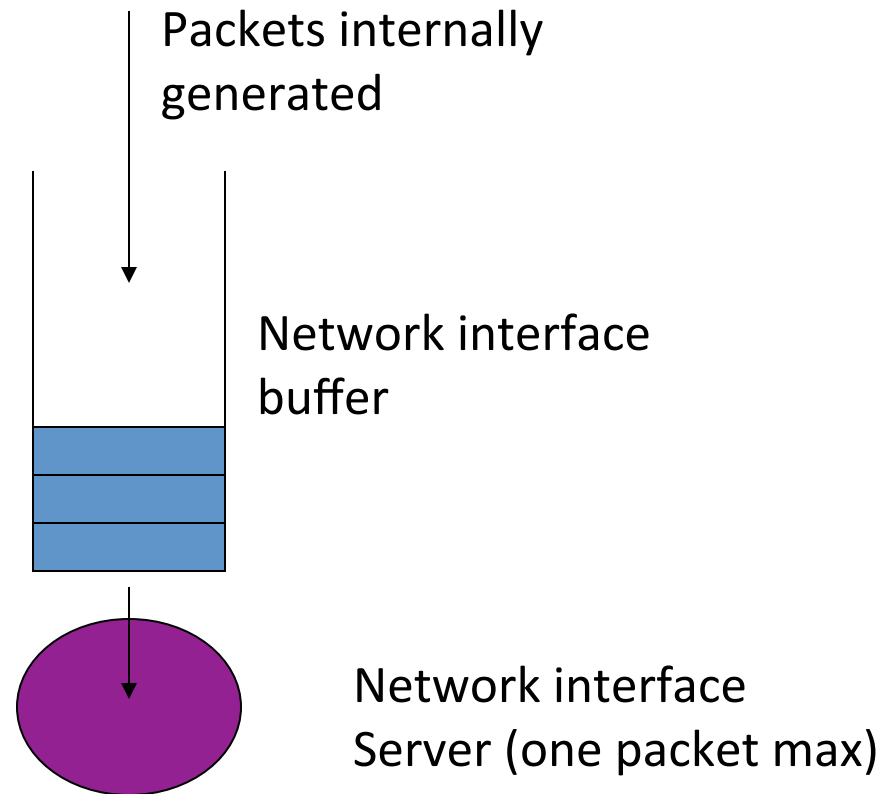


Random access and massive wireless networks

Philippe Jacquet

Nokia Bell Labs

Terminal network interface model

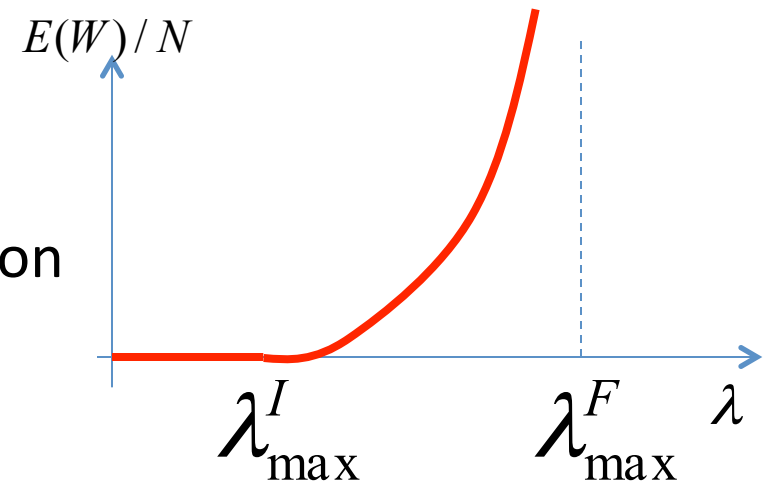


Traffic Poisson model

- Finite population model
 - Poisson model traffic λ_i per slot for node i
 - $\lambda = \sum_i \lambda_i$ *eg* $\lambda_i = \frac{\lambda}{N}$
 - Infinite buffer
 - Maximum stable capacity
- Infinite population model λ_{\max}^F
 - $N=\infty$
 - Buffer limited to 1 unit.
 - A Poisson generation of node with one packet
 - Maximum stable capacity $\lambda_{\max}^I \leq \lambda_{\max}^F$

Why infinite population model is interesting

- When $\lambda < \lambda_{\max}^I$
 - Average delivery delay is finite $E(W) < \infty$
 - Independent of N
- When $\lambda_{\max}^I \leq \lambda < \lambda_{\max}^F$
 - We expect $E(W) = O(N)$
 - λ_{\max}^F may vary with input repartition
 - Starvation effects
 - Problem when N increases
 - Eg N=10⁶ or larger



ALOHA Performance

- Packet generation over all nodes
 - Poisson process, cumulated rate λ packet per slot
- ALOHA Packet transmission attempt process: Two model cases:
 - infinite population: nodes transmit only one packet and die;
 - Finite population nodes are permanent and manage a queue of packets

$$P(\text{slot is empty}) = e^{-\rho}$$

$$P(\text{slot is success}) = \rho e^{-\rho}$$

$$P(\text{slot is collision}) = 1 - (1 + \rho)e^{-\rho}$$

- Poisson process, cumulated rate ρ packet per slot

Aloha and infinite population

- Is unstable for all $\lambda > 0$: $\lambda_{\max}^I = 0$
 - Take B large number of waiting packets:
$$P(\text{slot is success}) = (1 - p)^B \lambda e^{-\lambda} + Bp(1 - p)^{B-1} e^{-\lambda} < \lambda$$
 - System diverges: B(t) at time t
$$E(B(t + 1) - B(t) \mid B(t) = B) = \lambda - P(\text{slot is success})$$
 - $\lambda_{\max}^I = 0$ for binary exponential backoff (Ethernet, Wifi)



Aloha and finite population

- N nodes

- In this case $\max\{B(t)\}=N$

- System is stable when $B=N$ and

$$P(\text{slot is success}) = Np(1-p)^{N-1} > \lambda$$

- When $p = O(\frac{1}{N})$

$$P(\text{slot is success}) \approx Np \exp(-Np)$$

- And max throughput

$$\lambda_{\max}^F = e^{-1} \approx 0.36787 \dots$$

Stack collision resolution in infinite population

- Stack algorithm
local procedure

```
C ← 0;  
While packet to transmit {  
  if (C=0) then {  
    transmit;  
    if collision then C ← rand(0,1) }  
  else {  
    if listen=collision then C ← C+1;  
    else C ← C-1  
  }  
}
```


Stack algorithm stability condition

ABC	AB	-	AB	A	B	C
	C	AB	C	B	C	
		C		C		

$$\lambda_{\max} \approx 0.360177\dots$$

Ternary Stack collision resolution

- Ternary Stack algorithm

local procedure

```
    C ← 0;  
While packet to transmit {  
    if (C=0) then {  
        transmit;  
        if collision then C ← rand(0,1,2) }  
    else {  
        if listen=collision then C ← C+1;  
        else C ← C-1  
    }  
}
```

$$\lambda_{\max} \approx 0.401599\dots$$

Upper bound on collision resolution algorithms stability

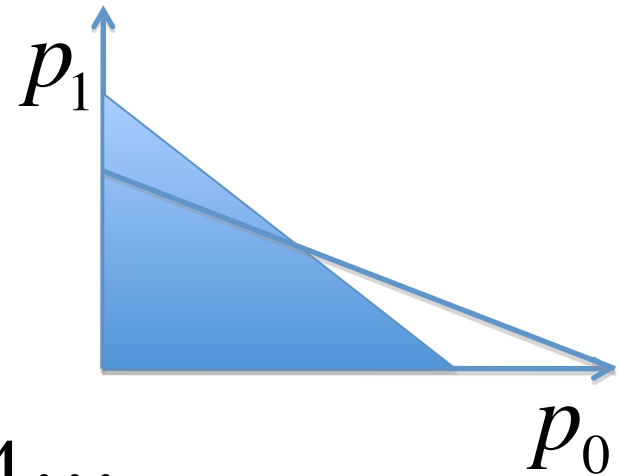
$$p_0 = P(\text{algo returns } 0)$$

$$p_1 = P(\text{algo returns } 1)$$

$$\begin{cases} p_0 \lambda e^{-\lambda} + p_1 e^{-\lambda} = \lambda \\ p_0 + p_1 \leq 1 \end{cases}$$

$$\lambda_{\max}^I \leq e^{-\lambda_{\max}^I} : \lambda_{\max}^I \leq 0.56714\dots$$

largest known 0.487...



Aloha under small load

- Infinite population with $\lambda \ll e^{-1}$
- Transmission and retransmission is a Poisson process
 - cumulated rate ρ packet per slot

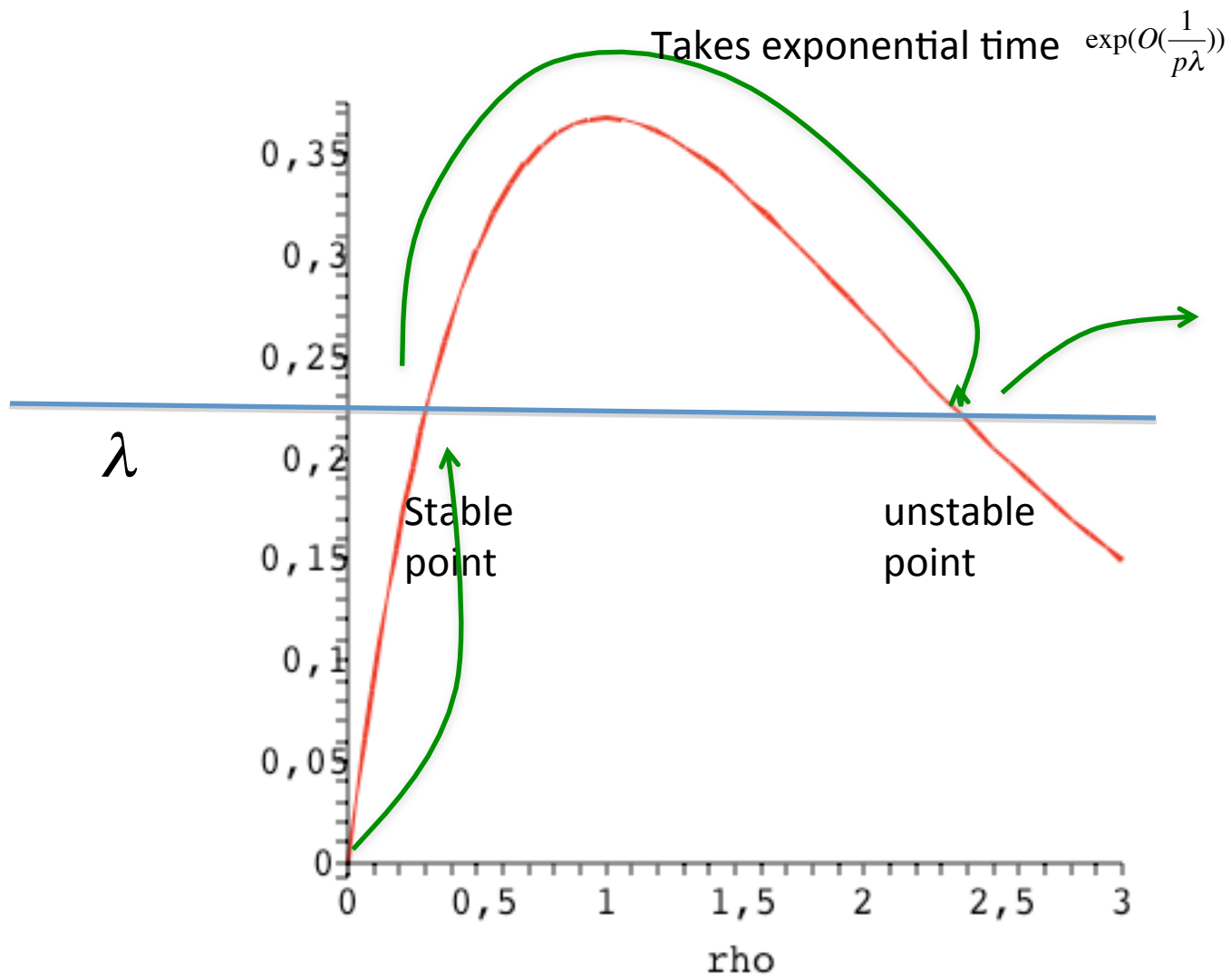
$$P(\text{slot is empty}) = e^{-\rho}$$

$$P(\text{slot is success}) = \rho e^{-\rho}$$

$$P(\text{slot is collision}) = 1 - (1 + \rho)e^{-\rho}$$

- Equilibrium equation:

$$\lambda = \rho e^{-\rho}$$



ALOHA in finite population

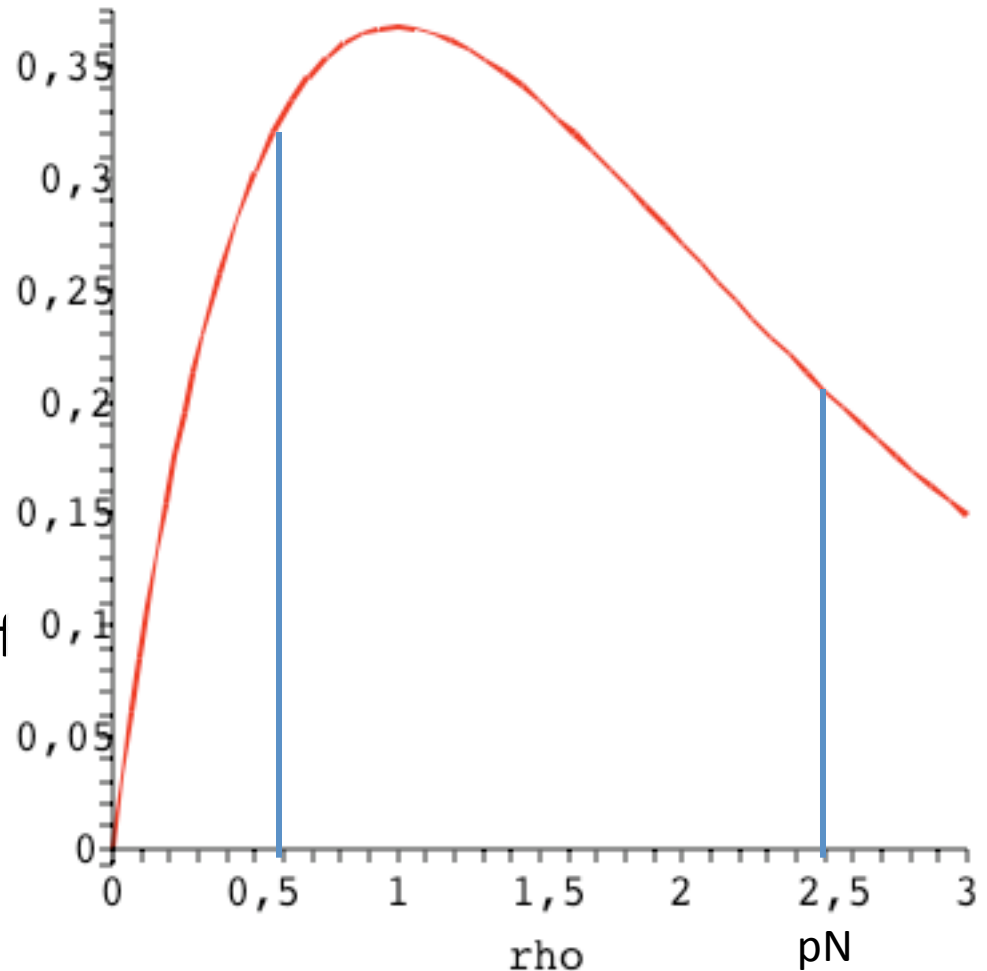
- Maximum throughput

$$\lambda_{\max}^F = pN e^{-pN}$$

- All buffers full

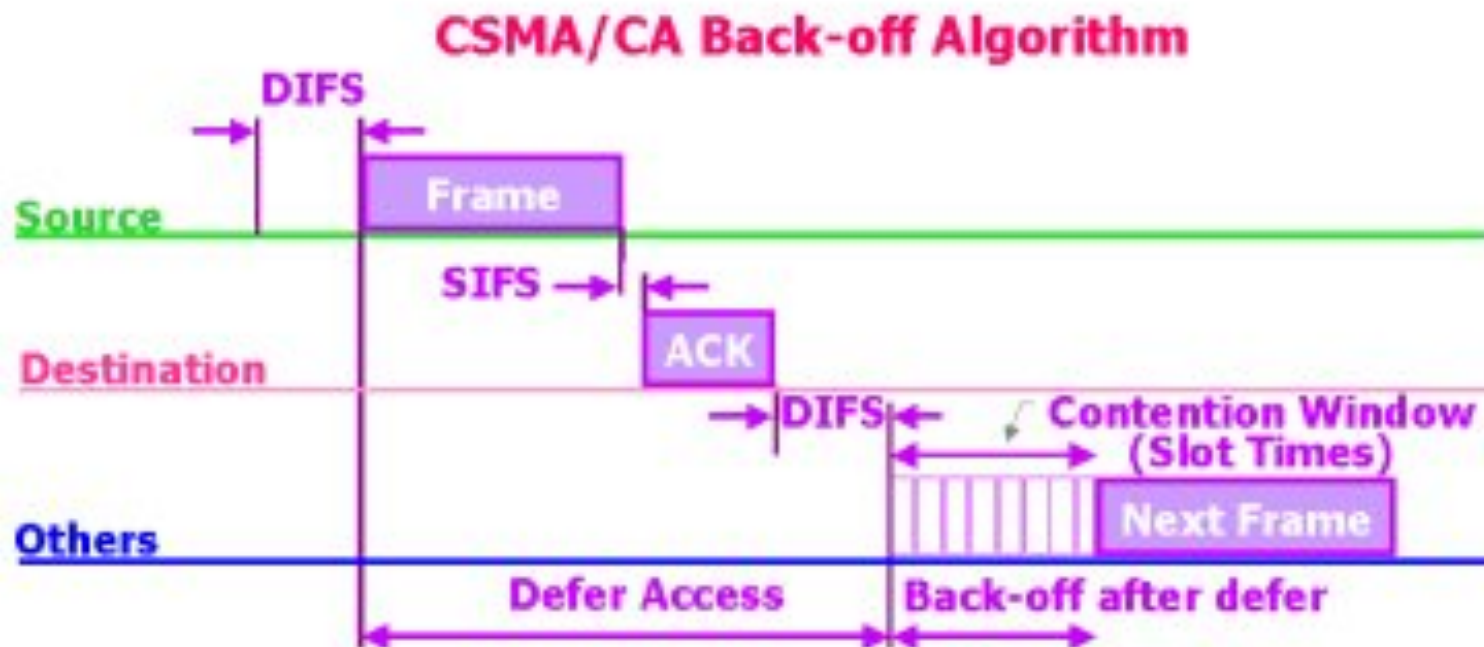
$$\rho = pN$$

- Takes long to attain except if big burst of traffic
- If $pN < 1$: starvation



Protocol CSMA (Wifi)

- Mini-slots

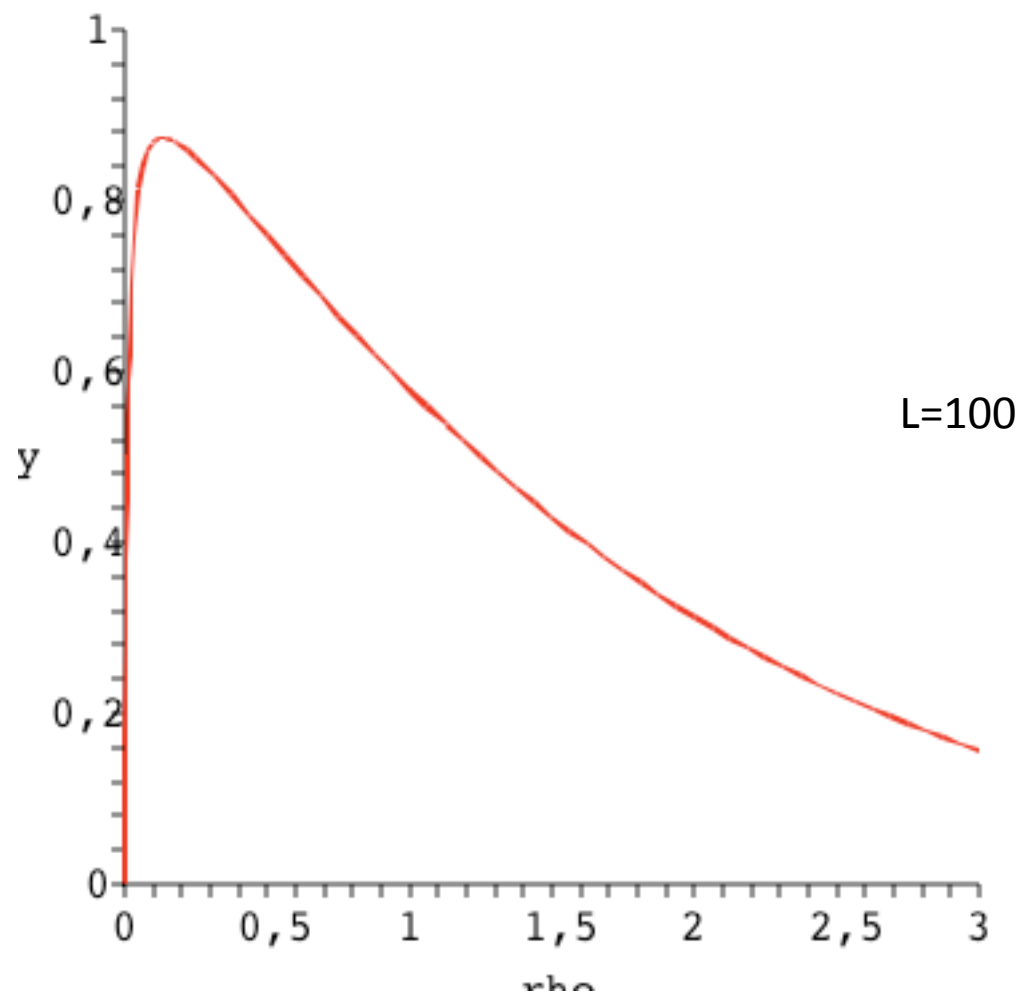


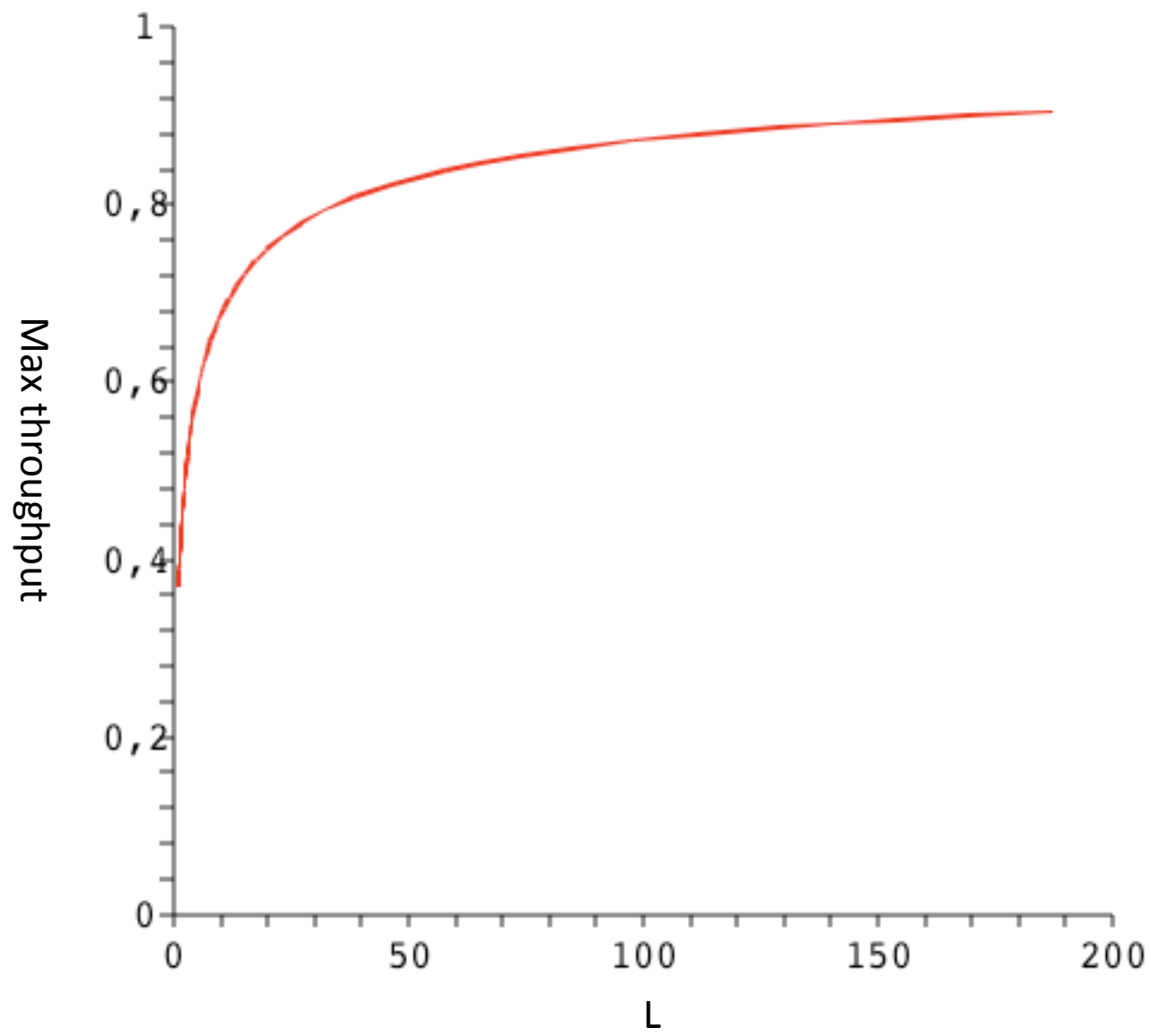
Performances of stationary CSMA

- Poisson model:
 - ρ : per mini-slot load
 - L : packet length (in mini-slots)
- Net throughput

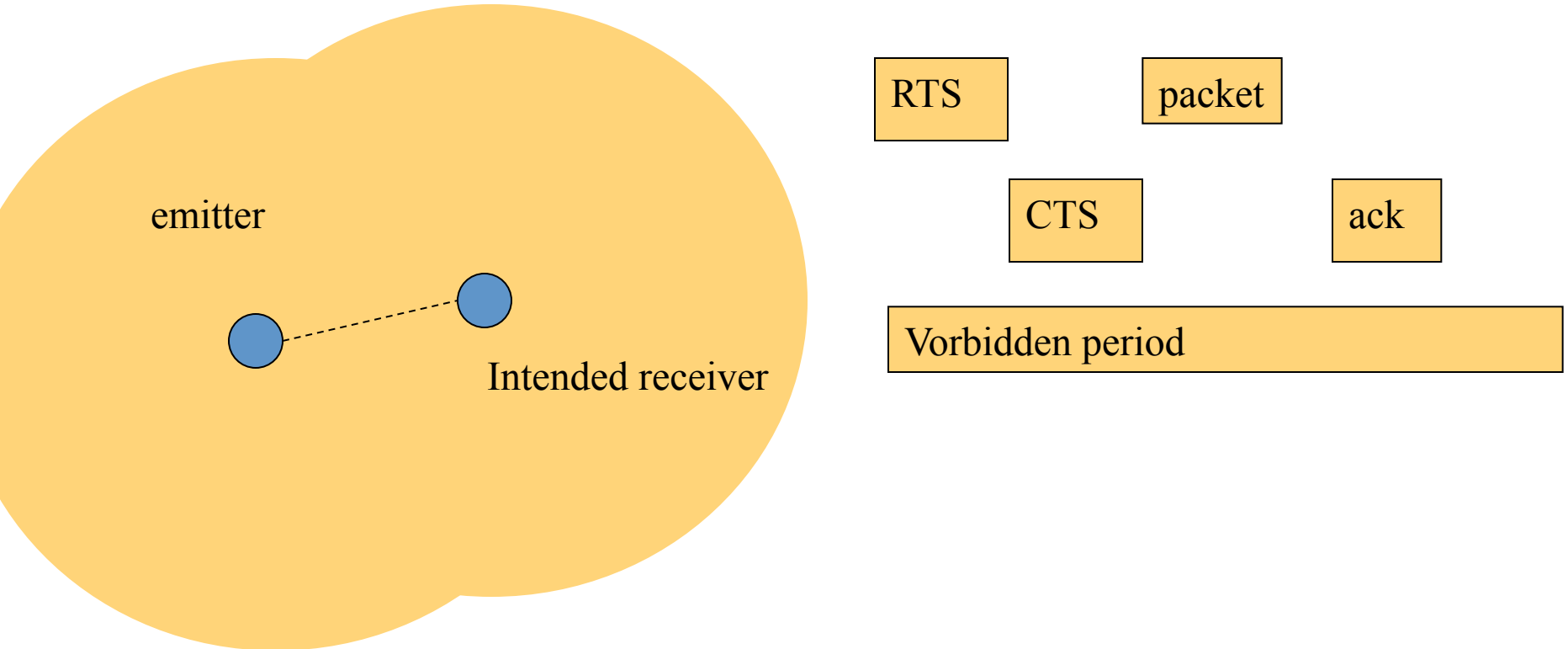
$$\frac{L\rho}{1 + (e^\rho - 1)L}$$

$$\max \approx 1 - \sqrt{\frac{2}{L}}$$





RTS-CTS



CSMA/CA performances

- Net throughput with RTS-CTS

$$C_{\max} = \frac{\rho L}{1 + \rho L + (e^{\rho} - 1)R}$$

$$C_{\max} = \frac{1}{1 + \frac{\beta(R)}{L}} \approx 1 - \frac{\beta(R)}{L}$$

Green contention

- Hypothesis: we know an upper bound of the population.
- Quasi channel transparency
 - Delay are sublinear function of N .

Improvement to CSMA: Bursty Preamble transmission

- Each primary transmits sequence of burst before packet transmission



— Bursts used to resolve contentions

Access keys

- Divide preamble in mini-slots
 - Binary access pattern of a primary contender
 - « 1 »: contender transmits a burst
 - « 0 »: contender listens the slot

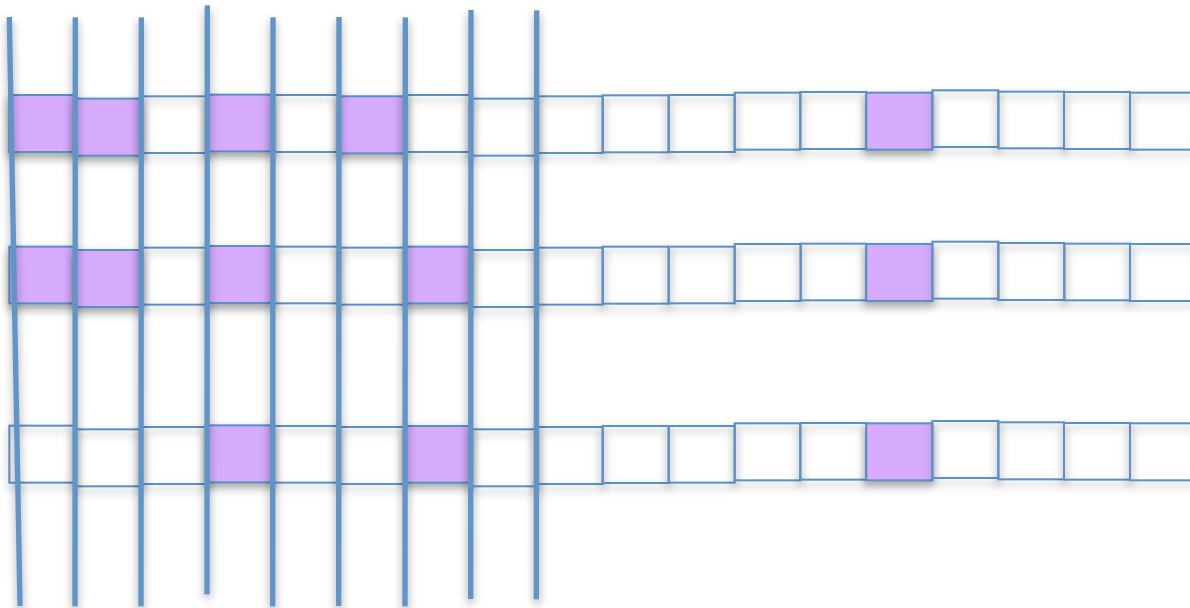


- Let integer k be the ratio frame/mini-slot (eg $k=10$)
 - Access keys are constrained $(0, k-1)$ sequences
 - Run of zeros should not exceeds $k-1$
 - to avoid desynchronisation
 - Sequence of super-alphabet $A_k = \{1, 01, 001, \dots, 0^{k-1}1\}$

Contention resolution (leader election)

- Contenders set their access keys before slot 1
- On i-th slot
 - surviving contenders with a « 1 » as i-th bit
 - Transmit a burst
 - Surviving contenders with a « 0 » as i-th bit
 - Listen to the slot
 - If burst detected, the contender aborts contention
 - Defer for the next election.

Contention resolution (leader election)



Access keys management

- Deterministic:
 - The access keys are derived from node ID and are unique (over N nodes)
 - In fact optimal packing with $\log_{\frac{1}{\rho}} N$ super-symbols with $\sum_{i=1}^k \rho^i = 1$

P. Jacquet, P. Mühlenthaler, "Cognitive networks: anew access scheme which introduces a Darwinian approach" Wireless Days, 2012

Fairness obtained by round robin-like protocol.
- Probabilistic:
 - The access keys can be probabilistic
 - Eg super-symbols are drawn uniformly on A_k
 - Residual collision may exist
 - Rate can be made negligible
 - Add to radio loss rate.

Part and try algorithm

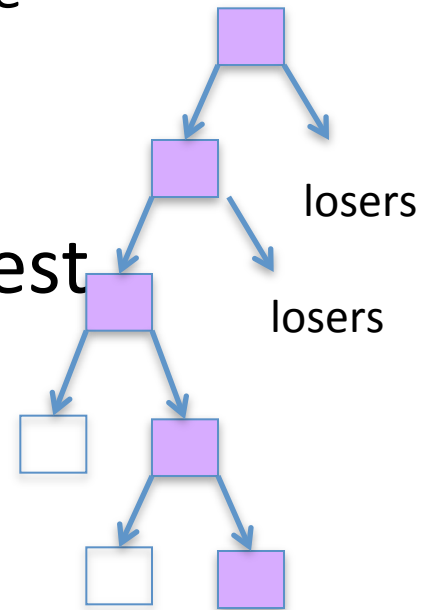
- Case $k=2$ is the part and try algorithm



- BS Tsybakov, VA Mikhailov "Random multiple packet access: part-and-try algorithm"
Problemy Peredachi Informatsii, 1980.

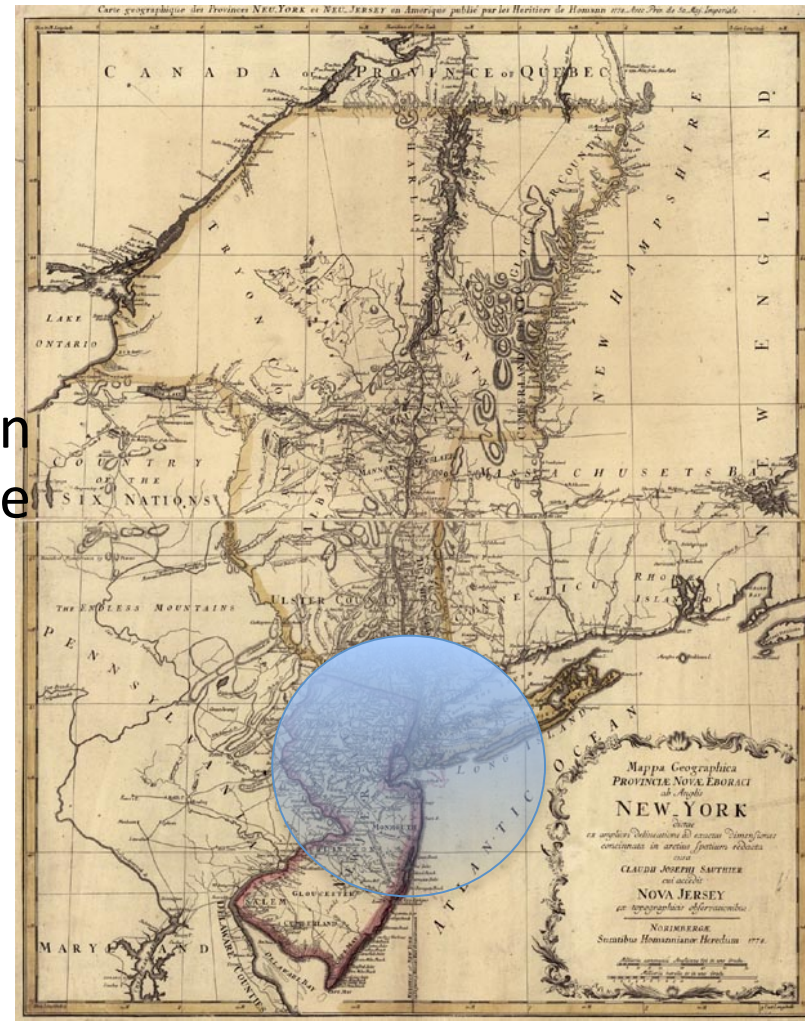
- The winners are those with the largest binary sequence

- Average election duration $\log_k n$



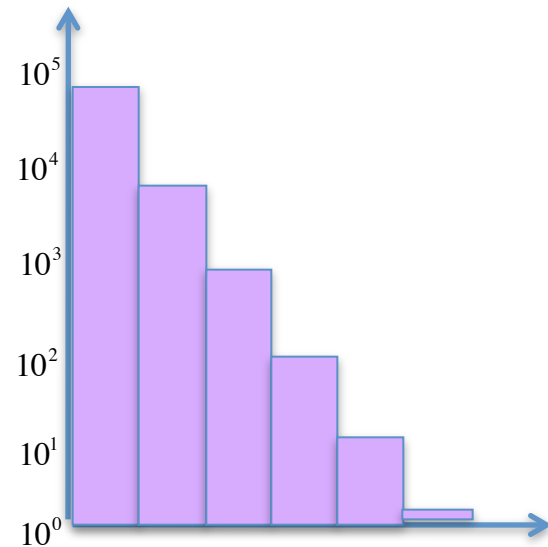
Energy cost issue

- Take the first burst.
 - In average $n/2$ transmit & collide
 - If n is of order the million (urban area)
 - The flash of the first burst can create of 100 km interference radius
- Further bursts
 - $n/4$, $n/8$, etc.
 - Average global energy cost per election is n



Energy cost

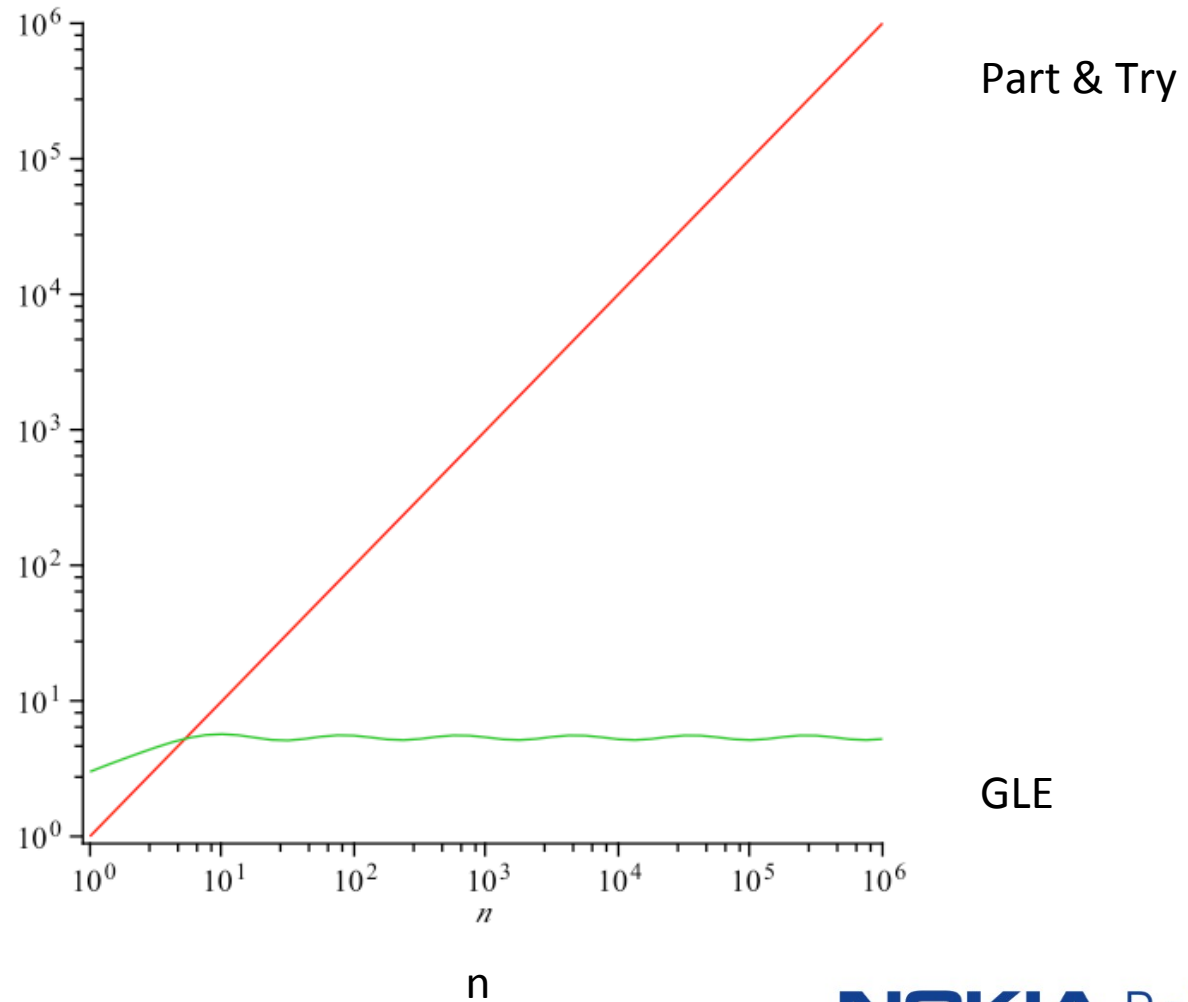
- A global energy cost of one million bursts per packet transmission is unacceptable
 - Would run-down batteries in seconds



Energy cost saving (green) leader election algorithm

- Algorithm performs election for $n \leq N$
 - Average duration $k \log_k \log N$ minislot
 - Average global energy cost in $O(\sqrt[k]{N})$
 - N is a maximum network size.
 - Residual collision rate bounded
 - Can be made arbitrary small
 - Example with $k=10$, $N=1,000,000$
 - Duration 30 minislots
 - Energy cost 5.5
 - Collision rate less than 1%

green leader election algorithm

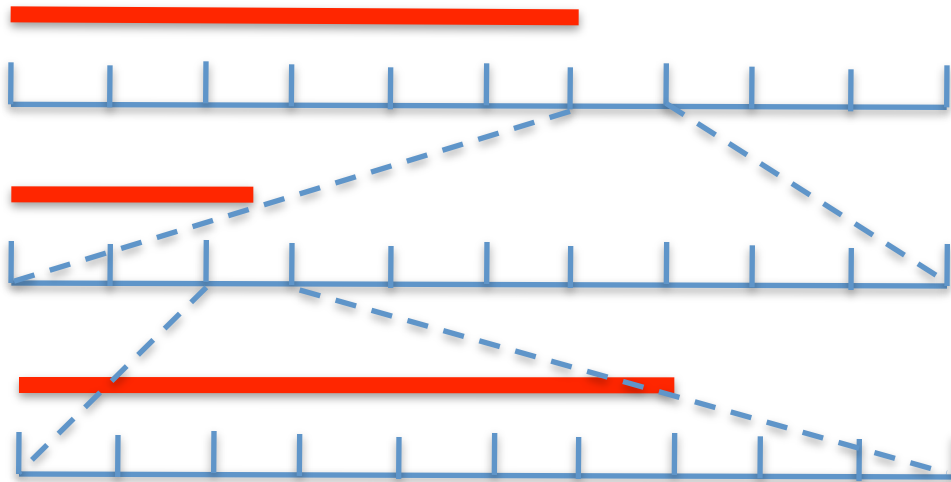


Energy cost saving (green) leader election algorithm

- Contender access key computation
 - Access key is made of $L_N = \log_k \log N + O(1)$ super-symbols
 - Say $L_N = 3$
 - Scalar p shared by all nodes
 - Say $p = 0.02$
 - Every contender selects a random integer X
 - X is geometric with probability rate $1 - p$
$$P(X \geq m) = (1 - p)^m$$
 - The access key is k -ary translation of $\max\{k^{L_N} - X - 1, 0\}$

Green leader election algorithm

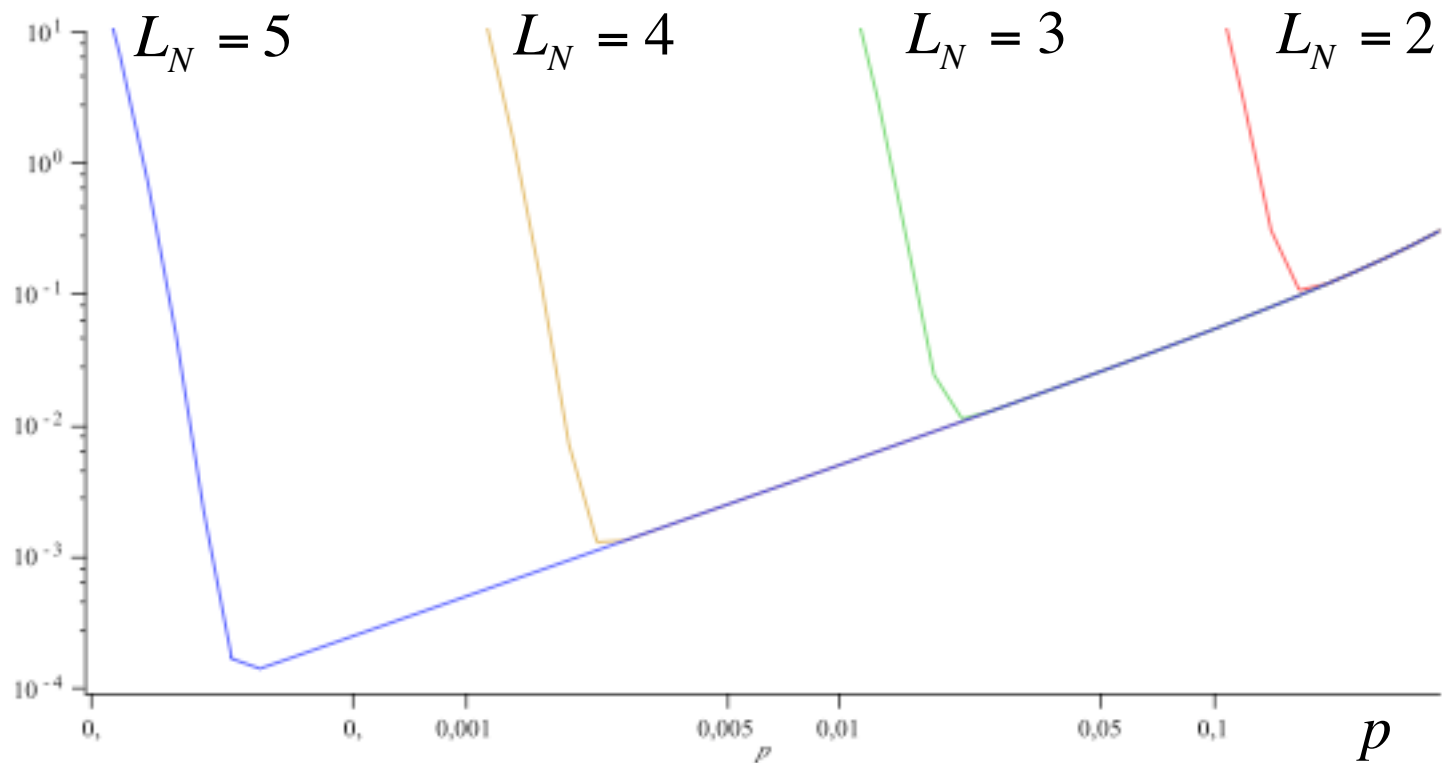
$$X = 372 = 999 - 627$$



access key : $0^6 10^2 10^7 1 = 000000100100000001$

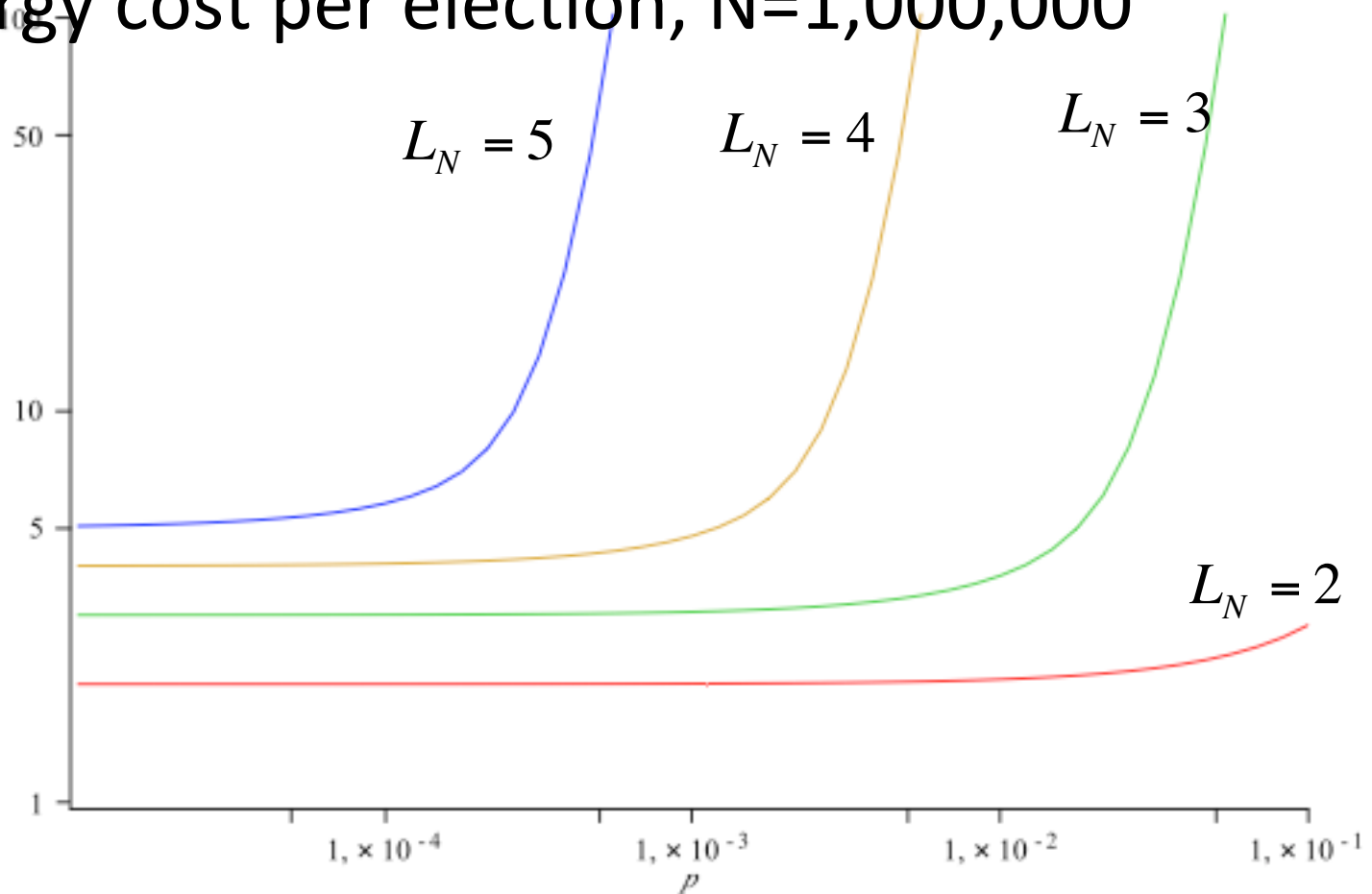
Parameters of the algorithm

- Residual collision rate, $N=1,000,000$



Parameters of the algorithm

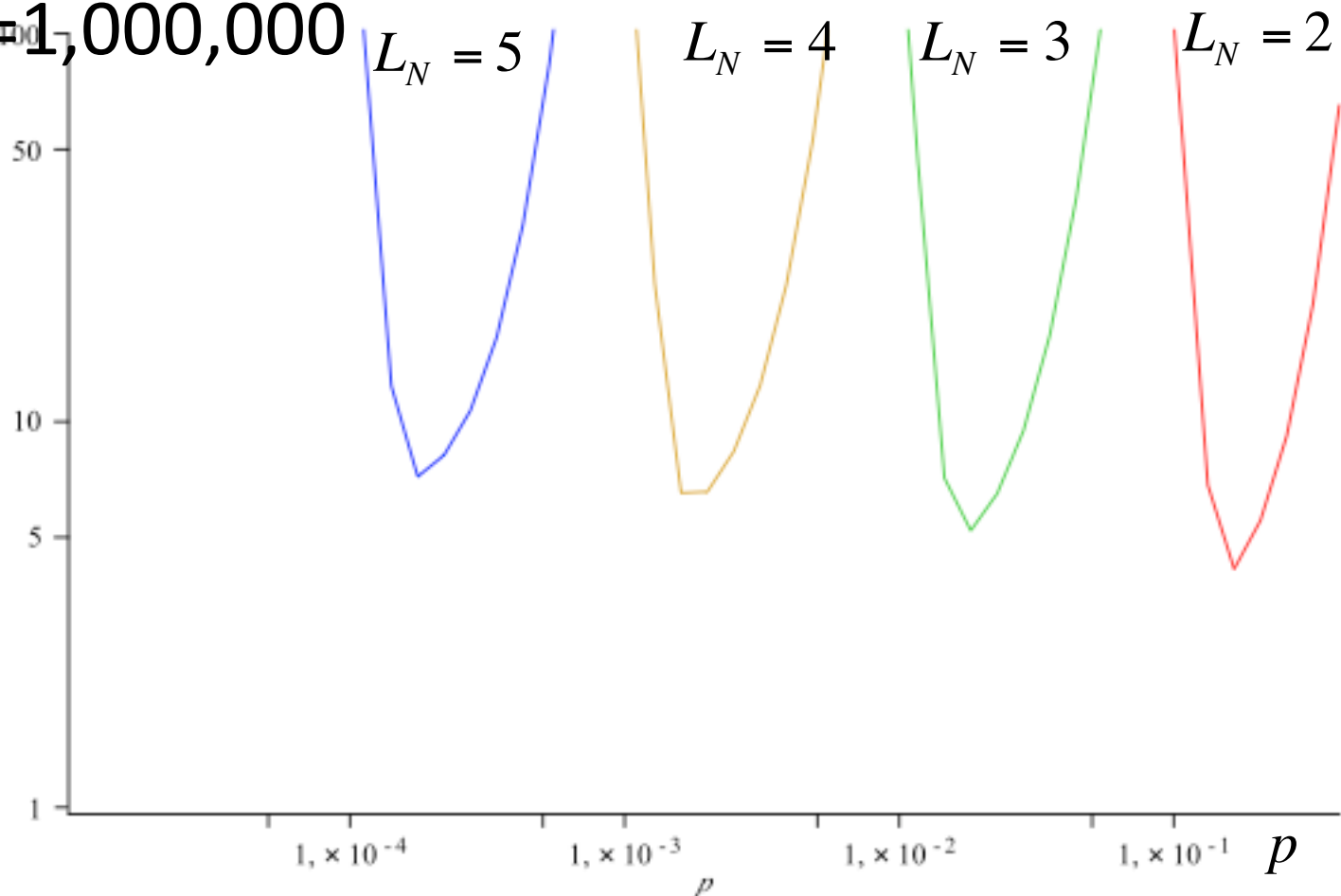
- Energy cost per election, $N=1,000,000$



Parameters of the algorithm

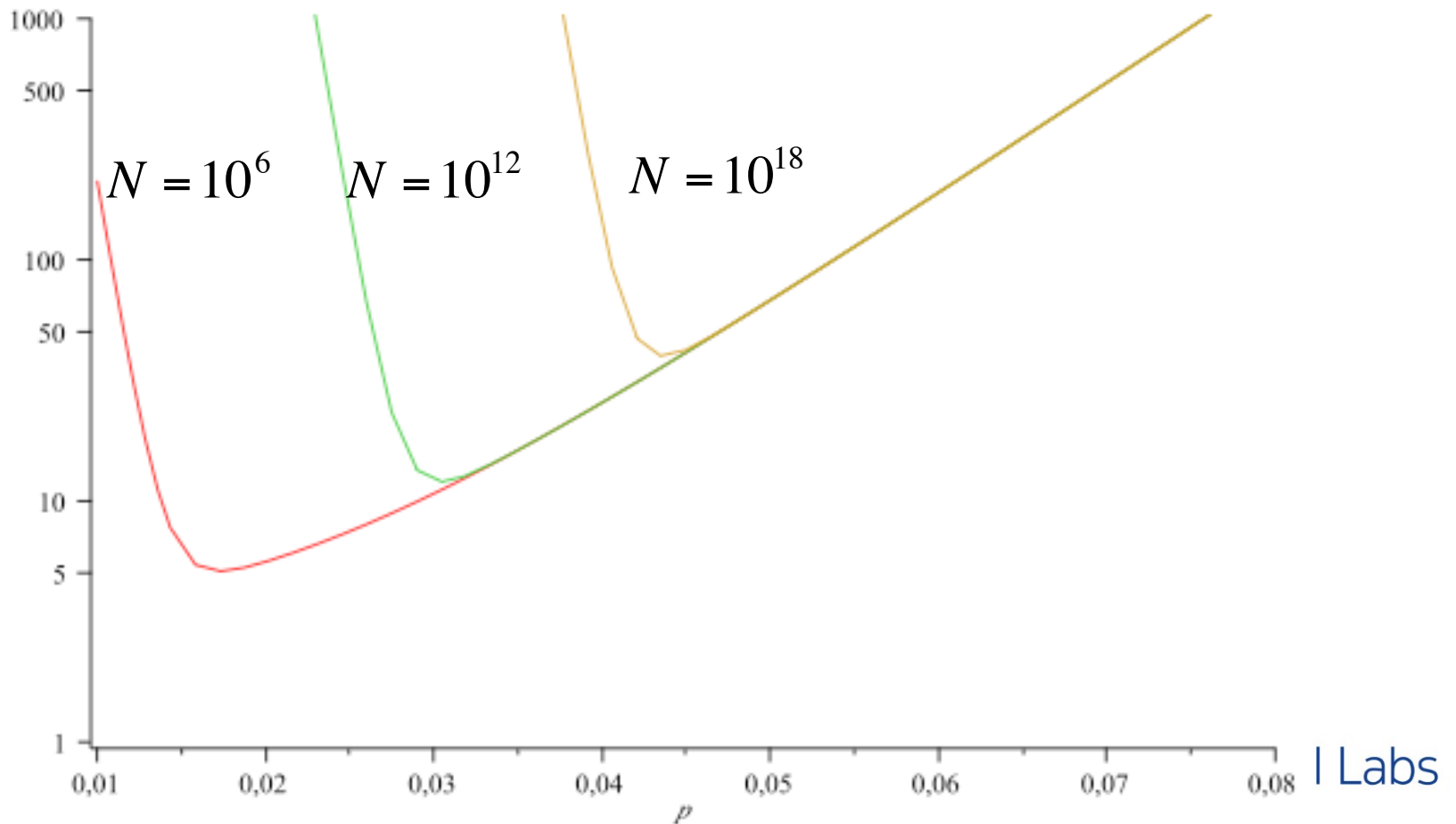
- Energy cost per **successful** election,

$N=1,000,000$



Extensibility of the Algorithm

Energy cost per successful election for $L_N = 3, N = 10^6, 10^{12}, 10^{18}$



Conclusion

- Random access
 - Infinite population model
 - channel transparency
 - Finite population model
 - Packet Delay proportional to N
 - Queues form on node,
 - unfairness and starvation may occur.
- **Green** collision resolution and leader election
 - Need a known upper bound N of population size
 - Intermediate with channel transparency
 - Packet Delay proportional to $\log \log N$
 - Energy per packet proportional to $O(\sqrt[10]{N})$