# COMP-261 Computer Organization and Assembly Language Fall Semester 2021

# **Simple Microprocessor Design**

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## 1 Introduction

This document gives an introduction to a simple microprocessor architecture based on MIPS microprocessor. The goal of the project is to build a 4-bit processor at logic level and then simulate the processor at layout level. This document introduces the basic concepts of microprocessor architecture in the simplest possible way with a custom-defined instruction set. The design of the processor is very primitive, but already quite complex, as shown in Figure 1-1.

#### 1.1 Objective

The objective and goal of this project is to Reproduce all basic building blocks of the RISC based microprocessor in order to design a complete data-path and control unit. Later to test the working of the processor, it is required to design a simple program to test the working of components as well as the microprocessor itself.

The tasks of the project are:

- Design of building blocks of microprocessor, which consist of; ALU, Program Memory, Data Memory, Register File, Program Counter.
- ii. Design of Instruction Formats, which includes: R-Format, I-Format, J-Format.
- iii. Design of Data-path, connecting microprocessor blocks as per the designed instruction formats.
- iv. Design of the Control Unit.
- v. Construction of test program.

#### 1.2 Deliverables

- i. Logisim file containing all components, from Half Adder till the final design.
- ii. Verilog/VHDL files of each component which demonstrate the working of the microprocessor.

#### 1.3 Submission

Details of submission will be notified later.

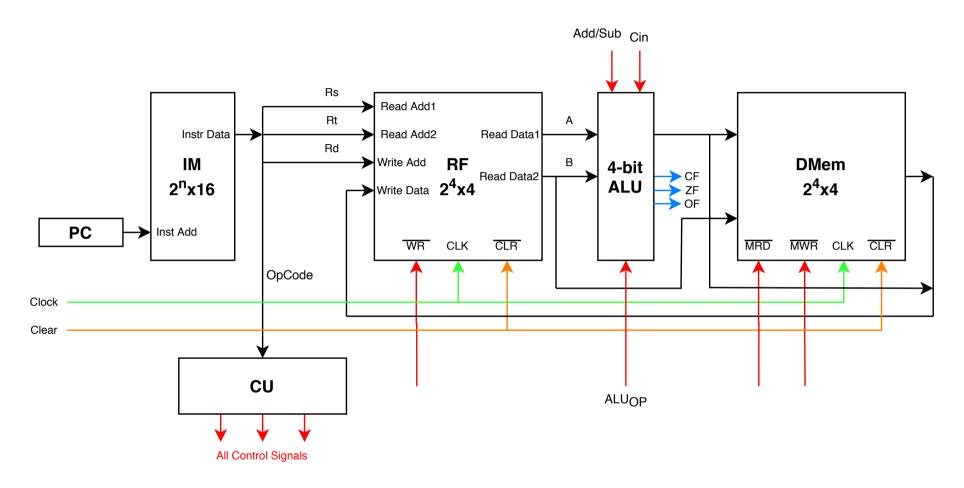


Figure 1-1. Abstract Design of a Simple Single Cycle RISC Microprocessor

# 2 Design of Microprocessor

The design of simple processor architecture consists of:

#### 2.1 Instructions

- Memory reference instructions: LW (Load Word), SW (Store Word).
- Arithmetic-Logical instructions: AND, OR, ADD, SUB, SLT (Set Less Than).
- Control flow instructions: BEQ (Branch equal), BNE (Branch not equal), J (Jump).

#### 2.2 Generic Implementation

- Use Program Counter (PC) to supply instruction address.
- Get the instruction from the Memory (also called as, Instruction memory or Program memory).
- Read Registers from Register File.
- Use the instruction to decide exactly what to do.
- All instructions use the ALU after reading the registers.

#### 2.3 Functional units

- Elements that operate on data values (Combinational)
  - Example: Instruction Memory (IM), Adder, ALU, Control Unit, Multiplexers etc.
- Elements that contain state (Sequential)
  - O Examples: Data Memory (DMEM), Register File, Program Counter (PC).

# 3 Building Blocks of Microprocessor

#### 3.1 Program Counter

A Program Counter (PC) is a 4-bit register and PC will start from 0000 to 1111.

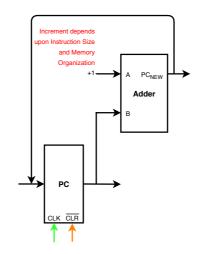


Figure 3-1. Block Diagram of Program Counter

#### 3.2 Memory

There are two types of memories; ROM based Instruction Memory (IM) to store instructions and RAM based Data Memory (DMEM) to hold data.

#### 3.2.1 Instruction Memory

• Instruction memory takes address from PC and supplies instruction data.

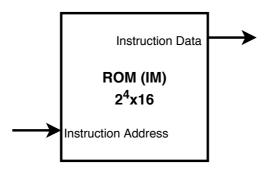


Figure 3-2. Block Diagram of Instruction Memory

#### 3.2.1.1 ROM Specifications

Table 3-1. Specifications of Instruction Memory (ROM)

Type Description				
Size	$2^4x16$			
	Total memory addresses are 16.			
	Each memory address can hold data of 16 bits (instruction size).			

Type	Description			
Input Instruction Address requires 4-bit address lines to access memory address.				
Output	<b>Instruction Data</b> is of 16 bits and requires 16-bit data output lines to fetch each instruction.			

# 3.2.2 Data Memory

- Data memory takes address and supply data for LW.
- Data memory takes address and data and write into the memory for SW.

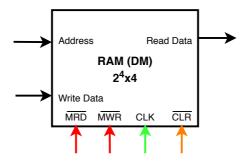


Figure 3-3. Block Diagram of Data Memory

#### 3.2.2.1 RAM Specifications

Table 3-2. Specifications of Data Memory (RAM)

Type	Description		
Size	$2^4x4$		
	Total memory addresses are 16.		
	Each memory address can hold data of 4 bits (data size).		
Control Inputs	<ul> <li>MRD is an active low input; when 0 (reading mode). Data memory contents designated by the Address input is put on the Read Data output.</li> <li>MWR is an active low input; when 0 (writing mode). Data memory contents designated by the Address input is replaced by the value on the Write Data input.</li> <li>CLR is an active low input; when 0 all memory will be cleared.</li> </ul>		
Input	Address requires 4-bit address lines to access any memory address.  Write Data requires 4-bit data lines to write on memory address		
0.44	specified by Address input.		
Output	<b>Read Data</b> is of 4 bits and requires 4-bit data output lines.		

## 3.3 Register File

A Register File to include registers; 4 general-purpose registers of 2-bit each.

- It requires two operands and write a result back in register file.
- Sometimes part of operands comes from the instructions.
- Support of immediate class of instructions.

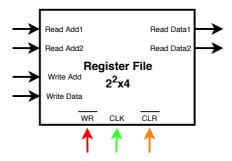


Figure 3-4. Block Diagram of Register File

#### 3.3.1 Register File Specifications

Table 3-3. Description of Register File Input/output Pins

Type	Description			
Size	$2^4x4$			
	Total number of registers are 4 and accessed using 2-bit address; e.g. $R0 = 000, R1 = 001,, R7 = 111.$			
	Each register can hold data of 4 bits.			
Control Inputs	$\overline{WR}$ is an active low input; when 0 (writing mode) and when 1 (reading mode).			
	$\overline{CLR}$ is an active low input; when 0 all registers data will be cleared.			
Input	<b>ReadAdd1</b> , <b>ReadAdd2</b> , <b>WriteAdd</b> requires 2-bit address lines to access specific registers.			
If $\overline{WR} = 1$ and $CLK = 1$ , then based on the $ReadAdd1$ , $ReadAdd$ addresses, the register file will generate outputs.				
	If $\overline{WR} = 0$ and $CLK = 0$ , then based on the $WriteAdd$ address the data present on $WriteData$ lines will be written on the specific register.			
Output	WriteData1, WriteData2 are 4-bit data output lines.			

#### 3.4 Arithmetic and Logical Units

An ALU will be composed of following units:

• Logical Unit: AND, OR.

• Arithmetic Unit: ADD, SUB.

# • Comparator: SLT.

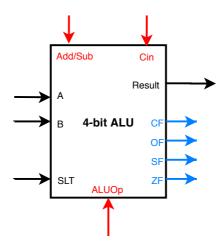


Figure 3-5. Block Diagram of 4-bit ALU

# 3.4.1 ALU Specifications

Table 3-4. Specifications of 4-bit ALU

Type	Description			
Input	A and B are 4 bits each. SLT is a single bit.			
Output	<b>Result</b> is of 4 bits.			
Control Signals	Add/Sub and Cin are single bit. ALUOp is 2 bits select line of 4x1 MUX, where:			
	00 – Connects AND gate output to Result			
	01 – Connects OR gate output to Result			
	10 – Connects FA to Result			
	11 – Connects SLT to Result			
Status Flags	Each flag is of 1 bit each.			
	CF – Carry Flag			
	<b>OF</b> – Overflow Flag			
	<b>SF</b> – Sign Flag			
	<b>ZF</b> – Zero Flag			

#### 4 Instruction Format

The simple microprocessor uses 16-bit instructions that are stored in the Instruction Memory. There are three types of instruction formats:

#### 4.1 Register to Register (R-Format) Instructions

- Instructions
  - o AND, OR, ADD, SUB, SLT
- Process
  - o Read source operands from Registers
  - o Execute operation (AND, ADD etc.) in ALU
  - Write result back to Registers

Unused	OpCode	Rs	Rt	Rd	
15:12	11:8	7:6	5:4	3:2	1:0

#### 4.2 Immediate (I-Format) Instructions

#### 4.2.1 Arithmetic Instructions

Instructions: ANDi, ORi, ADDi, SUBi, SLTi

#### **Process:**

- Read first source operand from Registers
- Read second source operand from Instruction
- Execute operation (Or, ADD etc.) in ALU
- Write result back to Registers

Unused	OpCode	Rs	Rt	Immediate Data (IMD)
15:12	11:8	7:6	5:4	3:0

#### 4.2.2 Memory Reference Instructions

Instruction: LW (Load Word) Instruction

#### **Process:**

• Read first source operand from Registers

- Read second source operand from Instruction
- Execute operation (**ADD**) in ALU to calculate DMEM address
- Read word from Data Memory
- Write result back to Registers

Unused	OpCode	Rs	Rt	Immediate Address (IMA)
15:12	11:8	7:6	5:4	3:0

Instruction: SW (Store Word) Instruction

#### **Process:**

• Read first source operand from Registers

• Read second source operand from Instruction

• Read data from Registers

• Execute operation (**ADD**) in ALU to calculate DMEM address

• Write word to Data Memory

Unused	OpCode	Rs	Rt	Immediate Address (IMA)
15:12	11:8	7:6	5:4	3:0

#### 4.2.3 Branch Instructions

Instructions: BEQ, BNE

#### **Process:**

• Read source operands from Registers

• Execute operation (SUB) in ALU to identify ZF

• For BEQ: If ZF = 1, then PC + 1 + Offset otherwise PC + 1

• For BNE: If ZF = 0, then PC + 1 + Offset otherwise PC + 1

Unused	OpCode	Rs	Rt	Immediate Offset	
15:12	11:8	7:6	5:4	3:0	

# 4.3 Jump (J-Format) Instructions

# Instruction: J

## **Process:**

• Load new PC with address specified within instruction: **PC** = **Address**.

Unused	OpCode	Unused	Address
15:12	11:8	7:4	3:0

# 5 Types of Instructions

#### **Data Operations:**

- Arithmetic (ADD, SUB, ADDi, SUBi)
- Logical (AND, OR, ANDi, ORi)

#### **Data Transfer:**

- Load (LW) Memory to Register
- Store (SW) Register to Memory

#### **Sequencing:**

- Branch (Conditional, e.g., <, >, ==)
- Jump (Conditional, e.g., j)

Assume that all registers initially store the numeric value 0, and Rs, Rt, Rd can refer to any register within Register File. The microprocessor you have to design will have the following types of instructions:

Table 5-1. Types of Instructions (Examples)

Function	OpCode	Type	Instruction	Operation
AND	0000	R	AND Rd, Rs, Rt	Rd = Rs & Rt
OR	0001	R	OR Rd, Rs, Rt	$Rd = Rs \mid Rt$
ADD	0010	R	ADD Rd, Rs, Rt	Rd = Rs + Rt
SUB	0011	R	SUB Rd, Rs, Rt	Rd = Rs - Rt
ANDi	0100	I	ANDi Rt, Rs, IMD	Rt = Rs & IMD
ORi	0101	I	OR Rt, Rs, IMD	$Rt = Rs \mid IMD$
ADDi	0110	I	ADD Rt, Rs, IMD	Rt = Rs + IMD
SUBi	0111	I	SUB Rt, Rs, IMD	Rt = Rs - IMD
SLT	1000	R	SLT Rd, Rs, Rt	if (Rs < Rt) then Rd=1 else Rd=0
SLTi	1001	I	SLT Rt, Rs, IMD	if (Rs < IMD) then Rt=1 else Rt=0
BEQ	1010	I	BEQ Rt, Rs, Offset	if (Rs == Rt) then goto PC+1+ Offset
BNE	1011	I	BNE Rt, Rs, Offset	if (Rs != Rt) then goto PC+1+ Offset
J	1100	J	J Address	Goto PC = Address
Unused	1101			
LW	1110	I	LW Rt, IMA(Rs)	Rt = DMEM[Rs + IMA]
SW	1111	I	SW Rt, IMA(Rs)	DMEM[Rs + IMA] = Rt

# 6 Digital Circuit Design

#### 6.1 ALU Design (4-bit)

The core of the processor - all the actual computations are performed here. As shown in the instruction set, operations such as addition, subtraction and logical operations are all done in this unit. Also, the output of the ALU is used as the address for certain memory related operations. The block diagram of 4-bit ALU is mentioned above in the Figure 3-5.

An hierarchical approach is used to design the 4-bit ALU, starting from gates to construct Half Adder (HA), and then using two HAs to design Full Adder (FA), as shown in Figure 6-1, and then arithmetic unit (for addition and subtraction operations) and lastly logical component (of AND and OR gate operations) is integrated to design 1-bit ALU, as shown in Figure 6-2. By using 4 1-bit ALUs, 4-bit ALU is designed, as shown in Figure 6-3.

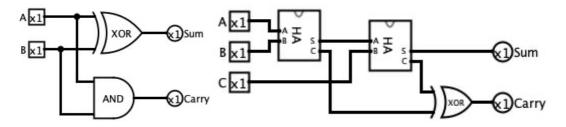


Figure 6-1. Digital Circuits of Half Adder and Full Adder

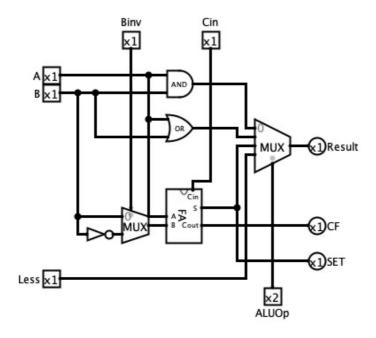


Figure 6-2. Digital Circuit of 1-bit ALU

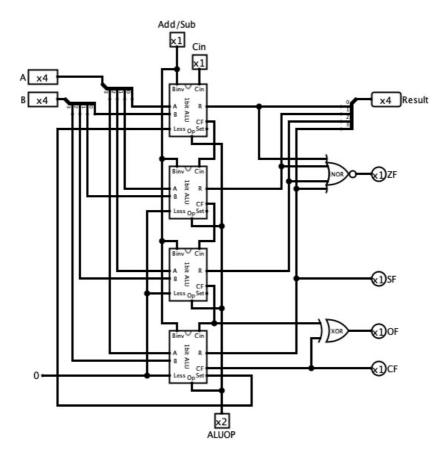


Figure 6-3. Digital Circuit of 4-bit ALU

As mentioned above, the ALU is able to execute the following operations:

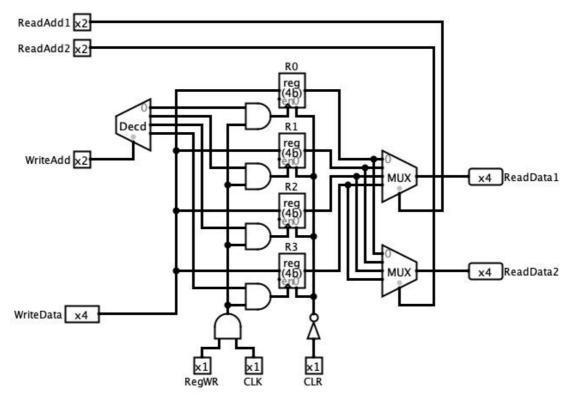
Table 6-1. Verification of ALU Working

	Inp	outs		Cont	rol Inputs	Output		Status	Flags		
Operation	A B		ALUOp [A1A0]		Add/Sub (as Binv)	Cin	Result	CF	OF	SF	ZF
AND	1010	0110	0	0	X	x	0010	Х	х	х	Х
OR	0010	1000	0	1	X	X	1010	X	х	Х	X
ADD	0011 (+3)	0011 (+3)	1	0	0	0	0110 (+6)	0	0	0	0
ADD	1101 (-3)	0111 (+7)	1	1 0	0	0	0100 (+4)	1	0	0	0
SUB	1100 (-4)	0001 (+1)	1	0	1	1	1011 (-5)	1	0	1	0
SUB	0111 (+7)	0111 (+7)	1	0	1	1	0000 (0)	1	0	0	1
SUB	1000 (-8)	0001 (+1)	1	0	1	1	0111 (x)	1	1	0	0
SLT	0011 (+3)	0010 (+2)	1	1	1	1	If A <b, 0<br="" then="">0000</b,>	1	0	0	1
SLT	0011 (+3)	0110 (+6)	1	1	1	1	If B <a, 1<br="" then="">0001</a,>	0	0	0	0

Rebuild the similar ALU in Logisim and verify it's working.

#### 6.2 Register File $(2^4x4)$

Consider the block diagram of Register File (RF) as mentioned above in the Figure 3-4. The RF is a set of 4 registers: named as R0, R1, R2, R3, each storing a 4-bit value. There are 2 output values ReadData1 and ReadData2, whose values are selected based on the instruction fields: Rs (ReadAdd1) and Rt (ReadAdd2), as in the instruction definitions given above by giving control signal (RegWR = 1). There is one port by which data can be written into by one of the register Rd (WriteAdd), but make sure to provide a control signal (RegWR = 0) to control whether or not to update the value. The clear signal  $\overline{CLR}$  is to clear the contents of RF.



Registers trigger is on CLK Falling Edge

Figure 6-4. Digital Circuit of Register File

In Logisim, D-Flip Flops or Register component (*trigger is on CLK Falling Edge*) can be used to create Register File, as shown in the Figure 6-4.

Rebuild the similar Register File in Logisim and verify it's working.

Table 6-2. Verification of Register File Working

Operation	Inputs			Co	ontrol Input	Outputs			
Operation	ReadAdd1	ReadAdd2	WriteAdd	WriteData	RegWR	CLK	CLR	ReadData1	ReadData2
Clear	XX	XX	XX	xxxx	X	X	0	xxxx	xxxx

0		Inp	uts		Co	ontrol Input	Outputs		
Operation	ReadAdd1	ReadAdd2	WriteAdd	WriteData	RegWR	CLK	CLR	ReadData1	ReadData2
Write R0	XX	XX	00	0010	0	<b>↓</b>	1	xxxx	xxxx
Write R3	xx	XX	11	0100	0	<b>↓</b>	1	xxxx	xxxx
Read R0,R3	00	11	xx	xxxx	1	1	1	0010	0100

#### 6.3 Instruction Memory (2<sup>4</sup>x16)

This can be a combinational unit - it takes just the address bus (4-bit value) as input and gives out a 16-bit value that is the instruction to be decoded. The address is provided by the Program Counter (PC). The Block diagram of Instruction Memory is mentioned above in the Figure 3-2.

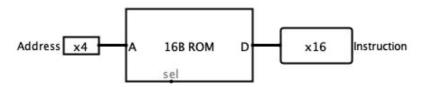


Figure 6-5. Digital Circuit of Instruction Memory

Build the Program Memory using ROM component in Logisim, as shown in Figure 6-5 and verify it's working.

#### **6.4 Data Memory** (2<sup>4</sup>x4)

This needs to be a sequential / clocked unit. At any given cycle, you are either reading from it or writing to it. In case of a LW or SW instruction, the address is either immediate or the output of the ALU. The data output of the DMEM will always go into the Register File, where it gets stored into a register selected by Rd. The Data Memory circuit diagram is shown in Figure 6-6.

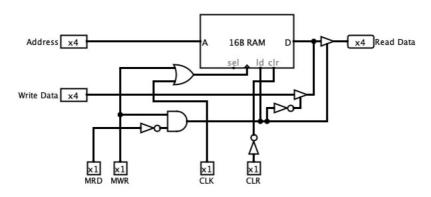


Figure 6-6. Digital Circuit of Data Memory

Rebuild the similar Data Memory in Logisim using RAM component and verify it's working.

Table 6-3. Verification of Data Memory Working

0 "	Iı	nputs		Output				
Operation	Address	WriteData	MRD	MWR	CLK	CLR	ReadData	
Clear	xxxx	xxxx	X	X	X	0	xxxx	
Write DMEM[5]	0101	1111	1	0	1	1	xxxx	
Read DMEM[5] 0101		xxxx	0	1	<b>↑</b>	1	1111	

# 6.5 Program Counter (4-bit)

Program Counter is a 4-bit register. Under normal operations, will always increment by 1 on every clock cycle, to access the next instruction.

The Program Counter circuit diagram is shown in Figure 6-7.

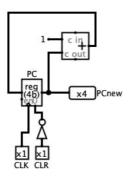


Figure 6-7. Digital Circuit of Program Counter

Rebuild the similar Program Counter in Logisim and verify it's working.

Table 6-4. Verification of Program Counter

Onovotion	Contro	Inputs	Output		
Operation	CLK	CLR	PCnew		
Clear / Reset	X	0	0000		
At each CLK pulse: Increment	1	1	0001 0010  1111 0000 0001		

#### 6.6 Control Unit

The unit that actually makes the entire processor work as expected. The input to this is the instruction word, and the output is a set of control signals that decide, for example, whether the register file is to be updated, what operation is to be done by the ALU, whether memory read or write is required etc.

One way to implement this is to make it a combinational block that will generate the following signals:

Table 6-5. Control Signals of 4-bit Microprocessor

		Input						Output	ts				
Function	Type	OpCode	A1A0	Add/Sub	Cin	RegWR	MRD	MWR	RegDst (SW)	MemtoReg (LW)	ALUSrc (IMM)	Branch	Jump
AND	R	0000	00	X	X								
OR	R	0001	01	X	X								
ADD	R	0010	10	1	0								
SUB	R	0011	10	1	1								
ANDi	I	0100	00	X	X								
ORi	I	0101	01	X	X								
ADDi	I	0110	10	1	0								
SUBi	I	0111	10	1	1								
SLT	R	1000	11	1	1								
SLTi	I	1001	11	1	1								
BEQ	I	1010	10	1	1								
BNE	I	1011	10	1	1								
J	J	1100	XX	X	X								
Unused		1101	XX	X	X								
LW	I	1110	10	1	0								
SW	I	1111	10	1	0								

Design a combinational circuit of the Control Unit by applying K-Maps or any technique and build a circuit using Logisim.

# 7 Logisim

It is strongly recommended that you download and run Logisim on your local machine while developing your processor. As you've probably discovered in lab, Logisim can quickly overwhelm the instructional machines. Though Logisim is relatively stable, it is still recommended that you save often and also make backup copies of your .circ files early and often. The official version of Logisim we will be using is available on the course webpage.

If you are having trouble with Logisim: RESTART IT and RELOAD your circuit! Don't waste your time chasing a bug that is not your fault. However, if restarting doesn't solve the problem, it is more likely that the bug is a flaw in your project. Please post to the newsgroup about any crazy bugs that you find, and we will investigate.

Do NOT copy and paste from different Logisim windows.

Logisim has been known to have trouble with this in the past. So, try to avoid it.