#### **CSE502: Foundations of Parallel Programming**

# Lecture 02: Refresher – Processes and Threads

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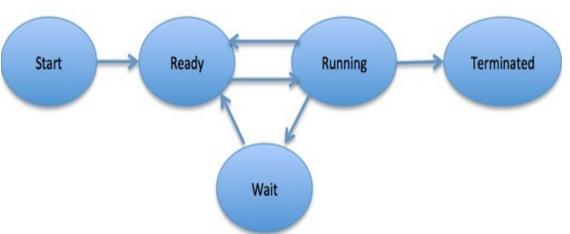
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#### Today's Class

- Processes and threads
- Shared memory parallel programming using Pthreads
  - Pthread creation and joining
  - Critical sections and mutual exclusion
  - Condition variables for synchronizations

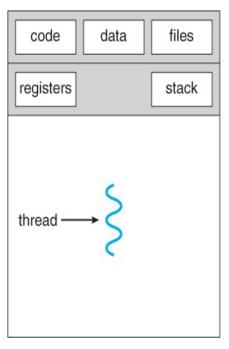
## Process is a Program in Execution

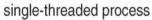


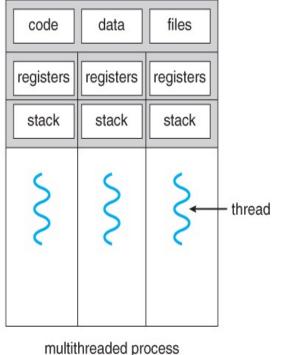
#### Process contains:

- Program instructions (code)
- Program data (global variables)
- Program counter (address of the currently executing instruction)
- CPU registers
- Stack (local variables, callercallee relationship between function)
- Diagram on left shows process life-cycle
  - New process being created
  - Ready waiting for a free processor
  - Running instructions are executing
  - Waiting waiting for some event (I/O, etc.)
  - Terminated execution is completed

#### Thread – A Lightweight Process







- Processes are heavyweight
  - Personal address space (allocated memory)
  - Communication across process always requires help from Operating System
- Threads are lightweight
  - Share resources inside the parent process (code, data and files)
    - Easy to communicate across sibling threads!
  - They have their own personal stack (local variables, caller-callee relationship between function)
    - Each thread is assigned a different job in the program
- A process can have one or more threads

#### Advantages of Multithreading

- Responsiveness
  - Even if part of program is blocked or performing lengthy operation, multithreading allows the program to continue
- Economical resource sharing
  - Threads share memory and resources of their parent process which allows multiple tasks to be performed simultaneously inside the process
- Utilization of multicores
  - Easily scale on modern multicore processors

#### POSIX Thread API (Pthreads)

- Standard threads API supported on almost all platforms
- Do-it-yourself scheduling (tasks-to-threads mapping)
- Each thread implements an abstraction of a processor, which are multiplexed onto machine resources
- Threads communicate though shared memory
  - Very cheap than inter-process communication

#### Why Should I Care About Pthreads?

## Pthreads is the foundation for multithreaded programming models

- Used to implement several parallel programming models, such as OpenMP, Cilk, X10, TBB, Habanero-C, etc.
- You will have a hard time understanding this course without a background on Pthreads

#### **Key Pthread APIs**

- Thread creation and joining
- Critical section and mutual exclusion
- Condition variables for synchronization

#### **Pthread Creation**

```
//Asynchronously invoke func in a new thread
int pthread_create(
            //returned identifier for the new thread
            pthread t *thread,
            //specifies the size of thread's stack and
            //how the thread should be managed by OS
            const pthread attr t *attr,
            //routine executed after creation
            void *(*func)(void *),
            //a single argument passed to func
            void *arg
)//returns error status
```

#### Wait for Pthread Termination

#### Fibonacci Program

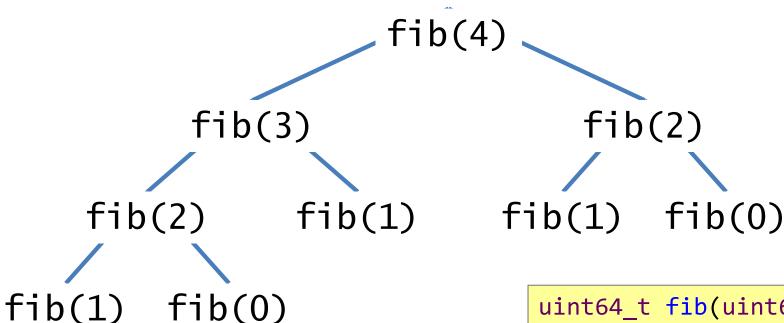
```
#include <inttypes.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
  if (n < 2) {
    return n;
  } else {
    uint64_t x = fib(n-1);
    uint64 t y = fib(n-2);
    return (x + y);
int main(int argc, char *argv[]) {
  uint64_t n = atoi(argv[1]);
  uint64_t result = fib(n);
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
         n, result);
  return 0;
```

#### **Disclaimer to Algorithms Police**

This recursive program is a poor way to compute the nth Fibonacci number, but it provides a good didactic example.

> Can we write a parallel version of this code using Pthreads?

#### Fibonacci Execution



#### **Key idea for parallelization**

The calculations of fib(n-1) and fib(n-2) can be executed simultaneously without mutual interference.

```
uint64_t fib(uint64_t n) {
   if (n < 2) {
      return n;
   } else {
      uint64_t x = fib(n-1);
      uint64_t y = fib(n-2);
      return (x + y);
   }
}</pre>
```

```
#include <inttypes.h>
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
typedef struct {
  uint64_t input:
  uint64_t output;
} thread_args:
void *thread_func(void *ptr) {
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result:
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1;
    status = pthread_create(&thread,
                             NULL.
                             thread_func.
                             (void*) &args);
    // main can continue executing
    if (status != NULL) { return 1; }
    result = fib(n-2);
    // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes.h>
#include <pthread.h>
                            Original code.
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
typedef struct {
  uint64_t input:
  uint64_t output:
} thread_args;
void *thread_func(void *ptr) {
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result:
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1;
    status = pthread_create(&thread,
                            NULL.
                            thread_func.
                             (void*) &args);
   // main can continue executing
   if (status != NULL) { return 1; }
    result = fib(n-2);
   // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes.h>
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
                             Structure for
                                thread
typedef struct {
                              arguments.
  uint64_t input;
  uint64_t output:
} thread_args;
void *thread_func(void *ptr) {
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result;
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
 } else {
    args.input = n-1;
    status = pthread_create(&thread,
                             NULL.
                             thread_func.
                             (void*) &args);
   // main can continue executing
   if (status != NULL) { return 1; }
    result = fib(n-2);
   // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes.h>
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
                              Function
                            called when
typedef struct {
                              thread is
  uint64_t input;
  uint64_t output:
                              created.
} thread_args;
void *thread_func(void *ptr) {
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result;
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1;
    status = pthread_create(&thread,
                            NULL.
                            thread_func.
                             (void*) &args);
   // main can continue executing
   if (status != NULL) { return 1; }
    result = fib(n-2);
   // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes</pre>
#include <pthread</pre>
                     No point in creating
#include <stdio.h</pre>
                      thread if there isn't
#include <stdlib.</pre>
                         enough to do.
uint64 t fib(uint
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
typedef struct {
  uint64_t input:
  uint64_t output:
} thread_args;
void *thread_func(void *ptr) {
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result:
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1;
    status = pthread_create(&thread,
                             NULL.
                             thread_func.
                             (void*) &args);
   // main can continue executing
   if (status != NULL) { return 1; }
    result = fib(n-2);
   // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes.h>
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
typedef struct {
  uint64_t input;
  uint64_t output:
} thread_args;
void *thread_func(void *ptr) {
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result:
                                  Marshal input
  if (argc < 2) { return 1; }
                                   argument to
  uint64_t n = strtoul(argv[1
                                      thread.
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1;
    status = pthread_create(&thread,
                            NULL.
                            thread_func,
                             (void*) &args);
   // main can continue executing
   if (status != NULL) { return 1; }
    result = fib(n-2);
   // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes.h>
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
typedef struct {
                          Create thread to
  uint64_t input;
                        execute fib(n-1).
  uint64_t output:
} thread_args;
void *thread_func(void *ptr) {
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result:
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1:
    status = pthread_create(&thread,
                             NULL.
                             thread_func.
                             (void*) &args);
    // main can continue executing
    if (status != NULL) { return 1; }
    result = fib(n-2);
    // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes.h>
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
                       Main program
typedef struct {
 uint64_t input;
                          executes
  uint64_t output:
                      fib(n-2) in
} thread_args;
                        parallel.
void *thread func(\
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result;
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1;
    status = pthread_create(&thread,
                             NULL.
                             thread_func,
                             (void*) &args);
    // main can continue executing
    if (status != NULL) { return 1; }
    result = fib(n-2);
    // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes.h>
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
                        Block until the
typedef struct {
  uint64_t input:
                       auxiliary thread
  uint64_t output:
} thread_args:
                           finishes.
void *thread_func(void "pti) 1
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result:
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1;
    status = pthread_create(&thread,
                             NULL.
                             thread_func.
                             (void*) &args);
   // main can continue executing
    if (status != NULL) { return 1; }
    result = fib(n-2);
    // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
    result += args.output;
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

```
#include <inttypes.h>
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
uint64 t fib(uint64 t n) {
 if (n < 2) {
   return n;
 } else {
   uint64 t x = fib(n-1);
   uint64 t y = fib(n-2);
   return (x + y);
typedef struct {
  uint64_t input:
  uint64_t output:
} thread_args:
void *thread_func(void *ptr) {
  uint64 t i =
    ((thread_args *) ptr)->input;
  ((thread_args *) ptr)->output = fib(i);
  return NULL;
```

Add the results together to produce the final output.

```
int main(int argc, char *argv[]) {
  pthread_t thread;
  thread_args args:
  int status;
  uint64_t result;
  if (argc < 2) { return 1; }
  uint64_t n = strtoul(argv[1], NULL, 0);
  if (n < 30) {
   result = fib(n);
  } else {
    args.input = n-1:
    status = pthread_create(&thread,
                            NULL.
                            thread_func,
                             (void*) &args);
   // main can continue executing
   if (status != NULL) { return 1; }
    result = fib(n-2);
   // Wait for the thread to terminate.
    status = pthread_join(thread, NULL);
    if (status != NULL) { return 1; }
   result += args.output:
  printf("Fibonacci of %" PRIu64 " is %" PRIu64 ".\n",
        n, result);
  return 0:
```

#### Today's Class

- Shared memory parallel programming using Pthreads
  - Pthread creation and joining



- Critical sections and mutual exclusion
- Condition variables for synchronizations

#### Critical Sections and Mutual Exclusion

Critical section = code executed by only one thread at a time

```
/* threads compete to update global variable minval */
if (my_minval < minval)
  minval = my_minval;</pre>
```

created by pthread mutex attr init

specifies mutex type

- Mutex locks enforce mutual exclusion in Pthreads
  - mutex lock states: locked and unlocked
  - only one thread can lock a mutex lock at any particular time
- Using mutex locks
  - request lock before executing critical section
  - enter critical section when lock granted
  - release lock when leaving critical section
- Operations

#### Reduction Using Mutex Locks

```
pthread_mutex_t _lock;
int minval;
int main() {
    . . .
    pthread_mutex_init(&_lock, NULL);
}
void *find_minval(void *list_ptr) {
    pthread_mutex_lock(&_lock); /* lock the mutex */
    if (my minval < minval)</pre>
                                        Critical Section
   minval = my_minval;
   pthread_mutex_unlock(&_lock); /* unlock the mutex */
```

#### Today's Class

- Shared memory parallel programming using Pthreads
  - Pthread creation and joining
  - Critical sections and mutual exclusion



Condition variables for synchronizations

#### Condition Variables for Synchronization

#### Condition variable: associated with a predicate and a mutex

- Using a condition variable
  - thread can block itself until a condition becomes true
    - thread locks a mutex
    - tests a predicate defined on a shared variable
       if predicate is false, then wait on the condition variable
       waiting on condition variable unlocks associated mutex
  - when some thread makes a predicate true
    - that thread can signal the condition variable to either wake one waiting thread
       wake all waiting threads
    - when thread releases the mutex, it is passed to first waiter

#### Pthread Condition Variable APIs

```
/* initialize or destroy a condition variable */
int pthread cond init(pthread cond t *cond,
                  const pthread condattr t *attr);
int pthread cond destroy(pthread cond t *cond);
/* block until a condition is true */
int pthread cond wait(pthread cond t *cond,
                     pthread mutex t *mutex);
/* signal one or all waiting threads that condition
   is true */
int pthread_cond_signal(pthread_cond_t *cond);
int pthread cond broadcast(pthread_cond_t *cond);
  wake one
                                            wake all
```

```
pthread_mutex_lock(&mutex);
2. while(task_queue_size() == 0)
    pthread_cond_wait(&cond, &mutex);
4.
   task = pop_task_queue();
   pthread_mutex_unlock(&mutex);
   execute_task (task);
         Consumer(s)
```

```
pthread_mutex_lock(&mutex);
2. int queue_size = task_queue_size();
   push_task_queue(&task);
4. if(queue_size == 0) {
    pthread_cond_broadcast(&cond);
6.
   pthread_mutex_unlock(&mutex);
```

Producer

```
Mutex lock
   pthread_mutex_lock(&mutex);
                                                              pthread_mutex_lock(&mutex);
   while(task_queue_size() == 0)
                                                              int queue_size = task_queue_size();
3.
    pthread_cond_wait(&cond, &mutex);
                                                              push_task_queue(&task);
4.
                                                              if(queue_size == 0) {
5.
                                                               pthread_cond_broadcast(&cond);
   task = pop_task_queue();
   pthread_mutex_unlock(&mutex);
                                                          6.
   execute task (task);
                                                              pthread_mutex_unlock(&mutex);
                              Consumer
```

Thread

```
Mutex lock

1. pthread_mutex_lock(&mutex);
2. int average size a teals group size.
```

```
    pthread_mutex_lock(&mutex);
    while(task_queue_size() == 0)
    pthread_cond_wait(&cond, &mutex);
    }
    task = pop_task_queue();
```

- 6. pthread\_mutex\_unlock(&mutex);
- 7. execute\_task (task);

```
    int queue_size = task_queue_size();
    push_task_queue(&task);
    if(queue_size == 0) {
    pthread_cond_broadcast(&cond);
    }
    pthread_mutex_unlock(&mutex);
```

Consumer Thread

Mutex lock

```
    pthread_mutex_lock(&mutex);
    while(task_queue_size() == 0)
    pthread_cond_wait(&cond, &mutex);
    }
    task = pop_task_queue();
    pthread_mutex_unlock(&mutex);
    execute task (task);
```

```
Consumer
Thread
```

```
    pthread_mutex_lock(&mutex);
    int queue_size = task_queue_size();
    push_task_queue(&task);
    if(queue_size == 0) {
    pthread_cond_broadcast(&cond);
    }
    pthread_mutex_unlock(&mutex);
```

Mutex lock

```
    pthread_mutex_lock(&mutex);
```

- 2. while(task\_queue\_size() == 0)
- pthread\_cond\_wait(&cond, &mutex);
- 4.
- 5. task = pop\_task\_queue();
- 6. pthread\_mutex\_unlock(&mutex);
- 7. execute\_task (task);

```
    pthread_mutex_lock(&mutex);
```

- int queue\_size = task\_queue\_size();
- push\_task\_queue(&task);
- 4. if(queue\_size == 0) {
- 5. pthread\_cond\_broadcast(&cond);
- 6. }
- 7. pthread\_mutex\_unlock(&mutex);

Consumer Thread

```
Mutex lock
1.
```

```
    pthread_mutex_lock(&mutex);
```

- while(task\_queue\_size() == 0)
- pthread\_cond\_wait(&cond, &mutex);
- 4. }
- 5. task = pop\_task\_queue();
- pthread\_mutex\_unlock(&mutex);
- 7. execute\_task (task);

```
    pthread_mutex_lock(&mutex);
```

- 2. int queue\_size = task\_queue\_size();
- push\_task\_queue(&task);
- 4. if(queue\_size == 0) {
- 5. pthread\_cond\_broadcast(&cond);
- 6.
- 7. pthread\_mutex\_unlock(&mutex);

Consumer Thread

```
Mutex lock
   pthread_mutex_lock(&mutex);
                                                               pthread_mutex_lock(&mutex);
   while(task_queue_size() == 0)
                                                               int queue_size = task_queue_size();
3.
     pthread_cond_wait(&cond, &mutex);
                                                               push_task_queue(&task);
4.
                                                               if(queue_size == 0) {
                                                                 pthread_cond_broadcast(&cond);
   task = pop_task_queue();
   pthread_mutex_unlock(&mutex);
                                                           6.
   execute task (task);
                                                               pthread_mutex_unlock(&mutex);
```

Consumer Thread

Mutex lock

```
    pthread_mutex_lock(&mutex);
    while(task_queue_size() == 0)
    pthread_cond_wait(&cond, &mutex);
    }
    task = pop_task_queue();
    pthread_mutex_unlock(&mutex);
    execute task (task);
```

```
    pthread_mutex_lock(&mutex);
    int queue_size = task_queue_size();
    push_task_queue(&task);
    if(queue_size == 0) {
    pthread_cond_broadcast(&cond);
    }
    pthread_mutex_unlock(&mutex);
```

Consumer Thread

```
Mutex lock
   pthread_mutex_lock(&mutex);
                                                            pthread_mutex_lock(&mutex);
   while(task_queue_size() == 0)
                                                            int queue_size = task_queue_size();
3.
    pthread_cond_wait(&cond, &mutex);
                                                            push_task_queue(&task);
4.
                                                           if(queue_size == 0) {
                                                             pthread_cond_broadcast(&cond);
   task = pop_task_queue();
   pthread_mutex_unlock(&mutex);
                                                        6.
   execute task (task);
                                                            pthread_mutex_unlock(&mutex);
                                                   Producer
                             Consumer
                             Thread
                                                   Thread
```

```
    pthread_mutex_lock(&mutex);
    while(task_queue_size() == 0)
    pthread_mutex_lock(&mutex);
    int queue_size = task_queue_size();
    push_task_queue(&task);
    jef(queue_size == 0) {
    task = pop_task_queue();
    pthread_cond_broadcast(&cond);
```

Consumer Thread

pthread\_mutex\_unlock(&mutex);

execute task (task);

Producer Thread

6.

pthread\_mutex\_unlock(&mutex);

```
Mutex lock
```

```
    pthread_mutex_lock(&mutex);
    while(task_queue_size() == 0)
    pthread_cond_wait(&cond, &mutex);
    }
    task = pop_task_queue();
    pthread_mutex_unlock(&mutex);
    execute task (task);
```

```
    pthread_mutex_lock(&mutex);
    int queue_size = task_queue_size();
    push_task_queue(&task);
    if(queue_size == 0) {
    pthread_cond_broadcast(&cond);
    }
    pthread_mutex_unlock(&mutex);
```

Consumer Thread

#### Reminders about this Course!!

- No lecture recordings
- You are not allowed to open-source the course assignments/labs/projects even after the course is over
- You should learn C/C++ on your own
- We will strictly follow IIITD plagiarism policy

So, plan accordingly. Registering to this course means you are agreeing to all these requirements

#### Reading Materials

- Process and threads
  - Please go though your favorite Operating Systems book and read the chapters on processes and threads
- POSIX Threads programming
  - <a href="https://hpc-tutorials.llnl.gov/posix/">https://hpc-tutorials.llnl.gov/posix/</a>
  - Note: Pthread APIs related to thread-specific data were not discussed in class and you should read it on your own. There are plenty of online resources
    - pthread\_key\_create, pthread\_setspecific, pthread\_getspecific

#### **Next Class**

- Introduction to parallel architectures and programming models
- Assignment-1 will be announced on 21/01 noon with a deadline of 24/01 midnight
  - No extensions!

#### Acknowledgements

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  - Course CSE539S, Prof. I-Ting Angelina Lee, Washington University in St. Louis
- Contents are also borrowed from following sources:
  - "Introduction to Parallel Computing" by Ananth Grama, Anshul Gupta, George Karypis, and Vipin Kumar. Addison Wesley, 2003
  - https://computing.llnl.gov/tutorials/parallel\_comp/
  - <a href="https://images.google.com/">https://images.google.com/</a>