

Ressource Allocation Schemes for D2D Communications

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Outline

General Introduction

Hetnets - D2D with Non real Time Data

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- ▶ Future 5G networks must support the 1000-fold increase in traffic demand
- ▶ New physical layer techniques, e.g. Massive MIMO, Millimeter wave (mmWave)
- ▶ New network architecture
- ▶ Local caching of popular video traffic at devices and RAN edge
- ▶ Network topology
- ▶ Device-to-Device (D2D) communications

General Introduction

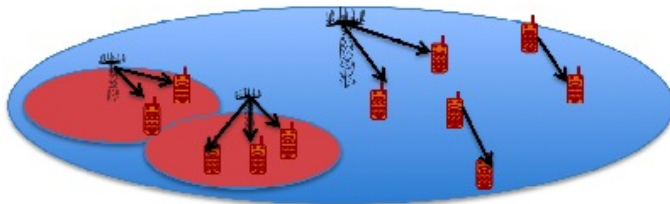


Figure: Wireless network

Resource Allocation in Wireless Networks

- ▶ Resource Allocation improves the network performance
- ▶ Resources: slots, channels, power, beamformers,...
- ▶ Hetnets architecture (small cells, macro cells, D2D)
- ▶ Existence/Non-existence of a central entity that can handle the allocation (e.g. D2D) and the amount of information exchange (signaling) between transmitters.
- ▶ Connectivity of the nodes (e.g. D2D communication).
- ▶ Services: voice, video streaming, interactive games, smart maps, ...
- ▶ Typical Utility functions: throughput, outage, packet error rate, transmit power,...
- ▶ Availability of the system state information (e.g. CSI).
- ▶ Low signaling overhead, low complexity solutions

Example of System Model

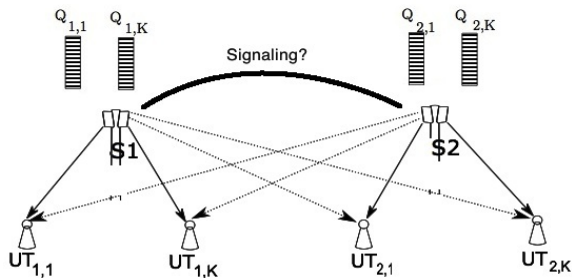


Figure: System Model

Existing Formulations of the Beamforming Allocation Problem

- ▶ Usually we define a continuous and nondecreasing function $f_{i,j}$ w.r.t. SINR (e.g. $\text{Log}(1 + \Lambda_{i,j})$)
- ▶ The utility of the network is $g(f_{1,1}, \dots, f_{i,j}, \dots)$ where g is continuous and nondecreasing w.r.t to each $f_{i,j}$
- ▶ Two main issues: complexity and signaling overhead (centralized/decentralized)

$$\begin{aligned} \max_{\mathbf{w}_{i,j} \forall i,j} \quad & g(f_{1,1}, \dots, f_{i,j}, \dots) \\ \text{s.t.} \quad & h(\Lambda_{1,1}, \dots, \Lambda_{i,j}, \dots) \leq 0 \end{aligned} \tag{1}$$

Existing Formulations of the Beamforming Allocation Problem

- ▶ Examples:
 - ▶ Sum or weighted sum: $\sum_{i,j} f_{i,j}(\Lambda_{i,j})$
 - ▶ Proportional Fairness: $\sum_{i,j} \log(f_{i,j}(\Lambda_{i,j}))$
 - ▶ MaxMin Fairness: $\max_{\mathbf{w}_{i,j}} \min_{i,j} f_{i,j}(\Lambda_{i,j})$
- ▶ Constraint $h(\Lambda_{1,1}, \dots, \Lambda_{i,j}, \dots) \leq 0$
 - ▶ $\Lambda_{i,j}^{\text{DL}} \geq \gamma_{i,j} \quad \forall i,j$: Not convex (but can be reformulated)
 - ▶ $\sum_j \mathbf{w}_{i,j}^H \mathbf{w}_{i,j} \leq P_{\max}^i$: convex

Complexity of Optimization Problems

- ▶ Constraint $\Lambda_{i,j}^{\text{DL}} \geq \gamma_{i,j} \quad \forall i,j$; utility: $\sum_{i,j} \mathbf{w}_{i,j}^H \mathbf{w}_{i,j}$
- ▶ Constraint $\sum_j \mathbf{w}_{i,j}^H \mathbf{w}_{i,j} \leq P_{\max}^i$; Other utility functions

Table: Complexity

Objective function	MIMO	Single Antenna
Weighted Sum	NP-hard	NP-hard
Proportional Fairness	NP-hard	Convex
MaxMin Fair	Quasi-Convex	Quasi-Convex
Harmonic Mean	NP-hard	Convex
Sum Power	Convex	Linear

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Outline

General Introduction

Hetnets - D2D with Non real Time Data

Energy Efficient Beamforming Allocation ¹

- ▶ Hetnets architecture
- ▶ Delay tolerant traffic (flexibility to dynamically allocate resources over the fading channel states)
- ▶ Decentralized Solution (Lyapunov Optimization)
- ▶ Simple online solutions based only on the current knowledge of the system state
- ▶ Only local knowledge of CSI is required
- ▶ Does not require a-priori the knowledge of the statistics of the random processes in the system
- ▶ Joint design of feedback and beamforming

¹S. Lakshminaryana, M. Assaad and M. Debbah, "Energy Efficient Cross Layer Design in MIMO Systems," in IEEE JSAC, Special issue on Hetnets, 33 (10), pp. 2087-2103, Oct. 2015.

Problem Formulation

- ▶ The transmission power by each transmitter
 $P_i[t] = \sum_{j=1}^K \mathbf{w}_{i,j}^H[t] \mathbf{w}_{i,j}[t]$, $i = 1, \dots, N$.
- ▶ The optimization problem is to minimize the time average power subject to time average QoS constraint

$$\min \quad \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} \mathbb{E} \left[\sum_{i=1}^N P_i[t] \right] \quad (2)$$

$$\text{s.t.} \quad \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} \mathbb{E} [\gamma_{i,j}[t]] \geq \lambda_{i,j}, \quad \forall i, j \quad (3)$$

$$\sum_{j=1}^K \mathbf{w}_{i,j}^H[t] \mathbf{w}_{i,j}[t] \leq P_{\text{peak}} \quad \forall i, t \quad (4)$$

where P_{peak} is the peak power

Static Problem

► Static Problem

$$\min \sum_{i,j} \mathbf{w}_{i,j}^H \mathbf{w}_{i,j} \quad (5)$$

$$\text{s.t.} \quad \frac{|\mathbf{w}_{i,j}^H \mathbf{h}_{i,i,j}|^2}{\sum_{\substack{(n,k) \\ \neq (i,j)}} |\mathbf{w}_{n,k}^H \mathbf{h}_{n,i,j}|^2 + \sigma^2} \geq \gamma_{i,j}, \quad \forall i,j \quad (6)$$

$$(7)$$

where $\gamma_{i,j}$ is the instantaneous target SINR of UT $_{i,j}$.

Lyapunov Optimization

- ▶ Suboptimal solution using Lyapunov optimization approach ².
- ▶ Lyapunov vs. MDP base approach
- ▶ Nonconvex static problems but can be solved using SDP
- ▶ The complexity of our solution is at most $O(N * N_t^3)$. (usually $O(N + N_t^2)^{3.5}$ for SDP)
- ▶ Our solution is distributed (based on local CSI)
- ▶ The transmitters have to exchange the virtual queues (signaling overhead « CSIs)

Main Result

Optimality gap: $O(C_1 / V)$; Delay: $O(V)$

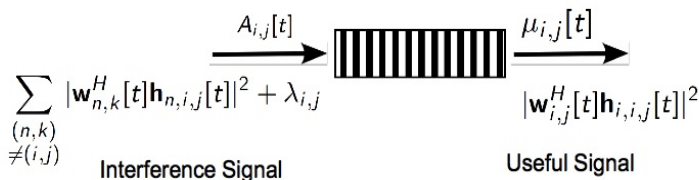
²M. Neely, Stochastic Network Optimization with Application to Communication and Queueing Systems. Morgan & Claypool, 2010.

Lyapunov Optimization - More details

- The QoS metric which we denote by $\gamma_{i,j}[t]$ is

$$\gamma_{i,j}[t] = |\mathbf{w}_{i,j}^H[t]\mathbf{h}_{i,i,j}[t]|^2 - \nu_{i,j} \sum_{\substack{(n,k) \\ \neq (i,j)}} |\mathbf{w}_{n,k}^H[t]\mathbf{h}_{n,i,j}[t]|^2 \quad (8)$$

- Virtual queue evolves as follows $Q_{i,j}[t+1] = \max(Q_{i,j}[t] - \mu_{i,j}[t], 0) + A_{i,j}[t]$ where $A_{i,j}[t] = \nu_{i,j} \sum_{\substack{(n,k) \\ \neq (i,j)}} |\mathbf{w}_{n,k}^H[t]\mathbf{h}_{n,i,j}[t]|^2 + \lambda_{i,j}$ and $\mu_{i,j}[t] = |\mathbf{w}_{i,j}^H[t]\mathbf{h}_{i,i,j}[t]|^2$



Queue Model

- ▶ Let $\mathbf{Q}(t)$ a discrete time queueing system with K queues.
- ▶ For each queue i , $a_i(t)$ and $r_i(t)$ denote the arrival and departure processes
- ▶ Arrivals occur at the end of slot t
- ▶ The $\mathbf{Q}(t)$ process evolves according to the following discrete time dynamic:

$$Q_i(t+1) = [Q_i(t) - r_i(t)]^+ + a_i(t) \quad (9)$$

- ▶ The time average expected arrival process satisfies
 - ▶ There exists $0 < \lambda_i < \infty$ such that

$$\lim_{t \rightarrow \infty} \frac{1}{t} \sum_{\tau=0}^{t-1} \mathbb{E}(a_i(\tau)) = \lambda_i \quad (10)$$

- ▶ There exists $0 < A_{max} < \infty$ such that $\forall t$

$$\mathbb{E}\{a_i^2(t) | \Omega[t]\} \leq A_{max} \quad (11)$$

- ▶ $\Omega[t]$ represents all events (or the history) up to time t
- ▶ Similar assumptions for the departure process $r_i(t)$ ($r_i(t) \leq r_{max}$).

Queue Stability

Definition

A discrete time process $\mathbf{Q}(t)$ is rate stable if

$$\lim_{t \rightarrow \infty} \frac{1}{t} \mathbf{Q}(t) = 0 \quad w.p.1$$



Definition

A discrete time process $\mathbf{Q}(t)$ is mean rate stable if

$$\lim_{t \rightarrow \infty} \frac{1}{t} \mathbb{E} [\mathbf{Q}(t)] = 0$$



Definition

A discrete time process $\mathbf{Q}(t)$ is strongly stable if

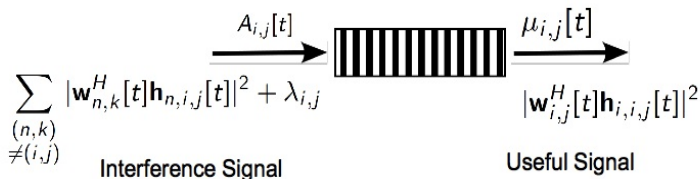
$$\lim_{t \rightarrow \infty} \sup \frac{1}{t} \sum_{\tau=1}^t \mathbb{E} [\mathbf{Q}(\tau)] < \infty$$

Lyapunov Optimization - More details

- ▶ The notion of strong stability of the virtual queue is given as $\sum_{i,j} \bar{Q}_{i,j}[t] < \infty$.
- ▶ Strong stability of the queues implies

$$\bar{A}_{i,j}[t] - \bar{\mu}_{i,j}[t] \leq 0 \quad \forall i,j. \quad (12)$$

- ▶ Virtual Queue stability implies that the time average constraint is satisfied
- ▶ Modified optimization problem - Minimize energy expenditure subject to virtual queue-stability



Lyapunov Optimization - More details

- ▶ $V(\mathbf{Q}[t]) = \frac{1}{2} \sum_{i,j} (Q_{i,j}[t])^2$. The Lyapunov function is a scalar measure of the aggregate queue-lengths in the system. We define the one-step conditional Lyapunov drift as

$$\Delta(\mathbf{Q}[t]) = \mathbb{E} \left[V(\mathbf{Q}[t+1]) - V(\mathbf{Q}[t]) | \mathbf{Q}[t] \right] \quad (13)$$

- ▶ Lyapunov Optimization [Neely2006] - If there exist constants $B > 0, \epsilon > 0, V > 0$ such that for all timeslots t we have,

$$\Delta(\mathbf{Q}[t]) + V \mathbb{E} \left[\sum_i P_i(t) | \mathbf{Q}[t] \right] \leq B - \epsilon \sum_{i,j} Q_{i,j}(t) + V P_{inf}$$
- ▶ Time average energy expenditure is bounded distance from P_{inf}
- ▶ Allows us to consider the result of queuing stability and performance optimization using a single drift analysis.

Lyapunov Optimization - Decentralized Solution

- Each BS must solve the optimization problem given by

$$\begin{aligned} \max_{\mathbf{w}} \quad & \sum_j \mathbf{w}_{i,j}^H \mathbf{A}_{i,j} \mathbf{w}_{i,j} \\ \text{s.t.} \quad & \sum_j \mathbf{w}_{i,j}^H \mathbf{w}_{i,j} \leq P_{\text{peak}}. \end{aligned} \quad (14)$$

where the matrix $\mathbf{A}_{i,j} = \mathbf{Q}_{i,j} \mathbf{H}_{i,i,j} - \sum_{\substack{(n,k) \\ \neq (i,j)}} \nu_{n,k} \mathbf{Q}_{n,k} \mathbf{H}_{i,n,k} - \mathbf{V}\mathbf{I}$ and

$$\mathbf{H}_{i,n,k} = \mathbf{h}_{i,n,k} \mathbf{h}_{i,n,k}^H.$$

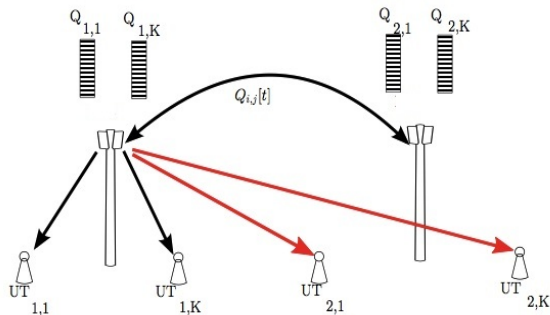


$$P_{i,j}^{\text{opt}} = \begin{cases} P_{\text{peak}} & \text{if } j = j^* \text{ and } \lambda^{\max}(\mathbf{A}_{i,j^*}) > 0 \\ 0 & \text{else.} \end{cases} \quad (15)$$

$$j^* = \arg \max_j \lambda^{\max}(\mathbf{A}_{i,j}).$$

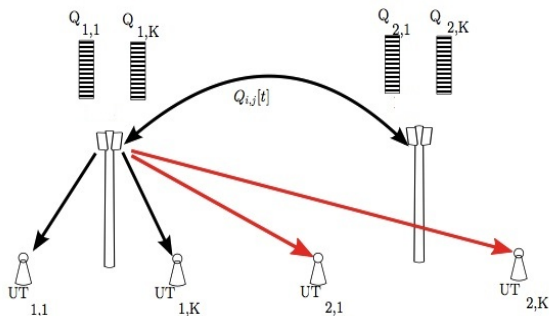
Lyapunov Optimization - Decentralized Solution

- ▶ The transmitters have to exchange the queue-length information
- ▶ No CSI exchange required



Lyapunov Optimization - Decentralized Solution

- ▶ The virtual queue is strongly stable and for any $V \geq 0$, the time average queue-length satisfies $\sum_{i,j} \bar{Q}_{i,j}^{\text{opt}}[t] \leq \frac{C_1 + VNKP_{\text{peak}}}{\epsilon}$ and the time average energy expenditure yields, $\sum_{i=1}^N \bar{P}_i^{\text{opt}}[t] \leq P_{\text{inf}} + \frac{C_1}{V}$.



Delayed Queues

- ▶ The transmitters exchange the queue-length information with a delay of $\tau < \infty$ time slots.
- ▶ Each transmitter i knows $Q_{i,j}[t] \forall j$ and $Q_{n,k}[t - \tau], \forall n \neq i, k$.

Main Result

Optimality gap: $O((C_1 + C_2)/V)$; Delay: $O(V)$

Lemma

There exists a $0 \leq C_2 < \infty$ independent of the current queue-length $Q_{i,j}[t], \forall i, j$ such that,

$$\sum_{i,j} \text{Tr}(\mathbf{A}_{i,j}[t] \mathbf{W}_{i,j}^{\text{opt}}[t]) \leq \sum_{i,j} \text{Tr}(\mathbf{A}_{i,j}[t] \mathbf{W}_{i,j}^{\text{del}}[t]) + C_2 \forall t. \quad (16)$$

Numerical Result I

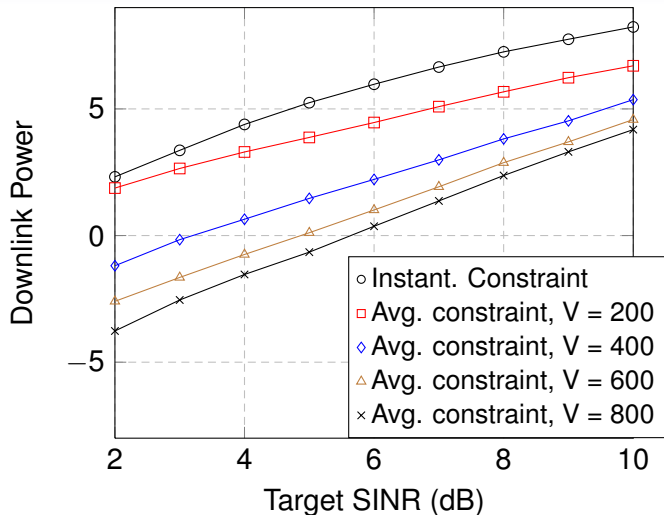
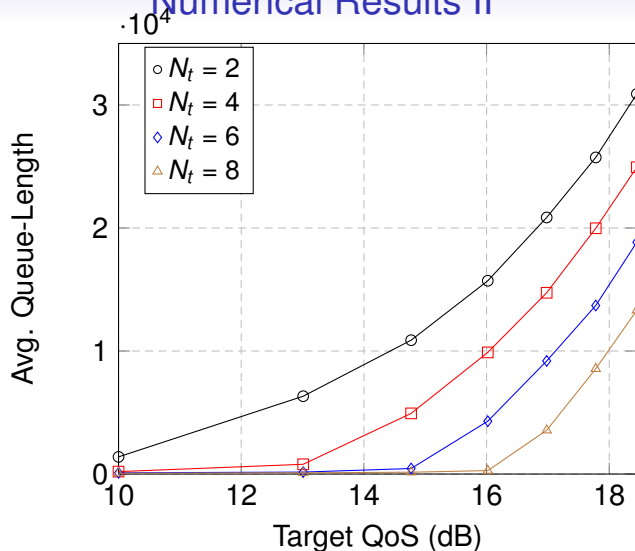


Figure: each transmitter is connected to two UTs, $N_t = 5$,

Numerical Results II

Figure: $V = 100$.

Numerical Results III

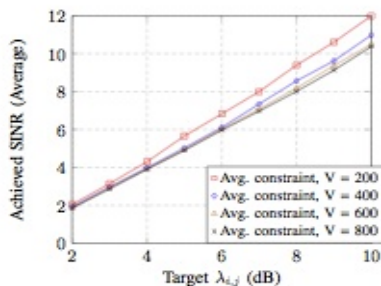


Figure: Achieved time average SINR Vs target QoS, each transmitter is connected to two UTs, $N_t=5$.

Lyapunov Optimization - Some References

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Queueing Stability in MIMO Systems

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Queueing Stability in MIMO Systems

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- ▶ etc...

End of the Talk

Thank you for listening!
Questions??