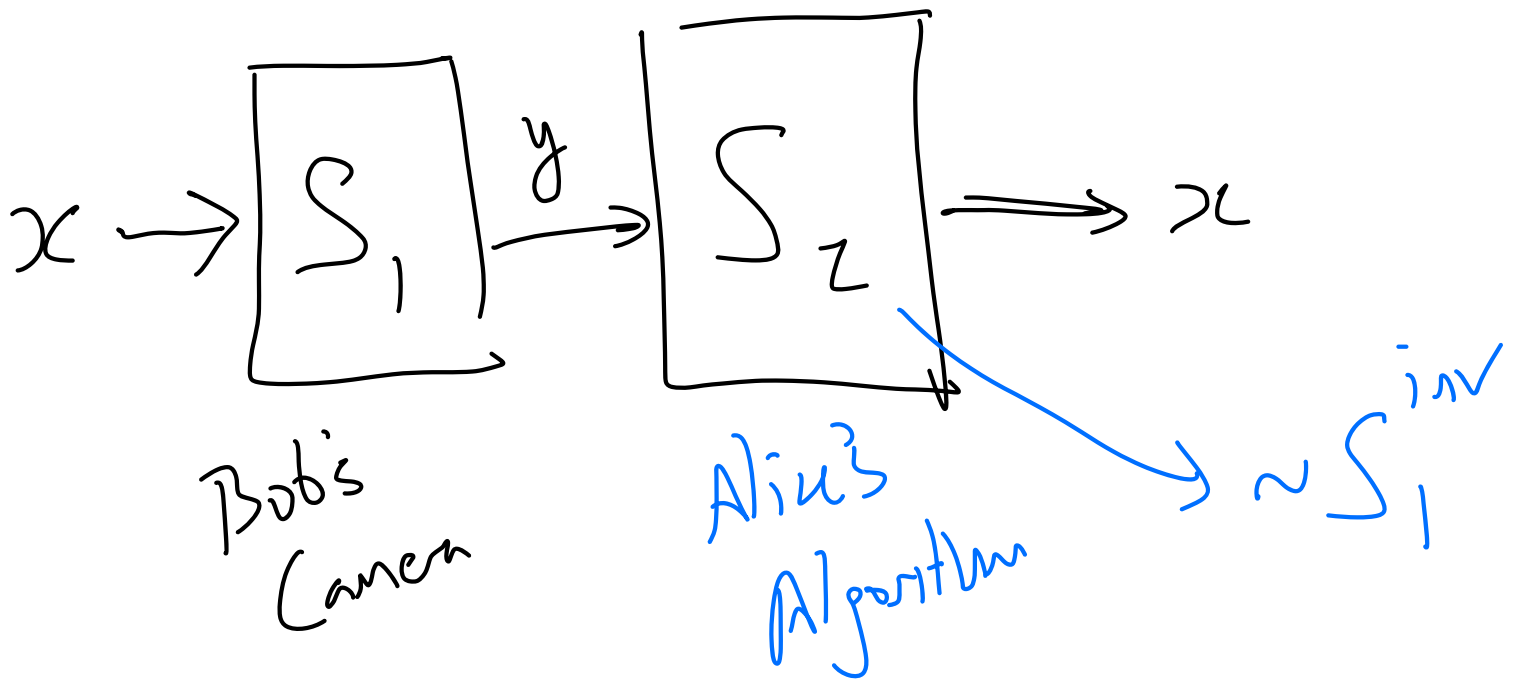
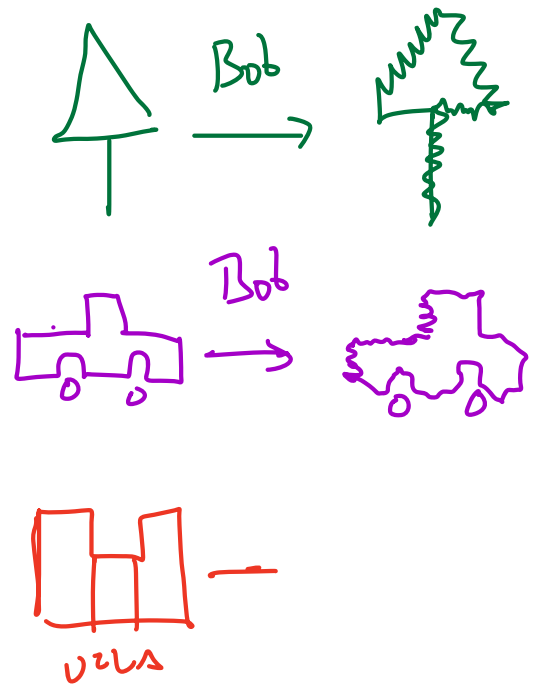
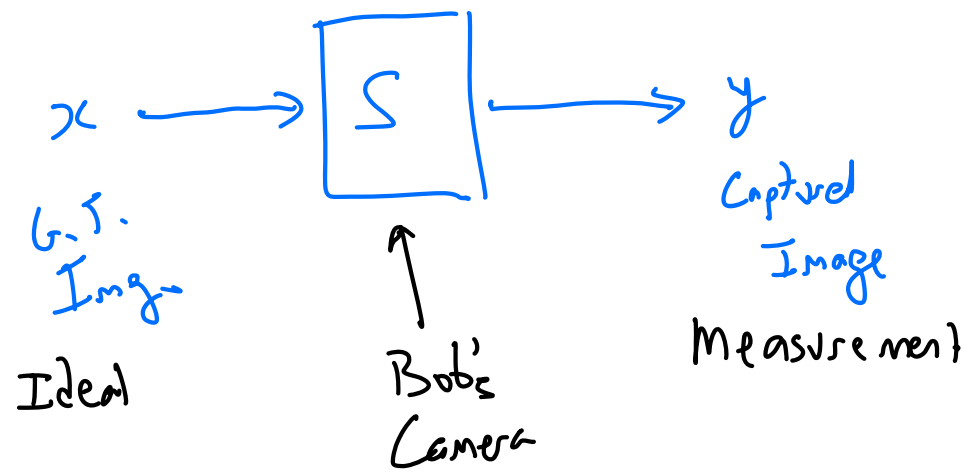
---

- **Syllabus link** is on BruinLearn
- Practice Midterm Released Early

**Slide Credits:** This lecture adapted from Prof. Jonathan Kao (UCLA) and recursive credits apply to Prof. Cabric (UCLA), Prof. Yu (Carnegie Mellon), Prof. Pauly (Stanford), and Prof. Fragouli (UCLA)

Alice  $\nabla$  Bob.

Image Corp



# Impulse Response

---

## System impulse response

This lecture introduces time-domain analysis of systems, including the impulse response. It also discusses linear time-invariant systems. Topics include:

- Impulse response definition
- Impulse response of LTI systems
- The impulse response as a sufficient characterization of an LTI system
- Impulse response and the convolution integral

# Impulse Response (cont.)

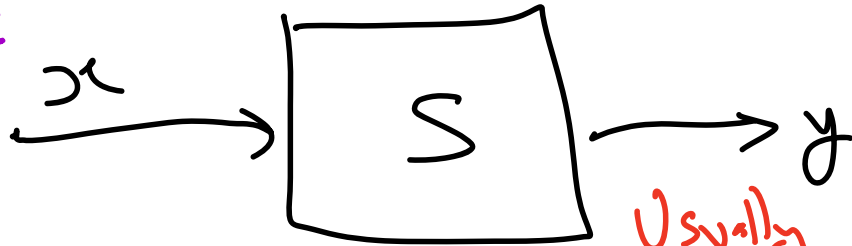
---

# Why do we need the impulse response?

① E.g.  $y(t) = [x(t)]^2$

This is a preset fct. NOT real life

② Real-Life. We do not know much, if anything, about the functional form of  $S$ .



Usually  $S$  describes something complicated and not known

Goal: Given some input, specific input  $x$ , predict  $y$ .

Soln: If I know the systems response to  $x = \delta(t)$ , then I know response to ANY  $x$ .

# Types of Responses $x \rightarrow \boxed{H} \rightarrow y$

Several systems are characterized by their functional response

- zero response:  $H[0]$
- impulse response:  $H[\delta(t)]$
- step response:  $H[u(t)]$

Q: Say  $H$  is linear, what is its zero response?

Ans:  $H(ax) = aH(x) \quad \forall a, x.$  Suppose  $a = 0$

$$\boxed{H(0) = 0}$$

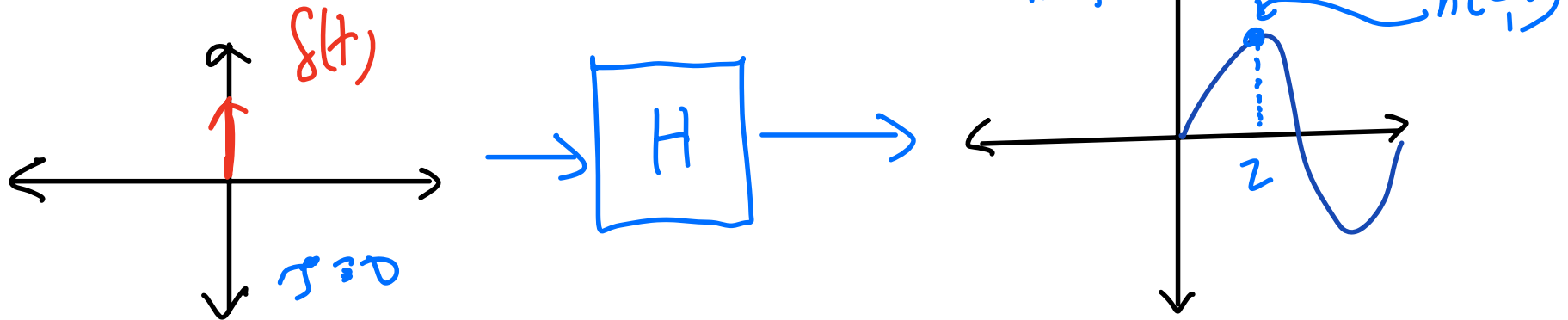
# Impulse Response Definition

Impulse Response: Let  $H$  be a system and  $y(t) = H[x(t)]$

The impulse response is

$$h(t, \tau) = H(\delta(t - \tau))$$

Intuition: Send impulse at time  $\tau$ , receive output  $h(t, \tau)$





$x(t)$   
input

$y(t)$   
output

$h(t)$  typically used  
for IR.

$$h(t, \tau) = H(\delta(t - \tau))$$

There are important things to be careful of when looking at this equation.

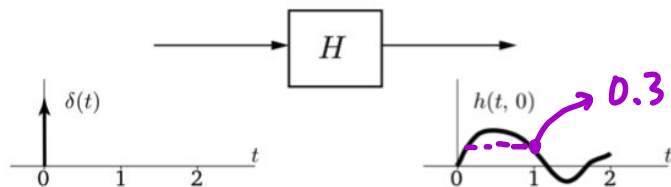
- The  $t$  on the left and right hand side of these equations *are not the same!*
- The  $t$  on the left hand side is the impulse response at a specific value of time.
- The  $t$  on the right hand side varies across all time.
- The output at the specific time  $t$  on the left will depend on the input at several times  $t$  on the right.

# Notation on t

$$h(t, \tau) = H(\delta(t - \tau))$$

There are important things to be careful of when looking at this equation.

An example of these  $t$ 's not being the same is shown below. In this example, let  $\tau = 0$ .



It may be tempting to write:

$$h(1, 0) = H(\delta(1))$$

This is wrong.

- On the left,  $\delta(1) = 0$ . We know if  $H$  is linear, then  $H(0) = 0$ , implying that  $h(1, 0) = 0$ .
- But in general, the impulse response can be non-zero, i.e.,  $h(1, 0) \neq 0$  in the above diagram, if the impulse response produces some non-zero response.

Assume  $\tau = 0$

$$h(t, 0) = H[\delta(t)]$$

DO NOT CHANGE

Set  $t=1$

$$h(1, 0) = H[\delta(1)]$$

Non-zero  
 $\approx 0.3$

Zero.

# Time invariant Impulse Response

Time Invariant H

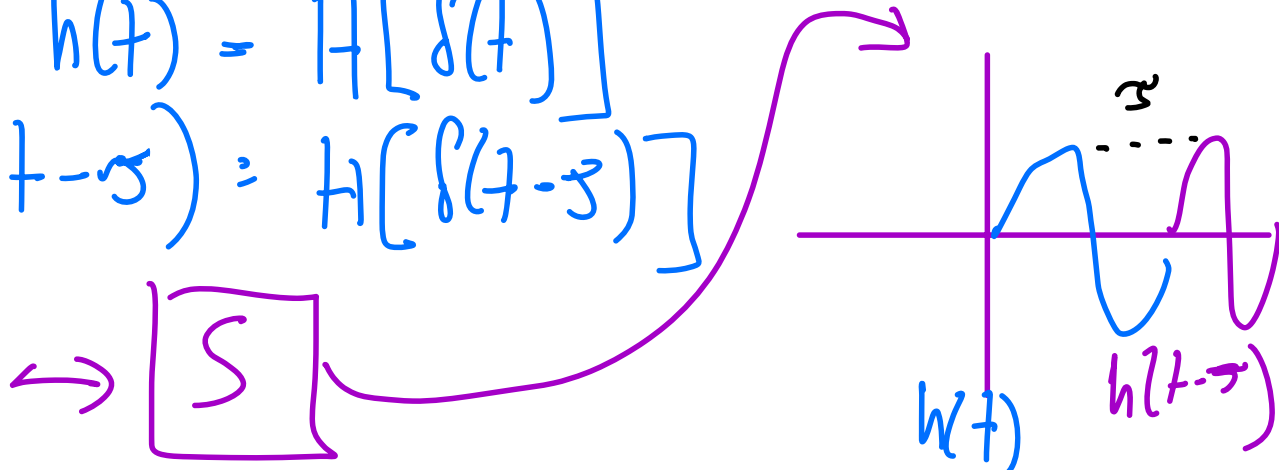
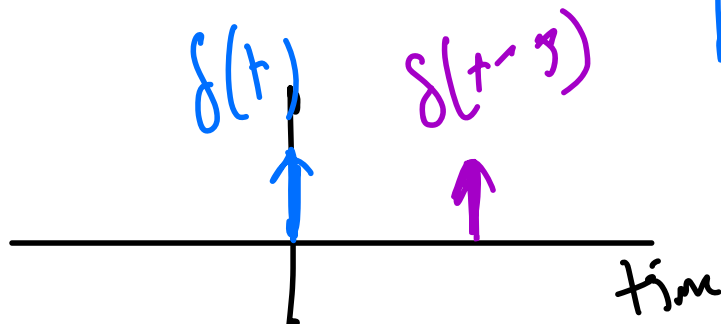
$$h(t, \tau) = H[\delta(t - \tau)]$$

$$h(t, 0) = H[\delta(t)]$$

Suppose H is time invariant.  $H[\delta(t - \tau)] = h(t - \tau, 0) = h(t, \tau)$

So I can simplify notation.  $h(t) = H[\delta(t)]$

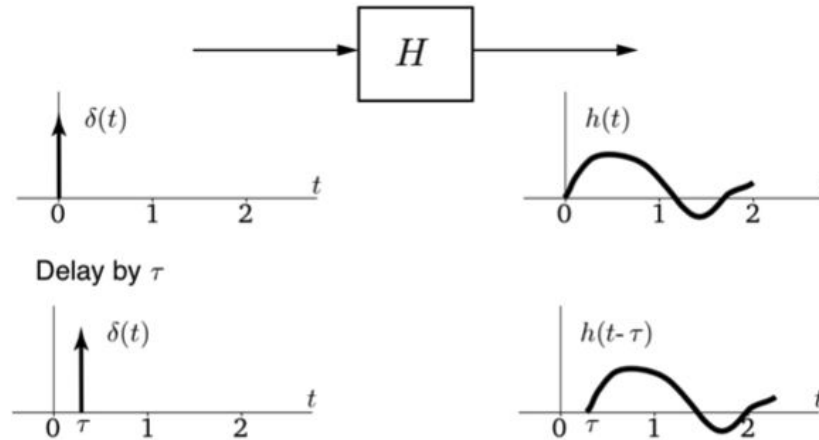
$$h(t - \tau) = H[\delta(t - \tau)]$$



# Time Invariant Impulse Response

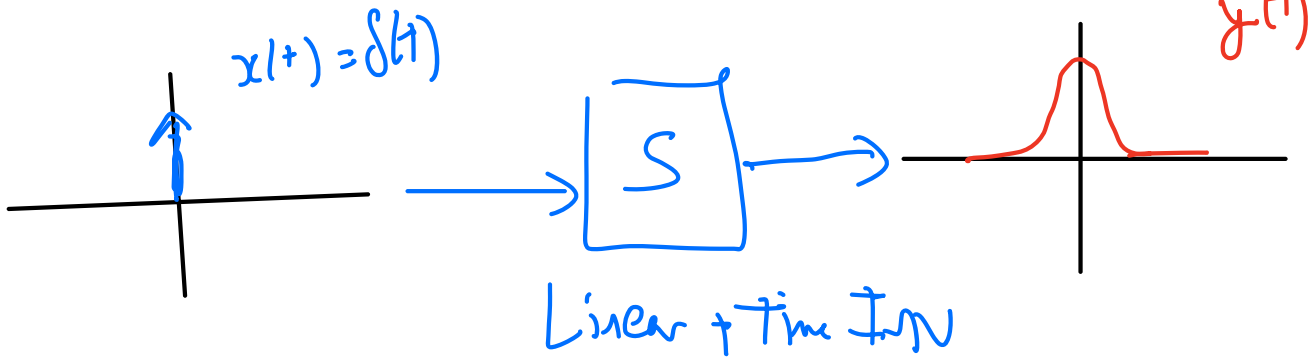
## Impulse response of a time-invariant system (cont.)

This property of the impulse response for a time-invariant system is drawn below:

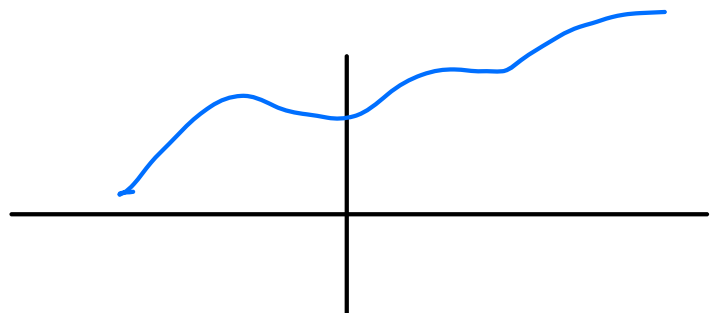
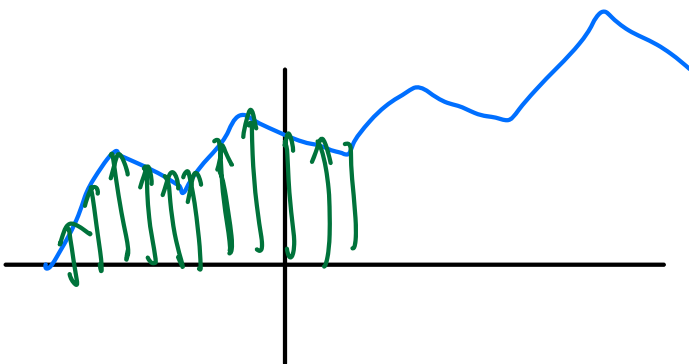
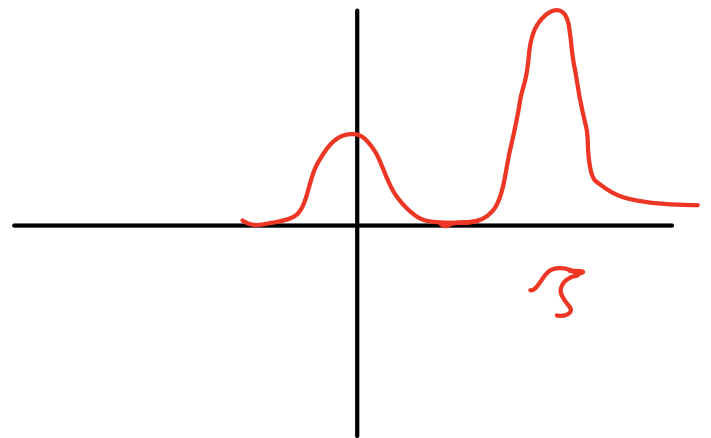
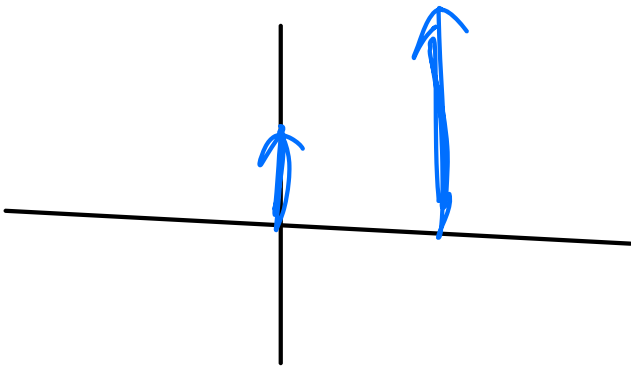
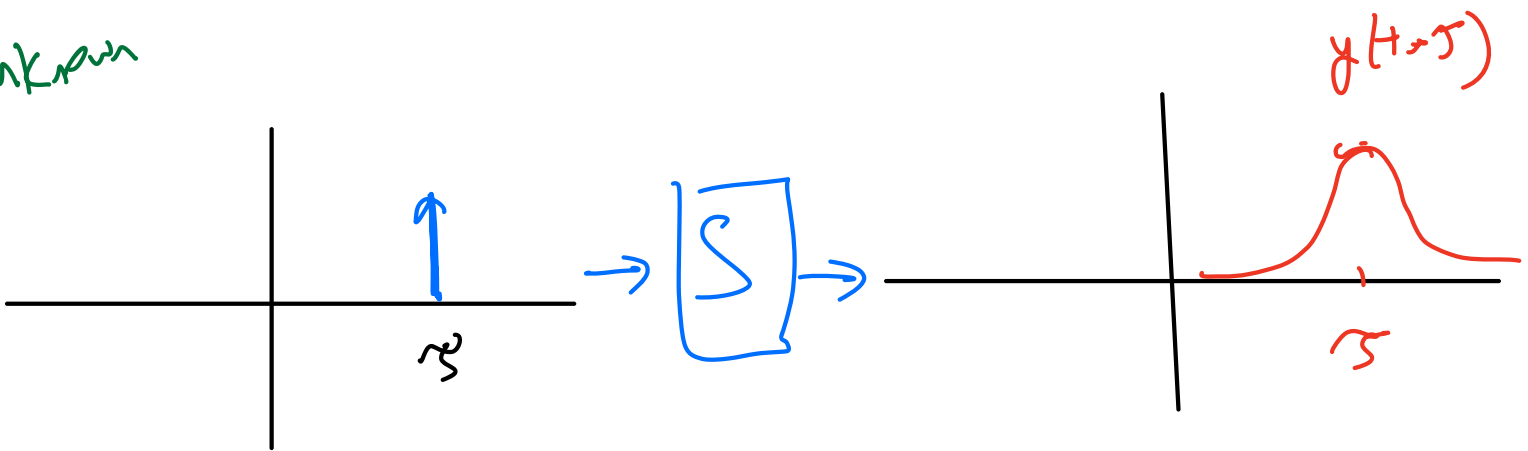


# Input Examples

# Outputs



Unknown



# Important Fact about the Impulse Response

---

**FACT:** If  $H$  is an LTI (linear time-invariant system) with impulse response

$$h(t) = H(\delta(t))$$

then we can calculate  $H(x(t))$  for ANY  $x(t)$  **IF** we know  $h(t)$ .

**This is a \*\*\*very important\*\*\* result.**