210490131502		Artificial Intelligence
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Aim: Write a program to implement Tic-Tac-Toe game problem.

Code:

```
import numpy as np
import random
from time import sleep
def create_board():
        return(np.array([[0, 0, 0],
                                         [0, 0, 0],
                                         [0, 0, 0]])
def possibilities(board):
        1 = \prod
        for i in range(len(board)):
                for j in range(len(board)):
                        if board[i][j] == 0:
                                 1.append((i, j))
        return(1)
def random_place(board, player):
        selection = possibilities(board)
        current_loc = random.choice(selection)
        board[current_loc] = player
        return(board)
def row_win(board, player):
        for x in range(len(board)):
                win = True
                for y in range(len(board)):
                        if board[x, y] != player:
                                 win = False
                                 continue
                if win == True:
                        return(win)
        return(win)
def col_win(board, player):
        for x in range(len(board)):
                win = True
                for y in range(len(board)):
                        if board[y][x] != player:
                                 win = False
                                 continue
                if win == True:
```

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```
return(win)
        return(win)
def diag_win(board, player):
        win = True
        y = 0
        for x in range(len(board)):
                if board[x, x] != player:
                        win = False
        if win:
                return win
        win = True
        if win:
                for x in range(len(board)):
                        y = len(board) - 1 - x
                        if board[x, y] != player:
                                win = False
        return win
def evaluate(board):
        winner = 0
        for player in [1, 2]:
                if (row_win(board, player) or
                                col_win(board, player) or
                                diag_win(board, player)):
                        winner = player
        if np.all(board != 0) and winner == 0:
                winner = -1
        return winner
def play_game():
        board, winner, counter = create_board(), 0, 1
        print(board)
        sleep(2)
        while winner == 0:
                for player in [1, 2]:
                        board = random_place(board, player)
                        print("Board after " + str(counter) + " move")
                        print(board)
                        sleep(2)
                        counter += 1
                        winner = evaluate(board)
                        if winner != 0:
                                break
        return(winner)
print("Winner is: " + str(play_game()))
```

Case 1:

```
Player 0, enter row and column (e.g., 1 2): 2 2

X | 0 |

------

X | 0 |

------

I | |

-------

Player X, enter row and column (e.g., 1 2): 3 1

X | 0 |

------

X | 0 |

-------

Player X wins!

Process finished with exit code 0
```

Case 2:

Case 3:

```
Player 0, enter row and column (e.g., 1 2): 1 2

0 | 0 | X

------

X | X | 0

------

0 | X |

------

Player X, enter row and column (e.g., 1 2): 3 3

0 | 0 | X

------

X | X | 0

------

It's a tie!

Process finished with exit code 0
```

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Aim: - Write a program to implement BFS (for 8 puzzle problem or Water Jugproblem or any AI search problem).

Code:

```
from collections import deque
def BFS(a, b, target):
m = \{\}
isSolvable = False
path = []
q = deque()
q.append((0,0))
while (len(q) > 0):
       u = q.popleft()
       if ((u[0], u[1]) in m):
                continue
       if ((u[0] > a \text{ or } u[1] > b \text{ or }
               u[0] < 0 \text{ or } u[1] < 0):
                continue
       path.append([u[0], u[1]])
       m[(u[0], u[1])] = 1
       if (u[0] == target or u[1] ==
               target):isSolvable = True
               if (u[0] == target):
                       if (u[1] != 0):
```

```
path.append([u[0], 0])
               else:
                       if (u[0] != 0):
                                path.append([0, u[1]])
               sz = len(path)
               for i in range(sz):
                       print("(", path[i][0], ",",
                                path[i][1], ")")
               break
       q.append([u[0], b])
      q.append([a, u[1]])
       for ap in range(max(a, b) + 1):
                c = u[0] + ap
               d = u[1] - ap
               if (c == a \text{ or } (d == 0 \text{ and } d >=
                       0)):q.append([c, d])
              c = u[0] - ap d
                 = u[1] + ap
               if ((c == 0 \text{ and } c >= 0) \text{ or } d ==
                       b):q.append([c, d])
                       q.append([a, 0])
                       q.append([0, b])
if (not isSolvable):
```

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```
print("No solution")

if __name__ == '__main__':

Jug1, Jug2, target = 4, 3, 2

print("Path from initial state " "to solution state ::")

BFS(Jug1, Jug2, target)
```

```
Path from initial state to solution state ::
(0,0)
(0,3)
(4,0)
(4,3)
(3,0)
(1,3)
(3,3)
(4,2)
(0,2)

...Program finished with exit code 0

Press ENTER to exit console.
```

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Aim: Write a program to implement DFS (for 8 puzzle problem or Water Jug problem or any AI search problem).

Code:

```
def water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1=0, jug2=0,
  visited=set()): if jug1 == target_amount and jug2 == 0:
   return [(jug1,
jug2)
visited.add((jug1,
jug2))
if jug1 < jug1_capacity and (jug1_capacity, jug2) not in visited:
 path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1_capacity,
jug2, visited) if path:
 return [(jug1, jug2)] + path
if jug2 < jug2_capacity and (jug1, jug2_capacity) not in visited:
 path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1,
jug2_capacity, visited) if path:
  return [(jug1, jug2)] +
path if path:
  return [(jug1, jug2)] + path
if jug2 > 0 and (jug1, 0) not in visited:
  path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1, 0,
visited) if path:
   return [(jug1, jug2)] + path
if jug1 > 0 and jug2 < jug2\_capacity:
pour_amount = min(jug1, jug2_capacity - jug2)
path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1 - pour_amount,
jug2 + pour_amount, visited)
if path:
 return [(jug1, jug2)] + path
```

```
pour_amount = min(jug2, jug1_capacity - jug1)

path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1 + pour_amount, jug2 - pour_amount, visited)

if path:
    return [(jug1, jug2)] + path return []

jug1_capacity = 4 jug2_capacity = 3 target_amount = 2

solution = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount) if solution:
    for step, state
    inenumerate(solution):
    print(f"Step{p+1}: {state}")

else:
    print("No solution found.")
```

```
Step 1: (0, 0)
Step 2: (4, 0)
Step 3: (4, 3)
Step 4: (0, 3)
Step 5: (3, 0)
Step 6: (3, 3)
Step 7: (4, 2)
Step 8: (0, 2)
Step 9: (2, 0)
```

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Aim: - Write a program to implement Single Player Game (Using any Heuristic Function)

```
Code:
```

```
import random
def heuristic_guess(low, high):
   return (low + high) // 2
def play_game():
   print("Welcome to the Guessing
   Game!") target_number =
   random.randint(1, 100) low, high = 1,
   100
   attempts = 0
   while True:
guess = heuristic_guess(low, high)
print(f"I guess {guess}")
if guess == target_number:
       print(f"Congratulations! I guessed the number {target_number} in {attempts}
attempts.")
       break
     elif guess < target_number:
       print("Too low!")
  low = guess + 1 else:
       print("Too
       high!") high =
       guess - 1
attempts += 1
if __name__ == "__main__":
   play_game()
```

```
Welcome to the Guessing Game!
I guess 50
Too high!
I guess 25
Too low!
I guess 37
Too high!
I guess 31
Too low!
I guess 34
Too high!
I guess 32
Too low!
I guess 32
Too low!
I guess 33
Congratulations! I guessed the number 33 in 6 attempts.
```

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AIM: Implement A* algorithm.

```
Code:
import heapq
class Node:
  def init (self, state, parent=None, action=None, cost=0, heuristic=0):
     self.state = state
     self.parent = parent
     self.action = action
     self.cost = cost
     self.heuristic = heuristic
  def __lt__(self, other):
     return (self.cost + self.heuristic) < (other.cost + other.heuristic)
def astar(start state, goal state, get neighbors, heuristic):
  open list = []
  closed\_set = set()
  start_node = Node(start_state, None, None, 0, heuristic(start_state, goal_state))
  heapq.heappush(open_list, start_node)
  while open list:
     current_node = heapq.heappop(open_list)
     if current_node.state == goal_state:
       path = []
       while current_node:
          path.append((current_node.state, current_node.action))
          current_node = current_node.parent
       return list(reversed(path))
     closed_set.add(current_node.state)
     for neighbor_state, action, step_cost in get_neighbors(current_node.state):
       if neighbor state in closed set:
          continue
       g score = current node.cost + step cost
       h_score = heuristic(neighbor_state, goal_state)
       f_score = g_score + h_score
       neighbor node = Node(neighbor state, current node, action, g score, h score)
       # Check if the neighbor is already in the open list
       found = False
       for node in open list:
          if node.state == neighbor state:
            found = True
            if g_score < node.cost:
               open list.remove(node)
              heapq.heappush(open_list, neighbor_node)
            break
       if not found:
          heapq.heappush(open_list, neighbor_node)
```

```
return None # No path found
def get_neighbors(state):
  x, y = state
  neighbors = []
  for dx, dy in [(1, 0), (-1, 0), (0, 1), (0, -1)]:
     new_x, new_y = x + dx, y + dy
   if 0 \le \text{new}_x \le \text{len}(\text{grid}) and 0 \le \text{new}_y \le \text{len}(\text{grid}[0]) and \text{grid}[\text{new}_x][\text{new}_y] == 0:
        neighbors.append(((new_x, new_y), f"Move to ({new_x}, {new_y})", 1))
  return neighbors
def manhattan_distance(state, goal):
  x1, y1 = state
  x2, y2 = goal
  return abs(x1 - x2) + abs(y1 - y2)
path = astar(start, goal, get_neighbors, manhattan_distance)
if path:
  for state, action in path:
     print(f"Action: {action}, State: {state}")
else:
  print("No path found.")
```

```
"C:\Users\HP DR0006TX\PycharmProjects\pythonProject11\venv\Scripts\python.exe
Shortest path from A to F: ['A', 'C', 'F']
Process finished with exit code 0
```

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Aim: Write a program to implement mini-max algorithm for any game development.

Code:

```
# A simple Python3 program to
 find# maximum score that
 # maximizing player can
 getimport math
 def minimax (curDepth, nodeIndex,
                maxTurn,
                scores,
                targetDepth):
 # base case : targetDepth
 reachedif (curDepth ==
 targetDepth):
        return scores[nodeIndex]
if (maxTurn):
       return max(minimax(curDepth + 1, nodeIndex * 2,
                             False, scores, targetDepth),
                       minimax(curDepth + 1, nodeIndex * 2
                           + 1,False, scores, targetDepth))
else:
       return min(minimax(curDepth + 1, nodeIndex * 2,
                             True, scores, targetDepth),
                       minimax(curDepth + 1, nodeIndex * 2
                           + 1,True, scores, targetDepth))
 # Driver code
 scores = [3, 5, 2, 9, 12, 5, 23, 23]
 treeDepth = math.log(len(scores), 2)
 print("The optimal value is : ", end = "")
 print(minimax(0, 0, True, scores,
 treeDepth))
 # This code is
 contributed# by
 rootshadow
```

```
The optimal value is: 12

...Program finished with exit code 0

Press ENTER to exit console.
```

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Aim: Assume given a set of facts of the form father (name1, name2) (name1is the father of name2).

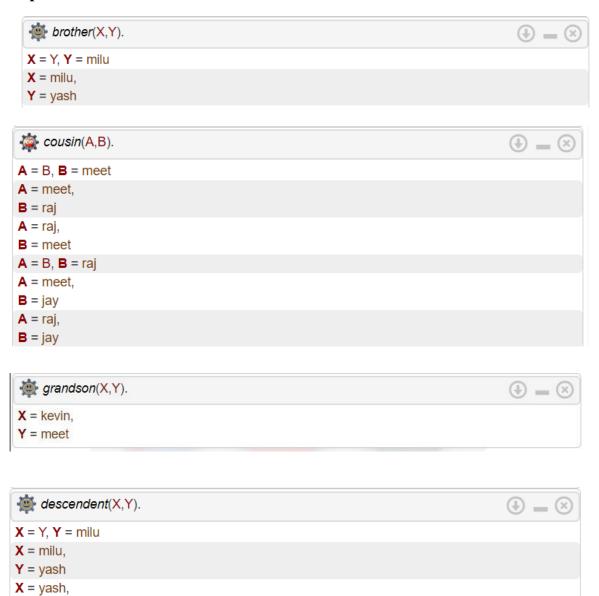
```
Code:
female(pam).
female(liz).
female(pat).
female(ann).
male(jim).
male(bob).
male(tom).
male(peter).
parent(pam,bob).
parent(tom,bob).
parent(tom,liz).
parent(bob,ann).
parent(bob,pat).
parent(pat,jim).
parent(bob,peter).
parent(peter,jim).
mother(X,Y):-parent(X,Y),female(X).
father(X,Y):-parent(X,Y),male(X).
sister(X,Y):-parent(Z,X),parent(Z,Y),female(X),X == Y.
brother(X,Y):-parent(Z,X),parent(Z,Y),male(X),X = Y.
grandparent(X,Y):-parent(X,Z),parent(Z,Y).
grandmother(X,Z):-mother(X,Y),parent(Y,Z).
grandfather(X,Z):-father(X,Y),parent(Y,Z).
wife(X,Y):-
parent(X,Z),parent(Y,Z),female(X),male(Y).
uncle(X,Z):-brother(X,Y),parent(Y,Z).
```



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```
Aim : Define a predicate brother (X,Y) which holds iff X and Y are brothers.
Define a predicate cousin(X,Y) which holds iff X and Y are cousins.
Define a predicate grandson(X,Y) which holds iff X is a grandson of Y.
Define a predicate descendent(X,Y) which holds iff X is a descendent of Y.
Consider the following genealogical tree: father(a,b). father(a,c). father(b,d).
father(b,e). father(c,f).
Say which answers, and in which order, are generated by your
definitions for the following queries in Prolog:
?- brother(X,Y).
?-cousin(X,Y).
?- grandson(X,Y).
?- descendent(X,Y).
Code:
father(kevin,milu).
father(kevin,yash).
father(milu, meet).
father(milu,raj).
father(yash,jay).
brother(X,Y):-father(K,X),father(K,Y).
cousin(A,B):-father(K,X),father(K,Y),father(X,A),father(Y,B).
grandson(X,Y):-father(X,K),father(K,Y).
descendent(X,Y):-father(K,X),father(K,Y).
descendent(X,Y):-father(K,X),father(K,Y),father(X,A),father(Y,B).
```

Y = milu



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Aim: - Write a program to solve Tower of Hanoi problem using Prolog.

Code:

```
move(1,X,Y,\_) := \\ write('Move top disk from '), write(X), write(' to '), write(Y), nl. \\ move(N,X,Y,Z) := \\ N>1, \\ M is N-1, \\ move(M,X,Z,Y), \\ move(1,X,Y,\_), \\ move(M,Z,Y,X). \\ \end{cases}
```

```
SWI-Prolog (AMD64, Multi-threaded, version 8.4.3)
                                                                                  X
                                                                            File Edit Settings Run Debug Help
For online help and background, visit https://www.swi-prolog.org
For built-in help, use ?- help(Topic). or ?- apropos(Word).
% c:/Users/patil/OneDrive/Desktop/pr9.pl compiled 0.00 sec, 2 clauses
     move(4, source, target, auxiliary).
Move top disk from source to auxiliary
Move top disk from source to target
Move top disk from auxiliary to target
Move top disk from source to auxiliary
Move top disk from target to source
Move top disk from target to auxiliary
Move top disk from source to auxiliary
Move top disk from source to target
Move top disk from auxiliary to target
Move top disk from auxiliary to source
Move top disk from target to source
Move top disk from auxiliary to target
Move top disk from source to auxiliary
Move top disk from source to target
Move top disk from auxiliary to target
true
```

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Aim: - Write a program to solve N-Queens problem using Prolog.

Code:

```
% render solutions nicely. use_rendering(chess).

queens(N, Queens) :- length(Queens, N), board(Queens, Board, 0, N, _, _),
queens(Board, 0, Queens).

board([], [], N, N, _, _). board([_|Queens],
[Col-Vars|Board],

Col0, N, [_|VR], VC) :- Col is Col0+1, functor(Vars, f, N),
constraints(N, Vars, VR, VC),

board(Queens, Board, Col, N, VR, [_|VC]). constraints(0, _, _, _) :- !.

constraints(N, Row, [R|Rs], [C|Cs]) :- arg(N, Row, R-C),

M is N-1,
constraints(M, Row, Rs, Cs).
queens([], _, []).
queens([C|Cs], Row0, [Col|Solution]) :- Row is Row0+1,
select(Col-Vars, [C|Cs], Board), arg(Row, Vars, Row-Row), queens(Board, Row, Solution).
```

```
SWI-Prolog (AMD64, Multi-threaded, version 8.4.3)

File Edit Settings Run Debug Help

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For online help and background, visit https://www.swi-prolog.org
For built-in help, use ?- help(Topic). or ?- apropos(Word).

?-

% c:/Users/patil/OneDrive/Desktop/pr10.pl compiled 0.00 sec, 7 clauses
?-

| queens(4,Queens).
Queens = [2, 4, 1, 3],
?- queens(2,Queens).
false.
?- ■
```

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Aim: - Write a program to solve 8 puzzle problem using Prolog.

Code:

goal([1,2,3, 4,0,5, 6,7,8]).

move([X1,0,X3, X4,X5,X6, X7,X8,X9],

[0,X1,X3,X4,X5,X6,X7,X8,X9]).

move([X1,X2,0, X4,X5,X6, X7,X8,X9],

[X1,0,X2, X4,X5,X6, X7,X8,X9]).

move([X1,X2,X3, X4,0,X6,X7,X8,X9],

[X1,X2,X3,0,X4,X6,X7,X8,X9]).

move([X1,X2,X3, X4,X5,0,X7,X8,X9],

[X1,X2,X3,X4,0,X5,X7,X8,X9]).

move([X1,X2,X3, X4,X5,X6, X7,0,X9],

[X1,X2,X3,X4,X5,X6,0,X7,X9]).

move([X1,X2,X3, X4,X5,X6, X7,X8,0],

[X1,X2,X3, X4,X5,X6, X7,0,X8]).

move([0,X2,X3,X4,X5,X6,X7,X8,X9],

[X2,0,X3, X4,X5,X6, X7,X8,X9]).

move([X1,0,X3, X4,X5,X6, X7,X8,X9],

[X1,X3,0, X4,X5,X6, X7,X8,X9]).

move([X1,X2,X3, 0,X5,X6, X7,X8,X9],

[X1,X2,X3,X5,0,X6,X7,X8,X9]).

move([X1,X2,X3, X4,0,X6, X7,X8,X9],

[X1,X2,X3, X4,X6,0, X7,X8,X9]).

move([X1,X2,X3, X4,X5,X6,0,X8,X9],

[X1,X2,X3,X4,X5,X6,X8,0,X9]).

move([X1,X2,X3, X4,X5,X6,X7,0,X9],

[X1,X2,X3,X4,X5,X6,X7,X9,0]).

move([X1,X2,X3, 0,X5,X6, X7,X8,X9],

[0,X2,X3,X1,X5,X6,X7,X8,X9]).

move([X1,X2,X3, X4,0,X6, X7,X8,X9],

[X1,0,X3,X4,X2,X6,X7,X8,X9]).

move([X1,X2,X3, X4,X5,0, X7,X8,X9],

[X1,X2,0, X4,X5,X3, X7,X8,X9]).

move([X1,X2,X3, X4,X5,X6, X7,0,X9],

[X1,X2,X3,X4,0,X6,X7,X5,X9]).

move([X1,X2,X3, X4,X5,X6, X7,X8,0],

[X1,X2,X3, X4,X5,0, X7,X8,X6]).

move([X1,X2,X3, X4,X5,X6, 0,X8,X9],

[X1,X2,X3, 0,X5,X6, X4,X8,X9]).

move([0,X2,X3, X4,X5,X6, X7,X8,X9],

[X4,X2,X3, 0,X5,X6, X7,X8,X9]).

move([X1,0,X3, X4,X5,X6, X7,X8,X9],

[X1,X5,X3, X4,0,X6, X7,X8,X9]).

move([X1,X2,0, X4,X5,X6, X7,X8,X9],

[X1,X2,X6, X4,X5,0, X7,X8,X9]).

move([X1,X2,X3, 0,X5,X6, X7,X8,X9],

[X1,X2,X3, X7,X5,X6, 0,X8,X9]).

move([X1,X2,X3, X4,0,X6, X7,X8,X9],

[X1,X2,X3, X4,X8,X6, X7,0,X9]).

move([X1,X2,X3, X4,X5,0, X7,X8,X9],

[X1,X2,X3,X4,X5,X9,X7,X8,0]). dfsSimplest(S, [S]) :- goal(S).

dfsSimplest(S, [S|Rest]) :- move(S, S2), dfsSimplest(S2, Rest). dfs(S, Path, Path) :-

goal(S). dfs(S, Checked, Path) :- move(S, S2), \+member(S2, Checked), dfs(S2,

[S2|Checked], Path).

```
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?-

% c:/Users/patil/OneDrive/Desktop/prl1.pl compiled 0.00 sec, 29 clauses
?-

| dfs([6,1,3,4,999,5,7,2,0],_,_).

false.
?- ■
```

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Aim: - Write a program to solve 8 puzzle problem using Prolog.

Code:

- edge(a, b, 3).
- edge(a, c, 4).
- edge(a, d, 2).
- edge(a, e, 7).
- edge(b, c, 4).
- edge(b, d, 6).
- edge(b, e, 3).
- edge(c, d, 5).
- edge(c, e, 8).
- edge(d, e, 6).
- edge(b, a, 3).
- edge(c, a, 4).
- edge(d, a, 2).
- edge(e, a, 7).
- edge(c, b, 4).
- edge(d, b, 6).
- edge(e, b, 3).
- edge(d, c, 5).
- edge(e, c, 8).
- edge(e, d, 6).
- edge(a, h, 2).
- edge(h, d, 1).
- len([], 0).
- $len([H|T], N):-len(T, X), N is X+1 . best_path(Visited, Total):- path(a, a, Visited, Total).$
- path(Start, Fin, Visited, Total):-path(Start, Fin, [Start], Visited, 0, Total). path(Start,
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```
Fin, CurrentLoc, Visited, Costn, Total):-
```

edge(Start, StopLoc, Distance), NewCostn is Costn + Distance, \+ member(StopLoc,
CurrentLoc),

path(StopLoc, Fin, [StopLoc|CurrentLoc], Visited, NewCostn, Total).

path(Start, Fin, CurrentLoc, Visited, Costn, Total):-

edge(Start, Fin, Distance), reverse([Fin|CurrentLoc], Visited), len(Visited, Q), (Q\=7 -> Total is 100000; Total is Costn + Distance).

shortest_path(Path):-setof(Cost-Path, best_path(Path,Cost), Holder),pick(Holder,Path). best(Cost-Holder,Bcost-_,Cost-Holder):- Cost<Bcost,!.

 $best(_,X,X)$.

pick([Cost-Holder|R],X):-pick(R,Bcost-Bholder),best(Cost-Holder,Bcost-Bholder,X),!.pick([X],X).

```
SWI-Prolog (AMD64, Multi-threaded, version 8.4.3)

File Edit Settings Run Debug Help

Welcome to SWI-Prolog (threaded, 64 bits, version 8.4.3)

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?-

Warning: C:/users/patil/onedrive/desktop/pr12.pl:1:
Warning: Singleton variables: [H]

% c:/Users/patil/OneDrive/Desktop/pr12.pl compiled 0.00 sec, 33 clauses

?-

| shortest_path(Path).
Path = 20-[a, h, d, e, b, c, a].

?- ■
```