

Foundations & applications of generalised symmetries

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1 Foundations

1.1 Conventional symmetries *

Most parts of this section are adopted from the materials below.

- [1] M. E. Peskin and D. V. Schroeder, “An Introduction to quantum field theory”
- [2] M. Srednicki, “Quantum field theory”
- [3] P. R. S. Gomes, “An introduction to higher-form symmetries”, Section 3

1.1.1 Schwinger-Dyson equation & conversation laws

Proposition^{ph} 1.1. We have following relation, which is well-known as Schwinger-Dyson equation.

$$\left\langle \frac{\partial S[\varphi]}{\partial \varphi(x)} \varphi(x_1) \cdots \varphi(x_n) \right\rangle = i \sum_{i=1}^n \langle \varphi(x_1) \cdots \delta^D(x - x_i) \cdots \varphi(x_n) \rangle. \quad (1.1)$$

Proof. First of all, we prove the general relation

$$\int \mathcal{D}\varphi \frac{\delta}{\delta \varphi(x)} \left(F[\varphi] e^{iS[\varphi]} \right) = 0. \quad (1.2)$$

We start from the obvious relation

$$\int \mathcal{D}\varphi F[\varphi] e^{iS[\varphi]} = \int \mathcal{D}\varphi' F[\varphi'] e^{iS[\varphi']}, \quad (1.3)$$

¹The sections with asterisk “*” are materials that is not directly related to generalised symmetries but supplemental.

which is just a renaming of a dummy variable of the integration. Now we perform a change of variables $\varphi'(x) \mapsto \varphi(x) + \varepsilon(x)$. Then we have

$$\begin{aligned}
\int \mathcal{D}\varphi F[\varphi] e^{iS[\varphi]} &= \int \mathcal{D}\varphi F[\varphi + \varepsilon] e^{iS[\varphi + \varepsilon]} \\
&= \int \mathcal{D}\varphi \left\{ F[\varphi] + \int d^D x \frac{\delta F[\varphi]}{\delta \varphi(x)} \varepsilon(x) \right\} \exp \left\{ iS[\varphi] + i \int d^D x \frac{\delta S[\varphi]}{\delta \varphi(x)} \varepsilon(x) \right\} \\
&= \int \mathcal{D}\varphi \left\{ F[\varphi] + \int d^D x \frac{\delta F[\varphi]}{\delta \varphi(x)} \varepsilon(x) \right\} \left\{ 1 + i \int d^D x \frac{\delta S[\varphi]}{\delta \varphi(x)} \varepsilon(x) \right\} e^{iS[\varphi]} \\
&= \int \mathcal{D}\varphi F[\varphi] e^{iS[\varphi]} + \int \mathcal{D}\varphi \int d^D x \left\{ \frac{\delta F[\varphi]}{\delta \varphi(x)} e^{iS[\varphi]} + F[\varphi] i \frac{\delta S[\varphi]}{\delta \varphi(x)} e^{iS[\varphi]} \right\} \varepsilon(x), \quad \forall \varepsilon(x), \quad (1.4)
\end{aligned}$$

which leads us to the identity

$$\int \mathcal{D}\varphi \left\{ \frac{\delta F[\varphi]}{\delta \varphi(x)} e^{iS[\varphi]} + F[\varphi] i \frac{\delta S[\varphi]}{\delta \varphi(x)} e^{iS[\varphi]} \right\} = 0. \quad (1.5)$$

Now, by substituting $F[\varphi]$ with $\varphi(x_1) \cdots \varphi(x_n)$ we get

$$i \int \mathcal{D}\varphi \frac{\delta S[\varphi]}{\delta \varphi(x)} \varphi(x_1) \cdots \varphi(x_n) e^{iS[\varphi]} = - \sum_{i=1}^n \int \mathcal{D}\varphi \varphi(x_1) \cdots \delta^D(x - x_i) \cdots \varphi(x_n) e^{iS[\varphi]}, \quad (1.6)$$

which we simply denote

$$\left\langle \frac{\delta S[\varphi]}{\delta \varphi(x)} \varphi(x_1) \cdots \varphi(x_n) \right\rangle = i \sum_{i=1}^n \langle \varphi(x_1) \cdots \delta^D(x - x_i) \cdots \varphi(x_n) \rangle. \quad (1.7)$$

□

Remark 1.1. Schwinger-Dyson equation is the generalisation of Ward-Takahashi identity.

Proposition^{ph} 1.2. We have following relation, which is a correlation function representation of the conservation law of Noether current.

$$\langle \{ \partial_\mu j^\mu(x) \} \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) \rangle = -i \sum_{i=0}^n \langle \varphi_{a_1}(x_1) \cdots \delta^D(x - x_i) \delta \varphi_{a_i}(x_i) \cdots \varphi_{a_n}(x_n) \rangle. \quad (1.8)$$

Proof. Now, we consider the transformation

$$\varphi_a(x) \mapsto \varphi'_a(x) = \varphi_a(x) + \delta_{\varepsilon(x)} \varphi_a(x) = \varphi_a(x) + \varepsilon(x) g_a(x). \quad (1.9)$$

We first prove the relation

$$\delta_{\varepsilon(x)} S[\varphi] = - \int d^D x \varepsilon(x) \partial_\mu \left\{ \sum_{a=1}^N g_a(x) \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi_a(x))} - K^\mu[\varphi] \right\} = - \int d^D x \varepsilon(x) \partial_\mu j^\mu(x) \quad (1.10)$$

where we defined $j^\mu(x)$ as

$$j^\mu(x) = \sum_{a=1}^N g_a(x) \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi_a(x))} - K^\mu[\varphi]. \quad (1.11)$$

The direct calculation of $\delta_{\varepsilon(x)}S[\varphi]$ is as follows.

$$\begin{aligned}
\delta_{\varepsilon(x)}S[\varphi] &= \int d^Dx \delta_{\varepsilon(x)}\mathcal{L}[\varphi, \partial_\mu\varphi] = \int d^Dx \{\mathcal{L}[\varphi(x) + \varepsilon(x)\varphi(x), \partial_\mu\{\varphi(x) + \varepsilon(x)g(x)\}] - \mathcal{L}[\varphi(x), \partial_\mu\varphi(x)]\} \\
&= \int d^Dx \{\mathcal{L}[\varphi(x) + \varepsilon(x)\varphi(x), \partial_\mu\varphi(x) + \partial_\mu\varepsilon(x)g(x) + \varepsilon(x)\partial_\mu g(x)] - \mathcal{L}[\varphi(x), \partial_\mu\varphi(x)]\} \\
&= \int d^Dx \left\{ \varepsilon(x) \sum_{a=1}^N g_a(x) \frac{\partial\mathcal{L}}{\partial\varphi_a(x)} + \varepsilon(x) \sum_{a=1}^N \partial_\mu g_a(x) \frac{\partial\mathcal{L}}{\partial(\partial_\mu\varphi_a(x))} + \partial_\mu\varepsilon(x) \sum_{a=1}^N g_a(x) \frac{\partial\mathcal{L}}{\partial(\partial_\mu\varphi_a(x))} \right\} \\
&= \int d^Dx \varepsilon(x) \partial_\mu K^\mu(x) + \int d^Dx \partial_\mu\varepsilon(x) \sum_{a=1}^N g_a(x) \frac{\partial\mathcal{L}}{\partial(\partial_\mu\varphi_a(x))} \tag{1.12}
\end{aligned}$$

Here, we assumed

$$\sum_{a=1}^N g_a(x) \frac{\partial\mathcal{L}}{\partial\varphi_a(x)} + \sum_{a=1}^N \partial_\mu g_a(x) \frac{\partial\mathcal{L}}{\partial(\partial_\mu\varphi_a(x))} = \partial_\mu K^\mu[\varphi(x)], \quad \exists K^\mu[\varphi(x)]. \tag{1.13}$$

Integrating the second term by parts, we get

$$\delta_{\varepsilon(x)}S[\varphi] = \int d^Dx \varepsilon(x) \partial_\mu K^\mu(x) - \int d^Dx \varepsilon(x) \partial_\mu \left\{ g_a(x) \frac{\partial\mathcal{L}}{\partial(\partial_\mu\varphi_a(x))} \right\} = - \int d^Dx \varepsilon(x) \partial_\mu j^\mu(x). \tag{1.14}$$

Now, we move on to the proof of the relation in consider. We start from the trivial relation

$$\int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) e^{iS[\varphi]} = \int \left(\prod_{a=1}^N \mathcal{D}\varphi'_a \right) \varphi'_{a_1}(x_1) \cdots \varphi'_{a_n}(x_n) e^{iS[\varphi]}. \tag{1.15}$$

Here, we perform the change of variable $\varphi'_a(x) = \varphi_a(x) + \varepsilon(x)g_a(x)$ and we get

$$\begin{aligned}
\int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) e^{iS[\varphi]} &= \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) e^{iS[\varphi]} \\
&\quad + i \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) \left\{ - \int d^Dx \varepsilon(x) \partial_\mu j^\mu(x) \right\} e^{iS[\varphi]} \\
&\quad + \sum_{i=1}^n \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varepsilon(x_i) g_{a_i}(x_i) \cdots \varphi_{a_n}(x_n) e^{iS[\varphi]}, \tag{1.16}
\end{aligned}$$

which leads us to

$$\begin{aligned}
&- i \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) \left\{ \int d^Dx \varepsilon(x) \partial_\mu j^\mu(x) \right\} e^{iS[\varphi]} \\
&= \sum_{i=1}^n \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varepsilon(x_i) g_{a_i}(x_i) \cdots \varphi_{a_n}(x_n) e^{iS[\varphi]} = 0. \tag{1.17}
\end{aligned}$$

Now, we substitute $\varepsilon(x_i)$ in RHS with a trivial relation $\varepsilon(x_i) = \int d^Dx \varepsilon(x) \delta^D(x - x_i)$, we get

$$\begin{aligned}
&- i \int d^Dx \varepsilon(x) \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) \{ \partial_\mu j^\mu(x) \} e^{iS[\varphi]} \\
&= \int d^Dx \varepsilon(x) \sum_{i=1}^n \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \delta^D(x - x_i) g_{a_i}(x_i) \cdots \varphi_{a_n}(x_n) e^{iS[\varphi]}, \quad \forall \varepsilon(x). \tag{1.18}
\end{aligned}$$

Then we get

$$i \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) \{ \partial_\mu j^\mu(x) \} e^{iS[\varphi]} = \sum_{i=1}^n \int \left(\prod_{a=1}^N \mathcal{D}\varphi_a \right) \varphi_{a_1}(x_1) \cdots \delta^D(x - x_i) g_{a_i}(x_i) \cdots \varphi_{a_n}(x_n) e^{iS[\varphi]}, \quad (1.19)$$

which means that

$$\langle \varphi_{a_1}(x_1) \cdots \varphi_{a_n}(x_n) \{ \partial_\mu j^\mu(x) \} \rangle = -i \sum_{i=0}^n \langle \varphi_{a_1}(x_1) \cdots \delta^D(x - x_i) g_{a_i}(x_i) \cdots \varphi_{a_n}(x_n) \rangle. \quad (1.20)$$

□

1.1.2 Reformulation in differential forms

Fact^{ph} 1.1. Mathematically speaking, Noether current $j^\mu(x)$ are coefficients of a vector field on the spacetime manifold \mathcal{M} , which is a section of the tangent bundle $T\mathcal{M}$. And equivalently $j_\mu(x)$ are coefficients of a covector field of a section of the cotangent bundle $T^*\mathcal{M}$. Let us stick to the representation on cotangent bundle in this notes, then we can write

$$j = j_\mu(x) dx^\mu. \quad (1.21)$$

And obviously, we have the Hodge dual of it.

$$*j = \frac{1}{(D-1)!} j_{\mu_0}(x) \epsilon^{\mu_0}_{\mu_1 \cdots \mu_{D-1}} dx^{\mu_1} \wedge \cdots \wedge dx^{\mu_{D-1}}. \quad (1.22)$$

Proposition^{ph} 1.3. The conversation law $\partial_\mu j^\mu(x) = 0$ can be written as

$$d * j = 0. \quad (1.23)$$

Proof. We will see the equivalence of the two representations $\partial_\mu j^\mu = \partial^\mu j_\mu = 0$ and $d * j = 0$. We start from

$$\begin{aligned} d * j &= \frac{1}{(D-1)!} \partial_\alpha j_{\mu_0}(x) \epsilon^{\mu_0}_{\mu_1 \cdots \mu_{D-1}} dx^\alpha \wedge dx^{\mu_1} \wedge \cdots \wedge dx^{\mu_{D-1}} = \frac{1}{(D-1)!} \partial_\alpha j_{\mu_0}(x) \epsilon^{\mu_0}_{\mu_1 \cdots \mu_{D-1}} \epsilon^{\alpha \mu_1 \cdots \mu_{D-1}} \\ &= (-1)^{D-1} \partial_\alpha j_{\mu_0}(x) \eta^{\mu_0 \alpha} dx^0 \wedge \cdots \wedge dx^{D-1} = (-1)^{D-1} \partial^\mu j_\mu(x) dx^0 \wedge \cdots \wedge dx^{D-1}. \end{aligned} \quad (1.24)$$

Now, if we assume $d * j = 0$, obviously $\partial_\mu j^\mu(x) = 0$ because $dx^0 \wedge \cdots \wedge dx^{D-1} \neq 0$. Also if we assume $\partial_\mu j^\mu(x) = 0$, obviously $d * j = 0$ from the relation we just derived. □

Remark 1.2. In the Euclidean theory, which we will be using so often in this note, we simply have

$$d * j = \partial_\mu j^\mu(x) dx^0 \wedge \cdots \wedge dx^{D-1}. \quad (1.25)$$

Proposition^{ph} 1.4. The definition of Noether charge $Q = \int d^{D-1}x j_0(x)$ is translated to differential forms as follows.

$$Q = \int_\Sigma *j, \quad (1.26)$$

where, Σ is the spatial submanifold of the spacetime manifold \mathcal{M} .

Proof. We start by rewriting the integral.

$$\begin{aligned}
Q &= \int_{\Sigma} *j = \int_{\Sigma} \frac{1}{(D-1)!} j_{\mu_0}(x) \epsilon^{\mu_0}_{\mu_1 \dots \mu_{D-1}} dx^{\mu_1} \wedge \dots \wedge dx^{\mu_{D-1}} \\
&= \int_{\Sigma} \frac{1}{(D-1)!} j_{\mu_0}(x) \epsilon^{\mu_0}_{\mu_1 \dots \mu_{D-1}} \epsilon^{0\mu_1 \dots \mu_{D-1}} dx^1 \wedge \dots \wedge dx^{D-1} = \int_{\Sigma} j_{\mu_0}(x) (-1)^{D-1} \eta^{\mu_0 0} dx^1 \wedge \dots \wedge dx^{D-1}.
\end{aligned} \tag{1.27}$$

Obviously, (1.27) = 0 for $\mu_0 \neq 0$. Then we have

$$Q = (-1)^{D-1} \int_{\Sigma} j_0(x) dx^1 \wedge \dots \wedge dx^{D-1}, \tag{1.28}$$

which has the same meaning as $\int d^{D-1}x j_0(x)$.² □

Proposition^{ph} 1.5.

1.2 Definition of higher-form symmetries

Most parts of this section are adopted from the materials below.

[3] P. R. S. Gomes, “An introduction to higher-form symmetries”

2 Applications

References

- [1] M. E. Peskin and D. V. Schroeder, Addison-Wesley, 1995, ISBN 978-0-201-50397-5, 978-0-429-50355-9, 978-0-429-49417-8 doi:10.1201/9780429503559
- [2] M. Srednicki, Cambridge University Press, 2007, ISBN 978-0-521-86449-7, 978-0-511-26720-8 doi:10.1017/CBO9780511813917
- [3] P. R. S. Gomes, SciPost Phys. Lect. Notes **74** (2023), 1 doi:10.21468/SciPostPhysLectNotes.74 [arXiv:2303.01817 [hep-th]].

²Here, we ignore the factor $(-1)^{D-1}$ because it does not affect the physical invariant.