# Linear Algebra cheat sheet

### Vectors

dot product: 
$$u * v = ||u|| * ||v|| * cos(\phi) = u_x v_x + u_y v_y$$
  
cross product:  $u \times v = \begin{pmatrix} u_y v_z - u_z v_y \\ u_z v_x - u_x v_z \\ u_x v_y - u_y v_x \end{pmatrix}$ 

enclosed angle:

$$cos\phi = \frac{u*v}{||u||*||v||}$$
 
$$||u||*||v|| = \sqrt{(u_x^2 + u_y^2)(v_x^2 + v_y^2)}$$

### Matrices

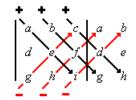
## basic operations

transpose:  $[A^{\mathrm{T}}]_{ij} = [A]_{ji}$ : "mirror over main diagonal"

multiply: 
$$A_{N\times M}*B_{R\times K}=M_{N\times K}$$
 invert:  $\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1}=\frac{1}{\det(\mathbf{A})}\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}=\frac{1}{ad-bc}\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$  norm: condition:

# determinants

 $\det(A) = \sum_{\sigma \in S_n} \operatorname{sgn}(\sigma) \prod_{i=1}^n A_{i,\sigma_i}$ For 3×3 matrices (Sarrus rule):



# arithmetic rules:

$$\det(A \cdot B) = \det(A) \cdot \det(B)$$

$$\det(A^{-1}) = \frac{1}{\det(A)}$$
 
$$\det(rA) = r^n \det A \text{ , for all } A^{n \times n} \text{ and scalars } r$$

## eigenvalues, eigenvectors, eigenspace

1. Calculate **eigenvalues** by solving det  $(A - \lambda I) = 0$ 

2. Any vector x that satisfies  $(A - \lambda_i I) x = 0$  is **eigenvector** for  $\lambda_i$ .

3. Eig<sub>4</sub> $(\lambda_i) = \{x \in \mathbb{C}^n : (A - \lambda_i)x = 0\}$  is **eigenspace** for  $\lambda_i$ .

#### definiteness

## obvious properties

square:  $N \times N$ symmetric:  $A = A^T$ **diagonal**: 0 except  $a_{kk}$ 

⇒ implies triangular (eigenvalues on main diagonale)

## orthogonal

$$A^{T} = A^{-1}$$

## nonsingular

A is nonsingular = invertible = regular iff:

There is a matrix  $B := A^{-1}$  such that AB = I = BA.

$$det(A) \neq 0$$

TAx = b has exactly one solution for each b.

The columns of A are linearly independent.

$$\Rightarrow det(A)^{-1} = det(A^{-1})$$
  
$$\Rightarrow (A^{-1})^{-1} = A$$
  
$$\Rightarrow (A^{T})^{-1} = (A^{-1})^{T}$$

## diagonalizable

 $A^{N\times N}$  can be diagonalized iff it has n linear independent eigenvectors. Then, there is an invertible T, such that:

$$D := T^{-1}AT = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}$$

$$A = T^{-1}DT$$
 and  $AT = T \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}$ 

T can be created with eigenvectors of A.

## diagonally dominant matrix

$$\forall i. |a_{ii}| \geq \sum_{i \neq i} |a_{ij}|$$

#### Hermitian

#### triangular

⇒ Eigenvalues on main diagonale

#### unitary

$$\Rightarrow cond_2(A) = 1$$

### idempotent

#### adjugate

#### block matrices

$$\det\begin{pmatrix} A & 0 \\ C & D \end{pmatrix} = \det\begin{pmatrix} A & B \\ 0 & D \end{pmatrix} = \det(A)\det(D)$$

#### rank

#### kernel

#### trace

defined on n×n square matrices:  $tr(A) = a_{11} + a_{22} + \cdots + a_{nn}$ (sum of the elements on the main diagonal)

#### span

## spectrum

 $\sigma(A) = \{ \lambda \in \mathbb{C} : \lambda \text{ is eigenvalue of A} \}$