

Physics::OverlapSpherePlane

Rigidbody::UpdateBody

Transform::TranslateGlobal

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graph LR; A[Physics::OverlapSpherePlane] --> D[Transform::TranslateGlobal]; B[Rigidbody::UpdateBody] --> D;
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The diagram illustrates a dependency or call relationship. Two source functions, 'Physics::OverlapSpherePlane' and 'Rigidbody::UpdateBody', are shown on the left. Both have blue arrows pointing to a single target function, 'Transform::TranslateGlobal', which is highlighted with a gray background. The arrows originate from the right side of the source boxes and point towards the left side of the target box.