Chapter 8: Main Memory

Chapter 8: Memory Management

- Background
- Swapping
- Contiguous Memory Allocation
- Paging
- Structure of the Page Table
- Segmentation
- Example: The Intel Pentium

Objectives

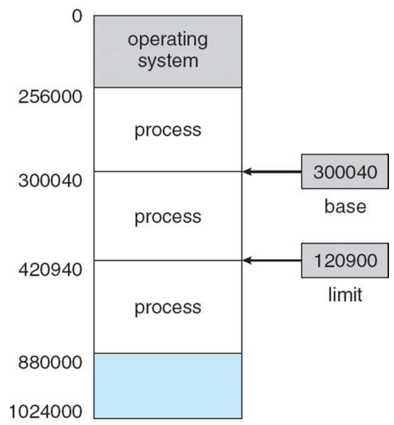
- To provide a detailed description of various ways of organizing memory hardware
- To discuss various memory-management techniques, including paging and segmentation
- To provide a detailed description of the Intel Pentium, which supports both pure segmentation and segmentation with paging

Background

- Program must be brought (from disk) into memory and placed within a process for it to be run
- Main memory and registers are only storage CPU can access directly
- Register access in one CPU clock (or less)
- Main memory can take many cycles
- **Cache** sits between main memory and CPU registers
- Protection of memory required to ensure correct operation

Base and Limit Registers

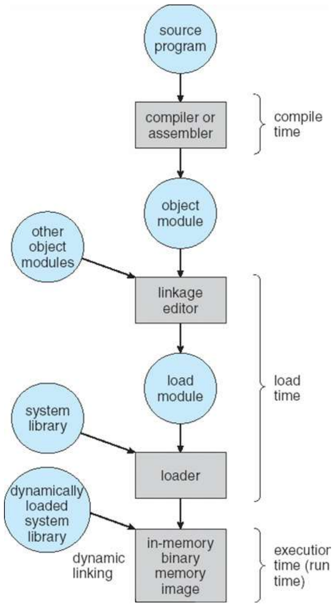
- A pair of **base** and **limit** registers define the logical address space



Binding of Instructions and Data to Memory

- Address binding of instructions and data to memory addresses can happen at three different stages
  - **Compile time**: If memory location known a priori, **absolute code** can be generated; must recompile code if starting location changes
  - **Load time**: Must generate **relocatable code** if memory location is not known at compile time
  - **Execution time**: Binding delayed until run time if the process can be moved during its execution from one memory segment to another. Need hardware support for address maps (e.g., base and limit registers)

Multistep Processing of a User Program



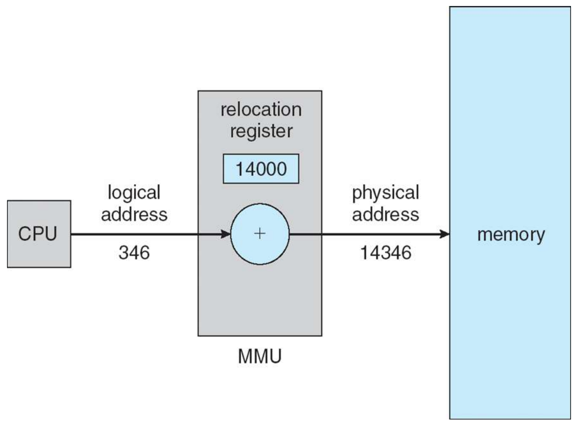
Logical vs. Physical Address Space

- The concept of a logical address space that is bound to a separate **physical address space** is central to proper memory management
  - **Logical address** – generated by the CPU; also referred to as **virtual address**
  - **Physical address** – address seen by the memory unit
- Logical and physical addresses are the same in compile-time and load-time address-binding schemes; logical (virtual) and physical addresses differ in execution-time address-binding scheme

Memory-Management Unit (MMU)

- Hardware device that maps virtual to physical address
- In MMU scheme, the value in the relocation register is added to every address generated by a user process at the time it is sent to memory
- The user program deals with *logical* addresses; it never sees the *real* physical addresses

Dynamic relocation using a relocation register



Dynamic Loading

- Routine is not loaded until it is called
- Better memory-space utilization; unused routine is never loaded
- Useful when large amounts of code are needed to handle infrequently occurring cases
- No special support from the operating system is required implemented through program design

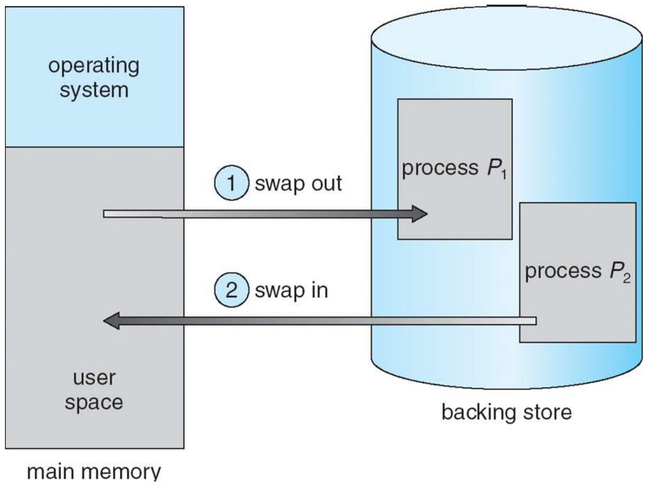
Dynamic Linking

- Linking postponed until execution time
- Small piece of code, *stub*, used to locate the appropriate memory-resident library routine
- Stub replaces itself with the address of the routine, and executes the routine
- Operating system needed to check if routine is in processes' memory address
- Dynamic linking is particularly useful for libraries
- System also known as **shared libraries**

Swapping

- A process can be swapped temporarily out of memory to a backing store, and then brought back into memory for continued execution
- **Backing store** – fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images
- **Roll out, roll in** – swapping variant used for priority-based scheduling algorithms; lower-priority process is swapped out so higher-priority process can be loaded and executed
- Major part of swap time is transfer time; total transfer time is directly proportional to the amount of memory swapped
- Modified versions of swapping are found on many systems (i.e., UNIX, Linux, and Windows)
- System maintains a **ready queue** of ready-to-run processes which have memory images on disk

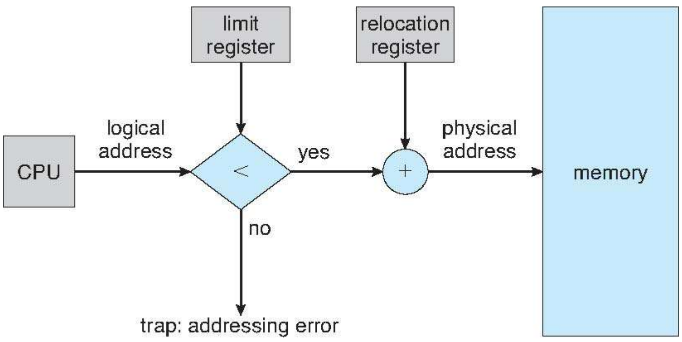
Schematic View of Swapping



Contiguous Allocation

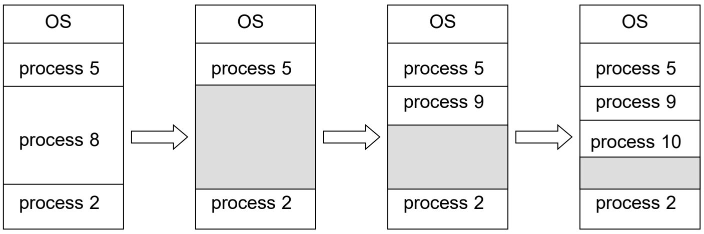
- Main memory usually into two partitions:
  - Resident operating system, usually held in low memory with interrupt vector
  - User processes then held in high memory
- Relocation registers used to protect user processes from each other, and from changing operating-system code and data
  - Base register contains value of smallest physical address
  - Limit register contains range of logical addresses – each logical address must be less than the limit register
  - MMU maps logical address *dynamically*

Hardware Support for Relocation and Limit Registers



Contiguous Allocation (Cont)

- Multiple-partition allocation
  - Hole – block of available memory; holes of various size are scattered throughout memory
  - When a process arrives, it is allocated memory from a hole large enough to accommodate it
  - Operating system maintains information about:
    a) allocated partitions   b) free partitions (hole)



Dynamic Storage-Allocation Problem

How to satisfy a request of size *n* from a list of free holes

- **First-fit**: Allocate the *first* hole that is big enough
- **Best-fit**: Allocate the *smallest* hole that is big enough; must search entire list, unless ordered by size
  - Produces the smallest leftover hole
- **Worst-fit**: Allocate the *largest* hole; must also search entire list
  - Produces the largest leftover hole

First-fit and best-fit better than worst-fit in terms of speed and storage utilization

Fragmentation

- **External Fragmentation** – total memory space exists to satisfy a request, but it is not contiguous
- **Internal Fragmentation** – allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used
- Reduce external fragmentation by **compaction**
  - Shuffle memory contents to place all free memory together in one large block
  - Compaction is possible *only* if relocation is dynamic, and is done at execution time
  - I/O problem
    - Latch job in memory while it is involved in I/O
    - Do I/O only into OS buffers

Paging

- Logical address space of a process can be noncontiguous; process is allocated physical memory whenever the latter is available
- Divide physical memory into fixed-sized blocks called **frames** (size is power of 2, between 512 bytes and 8,192 bytes)
- Divide logical memory into blocks of same size called **pages**
- Keep track of all free frames
- To run a program of size ***n*** pages, need to find *n* free frames and load program
- Set up a page table to translate logical to physical addresses
- Internal fragmentation

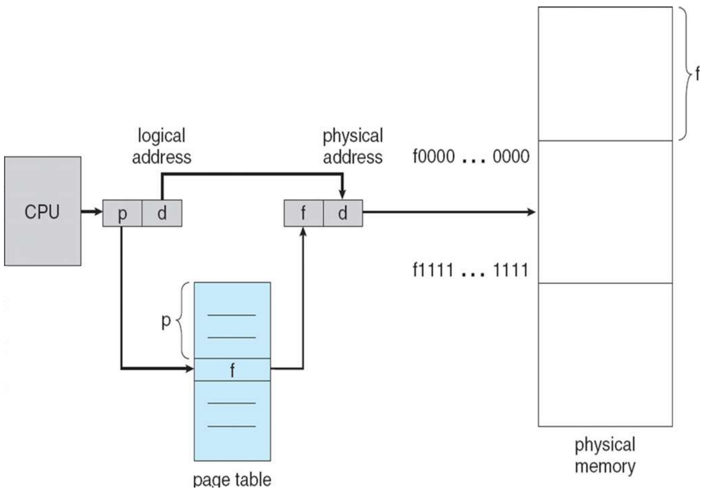
Address Translation Scheme

- Address generated by CPU is divided into:
  - **Page number (*p*)** – used as an index into a *page table* which contains base address of each page in physical memory
  - **Page offset (d)** – combined with base address to define the physical memory address that is sent to the memory unit

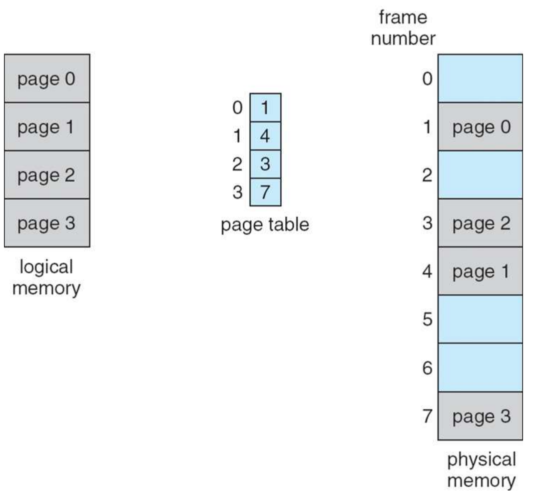
page number	page offset
p	*d*
m - n	*n*

  - For given logical address space 2^m *and page size* 2^n

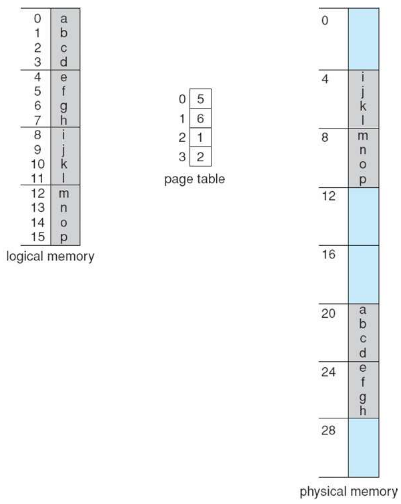
Paging Hardware



Paging Model of Logical and Physical Memory

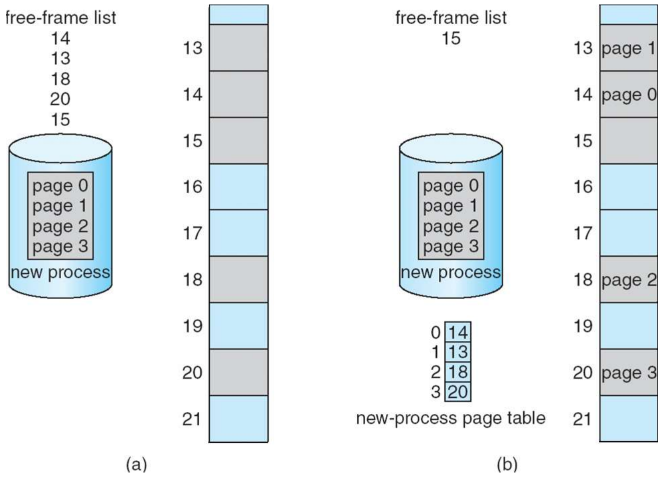


Paging Example



32-byte memory and 4-byte pages

Free Frames



Before allocation

After allocation

Implementation of Page Table

- Page table is kept in main memory
- **Page-table base register (PTBR)** points to the page table
- **Page-table length register (PRLR)** indicates size of the page table
- In this scheme every data/instruction access requires two memory accesses. One for the page table and one for the data/instruction.
- The two memory access problem can be solved by the use of a special fast-lookup hardware cache called **associative memory** or **translation look-aside buffers (TLBs)**
- Some TLBs store **address-space identifiers (ASIDs)** in each TLB entry – uniquely identifies each process to provide address-space protection for that process

Associative Memory

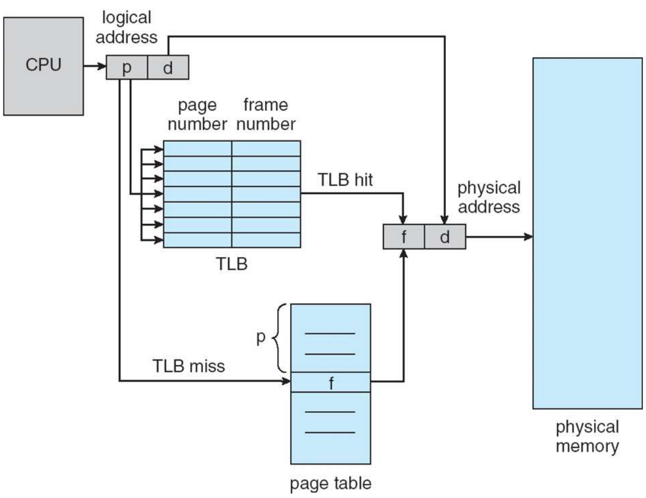
- Associative memory – parallel search

Page #	Frame #

Address translation (p, d)

- If p is in associative register, get frame # out
- Otherwise get frame # from page table in memory

Paging Hardware With TLB



Effective Access Time

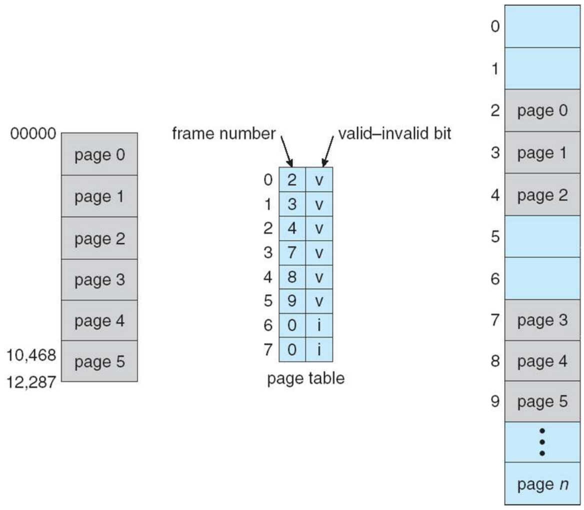
- Associative Lookup = ε time unit
- Assume memory cycle time is 1 microsecond
- Hit ratio – percentage of times that a page number is found in the associative registers; ratio related to number of associative registers
- Hit ratio = α
- **Effective Access Time** (EAT)

$$\begin{aligned} EAT &= (1 + \varepsilon)\,\alpha + (2 + \varepsilon)(1 - \alpha) \\ &= 2 + \varepsilon - \alpha \end{aligned}$$

Memory Protection

- Memory protection implemented by associating protection bit with each frame
- **Valid-invalid** bit attached to each entry in the page table:
  - "valid" indicates that the associated page is in the process' logical address space, and is thus a legal page
  - "invalid" indicates that the page is not in the process' logical address space

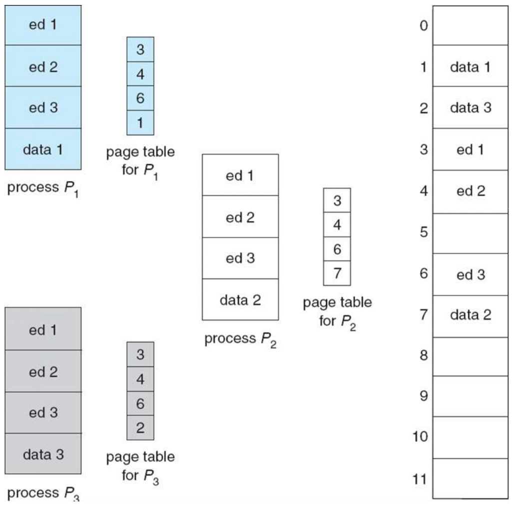
Valid (v) or Invalid (i) Bit In A Page Table



Shared Pages

- **Shared code**
  - One copy of read-only (reentrant) code shared among processes (i.e., text editors, compilers, window systems).
  - Shared code must appear in same location in the logical address space of all processes
- **Private code and data**
  - Each process keeps a separate copy of the code and data
  - The pages for the private code and data can appear anywhere in the logical address space

Shared Pages Example



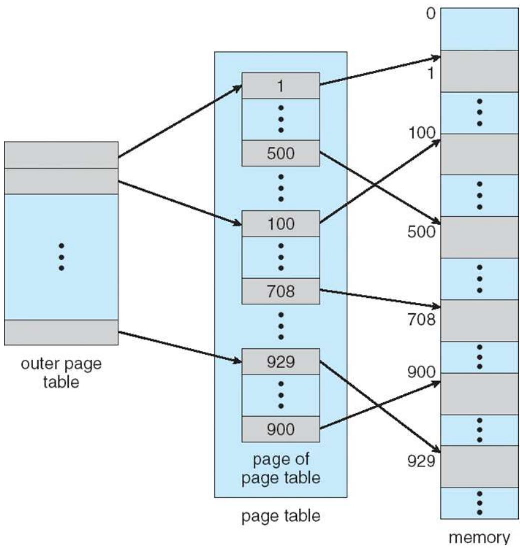
Structure of the Page Table

- Hierarchical Paging
- Hashed Page Tables
- Inverted Page Tables

Hierarchical Page Tables

- Break up the logical address space into multiple page tables
- A simple technique is a two-level page table

Two-Level Page-Table Scheme



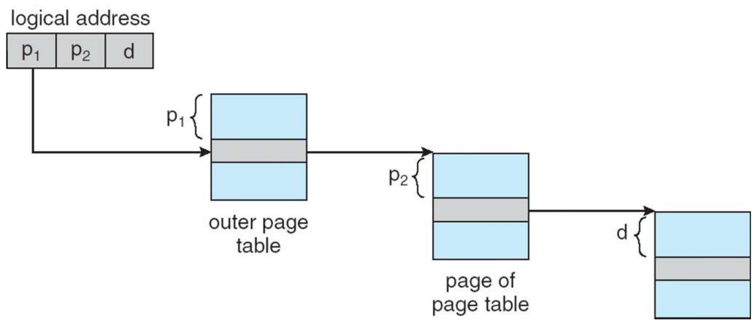
Two-Level Paging Example

- A logical address (on 32-bit machine with 1K page size) is divided into:
  - a page number consisting of 22 bits
  - a page offset consisting of 10 bits
- Since the page table is paged, the page number is further divided into:
  - a 12-bit page number
  - a 10-bit page offset
- Thus, a logical address is as follows:

page number		page offset
p_i	p_2	d
12	10	10

where p_i is an index into the outer page table, and p_2 is the displacement within the page of the outer page table

Address-Translation Scheme



Three-level Paging Scheme

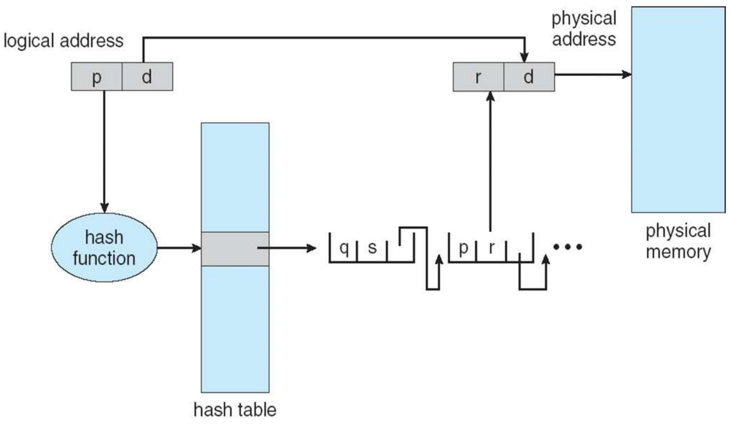
outer page	inner page	offset
p_1	p_2	d
42	10	12

2nd outer page	outer page	inner page	offset
p_1	p_2	p_3	d
32	10	10	12

Hashed Page Tables

- Common in address spaces > 32 bits
- The virtual page number is hashed into a page table
  - This page table contains a chain of elements hashing to the same location
- Virtual page numbers are compared in this chain searching for a match
  - If a match is found, the corresponding physical frame is extracted

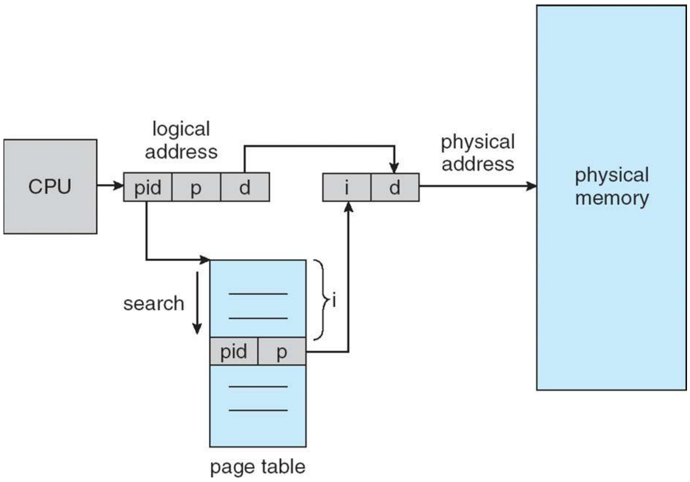
Hashed Page Table



Inverted Page Table

- One entry for each real page of memory
- Entry consists of the virtual address of the page stored in that real memory location, with information about the process that owns that page
- Decreases memory needed to store each page table, but increases time needed to search the table when a page reference occurs
- Use hash table to limit the search to one — or at most a few — page-table entries

Inverted Page Table Architecture

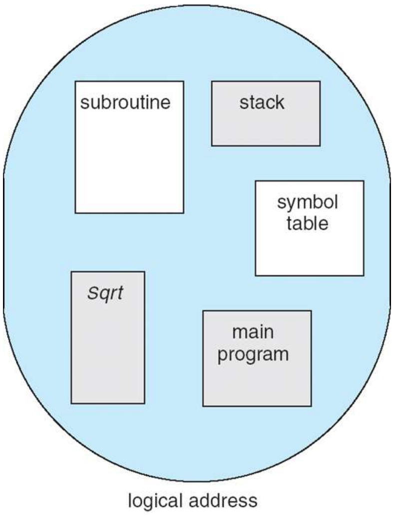


Segmentation

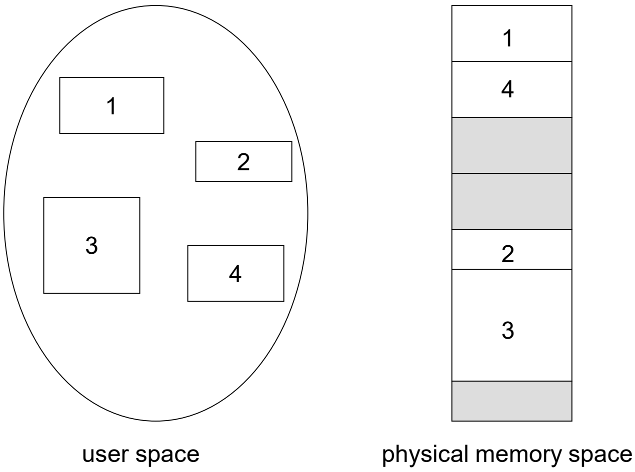
- Memory-management scheme that supports user view of memory
- A program is a collection of segments
  - A segment is a logical unit such as:

    main program
    procedure
    function
    method
    object
    local variables, global variables
    common block
    stack
    symbol table
    arrays

User’s View of a Program



Logical View of Segmentation



Segmentation Architecture

- Logical address consists of a two tuple:

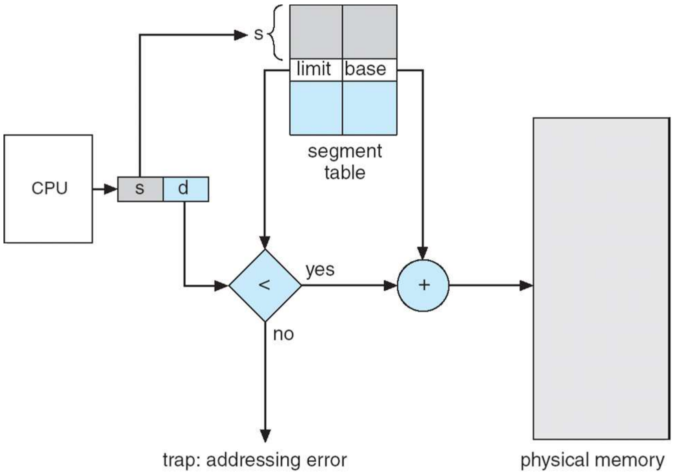
  <segment-number, offset>,
- **Segment table** – maps two-dimensional physical addresses; each table entry has:
  - **base** – contains the starting physical address where the segments reside in memory
  - **limit** – specifies the length of the segment
- **Segment-table base register (STBR)** points to the segment table's location in memory
- **Segment-table length register (STLR)** indicates number of segments used by a program;

  segment number ***s*** is legal if ***s*** < **STLR**

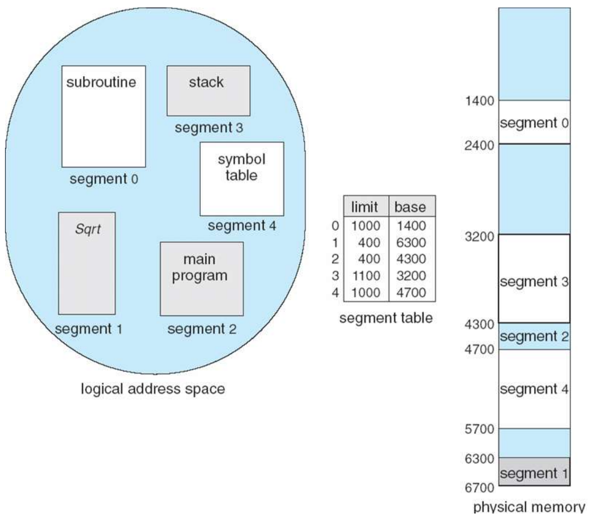
Segmentation Architecture (Cont.)

- Protection
  - With each entry in segment table associate:
    - validation bit = 0 $\Rightarrow$ illegal segment
    - read/write/execute privileges
- Protection bits associated with segments; code sharing occurs at segment level
- Since segments vary in length, memory allocation is a dynamic storage-allocation problem
- A segmentation example is shown in the following diagram

Segmentation Hardware



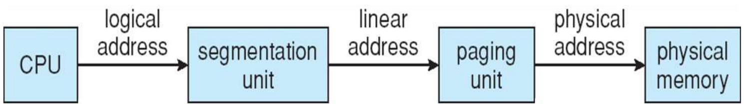
Example of Segmentation

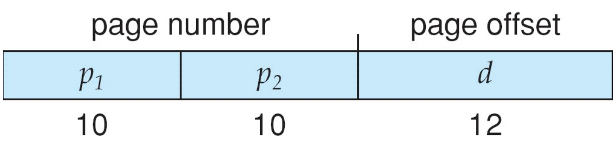


Example: The Intel Pentium

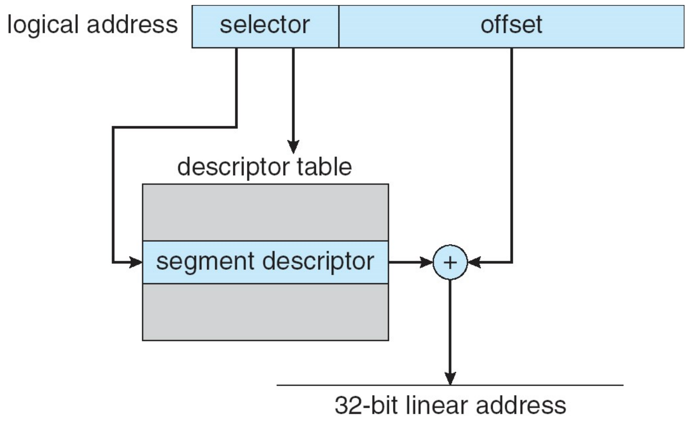
- Supports both segmentation and segmentation with paging
- CPU generates logical address
  - Given to segmentation unit
    - Which produces linear addresses
  - Linear address given to paging unit
    - Which generates physical address in main memory
    - Paging units form equivalent of MMU

Logical to Physical Address Translation in Pentium

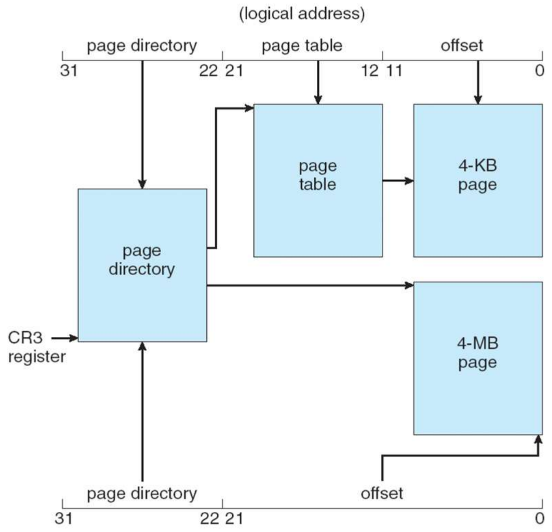




Intel Pentium Segmentation



Pentium Paging Architecture

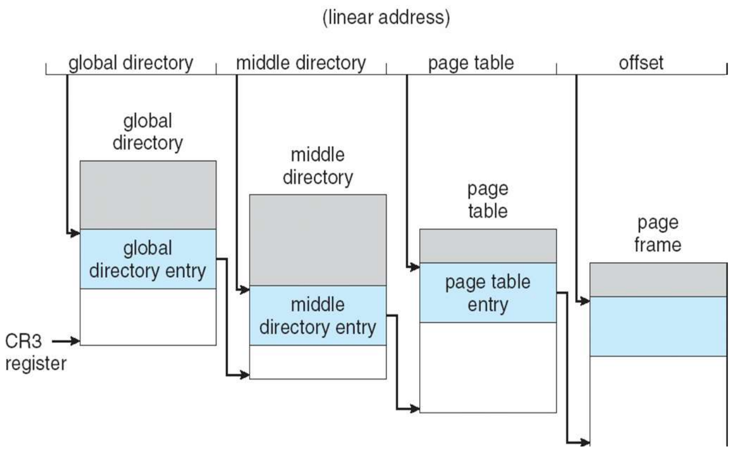


Linear Address in Linux

Broken into four parts:

global directory	middle directory	page table	offset

Three-level Paging in Linux



End of Chapter 8

Chapter 9: Virtual Memory

Chapter 9: Virtual Memory

- Background
- Demand Paging
- Copy-on-Write
- Page Replacement
- Allocation of Frames
- Thrashing
- Memory-Mapped Files
- Allocating Kernel Memory
- Other Considerations
- Operating-System Examples

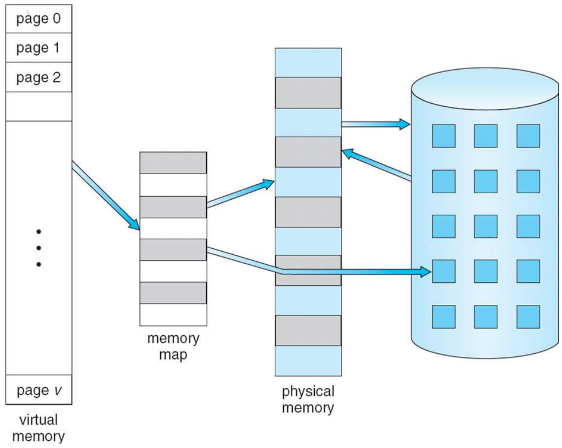
Objectives

- To describe the benefits of a virtual memory system
- To explain the concepts of demand paging, page-replacement algorithms, and allocation of page frames
- To discuss the principle of the working-set model

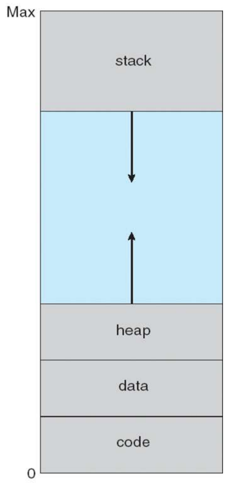
Background

- **Virtual memory** – separation of user logical memory from physical memory.
  - Only part of the program needs to be in memory for execution
  - Logical address space can therefore be much larger than physical address space
  - Allows address spaces to be shared by several processes
  - Allows for more efficient process creation
- Virtual memory can be implemented via:
  - Demand paging
  - Demand segmentation

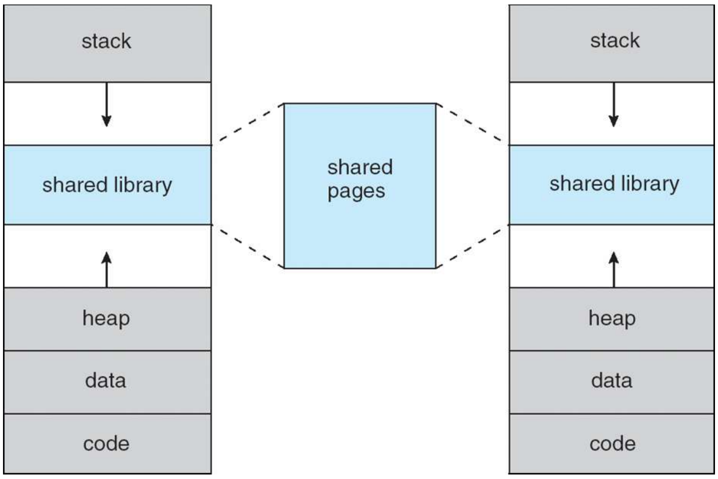
Virtual Memory That is Larger Than Physical Memory



Virtual-address Space



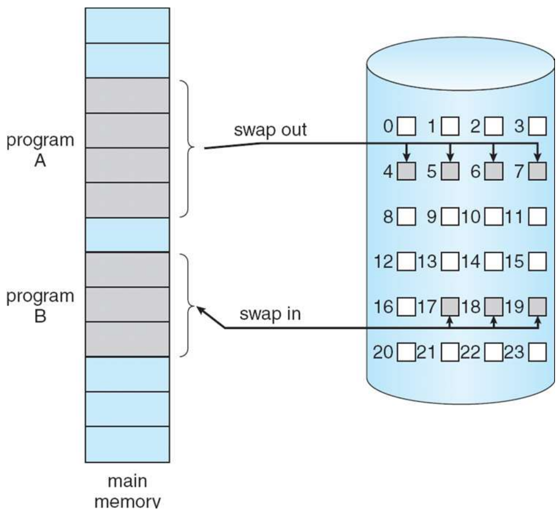
Shared Library Using Virtual Memory



Demand Paging

- Bring a page into memory only when it is needed
  - Less I/O needed
  - Less memory needed
  - Faster response
  - More users
- Page is needed $\Rightarrow$ reference to it
  - invalid reference $\Rightarrow$ abort
  - not-in-memory $\Rightarrow$ bring to memory
- **Lazy swapper** – never swaps a page into memory unless page will be needed
  - Swapper that deals with pages is a **pager**

Transfer of a Paged Memory to Contiguous Disk Space



Valid-Invalid Bit

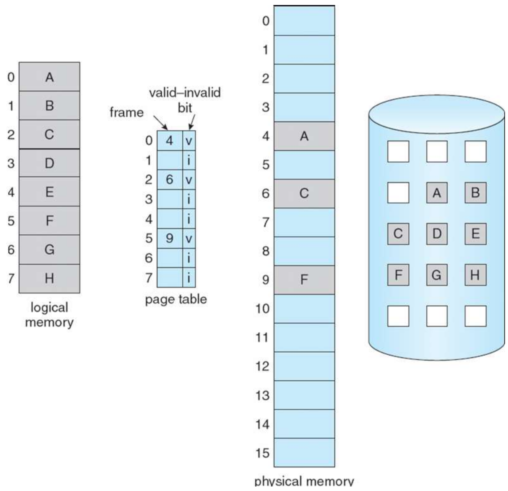
- With each page table entry a valid–invalid bit is associated
  (**v** ⇒ in-memory, **i** ⇒ not-in-memory)
- Initially valid–invalid bit is set to **i** on all entries
- Example of a page table snapshot:

Frame #	valid-invalid bit
	v
	v
	v
	v
	i
….	
	i
	i

page table

- During address translation, if valid–invalid bit in page table entry is **I** ⇒ page fault

Page Table When Some Pages Are Not in Main Memory



Page Fault

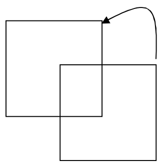
- If there is a reference to a page, first reference to that page will trap to operating system:

  page fault

1. Operating system looks at another table to decide:
   - Invalid reference $\Rightarrow$ abort
   - Just not in memory
2. Get empty frame
3. Swap page into frame
4. Reset tables
5. Set validation bit = **v**
6. Restart the instruction that caused the page fault

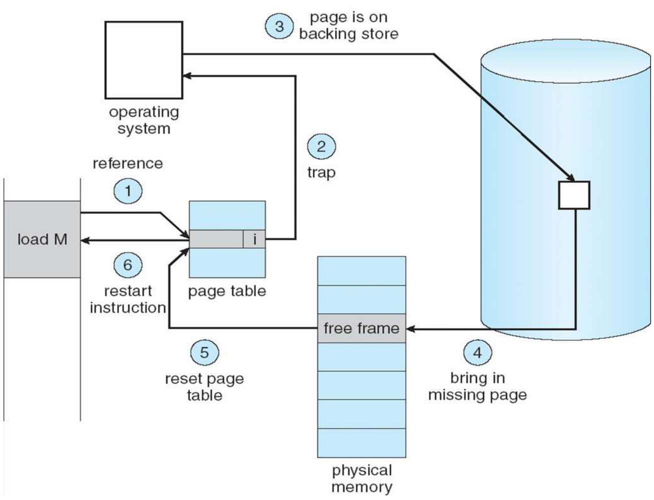
Page Fault (Cont.)

- Restart instruction
  - block move



  - auto increment/decrement location

Steps in Handling a Page Fault



Performance of Demand Paging

- Page Fault Rate $0 \le p \le 1.0$
  - if $p = 0$ no page faults
  - if $p = 1$, every reference is a fault
- Effective Access Time (EAT)

  EAT = (1 – *p*) x memory access
  + *p* (page fault overhead
  + swap page out
  + swap page in
  + restart overhead
)

Demand Paging Example

- Memory access time = 200 nanoseconds
- Average page-fault service time = 8 milliseconds
- EAT = (1 – p) x 200 + p (8 milliseconds)
  = (1 – p x 200 + p x 8,000,000
  = 200 + p x 7,999,800
- If one access out of 1,000 causes a page fault, then
  EAT = 8.2 microseconds.
  This is a slowdown by a factor of 40!!

Process Creation

- Virtual memory allows other benefits during process creation:

  - Copy-on-Write

  - Memory-Mapped Files (later)

Copy-on-Write

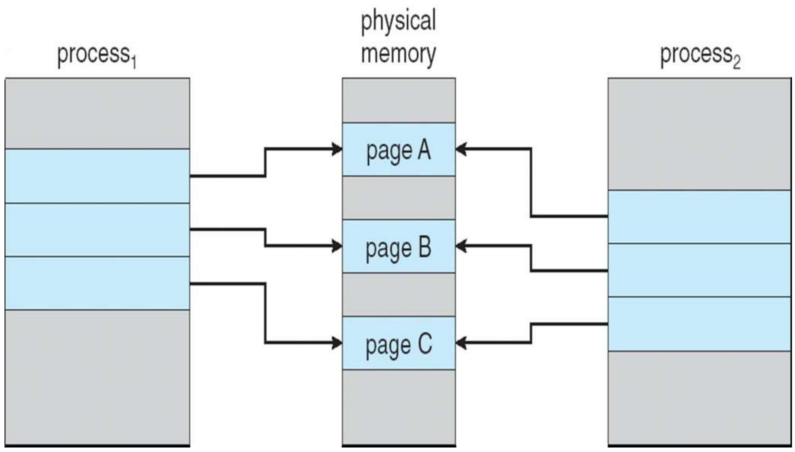
- Copy-on-Write (COW) allows both parent and child processes to initially *share* the same pages in memory

  If either process modifies a shared page, only then is the page copied

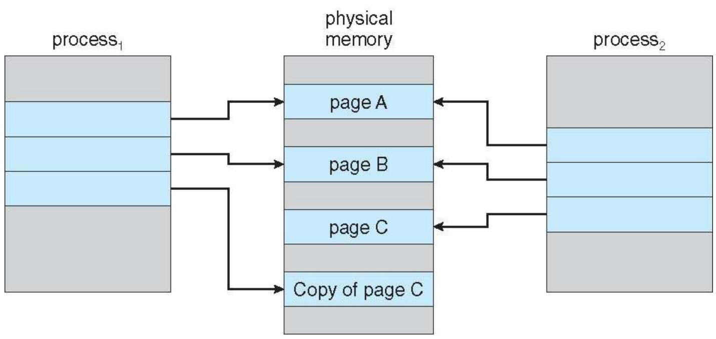
- COW allows more efficient process creation as only modified pages are copied

- Free pages are allocated from a **pool** of zeroed-out pages

Before Process 1 Modifies Page C



After Process 1 Modifies Page C



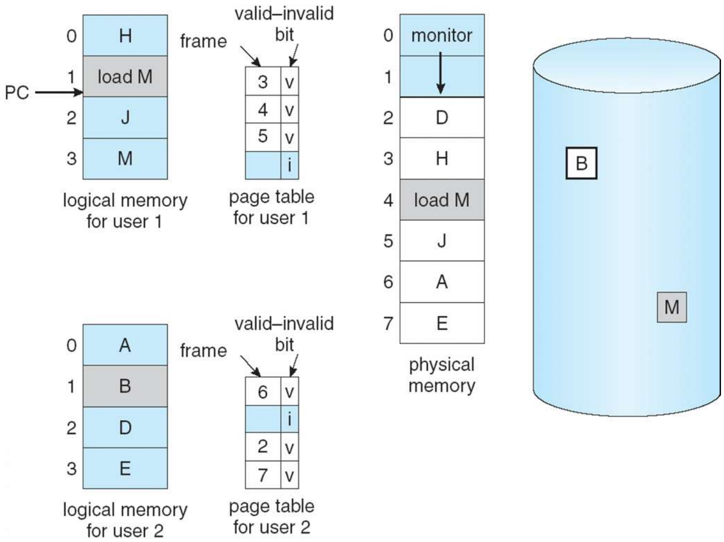
What happens if there is no free frame?

- Page replacement – find some page in memory, but not really in use, swap it out
  - algorithm
  - performance – want an algorithm which will result in minimum number of page faults
- Same page may be brought into memory several times

Page Replacement

- Prevent over-allocation of memory by modifying page-fault service routine to include page replacement
- Use **modify (dirty) bit** to reduce overhead of page transfers – only modified pages are written to disk
- Page replacement completes separation between logical memory and physical memory – large virtual memory can be provided on a smaller physical memory

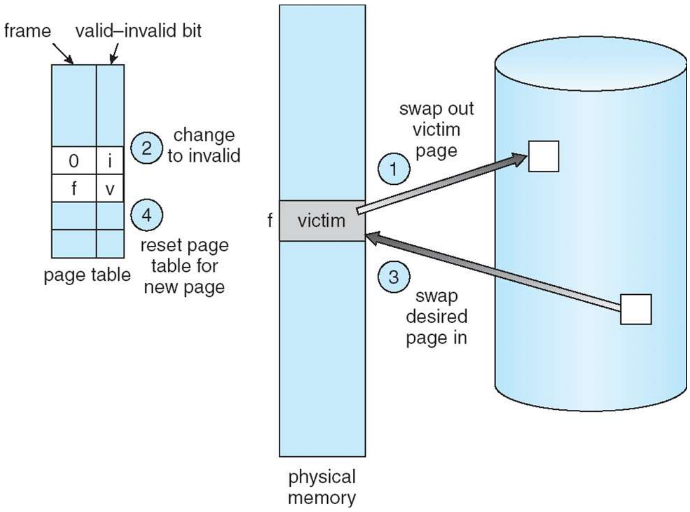
Need For Page Replacement



Basic Page Replacement

1. Find the location of the desired page on disk
2. Find a free frame:
   - If there is a free frame, use it
   - If there is no free frame, use a page replacement algorithm to select a **victim** frame
3. Bring the desired page into the (newly) free frame; update the page and frame tables
4. Restart the process

Page Replacement

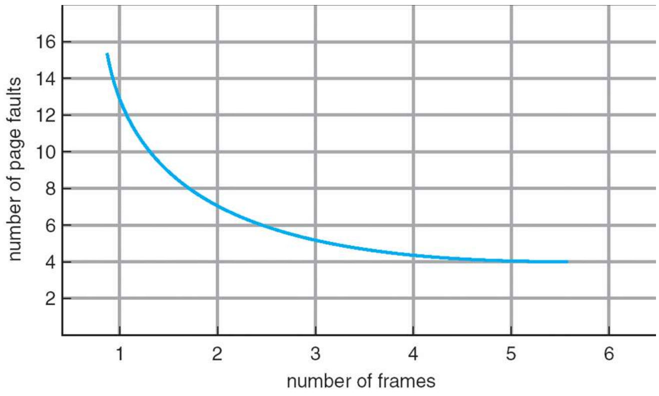


Page Replacement Algorithms

- Want lowest page-fault rate
- Evaluate algorithm by running it on a particular string of memory references (reference string) and computing the number of page faults on that string
- In all our examples, the reference string is

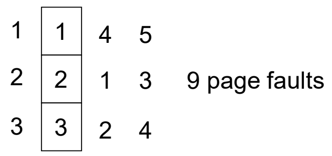
  1, 2, 3, 4, 1, 2, 5, 1, 2, 3, 4, 5

Graph of Page Faults Versus The Number of Frames

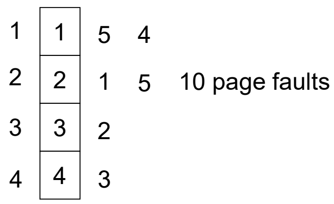


First-In-First-Out (FIFO) Algorithm

- Reference string: 1, 2, 3, 4, 1, 2, 5, 1, 2, 3, 4, 5
- 3 frames (3 pages can be in memory at a time per process)

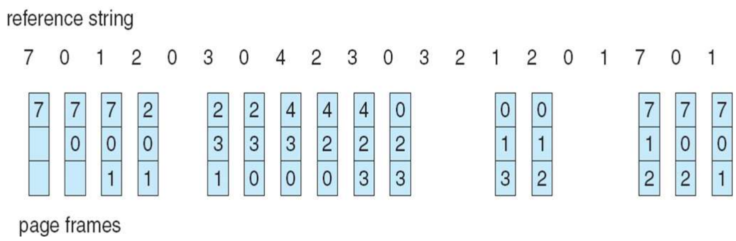


- 4 frames

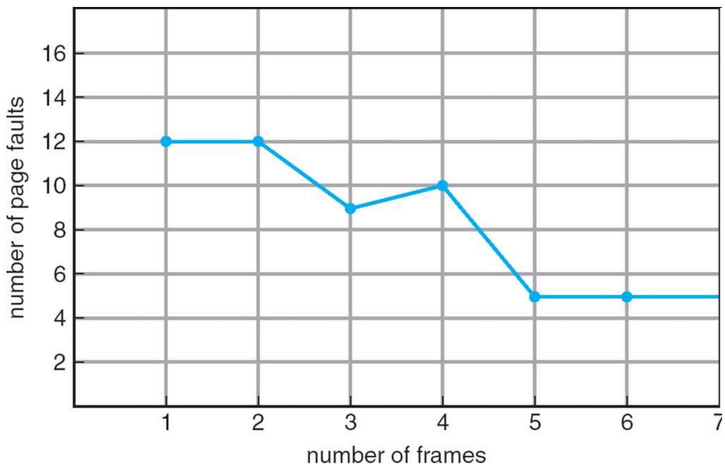


- Belady’s Anomaly: more frames $\Rightarrow$ more page faults

FIFO Page Replacement



FIFO Illustrating Belady's Anomaly



Optimal Algorithm

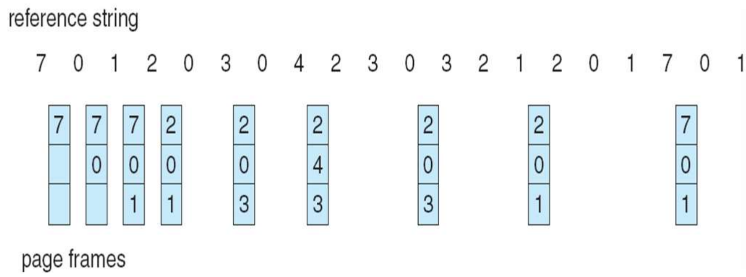
- Replace page that will not be used for longest period of time
- 4 frames example

1, 2, 3, 4, 1, 2, 5, 1, 2, 3, 4, 5

1	4	
2		6 page faults
3		
4	5	

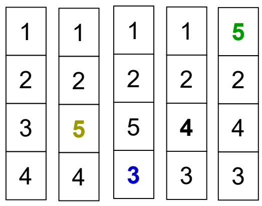
- How do you know this?
- Used for measuring how well your algorithm performs

Optimal Page Replacement



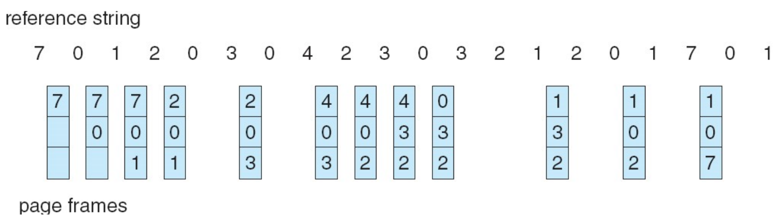
Least Recently Used (LRU) Algorithm

- Reference string: 1, 2, 3, 4, 1, 2, **5**, 1, 2, **3**, **4**, **5**



- Counter implementation
  - Every page entry has a counter; every time page is referenced through this entry, copy the clock into the counter
  - When a page needs to be changed, look at the counters to determine which are to change

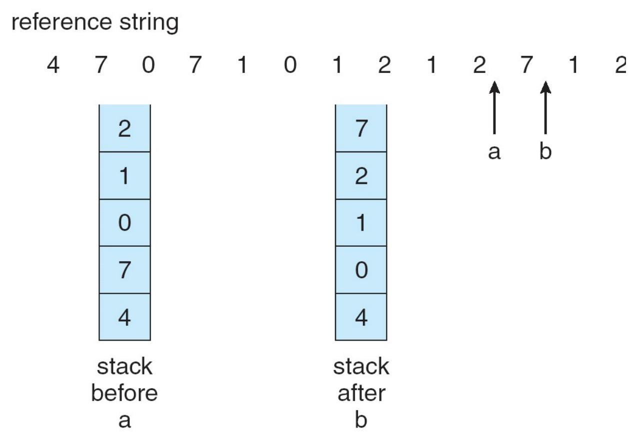
LRU Page Replacement



LRU Algorithm (Cont.)

- Stack implementation – keep a stack of page numbers in a double link form:
  - Page referenced:
    - move it to the top
    - requires 6 pointers to be changed
  - No search for replacement

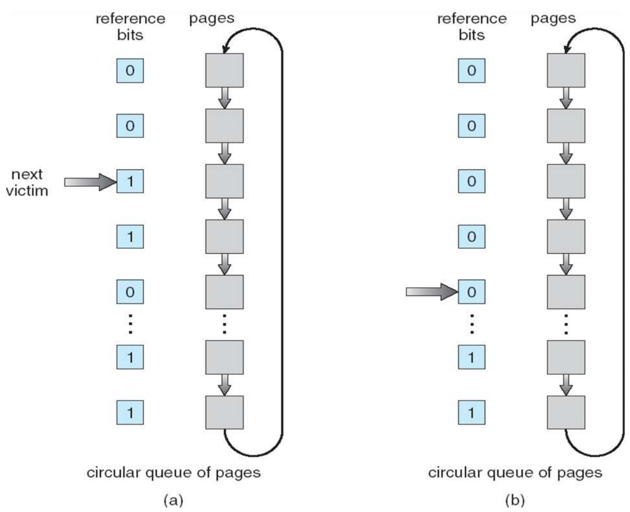
Use Of A Stack to Record The Most Recent Page References



LRU Approximation Algorithms

- Reference bit
  - With each page associate a bit, initially = 0
  - When page is referenced bit set to 1
  - Replace the one which is 0 (if one exists)
    - We do not know the order, however
- Second chance
  - Need reference bit
  - Clock replacement
  - If page to be replaced (in clock order) has reference bit = 1 then:
    - set reference bit 0
    - leave page in memory
    - replace next page (in clock order), subject to same rules

Second-Chance (clock) Page-Replacement Algorithm



Counting Algorithms

- Keep a counter of the number of references that have been made to each page
- **LFU Algorithm**: replaces page with smallest count
- **MFU Algorithm**: based on the argument that the page with the smallest count was probably just brought in and has yet to be used

Allocation of Frames

- Each process needs *minimum* number of pages
- Example: IBM 370 – 6 pages to handle SS MOVE instruction:
  - instruction is 6 bytes, might span 2 pages
  - 2 pages to handle *from*
  - 2 pages to handle *to*
- Two major allocation schemes
  - fixed allocation
  - priority allocation

Fixed Allocation

- Equal allocation – For example, if there are 100 frames and 5 processes, give each process 20 frames.
- Proportional allocation – Allocate according to the size of process
  - s_i = size of process p_i
  - $S = \sum s_i$
  - m = total number of frames
  - a_i = allocation for $p_i = \frac{s_i}{S} \times m$

$$m = 64$$
$$s_i = 10$$
$$s_2 = 127$$
$$a_1 = \frac{10}{137} \times 64 \approx 5$$
$$a_2 = \frac{127}{137} \times 64 \approx 59$$

Priority Allocation

- Use a proportional allocation scheme using priorities rather than size
- If process P_i generates a page fault,
  - select for replacement one of its frames
  - select for replacement a frame from a process with lower priority number

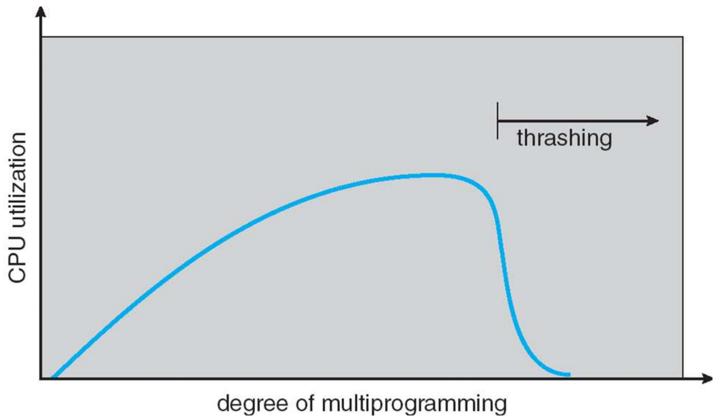
Global vs. Local Allocation

- **Global replacement** – process selects a replacement frame from the set of all frames; one process can take a frame from another
- **Local replacement** – each process selects from only its own set of allocated frames

Thrashing

- If a process does not have “enough” pages, the page-fault rate is very high. This leads to:
  - low CPU utilization
  - operating system thinks that it needs to increase the degree of multiprogramming
  - another process added to the system
- **Thrashing** ≡ a process is busy swapping pages in and out

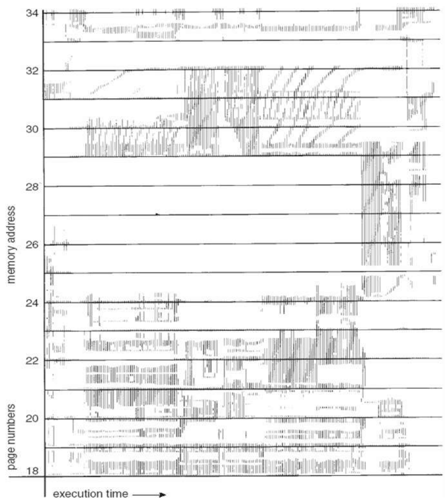
Thrashing (Cont.)



Demand Paging and Thrashing

- Why does demand paging work?
  Locality model
  - Process migrates from one locality to another
  - Localities may overlap
- Why does thrashing occur?
  Σ size of locality > total memory size

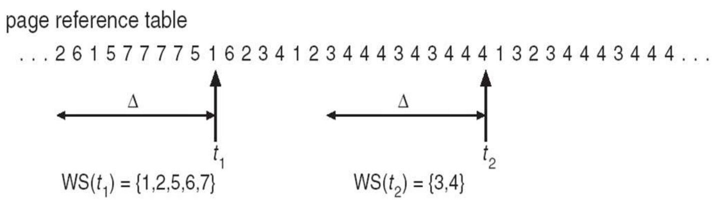
Locality In A Memory-Reference Pattern



Working-Set Model

- $\Delta \equiv$ working-set window $\equiv$ a fixed number of page references
  Example: 10,000 instruction
- WSS_i (working set of Process P_i) =
  total number of pages referenced in the most recent Δ (varies in time)
  - if Δ too small will not encompass entire locality
  - if Δ too large will encompass several localities
  - if $\Delta = \infty \Rightarrow$ will encompass entire program
- $D = \Sigma\ WSS_i \equiv$ total demand frames
- if $D > m \Rightarrow$ Thrashing
- Policy if D > m, then suspend one of the processes

Working-set model

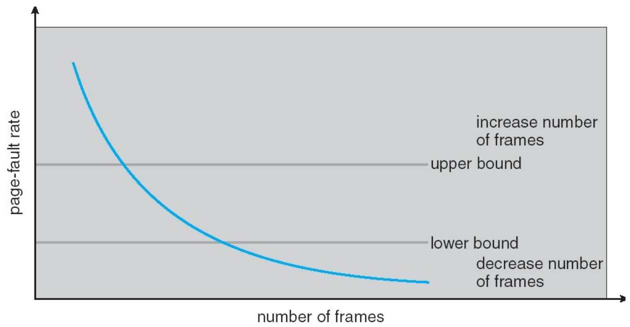


Keeping Track of the Working Set

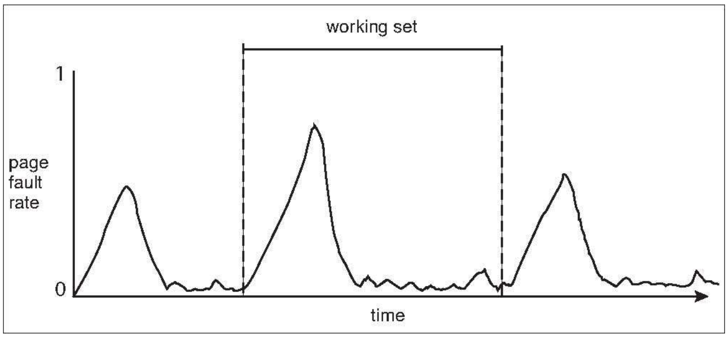
- Approximate with interval timer + a reference bit
- Example: Δ = 10,000
  - Timer interrupts after every 5000 time units
  - Keep in memory 2 bits for each page
  - Whenever a timer interrupts copy and sets the values of all reference bits to 0
  - If one of the bits in memory = 1 $\Rightarrow$ page in working set
- Why is this not completely accurate?
- Improvement = 10 bits and interrupt every 1000 time units

Page-Fault Frequency Scheme

- Establish "acceptable" page-fault rate
  - If actual rate too low, process loses frame
  - If actual rate too high, process gains frame



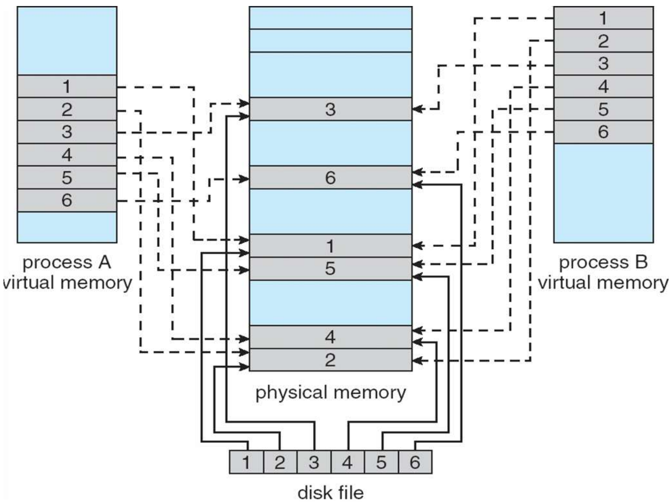
Working Sets and Page Fault Rates



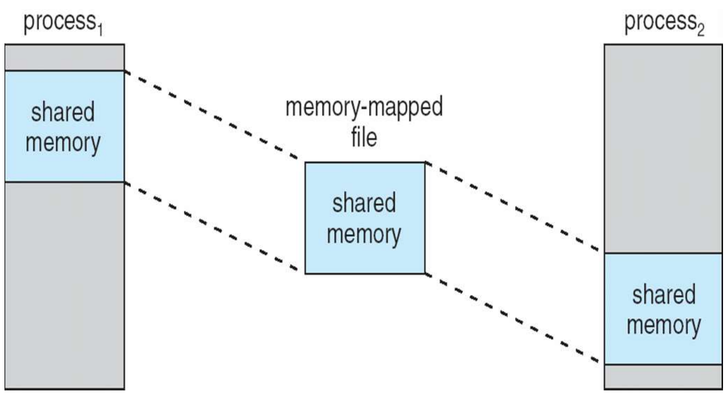
Memory-Mapped Files

- Memory-mapped file I/O allows file I/O to be treated as routine memory access by **mapping** a disk block to a page in memory
- A file is initially read using demand paging. A page-sized portion of the file is read from the file system into a physical page. Subsequent reads/writes to/from the file are treated as ordinary memory accesses.
- Simplifies file access by treating file I/O through memory rather than `read()` `write()` system calls
- Also allows several processes to map the same file allowing the pages in memory to be shared

Memory Mapped Files



Memory-Mapped Shared Memory in Windows



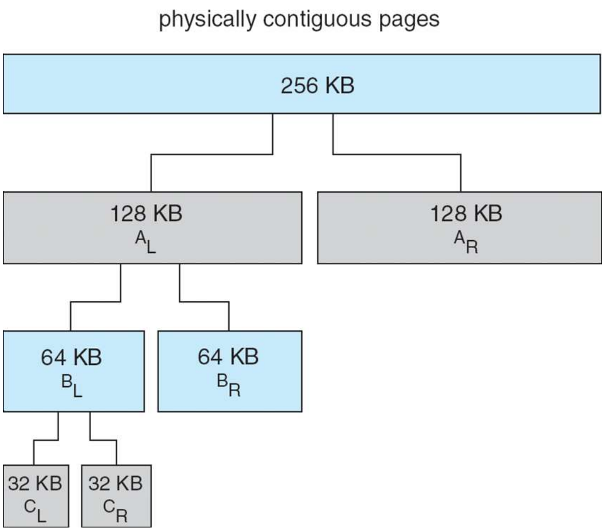
Allocating Kernel Memory

- Treated differently from user memory
- Often allocated from a free-memory pool
  - Kernel requests memory for structures of varying sizes
  - Some kernel memory needs to be contiguous

Buddy System

- Allocates memory from fixed-size segment consisting of physically-contiguous pages
- Memory allocated using **power-of-2 allocator**
  - Satisfies requests in units sized as power of 2
  - Request rounded up to next highest power of 2
  - When smaller allocation needed than is available, current chunk split into two buddies of next-lower power of 2
    - Continue until appropriate sized chunk available

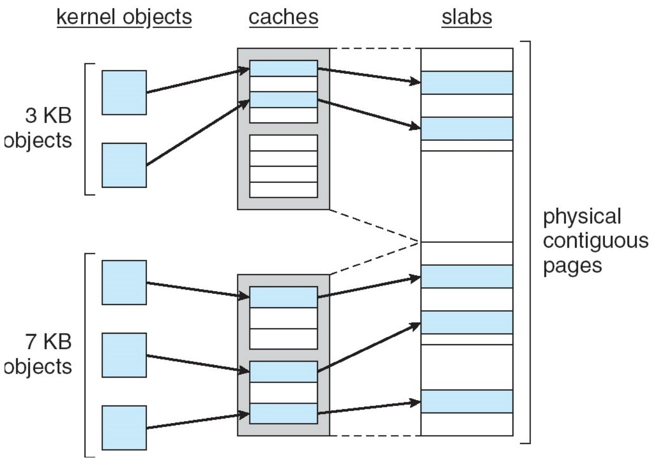
Buddy System Allocator



Slab Allocator

- Alternate strategy
- **Slab** is one or more physically contiguous pages
- **Cache** consists of one or more slabs
- Single cache for each unique kernel data structure
  - Each cache filled with **objects** – instantiations of the data structure
- When cache created, filled with objects marked as **free**
- When structures stored, objects marked as **used**
- If slab is full of used objects, next object allocated from empty slab
  - If no empty slabs, new slab allocated
- Benefits include no fragmentation, fast memory request satisfaction

Slab Allocation



Other Issues -- Prepaging

- Prepaging
  - To reduce the large number of page faults that occurs at process startup
  - Prepage all or some of the pages a process will need, before they are referenced
  - But if prepaged pages are unused, I/O and memory was wasted
  - Assume s pages are prepaged and α of the pages is used
    - Is cost of $s * \alpha$ save pages faults > or < than the cost of prepaging
      $s * (1- \alpha)$ unnecessary pages?
    - α near zero $\Rightarrow$ prepaging loses

Other Issues – Page Size

- Page size selection must take into consideration:
  - fragmentation
  - table size
  - I/O overhead
  - locality

Other Issues – TLB Reach

- TLB Reach - The amount of memory accessible from the TLB
- TLB Reach = (TLB Size) X (Page Size)
- Ideally, the working set of each process is stored in the TLB
  - Otherwise there is a high degree of page faults
- Increase the Page Size
  - This may lead to an increase in fragmentation as not all applications require a large page size
- Provide Multiple Page Sizes
  - This allows applications that require larger page sizes the opportunity to use them without an increase in fragmentation

Other Issues – Program Structure

- Program structure
  - `Int[128,128] data;`
  - Each row is stored in one page
  - Program 1

```
for (j = 0; j <128; j++)
     for (i = 0; i < 128; i++)
            data[i,j] = 0;
```

128 x 128 = 16,384 page faults

  - Program 2

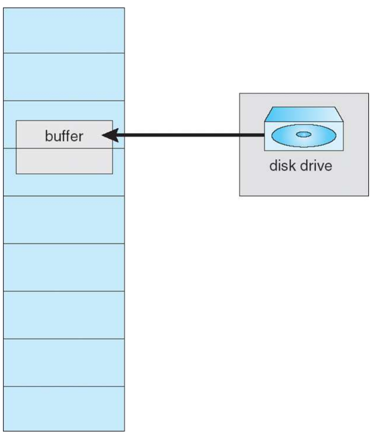
```
for (i = 0; i < 128; i++)
     for (j = 0; j < 128; j++)
            data[i,j] = 0;
```

128 page faults

Other Issues – I/O interlock

- **I/O Interlock** – Pages must sometimes be locked into memory
- Consider I/O - Pages that are used for copying a file from a device must be locked from being selected for eviction by a page replacement algorithm

Reason Why Frames Used For I/O Must Be In Memory



Operating System Examples

- Windows XP
- Solaris

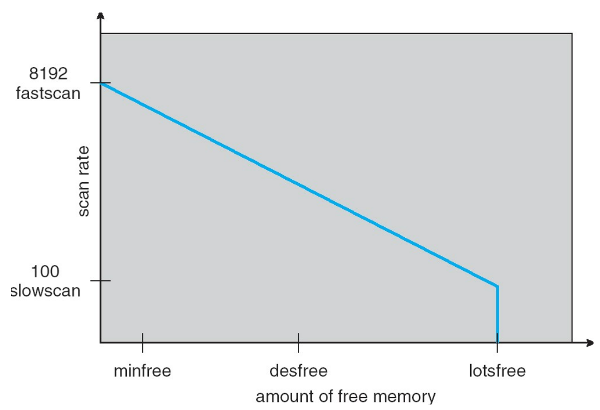
Windows XP

- Uses demand paging with **clustering**. Clustering brings in pages surrounding the faulting page
- Processes are assigned **working set minimum** and **working set maximum**
- Working set minimum is the minimum number of pages the process is guaranteed to have in memory
- A process may be assigned as many pages up to its working set maximum
- When the amount of free memory in the system falls below a threshold, **automatic working set trimming** is performed to restore the amount of free memory
- Working set trimming removes pages from processes that have pages in excess of their working set minimum

Solaris

- Maintains a list of free pages to assign faulting processes
- *Lotsfree* – threshold parameter (amount of free memory) to begin paging
- *Desfree* – threshold parameter to increasing paging
- *Minfree* – threshold parameter to being swapping
- Paging is performed by *pageout* process
- Pageout scans pages using modified clock algorithm
- *Scanrate* is the rate at which pages are scanned. This ranges from *slowscan* to *fastscan*
- Pageout is called more frequently depending upon the amount of free memory available

Solaris 2 Page Scanner



End of Chapter 9