

Implementation of std::rotate algorithm

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std::rotate(Introduction)

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What is std::rotate

```
// I models Forward Iterator  
template<class I> // (until C++11)  
void rotate(I first, I n_first, I last);  
  
template<class I> // (since C++11)  
I rotate(I first, I n_first, I last);
```

Performs a left rotation on a range of elements.

```
vector<int> s{0, 1, 2, 2, 3, 4, 5, 7, 7, 10};  
rotate(s.begin(), s.begin()+1, s.end());  
// rotate left : 1, 2, 2, 3, 4, 5, 7, 7, 10, 0
```

Inserting elements in vector using rotate in $O(n)$

```
// I models Input Iterator to T
template <typename T, typename I>
void insert(vector<T>& v,
            typename vector<T>::iterator ip,
            I first, I limit) {
    auto n = v.end() - v.begin();
    while (first != limit) {
        v.push_back(*first);
        ++first;
    }
    rotate(ip, v.begin() + n, v.end());
}
```

Implementation using bidirectional iterator

```
// I models Bidirectional Iterator  
// f: first  
// m: rotation point  
// l: limit  
// [f, l) is valid and m is in [f, l)  
template <typename I>  
void rotate(I f, I m, I l) {  
    reverse(f, m);  
    reverse(m, l);  
    reverse(f, l);  
}
```

Implementation using forward iterator

```
// I models Forward Iterator  
// f: first  
// m: rotation point  
// l: limit  
// [f, l) is valid and m is in [f, l)  
template <typename I>  
void rotate(I f, I m, I l) {  
    pair<I, I> p = swap_ranges(f, m, m, l);  
    I u = p.first;  
    I v = p.second;  
    if (v != l)  
        rotate(u, v, l);  
    else if (u != m)  
        rotate(u, m, l);  
}
```

Implementation using random-access iterator

```
// I models Forward Iterator
// f: first
// m: rotation point
// l: limit
// [f, l) is valid and m is in [f, l)
template <typename I>
pair<I, I> rotate(I f, I m, I l) {
    DISTANCE_TYPE(I) n = gcd(m - f, l - m);
    rotate_iterator_action<I> action(f, m, l);
    while (n > 0) {
        --n;
        do_cycle(f + n, action);
    }
    I n_m = f + (l - m);
    return (n_m < m) ? pair<I, I>(n_m, m)
        : pair<I, I>(m, n_m);
}
```