

Quicksort

Algorithms & Data Structures
ITCS 6114/8114

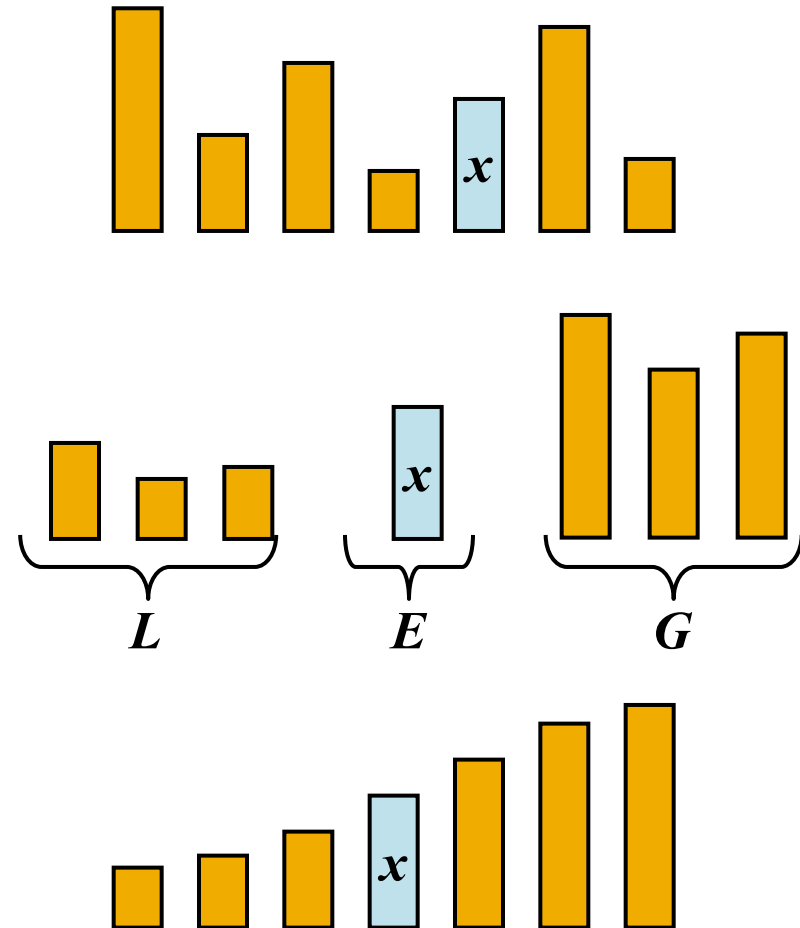
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Outline and Reading

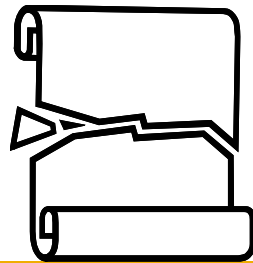
- Quick-sort (§4.3)
 - ▣ Algorithm
 - ▣ Partition step
 - ▣ Quick-sort tree
 - ▣ Execution example
- Analysis of quick-sort (4.3.1)
- In-place quick-sort (§4.8)
- Summary of sorting algorithms

Quick-Sort

- **Quick-sort** is a randomized sorting algorithm based on the divide-and-conquer paradigm:
 - ▣ **Divide**: pick a random element x (called pivot) and partition S into
 - L elements less than x
 - E elements equal to x
 - G elements greater than x
 - ▣ **Recur**: sort L and G
 - ▣ **Conquer**: join L , E and G



Partition



- We partition an input sequence as follows:
 - ▣ We remove, in turn, each element y from S and
 - ▣ We insert y into L , E or G , depending on the result of the comparison with the pivot x
- Each insertion and removal is at the beginning or at the end of a sequence, and hence takes $O(1)$ time
- Thus, the partition step of quick-sort takes $O(n)$ time

Algorithm `partition(S, p)`

Input sequence S , position p of pivot
Output subsequences L , E , G of the elements of S less than, equal to, or greater than the pivot, resp.

L , E , $G \leftarrow$ empty sequences

$x \leftarrow S.remove(p)$

while $\neg S.isEmpty()$

$y \leftarrow S.remove(S.first())$

if $y < x$

$L.insertLast(y)$

else if $y = x$

$E.insertLast(y)$

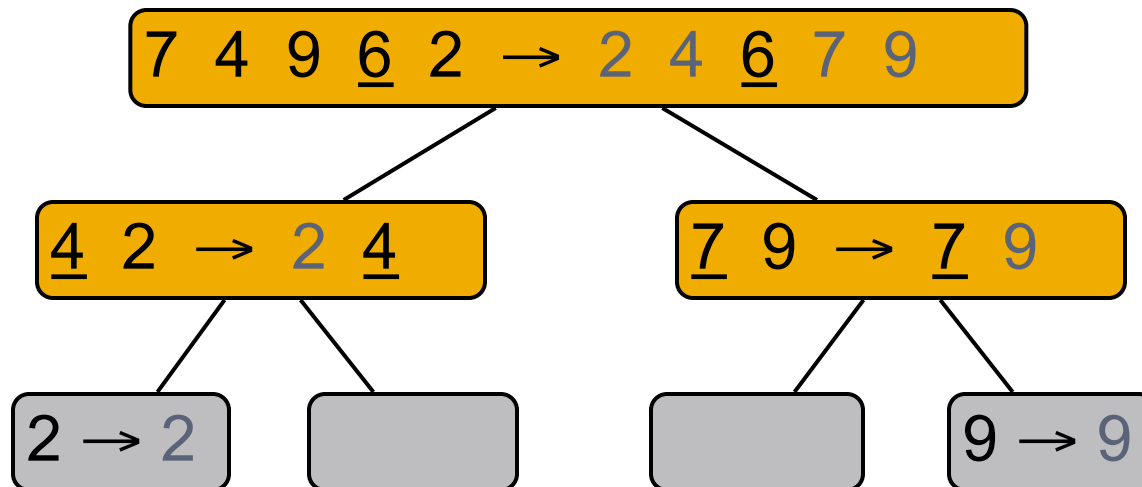
else { $y > x$ }

$G.insertLast(y)$

return L , E , G

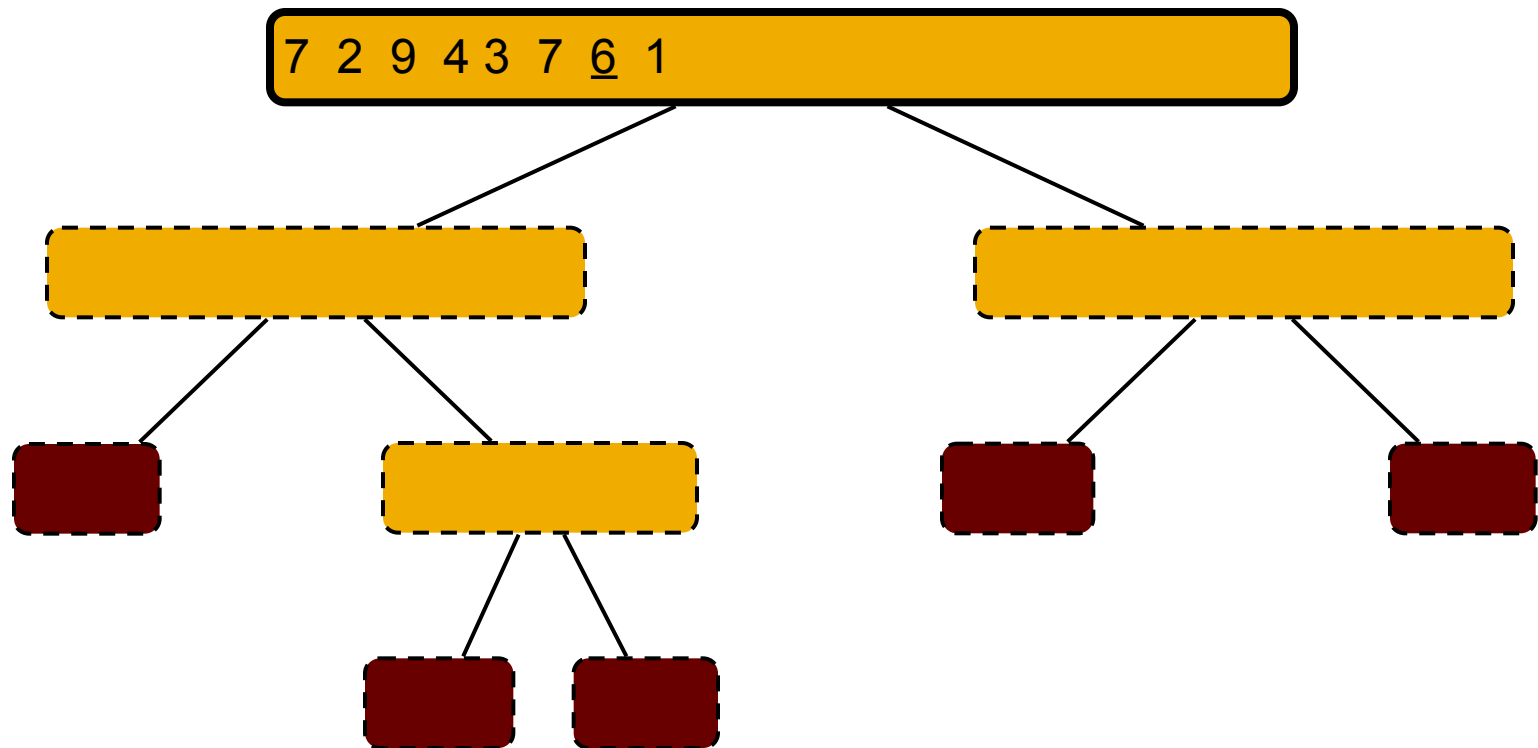
Quick-Sort Tree

- An execution of quick-sort is depicted by a binary tree
 - ▣ Each node represents a recursive call of quick-sort and stores
 - Unsorted sequence before the execution and its pivot
 - Sorted sequence at the end of the execution
 - ▣ The root is the initial call
 - ▣ The leaves are calls on subsequences of size 0 or 1



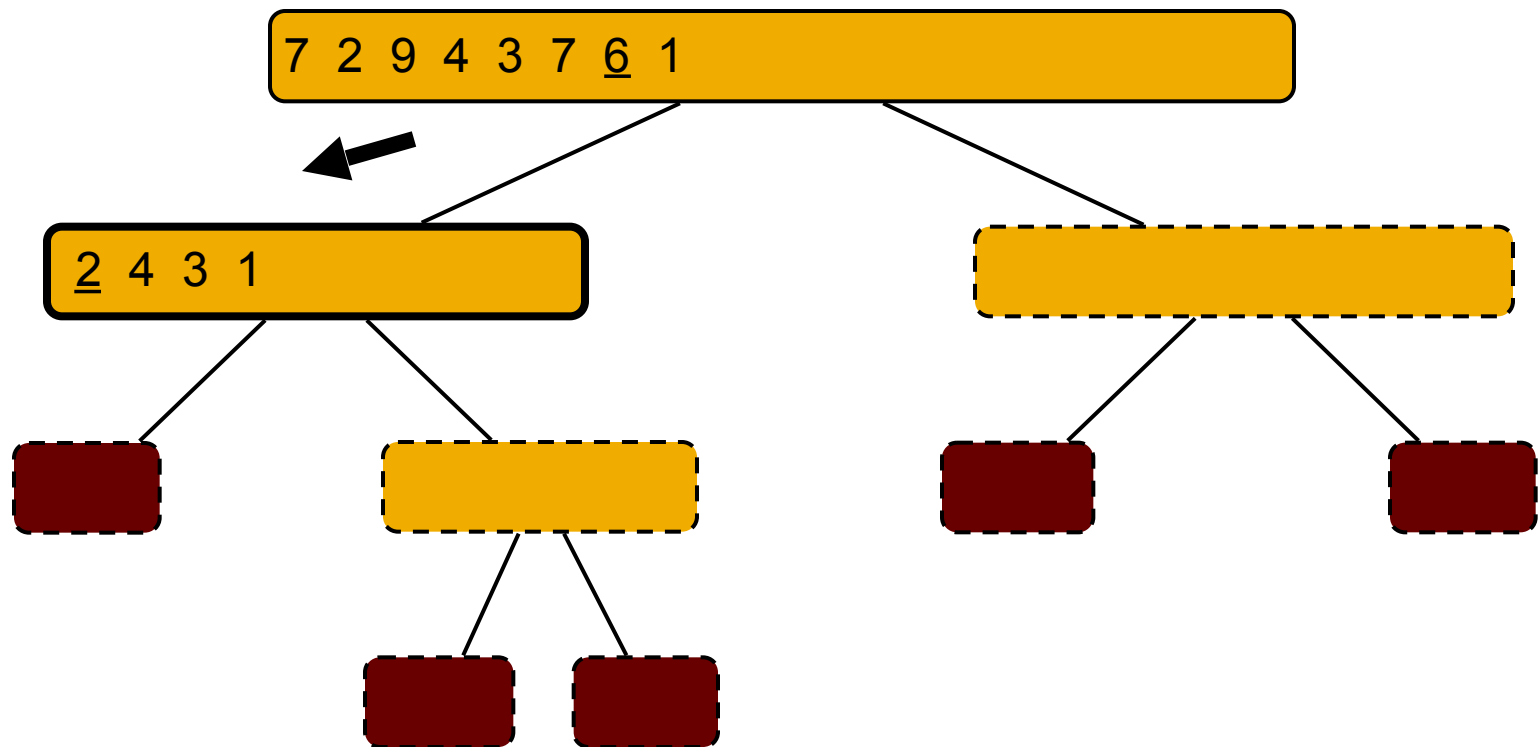
Execution Example

- Pivot selection



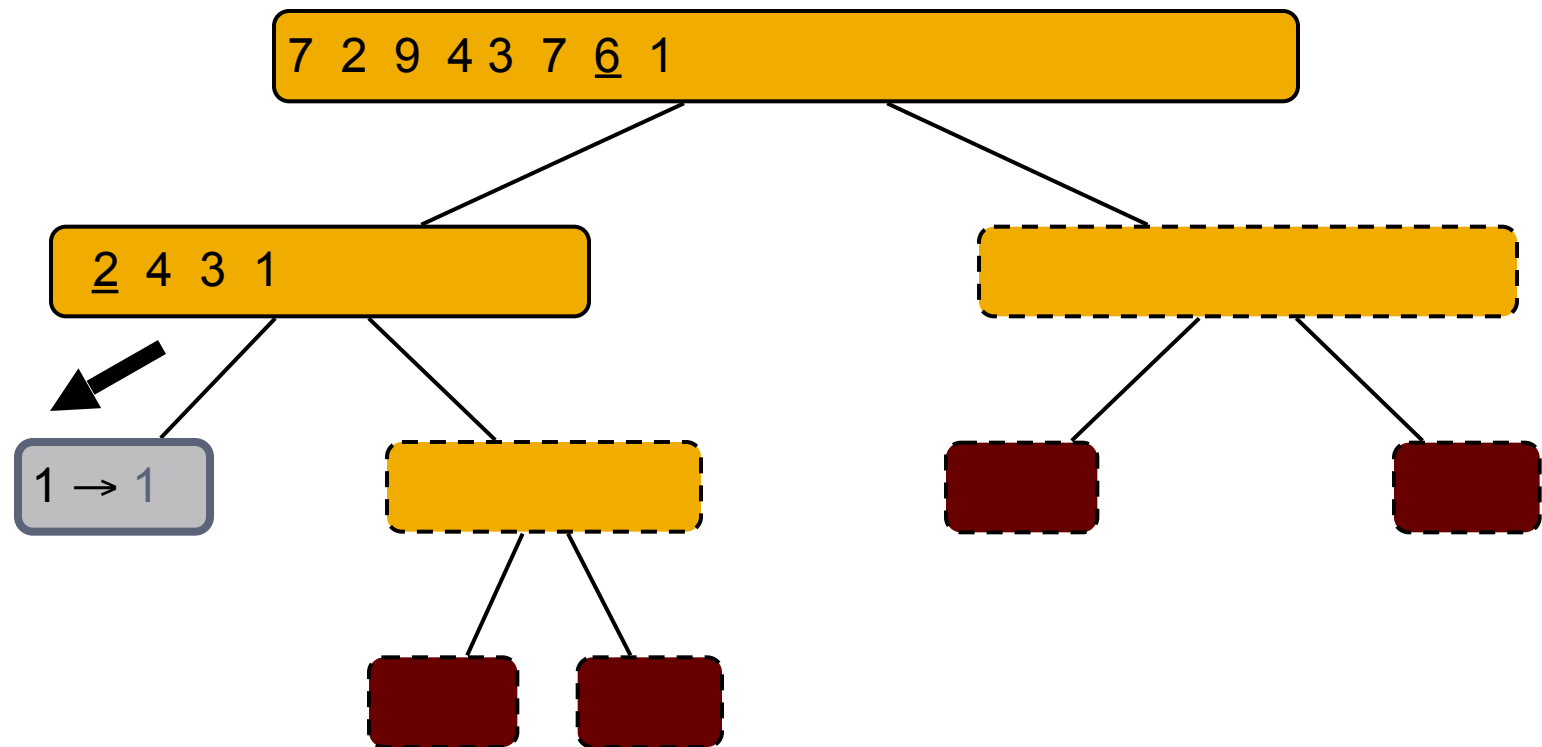
Execution Example (cont.)

- Partition, recursive call, pivot selection



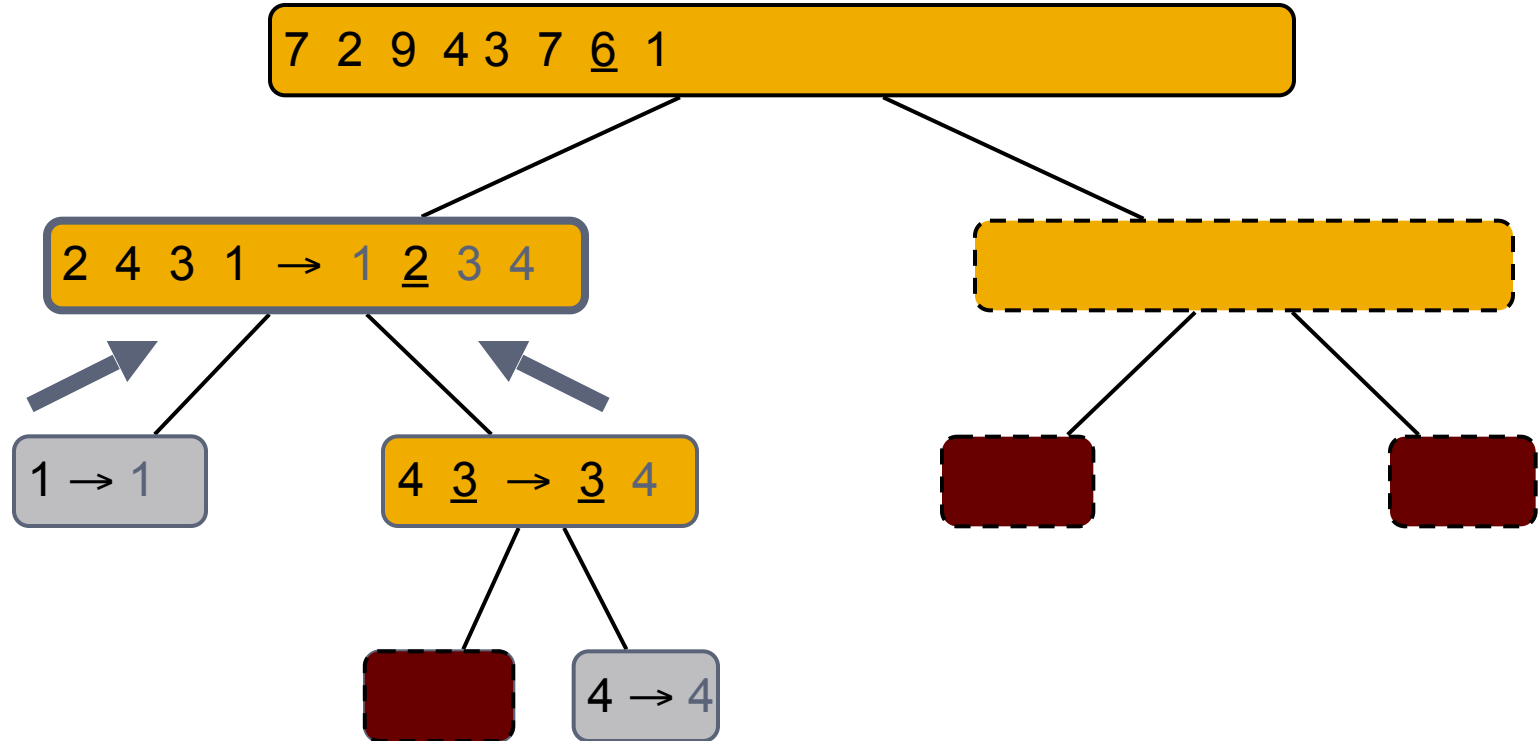
Execution Example (cont.)

- Partition, recursive call, base case



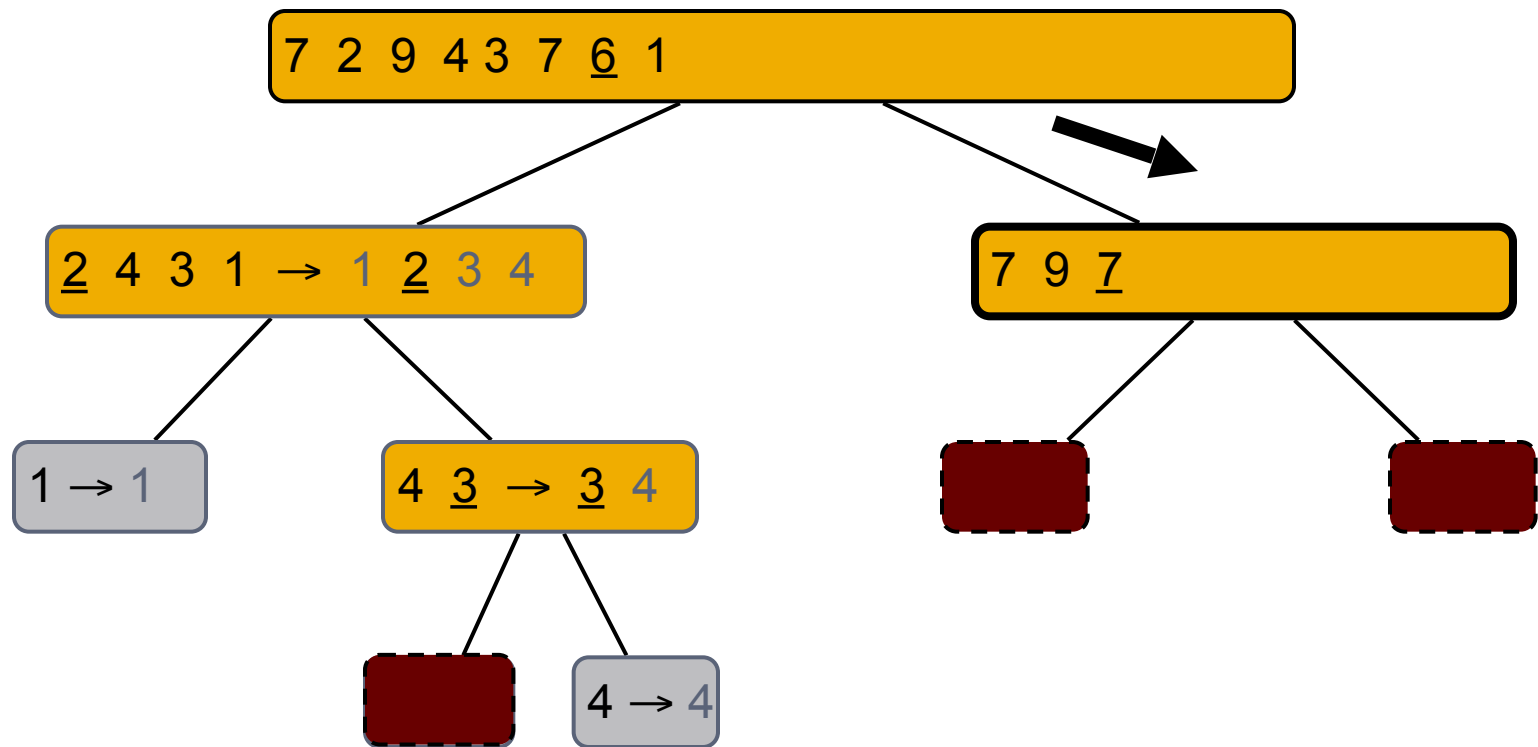
Execution Example (cont.)

- Recursive call, ..., base case, join



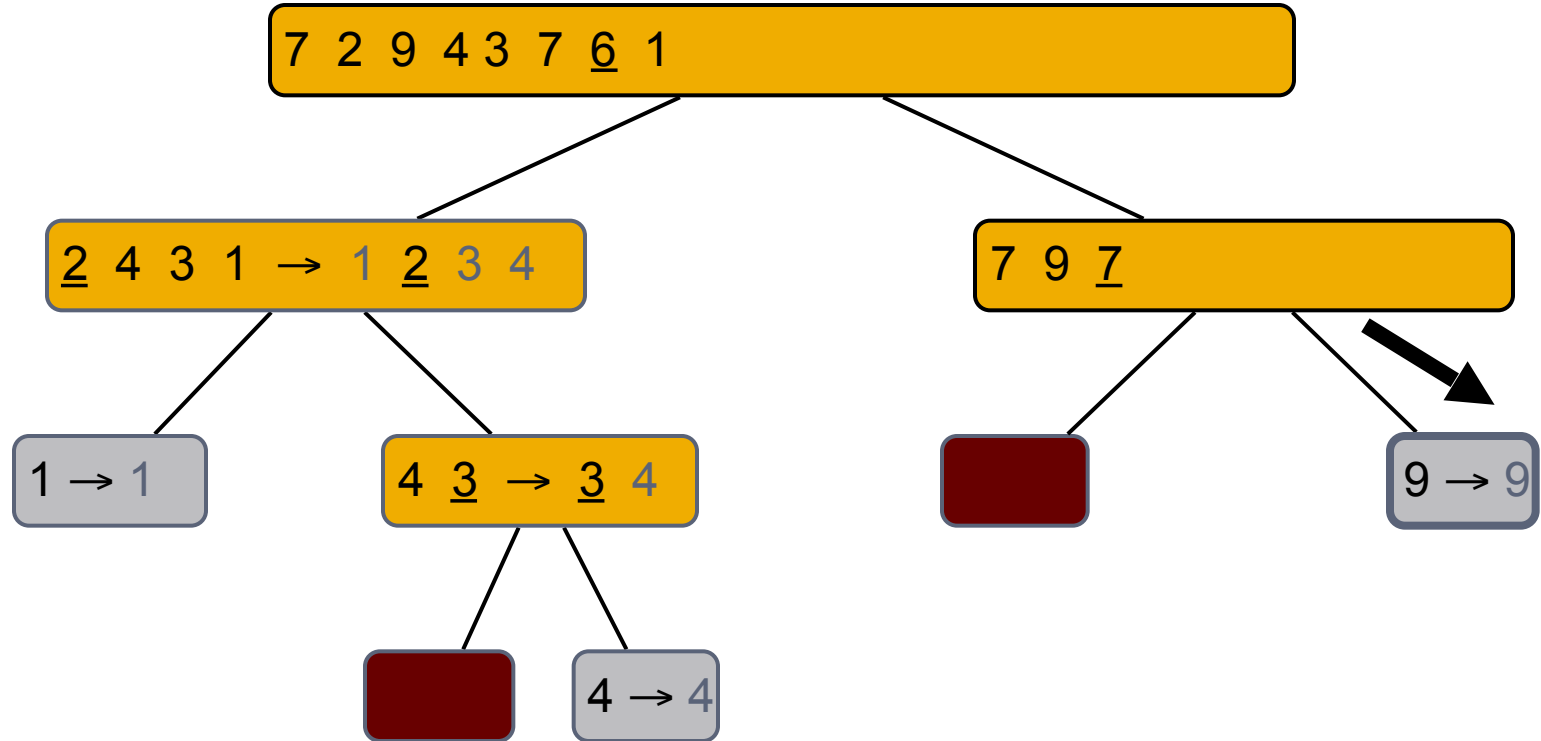
Execution Example (cont.)

- Recursive call, pivot selection



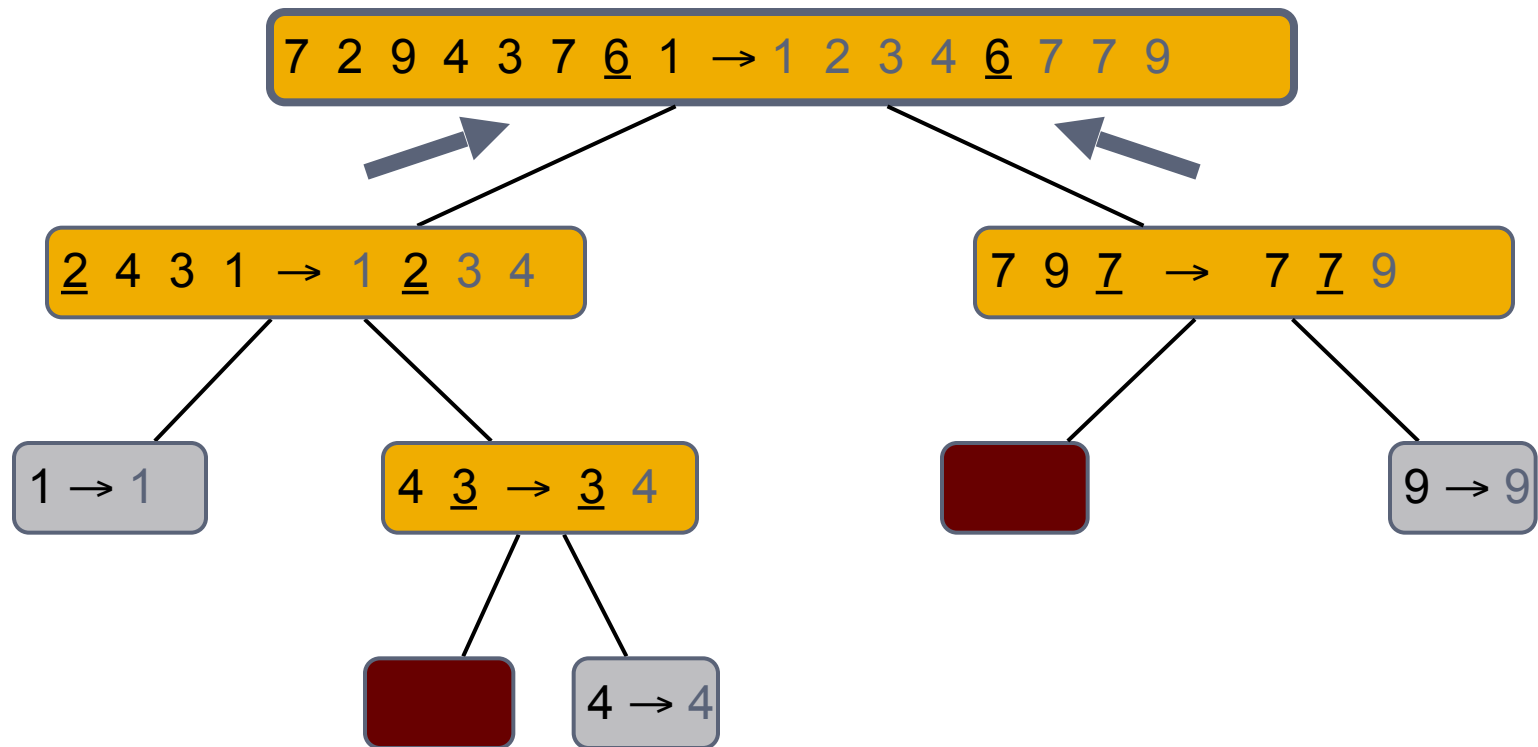
Execution Example (cont.)

- Partition, ..., recursive call, base case



Execution Example (cont.)

- Join, join



Quicksort - Best case

- We cut the array size in half each time
- So the depth of the recursion is $\log_2 n$
- At each level of the recursion, all the partitions at that level do work that is linear in n
- $O(\log_2 n) * O(n) = O(n \log_2 n)$
- Hence in the best case, quicksort has time complexity $O(n \log_2 n)$

Worst-case Running Time

- In the worst-case, partitioning always divides the size n array into these three parts:
 - ▣ A length **one** part, containing the pivot itself
 - ▣ A length **zero** part, and
 - ▣ A length **$n-1$** part, containing everything else
- We don't recur on the zero-length part
- Recurring on the length **$n-1$** part requires (in the worst case) recurring to depth **$n-1$**

Worst-case Running Time (cont..)

- The worst case for quick-sort occurs when **the pivot is the unique minimum or maximum element**
- The running time is proportional to the sum

$$n + (n - 1) + \dots + 2 + 1$$

- Thus, the worst-case running time of quick-sort is $O(n^2)$

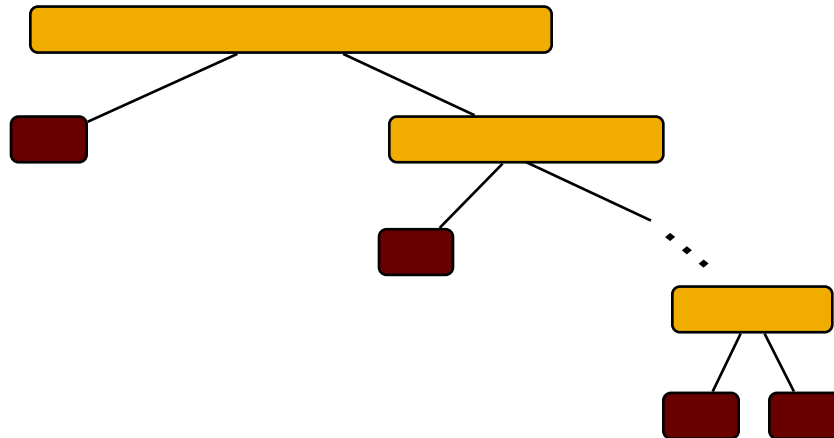
depth time

0 n

1 $n - 1$

...

$n - 1$ 1



Worst-case Running Time

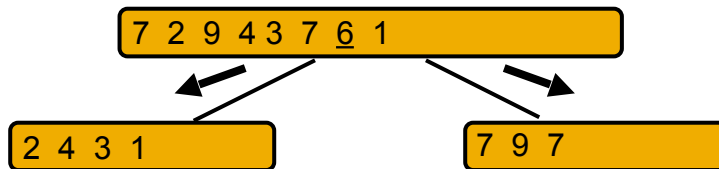
- When does this happen?
 - ▣ There are many arrangements that *could* make this happen
 - ▣ Here are two common cases:
 - When the array is already sorted
 - When the array is *inversely* sorted (sorted in the opposite order)

Typical case for quicksort

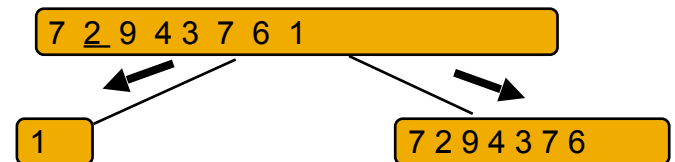
- If the array is sorted to begin with, Quicksort is terrible: $O(n^2)$
- However, Quicksort is *usually* $O(n \log_2 n)$
- Quicksort is generally the fastest algorithm known
- Most real-world sorting is done by Quicksort

Expected Running Time

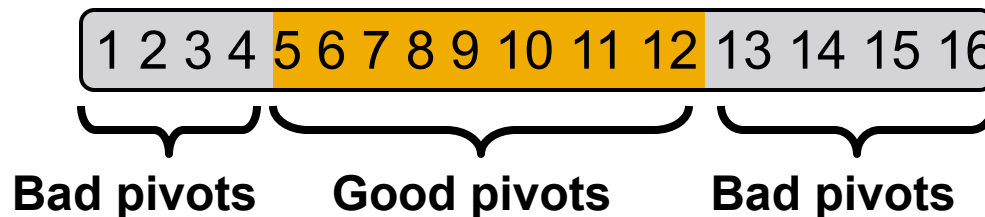
- Consider a recursive call of quick-sort on a sequence of size n
 - ▣ **Good call:** the sizes of L and G are at most $3n/4$ and at least $n/4$
 - ▣ **Bad call:** one of L and G has size greater than $3n/4$
- A call is **good** with probability $1/2$
 - ▣ $1/2$ of the possible pivots cause good calls:



Good call



Bad call

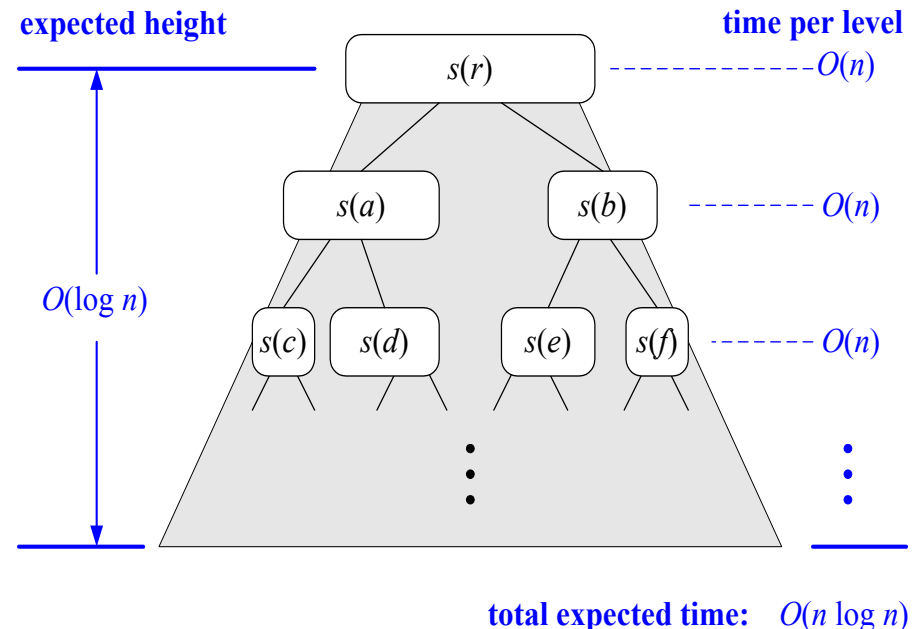


Expected Running Time, Part 2

- ☐ **Probabilistic Fact:** The expected number of coin tosses required in order to get k heads is $2k$
- ☐ For a node of depth i , we expect $i/2$ ancestors are good calls

If a node v of the quicksort tree T is associated with a “good” recursive call, the input size of the children of v are at most $3s(v)/4$ [i.e. $\frac{s(v)}{4/3}$]

If we take a path in T from the root to an external node, then the length of this path is at most the number of invocations that have to be made until achieving $\log_{4/3} n$ good invocations.

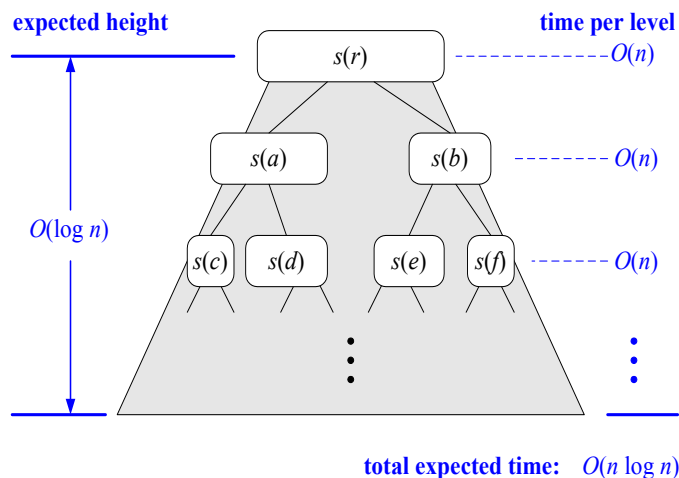


Expected Running Time, Part 2

- The expected number of invocations we must make until this occurs is $2 \log_{4/3} n$ (if a path terminates before this level, this is better)
- The expected height of the quick-sort tree is $O(\log n)$

The amount of work done at the nodes of the same depth is $O(n)$

Thus, the expected running time of quick-sort is $O(n \log n)$



In-Place Quick-Sort



- Quick-sort can be implemented to run in-place
- In the partition step, we use replace operations to rearrange the elements of the input sequence such that
 - ▣ the elements less than the pivot have rank less than h
 - ▣ the elements equal to the pivot have rank between h and k
 - ▣ the elements greater than the pivot have rank greater than k
- The recursive calls consider
 - ▣ elements with rank less than h
 - ▣ elements with rank greater than k

```
Algorithm inPlaceQuickSort( $S, l, r$ )
  Input sequence  $S$ , ranks  $l$  and  $r$ 
  Output sequence  $S$  with the
    elements of rank between  $l$  and  $r$ 
    rearranged in increasing order
  if  $l \geq r$ 
    return
   $i \leftarrow$  a random integer between  $l$  and  $r$ 
   $x \leftarrow S.\text{elemAtRank}(i)$ 
   $(h, k) \leftarrow \text{inPlacePartition}(x)$ 
  inPlaceQuickSort( $S, l, h - 1$ )
  inPlaceQuickSort( $S, k + 1, r$ )
```



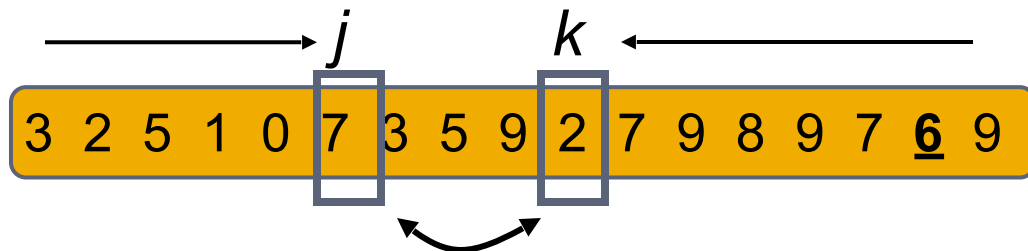
In-Place Partitioning

- Perform the partition using two indices to split S into L and $E \cup G$ (a similar method can split $E \cup G$ into E and G).

j k

3 2 5 1 0 7 3 5 9 2 7 9 8 9 7 6 9 (*pivot = 6*)

- Repeat until j and k cross:
 - ▣ Scan j to the right until finding an element $\geq x$.
 - ▣ Scan k to the left until finding an element $< x$.
 - ▣ Swap elements at indices j and k



Example of partitioning

choose pivot: 4 3 6 9 2 7 3 1 2 1 8 9 3 5 6

search: 4 3 6 9 2 7 3 1 2 1 8 9 3 5 6

swap: 4 3 3 9 2 7 3 1 2 1 8 9 6 5 6

search: 4 3 3 9 2 7 3 1 2 1 8 9 6 5 6

swap: 4 3 3 1 2 7 3 1 2 9 8 9 6 5 6











search: 4 3 3 1 2 7 3 1 2 9 8 9 6 5 6

swap: 4 3 3 1 2 2 3 1 7 9 8 9 6 5 6

search: 4 3 3 1 2 2 3 1 7 9 8 9 6 5 6 (left > right)

swap with pivot: 1 3 3 1 2 2 3 4 7 9 8 9 6 5 6

Summary of Sorting Algorithms

Algorithm	Time	Notes
selection-sort	$O(n^2)$	 in-place  slow (good for small inputs)
insertion-sort	$O(n^2)$	 in-place  slow (good for small inputs)
quick-sort	$O(n \log n)$ expected	 in-place, randomized  fastest (good for large inputs)
heap-sort	$O(n \log n)$	 in-place  fast (good for large inputs)
merge-sort	$O(n \log n)$	 sequential data access  fast (good for huge inputs)

Choice Of Pivot

Three ways to choose the pivot:

- Pivot is **rightmost (or leftmost)** element in list that is to be sorted
 - ▣ When sorting $A[1:30]$, use $A[30]$ (or $A[1]$) as the pivot
- **Randomly** select one of the elements to be sorted as the pivot
 - ▣ When sorting $A[1:30]$, generate a random number r in the range $[1, 30]$
 - ▣ Use $A[r]$ as the pivot

Small arrays

- Quicksort does not perform well for very small arrays
- How small depends on many factors, such as
 - ▣ the time spent making a recursive call, the compiler, etc.
- So, do not use quicksort recursively for small arrays
 - ▣ Instead, use a sorting algorithm that is efficient for small arrays, such as **insertion sort**

Pivot: median of three

- Use the median of the array
 - ▣ Partitioning always cuts the array into roughly half
 - ▣ An **optimal** quicksort ($O(n \log n)$)
 - ▣ However, hard to find the exact median
 - e.g., sort an array to pick the value in the middle

Pivot: median of three

- **Median-of-Three rule** - from the leftmost, middle, and rightmost elements of the list to be sorted, select the one with median key as the pivot
 - When sorting $A[1:20]$
 - examine $A[1]$, $A[10]$ $((1+20)/2)$, and $A[20]$
 - Select the element with median (i.e., middle) key
 - If
 - $A[1] = 30$,
 - $A[10] = 3$, and
 - $A[20] = 12$,
 - $A[20]$ becomes the pivot

Pivot: median of three

- We will use **median of three**
 - ▣ Compare just three elements: the leftmost, rightmost and center
 - ▣ Swap these elements if necessary so that
 - $A[\text{left}] = \text{Smallest}$
 - $A[\text{right}] = \text{Largest}$
 - $A[\text{center}] = \text{Median of three}$
 - ▣ Pick $A[\text{center}]$ as the pivot
 - ▣ Swap $A[\text{center}]$ and $A[\text{right} - 1]$ so that pivot is at second last position (why?)

Pivot: median of three

median3

```
center = (left+right) / 2;  
  
if ( a[center] < a[left] )  
    swap( a+left, a+center);  
if ( a[right] < a[left] )  
    swap( a+left, a+right);  
if ( a[right] < a[center] )  
    swap( a+center, a+right);  
  
swap(a+center, a+right-1);
```

Pivot: median of three

2	5	6	4	13	3	12	19	6
---	---	---	---	----	---	----	----	---

$A[\text{left}] = 2, A[\text{center}] = 13, A[\text{right}] = 6$

2	5	6	4	6	3	12	19	13
---	---	---	---	---	---	----	----	----

Swap $A[\text{center}]$ and $A[\text{right}]$

2	5	6	4	6	3	12	19	13
---	---	---	---	---	---	----	----	----

Choose $A[\text{center}]$ as pivot

↑
pivot

2	5	6	4	19	3	12	6	13
---	---	---	---	----	---	----	---	----

Swap pivot and $A[\text{right} - 1]$

↑
pivot

So now only need to partition $A[\text{left} + 1, \dots, \text{right} - 2]$. Why?

Main Quicksort Routine

```
if (left + 10 <= right)
{
```

Choose pivot

```
    int pivot = medianOfThree_pivot (a, left, right);
    int i = left, j = right - 2;
    for( ; ; ){
        while ( a[++i] < pivot );
        while ( pivot < a[--j] );
        if ( i < j )
            swap(a+i, a+j);
        else break;
    }
```

Partitioning

```
    swap (a+i, a+right-1);
    median3QuickSort( a, left, i-1);
    median3QuickSort( a, i+1, right);
```

Recursion

```
}
else
```

```
    insertionSort(a, left, right);
```

For small arrays

Quicksort Faster than Mergesort

- Both quicksort and mergesort take $O(n \log n)$ in the average case.
- Why is quicksort **faster** than mergesort?
 - ▣ The inner loop consists of an increment/decrement (by 1, which is fast), a test and a jump.
 - ▣ There is no extra juggling as in mergesort.

```
int i = left, j = right - 2;
for( ; ; ){
    while ( a[++i] < pivot );
    while ( pivot < a[--j] );
    if ( i < j )
        swap(a+i, a+j);
    else break;
}
```

inner loop

Analysis

□ Assumptions:

- ▣ A random pivot (no median-of-three partitioning)
- ▣ No cutoff for small arrays

□ Running time

- ▣ pivot selection: constant time, i.e. $O(1)$
 - ▣ partitioning: linear time, i.e. $O(N)$
 - ▣ running time of the two recursive calls
- $T(N) = T(i) + T(N - i - 1) + cN$ where c is a constant
- ▣ i : number of elements in S_1

Worst-Case Analysis

- What will be the worst case?
 - ▣ The pivot is the smallest element, all the time
 - ▣ Partition is always unbalanced

$$T(N) = T(N - 1) + cN$$

$$T(N - 1) = T(N - 2) + c(N - 1)$$

$$T(N - 2) = T(N - 3) + c(N - 2)$$

⋮

$$T(2) = T(1) + c(2)$$

$$T(N) = T(1) + c \sum_{i=2}^N i = O(N^2)$$

Best-case Analysis

$$T(N) = 2T\left(\frac{N}{2}\right) + cN$$

$$\frac{T(N)}{N} = \frac{T\left(\frac{N}{2}\right)}{\frac{N}{2}} + c$$

$$\frac{T\left(\frac{N}{2}\right)}{\frac{N}{2}} = \frac{T\left(\frac{N}{4}\right)}{\frac{N}{4}} + c$$

$$\frac{T\left(\frac{N}{4}\right)}{\frac{N}{4}} = \frac{T\left(\frac{N}{8}\right)}{\frac{N}{8}} + c$$

\vdots

$$\frac{T(2)}{2} = \frac{T(1)}{1} + c$$

□ What will be the best case?

- ▣ Partition is perfectly balanced.
- ▣ Pivot is always in the middle (median of the array)



$$\frac{T(N)}{N} = \frac{T(1)}{1} + c \log N$$

$$T(N) = cN \log N + N = O(N \log N)$$

Average-Case Analysis

- Assume
 - ▣ Each of the sizes for S_1 is equally likely
- This assumption is valid for our pivoting (median-of-three) strategy
- On average, the running time is $O(N \log N)$

Reference

- **Algorithm Design: Foundations, Analysis, and Internet Examples.** Michael T. Goodrich and Roberto Tamassia. John Wiley & Sons.
- **Introduction to Algorithms.** Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, Clifford Stein.