Introduction of Polyfit function in MATLAB

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Syntax & Description

- 1. p = polyfit(x,y,n)
 - Returns the coefficients for a polynomial p(x) of degree n that is a best fit (in a least-squares sense) for the data in y.
 - The coefficients in p are in descending powers, and the length of p is n+1.
 - $p(x) = p_1 x^n + p_2 x^{n-1} + \dots + p_n x + p_{n+1}$.
- 2. [p,S] = polyfit(x,y,n)
 - Returns a structure S that can be used as an input to polyval to obtain error estimates.
- 3. [p,S,mu] = polyfit(x,y,n)
 - mu(1) is mean(x), and mu(2) is std(x).
 - Using these values, polyfit centers x at zero and scales it to have unit standard deviation, $\hat{x} = \frac{x \bar{x}}{\sigma}$

Example: Fit Polynomial to Set of Point (1/2)

 Create a vector of 5 equally spaced points in the interval [0,1], and evaluate y(x)=1/(1+x) at those points.

• Fit a polynomial of degree 4 to the 5 points.

```
p = polyfit(x,y,4);
```

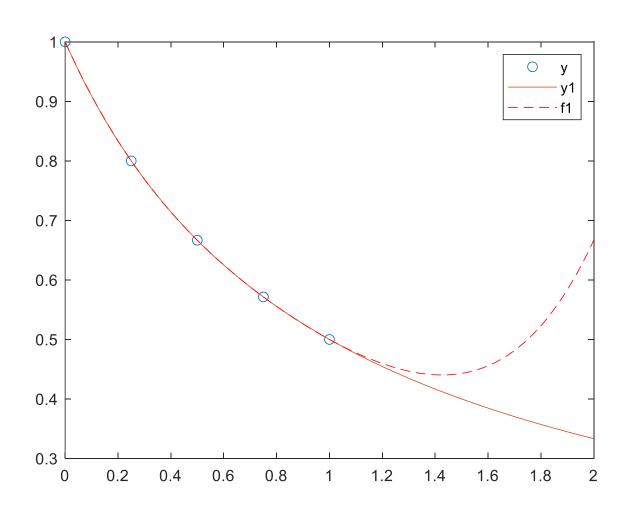
 Evaluate the original function between 0 and 2.

```
12  x1 = linspace(0,2);
13  y1 = 1./(1+x1);
```

• Evaluate the polynomial fit on a finer grid of points between 0 and 2.

```
f1 = polyval(p,x1);
```

Example: Fit Polynomial to Set of Point (2/2)



The polynomial fit is good in the original [0,1] interval, but quickly diverges from the fitted function outside of that interval.

Reference

1. https://www.mathworks.com/help/matlab/ref/polyfit.html#bufeks 8-1