Carl Hildebrandt

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Education

2018 - Present Ph.D. candidate in Computer Science, University of Virginia, USA

Advisor: Dr. Sebastian Elbaum

2013 – 2016 B.Eng. in Computer Engineering, University of Pretoria, South Africa

Research Interests

Intersection of autonomous systems, and software analysis. Focusing on the safety of autonomous systems through the validation and verification of their software.

Experience

2020

2018 - Present Research Assistant, Less Lab, University of Virginia

URL: less-lab-uva.github.io

2017 - 2018 Research Assistant, Nimbus Lab, University of Nebraska

URL: nimbus.unl.edu

Honours & Awards

IROS Best Paper Award on Safety, Security, and Recue Robotics: Fire-Aware Planning of Aerial Trajectories and Ignitions.

Distinguished Artifact Award: Feasible and Stressful Trajectory Generation for Mobile Robots

Publications & Talks

Conference Publications

Hildebrandt C, Elbaum S, Bezzo N. Feasible and Stressful Trajectory Generation for Mobile Robots.

In2020 ACM SIGSOFT International Symposium on Software Testing and Analysis Proceedings
(ISSTA) 2020 July 22. - Distinguished Artifact Award

Hildebrandt C, Elbaum S, Bezzo N. Blending Kinematic and Software Models for Tighter Reachability Analysis. In2020 IEEE/ACM 42nd International Conference on Software Engineering: New Ideas and Emerging Results (ICSE-NIER) 2020 July 6.

Beachly E, Detweiler C, Elbaum S, Duncan B, <u>Hildebrandt C</u>, Twidwell D, Allen C. *Fire-aware planning of aerial trajectories and ignitions*. In2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2018 Oct 1 (pp. 685-692). IEEE. - **Best Paper Award**

	Papers Under Development
2020	Hildebrandt C, Elbaum S, Mixed Reality Testing.
	Patents Applications
2020	Carl Hildebrandt , Jefferson Griscavage, Victor Aquino, Melony Bennis, and Tien Comlekoglu, Vuetech Health Innovations LLC, "Systems and Methods for Safety, Security and Well-Being of Individuals", Patent US63066296
	Talks
2020	Carl Hildebrandt "Feasible and Stressful Trajectory Generation for Mobile Robots", International Conference on Software Engineering, July 7 2020
2020	Carl Hildebrandt "Blending Kinematic and Software Models for Tighter Reachability Analysis", International Symposium on Software Testing and Analysis, July 21, 2020
	Teaching
2020	Lab Designer and Teaching Assistant Robotics for Software Engineers, The University of Virginia, Spring 2020
2016	Head Teaching Assistant Data Structures and Algorithms in Java, The University of Pretoria, First Semester 2016
2015	Head Teaching Assistant Program Design in C++, The University of Pretoria, Second Semester 2015
2015	Teaching Assistant Data Structures and Algorithms in Java, The University of Pretoria, First Semester 2015
2014	Teaching Assistant Introduction to Programming in C, The University of Pretoria, Second Semester 2014
	Achievements
2019	National Club Field Hockey Champions - UVA
2017	Half Iron Man

Comrades Ultra Marathon Summited Kilimanjaro

National u18B Hockey Team

2016

2012