

EE102

Lecture 5

EE102 Announcements

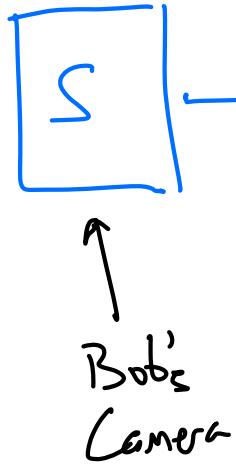
- **Syllabus link** is on BruinLearn
- Practice Midterm Released Early

Slide Credits: This lecture adapted from Prof. Jonathan Kao (UCLA) and recursive credits apply to Prof. Cabric (UCLA), Prof. Yu (Carnegie Mellon), Prof. Pauly (Stanford), and Prof. Fragouli (UCLA)

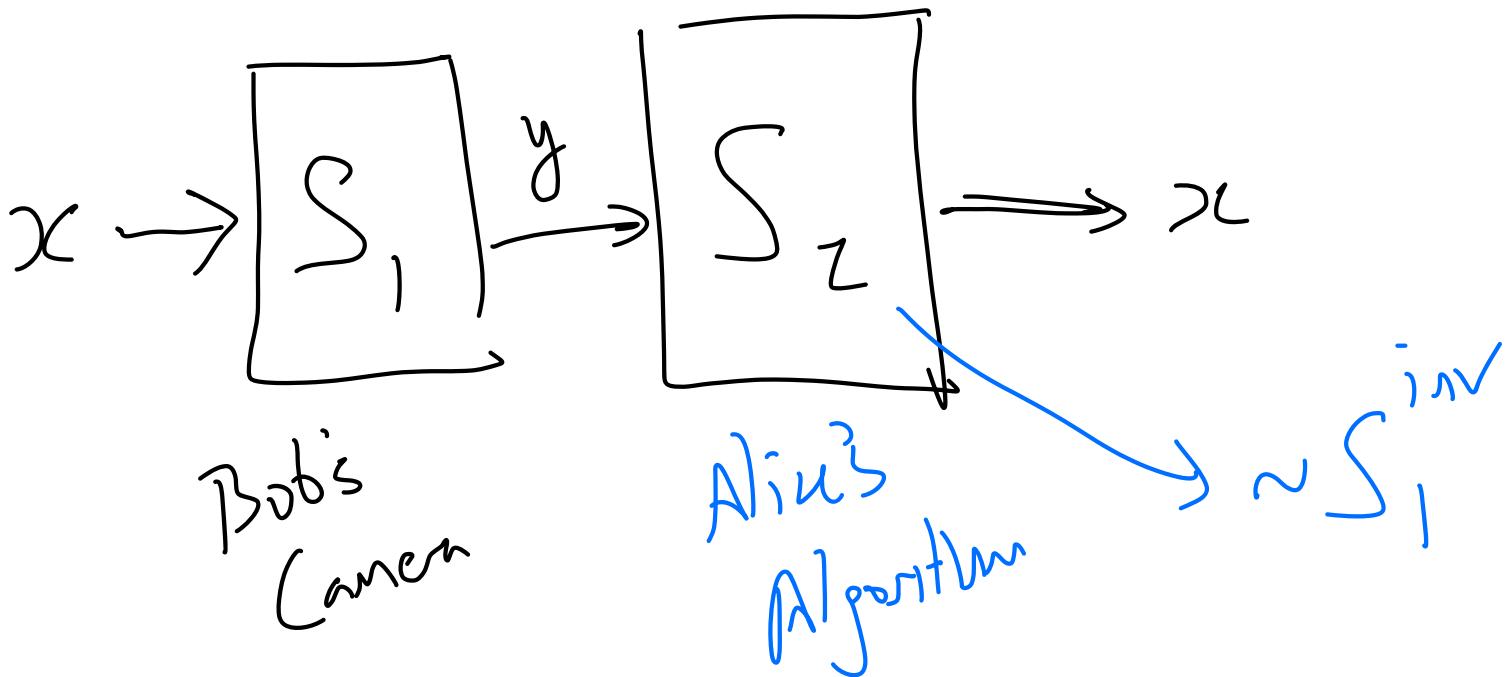
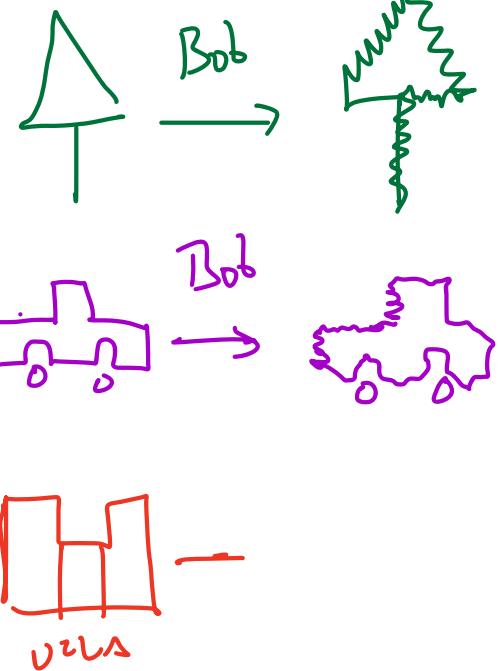
Alice $\xrightarrow{?}$ Bob.

Image Corp

U.S.
Image
Ideal



Captured
Image
Measurement



Impulse Response

System impulse response

This lecture introduces time-domain analysis of systems, including the impulse response. It also discusses linear time-invariant systems. Topics include:

- Impulse response definition
- Impulse response of LTI systems
- The impulse response as a sufficient characterization of an LTI system
- Impulse response and the convolution integral

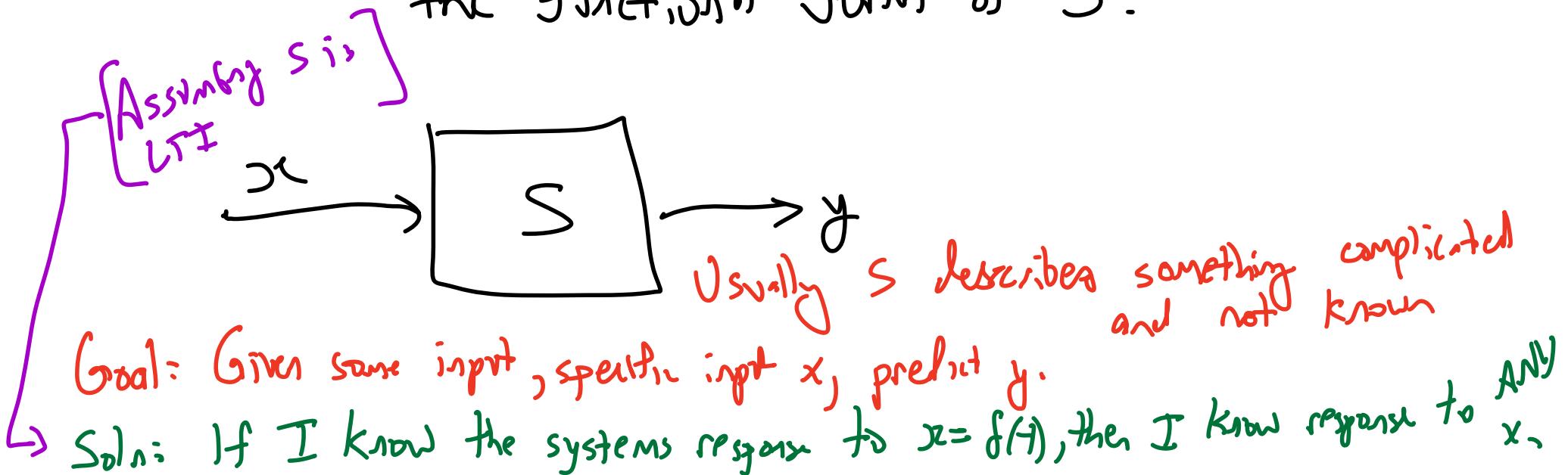
Impulse Response (cont.)

Why do we need the impulse response?

① E.g. $y(t) = [x(t)]^2$

This is a pset fct. NOT real life

- ② Real Life We do not know much, if anything, about the functional form of S .



Types of Responses $x \rightarrow [H] \rightarrow y$

Several systems are characterized by their functional response

- zero response: $H[0]$
- impulse response: $H[\delta(t)]$
- step response: $H[u(t)]$

CyV: Say H is linear, what is its zero response?

Ans: $H(ax) = a H(x) \quad \forall a, x.$ Suppose $a = 0$

$$H(0) = 0$$

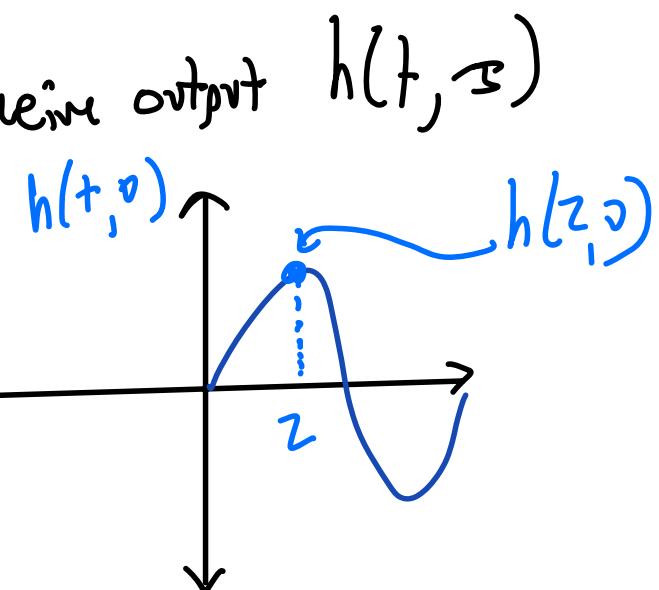
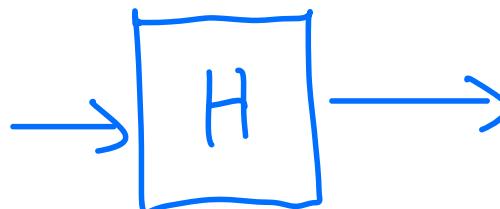
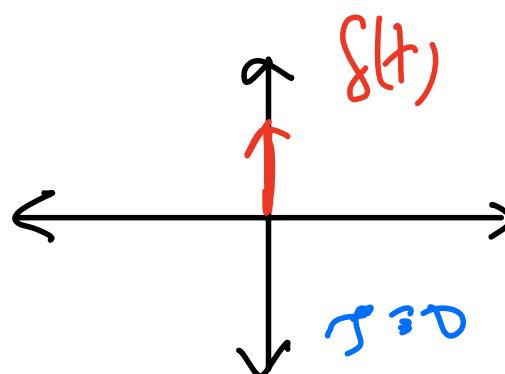
Impulse Response Definition

Impulse Response: Let H be a system and $y(t) = H[x(t)]$

The impulse response is

$$h(t, \tau) = H(\delta(t - \tau))$$

Intuition: Send impulse at time τ , receive output $h(t, \tau)$



$x(t)$ $y(t)$

input output

$h(t)$ → typically respond
for IR .

$$h(t, \tau) = H(\delta(t - \tau))$$

There are important things to be careful of when looking at this equation.

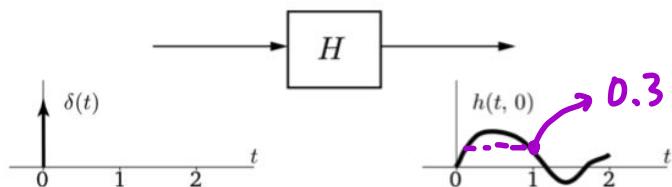
- The t on the left and right hand side of these equations are *not the same!*
- The t on the left hand side is the impulse response at a specific value of time.
- The t on the right hand side varies across all time.
- The output at the specific time t on the left will depend on the input at several times t on the right.

Notation on t

$$h(t, \tau) = H(\delta(t - \tau))$$

There are important things to be careful of when looking at this equation.

An example of these t 's not being the same is shown below. In this example, let $\tau = 0$.



It may be tempting to write:

$$h(1, 0) = H(\delta(1))$$

This is wrong.

- On the left, $\delta(1) = 0$. We know if H is linear, then $H(0) = 0$, implying that $h(1, 0) = 0$.
- But in general, the impulse response can be non-zero, i.e., $h(1, 0) \neq 0$ in the above diagram, if the impulse response produces some non-zero response.

Assume $\tau = 0$

$$h(t, 0) = H[\delta(t)]$$

DO NOT
cancel

Set $t=1$

$$\underline{h(1, 0) = H[\delta(1)]}$$

Non-zero
≈ 0.3

Zero.

Time invariant Impulse Response

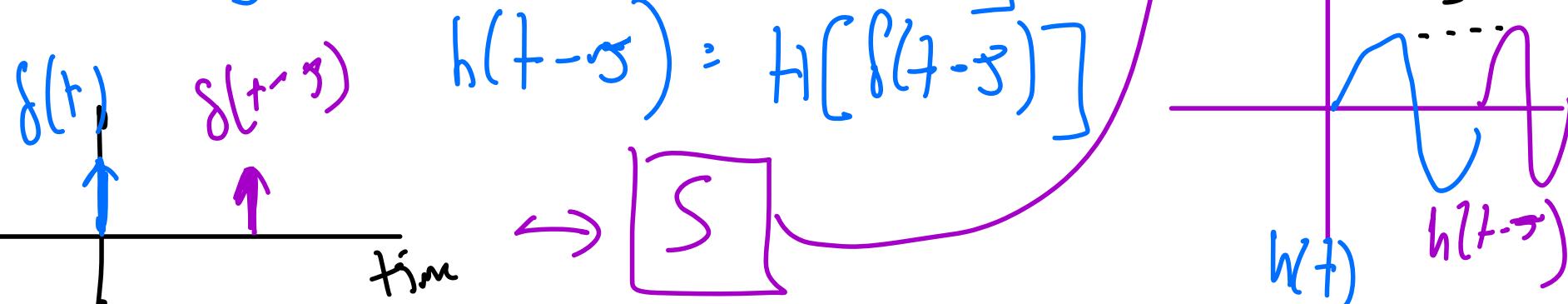
Time Invariant H

$$h(t, \tau) = H[\delta(t - \tau)]$$

$$h(t, 0) = H[\delta(t)]$$

Suppose H is time invariant. $H[\delta(t - \tau)] = h(t - \tau, 0) = h(t, \tau)$

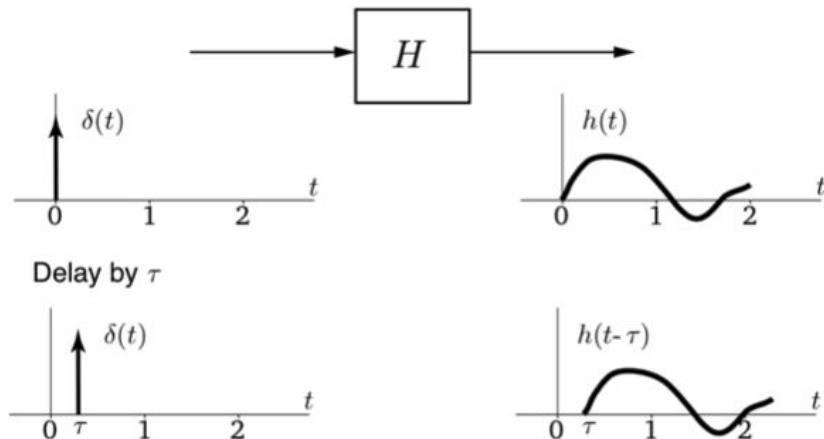
So I can simplify notation. $h(t) = H[\delta(t)]$



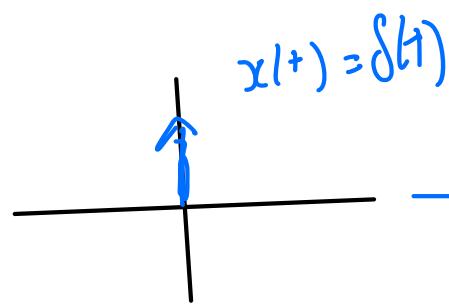
Time Invariant Impulse Response

Impulse response of a time-invariant system (cont.)

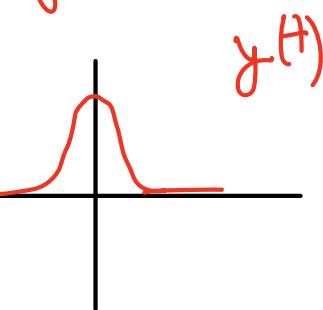
This property of the impulse response for a time-invariant system is drawn below:



Input Examples



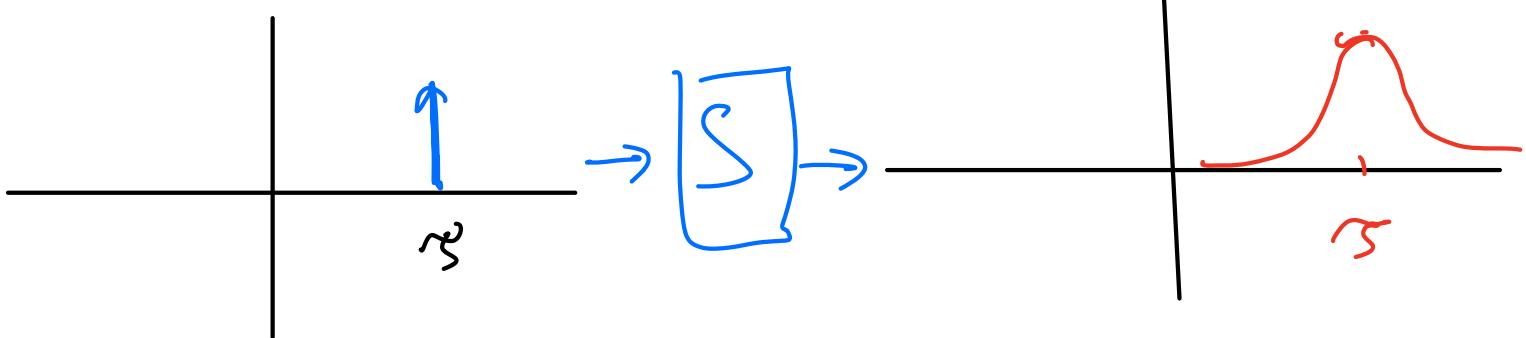
Outputs



Linear + Time Inv

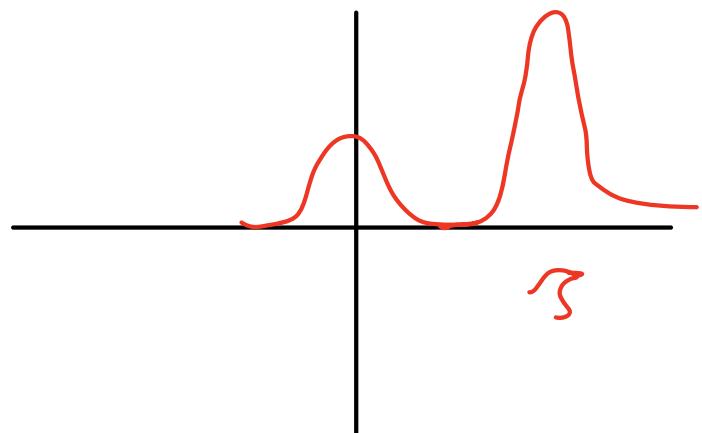
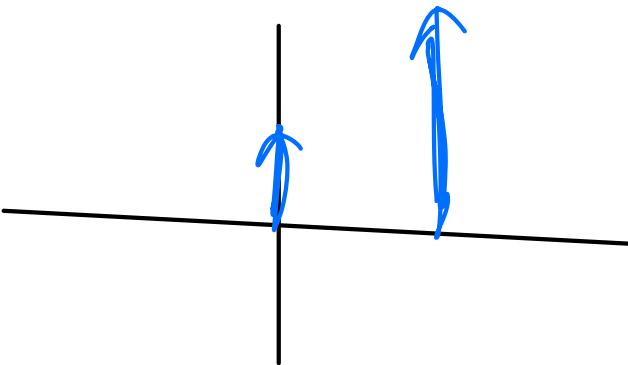
Known

Unknown

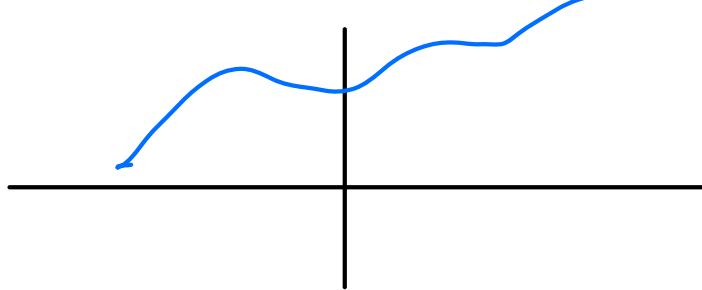
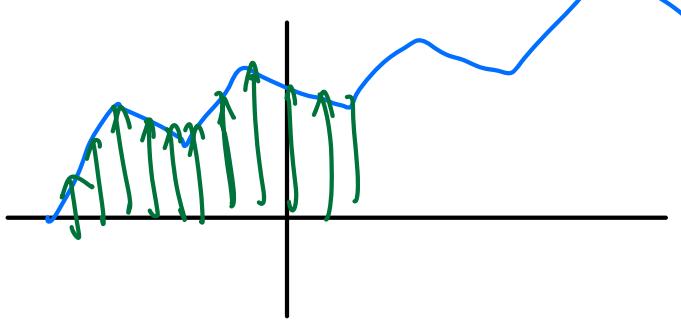


$y(t+\tau)$

τ



τ



Important Fact about the Impulse Response

FACT: If H is an LTI (linear time-invariant system) with impulse response

$$h(t) = H(\delta(t))$$

then we can calculate $H(x(t))$ for ANY $x(t)$ **IF** we know $h(t)$.

This is a *very important*** result.**