

Foundations & applications of generalised symmetries

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1 Foundations

1.1 Higher-form global symmetries

1.1.1 Symmetry as topological operators

Statement 1.1. Symmetry generators are topological operators.

We have Ward-Takahashi identity (in differential forms).

$$\langle d*j(x)\mathcal{O}(y) \rangle = -i\delta^{(D)}(x-y) \langle \delta\mathcal{O}(y) \rangle. \quad (1.1)$$

Noether charge is defined as follows.

$$Q_\Sigma = \int_\Sigma *j(x), \quad (1.2)$$

where Σ is a equal-time hypersurface on the spacetime manifold M .² Integrating the both sides of this equation on the manifold Ω that has the hypersurface Σ as its boundary, we get

$$\langle Q_\Sigma \mathcal{O}(x) \rangle = -i \text{Link}(P, \Omega) \langle \delta\mathcal{O}(x) \rangle, \quad (1.3)$$

where P is defined as $P = \{(y^0, \dots, y^{D-1})\}$. We can see that $\langle Q_\Sigma \mathcal{O}(x) \rangle$ is topological in the sense that it is invariant under the deformation of the manifold Ω that does not cross the point P .

¹The sections with asterisk “*” are materials that is not directly related to generalised symmetries but supplemental.
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This formulation leads us to the following observation.

Observation 1.1. The Ward-Takahashi identity we have derived

$$\langle Q_\Sigma \mathcal{O}(x) \rangle = -i \text{Link}(P, \Omega) \langle \delta \mathcal{O}(x) \rangle \quad (1.4)$$

provides a new perspective in generalising symmetries. We may put this relation as the starting point of the discussion of symmetries and generalising them by substituting P, Ω with some manifolds X, Y such that $\dim X + \dim Y = D$. And naturally, after the generalisation, the operator $\mathcal{O}(x)$ is not supported at a point anymore but supported on a manifold X .

$$\langle Q_\Sigma \mathcal{O}(X) \rangle = -i \text{Link}(X, Y) \langle \delta \mathcal{O}(X) \rangle. \quad (1.5)$$

1.1.2 Definition of p - form symmetries

Now, let us put the observation as the definition of symmetries (and we call this symmetry a higher-form symmetry).

Definition^(ph) 1.1. We define a p - form symmetry as follows. We say that there exists an p - form symmetry in the system in consider if there exists an operator Q_Σ that is supported on a $D - p - 1$ dimensional manifold Σ and it satisfies Ward-Takahashi identity

$$\langle Q_\Sigma \mathcal{O}(X) \rangle = -i \text{Link}(X, Y) \langle \delta \mathcal{O}(X) \rangle, \quad \Sigma = \partial Y. \quad (1.6)$$

We call this operator Q_Σ a symmetry operator.

1.1.3 Exmaples of p - form symmetries

$D = 4$ dimensional $U(1)$ gauge theory We consider an action

$$S[a] = -\frac{1}{2e^2} \int_M f \wedge *f, \quad f = da, \quad (1.7)$$

where a is the $U(1)$ gauge field. Considering the trivial relation $d^2 = 0$ and the equation of motion, we get

$$d*f = 0, \quad df = 0. \quad (1.8)$$

Now, let us define new operators as follows.

$$Q_\Sigma^{(e)} = \int_\Sigma *f, \quad Q_\Sigma^{(m)} = \int_\Sigma f. \quad (1.9)$$

Let us stick to $Q_\Sigma^{(e)}$ for a while. We first prove that $Q_\Sigma^{(e)}$ is a symmetry operator.

2 Applications