

Probability and Random Process

$$\mu = E(x) \quad \sigma^2 = E[(x - \mu)^2]$$

$$= \int_{-\infty}^{\infty} (x - \mu)^2 p(x) dx$$

Continuous Type Random Variable

1.) Normal (Gaussian) Distribution: =,
 X is a normal or Gaussian random
 with parameters μ and σ^2 its
 density function is given by

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \quad \text{--- (1)}$$

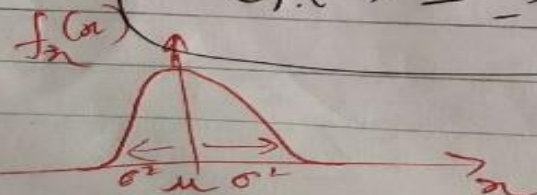
This is a bell-shaped curve,
 symmetric around the parameter
 μ . and its distribution
 function is given by

$$F_X(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-\mu)^2}{2\sigma^2}} dy$$

$$\triangleq G\left(\frac{x-\mu}{\sigma}\right)$$

where the function

$$G(x) \triangleq \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}} dy$$



$$N(\mu, \sigma^2)$$

$\frac{1}{\sqrt{2\pi\sigma^2}}$ is the height of the
 curve's peak.

$\mu \rightarrow$ is the position of the center peak.
 $\sigma \rightarrow$ control the width of the "bell"

Since $f_2(x)$ depends on two parameters μ and σ^2 , the notation $x \sim N(\mu, \sigma^2)$ will be used to represent the Gaussian ^{or normal} p.d.f.

The constant $\sqrt{2\pi\sigma^2}$ in (1) is the normalization constant that maintains the area under $f_n(x)$ to unity. (How proof it)

The special case $x \sim N(0, 1)$ is often referred to as the standard normal random variable.

^{normalization}
(Maxwell \Rightarrow velocity of molecules $N(\mu, \sigma^2)$)

& Hazen \Rightarrow theory of error \Rightarrow error is $N(\mu, \sigma^2)$
 \times In Signal Processing they serve to define gaussian filters.

Page - 90

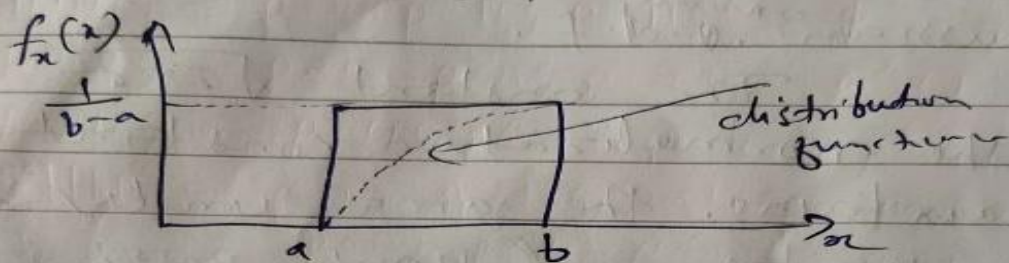
Uniform distribution

98 Conditional distribution

cc = 1.1

Uniform Distribution \Rightarrow

X is said to be uniformly distributed in the interval (a, b) , $-\infty < a < b < \infty$, if



eg:- Uniform density function

$$\text{if } f_X(x) = \begin{cases} \frac{1}{b-a} & ; a \leq x \leq b \\ 0 & ; \text{otherwise} \end{cases}$$

The distribution function of X is

$$F_X(x) = \begin{cases} 0 & ; x < a \\ \frac{x-a}{b-a} & ; a \leq x \leq b \\ 1 & ; x \geq b \end{cases}$$

The Binomial Probability Law

A Bernoulli trial involves performing an experiment once and noting whether a particular event A occurs. The outcome of the Bernoulli trial is said to be a "success" if A occurs and a "failure" otherwise.

We will view the outcome of a single Bernoulli trial as the outcome of a toss of a coin for which the probability of head (success) is $p = P(A)$. The probability of k successes in n Bernoulli trial is then equal to the probability of k heads in n tosses of the coin.

Ex 1 \Rightarrow Suppose that a coin is tossed three times. If we assume that the tosses are independent and the probability of heads is p , then the probability for the sequences of heads and tails is -

$$P\{HHH\} = P\{HH\} P\{H\} P\{H\} = p^3$$

$$P\{HHT\} = P\{HH\} P\{H\} P\{T\} = p^2(1-p)$$

$$P\{HTH\} = P\{HT\} P\{H\} P\{H\} = p^2(1-p)$$

$$P\{TTH\} = P\{TT\} P\{H\} P\{H\} = p^2(1-p)$$

$$P\{HTT\} = P\{HT\} P\{T\} P\{T\} = p(1-p)^2$$

$$P\{THT\} = P\{TH\} P\{H\} P\{T\} = p(1-p)^2$$

$$P\{TTT\} = P\{TT\} P\{T\} P\{T\} = p(1-p)^2$$

$$P\{TTT\} = p(1-p)^3$$

Let K be the number of heads in three trials, then

$$P[K=0] = P\{TTT\} = (1-p)^3$$

$$P[K=1] = P\{TTH, THT, HTT\} = 3p(1-p)^2$$

$$P[K=2] = P\{HHT, HTH, THH\} = 3p^2(1-p)$$

$$P[K=3] = P\{HHH\} = p^3$$

Theorem: let k be the number of successes in n independent Bernoulli trials, then the probabilities of k are given by the binomial probability law:

$$P_n(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

for $k = 0, 1, \dots, n$

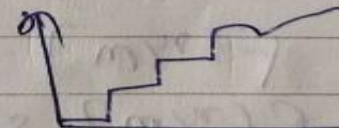
where $P_n(k)$ is the probability of k successes in n trials, and

$$\binom{n}{k} = \frac{n!}{k! (n-k)!}$$

$n!$ factorial $n! = n(n-1) \dots (2)(1)$.
 $0! = 1$

Poisson - Binomial distribution

$$P(Y=k) = \frac{e^{-\lambda} \lambda^k}{k!}$$



Standard distribution

See by yourself

- 1 -> Poisson distribution
- 2 -> Gamma distribution
- 3 -> chi-square
- 4 -> Rayleigh

5 -> Beta

1. Let A in \mathcal{A} be identified as the event $\{X \leq x\}$ for the random variable X . The resulting probability $P\{X \leq x | M\}$ is defined as the conditional distribution function of X , which we denote $F_x(\frac{x}{m})$.

Conditional Distribution: \Rightarrow

We know that the probability of an event A assuming M is given by

$$P(A|M) = \frac{P(A \cap M)}{P(M)} \quad \text{where } P(M) \neq 0$$

\hookrightarrow 2. The conditional distribution $F(x/m)$ of a random variable X , assuming M is defined as the conditional probability of the event $\{X \leq x\}$,

$$F(x/m) = P\{X \leq x | M\} = \frac{P\{X \leq x, M\}}{P(M)}$$

Here $\{X \leq x, M\}$ is the intersection of the events $\{X \leq x\}$ and M , that is, the event consisting of all outcomes ω such that $X(\omega) \leq x$ and $\omega \in M$.

So $F(x/m)$ is same as $F_x(x)$

So $P(x/m)$ should follow all properties of $F(x)$

$$1) F\left(\frac{\infty}{m}\right) = 1 \quad \& \quad F\left(-\frac{\infty}{m}\right) = 0$$

$$2) P\{x_1 < x \leq x_2\} = F\left(\frac{x_2}{m}\right) - F\left(\frac{x_1}{m}\right)$$

The conditional density $f(x/m)$ is the derivative of $F(x/m)$

$$f(x/m) = \frac{d}{dx} \left(F\left(\frac{x}{m}\right) \right)$$

The function is non-negative & its area equals 1.

Ex 1 ~~Ex 1~~ Determine the conditional $f(x/m)$ of the random variable $X(f_i) = 10i$ of the fair-die experiment, where $m = \{f_2, f_4, f_6\}$ is the event "even".

$$\text{Soln} \quad S = \{f_1, f_2, \dots, f_6\}$$

$$X = 10i$$

$$S_x = \{10, 20, 30, \dots, 60\}$$

if $x \geq 60$, then $\{x \leq a, m\} = \Omega$

$$F(x/m) = \frac{p(x \leq 60, m)}{p(m)} = \frac{p(f_2, f_9, f_6)}{p(m)} = \frac{p(m)}{p(m)} = 1$$

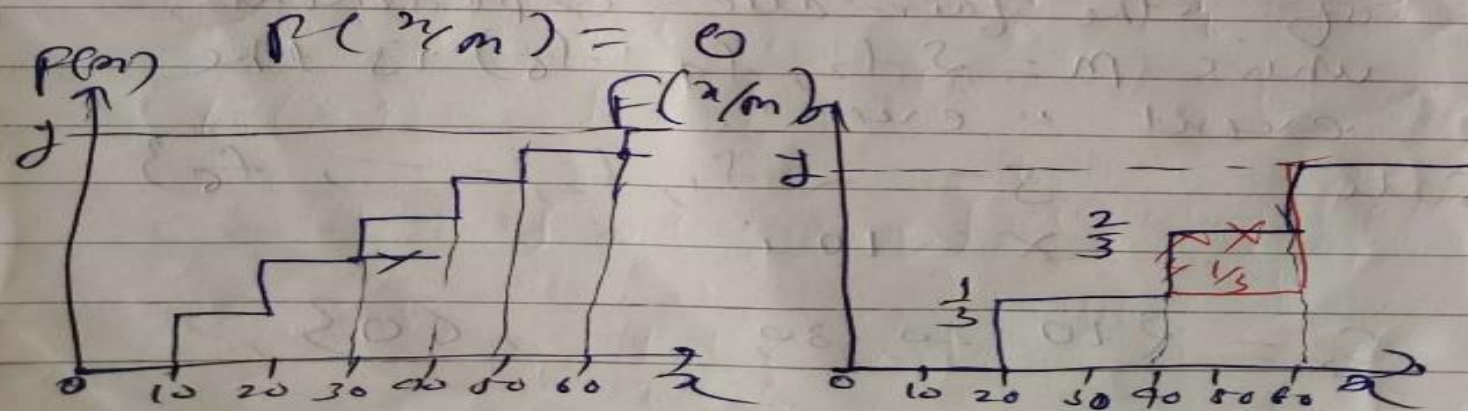
if $40 \leq a < 60$, then $\{x \leq a, m\} = \{f_2, f_9\}$

$$F(x/m) = \frac{p(\{f_2, f_9\})}{p(m)} = \frac{2/6}{3/6} = \frac{2}{3}$$

if $20 \leq a < 40$ then $\{x \leq a, m\} = \{f_2\}$

$$F(x/m) = \frac{p(f_2)}{p(m)} = \frac{1/6}{3/6} = \frac{1}{3}$$

if $a < 20$, then $\{x \leq a, m\} = \emptyset$



total probability

$$P(B) = P(B/A_1)P(A_1) + \dots + P(B/A_n)P(A_n)$$

• substitute $B = \{x \leq a\}$

$$f(x) = F(x/A_1)P(A_1) + \dots + F(x/A_n)P(A_n)$$

Bay's theorem:

$$f(x) = f(x/A_1)P(A_1) + \dots + f(x/A_n)P(A_n)$$

A_1, A_2, \dots form a partition of S .

Bay's theorem

$$P(B/A) = \frac{P(A/B) \cdot P(B)}{P(B)}$$

$$P(A_i/B) = \frac{P(B/A_i)P(A_i)}{P(B)}$$

if $B = \{x \leq a\}$

$$P(A_i/x=a) = \frac{P(\frac{x \leq a}{A_i}) \cdot P(A_i)}{P(x \leq a)}$$

$$\Rightarrow P(\frac{A}{x=a}) = \frac{f(x/A_i)P(A_i)}{f(x)}$$

mean (or expected value) and variance:

mean (or expected value) \Rightarrow the ^{mean (or exp)} $E\{X}$ of a random variable X is by definition the integral

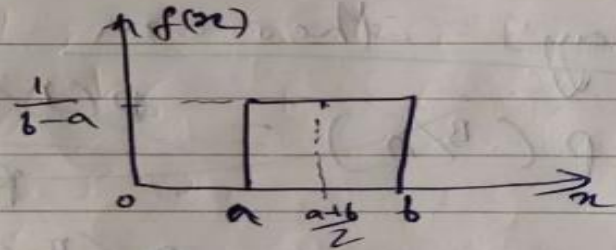
$$E\{X\} = \int_{-\infty}^{\infty} x f(x) dx \quad \text{--- (1)}$$

\bar{x} is a number & denoted by \bar{x} or μ (or central tendency)

Ex. If X is uniform in the interval (a, b) find the mean.

Soln. \Rightarrow

$$f(x) = \begin{cases} 0 & x < a \\ \frac{1}{b-a} & a \leq x \leq b \\ 0 & x > b \end{cases}$$



$$E(X) = \int_{-\infty}^{\infty} x f(x) dx$$

$$= \int_{-\infty}^a x f(x) dx + \int_a^b x f(x) dx + \int_b^{\infty} x f(x) dx$$

$$= 0 + \frac{1}{b-a} \int_a^b x dx + 0$$

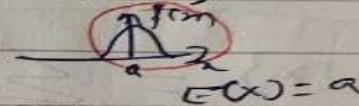
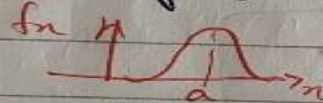
$$= \frac{1}{b-a} \left[\frac{x^2}{2} \right]_a^b = \frac{1}{2(b-a)} [b^2 - a^2]$$

$$= \frac{b+a}{2} \quad (\because a^2 - b^2 = (a-b)(a+b))$$

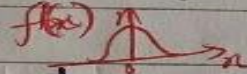
$$= \frac{a+b}{2}$$

we have note: \Rightarrow note: \Rightarrow

1. \Rightarrow If the vertical line $x=a$ is an axis of symmetry of $f(x)$ then $E\{x\} = a$.



2. \Rightarrow If $f(-x) = f(x)$, then $E\{x\} = 0$.



Discrete type \Rightarrow for discrete ^{type random} variables the integral can be written as a sum.

Suppose

$$E\{x\} = \sum_i p_i x_i \quad ; \quad p_i = P\{x = x_i\}$$

proof from eqn ① Suppose that x takes the values x_i with probability p_i . In this case

$$f(x) = \sum_i p_i \delta(x - x_i)$$

so

$$E\{x\} = \int_{-\infty}^{\infty} x \sum_i p_i \delta(x - x_i) dx$$

$$= \sum_i p_i \int_{-\infty}^{\infty} x \delta(x - x_i) dx$$

we know that

$$\int_{-\infty}^{\infty} x \delta(x - x_i) dx = x_i$$

$$(e.g. \int_{-\infty}^{\infty} 5 \cdot \delta(x - 5) dx = 5)$$

$$\int_{-\infty}^{\infty} \delta(x) dx = 1$$

$$E\{x\} = \sum_i p_i x_i$$

Ex If x takes the values 1, 2, ..., 6 with probability $\frac{1}{6}$ find $E\{x\}$.

$$\text{Sol: } E(x) = \sum_i p_i x_i$$

$$= \frac{1}{6} [1 + 2 + \dots + 6]$$

$$= 3.5$$

Conditional mean \Rightarrow The conditional mean of a random variable x assuming an event m is given by the index

$$\text{then } E\{x/m\} = \int_{-\infty}^{\infty} x f(x/m) dx$$

for discrete type random variable

$$E\{X/m\} = \sum_i x_i p\{X=x_i\}$$

properties of mean or expectation (E)

1) Linearity In particular, if $E(Y) = E(ax + b)$

then $E\{Y\} = aE\{X\} + b$ ($\because E\{ax\} = aE\{X\}$)

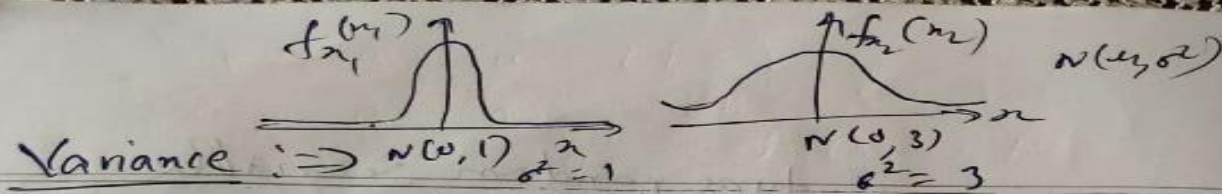
$(Y = g(X))$

OR $E[c_1 g_1(X) + c_2 g_2(X) + \dots] = c_1 E[g_1(X)] + c_2 E[g_2(X)] + \dots$

2. Complex random variable

if $Z = X + jY$, then

$$E\{Z\} = E\{X + jY\} \\ = E\{X\} + jE\{Y\}$$



Variance $\Rightarrow N(0, 1)$ $\sigma^2 = 1$

see note page 194

For a random variable X with mean μ , $X - \mu$ represents the deviation of the random variable from its mean. Since this deviation can be either positive or negative; consider the quantity $(X - \mu)^2$, and its average value $E[(X - \mu)^2]$ represents the average square deviation of X around its mean.

Define $\sigma_x^2 \triangleq E[(X - \mu)^2] > 0$

$$= \int_{-\infty}^{\infty} (x - \mu)^2 f_x(x) dx > 0$$

σ_x^2 is variance of random variable X
 σ_x is standard deviation of X .

Skewness \Rightarrow skewness is usually described as a measure of a dataset's symmetry - or lack of symmetry. [A perfectly symmetrical data set will have a skewness of 0. The normal distribution has a skewness of 0.]

The skewness is defined as

$$S \text{ or } \mu_3 = \frac{\sum (X_i - \bar{x})^3}{N \sigma^3}$$

where N is the sample size, X_i is the i th X value, \bar{x} is mean of X , σ is the sample standard deviation.