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A Procedure to Nudge Outcome Selection with Algorithmic Learners

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Before Proceeding



Applications/Interpretations of Learning

- 1. Boundedly rational model
- 2. Algorithm self-play
- 3. How to play against an algorithm?

Learning Generates Equilibrium?

Can bounded rational agents/Al/algorithms achieve equilibrium?

- ► Epistemological conditions for NE (Aumann and Brandenburger, 1995)
- Mixed results: There is no uncoupled learning algorithm that achieve NE in all games (Hart and Mas-Colell, 2003) but empirical distributions of play converge to the set of CE of the game (Hart and Mas-Colell, 2000; Foster and Vohra, 1997)
- ► "Game theory is somewhat unusual in having the notion of an equilibrium without associated dynamics that give rise to the equilibrium" Arrow (1986); Shoham et al. (2007)
- Strategic decision-making with possibly non-human subjects can have surprising outcomes (Calvano et al., 2020)



The Gap

- P.1 Which equilibrium does it converges to? (Canyakmaz et al., 2024; Borowski et al., 2019)
- P.2 Complexity of finding payoff improving CE (Barman and Ligett, 2015)
- P.3 Convergence guarantees are on distribution of play, not on actual play (Borowski et al., 2019)

Can we devise a welfare-improving learning algorithm?

► New algorithm and information design

This Paper

- 1. Introduce message-mediated augmentation of a learning algorithm
- 2. Apply to a variant of fictitious play
- 3. Simulate the discrete-time version
- 4. Analyze convergence in continuous time
- 5. Compare welfare with and without messages

Results

- Achieve welfare correlated version of the equilibrium (NE or QRE)
- 2. Can be payoff increasing
- 3. Show which message distribution it works (Robust Information Design)

Similar Papers

The Assumption vs Result Gap

- Q-learning (forward-looking) can converge to correlated equilibria but requires state-dependent payoffs (Greenwald et al., 2003)
- ▶ Requires a complicated algorithm that alternates between exploration and exploitation (Borowski et al., 2019; Marden, 2017)
- ► Induce learning by varying the utilities in each stage game (Canyakmaz et al., 2024)

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Game

$$\Gamma = (N, (A_i)_i, (u_i)_i)$$

- \triangleright $N = \{1, 2\}$, Repeated
- ► Equilibrium analysis of the stage-game

$$\begin{array}{c|ccccc} & a & b \\ \hline a & 6,6 & 2,7 \\ \hline b & 7,2 & 0,0 \\ \end{array}$$

Correlated equilibrium

- ▶ Message distribution $\mu \sim \Delta(M), M = \times_i M_i$
- $ightharpoonup \mu_i$ marginal distribution of μ
- ▶ Information Design perspective vs ML perspective

	m_1	m_2
$\overline{m_1}$	$\frac{1}{3}$	$\frac{1}{3}$
m_2	$\frac{1}{3}$	0

	m_1	m_2
m_1	$\frac{1}{2}$	$\frac{1}{4}$
m_2	$\frac{1}{4}$	0

$$Q_i^a(t) = (1-\alpha)Q_i^a(t-1) + u_i(a, a_{-i}(t))$$
 (attraction update)

$$\mathcal{X}_{i}^{a}(t) = \frac{\exp(\beta Q_{i}^{a}(t))}{\sum_{a \in A_{i}} \exp(\beta Q_{i}^{a}(t))}$$
(softmax)

 $\alpha \in [0,1]$ Memory-loss

 $\beta \in [0, \infty)$ Choice intensity

Approach

- Learning information: payoffs and non payoff-relevant messages
- Extension of EWA, extend Fictitious Play
- Intuitive algorithm
- Probability of action is monotonic in its past performance
- Encompass exploration, error, uncertainty
- Does not require knowledge of opponent's payoffs Uncoupled

$$Q_i^a(t) = (1 - lpha)Q_i^a(t) + u_i(a, a_{-i}(t))$$
 (attraction update)
$$\mathcal{X}_i^a(t) = \frac{exp(\beta Q_i^a(t))}{\sum_{a \in A_i} exp(\beta Q_i^a(t))}$$
 (softmax)

 $\alpha \in [0,1]$ Memory-loss

 $\beta \in [0, \infty)$ Choice intensity

Algorithm with Messages

Let $\mu \in \Delta(M)$ be a distribution over messages, $M = M_1 \times \cdots \times M_n$

$$Q_i^{a|m}(t) = egin{cases} (1-lpha)Q_i^{a|m}(t-1) + u_i(a,a_{-i}(t)), & ext{if } m_t = m \ Q_i^{a|m}(t-1), & ext{otherwise} \end{cases}$$
 (attraction update)

$$\mathcal{X}_{i}^{a|m}(t) = egin{cases} rac{\exp(eta Q_{i}^{a|m}(t))}{\sum_{a \in A_{i}} \exp(eta Q_{i}^{a|m}(t))}, & \text{if } m_{t} = m \\ 0, & \text{otherwise} \end{cases}$$
 (softmax)

 $lpha \in [0,1]$ Memory-loss

 $\beta \in [0, \infty)$ Choice intensity

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Simulation

For each combination (α, β) :

- 2 players play the Hawk-dove game
- ▶ Set initial values: $Q_i^{a|m}(0) = 0$, so $\mathcal{X}_i^{a|m}(t) = \frac{1}{|A_i|}$; fixed $\mu \in \Delta(M)$
- ▶ Episode length T = 500, last-iterate check if $\mathcal{X}_i^{a|m}(T)$ convergence to CE, NE or else (99.5% thershold)
- ► Repeat 100 times

Sim 1

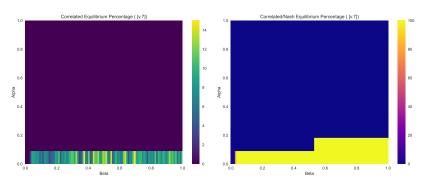


Figure: Convergence Percentage to the Pure Correlated Equilibrium (left) and to Correlated or Nash Equilibrium (right). Grid Heatmap: $\alpha \in [0, 1], \beta \in [0, 1]$



Sim 1'

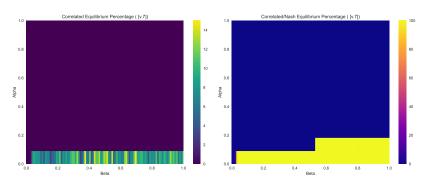


Figure: Convergence Percentage to the Pure Correlated Equilibrium (left) and to Correlated or Nash Equilibrium (right). Grid Heatmap: $\alpha \in [0, 1], \beta \in [0, 1]$

Robust Information Design

Price of Learning

$$PoL = \frac{\text{Welfare with messages}}{\text{Welfare without messages}}$$

- ► Everything is learnt in this framework: Payoffs, opponent's behavior, message correlation
- ► Bauch and Hartmann (2025)
- ► In the search of Optimal algorithm to calculate the optimal Price of Learning
- ► Robust Information Design (Feng et al., 2024)



Sim 2

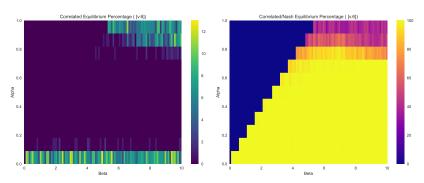


Figure: Convergence Percentage to the Pure Correlated Equilibrium (left) and to Correlated or Nash Equilibrium (right). Grid Heatmap: $\alpha \in [0, 1], \beta \in [0, 10]$



Sim 3

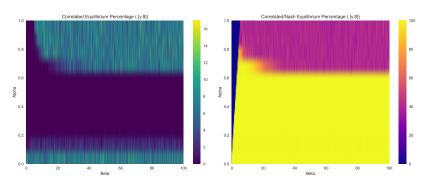


Figure: Convergence Percentage to the Pure Correlated Equilibrium (left) and to Correlated or Nash Equilibrium (right). Grid Heatmap: $\alpha \in [0, 1], \beta \in [0, 100]$

Time Difference Graph

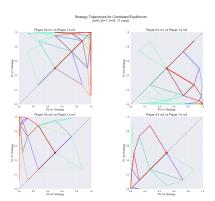


Figure: Strategy Trajectories for CE

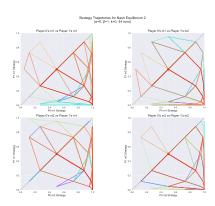


Figure: Strategy Trajectories for NE

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$$\mathcal{X}_{i}^{a}(t+1) = \frac{\mathcal{X}_{i}^{a}(t)e^{\beta[Q^{a}(t+1)-Q^{a}(t)]}}{\sum_{a'\in A_{i}}\mathcal{X}_{i}^{a'}(t)e^{\beta[Q^{a'}(t+1)-Q^{a'}(t)]}}$$

$$Q_{i}^{a}(t+1) - Q_{i}^{a}(t) = -\alpha Q_{i}^{a}(t) + u_{i}^{t}(a, a_{-i}(t))$$

$$\dot{Q}_i^a(t) = u_i^a(t) - \alpha Q_i^a(t)$$

$$\begin{split} \dot{\mathcal{X}}_{i}^{a}(t) &= \frac{d}{dt} \mathcal{X}_{i}^{a}(t) = \frac{d}{dt} \frac{\exp(\beta Q_{i}^{a}(t))}{\sum_{a' \in A_{i}} \exp(\beta Q_{i}^{a'}(t))} \\ &= \beta \mathcal{X}_{i}^{a}(t) \left[\dot{Q}_{i}^{a}(t) - \sum_{a' \in A_{i}} \dot{Q}_{i}^{a'}(t) \mathcal{X}_{i}^{a'}(t) \right] \end{split}$$

$$\frac{\dot{\mathcal{X}}_{i}^{a}(t)}{\mathcal{X}_{i}^{a}(t)} = \beta \left[u_{i}^{a}(t) - \sum_{a' \in A_{i}} u_{i}^{a'}(t) \mathcal{X}_{i}^{a'}(t) \right] - \alpha \left[\ln \mathcal{X}_{i}^{a}(t) - \sum_{a' \in A_{i}} \mathcal{X}_{i}^{a'}(t) \ln \mathcal{X}_{i}^{a'}(t) \right]$$

Algorithm with Messages

$$Q_i^{a|m}(t) - Q_i^{a|m}(t-1) = \mathbb{1}(m_t = m)[u_i(a, a_{-i}(t)) - \alpha Q_i^{a|m}(t-1)]$$
(1)

$$\dot{Q}_{i}^{a|m}(t) = \mathbb{P}(m_{t} = m) \left[\mathbb{E}_{a_{-i} \sim \mathcal{X}_{-i}^{a_{-i}}(t)} \left[u_{i}(a, a_{-i}(t)) - \alpha Q_{i}^{a|m}(t-1) \right] \right]$$
(2)

Messages

$$\mathcal{X}_{i}^{\mathsf{a}|m}(t) = P(m_{t} = m) \frac{\exp(\beta Q_{i}^{\mathsf{a}|m}(t))}{\sum_{\mathsf{a} \in A_{i}} \exp(\beta Q_{i}^{\mathsf{a}|m}(t))}$$
(3)

$$egin{align} \dot{\mathcal{X}}_i^{\mathsf{a}|m}(t) = \ &= \mathbb{P}(m_t = m) eta \mathcal{X}_i^{\mathsf{a}}(t) \left[\dot{Q}_i^{\mathsf{a}}(t) - \sum_{\mathsf{a}' \in A_i} \dot{Q}_i^{\mathsf{a}'}(t) \mathcal{X}_i^{\mathsf{a}'}(t)
ight] \end{aligned}$$

Final Message

$$\frac{\dot{\mathcal{X}}_{i}^{a|m}(t)}{\mathcal{X}_{i}^{a|m}(t)} = \beta \left[u_{i}(a, \mathcal{X}_{-i}^{a-i}(t)) - \sum_{a' \in A_{i}} u_{i}(a, \mathcal{X}_{i}^{a-i}(t)) \mathcal{X}_{i}^{a'|m}(t) \right] - \alpha \left[\ln \mathcal{X}_{i}^{a|m}(t) - \sum_{a' \in A_{i}} \mathcal{X}_{i}^{a'|m}(t) \ln \mathcal{X}_{i}^{a'|m}(t) \right]$$

Proposition

All pure strategy profiles given message $\mathcal{X}_{i}^{a|m}(t) \in \{0,1\}$ are a fixed point. If memory-loss is positive, $\alpha > 0$, then the fixed points are unstable. If $\alpha = 0$, the pure-strategy fixed points are stable iff correlated equilibrium.

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- ► EWA with messages
- Fixed-point analysis, simulations
- Robust Information Design
- Memory and choice intensity have a proportional relation on reaching pure strategy outcomes

Work in Progress

- Time Convergence and Convergence Guarantees
- Can it be manipulated?
- More messages = better?
- Expansion to the dynamic case: can it be manipulated? Dynamic Information Design
- Study chaotic cycles
- Basin of attractions
- ▶ Sanders et al. (2018) shows that the basin of attractions get smaller as $n \to \infty$



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