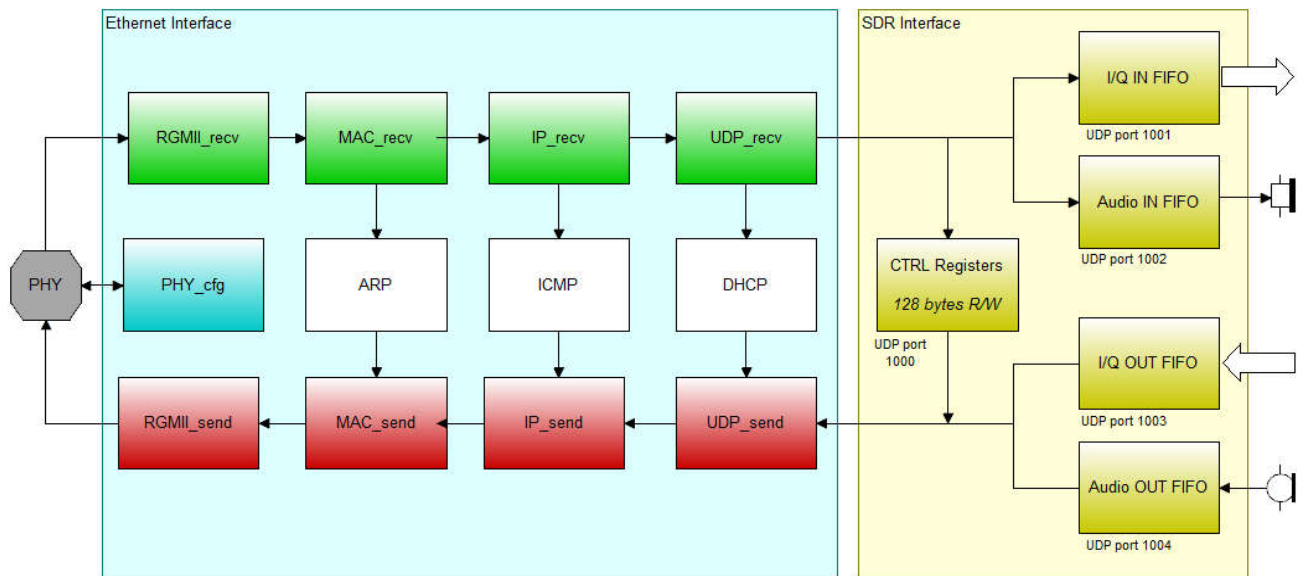


openHPSDR Ethernet Protocol

V3.8

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Hermes Network Interface



Revisions

Rev	Date	Changes	By
1.0	20 June 2015	First release	VK6PH
1.1	27 June 2015	Changed Hermes Lite reference number from 5 to 6. Added DSP clock frequency and number of DDCs implemented to Discovery reply. Enable either DDC and DUC frequency or phase word to be sent to hardware. Added memory mapped registers.	VK6PH KF7O
1.2	1 July 2015	Added version of Protocol implemented and frequency or phase word required to Discovery reply packet.	VK6PH
1.3	2 July 2015	Corrected network format to be Network Byte Order, or Big-Endian.	N2ADR
1.4	1 Aug 2015	Added Wideband packets per frame to General Packet	VK6PH

1.5	27 Aug 2015	<p>Corrected General Packet source and destination ports. Corrected Microphone and Wideband data packets source port. Removed default Wideband data rate, added default samples per frame for ANAN-10E. Removed blank page 15. Changed discovery hardware identification numbers to allow ANAN-10E to be identified. Added full hardware description option for Discovery reply.</p> <p>Added hardware time out should communications with host be lost.</p>	<p>VK6PH</p> <p>G4ELI</p>
1.6	6 Sept 2015	Added 10MHz reference PLL locked to High Priority packet	G4ELI
1.7	14 Sept 2015	<p>Added data format where 2's complement used. Added calibration information e.g. max I&Q value for -20dBm input.</p> <p>Corrected Envelope PWM_min and max settings, corrected byte 38 in General Packet to SDR, Corrected DDCK,0 in Figure 3.</p>	<p>VK6PH</p> <p>IW0HDV</p>
1.8	16 Oct 2015	Added Discovery reply for ANAN-100E, clarified where DSP clock frequency is obtained.	VK6PH
1.9	24 Oct 2015	Various typographical errors corrected. Clarified number of samples per Ethernet packet for Audio and I&Q data. Added Appendix C – block diagram of Alex filters.	G4ELI, VK6PH
2.0	28 Oct 2015	Clarified Open Collector drive. Added NOTE1 and 2 on page 3 relating to PureSignal operation, DUC I&Q data and DUC architecture. Added number of general purpose ADCs support to Appendix A. Expanded Alex filter operation in Appendix C. Added note on Page 19 relating to synchronous and multiplexed DDC restrictions.	G4ELI, VK6PH, KC9XG
2.1	9 Nov 2015	Added additional Alex filter descriptions in Appendix D. Increased support for Alex filters from 4 to 8. NOTE: Open Collector register in High Priority packet has moved due to this. Added support for XLM format Discovery reply. Clarified PA enable and Envelope Tracking bits. Added note that ANAN-10E only has 31dB attenuator. Corrected number of I&Q samples in DDC packet. Corrected number of bytes in DDC packet. Added conversion constants for supply volts, exciter, Forward and Reverse power to Appendix A.	<p>VK6PH, KC9XG,</p> <p>G4ELI</p>
2.2	30 Nov 2015	<p>Removed conversion constants on page 38 since now in Appendix A. Corrected number of DDC I&Q samples per packet in Appendix A. Updated Alex diagrams in Appendix D.</p> <p>Corrected number of DUC I&Q packets. Corrected DDCK0 default port in Fig3. Added a note relating to the sequence that DDC I&Q samples are received in.</p>	<p>VK6PH, G4ELI,</p> <p>KC9XG</p>
2.3	16 Dec 2015	<p>Set bits 26 & 27 in DUC Specific Packet to reserved. Added ability to send Discovery to hardware IP address or the broadcast address specific of the current subnet. – see page5. Added note regarding connecting to running hardware – see page 34, Byte 4.</p> <p>Replaced 100E with 100B on page 34. Added description of DAC data feedback via a DDC for PureSignal use – note 1 on page 3 and Byte 17</p>	<p>VK6PH, G4ELI,</p> <p>W5WC</p>

		on page 17.	
2.4	26 Dec 2015	Corrected Byte 1443 on page 17. Corrected length of IQ samples – page 28.	VK6PH, W5WC, G0ODC
2.5	28 Dec 2015	High Priority to Hardware Byte 4 bits [5] / [6] indicates I&Q FIFO empty/full – see page 38.	VK6PH, G0ODC, G4ELI
2.6	20 Feb 2016	Replace ‘receiver’ with DDC, replace ‘Rxn’ with DDCn, replace ‘transmitter’ with DUC, replace Txn with DUCn. Added note re DUC I&Q FIFO and re-sampling - Page 3. Added note re Drive level operation - Page 3. Changed DAC I&Q FIFO from empty/full to almost empty/almost full – Page 38. Added note that whilst in standby the PTT output and Open Collector outputs will be deactivated – Page 3.	VK6PH, WU2O, G4ELI
2.7	20 Mar 2016	Added hardware timer enable – General Packet, Byte 38 [0] – Page 13 and Page 3.	VK6PH
2.8	13 Apr 2016	Corrected Q Sample 237 on Page 45.	M6NNB
2.9	4 Aug 2016	Direct Fourier Conversion support added – Page 4. Added option for Little-Endian and I&Q data formats – see Page 15, Byte 39 and Page 37, Byte 22.	VK6PH, AD0ES
3.0	17 Aug 2016	Reduced Mic and Rx Audio packet lengths to 64 Samples to reduce latency – see Page 29 and 42.	VK6PH, NR0V
3.1	29 Oct 2016	Reserved Byte 40 of General Packet to SDR and Byte 23 of Discovery Reply Packet for future use.	AD0ES
3.2	29 Dec 2016	Corrected Open Collector data, Byte 1401, page 28. Added comment re reverse CW input, page 22. Page 23, byte 51 – line in gain explained.	G4ELI
3.3	12 Feb 2017	Added support for Orion MkII (ANAN-8000DLE) boards plus second Alex filter. See Page28, Page 35, byte 12 and Page 85.	W5WC
3.4	10 Mar 2017	Corrected BPF selections for Orion MkII (ANAN-8000DLE). Added Tx LPF selection and block diagram of ANAN-8000DLE. See pages 89 &90.	W5WC, KC9XG
3.5	3 Apr 2017	Added IO2, IO4, IO5, IO6 & IO8 inputs to High Priority Status packet, see Byte 59, page 41. Added byte 1400 to the High Priority Data packet to provide Transverter support and Audio Mute for the ANAN-8000DLE, page 28.	K5SO
3.6	20 May 2017	Replaced ANAN-8000DLE block diagram with corrected version. Page 89.	KC9XG

3.7	14 Jul 2018	Corrected number of audio and mic samples per packet from 720 to 64, Page 55 onwards. DUC I&Q FIFO almost full and almost empty no longer supported, see pages 4 and 41. Updated ANAN-8000DLE drawing and added ANAN-7000DLE drawing and Alex data registers. Removed Mux facility since was duplication of synchronisation feature. Added note regarding switching between synchronous modes, page 2. Added note regarding speed High Priority Status packet is sent normally and during Tx, page 40	AD0ES, G4ELI, KC9XG, VK6PH
3.8	27 Mar 2019	Corrected sidetone level, Tx Specific Packet, Byte 6 – page 23, 0 – 127. Corrected Open Collector mappings – page 29. Added ‘Beta version’ of code – Discovery Reply Packet, byte 23. Added 16 bit check sum to programming data in order to verify correct receipt – Command Reply Packet, bytes 13 & 14. NOTE: Versions of FPGA code released after this date may include this feature. Please see individual board release notes.	VK6PH, G4ELI, N1GP

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The follow have provided input and review of the protocol during its development:

Warren - NR0V, Doug - W5WC, Joe - K5SO, Chen - W7AY, George - K9TRV, Leif – SM5BSZ, Simon - G4ELI, Vasiliy - K3IT, Tom - N5EG, Edson - PY2SDR, Dave - KV0S, Alex - VE3NEA, John – G0ODC, Francis - ON5RF, Alberto – I2PHD, David - WA8YWQ, Roger – W3SZ, Bob - G3UKB, Steve-K7FO, Scott – WU2O, Steve – AD0ES, Rick – N1GP.

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Thanks also to those contributors who wish to remain anonymous.

Purpose

This specification describes the protocol used to communicate with current and future openHPSR hardware. Its intended audience is hardware and software developers who wish to develop, or modify, hardware and software to use this architecture and protocol.

Architecture

The basic architecture is built on the concept of using UDP ports to send and receive signals and Command & Control data.

Some configuration settings will change infrequently and can be applied to all DDCs and DUCs. These 'General' settings need only be sent when the SDR hardware is first turned on or when a setting changes during operation.

Settings that need to change more frequently are sent to control registers associated with DDCs or DUCs.

Settings that require near real-time responses are sent as priority packets to specific UDP ports.

Where possible the protocol does not restrict the number of configurable resources. The number of fully independent DDCs, associated with a particular analogue to digital converter (ADC), can be configured using the General settings. Similarly, the number of DDCs or DUCs that may be combined synchronously is configurable.

The basic architecture for UDP data from the Host (i.e. PC, Tablet etc) is shown in Figure 1. The UDP ports here configure General Registers (where data changes infrequently after initialisation), DUC and DDC Specific Registers and High Priority Registers (where, for example, register settings change between receive and transmit).

Figure 2 illustrates the architecture for UDP data from the SDR hardware to the Host. The ports here include the Microphone data and both wide and narrow band DDC data ports.

In both diagrams some UDP ports are predetermined. Others are set by the user and/or depending on the actual number of ADCs and DACs available on the specific SDR hardware and the number of synchronous and non-synchronous DDCs and DUCs the user wishes to configure.

Figure 3 illustrates how multiple DDCs can be configured on a specific ADC. It also shows how a specific DDC can be configured to be synchronised with other DDCs configured on other ADCs.

In general, the input of a specific DDC can be fed from a selected ADC or, for PureSignal requirements, from the data being sent to a specific DAC. Each DDC can operate independently from all others i.e. its sampling rate is set independently.

Where no synchronous DDCs are selected then the output of the DDC directly feeds a FIFO and subsequently, using its designated port, the Ethernet PHY.

Where synchronous DDCs are selected then the data from these additional DDCs are sequentially passed to the FIFO associated with the base DDC. All synchronous DDCs must operate at the same sampling rate.

Synchronous DDCs are phase coherent and are used when Diversity reception and/or PureSignal processing is required.

NOTE: A large number of wide data paths within the FPGA have to be reconfigured in order to switch to/from synchronous mode. In order for this transition to operate correctly ALL required settings (e.g. sample rates, ADC selection etc) MUST be sent in the same configuration packet (i.e. DDC Specific Packet).

Failure to simultaneously set all configurations may result in amplitude and phase differences between the two synchronised receivers.

The maximum number of synchronous DDCs that can be selected per base DDC is equal to the number of ADCs.

The DDC follows the conventional architecture of CORDIC, CIC filters and sinc compensating FIR filter.

Figure 4 illustrates how multiple DUCs can be configured in synchronous mode. Presently, no openHPSDR SDR hardware is able to support more than one DAC. In which case data from the FIFO connect to port 1029 (default) is connected directly to the DUC and the selection of synchronous data is not supported.

The DUC is configured as a 5 stage CIC filter and CORDIC. Note that the Host I&Q data (24 bit I&Q data at 192ksps) directly feeds the CIC filter. In which case the transmitted signal will be -1dB at +/- 22kHz. For most modes this is acceptable but should wider bandwidths be required the designer may wish to include a sinc compensation filter in the Host software.

In order to overcome any potential latency issues between the Host and SDR Hardware, RF and sidetone generation for CW is done in the SDR Hardware. This includes applying a raised cosine profile to the leading and trailing edges of the CW RF and sidetone waveforms. An Iambic Keyer is also implemented and operates in Straight, simulated Bug and Iambic A or B.

Variable frequency and amplitude sidetone is also generated in the SDR Hardware.

Time stamping of DDC I & Q packets is in accordance with the VITA-49 specification for Fractional-seconds Timestamps.

For the current hardware implementation an arbitrary limit of 80 DDCs and 8 ADCs has been applied. These limits will be removed as hardware that is capable of exceeding these settings becomes available.

Compared with the previous openHPSDR Ethernet/USB protocol, numerous new features and facilities have been added. However, we should bear in mind the 'Second-system effect' - see

http://en.wikipedia.org/wiki/Second-system_effect

Detailed operation

Consider a network made up of multiple SDRs and multiple Hosts (e.g. PCs). Each SDR on the network has a unique IP address, and listens on fixed port 1024 for Discovery packets.

The following scenario outlines how SDRs and Hosts interact within a given network segment. It is important that multiple SDRs and multiple Hosts each running multiple applications be able to interact on one segment. Note that the term “SDR” applies to a single network connection (IP address); there may be many hardware ports associated with each single IP address.

To establish communication, one network Host will broadcast a Discovery to address <255.255.255.255:1024> from its own IP address and a source port number. In this example, assume it is from <192.168.1.10:8000>.

Every device listening on port 1024 will respond to this broadcast with a response to the Hosts IP address and source port with its IP address and port number. In this example, the SDR responds to <192.168.1.10:8000> from its own fixed address of <192.168.1.30:1024>. Now a command/response channel has been established between the SDR and the Host. This channel will be used for all SDR-to-Host and Host-to-SDR communications until one or more other streams are established.

Once a channel has been established then the General Registers and DDC and DUC Specific Registers should be set up. A High Priority packet should then be sent with the ‘run’ bit set in order to start data from the Hardware.

In order to recover from a network interruption, a Command & Control packet (i.e. any C&C packet) must be sent from the host to the hardware at least every second (every 100 mS is recommended). Should a C&C packet not be received, and the hardware is in the RUN state, then the hardware will switch out of the RUN state into standby.

Whilst in standby the PTT output and Open Collector outputs will be deactivated. This is to ensure the system can’t be let in a Transmit state following a network interruption.

The session can be re-started either by sending a High Priority Packet with the RUN bit set, if the same network session is still active, or a Discovery exchange followed by re-initiation of all C&C settings and thence a High Priority Packet with the RUN bit set.

The automatic hardware reset on network or PC software failure may be disabled for debugging purposes. See the General Packet for specific details.

The format of the Ethernet packets is generally consistent in that they all commence with a 32 bit sequence number. This enables the Host and Hardware to determine if packets have been lost.

In general, configuration data that is typically required by all SDR hardware is sent at the head of a packet. Settings that are specific to openHPSDR hardware are sent at the end of a packet. This leaves room in the middle of the packet for additional register settings to be included in the future without disturbing existing settings.

RF output from the DAC(s) is controlled via a Drive setting. With current openHPSDR hardware this setting controls the current available from the associated DAC and hence the RF output. The Drive setting for a particular power output will vary with frequency. However, since the exciter and PA forward power is available the PC software can calibrate the power output verses Drive setting to ensure consistency with frequency if desired.

NOTE1: The protocol provides for any ADC to be used for PureSignal RF and DAC feedback. However, due to FPGA size limitations and timing requirements, for all current implementations RF feedback will be via DDC0 and DAC feedback via DDC1. DAC data may be fed back by setting 'n' in ADC(n) equal to the number of ADCs fitted to the hardware.

NOTE2: The protocol enables a variable DUC I&Q sample width and sample rate. For all current openHPSDR implementations the sample width is set to 24 bits and sampling rate fixed at 192 kps. In current hardware the DUC I&Q FIFO is 4096 by 48 bits wide. If the hardware contains an Audio CODEC (sourcing microphone data and sinking received audio) then the rate of sending I&Q data to the FIFO may be determined by the rate at which microphone data is being received e.g. there will be a fixed relationship between the number of microphone samples received and I&Q samples sent. In which case the FIFO is unlikely to over or underrun.

However, if an Audio CODEC is not provided, or microphone and receiver audio is not sourced from the hardware (e.g. a USB headset) then the data sample rate of the mic and receiver data will most likely not match the sample rate of the hardware. In which case there is potential for the FIFO to over or underrun.

In order to prevent this situation the status of the I&Q FIFO (e.g. almost full or almost empty) is returned in the High Priority Status packet. The presence of the FIFO status is intended to enable the PC software to pace how I&Q packets are sent in order to avoid an over or underrun situation.(SEE NOTE in next paragraph).

Rather than discarding or duplicating audio and I&Q samples in order to match the required sampling rates, it is recommended that PC code developers implement a fractional re-sampler. Note that if an Audio CODEC is fitted, but microphone data is not sourced from it, then mic data packets will still be sent to the PC. In which case the PC code may use the rate that this data is received in order to determine the rate at which I&Q samples to the DUC should be sent. **NOTE:** For code released from the date of this document the status of the I&Q FIFO has been removed since PC code developers that indicated that it is not necessary.

In order to minimise DUC latency, I&Q data should be sent as soon as sufficient data is available to full a UDP packet i.e. it is not necessary, nor desirable, to wait until 4096 by 48 bit samples are available.

Direct Fourier Conversion (DFC) support. From V2.9 onwards the protocol supports DFC systems. These systems undertake all Digital Signal Processing in software rather than some being done in an FPGA and the balance in software. The main additions are the ability to support Little-Endian data formats and to use either the existing 3 Byte DDC I&Q data format or float or double formats. The Discovery reply packet indicates what Endian and data formats are supported. The first general packet sent in response to the discovery reply packet is used to indicate which of the available choices will be used for all further packet transfers.

NOTE3: This document assumes an FPGA based hardware system is being used that uses Big-Endian data format and 3 Byte DDC I&Q data and indicates where additional options are available for DFC based systems.

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openHPSDR Host to Hardware Protocol

The Host will communicate with the Hardware using standard UDP protocol. For FPGA based hardware Byte order shall be MSB first (Network Byte Order, or Big-Endian) and all values are interpreted as unsigned integers unless otherwise noted. For DFC based software systems Big-Endian or Little-Endian Byte order may be supported in addition to float or double data formats. The Discovery response packet indicates the options available.

IP and UDP headers are as per UDP/IP standards.

Key:

IP Header (24 bytes)
UDP Header (8 bytes)
UDP Data (variable bytes)

Bits Bytes	0-7	8-15	16-23	24-31	32- 39	40-47	48-55	56-63
0	Version/IHL	Type of Service	Total Length		Identification		Flags/Fragment Offset	
8	TTL	Protocol	Header Checksum		Source IP Address			
16	Destination IP Address				IP Options			Pad
24	Source Port		Destination Port		UDP Length		UDP Checksum	
32... 1443	UDP Data							

Future diagrams will only show the UDP Data with a starting byte reference of zero.

DISCOVERY PACKET

A Discovery packet is sent from a Host in order to determine what SDRs are present on the network, and if so, how many. The format is as follows:

	Discovery - PC to Hardware	
Byte	To Port 1024	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	0x02	Command - Discovery
5		Zero
6		Zero
7		Zero
8		Zero
.....		
59		Zero

Destination Address

This may either be sent to the IP address of a specific SDR or a **broadcast** to Ethernet address 255.255.255.255 or the specific broadcast address of the current subnet.

Destination Port

This will be 1024.

Sequence Number

A 4-byte integer set to 0x00000000.

The hardware will respond with the relevant Command Reply Packet.

NOTE: The discovery packet will always use this format irrespective of what Endian mode is selected.

ERASE PACKET

An Erase packet is sent from a Host in order to erase the EEPROM on the hardware prior to programming it. The format is as follows:

	Erase Command - PC to Hardware	
Byte	To IP Address of Hardware and Port 1024	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	0x04	Command - Erase
5	Zero	
6	Zero	
7	Zero	
8	Zero	
...		
59	Zero	

Destination Address

This will be the Ethernet address assigned to the hardware.

Destination Port

This will be 1024.

Sequence Number

A 4-byte integer set to 0x00000000.

The hardware will respond with a Command Reply Packet confirming receipt of the Erase command and a subsequent reply when the erase has completed.

NOTE: Larger EEPROMS can take up to 15 seconds to erase. The Host program should include a timer such that if a reply has not been received within this time the user should be prompted to re-try.

PROGRAM PACKET

A Program packet is sent from a Host in order to program the EEPROM on the hardware. The format is as follows:

	Program Command - PC to Hardware	
Byte	To IP Address of Hardware and Port 1024	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	0x05	Command - Program
5	# of blocks [31:24]	
6	# of blocks [23:16]	
7	# of blocks [15:8]	
8	# of blocks [7:0]	
9	Program data 0	
10	Program data 1	
11	Program data 2	
12	Program data 3	
13	Program data 4	
14	Program data 5	
15	Program data 6	
....		
264	Program data 255	

Destination Address

This will be the Ethernet address assigned to the hardware.

Destination Port

This will be 1024.

Sequence Number

A 4-byte unsigned integer representing a sequence of packets from this port. The sequence starts at 0x00000000, increments for each new packet, and rolls over after exceeding 0xFFFFFFFF.

Each port decoder keeps a separate sequence count such that the hardware can determine if a decoder is missing samples in its stream. The sequence number is set to zero when initiating a Programming sequence.

Number of Blocks

A 4 byte integer that indicates the total number of 256 byte blocks that will be sent from the Host to the SDR hardware.

The hardware will respond with a Command Reply Packet that requests the next block of 256 bytes be sent.

NOTE: Should the Sequence Number in the Command Reply Packet not be consistent with the sent Sequence Number then the Program process should be aborted and the user given the option to restart. An affirmative response should initiate an Erase sequence followed by a Program sequence.

SET IP ADDRESS PACKET

A Set IP Address packet is sent from a Host in order to set the IP address of the hardware. Prior to setting an IP address a Discovery Packet should be sent and the MAC address of the hardware that's IP address is to be updated recorded.

The format is as follows:

Set IP Address - PC to Hardware		
Byte	Broadcast to Port 1024	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	0x03	Command - Set IP Address
5	ToMAC	MSB
6	ToMAC	
7	ToMAC	
8	ToMAC	
9	ToMAC	
10	ToMAC	LSB
11	AssignIP	MSB
12	AssignIP	
13	AssignIP	
14	AssignIP	LSB
15	Zero	
16	Zero	
17	Zero	
18	Zero	
....		
59	Zero	

Destination Address

This will be Ethernet address 255.255.255.255.

Destination Port

This will be 1024.

Sequence Number

A 4-byte integer set to 0x00000000.

MAC Address

A 6-byte value that contains the MAC address of the hardware that's IP address requires to be set.

IP Address

A 4-byte value that contains the IP address that is required to be set in the hardware's EEPROM. This may be increased in the future to enable IPv6 addressing. Setting the IP address to 0.0.0.0 will force the hardware to use DHCP addressing.

NOTE: After the IP address has been saved in EEPROM, which will take a few seconds, the successful setting of the IP address can be verified by sending a Discovery Command. The reply from the hardware will include the new IP address.

GENERAL PACKET TO SDR

The General packet contains data that sets infrequently changed settings of the transceiver subsystems. This data is sent when the UDP data changes and, optionally, periodically.

A General Packet should be sent following a successful Discovery exchange.

The format is as follows:

	Control Elements - PC to Hardware	
Byte	To IP Address of Hardware and Port 1024	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	0x00	Command
5	DDC Specific port [15:8]	Default Port # 1025
6	DDC Specific port [7:0]	
7	DUC Specific port [15:8]	Default Port # 1026
8	DUC Specific port [7:0]	
9	High Priority from PC port [15:8]	Default Port # 1027
10	High Priority from PC port [7:0]	
11	High Priority to PC port [15:8]	Default Port # 1025
12	High Priority to PC port [7:0]	
13	DDC Audio port [15:8]	Default Port # 1028
14	DDC Audio port [7:0]	
15	DUC0 I&Q port [15:8]	Base Port (Default Port # 1029)
16	DUC0 I&Q port [7:0]	
17	DDC0 port [15:8]	Base Port (Default Port # 1035), DDC1 = Base Port # + 1....DDC79 = Base Port # + 79
18	DDC0 port [7:0]	
19	Mic samples port [15:8]	Default Port # 1026
20	Mic samples port [7:0]	
21	Wideband ADC0 port [15:8]	Base Port (Default Port # 1027), ADC1 = Base Port # + 1....ADC7 = Base Port # + 7
22	Wideband ADC0 port [7:0]	
23	Wideband Enable [7:0]	WB0 = [0], WB1 = 1.....WB7 = [7]
24	Wideband Samples per packet [15:8]	Default 512
25	Wideband Samples per packet [7:0]	
26	Wideband sample size	Default 16 bits
27	Wideband update rate	0 to 255mS per frame, default 20ms per frame
28	Wideband packets per frame	Default to 32 (i.e. 16k by 16 bit samples per frame)
29	Memory mapped from PC port [15:8]	Default Port # xxxx
30	Memory mapped from PC port [7:0]	

31	Memory mapped to PC port [15:8]	Default Port # xxxx
32	Memory mapped to PC port [7:0]	
33	Envelope PWM_min	[15:8] Reserved for future use
34	Envelope PWM_min	[7:0] Reserved for future use
35	Envelope PWM_max	[15:8] Reserved for future use
36	Envelope PWM_max	[7:0] Reserved for future use
37	Bits - [0] Time stamp, [1] VITA-49, [2] VNA mode, [3] frequency or phase word	
38	Bit [0] set = enable hardware timer	
39	Select Endian and DDC I&D data format	See Below
40		Reserved for future use (AD0ES)
41...		Reserved for future use
56	Bits - Atlas bus configuration	[2:0] Configuration - see below
57	Bits - 10MHz ref source	[1:0] 10MHz reference source - see below
58	Bits - PA, Apollo, Mercury, clock source	[0] = PA, 1 = Apollo, [2] = Mercury Common Frequency, [3] Clock Source - see below
59	Bits - Alex(n) enable, 1= enable, 0 = disable	[0] = Alex 0....[7] = Alex7

Source Port

This will be set to the Source Port of the Host that initiated the Discovery Packet.

Destination Port

This will be set to 1024.

Sequence Number

A 4-byte integer set to 0x00000000.

Bytes 5 & 6

These two bytes form a 16 bit number that specifies the port that DDC Specific commands will be sent to. If set to zero the default port 1025 will be used.

Bytes 7 & 8

These two bytes form a 16 bit number that specifies the port that DUC Specific commands will be sent to. If set to zero the default port 1026 will be used.

Bytes 9 & 10

These two bytes form a 16 bit number that specifies the port that High Priority commands will be sent to. If set to zero the default port 1027 will be used.

Bytes 11 & 12

These two bytes form a 16 bit number that specifies the port that High Priority commands from the hardware will be sent from. If set to zero the default port 1025 will be used.

Bytes 13 & 14

These two bytes form a 16 bit number that specifies the port that DDC Audio will be sent to. If set to zero the default port 1028 will be used.

Bytes 15 & 16

These two bytes form a 16 bit number that specifies the port that DUC I&Q data will be sent to. If set to zero the default port 1029 will be used.

Bytes 17 & 18

These two bytes form a 16 bit number that specifies the port that DDC 0 I&Q data will originate from. If set to zero the default port 1035 will be used. Each subsequent DDC will increment the port number respectively e.g. DDC 1 will originate from Port + 1, DDC 2 from Port +2.....DDC 79 from Port + 79

Bytes 19 & 20

These two bytes form a 16 bit number that specifies the port that microphone or line in data will originate from. If set to zero the default port 1026 will be used.

Bytes 21& 22

These two bytes form a 16 bit number that specifies the port that wideband data from ADC0 will originate from. If set to zero the default port 1027 will be used. Each subsequent wideband data will increment the port number respectively e.g. ADC1 1 will originate from Port + 1, ADC 2 from Port +2.....ADC7 from Port + 7

Byte 23

Enable wideband data. A set bit enables Wideband data from an associated ADC to be sent e.g. bit 0 enables ADC0, bit1 enables ADC1 etc.

Bytes 24 & 25

These two bytes form a 16 bit number that specifies the number of wideband samples to use per packet. The default is 512 by 16 bits samples. (default only at present)

Byte 26

Sets the size of a wideband sample in bits. If set to zero the default of 16 bits will be used. (default only at present)

Byte 27

Sets the update rate of the wideband data in mS.

Byte 28

Sets the number of packets of wideband data sent per frame. The default is 32 (i.e. for defaults will send 32 * 512 = 16k by 16 bit samples per frame). For ANAN-10E this is fixed at 1024 by 16 bit samples per frame.

Bytes 29 & 30

These two bytes form a 16 bit number that specifies the port that memory mapped data from the PC will be sent to. If set to zero the default port xxxx will be used.

Bytes 31 & 32

These two bytes form a 16 bit number that specifies the port that memory mapped data to the PC will be sent to. If set to zero the default port xxxx will be used.

Bytes 33 & 34

These two bytes form a 16 bit number that specifies the minimum pulse width for the Envelope Tracking PWM.

Bytes 35 & 36

These two bytes form a 16 bit number that specifies the maximum pulse width for the Envelope Tracking PWM.

Byte 37

Bits when set activate the following functions; Bit[0] – Enable time stamping of DDC I&Q packets, Bit[1] - send data using VITA-49 format, Bit[2] – select VNA mode, Bit[3] selects if the DDC and DUC frequency data is sent as frequency ([3] = 0) (in Hz) or phase word ([3] = 1). A phase word is calculated as follows:

$$\text{phase_word}[31:0] = 2^{32} * \text{frequency(Hz)} / \text{DSP clock frequency (Hz)}$$

DSP clock frequency is dependent on the Board type and is either specified in Appendix A or, if hardware specific, then as part of the Discovery response as specified in Appendix B.

NOTE: Currently ALL openHPSDR FPGA code requires transmit and receive phase words.

Byte 38

Bit[0] when set enables the hardware reset timer. This should normally be set but can be clear to assist with software testing.

Byte 39

When set to zero, Big-Endian and I&Q data in 3 Byte format is selected. If indicated in the Discovery reply that they are supported then the following options can be selected.

- Bit 0 = 1 Use Big-Endian data format
- Bit 1 = 1 Use Little-Endian data format
- Bit 2 = 1 Use 3 Byte format for DDC I&Q data
- Bit 3 = 1 Use float for DDC I&Q data
- Bit 4 = 1 Use double for DDC I&Q data
- Bits 5, 6, 7 Reserved for future use

This data should be sent in the first General packet following a Discovery reply. This first packet must use the above format (i.e. Big-Endian). All subsequent packets will use the Endian data format specified in this first packet. See also Discovery Reply Packet, Byte 22.

Byte 56

This selects the Atlas bus Mercury DDC configuration as follows:

Configuration (Mercury)
000 - single DDC
001 - two DDCs
010 - three DDCs
011 - four DDCs

Byte 57

For Atlas based systems this selects the source of the 10MHz reference clock as follows:

10MHz reference source
00 = 10MHz reference from Atlas bus
01 = 10MHz reference from Penelope

10 = 10MHz reference from Mercury

Byte 58

Bit[0] when set enables the PA. When in VNA mode or when using the Transverter output, the PA stage may be disabled.

Bit[1] when set enables the Apollo automatic ATU if fitted.

For Atlas based systems, Bit [2] when set enables Mercury Common Frequency and Bit [3] selects the Clock Source - see below

Clock Source
0 = 122.88MHz source from Penelope
1 = 122.88MHz source from Mercury

Byte 59

Each bit enables the respective Alex filter board e.g. Bit [0] set enables Alex0, Bit [1] set enables Alex 1 etc.

DDC SPECIFIC PACKET

This sets the number of ADCs and the number of DDCs associated with each ADC. It also sets DDC parameters that change infrequently. This packet is sent following a successful Discovery command and prior to a Run command or when a parameter changes and, optionally, periodically.

The format of the packet is as follows:

Control Elements - PC to Hardware		
Byte	DDC Specific	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Number of ADCs	Max of 8 ADCs
5	Bits - Dither ADC0...7	[0] = ADC0, [1] = ADC1....[7] = ADC7
6	Bits - Random ADC0..7	[0] = ADC0, [1] = ADC1....[7] = ADC7
7	DDC Enable DDC0....DDC7	[0] = DDC0, [1]= DDC1.....[7] = DDC7
8	DDC Enable DDC 8.... DDC 15	
9	DDC Enable DDC 16.... DDC 23	
10	DDC Enable DDC 24.... DDC 31	
11	DDC Enable DDC 32.... DDC 39	
12	DDC Enable DDC 40.... DDC 47	
13	DDC Enable DDC 48.... DDC 55	
14	DDC Enable DDC 56.... DDC 63	
15	DDC Enable DDC 64.... DDC 71	
16	DDC Enable DDC 72.... DDC 79	[0] = DDC 72.....[7] = DDC 79
17	ADC DDC0	ADC(n) or DAC data that DDC 0 is allocated to
18	Sampling Rate DDC 0	[15:8] 48/96/192/384/768/1536
19	Sampling Rate DDC 0	[7:0]
20	CIC1 DDC 0	For Future use
21	CIC2 DDC 0	For Future use
22	Sample Size DDC0	Default 24 bits
23	ADC DDC 1	ADC(n) or DAC data that DDC 1 is allocated to.
24	Sampling Rate DDC 1	[15:8]
25	Sampling Rate DDC 1	[7:0]
26	CIC1 DDC 1	
27	CIC2 DDC 1	
28	Sample Size DDC 1	
29	ADC DDC 2	ADC(n) or DAC data that DDC 2 is allocated to.
30	Sampling Rate DDC 2	[15:8]
31	Sampling Rate DDC 2	[7:0]
32	CIC1 DDC 2	

33	CIC2 DDC 2	
34	Sample Size DDC 2	
35	ADC DDC 3	ADC(n) or DAC data that DDC 3 is allocated to.
36	Sampling Rate DDC 3	[15:8]
37	Sampling Rate DDC 3	[7:0]
38	CIC1 DDC 3	
39	CIC2 DDC 3	
40	Sample Size DDC 3	
41	ADC DDC 4	ADC(n) or DAC data that DDC 4 is allocated to.
42	Sampling Rate DDC 4	[15:8]
43	Sampling Rate DDC 4	[7:0]
44	CIC1 DDC 4	
45	CIC2 DDC 4	
46	Sample Size DDC 4	
...		
...		
485	ADC DDC 78	ADC(n) or DAC data that DDC 78 is allocated to.
486	Sampling Rate DDC 78	
487	Sampling Rate DDC 78	
488	CIC1 DDC 78	
489	CIC2 DDC 78	
490	Sample Size DDC 78	
491	ADC DDC 79	ADC(n) or DAC data that DDC 78 is allocated to.
492	Sampling Rate DDC 79	
493	Sampling Rate DDC 79	
494	CIC1 DDC 79	
495	CIC2 DDC 79	
496	Sample Size DDC 79	
...		
...		
1363	Sync DDC 0	[7:0] If bit set then DDC (n) is synched to DDC 0
1364	Sync DDC 1	[7:0] If bit set then DDC (n) is synched to DDC 1
1365	Sync DDC 2	[7:0] If bit set then DDC (n) is synched to DDC 2
...		
1442	Sync DDC 79	[7:0] If bit set then DDC (n) is synched to DDC 79
1443	Currently not used	

Destination Port

This may be set using the General packet and if zero defaults to 1025.

Sequence Number

A 4-byte integer set to 0x00000000.

Byte 4

Indicates the number of ADC that the hardware supports. This will be up to four on Atlas based systems, one on Hermes (ANAN-10/10E/100) and two on Angelia and Orion (ANAN-100D/200D),

Byte 5

A set bit activates Dither on the associated ADC e.g. Bit[0] activates ADC0, Bit[1] activates ADC1 etc.

Byte 6

A set bit activates Random on the associated ADC e.g. Bit[0] activates ADC0, Bit[1] activates ADC1 etc.

Byte 7

A set bit enables the associated DDC e.g. Bit[0] activates DDC 0, Bit[1] activates DDC 1 etc.

Bytes 8 to 16

A set bit enables DDCs 8 through 79.

Byte 17

Selects the ADC that DDC 0 is connected to where 0 connects to ADC0, 1 to ADC1 etc. For PureSignal use, to return the DAC data via a DDC, set the ADC selection to the number of ADCs fitted on the hardware.

Bytes 18 and 19

These two bytes form a 16 bit word that selects the sampling rate of DDC 0. Valid rates are 48/96/192/384/768/1536 ksp/s.

Bytes 20 & 21

For future use – to enable selection of the decimation rates of DDC 0 CIC filters.

Byte 22

Sets DDC 0 I&Q data sample size – default is 24 bits.

Bytes 23 to 496

Sets the ADC, sampling rate, CIC rates and data sample size of DDC 1 to 79 as above.

Bytes 1363 to 1442

Sets the DDC that DDC (n) is synchronised with. If a bit is set then DDC (n) is synchronised to the associated DDC. See the description of synchronous DDCs that follows.

Byte 1443

Currently not used.

Synchronous DDCs

NOTE: The sampling rate of all Synchronous DDCs must be the same and is the responsibility of the PC Control program to ensure this.

DDCs that are connected to a base DDC are usually disabled so they are not also sent from an Ethernet port. It is the responsibility of the PC Control program to ensure this.

The selection code will allow unsuitable or unnecessary DDC combinations e.g. DDC 0 + DDC 0 or DDC 0 + DDC 1 and DDC 1 + DDC 0. It is the responsibility of the PC Control program to prevent this.

There is no special provision for PureSignal operation. For PureSignal use, the PC Control program is responsible for setting the sampling rates, selecting DAC data as the source for one DDC and selecting either Synchronous or Multiplex operation of the RF and DAC DDC.

Synchronous DDCs: (where a number of DDCs are phase synchronous)

The maximum number of synchronised DDCs is equal to the number of ADCs.

For synchronous DDCs, if SyncDDC[n] is > 0 then DDC[n] is synchronised with another DDC(s). The bit(s) set indicate which DDC(s) are synchronised e.g. bit[0] = DDC0, bit[1] = DDC1.....bit[7] = DDC7.

All DDC's frequencies will be set to the frequency of the base DDC. If SyncDDC[n] is = 0 then there are no synchronous DDCs selected.

NOTE: For the time being, due to FPGA size limitations and timing closure issues only DDC0 and DDC1 may be synchronised with synchronised data presented from DDC0's output.

SyncDDC[n] bits [7:0] when set indicate which DDC(s) are synchronised e.g. bit[0] = DDC0, bit[1] = DDC1.....bit[7] = DDC7.

NOTE: For the time being, due to FPGA size limitations and timing closure issues, only DDC0 and DDC1 may be synchronised with synchronised data presented from DDC0 's output.

TRANSMITTER SPECIFIC PACKET

This sets the number of DACs and DUC parameters that change infrequently. This packet is sent following a successful Discovery command and prior to a Run command or when a parameter changes and, optionally, periodically.

The format of the packet is as follows:

Control Elements - PC to Hardware		
Byte	DUC Specific	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Number of DACs	Max of 4
5	Bits - Mode, CW, Reverse, Key Mode	See Below
6	Sidetone Level	
7	Sidetone Frequency (Hz)	[15:8]
8	Sidetone Frequency (Hz)	[7:0]
9	Keyer Speed	
10	Keyer Weight	
11	Hang delay	[15:8]
12	Hang delay	[7:0]
13	RF Delay	
14	DUC0 Sampling Rate	[15:8]
15	DUC0 Sampling Rate	[7:0]
16	DUC0 Bits	
17..25		Reserved for future use
26	DUC0 Phase Shift (0 - 359 degrees)	[15:8] Reserved for future use
27	DUC0 Phase Shift	[7:0] Reserved for future use
28..33		Reserved for future use
...		
...		
50	Bits - line in, mic boost, Orion mic	See Below
51	Line in gain	
52..58		Reserved for future use
59	Step Attenuator ADC0 on DUC0 (0 - 31dB)	Reserved for future use

Destination Port

This may be set using the General packet and if zero defaults to 1026.

Sequence Number

A 4-byte integer set to 0x00000000.

Byte 4

Indicates the number of DACs the hardware supports. Presently unused.

Byte 5

If no bits are set then CW is not selected, otherwise indicates the selection of CW options as follows:

Bits - Mode, CW, Reverse, Key Mode. 0 = off, 1 = on.	
[0]	EER
[1]	CW
[2]	Reverse CW Keys
[3]	Iambic
[4]	Sidetone
[5]	Mode B (Mode A if not set)
[6]	Strict Character Spacing
[7]	Break_in

NOTE: Setting Reverse CW Keys does not alter the actual key closures reported.

Byte 6

Sets the CW sidetone level, 0 = off, 127 = max

Bytes 7 & 8

Sets the CW sidetone frequency in Hz

Byte 9

Sets the CW keyer speed, 0 to 60 WPM

Byte 10

Sets the CW weight, 33 to 66, nominal is 50

Bytes 11 & 12

Sets the CW hang delay in mS

Byte 13

Sets the RF delay in mS

Bytes 14 & 15

Sets DUC0 sampling rate. For current hardware fixed at 192ksps.

Byte 16

Sets number of bits in the DUC I&Q data. For current hardware fixed at 24 bits per sample.

Bytes 17 to 49.

Reserved for future use.

Byte 50

Allows the selection of Line in or Microphone and Microphone selection for an Orion board (ANAN-200D) as follows:

Bits - line in, mic boost, Orion mic. 0 = off, 1 = on
[0] = Line in
[1] = Mic Boost
[2] = 0 = Orion mic PTT enabled, 1 = Orion mic PTT disabled
[3] = 0 = Orion mic PTT to ring and mic/mic bias to tip, 1 = Orion mic PTT to tip and mic/mic bias to ring
[4] = 0 = disables Orion mic bias, 1 = enables Orion microphone bias

Byte 51

Selects the Line in gain, 0 = +12dB, 31 = -34.5dB in 1.5dB steps.

DUC SYNCHRONISATION PACKET

The DUC Synchronisation packet is used to configure synchronous DUCs.

The data is sent prior to a Run command, whenever a value changes and, optionally, periodically.

For future use.

HIGH PRIORITY DATA PACKET

A High Priority Packet is sent to the associated SDR hardware whenever data changes and may also be sent periodically. It should be sent at a higher priority than any other packet. It should be sent after a successful Discovery process after configuration is complete. The format is as follows:

Control Elements - PC to Hardware Port (Default 1027)		
Byte	High Priority	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Bits - run, PTT(n)	[0] = run, [1] = PTT0...[4] = PTT3
5	CWX0	[0] = CWX, [1] = Dot, [2] = Dash
6	CWX1	Reserved for future use
7	CWX2	Reserved for future use
8	CWX3	Reserved for future use
9	Frequency/phase word DDC0	[31:24]
10		[23:16]
11		[15:8]
12		[7:0]
13	Frequency/phase word DDC1	[31:24]
14		[23:16]
15		[15:8]
16		[7:0]
17	Frequency/phase word DDC2	[31:24]
18		[23:16]
19		[15:8]
20		[7:0]
...		
...		
325	Frequency/phase word DDC79	[31:24]
326		[23:16]
327		[15:8]
328		[7:0]
329	Frequency/phase word DUC0	[31:24]
330	DUC0	[23:16]
331	DUC0	[15:8]
332	DUC0	[7:0]
333	Frequency/phase word DUC1	Reserved for future use
334	DUC1	Reserved for future use
335	DUC1	Reserved for future use
336	DUC1	Reserved for future use

337	Frequency/phase word DUC2	Reserved for future use
338	DUC2	Reserved for future use
339	DUC2	Reserved for future use
340	DUC2	Reserved for future use
341	Frequency/phase word DUC3	Reserved for future use
342	DUC3	Reserved for future use
343	DUC3	Reserved for future use
344	DUC3	Reserved for future use
345	DUC0 Drive Level	0-255
346	DUC1 Drive Level	Reserved for future use
347	DUC2 Drive Level	Reserved for future use
348	DUC3 Drive Level	Reserved for future use
...		
1400	Transverter and Audio enable	[7:0]
1401	Open Collector Outputs	[1] = Open Collector 1.....[7] = Open Collector 7
1402	User Outputs DB9 pins 1-4	[0] = pin1....[3] = pin4
1403	Mercury Attenuator (20dB)	[0] = Mercury1....[3] = Mercury4
1404	Alex 7	Reserved for future use
1405	Alex 7	Reserved for future use
1406	Alex 7	Reserved for future use
1407	Alex 7	Reserved for future use
1408	Alex 6	Reserved for future use
1409	Alex6	Reserved for future use
1410	Alex6	Reserved for future use
1411	Alex 6	Reserved for future use
1412	Alex5	Reserved for future use
1413	Alex5	Reserved for future use
1414	Alex5	Reserved for future use
1415	Alex 5	Reserved for future use
1416	Alex 4	Reserved for future use
1417	Alex 4	Reserved for future use
1418	Alex 4	Reserved for future use
1419	Alex 4	Reserved for future use
1420	Alex 3	Reserved for future use
1421	Alex 3	Reserved for future use
1422	Alex 3	Reserved for future use
1423	Alex 3	Reserved for future use
1424	Alex 2	Reserved for future use
1425	Alex 2	Reserved for future use
1426	Alex 2	Reserved for future use
1427	Alex 2	Reserved for future use
1428	Alex 1	Reserved for future use
1429	Alex 1	Reserved for future use

1430	Alex 1	[15:8] Orion Mk 11 (ANAN-8000DLE)
1431	Alex 1	[7:0] Orion Mk 11 (ANAN-8000DLE)
1432	Alex 0	[31:24]
1433	Alex 0	[23:16]
1434	Alex 0	[15:8]
1435	Alex 0	[7:0]
1436	Step Attenuator 7 (0 - 31dB)	Reserved for future use
1437	Step Attenuator 6 (0 - 31dB)	Reserved for future use
1438	Step Attenuator 5 (0 - 31dB)	Reserved for future use
1439	Step Attenuator 4 (0 - 31dB)	Reserved for future use
1440	Step Attenuator 3 (0 - 31dB)	Reserved for future use
1441	Step Attenuator 2 (0 - 31dB)	Reserved for future use
1442	Step Attenuator 1 (0 - 31dB)	
1443	Step Attenuator 0 (0 - 31dB)	

Destination Address

This will be the Ethernet address assigned to the hardware.

Destination Port

This may be set using the General packet and if zero defaults to 1027.

Sequence Number

A 4-byte integer set to 0x00000000.

Byte 4

Bit [0] when set enables the associated SDR hardware and when clear disables. Bit [1] enables transmit of the associated SDR hardware. Bits [2] to [7] are reserved for future use.

Byte 5

Bit[0] when set selects CW mode from the Host (e.g. a CW keyboard) with bit[1] and[2] being dot and dash respectively. A set bit will send a dot or dash at the speed selected by the DUC Specific packet.

Bytes 9 to 12

These bytes represent a 32bit word that is used to set the frequency of DDC0 in Hz.

Bytes 13 to 16

These bytes represent a 32bit word that is used to set the frequency of DDC1 in Hz.

Bytes 17 to 328

These bytes represent a 32bit word that is used to set the frequency of DDC2 to DDC79.

Bytes 329 to 332

These bytes represent a 32bit word that is used to set the frequency of DUC0 in Hz.

Byte 345

This byte sets the power out from DUC0. 0 represents 0 power out and 255 maximum.

Byte 1400

This byte is used by the ANAN-8000DLE and decodes as follows:

- [0] = XVTR_enable (0 = disabled, 1 = enabled)
- [1] = IO1 output to enable/mute audio (0=audio enabled, 1= mute)
- [2] = not assigned
- [3] = not assigned
- [4] = not assigned
- [5] = not assigned
- [6] = not assigned
- [7] = not assigned

Byte 1401

A set bit enables the associated open collector output. [1] = Open Collector 1,[7] = Open Collector 7.

Byte 1402

A set bit enables the associated Atlas Metis board User Outputs DB9 connector pins 1-4. [0] = pin1....[3] = pin4

Byte 1403

A set bit enables the 20dB attenuate on the associated Atlas Mercury board. [0] = Mercury1....[3] = Mercury4.

Bytes 1430 to 1435

These bytes form a 32bit word that selects the various functions on the (Alex) High and Low pass filters, preamplifier and antenna switching. See Appendix D for the mapping of bits to functions.

Byte 1442

Selects the attenuation applied to the 0-31dB attenuator before ADC1 (Angelia, Orion, ANAN-100D, ANAN-200D only).

Byte 1443

Selects the attenuation applied to the 0-31dB attenuator before ADC0 (not Mercury boards).

DDC AUDIO PACKET

The DDC Audio packet contains left and right audio to be presented to the hardware audio DAC.

It is sent whenever 64 Left and Right audio samples are available. Data defaults to 16 bits per sample at 48ksps.

	DDC Audio Data (default port 1028)	
Byte	Data	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Left Audio Sample 0	[15:8]
5	Left Audio Sample 0	[7:0]
6	Right Audio Sample 0	[15:8]
7	Right Audio Sample 0	[7:0]
8	Left Audio Sample 1	[15:8]
9	Left Audio Sample 1	[7:0]
10	Right Audio Sample 1	[15:8]
11	Right Audio Sample 1	[7:0]
....		
....		
256	Left Audio Sample 63	[15:8]
257	Left Audio Sample 63	[7:0]
258	Right Audio Sample 63	[15:8]
259	Right Audio Sample 63	[7:0]

Destination Port

This may be set using the General packet and if zero defaults to 1028.

Sequence Number

A 4-byte unsigned integer representing a sequence of packets from this port. The sequence starts at 0x00000000 and rolls over after exceeding 0xFFFFFFFF.

Each port decoder keeps a separate sequence count such that the hardware can determine if a decoder is missing samples in its stream. The sequence number is set to zero at program start or whenever a stop command is sent.

Bytes 4 to 259

A sequence of 64 2-byte signed integer 2's Complement values representing demodulated samples for the audio DAC on the hardware. These are sequential in time from the first to last sample.

DUC I&Q DATA PACKET

The I & Q data packet contains data to be presented to the hardware DUC(n). It is sent whenever 240 I&Q samples are available. Default samples are 24 bits at 192ksps.

	DUC I&Q Data (default port 1029)	
Byte	Data	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	I Sample 0	[23:16]
5	I Sample 0	[15:8]
6	I Sample 0	[7:0]
7	Q Sample 0	[23:16]
8	Q Sample 0	[15:8]
9	Q Sample 0	[7:0]
10	I Sample 1 (or Envelope data)	[23:16]
11	I Sample 1 (or Envelope data)	[15:8]
12	I Sample 1 (or Envelope data)	[7:0]
13	Q Sample 1 (or Envelope data)	[23:16]
14	Q Sample 1 (or Envelope data)	[15:8]
15	Q Sample 1 (or Envelope data)	[7:0]
...		
...		
1441	Q Sample 239	[23:16]
1442	Q Sample 239	[15:8]
1443	Q Sample 239	[7:0]

Destination Port

This may be set using the General packet and if zero defaults to 1029 for DAC0. It is automatically incremented by one for each subsequent DAC.

Sequence Number

A 4-byte unsigned integer representing a sequence of packets from this port. The sequence starts at 0x00000000 and rolls over after exceeding 0xFFFFFFFF.

Each port decoder keeps a separate sequence count such that the hardware can determine if a decoder is missing samples in its stream. The sequence number is set to zero at program start or whenever a stop command is sent.

I/Q Sample

A sequence of 240 3-byte signed integer 2's Complement I & Q values representing samples for the DUC on the SDR hardware. These are sequential in time from the first to last sample.

NOTE: When Envelope Tracking (ET) or Envelope Elimination & Restoration (EER) mode is selected then alternative I&Q pairs are for DUC and Envelope use respectively.

MEMORY MAPPED REGISTERS FROM PC

The memory mapped registers from PC packet contains address and data to be sent to the hardware. The format is as follows:

Memory Mapped - PC to hardware (default port xxxx)		
Byte	Memory Mapped	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Address0	[15:8]
5	Address0	[7:0]
6	Data0	[31:24]
7	Data0	[23:16]
8	Data0	[15:8]
9	Data0	[7:0]
10	Address1	[15:8]
11	Address1	[7:0]
12	Data1	[31:24]
13	Data1	[23:16]
14	Data1	[15:8]
15	Data1	[7:0]
16	Address2	[15:8]
17	Address2	[7:0]
18	Data2	[31:24]
19	Data2	[23:16]
20	Data2	[15:8]
21	Data2	[7:0]
22	Address3	[15:8]
23	Address3	[7:0]
24	Data3	[31:24]
25	Data3	[23:16]
26	Data3	[15:8]
27	Data3	[7:0]
...		
1438	Address239	[15:8]
1439	Address239	[7:0]
1440	Data239	[31:24]
1441	Data239	[23:16]
1442	Data239	[15:8]
1443	Data239	[7:0]

Destination Port

This may be set using the General packet and if zero defaults to xxxx.

Sequence Number

A 4-byte unsigned integer representing a sequence of packets from this port. The sequence starts at 0x00000000 and rolls over after exceeding 0xFFFFFFFF.

Each port decoder keeps a separate sequence count such that the hardware can determine if a decoder is missing samples in its stream. The sequence number is set to zero at program start or whenever a stop command is sent.

Bytes 4 & 5 (en sequence)

These form the 16 bit address the 32 bit data in the next 4 bytes will be sent to.

Bytes 6 to 9 (en sequence)

This form a 32 bit data word that will be sent to the address specified by the address bytes.

openHPSDR Hardware to Host Protocol

The hardware will communicate with the Host using standard UDP protocol. Byte order shall be MSB first (little Endian) and all values are interpreted as unsigned integers unless otherwise noted. For DFC based software systems Big-Endian or Little-Endian Byte order may be supported in addition to float or double data formats. The Discovery response packet indicates the options available.

IP and UDP headers are as per UDP/IP standards.

Key:

IP Header (24 bytes)
UDP Header (8 bytes)
UDP Data (variable bytes)

Bits Bytes	0-7	8-15	16-23	24-31	32- 39	40-47	48-55	56-63
0	Version/IHL	Type of Service	Total Length		Identification		Flags/Fragment Offset	
8	TTL	Protocol	Header Checksum		Source IP Address			
16	Destination IP Address				IP Options			Pad
24	Source Port		Destination Port		UDP Length		UDP Checksum	
32... 1443	UDP Data							

Future diagrams will only show the UDP Data with a starting byte reference of zero.

DISCOVERY REPLY PACKET

A Discovery Reply Packet is sent in response to a Host broadcasting a Discovery packet. The Host sends a discovery packet in order to determine what hardware is present on the network and how it is configured.

In order to allow for SDR hardware to provide complete details of all features available two reply formats are provided.

1. Where prior knowledge of the hardware is known by the Host software, and
2. Where the full description of the configuration of the hardware and its capabilities are provided in the response to the Discovery packet.

The data format for option 1 is shown below.

Response to Discovery - Hardware to Host (from port 1024)		
Byte	To IP address and Port of Host PC	Notes
0	Seq # = 0	[31:24]
1	Seq # = 0	[23:16]
2	Seq # = 0	[15:8]
3	Seq # = 0	[7:0]
4	0x02 (or 0x03)	Response to Discovery
5	Board MAC	MSB
6	Board MAC	
7	Board MAC	
8	Board MAC	
9	Board MAC	
10	Board MAC	LSB
11	Board Type	See Below
12	openHPSDR Protocol version supported	
13	Firmware Code Version	
14	Mercury 0 Code Version	
15	Mercury 1 Code Version	
16	Mercury 2 Code Version	
17	Mercury 3 Code Version	
18	Penny Code Version	
19	Metis Code Version	
20	Number of DDCs implemented	
21	Frequency or phase word	0 = frequency 1 = phase
22	Available Endian modes	See Below
23	Beta version	0 = false
24	Reserved for future use (AD0ES)	
25		
....		
59		

Source Port

This will be set to 1024.

Destination Port

This will be set to the Source Port of the Host that initiated the Command.

Sequence Number

A 4-byte integer set to 0x00000000.

Byte 4

Normally 0x02 but if the hardware is running and already connected to a different Host it will be 0x03.

If byte 4 is 0xFE (0xFF if running) then subsequent bytes contain the hardware configuration of the SDR.

Appendix A describes the format of the hardware configuration.

NOTE: If the reply indicates that the hardware is already connected to a different host then it is recommended that the PC code advise the user that hardware is available but in use. If the user chooses to ignore this message, and proceeds to send appropriate C&C commands, then the hardware will disconnect from the existing connection and connect to the PC sending the C&C commands.

MAC

This is 6 bytes and holds the MAC address of the hardware that is responding to the Command request

Board Type

A byte interpreted as follows:

0: board = "ATLAS"
1: board = "HERMES" (ANAN-10,100)
2: board = "HERMES" (ANAN-10E, 100B)
3: board = "ANGELA" (ANAN-100D)
4: board = "ORION" (ANAN-200D)
5: board = "ORION Mk II" (ANAN-7/8000DLE)
6: board = "Hermes Lite"
7: Reserved
8: Reserved
9: Reserved
254: XML hardware description follows
255: Full hardware description follows

Hardware descriptions for Board types less than 254 are documented in Appendix A. For a Board type of 254 a full hardware description is returned in XML format, see Appendix B. For a Board type of 255 a full hardware description is returned, see Appendix C.

Byte 12 - Code Version

A byte that indicates the version of this protocol that the board(s) implement. The Host interprets this as a decimal number e.g. 104 would be interpreted as version 10.4

Byte 13 - Code Version

For non-Atlas based systems, a byte that indicates the version of code loaded into the associated board. The Host interprets this as a decimal number e.g. 104 would be interpreted as version 10.4.

Bytes 14 to 19

Where an Atlas based system is identified, bytes 13 to 18 contain the code versions loaded into the respective boards. The Host interprets this as a decimal number e.g. 104 would be interpreted as version 10.4. A version number of zero indicates a board is not present.

Byte 20

This holds the number of independent DDCs that are implemented in the hardware.

Byte 21

This indicates if the hardware requires frequencies to be send as a frequency (Hz) or a phase word. A phase word is calculated as follows:

$$\text{phase_word}[31:0] = 2^{32} * \text{frequency(Hz)} / \text{DSP clock frequency (Hz)}$$

Byte 22

This Byte indicates the Endian modes and DDC IQ data formats available as follows:

If Byte 22 is zero then the data format is Big-Endian and I&Q data is in 3 Byte format. If the Byte is not zero then the following options are supported.

Bit 0 = 1 Big-Endian supported

Bit 1 = 1 Little-Endian supported

Bit 2 = 1 3 Byte data format supported

Bit 3 = 1 Float data format supported

Bit 4 = 1 Double data format supported

Bits 5, 6 & 7 Reserved for future use.

NOTE: The Discovery packet will always use this format irrespective of what Endian mode is selected. The radio can choose from any of these options via the first General packet Byte 39.

Byte 23 – If not zero then beta version of code installed.

Byte 24 – Reserved

COMMAND REPLY PACKET

A Command reply packet is returned to the Host making the Command request. The format of the reply is similar to a Discovery reply except that byte 4 (and for Program the sequence number) is different. The reply is returned in response to the following:

Erase. Following an EEPROM erase command the hardware will respond with a reply packet that indicates the command has been received and, after the erase is complete – which may take 10's of seconds, that the erase has been successful. Byte 4 will be set to 0x03.

Program. Following a Program command the hardware will respond with a reply packet that indicates that the next 256 bytes of data should be sent by the Host. Byte 4 will be set to 0x04 and the sequence number will be set to the last sequence number received from the Host.

During programming the Host should check the received sequence number in order to verify that a programming packet has been received and in the correct sequence. An incorrect sequence number should be used by the Host to initiate a new Erase and Program cycle. The host should also verify the final checksum matches the checksum of the firmware update file. This will include any filler 0xFF bytes needed to complete the final 256-byte packet. The checksum is the sum of all bytes received and is sent on each program packet reply. The response to a Program command is as follows:

Response to Program - Hardware to Host (from port 1024)		
Byte	To IP address and Port of Host PC	Notes
0	Seq # = 0	[31:24]
1	Seq # = 0	[23:16]
2	Seq # = 0	[15:8]
3	Seq # = 0	[7:0]
4	0x04	Response to Command
5	Board MAC	MSB
6	Board MAC	
7	Board MAC	
8	Board MAC	
9	Board MAC	
10	Board MAC	LSB
11	Firmware Code Version	
12	Board Type	
13	Firmware Checksum	MSB
14	Firmware Checksum	LSB
15		
...		
59		

Set IP. Following a successful Set IP command, the hardware will respond with a Discovery reply packet.

HIGH PRIORITY STATUS PACKET

The High Priority Status packet contains data that indicates the status of the transceiver subsystems. Data representing inputs is sent immediately the data changes, other data is sent periodically. The normal periodic update rate is every 50mS. This is increased to every mS when transmitting in order that the host receives Forward and Reflected Power levels fast enough to display SWR with low latency.

Any change of Status data will be sent as a priority and has precedence over any other packet.

Since actual status changes will be hardware specific the format will vary between different SDR hardware.

The packet format is as follows:

Control Elements - Hardware to PC (default port 1025)		
Byte	High Priority	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Bits - PTT, Dot, Dash	[0] = PTT, [1] = Dot, [2] = Dash, [4] PLL locked, [5] FIFO almost empty, [6] FIFO almost full
5	Bits - ADC Overload	[0] = ADC0...[7] = ADC7
6	Exciter Power 0	[15:8]
7	Exciter Power 0	[7:0]
8	Exciter Power 1	[15:8] Reserved for future use
9	Exciter Power 1	[7:0] Reserved for future use
10	Exciter Power 2	[15:8] Reserved for future use
11	Exciter Power 2	[7:0] Reserved for future use
12	Exciter Power 3	[15:8] Reserved for future use
13	Exciter Power 3	[7:0] Reserved for future use
14	Forward Power - Alex 0	[15:8] (Set to zero if Alex not selected)
15	Forward Power - Alex 0	[7:0] (Set to zero if Alex not selected)
16	Forward Power - Alex 1	[15:8] Reserved for future use
17	Forward Power - Alex 1	[7:0] Reserved for future use
18	Forward Power - Alex 2	[15:8] Reserved for future use
19	Forward Power - Alex 2	[7:0] Reserved for future use
20	Forward Power - Alex 3	[15:8] Reserved for future use
21	Forward Power - Alex 3	[7:0] Reserved for future use
22	Reverse Power - Alex 0	[15:8] (Set to zero if Alex not selected)
23	Reverse Power - Alex 0	[7:0] (Set to zero if Alex not selected)
24	Reverse Power - Alex 1	[15:8] Reserved for future use
25	Reverse Power - Alex 1	[7:0] Reserved for future use
26	Reverse Power - Alex 2	[15:8] Reserved for future use
27	Reverse Power - Alex 2	[7:0] Reserved for future use

28	Reverse Power - Alex 3	[15:8] Reserved for future use
29	Reverse Power - Alex 3	[7:0] Reserved for future use
30	0	Presently unused
...		
48	0	Presently unused
49	Supply Volts	[15:8]
50	Supply Volts	[7:0]
51	User ADC3	[15:8]
52	User ADC3	[7:0]
53	User ADC2	[15:8]
54	User ADC2	[7:0]
55	User ADC1	[15:8]
56	User ADC1	[7:0]
57	User ADC0	[15:8]
58	User ADC0	[7:0]
59	Bits - User logic inputs	[7:0]

Source Port

This may be set using the General packet and if zero defaults to 1025.

Destination Port

This will be set to the Source Port of the Host that initiated the Discovery Packet.

Sequence Number

A 4-byte integer set to 0x00000000. The sequence starts at 0x00000000 and rolls over after exceeding 0xFFFFFFFF. Each port decoder keeps a separate sequence count such that the Host can determine if a decoder is missing samples in its stream. The sequence number is set to zero at power on or whenever a stop command is received.

Byte 4

Bits [0] to [2] indicate the status of an attached PTT button or CW key. A bit is set when the input is active. Bit [4] set indicates that the PLL that locks the master VCXO to the 10MHz internal or external reference is locked. Bit [5] set indicates that the DUC I&Q FIFO is almost empty (≤ 511 samples), bit [6] set indicates that the FIFO is almost full ($\geq 3,840$ samples). **NOTE:** DUC I&Q FIFO almost full and almost empty no longer supported.

Byte 5

Bits [0] to [7] are set if the associated ADC[n] overload bit is set.

Bytes 6 & 7

These form a 16 bit word that represents the forward power from the exciter (or Penelope or Penny Lane boards). The conversion to power is described in Appendix A.

Bytes 14 & 15

These form a 16 bit word that represents the forward power from the exciter Power Amplifier. The conversion to power is described in Appendix A.

Bytes 22 & 23

These form a 16 bit word that represents the reverse power from the exciter Power Amplifier. The conversion to power is described in Appendix A.

Bytes 49 & 50

These form a 16 bit word that represents the supply voltage applied to the hardware (not Atlas bus systems). The conversion to Volts is described in Appendix A.

Bytes 51 to 58

These form 16 bit words that represent the general purpose analogue voltage inputs to the hardware. These are presently undefined since they are user specific.

Byte 59

Bits [0] to [7] are set if the associated general purpose digital input is set. These are mapped as follows:

- [0] = IO4 input
- [1] = IO5 input
- [2] = IO6 input
- [3] = IO8 input
- [4] = IO2 input
- [5] = not assigned
- [6] = not assigned
- [7] = not assigned

MICROPHONE DATA PACKET

The microphone data packet contains 64 samples from the microphone or line-in inputs on the hardware.

The sample rate is 48ksps and packet format is as follows:

Microphone Data (default port 1026)		
Byte	Data	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Mic Sample 0	[15:8]
5	Mic Sample 0	[7:0]
6	Mic Sample 1	[15:8]
7	Mic Sample 1	[7:0]
8	Mic Sample 2	[15:8]
9	Mic Sample 2	[7:0]
10	Mic Sample 3	[15:8]
11	Mic Sample 3	[7:0]
....		
....		
128	Mic Sample 62	[15:8]
129	Mic Sample 62	[7:0]
130	Mic Sample 63	[15:8]
131	Mic Sample 63	[7:0]

Source Port

This may be set using the General packet and if zero defaults to 1026.

Destination Port

This will be set to the Source Port of the Host that initiated the Discovery Packet.

Sequence Number

A 4-byte unsigned integer representing a sequence of packets from this port. The sequence starts at 0x00000000 and rolls over after exceeding 0xFFFFFFFF.

Each port decoder keeps a separate sequence count such that the Host can determine if a decoder is missing samples in its stream. The sequence number is set to zero at power on or whenever a stop command is received.

Mic Sample

A sequence of 64 2-byte signed integer 2's Complement values representing samples from the microphone or line-in on the hardware. These are sequential in time from the first to last sample.

WIDEBAND DATA PACKET

The Wideband data packet contains raw samples from the ADCs selected by the user. The number of bits per sample, number of samples per packet and update rate specified in the General to Hardware settings will be sent when the Wideband enable bit for the associated ADC is set. The Wideband data is intended to be used to display very wide spectral and waterfall displays. Whilst data within a packet, and number of packets set in the General Packet, is time sequential otherwise the data is presented on a block basis so may not be used for real-time demodulation purposes.

The following assumes 512 by 16 bit samples per packet.

Wideband Data (default port 1027)		
Byte	Data	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Wideband Sample 0	[15:8]
5	Wideband Sample 0	[7:0]
6	Wideband Sample 1	[15:8]
7	Wideband Sample 1	[7:0]
8	Wideband Sample 2	[15:8]
9	Wideband Sample 2	[7:0]
10	Wideband Sample 3	[15:8]
11	Wideband Sample 3	[7:0]
....		
....		
1024	Wideband Sample 510	[15:8]
1025	Wideband Sample 510	[7:0]
1026	Wideband Sample 511	[15:8]
1027	Wideband Sample 511	[7:0]

Source Port

This may be set using the General packet and if zero defaults to 1027 for ADC0. The source port is automatically incremented by one for each subsequent Wideband data source.

Destination Port

This will be set to the Source Port of the Host that initiated the Discovery Packet.

Sequence Number

A 4-byte unsigned integer representing a sequence of packets from this port. The sequence starts at 0x00000000 and rolls over after exceeding 0xFFFFFFFF.

Each port decoder keeps a separate sequence count such that the Host can determine if a decoder is missing samples in its stream. The sequence number is set to zero at power on or whenever a block of raw samples has been sent or whenever a stop command is received.

ADC Sample

A sequence of 2-byte signed integer values (default is 512) representing raw samples from the selected ADC on the hardware. These are sequential in time from the first to last sample. Following a request to send wideband data, the sequence number will be set to zero and incremented in each sequential packet until the number of samples set in the General packet has been sent. The sequence number is reset to zero for the next packet or when a stop command is received.

DDC PACKET

I & Q data from a DDC connected to an ADC will be sent from a UDP port with bits per sample specified by the General settings. I & Q data from either a single DDC or multiple synchronous DDCs can be presented.

The following assumes one DDC using 24 bits per sample.

	DDC I&Q Data (DDC0 default port 1035)	
Byte	Data	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Time Stamp	[63:56]
5	Time Stamp	[55:48]
6	Time Stamp	[47:40]
7	Time Stamp	[39:32]
8	Time Stamp	[31:24]
9	Time Stamp	[23:16]
10	Time Stamp	[15:8]
11	Time Stamp	[7:0]
12	Bits per sample	[15:8]
13	Bits per sample	[7:0]
14	I&Q Samples per frame	[15:8]
15	I&Q Samples per frame	[7:0]
16	I Sample 0	[23:16]
17	I Sample 0	[15:8]
18	I Sample 0	[7:0]
19	Q Sample 0	[23:16]
20	Q Sample 0	[15:8]
21	Q Sample 0	[7:0]
22	I Sample 1	[23:16]
23	I Sample 1	[15:8]
24	I Sample 1	[7:0]
25	Q Sample 1	[23:16]
26	Q Sample 1	[15:8]
27	Q Sample 1	[7:0]
...		
...		
1441	Q Sample 237	[23:16]
1442	Q Sample 237	[15:8]
1443	Q Sample 237	[7:0]

Source Port

The DDC port will be as allocated by the General Packet and if zero defaults to 1035 for DDC 0.

Each additional DDC will be allocated the next sequential port number e.g. DDC 1 will originate from port 1036.

Destination Port

This will be set to the Source Port of the Host that initiated the Discovery Command

Sequence Number

A 4-byte unsigned integer representing a sequence of packets from this port. The sequence starts at 0x00000000 and rolls over after exceeding 0xFFFFFFFF.

Each port decoder keeps a separate sequence count such that the Host can determine if a decoder is missing samples in its stream. The sequence number is set to zero at power on or whenever a stop command is received.

Time stamp

This is a 64 bit unsigned integer that is incremented at the sample rate of the ADC from which the data is being generated and is set to zero at the 0 to 1 transition of the 1 PPS from a GPS DDC. This complies with the 'Fractional -Seconds Timestamp - The Sample Count Timestamp' of the VITA-49 specification section 6.1.5.1.

Bits per sample

A two byte unsigned integer that indicates the number of bits per sample. Current hardware FPGA code supports 24 bits per sample.

I&Q Samples per frame

A two byte unsigned integer that indicates the number of samples that follow. The number of samples will not exceed the maximum length of the data payload for a UDP packet and will contain an integer number of I&Q samples. Where synchronous DDC data is presented then the UDP packet will contain an integer number of samples e.g. for two synchronous DDCs [(I0, Q0), (I1, Q1)] x 164.

The data diagram above illustrates the case for one DDC. Should a greater number of synchronous DDCs be used the above data format will be modified accordingly. The number of samples per UDP frame will depend on the width of each I & Q sample i.e. 8, 16, 24, or 32 bits.

DDC I/Q Samples

This is a sequence of signed integer 2's Complement values representing one I or one Q sample from the DDC hardware. These are sequential in time from the first to last sample.

For synchronous DDCs the sample rate of each DDC will be the same and specified by the register settings set using the DDC Specific packet.

NOTE: The sequence of the DDC I&Q samples is represented as 'I' samples followed by 'Q' samples. There does not appear to be an exact definition as to what constitutes an I or Q sample. In which case when processed by an FFT to resulting spectrum may appear reversed. In which case the I&Q samples should be reversed. However, if samples are considered to be reversed the sequence in which the samples are received will be invariant.

MEMORY MAPPED REGISTERS FROM HARDWARE

The memory mapped registers from PC packet contains address and data to be sent to the PC. The data should be sent whenever data changes and optionally periodically. The format is as follows:

Memory Mapped - Hardware to PC (default port xxxx)		
Byte	Memory Mapped	Notes
0	Seq #	[31:24]
1	Seq #	[23:16]
2	Seq #	[15:8]
3	Seq #	[7:0]
4	Address0	[15:8]
5	Address0	[7:0]
6	Data0	[31:24]
7	Data0	[23:16]
8	Data0	[15:8]
9	Data0	[7:0]
10	Address1	[15:8]
11	Address1	[7:0]
12	Data1	[31:24]
13	Data1	[23:16]
14	Data1	[15:8]
15	Data1	[7:0]
16	Address2	[15:8]
17	Address2	[7:0]
18	Data2	[31:24]
19	Data2	[23:16]
20	Data2	[15:8]
21	Data2	[7:0]
22	Address3	[15:8]
23	Address3	[7:0]
24	Data3	[31:24]
25	Data3	[23:16]
26	Data3	[15:8]
27	Data3	[7:0]
...		
1438	Address239	[15:8]
1439	Address239	[7:0]
1440	Data239	[31:24]
1441	Data239	[23:16]
1442	Data239	[15:8]
1443	Data239	[7:0]

Destination Port

This may be set using the General packet and if zero defaults to xxxx.

Sequence Number

A 4-byte unsigned integer representing a sequence of packets from this port. The sequence starts at 0x00000000 and rolls over after exceeding 0xFFFFFFFF.

Each port decoder keeps a separate sequence count such that the hardware can determine if a decoder is missing samples in its stream. The sequence number is set to zero at program start or whenever a stop command is sent.

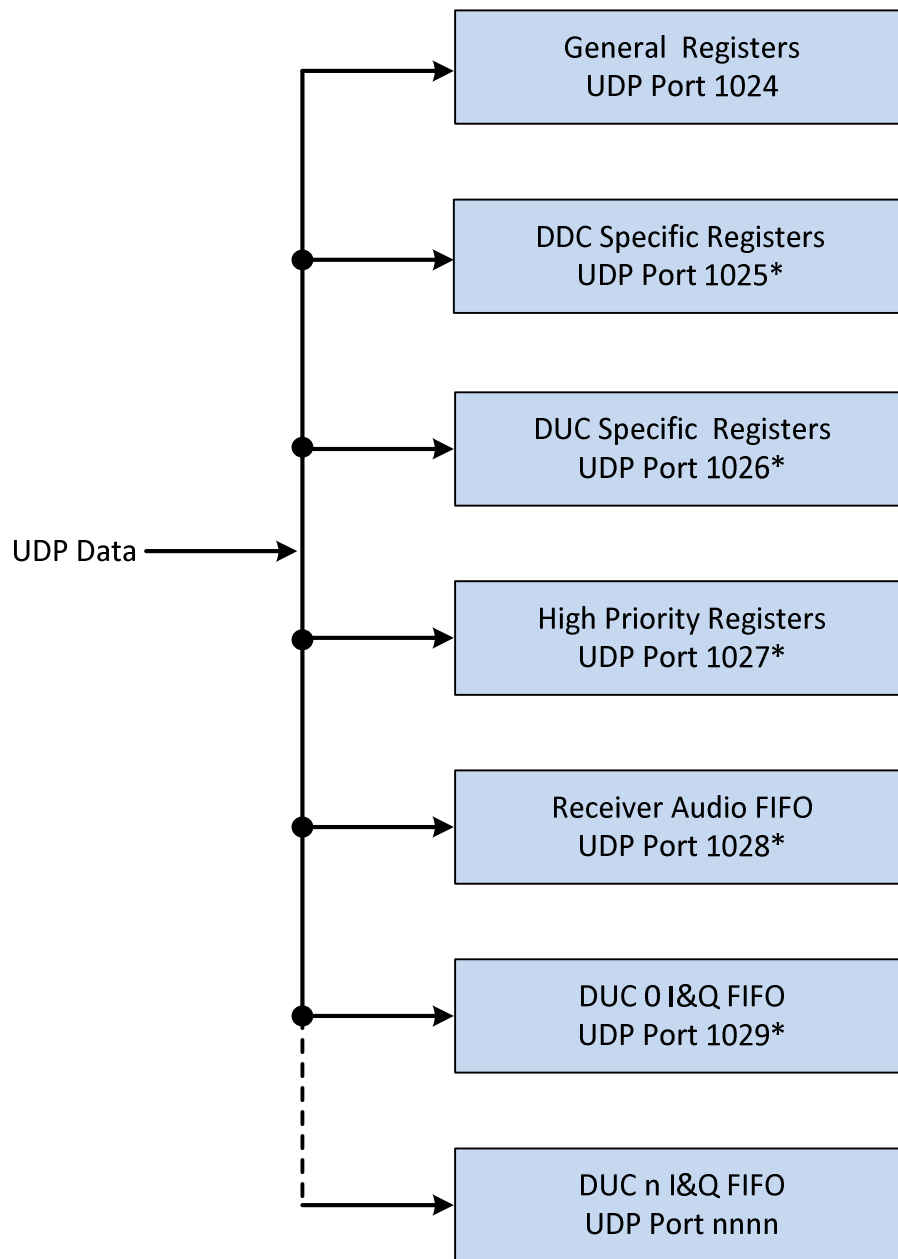
Bytes 4 & 5 (en sequence)

These form the 16 bit address the 32 bit data in the next 4 bytes will be sent from.

Bytes 6 to 9 (en sequence)

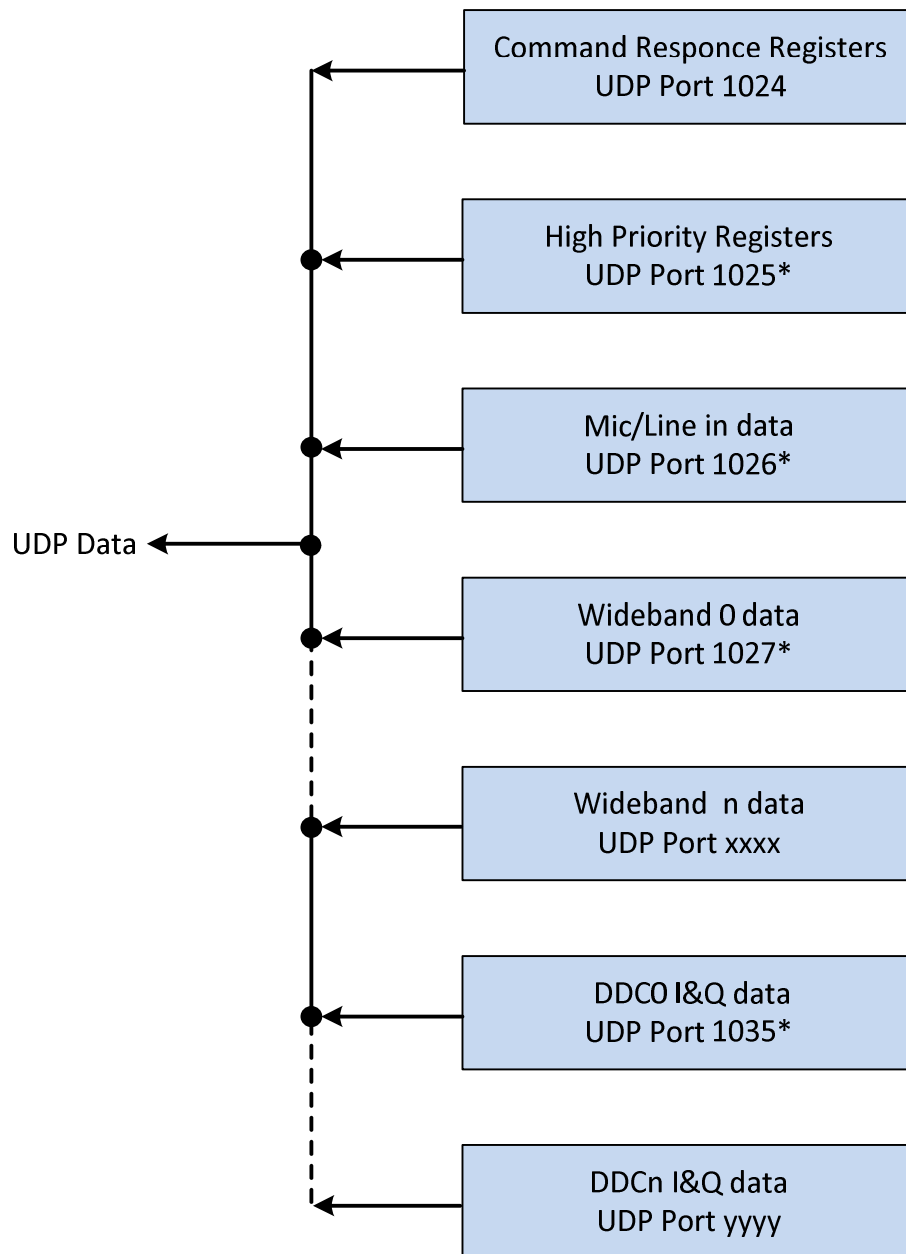
This form a 32 bit data word that is the data contained at the address specified by the address bytes.

Figure 1 UDP Data from Host



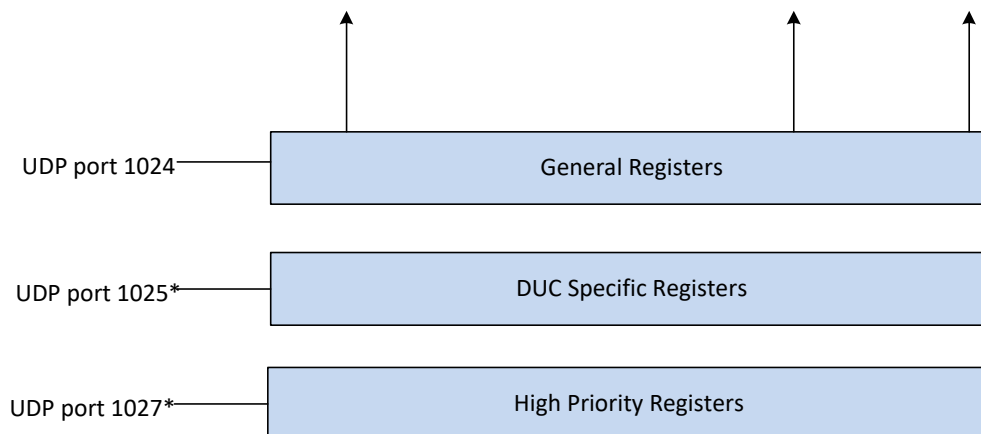
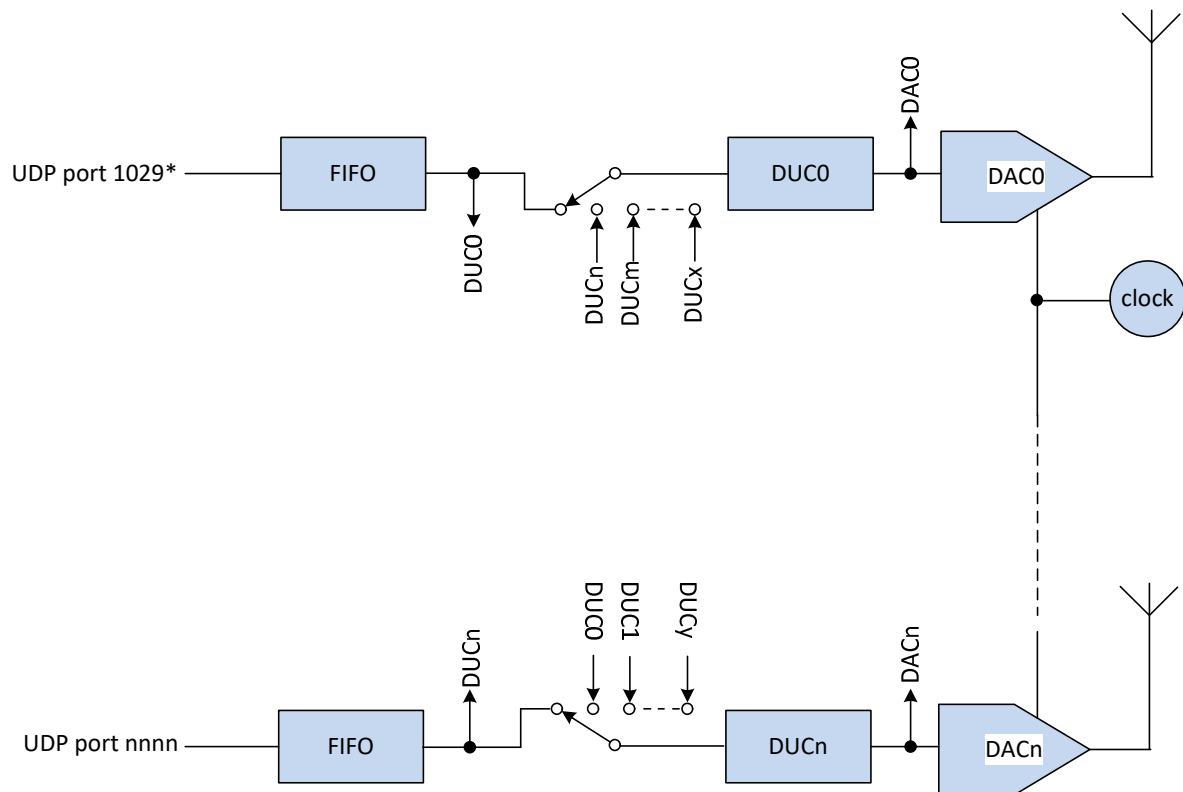
* Default Port

Figure 2 UDP Data to Host



* Default Port

Figure 4 DUC Architecture



* Default Port

Appendix A – Hardware capabilities – openHPSDR boards

Board 0 = Atlas Based Systems

To be written

Board 1 = Hermes (ANAN-10, 100)

Hardware Capabilities	
Host update of firmware supported	Yes
Setting of UDP/IP ports supported	Yes
Setting IP address supported	Yes
Memory mapped registers supported	No
Alex protocol receive filters supported	Yes
Alex protocol transmit filters supported	Yes
VITA-49 protocol supported	No
DSP clock frequency (Hz)	122.88MHz
Number of RF ADCs	1
Dither supported	Yes
Random supported	Yes
Number of DDCs supported	TBA
DDC Frequency or Phase Word	Phase
Receive attenuator supported	Yes
Wideband data supported	Yes
Wideband samples per Ethernet packet	512
Wideband bits per sample fixed or variable	Fixed
Wideband bits per sample fixed value	16
Wideband update rate fixed or variable	Variable
Wideband update rate fixed (mS)	
Wideband packets per frame fixed or variable	Variable
Wideband packets per frame fixed	
Individual DDC sample rates supported	Yes
Minimum DDC sampling rate (ksps)	48
Maximum DDC sampling rate (ksps)	1,536
CIC decimation values settable	No
Synchronous DDCs supported	Yes (for PureSignal only)
DDC Audio CODEC supported	Yes, stereo
Audio CODEC sample rate (ksps)	48
Audio CODEC bits per sample	16
Audio samples per Ethernet packet	64 Left, 64 Right
Time stamping of I&Q data supported	No
Number of DUCs supported	1
DUC Audio CODEC supported	Yes
Microphone supported	Yes
Line in supported	Yes
Audio CODEC sample rate (ksps)	48
Audio CODEC bits per sample	16
Audio samples per Ethernet packet	64
DUC Frequency or phase word required	Phase
DUC I&Q sample rate (ksps)	192

Bits per I/Q sample	24
I&Q samples per Ethernet packet (24bits per sample)	238 I samples, 238 Q samples
Envelope Tracking supported	No
CW Sidetone supported	Yes
CW from the Host supported	Yes
CW Iambic Keyer supported	Yes
CW break-in supported	Yes
Hang supported (mS)	Yes, 1 to 1000
RF Delay supported (mS)	Yes, 1 to 255
DUC Phase shift supported	No
Receive attenuator on DUC supported	Yes
Open collector outputs supported	7
DDC Calibration	-138dBm (see Note)
Number of General Purpose ADCs	6
Calibration constant for Supply Voltage. $V = \text{ADC value} / 4095 * \text{constant}$	constant = 3.3
Calibration constant for Exciter, FWD & REV power $W = (\text{ADC value} / 4095 * \text{constant1})^2 / \text{constant2}$ Sale Exciter to 0 to 1000mW Scale ANAN-10 FWD & REV 0 to 20W Scale ANAN-100 FWD & REV 0 – 150W	Constant1 = 3.3 Constant2 = 0.09 (ANAN-10) Constant2 = 0.095 (ANAN-100)

NOTE: DDC calibration. Calibration level is with a 50 ohm load connected to the antenna input, the DDC set to 20m, 500 Hz bandwidth and is the averaged value of the magnitude of the I&Q samples at the output of the filter i.e. DDC noise floor.

Board 2 = Hermes (ANAN-10E)

Hardware Capabilities	
Host update of firmware supported	No, use Bootloader mode
Setting of UDP/IP ports supported	No, use Bootloader mode
Setting IP address supported	No, use Bootloader mode
Memory mapped registers supported	No
Alex protocol receive filters supported	No
Alex protocol transmit filters supported	Yes (only used on DUC output)
VITA-49 protocol supported	No
DSP clock frequency (Hz)	122,880,000
Number of ADCs	1
Dither supported	Yes
Random supported	Yes
Number of DDCs supported	2
DDC Frequency or Phase Word	Phase
Receive attenuator supported	Yes, 0 to 31dB only, no Alex attenuators.
Wideband data supported	Yes
Wideband samples per Ethernet packet	512
Wideband bits per sample fixed or variable	Fixed
Wideband bits per sample fixed value	16
Wideband update rate fixed or variable	Fixed
Wideband update rate fixed (mS)	100
Wideband packets per frame fixed or variable	Fixed
Wideband packets per frame fixed	4
Individual DDC sample rates supported	Yes
Minimum DDC sampling rate (ksps)	48
Maximum V sampling rate (ksps)	1,536
CIC decimation values settable	No
Synchronous DDCs supported	Yes (for PureSignal only)
DDC Audio CODEC supported	Yes, stereo
Audio CODEC sample rate (ksps)	48
Audio CODEC bits per sample	16
Audio samples per Ethernet packet	64 left, 64 Right
Time stamping of I&Q data supported	No
Number of DUCs supported	1
DUC Audio CODEC supported	Yes
Microphone supported	Yes
Line in supported	Yes
Audio CODEC sample rate (ksps)	48
Audio CODEC bits per sample	16
Audio samples per Ethernet packet	64

DUC Frequency or phase word required	Phase
DUC I&Q sample rate (ksps)	192
Bits per I/Q sample	24
DUC I&Q samples per Ethernet packet	240 I, 240 Q
Envelope Tracking supported	No
CW Sidetone supported	Yes
CW from the Host supported	Yes
CW Iambic Keyer supported	Yes
CW break-in supported	Yes
Hang supported (mS)	Yes, 1 to 1000
RF Delay supported (mS)	Yes, 1 to 255
DUC Phase shift supported	No
Receive attenuator on DUC supported	Yes
Open collector outputs supported	7
DDC Calibration	-138dBm (see Note)
Number of General Purpose ADCs	6
Calibration constant for Supply Voltage. $V = \text{ADC value} / 4095 * \text{constant}$	constant = 3.3
Calibration constant for Exciter, FWD & REV power $W = (\text{ADC value} / 4095 * \text{constant1})^2 / \text{constant2}$ Sale Exciter to 0 to 1000mW Scale ANAN-10E FWD & REV 0 to 20W	Constant1 = 3.3 Constant2 = 0.09

NOTE: DDC calibration. Calibration level is with a 50 ohm load connected to the antenna input, the DDC set to 20m, 500 Hz bandwidth and is the averaged value of the magnitude of the I&Q samples at the output of the filter i.e. DDC noise floor.

Board 3 = Angelia (ANAN-100D)

Hardware Capabilities	
Host update of firmware supported	Yes
Setting of UDP/IP ports supported	Yes
Setting IP address supported	Yes
Memory mapped registers supported	No
Alex protocol receive filters supported	Yes
Alex protocol transmit filters supported	Yes
VITA-49 protocol supported	No
DSP clock frequency (Hz)	122,880,000
Number of ADCs	2
Dither supported	Yes
Random supported	Yes
Number of DDCs supported	7
DDC Frequency or Phase Word	Phase
Receive attenuator supported	Yes
Wideband data supported	Yes
Wideband samples per Ethernet packet	512
Wideband bits per sample fixed or variable	Fixed
Wideband bits per sample fixed value	16
Wideband update rate fixed or variable	Variable
Wideband update rate fixed (mS)	
Wideband packets per frame fixed or variable	Variable
Wideband packets per frame fixed	
Individual DDCs sample rates supported	Yes
Minimum DDC sampling rate (ksps)	48
Maximum DDC sampling rate (ksps)	1,536
DDC I & Q samples per Ethernet packet (24 bits)	328 I, 328 Q
CIC decimation values settable	No
Synchronous DDCs supported	Yes
DDC Audio CODEC supported	Yes, stereo
Audio CODEC sample rate (ksps)	48
Audio CODEC bits per sample	16
Audio samples per Ethernet packet	64 Left, 64 Right
Time stamping of I&Q data supported	No
Number of DUCs supported	1
DUC Audio CODEC supported	Yes
Microphone supported	Yes
Line in supported	Yes
Audio CODEC sample rate (ksps)	48
Audio CODEC bits per sample	16
Audio samples per Ethernet packet	64
DUC Frequency or phase word required	Phase

DUC I&Q sample rate (ksps)	192
Bits per I/Q sample	24
I&Q samples per Ethernet packet (24 bit samples)	238 I, 238 Q
Envelope Tracking supported	No
CW Sidetone supported	Yes
CW from the Host supported	Yes
CW Iambic Keyer supported	Yes
CW break-in supported	Yes
Hang supported (mS)	Yes, 1 - 1000
RF Delay supported (mS)	Yes, 1 - 255
DUC Phase shift supported	No
Receive attenuator on DUC supported	Yes
Open collector outputs supported	7
DDC Calibration	-138dBm (see Note)
Number of General Purpose ADCs	6
Calibration constant for Supply Voltage. $V = \text{ADC value} / 4095 * \text{constant}$	constant = 3.3
Calibration constant for Exciter, FWD & REV power $W = (\text{ADC value} / 4095 * \text{constant1})^2 / \text{constant2}$ Sale Exciter to 0 to 1000mW Scale ANAN-100D FWD & REV 0 – 150W	Constant1 = 3.3 Constant2 = 0.095

NOTE: DDC calibration. Calibration level is with a 50 ohm load connected to the antenna input, the DDC set to 20m, 500 Hz bandwidth and is the averaged value of the magnitude of the I&Q samples at the output of the filter i.e. DDC noise floor.

Board 4 = Orion (ANAN-200D)

Hardware Capabilities	
Host update of firmware supported	Yes
Setting of UDP/IP ports supported	Yes
Setting IP address supported	Yes
Memory mapped registers supported	No
Alex protocol receive filters supported	Yes
Alex protocol transmit filters supported	Yes
VITA-49 protocol supported	No
DSP clock frequency (Hz)	122,880,000
Number of ADCs	2
Dither supported	Yes
Random supported	Yes
Number of DDCs supported	TBA
DDC Frequency or Phase Word	Phase
DDC attenuator supported	Yes
Wideband data supported	Yes
Wideband samples per Ethernet packet	512
Wideband bits per sample fixed or variable	Fixed
Wideband bits per sample fixed value	16
Wideband update rate fixed or variable	Variable
Wideband update rate fixed (mS)	
Wideband packets per frame fixed or variable	Variable
Wideband packets per frame fixed	
Individual DDC sample rates supported	Yes
Minimum DDC sampling rate (ksps)	48
Maximum DDC sampling rate (ksps)	1,536
DDC I & Q samples per Ethernet packet (24 bits)	328 I, 328 Q
Synchronous DDCs supported	Yes
DDC Audio CODEC supported	Yes, stereo
Audio CODEC sample rate (ksps)	48
Audio CODEC bits per sample	16
Audio samples per Ethernet packet	64 left, 64 right
Time stamping of I&Q data supported	No
Number of DUCs supported	1
DUC Audio CODEC supported	Yes
Microphone supported	Yes
Line in supported	Yes
Audio CODEC sample rate (ksps)	48
Audio CODEC bits per sample	16
Audio samples per Ethernet packet	64
DUC Frequency or phase word required	Phase
DUC I&Q sample rate (ksps)	192

Bits per I/Q sample	24
Transmit I&Q samples per Ethernet packet	240 I, 240 Q
Envelope Tracking supported	No
CW Sidetone supported	Yes
CW from the Host supported	Yes
CW Iambic Keyer supported	Yes
CW break-in supported	Yes
Hang supported (mS)	Yes, 1 - 1000
RF Delay supported (mS)	Yes, 1 - 255
DUC Phase shift supported	No
Receive attenuator on DUC supported	Yes
Open collector outputs supported	7
DDC Calibration	-138dBm (See Note)
Number of General Purpose ADCs	6
Calibration constant for Supply Voltage. $V = \text{ADC value} / 4095 * \text{constant}$	constant = 5.0
Calibration constant for Exciter, FWD & REV power $W = (\text{ADC value} / 4095 * \text{constant1})^2 / \text{constant2}$ Scale Exciter to 0 to 1000mW Scale ANAN-100 FWD & REV 0 – 150W	Constant1 = 5.0 Constant2 = 0.108

NOTE: DDC calibration. Calibration level is with a 50 ohm load connected to the antenna input, the DDC set to 20m, 500 Hz bandwidth and is the averaged value of the magnitude of the I&Q samples at the output of the filter i.e. DDC noise floor.

To be written

APPENDIX C – Hardware capabilities – SPECIFIC

Response to Discovery - Hardware to Host (from port 1024)		
Byte	To IP address and Port of Host PC	Notes
0	Seq # = 0	[31:24]
1	Seq # = 0	[23:16]
2	Seq # = 0	[15:8]
3	Seq # = 0	[7:0]
4	0x02 (or 0x03)	Response to Discovery
5	Board MAC	MSB
6	Board MAC	
7	Board MAC	
8	Board MAC	
9	Board MAC	
10	Board MAC	LSB
11	Board Type	255
12	openHPSDR Protocol version supported	
13	Firmware Code Version	
14	Spare	
15	Spare	
16	Spare	
17	Spare	
18	Spare	
19	Spare	
20	Host update of firmware supported	
21	Setting of UDP/IP ports supported	
22	Setting IP address supported	
23	Memory mapped registers supported	
24	Alex protocol receive filters supported	
25	Alex protocol transmit filters supported	
26	VITA-49 protocol supported	
27	DSP clock frequency (Hz)	[31:24]
28	DSP clock frequency (Hz)	[23:16]
29	DSP clock frequency (Hz)	[15:8]
30	DSP clock frequency (Hz)	[7:0]
31...35	Reserved for additional General settings	
36	Number of ADCs	
37	Dither supported	
38	Random supported	
39	Number of DDCs supported	

40	Frequency or Phase Word	0 = frequency 1 = phase
41	Receive attenuator supported	
42	Wideband data supported	
43	Wideband samples per Ethernet packet	[15:8]
44	Wideband samples per Ethernet packet	[7:0]
45	Wideband bits per sample fixed or variable	0 = fixed 1 = variable
46	Wideband bits per sample fixed value	
47	Wideband update rate fixed or variable	0 = fixed 1 = variable
48	Wideband update rate fixed (mS)	
49	Wideband packets per frame fixed or variable	0 = fixed 1 = variable
50	Wideband packets per frame fixed	
51	Individual DDC sample rates supported	
52	Minimum DDC sampling rate (ksps)	[15:8]
53	Minimum DDC sampling rate (ksps)	[7:0]
54	Maximum DDC sampling rate (ksps)	[15:8]
55	Maximum DDC sampling rate (ksps)	[7:0]
56	CIC decimation values settable	
57	Synchronous DDCs supported	0 = no n = number
58	(Not currently used)	
59	DDC Audio CODEC supported	0 = no 1 = mono 2 = stereo
60	Audio CODEC sample rate (ksps)	
61	Audio CODEC bits per sample	
62	Audio samples per Ethernet packet	[15:8]
63	Audio samples per Ethernet packet	[7:0]
64	Time stamping of I&Q data supported	
65...69	Reserved for additional DDC settings	
70	Number of DUCs supported	0 = none n = number
71	DUC Audio CODEC supported	
72	Microphone supported	
73	Line in supported	
74	Audio CODEC sample rate (ksps)	
75	Audio CODEC bits per sample	
76	Audio samples per Ethernet packet	[15:8]
77	Audio samples per Ethernet packet	[7:0]
78	Frequency or phase word required	0 = frequency 1 = phase
79	I&Q sample rate (ksps)	
80	Bits per I/Q sample	
81	I&Q samples per Ethernet packet	[15:8]
82	I&Q samples per Ethernet packet	[7:0]
83	Envelope Tracking supported	
84	CW Sidetone supported	

85	CW from the Host supported	
86	CW Iambic Keyer supported	
87	CW break-in supported	
88	Hang supported (mS)	0 = no n = max delay [15:8]
89	Hang supported (mS)	0 = no n = max delay [7:0]
90	RF Delay supported (mS)	0 = no n = max delay
91	DUC Phase shift supported	
92	Receive attenuator on DUC supported	
93	Open collector outputs supported	0 = no n = number
94	DDC Calibration	[15:8]
95	DDC Calibration	[7:0]
96	Number of General Purpose ADCs	[7:0]
97...1439	For future use	

Source Port

This will be set to 1024.

Destination Port

This will be set to the Source Port of the Host that initiated the Command.

Sequence Number

A 4-byte integer set to 0x00000000.

Byte 4

Normally 0x02 but if the hardware is running and already connected to a different Host it will be 0x03.

Bytes 5 to 10 - MAC

This is 6 bytes and holds the MAC address of the hardware that is responding to the Command request

Byte 12

A byte that indicates the openHPSDR Protocol Version supported. The Host interprets this as a decimal number e.g. 104 would be interpreted as version 10.4.

Byte 13 - Firmware Code Version

A byte that indicates the version of code loaded into the associated board(s). The Host interprets this as a decimal number e.g. 15 would be interpreted as version 1.5.

Bytes 14 to 19

Where an Atlas based system is identified, bytes 14 to 19 contain the code versions loaded into the respective boards. A version number of zero indicates a board is not present.

Byte 20

Bit [0] set when openHPSDRProgrammer.exe can be used to update the FPGA code.

Byte 21

Bit[0] set when other than default UDP/IP ports can be set.

Byte 22

Bit[0] set when openHPSDRProgrammer.exe can be used to set a fixed IP address.

Byte 23

Bit[0] set when memory mapped registers supported

Byte 24

Bit[0] set when Alex protocol receive filters supported

Byte 25

Bit[0] set when Alex protocol transmit filters supported

Byte 26

Bit[0] set when VITA-49 protocol supported

Bytes 27 to 30

A four byte value representing the DSP clock frequency in Hz

Byte 36

A byte indicating the number of ADC available

Byte 37

Bit [0] set indicates that ADC dither is supported

Byte 38

Bit [0] set indicates that ADC random is supported

Byte 39

A byte indicating the number of DDCs supported

Byte 40

Bit [0] set when phase words are required, if not set then frequency required.

Byte 41

Bit [0] set when DDC input attenuator supported

Byte 42

Bit [0] set when wideband (i.e. raw ADC samples) supported

Bytes 43 and 44

A 16 bit word indicating the number of wideband samples per Ethernet packet

Byte 45

Bit [0] set when variable bits per wideband sample are supported

Byte 46

A byte indicating the number of fixed bits per wideband sample

Byte 47

Bit [0] set when the wideband update rate is variable

Byte 48

A byte indicating the fixed wideband update rate

Byte 49

Bit [0] set when the number of wideband packets per frame are variable

Byte 50

A byte indicating the fixed number of wideband packets per frame

Byte 51

Bit [0] set when individual DDC sample rates are supported

Bytes 52 and 53

A 16 bit word indicating the minimum DDC sampling rate

Bytes 54 and 55

A 16 bit word indicating the maximum DDC sampling rate

Byte 56

Bit [0] set when CIC decimation values settable

Byte 57

A byte indicating the number of synchronous DDCs supported, zero equates to none.

Byte 58

Not currently used

Byte 59

A byte indicating an Audio CODEC is supported, zero equates to no, 1 equates to mono and 2 to stereo

Byte 60

A byte indicating the Audio CODECs sampling rate in ksp/s

Byte 61

A byte indicating the Audio CODEC bits per sample

Byte 62 and 63

A 16 bit word indicating the number of audio samples per Ethernet packet

Byte 64

Bit [0] set when time stamping of I&Q samples is supported

Byte 70

A byte indicating the number of DUCs supported, zero equates to none

Byte 71

Bit [0] set when a DUC Audio CODEC is supported

Byte 72

Bit [0] set when a microphone input to the DUC Audio CODEC is supported

Byte 73

Bit [0] set when a line input to the DUC Audio CODEC is supported

Byte 74

A byte indicating the Audio CODEC's sampling rate in ksps

Byte 75

A byte indicating the Audio CODEC bits per sample

Byte 76 and 77

A 16 bit word indicating the number of audio samples per Ethernet packet

Byte 78

Bit [0] set when a DUC phase word is required, if zero then frequency required

Byte 79

A byte indicating the transmit I&Q data sample rate in ksps

Byte 80

A byte indicating the transmit I&Q data sample size in bits

Byte 81 and 82

A 16 bit word indicating the number DUC I&Q samples per Ethernet packet

Byte 83

Bit [0] set when an Envelope Tracking or Envelope Elimination and Restoration amplifier is supported

Byte 84

Bit [0] set when hardware CW sidetone generation is supported

Byte 85

Bit [0] set when CW from host is supported

Byte 86

Bit [0] set when an Iambic hardware CW keyer is supported

Byte 87

Bit [0] set when CW break-in is supported

Bytes 89 and 89

A 16 bit word indicating the maximum delay of CW Hang supported in mS. A zero value indicates not supported

Byte 90

A byte indicating the maximum delay of RF Delay supported in mS. A zero value indicates not supported

Byte 91

Bit [0] set indicates DUC RF phase shift supported

Byte 92

Bit [0] set indicates the DDC front end attenuator may be activated on transmit is supported. A zero value indicates not supported

Byte 93

A byte indicating the number of open collector outputs supported. A zero value indicates none.

Bytes 94 and 95

A 16 bit word indicating the calibration value for a DDC. The value is the maximum value of an I or Q sample with a RF input of -20dBm at a frequency of 14.200 MHz with the DDC tuned to 14.210 MHz and the sample rate set a 48ksps. This value is intended to enable a bandscope and/or S Meter to be calibrated.

Byte 96

A byte indicating the number of general purpose ADCs available. These are typically used to indicate forward and reverse powers, supply voltages and temperatures etc.

Appendix D – Alex filters description

High Pass Filters (HPF) and Low Pass Filters (LPF) may be used with any openHPSDR board set.

The filters are called 'Alex' filters (short for Alexiares) which were initially designed by Graham, KE9H, for use with the original Atlas based hardware. The original Alex filters are currently used with Atlas based hardware, but the design has evolved over time for use with other openHPSDR designs.

The method of controlling the various relays that select filters, 6m pre-amp, antennas and attenuators has not changed significantly over time. In which case this document will refer to Alex filters which implies the Alex data protocol rather than the original Alex hardware.

Whilst individual Alex implementations will differ, hence the specific descriptions that follow, the common factor is the use of a 32 bit data word [31:0] that controls the various filters, 6m pre-amp, antenna selection and attenuators.

The top 16 bits [31:16] control LPFs, antenna selection and the antenna change over relay whilst the lower 16 bits [15:0] control HPFs, DDC inputs and attenuators. In general, a set bit activates a relay that selects a filter, antenna or attenuator.

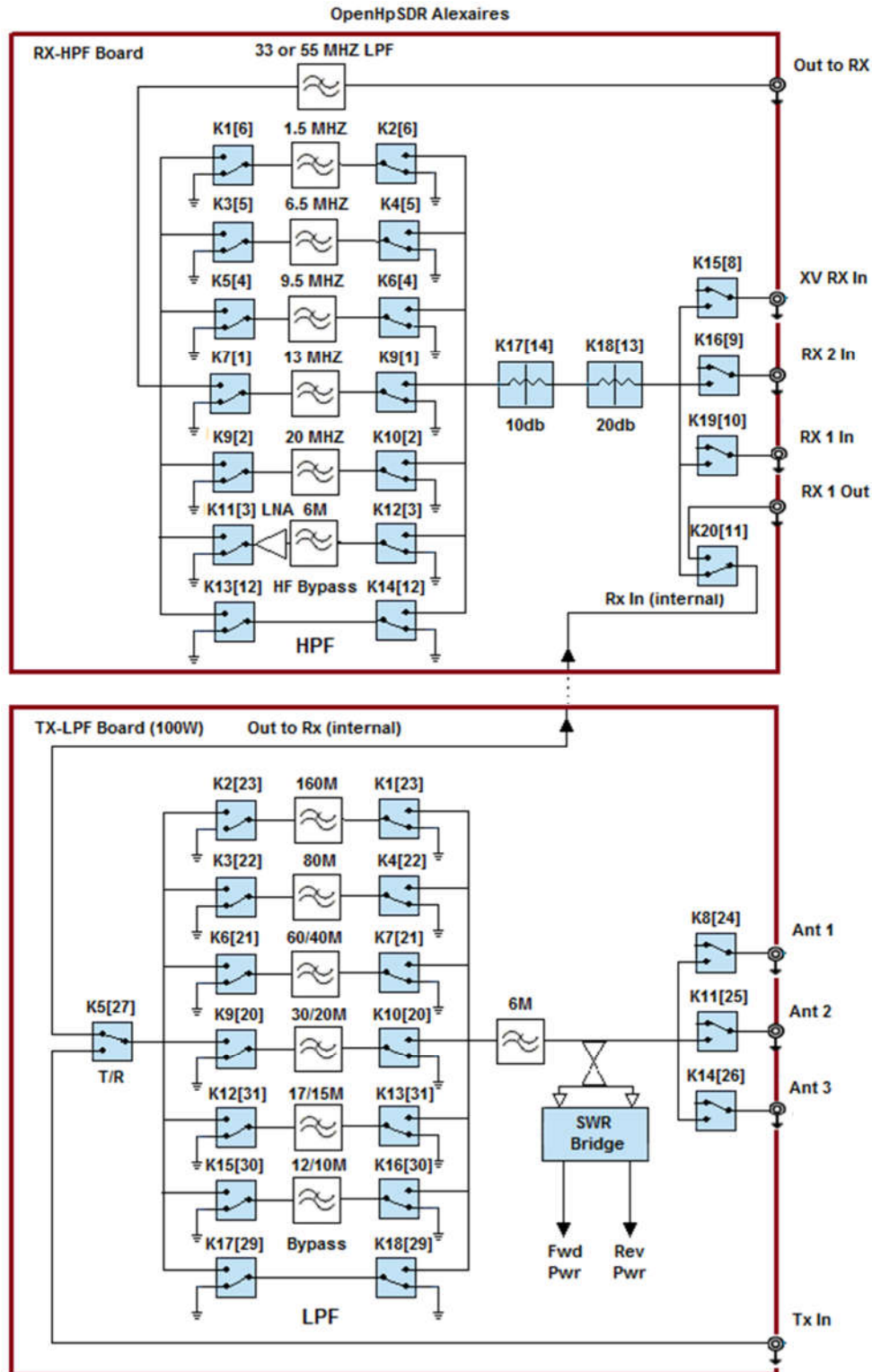
At power on all 32 bits are set to 0 by the FPGA code and remain in that state until an Alex command is received.

In the following block diagrams the numbers against each relay refer to the relay designation in the relevant board schematic followed by the bit that operates it e.g. K2 [23] indicates relay K2 which is operated when bit [23] is set.

Note that in order to use an Alex filter it is necessary to set the relevant bit in Byte 59 of the 'General to hardware' packet. Since all existing openHPSDR hardware includes only one Alex filter set, this will mean setting bit [0] of Byte 59.

ALEX FILTERS FOR ATLAS BASED SYSTEMS

The Alex filters used with Atlas based system comprise two circuit boards, one containing LPFs, Antenna selection and change over relay and the other HPFs, 6m pre-amp, Receive Antenna selection and Attenuators. A block diagram of the filter system is shown in the following diagram.



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11/11/2015

Relays are shown in de-energised state. The bits in the Alex data register map as follows:

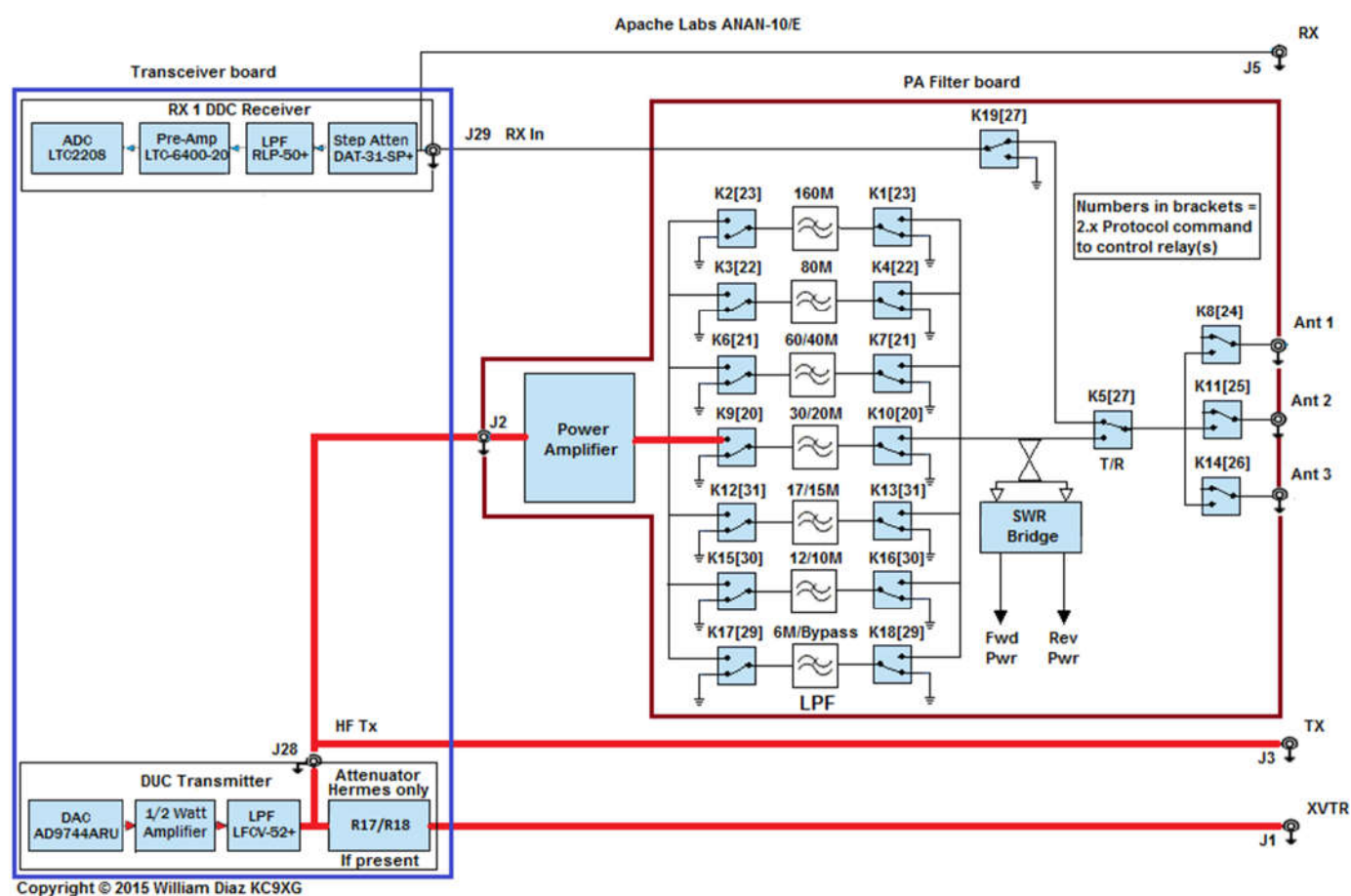
Bit	Function	Bit	Function
0	YELLOW LED	16	N.C.
1	13 MHz HPF	17	N.C.
2	20 MHz HPF	18	N.C.
3	6M Preamp	19	YELLOW LED
4	9.5 MHz HPF	20	30/20 Meters LPF
5	6.5 MHz HPF	21	60/40 Meters LPF
6	1.5 MHz HPF	22	80 Meters LPF
7	N.C.	23	160 Meters LPF
8	XVTR DDC In	24	ANT 1
9	DDC 2 In	25	ANT 2
10	DDC 1 In	26	ANT 3
11	DDC 1 Out	27	T/R
12	HF Bypass	28	RED LED
13	20 dB Atten.	29	Bypass
14	10 dB Atten.	30	12/10 Meters LPF
15	RED LED	31	17/15 Meters LPF

Where all bits are active high and bit 27 high selects transmit.

More details of the board features can be found here: <http://openhpsdr.org/alex.php>

ALEX FILTERS FOR ANAN-10 & ANAN-10E SYSTEMS

Both these systems use LPFs only. A block diagram of the filter system is shown in the following diagram.



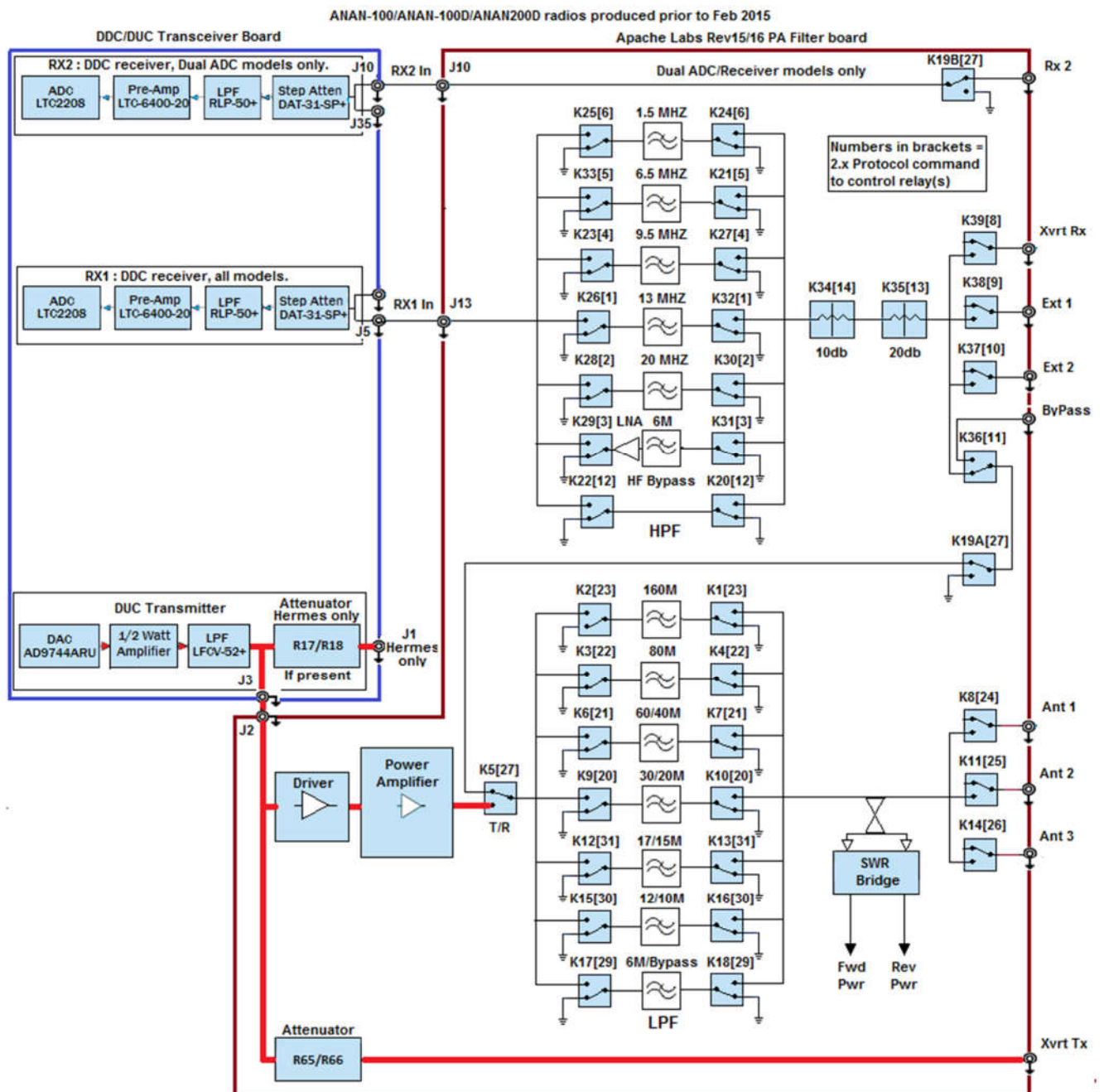
Relays are shown in de-energised state. The bits in the Alex data register map as follows:

Bit	Function
20	30/20 Meters LPF
21	60/40 Meters LPF
22	80 Meters LPF
23	160 Meters LPF
24	ANT 1
25	ANT 2
26	ANT 3
27	T/R
28	N.C.
29	6 Mtrs/Bypass
30	12/10 Meters LPF
31	17/15 Meters LPF

Where all bits are active high and bit 27 high selects transmit.

ALEX FILTERS FOR ANAN-100, 100D AND 200D SYSTEMS (REV 15/16)

The following block diagram relates to Rev15/16 boards which were fitted prior to **February 2015**.



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Relays are shown in de-energised state. The bits in the Alex data register map* as follows:

Bit	Function	Bit	Function
0	YELLOW LED	16	N.C.
1	13 MHz HPF	17	N.C.
2	20 MHz HPF	18	N.C.
3	6M Preamp	19	YELLOW LED
4	9.5 MHz HPF	20	30/20 Meters LPF
5	6.5 MHz HPF	21	60/40 Meters LPF
6	1.5 MHz HPF	22	80 Meters LPF
7	N.C.	23	160 Meters LPF
8	Xvrt DDC	24	ANT 1
9	Ext 1	25	ANT 2
10	Ext 2	26	ANT 3
11	ByPass	27	T/R
12	HF Bypass	28	RED LED
13	20 dB Atten.	29	6M/Bypass
14	10 dB Atten.	30	12/10 Meters LPF
15	RED LED	31	17/15 Meters LPF

*For the Orion II (ANAN-8000DLE) the following register map applies:

For Alex 0

Bit	Function	Bit	Function
0	YELLOW LED	16	N.C.
1	13 MHz HPF	17	N.C.
2	20 MHz HPF	18	TxRx Status
3	6M Preamp	19	YELLOW LED
4	9.5 MHz HPF	20	30/20 Meters LPF
5	6.5 MHz HPF	21	60/40 Meters LPF
6	1.5 MHz HPF	22	80 Meters LPF
7	N.C.	23	160 Meters LPF
8	N.C.	24	ANT 1
9	N.C.	25	ANT 2
10	N.C.	26	ANT 3
11	N.C.	27	T/R
12	HF Bypass	28	RED LED
13	N.C.	29	6M/Bypass
14	N.C.	30	12/10 Meters LPF
15	RED LED	31	17/15 Meters LPF

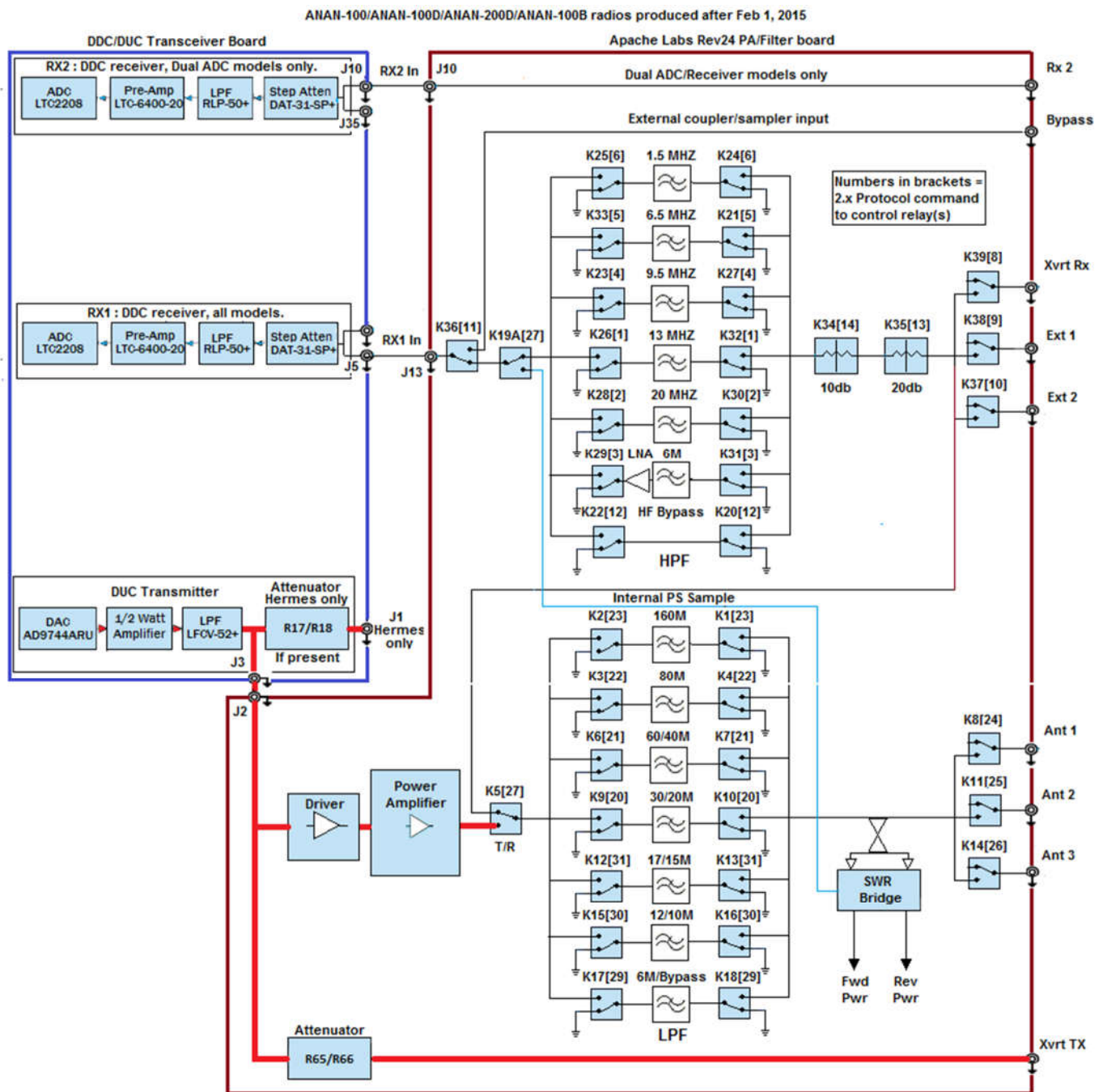
For Alex 1 (HPF)

Bit	Function
0	YELLOW LED
1	13 MHz HPF
2	20 MHz HPF
3	6M Preamp
4	9.5 MHz HPF
5	6.5 MHz HPF
6	1.5 MHz HPF
7	N.C.
8	Rx2 Ground
9	N.C.
10	N.C.
11	N.C.
12	HF Bypass
13	N.C.
14	N.C.
15	RED LED

Where all bits are active high and bit 27 high selects transmit.

ALEX FILTERS FOR ANAN- 100/100B/100E/200D SYSTEMS (REV 24)

The following block diagram relates to Rev24 boards which were fitted post **February 2015**.



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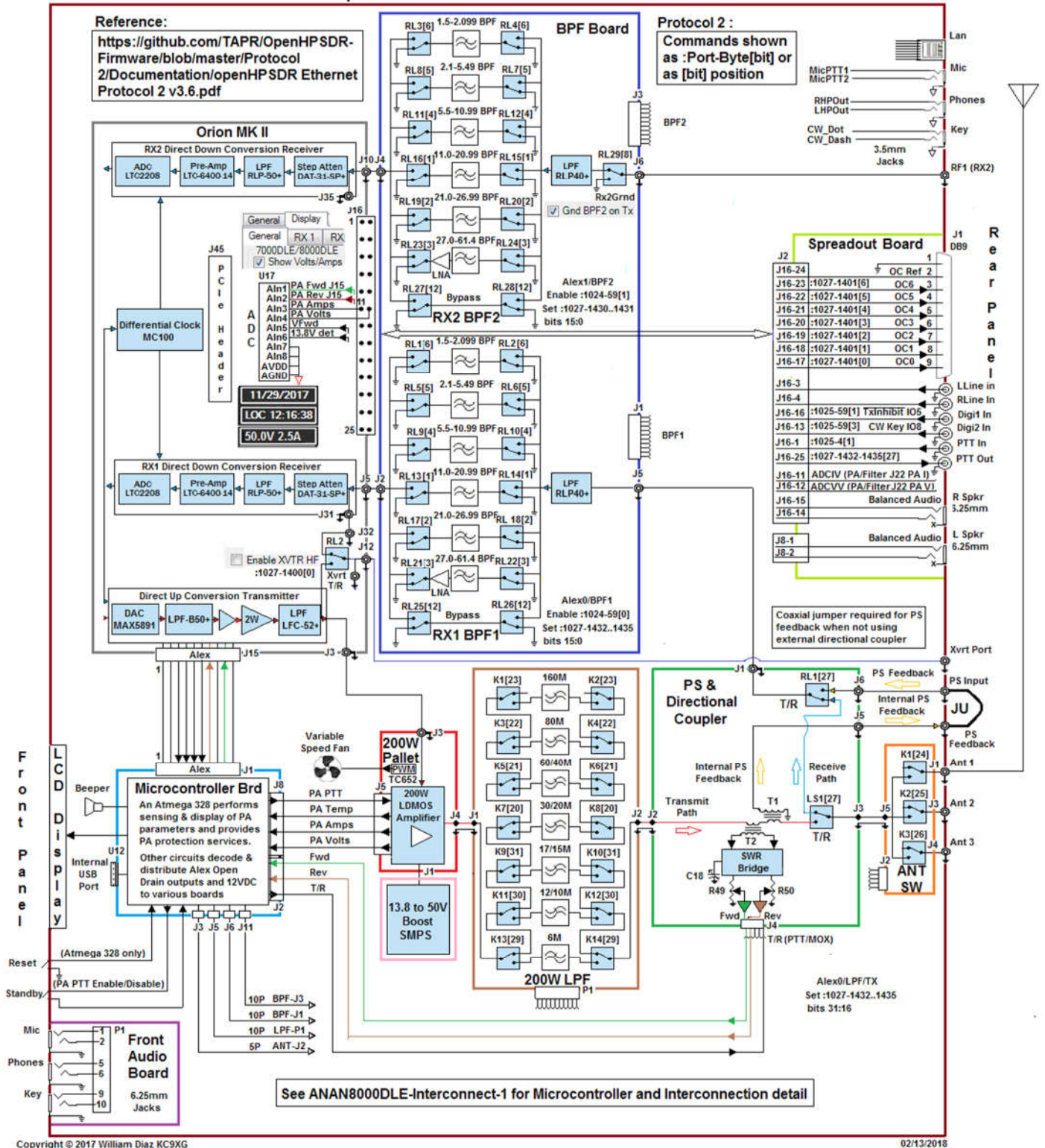
Relays are shown in de-energised state. The bits in the Alex data register (1027-1432..1435) map as follows:

Bit	Function	Bit	Function
0	YELLOW LED	16	N.C.
1	13 MHz HPF	17	N.C.
2	20 MHz HPF	18	N.C.
3	6M Preamp	19	YELLOW LED
4	9.5 MHz HPF	20	30/20 Meters LPF
5	6.5 MHz HPF	21	60/40 Meters LPF
6	1.5 MHz HPF	22	80 Meters LPF
7	N.C.	23	160 Meters LPF
8	Xvrt DDC	24	ANT 1
9	Ext 1	25	ANT 2
10	Ext 2	26	ANT 3
11	Bypass	27	T/R
12	HF Bypass	28	RED LED
13	20 dB Atten.	29	6M/Bypass
14	10 dB Atten.	30	12/10 Meters LPF
15	RED LED	31	17/15 Meters LPF

Where all bits are active high and bit 27 high selects transmit.

ALEX FILTERS FOR ORION MKII, ANAN-8000DLE

Apache Labs ANAN-8000DLE Protocol 2 Reference



Relays are shown in de-energised state.

The bits in the Alex 0 data registers (1027-1432..1435) follows:

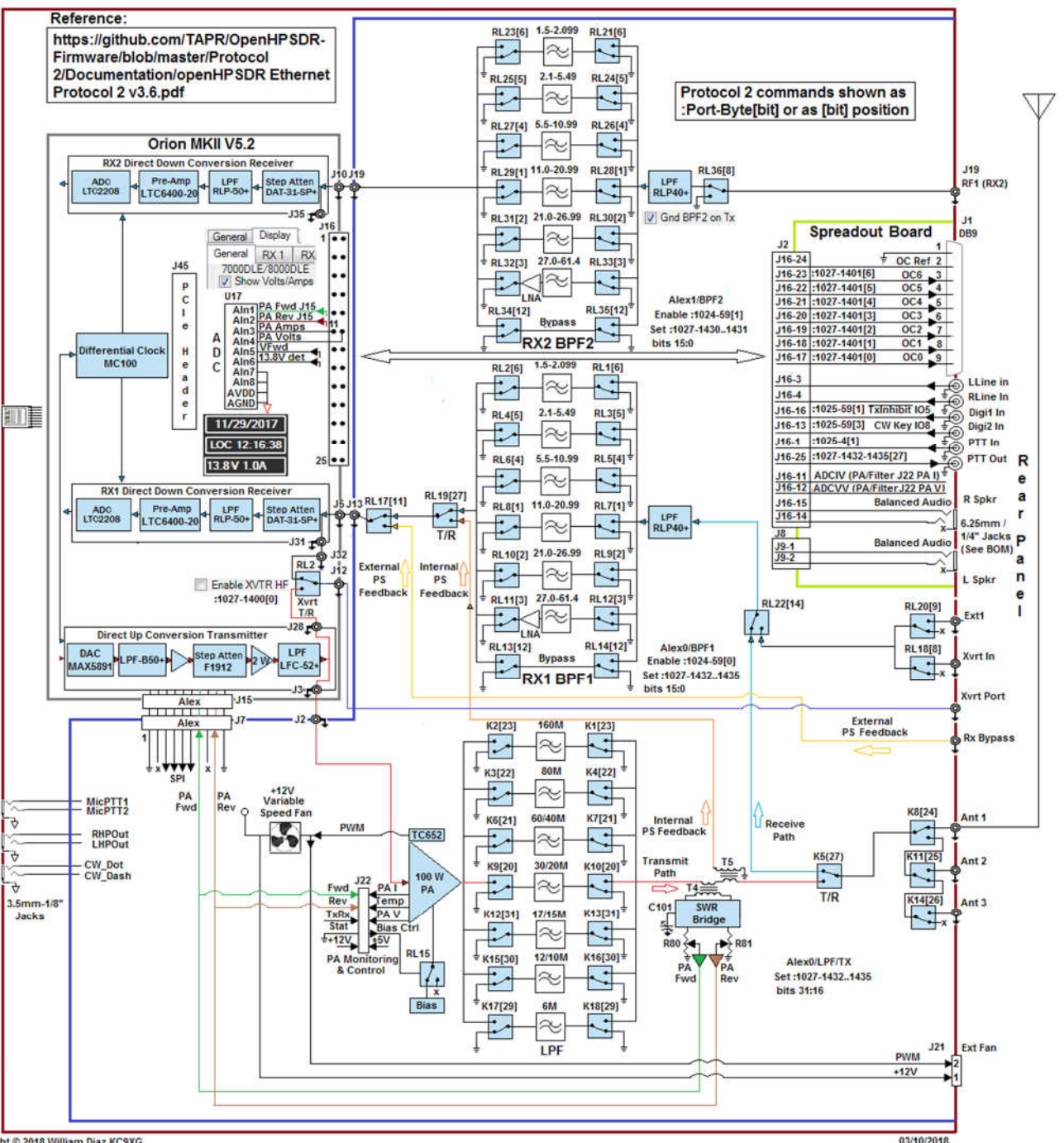
Bit	Function	Bit	Function
0	YELLOW LED	16	N.C.
1	13 MHz BPF	17	N.C.
2	20 MHz BPF	18	TX/RX Status
3	6M Preamp	19	YELLOW LED
4	9.5 MHz BPF	20	30/20 Meters LPF
5	6.5 MHz BPF	21	60/40 Meters LPF
6	1.5 MHz BPF	22	80 Meters LPF
7	N.C.	23	160 Meters LPF
8	N.C.	24	ANT 1
9	N.C.	25	ANT 2
10	N.C.	26	ANT 3
11	N.C.	27	T/R
12	HF Bypass	28	RED LED
13	N.C.	29	6M/Bypass
14	N.C.	30	12/10 Meters LPF
15	RED LED	31	17/15 Meters LPF

The bits in the Alex1 (BPF2/RX2) data registers (1027-1430..1431) follow:

Bit	Function
0	YELLOW LED 2
1	13 MHz BPF 2
2	20 MHz BPF 2
3	6M Preamp 2
4	9.5 MHz BPF 2
5	6.5 MHz BPF 2
6	1.5 MHz BPF 2
7	N.C.
8	RX2 Ground
9	NC
10	NC
11	NC
12	HPF Bypass 2
13	NC
14	NC
15	RED LED 2

ALEX FILTERS FOR ORION MKII 5.2, ANAN-7000DLE

Apache Labs ANAN-7000DLE Protocol 2 Reference



Relays are shown in de-energised state.

The bits in the Alex 0 data registers (1027-1432..1435) follows:

Bit	Function	Bit	Function
0	YELLOW LED	16	N.C.
1	13 MHz BPF	17	N.C.
2	20 MHz BPF	18	TX/RX Status
3	6M Preamp	19	YELLOW LED
4	9.5 MHz BPF	20	30/20 Meters LPF
5	6.5 MHz BPF	21	60/40 Meters LPF
6	1.5 MHz BPF	22	80 Meters LPF
7	N.C.	23	160 Meters LPF
8	Xvrt DDC	24	ANT 1
9	Ext 1	25	ANT 2
10	N.C.	26	ANT 3
11	PS Sample Select	27	T/R
12	HF Bypass	28	RED LED
13	N.C.	29	6M/Bypass
14	Rx Master in Sel.	30	12/10 Meters LPF
15	RED LED	31	17/15 Meters LPF

The bits in the Alex1 (BPF2/RX2) data registers (1027-1430..1431) Follow:

Bit	Function
0	YELLOW LED 2
1	13 MHz BPF 2
2	20 MHz BPF 2
3	6M Preamp 2
4	9.5 MHz BPF 2
5	6.5 MHz BPF 2
6	1.5 MHz BPF 2
7	N.C.
8	RX2 Ground
9	N.C.
10	N.C.
11	N.C.
12	HF Bypass 2
13	N.C.
14	N.C.
15	RED LED 2