

# Time Integration Methods So Far

Forward Euler: Use slope at starting point.

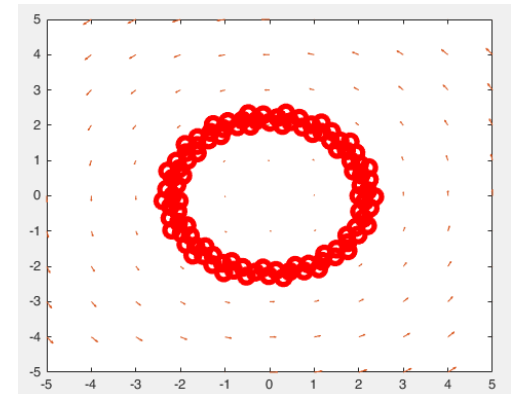
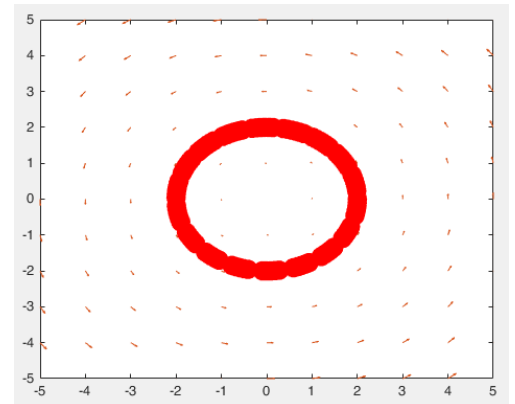
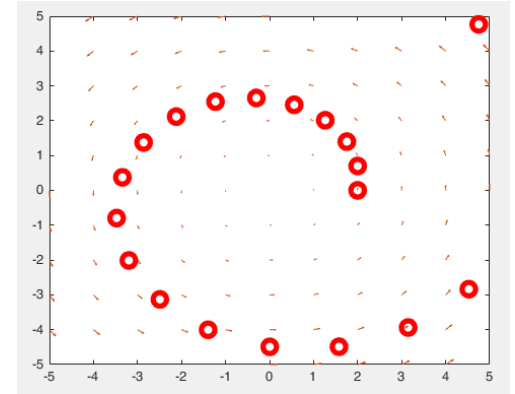
- Local Truncation Error (LTE):  $O(h^2)$ . Explicit. Single-Step.

Trapezoidal: Use average of slope at start and end of step.

- LTE:  $O(h^3)$ . **Implicit**. Single-Step.

Improved Euler: Use average of slope at start and (approximate) end.

- LTE:  $O(h^3)$ . Explicit. Single-Step.



# Improved Euler / Trapezoidal Example

We previously applied F.E. to the problem:

$$\begin{aligned}x'(t) &= -y(t) \\ y'(t) &= x(t)\end{aligned}$$

with initial conditions  $x(t_0) = 2, y(t_0) = 0, t_0 = 0$ .

- 1) Apply *improved Euler* with time step size  $h = 2$  to find  $x, y$  at  $t = 4$ .
- 2) What equations do we need to solve if we apply the trapezoidal method?

# Even More Schemes!

There are many more time integration schemes, each with its own particular properties. (Impossible to cover them all.)

We will see a few more, and (continue to) focus on:

1. Truncation error
2. Explicit v.s. implicit
3. Single-step v.s. multistep
4. Stability (Still to come!)

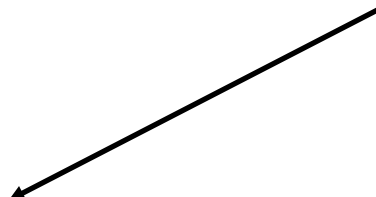
# Backwards (Implicit) Euler method

Similar to forward Euler, but implicit.

Forward Euler:

$$y_{n+1} = y_n + hf(t_n, y_n)$$

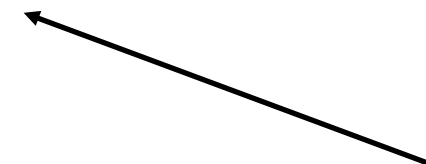
Start of Step Slope,  
i.e. time  $t_n$ .



*Backwards Euler* uses the slope from **only** the end of the step:

$$y_{n+1} = y_n + hf(t_{n+1}, y_{n+1})$$

End of Step Slope,  
i.e. time  $t_{n+1}$ .



Its local truncation error is  $O(h^2)$ , like F.E.

# Explicit “Runge Kutta” schemes

Improved Euler can (equivalently) be written as:

$$k_1 = h \cdot f(t_n, y_n),$$

$$k_2 = h \cdot f(t_n + h, y_n + k_1),$$

$$y_{n+1} = y_n + \frac{k_1}{2} + \frac{k_2}{2}.$$

There is an entire family of similar schemes: *Runge Kutta* methods.  
Often written in this form.

# (Explicit) Midpoint method

Another explicit Runge Kutta scheme (with LTE  $O(h^3)$ ) is the *explicit midpoint method* (course notes p54):

$$k_1 = h \cdot f(t_n, y_n),$$

$$k_2 = h \cdot f\left(t_n + \frac{h}{2}, y_n + \frac{k_1}{2}\right),$$

$$y_{n+1} = y_n + k_2.$$

Intuition?

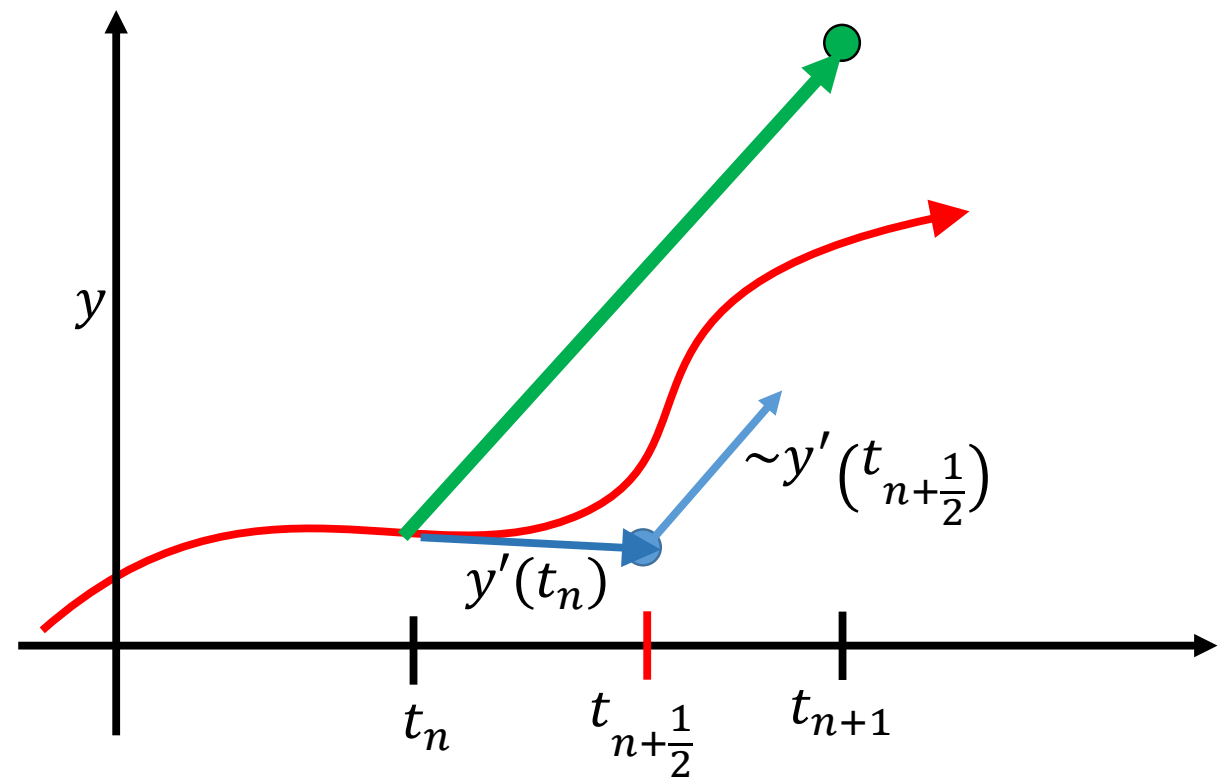
# (Explicit) Midpoint method - Intuition

1. Take a FE step to the “halfway” point in time.
2. Evaluate the slope there.
3. Use *that* slope to take a full step from the start.

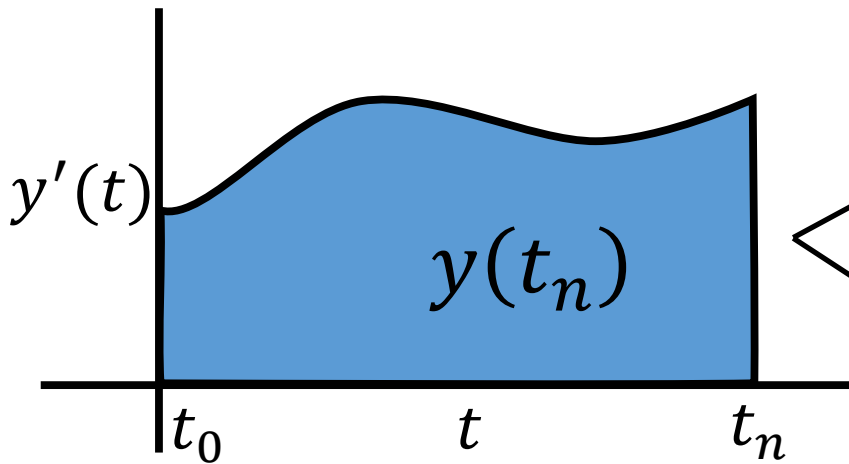
Equivalent expression:

$$y_{n+\frac{1}{2}}^* = y_n + \frac{h}{2} f(t_n, y_n),$$

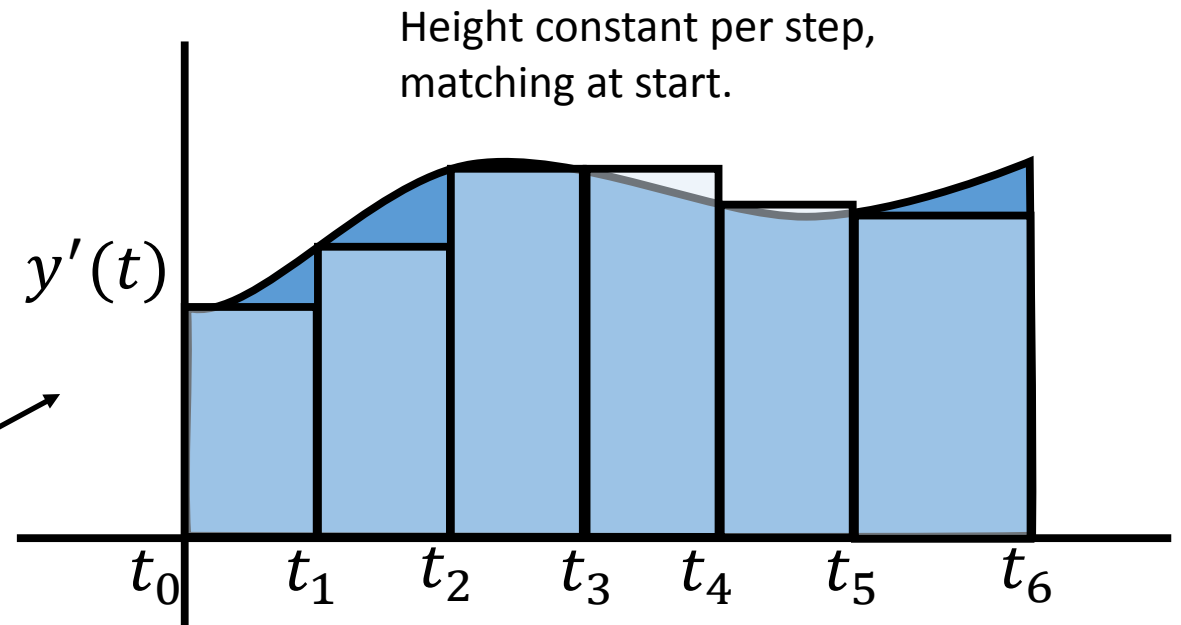
$$y_{n+1} = y_n + hf\left(t_n + \frac{h}{2}, y_{n+\frac{1}{2}}^*\right)$$



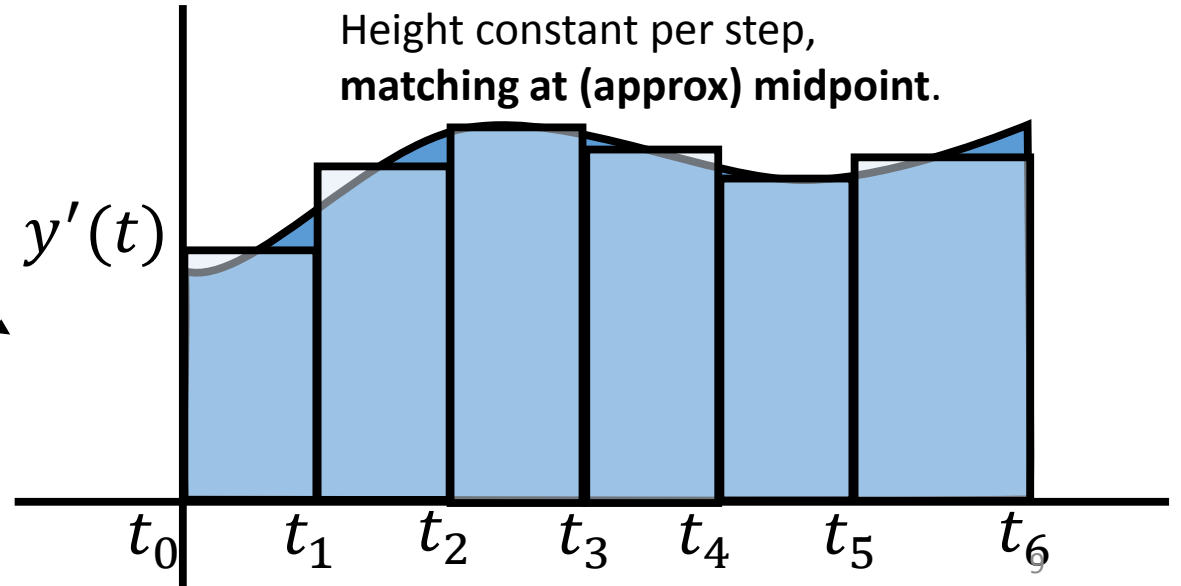
# Area Integration View



Forward  
Euler



(Explicit)  
Midpoint





## 4<sup>th</sup> Order Runge Kutta

Similar schemes exist for higher orders,  $O(h^\alpha)$  for  $\alpha = 4, 5, 6 \dots$

“Classical” Runge-Kutta, or “RK4”, with LTE of  $O(h^5)$ :

$$\begin{aligned} k_1 &= h \cdot f(t_n, y_n), \quad k_2 = h \cdot f\left(t_n + \frac{h}{2}, y_n + \frac{k_1}{2}\right), \\ k_3 &= h \cdot f\left(t_n + \frac{h}{2}, y_n + \frac{k_2}{2}\right), \quad k_4 = h \cdot f(t_n + h, y_n + k_3), \\ y_{n+1} &= y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4). \end{aligned}$$

Again, evaluate  $y'(t) = f(t, y)$  at various intermediate positions, and take a specific linear combination to find  $y_{n+1}$ .

# RK4 – Area integration (& interpolation)

RK4 also approximates area under the derivative curve! (But not using rectangle or trapezoids.)

Fit a ***quadratic*** to the start, middle, and end points, and exactly integrate area beneath. (AKA “Simpson’s rule”.)

