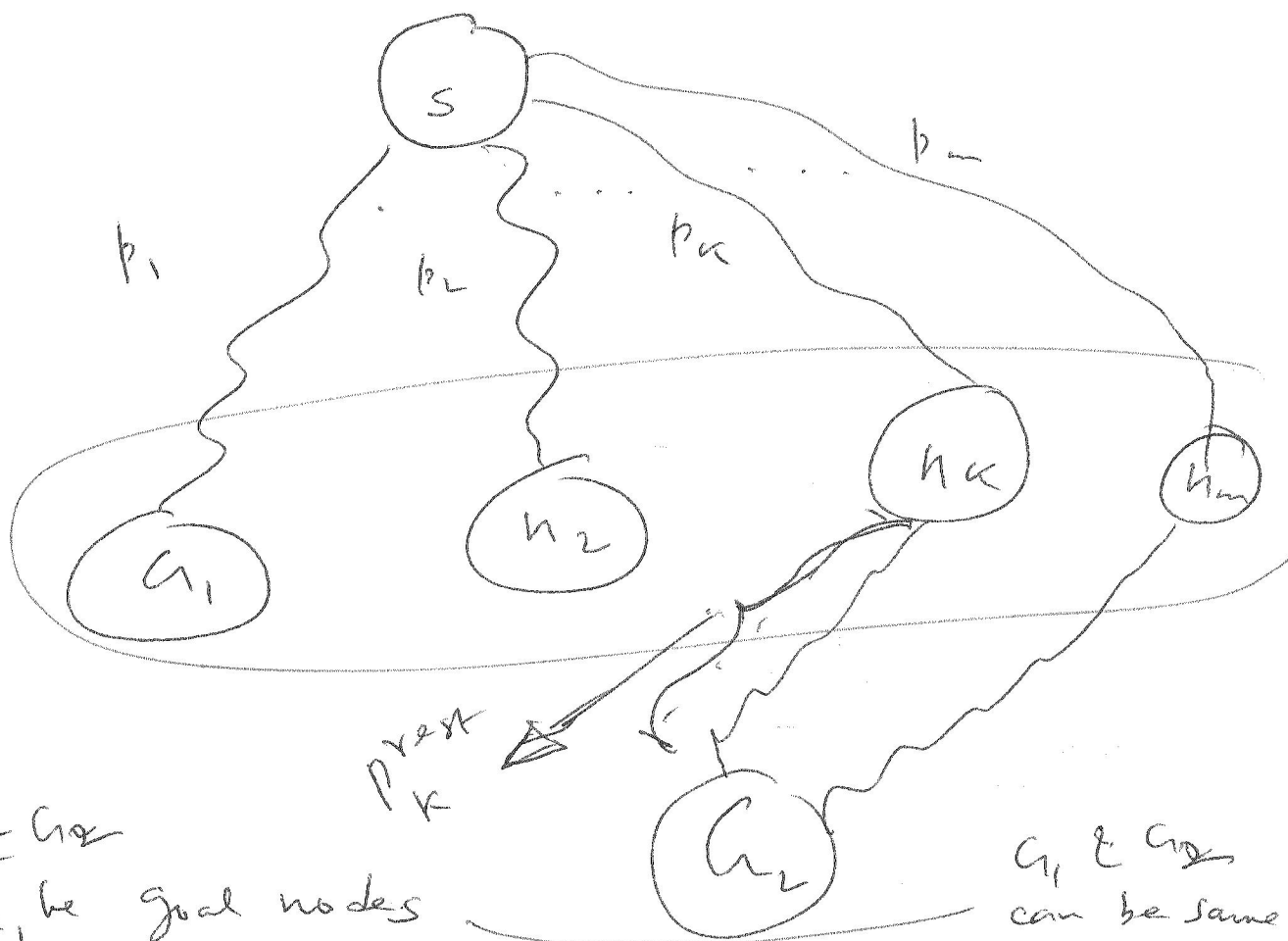


Uniform Search Optimality

Proof



Let n_1 be goal nodes

$C(p_i)$ = cost of path p_i .

Let $C(p_i) = \min \{ C(p_1), C(p_2), \dots, C(p_m) \}$

Each edge cost > 0 .

Let p_k^{rest} = path from n_k to n_2

If $C(p_i)$ is not optimal let

$p_i + p_k^{\text{rest}}$ = optimal path.

$$\text{Let } C_{opt} = \text{Cost} (p_k + p_k^{rent})$$

$$\text{So } C(p_1) > C_{opt}$$

$$> C(p_k) + C(p_k^{rent})$$

$$\downarrow$$

$$> 0$$

$$\text{So } C(p_1) > C(p_k)$$

So algorithm ~~on~~ should have picked ~~p_1~~ p_k instead of p_1 —

a contradiction.

Tree Search (A^* Search)

Let DS denote data structure.

Put start state in DS

Repeat until Solution is found:

1. Pick a node from DS such that it has lowest ~~f~~ f value among all nodes in DS
 2. If node picked is goal then Solution found. & exit.
 3. Otherwise generate its successors & push them in DS with their f values.
-

Graph Search (A^*)

CL - Closed list (or Expanded list)
DS - data Structure.

Put Start State in DS.

Repeat until solution is found.

1. Pick a node say n from DS such that $f(n)$ is the lowest among all nodes in DS.
2. If ~~node~~ n is goal then solution found & exit.
3. Otherwise:
 - (i) Put n in CL.
 - (ii) generate successors of n .
 - (iii) Only insert those successors of n ~~that are not~~ in DS that are not in CL.

Open/Fringe

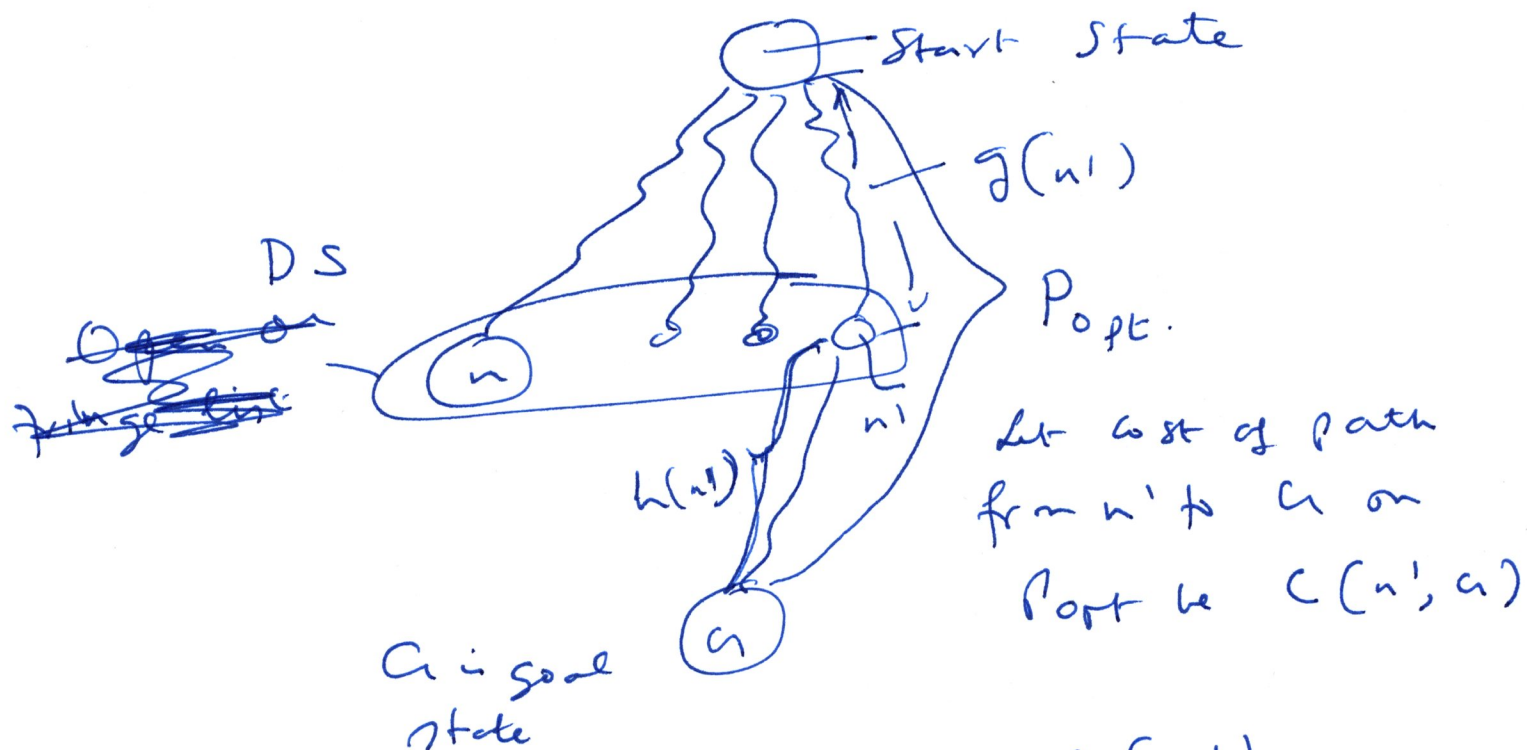
Let C_{opt} be cost of optimal ~~solution~~ solution. DS is data structure. Also called open list or fringe list.

Lemma - If a node n is chosen

for expansion from ~~DS~~ DS

then $f(n) \leq C_{opt}$.

Proof (Sketch) P_{opt} is path whose cost is C_{opt} .



$$f(n) \leq f(n') = g(n') + h(n')$$

By admissibility

$$C(n', n) \geq h(n')$$

$$\therefore f(n') \leq C_{opt} \quad \& \quad \therefore f(n) \leq C_{opt}$$

Defn heuristic h_2 is more ~~informed~~
informed than heuristic h_1
iff $\forall \text{ nodes } n \quad h_2(n) > h_1(n)$

Theorem Any node

Let A_1 be the search tree
constructed by A^* using h_1 . - $A^*(n_1)$
& A_2 be the search tree constructed
by A^* using h_2 . - ~~A^*~~ $A^*(n_2)$

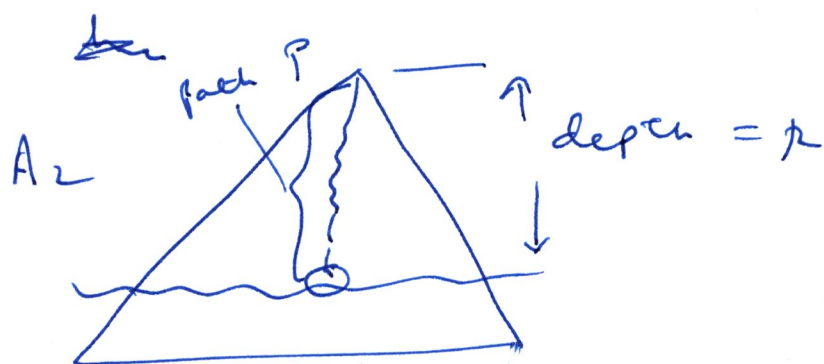
Theorem Any node expanded by
 $A^*(h_2)$ will be expanded by
 $A^*(h_1)$

Proof (Sketch)

Assume by induction that $A_1^*(h_1)$ expands all nodes expanded by $A^*(h_1)$ whose depth in $A_2 \leq R$.

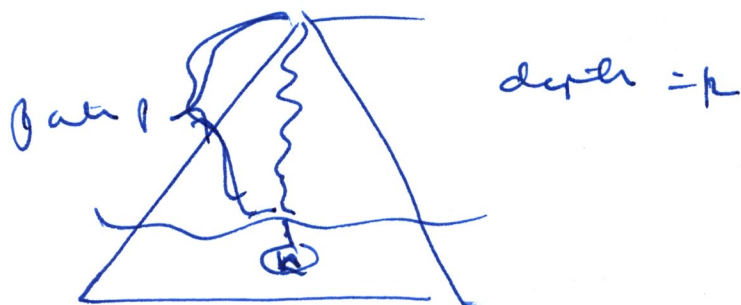
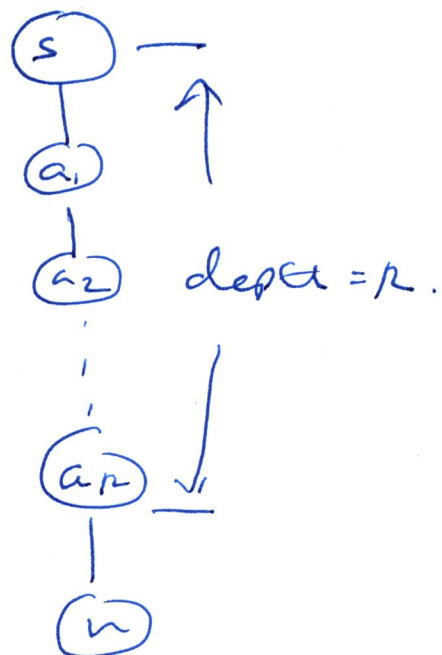
Base If depth = 0 then node expanded is start state in both A_1 & A_2 .

Induction step ~~Assume inductive~~



Assume n is expanded in A_2 but not in A_1 .

Claim: By induction hypothesis P exists in A_1 also.



h is expanded in A_2 but not in A_1 . ~~h~~ n is in DS in A_1 .

So when solution is found:

$$f(n) \leq C_{opt} \text{ in } A_2$$

$$\text{i.e., } h_2(n) + g(n) \leq C_{opt}$$

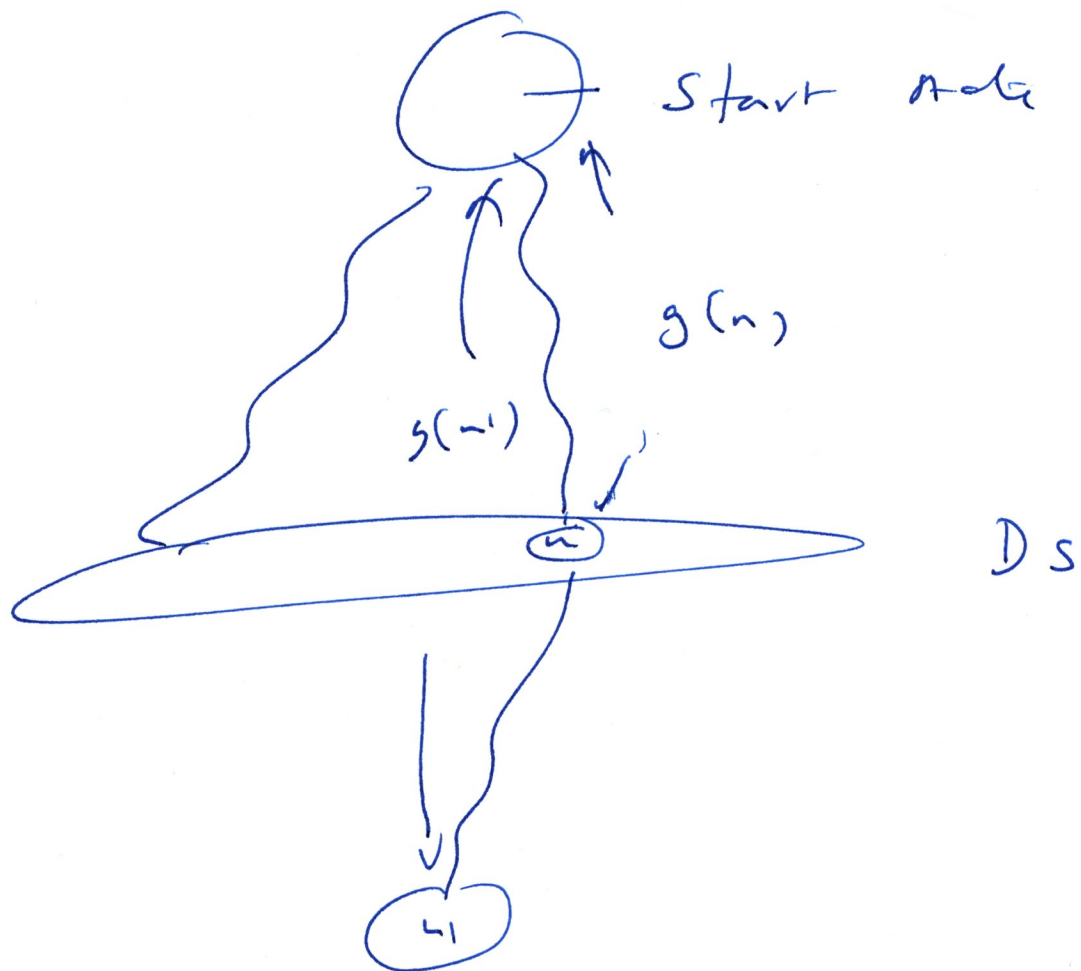
$$\text{But } C_{opt} \leq f(n) \text{ in } A_1 \left(\begin{array}{l} \text{Since} \\ n \in DS \\ \text{in } A_1 \end{array} \right)$$
$$\leq h_1(n) + g(n)$$

$$\therefore h_2(n) \leq h_1(n) -$$

contradiction.

~~g~~

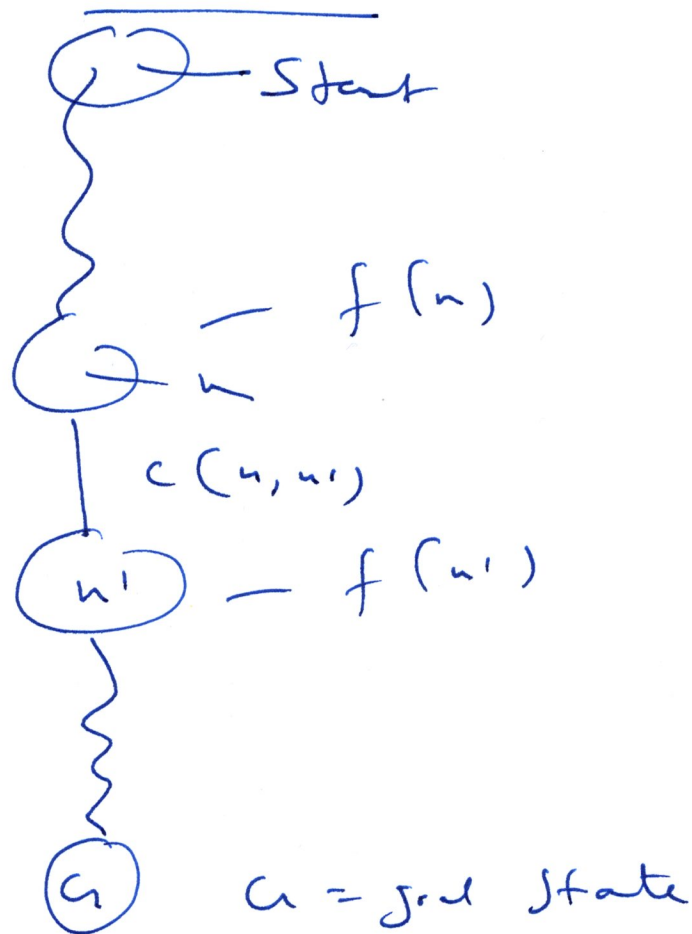
Let's revisit Uniform Cost Search



Path cost based on g monotonically
~~g~~
increases.

i.e. $g(u_1) \geq g(u)$ if
 u appears before u_1 in path
from S . This is because
Cost on edges are non-negative.

How do we ensure this
if we use $f(n)$.



$$f(n) = g(n) + h(n)$$

$$f(n') = g(n') + h(n')$$

We want: $= g(n) + c(n, n') + h(n')$

$$f(n) \leq f(n') \quad \text{is the}$$

$$\therefore h(n) \leq c(n, n') + h(n') .$$