

**EE1206 Linear Systems and Signal Processing
Exam 2**

Time: 120 min
Maximum score:
30 points

Instructions

- This is a closed book closed notes exam. No phones, calculators, or laptops can be used during the exam. The notation used is the same as from class.
- There are 6 questions for 6 marks each. The maximum score you can obtain is 30 points (and not 36 marks)
- There are no negative marks. Use a blue or a black pen to answer the questions.

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1. (6 pts) (a) Let $X(t)$ be a wide sense stationary random process with autocorrelation $R_{xx}(\tau)$. Let $Y(t) = aX(ct)$ for some constants $a, c \neq 0$. Is Y WSS (and if so, what is its autocorrelation function) ?
- (b) Let $w(t)$ be a (deterministic, non random) signal, and C a random variable. Identify the conditions on C and $w(t)$ such that $X(t) = Cw(t)$ is WSS.

2. (6 pts) Let $X(t)$ be a WSS random process with autocorrelation $R_{xx}(\tau)$ and PSD $S_{xx}(s)$.

(a) Explain why $R_{xx}(\tau) = 2 \int_0^\infty S_{xx}(s) \cos 2\pi s \tau ds$.

(b) Show that

$$R_{xx}(0) - R_{xx}(\tau) \geq \frac{1}{4^n} (R_{xx}(0) - R_{xx}(2^n \tau)).$$

You may find the inequality $1 - \cos \theta \geq (1 - \cos 2\theta)/4$ helpful.

- (c) Let $Y(t)$ be the output of an LTI system with input process $X(t)$. Suppose it is known that the PSDs S_{xx} of the input and S_{yy} of the output satisfy $S_{xx}(s)S_{yy}(s) = 0$ for all s . What can you say about the output process $Y(t)$?
3. (6 pts) (a) A randomly phased sinusoid $X(t) = \cos(2\pi ft + \Theta)$, with Θ uniformly distributed in $(0, 2\pi)$ is given as input to an LTI system with frequency response $H(s)$ (assume the LTI system has a real impulse response, as usual). What is the autocorrelation function of the output of this filter?
- (b) A discrete-time white noise random process is given as input to an LTI system with impulse response h . We know that $h(0) = 1$, and that all impulse response values $h(m)$ are nonzero. Can the output power of the filter ever be less than the input power? Justify with a proof or counterexample.
4. (6 pts) A zero mean discrete time WSS random process $Y(n)$ with PSD $S_{yy}(s) = 2 - 2\cos(2\pi s)$ is corrupted by zero mean white noise $Z(n)$ with power $E(Z(0)^2) = 1$; so that we have measurements of $X(n) = Y(n) + Z(n)$.
- (a) What is the frequency response of the optimal Wiener filter to recover $Y(t)$? Plot this frequency response as a function of the frequency s , for $-1/2 \leq s \leq 1/2$. Is this a low-pass or a high-pass filter ?
- (b) Does the power of the estimate \hat{Y} match the power in Y , i.e do we have $E(Y(0)^2) = E(\hat{Y}(0)^2)$?
5. (6 pts) Let $f(t)$ be a bandlimited signal whose Fourier transform satisfies $|\mathcal{F}f(s)| = 0$ for $|s| \geq 1$. According to the sampling theorem, one has to sample $f(t)$ with $\text{III}_{1/2}(t)$ to reproduce the signal without aliasing.

You try to test this out in the lab, but there is something wrong with the ideal sampler — it can *only* sample using $\text{III}_1(t)$. This will inevitably cause aliasing, but you think you can devise a scheme to somehow reconstruct $f(t)$ without aliasing.

This problem explores how this can be done by using this faulty sampler and some filter $h(t)$.

- (a) Let $h(t) = -1/(\pi it)$. If $g(t) = (f * h)(t)$, express $G(s)$ in terms of $F(s)$ *only*. *Hint: Consider the cases $s = 0$, $s > 0$ and $s < 0$.*
 - (b) Suppose you sample $f(t)$ with $\text{III}_1(t)$ to yield $y(t)$. For the case of $0 < s < 1$, express $Y(s)$ in terms of $F(s)$ and $F(s - 1)$ *only*.
 - (c) Suppose you sample $g(t)$ with $\text{III}_1(t)$ to yield $x(t)$. For the case of $0 < s < 1$, express $X(s)$ in terms of $F(s)$ and $F(s - 1)$ *only*.
 - (d) Using the two equations you have from parts (b) and (c), show how you might reconstruct $f(t)$ without aliasing.
6. (6 pts) Earlier in the course we discussed the uncertainty principle for continuous time signals, the main idea being that time width and frequency width are inversely related. A similar relationship holds for discrete signals, as we will see in this problem. Let f be an N -length vector and $F = \mathcal{F}f$ be its DFT. Let $\phi(f)$ indicate the number of nonzero coordinates in f , and similarly let $\phi(\mathcal{F}f)$ be the number of non-zero coordinates in $F = \mathcal{F}f$. Then the discrete uncertainty principle states that

$$\phi(f)\phi(\mathcal{F}f) \geq N.$$

In other words, the time width ($\phi(f)$) and frequency width ($\phi(\mathcal{F}f)$) are inversely related.

Below is an outline of the proof of this uncertainty principle. Complete the proof by briefly justifying the statements (a)-(f) in the proof.

Proof: Let the vector s denote the sign of f :

$$s[n] := \begin{cases} 1 & \text{if } f[n] > 0, \\ -1 & \text{if } f[n] < 0, \\ 0 & \text{if } f[n] = 0, \end{cases}$$

and let (f, s) denote the dot product of the vectors f and s . Assume that $f \neq 0$. Defining $s[n]$ gives us the advantage of expressing $|f[n]|$ as $|f[n]| = f[n]s[n]$.

Now

$$\begin{aligned} \max_m |F[m]| &\stackrel{(a)}{\leq} \sum_{n=0}^{N-1} |f[n]| \stackrel{(b)}{=} (f, s) \\ &\stackrel{(c)}{\leq} (f, f)^{1/2} (s, s)^{1/2} \stackrel{(d)}{=} \frac{1}{\sqrt{N}} (F, F)^{1/2} (s, s)^{1/2} \\ &\stackrel{(e)}{=} \frac{1}{\sqrt{N}} (F, F)^{1/2} \phi(f)^{1/2} \stackrel{(f)}{\leq} \frac{\max_m |F[m]|}{\sqrt{N}} \phi(F)^{1/2} \phi(f)^{1/2}. \end{aligned}$$

Canceling out $\max_m |F[m]|$ on both sides, we are left with the desired inequality

$$\phi(f)\phi(F) \geq N.$$