Carl Hildebrandt

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Education

2018 - Present Ph.D. candidate in Computer Science, University of Virginia, USA

Advisor: Dr. Sebastian Elbaum

2013 - 2016 B.Eng. in Computer Engineering, University of Pretoria, South Africa

Research Interests

Intersection of autonomous systems, and software analysis. Focusing on the safety of autonomous systems through the validation and verification of their software.

Experience

2020

2018

2018 - Present Research Assistant, Less Lab, University of Virginia

URL: less-lab-uva.github.io

2017 - 2018 Research Assistant, Nimbus Lab, University of Nebraska

URL: nimbus.unl.edu

Honours & Awards

IROS Best Paper Award on Safety, Security, and Recue Robotics: Fire-Aware Planning of Aerial Trajectories and Ignitions.

Distinguished Artifact Award: Feasible and Stressful Trajectory Generation for Mobile Robots

Publications & Talks

Conference Publications

Hildebrandt C, Elbaum S. World-in-the-Loop Simulation for Autonomous Systems Validation. In 2021 IEEE International Conference on Robotics and Automation (ICRA) 2021 May 30.

Hildebrandt C, Elbaum S, Bezzo N. Feasible and Stressful Trajectory Generation for Mobile Robots.

In 2020 ACM SIGSOFT International Symposium on Software Testing and Analysis Proceedings (ISSTA) 2020 July 22. - Distinguished Artifact Award

Hildebrandt C, Elbaum S, Bezzo N. Blending Kinematic and Software Models for Tighter Reachability Analysis. In 2020 IEEE/ACM 42nd International Conference on Software Engineering: New Ideas and Emerging Results (ICSE-NIER) 2020 July 6.

Beachly E, Detweiler C, Elbaum S, Duncan B, <u>Hildebrandt C</u>, Twidwell D, Allen C. *Fire-aware planning of aerial trajectories and ignitions*. In2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2018 Oct 1 (pp. 685-692). IEEE. - **Best Paper Award**

PAPERS	UNDER	Develo	PMFNT
LALLICO	CHULK	DEVELO	TIME

Hildebrandt C, M Stein, Elbaum S, Physical Coverage for Autonomous Systems.

PATENTS APPLICATIONS

Carl Hildebrandt, Jefferson Griscavage, Victor Aquino, Melony Bennis, and Tien Comlekoglu, Vuetech Health Innovations LLC, "Systems and Methods for Safety, Security and Well-Being of Individuals", Patent US63066296

TALKS

2021

2020

2014

Carl Hildebrandt "Feasible and Stressful Trajectory Generation for Mobile Robots", International Conference on Software Engineering, July 7 2020

Carl Hildebrandt "Blending Kinematic and Software Models for Tighter Reachability Analysis", International Symposium on Software Testing and Analysis, July 21, 2020

Teaching

Lab Designer and Guest Lecturer

Robotics for Software Engineers, The University of Virginia, Spring 2021

Lab Designer and Teaching Assistant

Robotics for Software Engineers, The University of Virginia, Spring 2020

2016 Head Teaching Assistant

Data Structures and Algorithms in Java, The University of Pretoria, First Semester 2016

2015 Head Teaching Assistant

Program Design in C++, The University of Pretoria, Second Semester 2015

2015 Teaching Assistant

Data Structures and Algorithms in Java, The University of Pretoria, First Semester 2015

Teaching Assistant

Introduction to Programming in C, The University of Pretoria, Second Semester 2014

Achievements

National Club Field Hockey Champions - UVA

2017 Half Iron Man

2017 Comrades Ultra Marathon 2016 Summited Kilimanjaro

National u18B Hockey Team