view frames Result Recorded at time: 1649823889.3125494 base link Broadcaster: /my\_gen3/robot\_state\_publisher Broadcaster: /my\_gen3/camera\_to\_base\_tf Average rate:  $40.\overline{2}01$ Average rate: 10.191 Buffer length: 4.975 Buffer length: 4.906 Most recent transform: 1649823889.261 Most recent transform: 1649823889.334 Oldest transform: 1649823884.286 Oldest transform: 1649823884.428 shoulder link camera Broadcaster: /my\_gen3/robot\_state\_publisher Broadcaster: /frameHandler Broadcaster: /frameHandler Broadcaster: /frameHandler Average rate:  $40.\overline{201}$ Average rate: 54.24 Average rate: 54.24 Average rate: 54.24 Buffer length: 4.975 Buffer length: 4.978 Buffer length: 4.978 Buffer length: 4.978 Most recent transform: 1649823889.261 Most recent transform: 1649823889.276 Most recent transform: 1649823889.276 Most recent transform: 1649823889.276 Oldest transform: 1649823884.286 Oldest transform: 1649823884.298 Oldest transform: 1649823884.298 Oldest transform: 1649823884.298 half\_arm\_1\_link pelvis probe ee\_marker Broadcaster: /my gen3/robot state publisher Broadcaster: /frameHandler Average rate: 54.24 Average rate:  $40.\overline{2}01$ Buffer length: 4.975 Buffer length: 4.978 Most recent transform: 1649823889.261 Most recent transform: 1649823889.276 Oldest transform: 1649823884.286 Oldest transform: 1649823884.298 half\_arm\_2\_link probetip Broadcaster: /my\_gen3/robot\_state\_publisher Average rate:  $40.\overline{2}01$ Buffer length: 4.975 Most recent transform: 1649823889.261 Oldest transform: 1649823884.286 forearm link Broadcaster: /my gen3/robot state publisher Average rate:  $40.\overline{2}01$ Buffer length: 4.975 Most recent transform: 1649823889.261 Oldest transform: 1649823884.286 spherical\_wrist\_1\_link Broadcaster: /my\_gen3/robot\_state\_publisher Average rate:  $40.\overline{201}$ Buffer length: 4.975 Most recent transform: 1649823889.261 Oldest transform: 1649823884.286 spherical\_wrist\_2\_link Broadcaster: /my\_gen3/robot\_state\_publisher Average rate:  $40.\overline{2}01$ Buffer length: 4.975 Most recent transform: 1649823889.261 Oldest transform: 1649823884.286 bracelet link Broadcaster: /my\_gen3/robot\_state\_publisher Average rate:  $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 end effector link Broadcaster: /my\_gen3/robot state publisher Broadcaster: /my\_gen3/robot\_state\_publisher | Broadcaster: /my\_gen3/robot\_state\_publisher Broadcaster: /my gen3/robot state publisher Broadcaster: /my\_gen3/robot\_state\_publisher Average rate:  $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera\_color\_frame camera link camera\_depth\_frame robotiq arg2f base link tool frame Broadcaster: /my\_gen3/robot\_state\_publisher Broadcaster: /my\_gen3/robot\_state\_publisher Broadcaster: /my\_gen3/robot\_state\_publisher Broadcaster: /my\_gen3/robot\_state\_publisher Average rate:  $40.\overline{2}01$ Average rate:  $40.\overline{2}01$ Average rate:  $40.\overline{201}$ Average rate:  $40.\overline{201}$ Buffer length: 4.975 Buffer length: 4.975 Buffer length: 4.975 Buffer length: 4.975 Most recent transform: 1649823889.261 Most recent transform: 1649823889.261 Most recent transform: 1649823889.261 Most recent transform: 1649823889.261 Oldest transform: 1649823884.286 Oldest transform: 1649823884.286 Oldest transform: 1649823884.286 Oldest transform: 1649823884.286 left outer\_knuckle right inner knuckle right outer knuckle left inner knuckle Broadcaster: /my\_gen3/robot\_state\_publisher Broadcaster: /my\_gen3/robot\_state\_publisher Average rate:  $100\overline{0}0.0$ Average rate:  $100\overline{0}0.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 left outer finger right outer finger Broadcaster: /my gen3/robot state publisher Broadcaster: /my gen3/robot state publisher Average rate:  $40.\overline{201}$ Average rate:  $40.\overline{201}$ Buffer length: 4.975 Buffer length: 4.975 Most recent transform: 1649823889.261 Most recent transform: 1649823889.261 Oldest transform: 1649823884.286 Oldest transform: 1649823884.286 left\_inner\_finger right\_inner\_finger Broadcaster: /my gen3/robot state publisher Broadcaster: /my\_gen3/robot\_state\_publisher Average rate:  $100\overline{0}0.0$ Average rate:  $100\overline{0}0.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 left\_inner\_finger\_pad right\_inner\_finger\_pad